

Domains of simple-stable representations

Tianqi WANG

Yale University

April 26, 2025

- Γ hyperbolic group
 - $\Gamma = F_n$ free group
 - $\Gamma = \pi_1(S)$ closed surface group.
- G semisimple Lie group of non-compact type
 - $G = PSL(2, \mathbb{R}), PSL(2, \mathbb{C}),$
 - $SO^+(n, 1) \cong Isom^+(\mathbb{H}^n)$
 - $G = SL(d, \mathbb{C})$
- $X(\Gamma, G) = \text{Hom}(\Gamma, G) // G$ the character variety
- $\text{Out}(\Gamma) = \text{Aut}(\Gamma) / \text{Inn}(\Gamma) \rightarrow X(\Gamma, G)$ by pre-composition

S_g closed oriented surface of genus $g \geq 2$

Theorem (Goldman 80)

- $\chi(\pi_1(S_g), \text{PSL}(2, \mathbb{R}))$ has $4g-3$ connected components, characterized by the Euler number $e \in [2-2g, 2g-2] \cap \mathbb{Z}$
- $e = 2-2g, 2g-2$ corresponding to two copies of $\text{Teich}(S_g)$ with $\text{Out}(\pi_1(S_g)) = \text{MCG}(S_g)$ - action properly discontinuous.

Goldman's Conjecture

- The $\text{MCG}(S_g)$ -action on the other components is ergodic.

Theorem (Sauto - Storm 06, Lee 15)

- The domain of quasi-Fuchsian (convex-cocompact) representations is a maximal connected domain of discontinuous in $X(\pi_1(S_g), \text{PSL}(2, \mathbb{C}))$.

Convex cocompactness

Simple - Stability

$$f : \pi_1(S_g) \rightarrow \text{Isom}(\mathbb{H}^n) \rightsquigarrow \tau_{f, o} : \pi_1(S_g) \rightarrow \mathbb{H}^n$$

$\gamma \mapsto f(\gamma) \cdot o$

orbit map

simple-stable
 f is convex cocompact if

$\tau_{f, o}$ is a quasi-isometric embedding along simple
closed geodesics of S_g uniformly.

Theorem (Minsky 13, Lee 15, Tholozan-W. 23)

- The set of simple-stable representations is a domain of discontinuity in $X(\pi_1(S_g), \text{Isom}^+(\mathbb{H}^n))$.

$$\text{ee} \subseteq \text{ss}$$

$\overset{+}{\text{SO}(2,1)} \cong \text{PSL}(2, \mathbb{R})$ Goldman's conjecture $\Rightarrow " = "$

$\overset{+}{\text{SO}(3,1)} \cong \text{PSL}(2, \mathbb{C})$ Connected component " $=$ " holds

$\overset{+}{\text{SO}(n,1)} \quad n \geq 4$ \subseteq

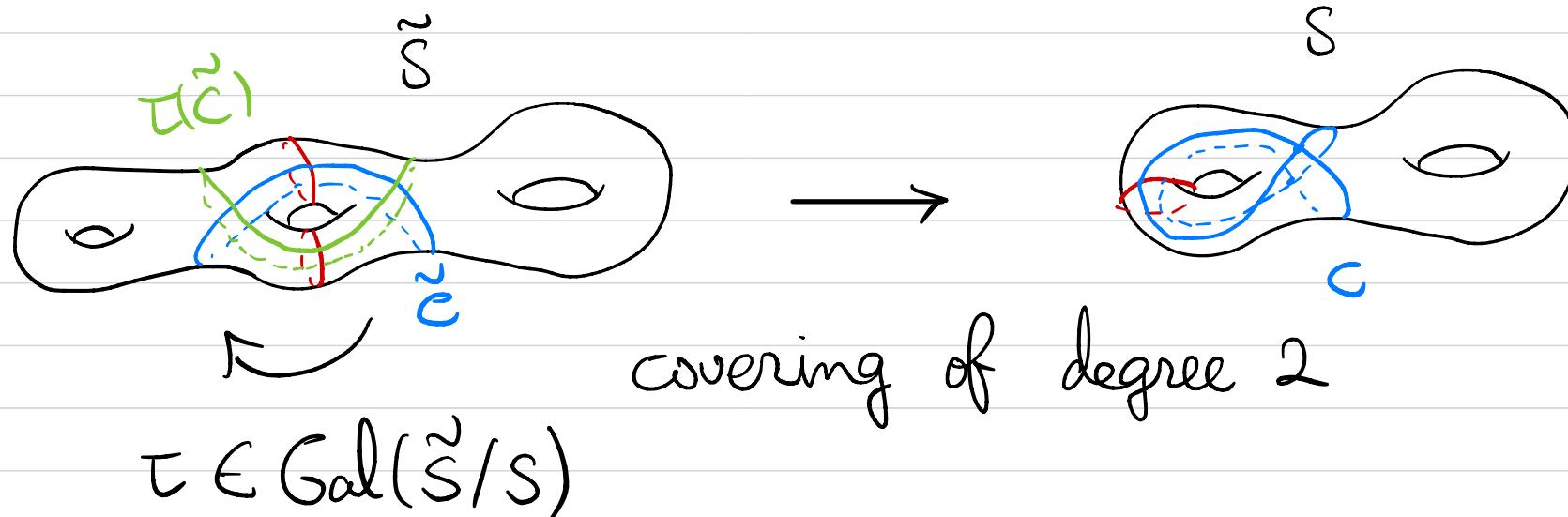
Theorem (Minsky-W. 25)

- There exists a simple-stable representation

$\varphi : \pi_1(S_g) \rightarrow SO^+(4, 1)$ on the boundary

of domain of convex-cocompact representations.

Construction



Find $\tilde{\rho}: \pi_1(\tilde{S}) \rightarrow \text{PSL}(2, \mathbb{C})$ geometrically finite

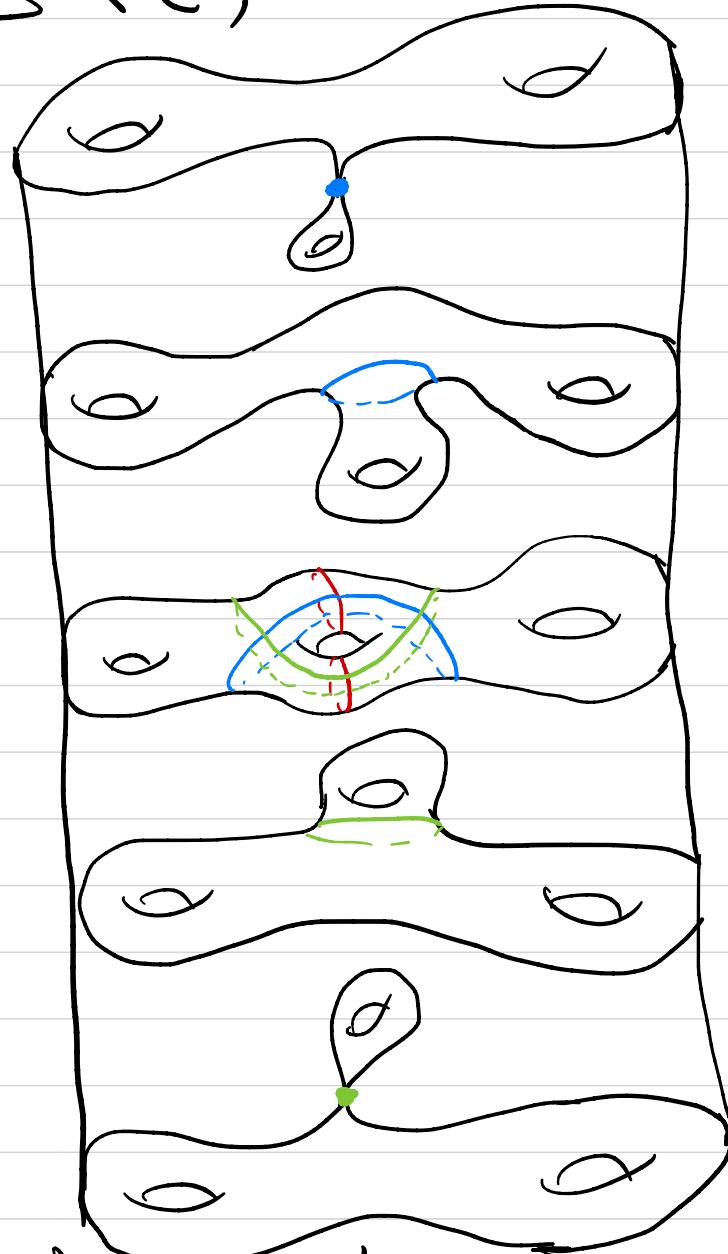
with parabolicity only at \tilde{c} and $\tau(\tilde{c})$

that can extend to a representation of $\pi_1(S)$.

Generalized Simultaneous Uniformization Theorem

(Ahlfors 60 , Bers 06 , Kra 72 , Marden 74 , Maskit 70 ,
Mostow 68 , Prasad 73 , Thurston 82)

$$\left\{ \begin{array}{l} \text{geometrically finite} \\ \rho : \pi_1(S) \rightarrow \mathrm{PSL}(2, \mathbb{C}) \end{array} \right\} \longleftrightarrow \left\{ \begin{array}{l} \text{multicurves} \\ P^+, P^- \\ v^+ \in \overline{\mathrm{Teich}}(S \setminus P^+) \\ v^- \in \overline{\mathrm{Teich}}(S \setminus P^-) \end{array} \right\}$$

$v^+ \in \text{Teich}(\tilde{S} \setminus \tilde{c})$  $v^- = \tau(v^+) \in \text{Teich}(\tilde{S} \setminus \tau(\tilde{c}))$
 $P^2 \rightsquigarrow P$
by ϕ $v^- = \tau(v^+) \in \text{Teich}(\tilde{S} \setminus \tau(\tilde{c}))$ $\tilde{S} \times \mathbb{R}$

$$\tilde{\rho} : \pi_1(\tilde{S}) \rightarrow \mathrm{PSL}(2, \mathbb{C}) \cong \mathrm{SO}^+(3, 1) + \mathbb{D}$$



$$\rho : \pi_1(S) \rightarrow O^+(3, 1) \subset SO^+(4, 1)$$

Graph Products of Morse Local-to-Global Groups

Joshua Perlmutter

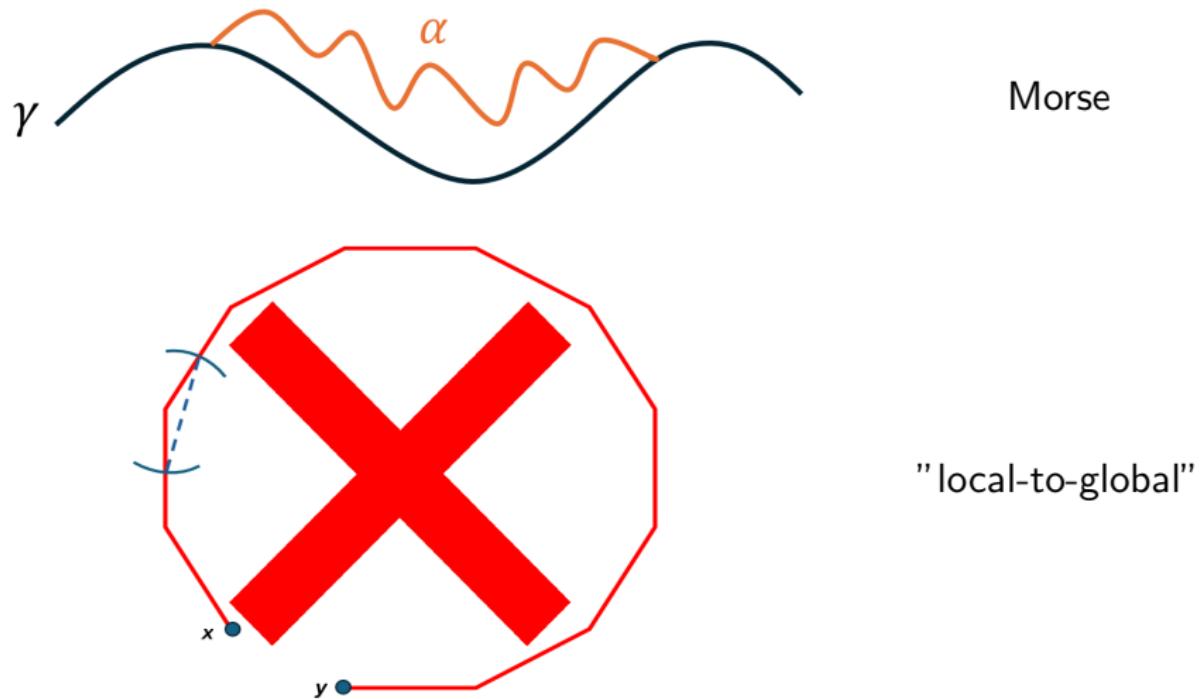
Brandeis University

jperlmutter@brandeis.edu

April 26, 2025

Motivation: Generalizing Hyperbolic Groups

In a hyperbolic space, all quasi-geodesics are



Morse Local-to-Global Groups and Spaces

Defined by Russell, Spriano, Tran (2022)

- Non-hyperbolic spaces can have Morse quasi-geodesics
- If all the Morse quasi-geodesics have the "local-to-global" property, the space is **Morse local-to-global**

$$\begin{array}{ccc} \text{locally Morse} & & \text{globally Morse} \\ + & \implies & + \\ \text{locally quasi-geodesic} & & \text{globally quasi-geodesic} \end{array}$$

Examples of Morse Local-to-Global Groups

From Russell, Spriano, Tran (2022):

- Direct Products of Infinite Groups
- Hierarchically Hyperbolic Groups
- CAT(0) Groups
- Hyperbolic Groups Relative to MLTG Groups

Non-Examples?

Theorem (Russell, Spriano, Tran 2022)

There exists groups which are not Morse local-to-global.

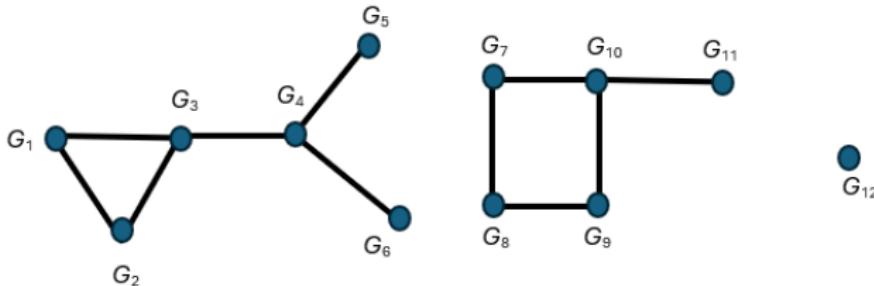
All known examples are infinitely presented!

Graph Products

Definition (Graph Products)

Let Γ be a finite simplicial graph with vertex set $V(\Gamma)$ and edge set $E(\Gamma)$. Assign a group G_v to each $v \in V(\Gamma)$. The graph product G_Γ is defined to be

$$G_\Gamma = \left(\ast_{v \in V(\Gamma)} G_v \right) / \langle\langle [g_v, g_w] \mid g_v \in G_v, g_w \in G_w, \{v, w\} \in E(\Gamma) \rangle\rangle.$$



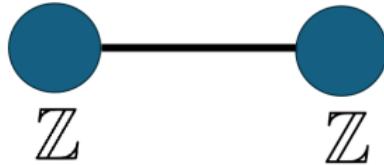
Examples of Graph Products

Right-angled Artin groups are graph products (all vertex groups being \mathbb{Z})

Examples:



$$\Gamma = F_2 = \langle a, b \rangle$$



$$\Gamma = \mathbb{Z}^2 = \langle a, b \mid ab = ba \rangle$$

Technique

Tools from hierarchically hyperbolic groups

+

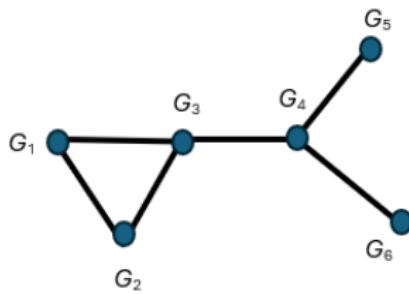
Theorem (Berlyne, Russell 2022)

Graph products are relatively hierarchically hyperbolic groups.

Main Result

Theorem (P, in progress)

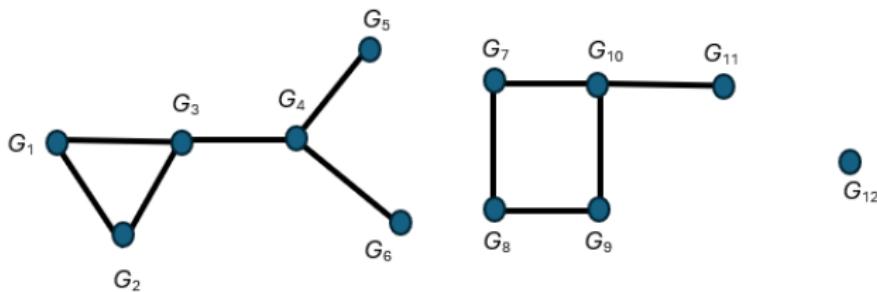
Multi-vertex connected graph products of infinite groups are Morse local-to-global.



Main Result (Continued)

Corollary (P, in progress)

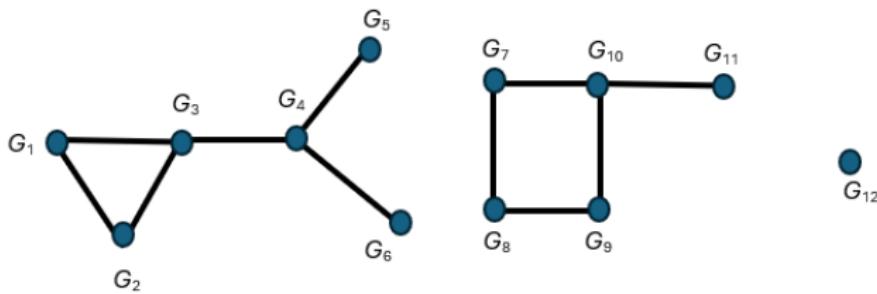
Graph Products of infinite Morse local-to-global groups are Morse local-to-global.



Main Result (Continued)

Corollary (P, in progress)

Graph Products of infinite Morse local-to-global groups are Morse local-to-global.



Thank You

Singularity of Stationary measures and Patterson–Sullivan measures for Mapping Class Groups

Dongryul M. Kim

Yale University

GATSBY 2025 Spring

Let

S : closed conn. ori. surface of genus ≥ 2

$\text{Mod}(S)$: Mapping class group of S ($= \text{Homeo}^+(S)/\sim$)

Let

μ : probability on $\text{Mod}(S)$ with finite support

For each $n \in \mathbb{N}$,

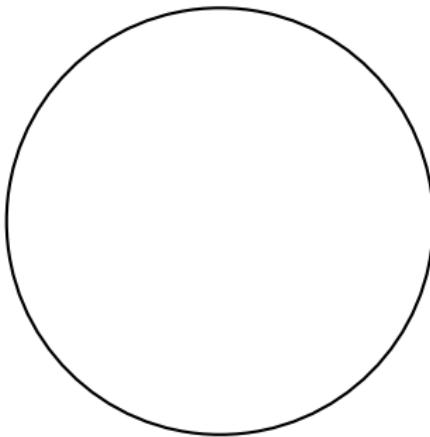
$$w_n := g_1 \cdots g_n, \quad g_i \sim \mu \quad \text{i.i.d.}$$

$\rightsquigarrow (w_n)_{n \in \mathbb{N}}$: “Random walk on $\text{Mod}(S)$ ”

$\mathcal{T}(S)$: Teichmüller space of S (equipped with the Teichmüller distance)

For a fixed $o \in \mathcal{T}(S)$,

$\{w_n o \in \mathcal{T}(S) : n \in \mathbb{N}\} \rightsquigarrow \text{random walk in } \mathcal{T}(S)$



$\mathcal{T}(S)$: Teichmüller space of S (equipped with the Teichmüller distance)

For a fixed $o \in \mathcal{T}(S)$,

$\{w_n o \in \mathcal{T}(S) : n \in \mathbb{N}\} \rightsquigarrow \text{random walk in } \mathcal{T}(S)$

Theorem (Kaimanovich–Masur, 1996)

Almost every $(w_n o)_{n \in \mathbb{N}}$ converges to \mathcal{PMF} ($=$ Thurston's boundary of $\mathcal{T}(S)$).

$\mathcal{T}(S)$: Teichmüller space of S (equipped with the Teichmüller distance)

For a fixed $o \in \mathcal{T}(S)$,

$\{w_n o \in \mathcal{T}(S) : n \in \mathbb{N}\} \rightsquigarrow \text{random walk in } \mathcal{T}(S)$

Theorem (Kaimanovich–Masur, 1996)

Almost every $(w_n o)_{n \in \mathbb{N}}$ converges to \mathcal{PMF} ($=$ Thurston's boundary of $\mathcal{T}(S)$).

Moreover, the hitting measure

$$\nu_{\text{Hit}}(E) = \text{Prob} \left((w_n)_{n \in \mathbb{N}} : \lim_{n \rightarrow \infty} w_n o \in E \right) \quad \text{for} \quad E \subset \mathcal{PMF}$$

is the unique μ -stationary measure on \mathcal{PMF} .

Another natural measure on \mathcal{PMF} :

Patterson–Sullivan (or, conformal) measure of $\langle \text{supp } \mu \rangle < \text{Mod}(S)$

(e.g. Athreya–Bufetov–Eskin–Mirzakhani (2012): \exists PS-meas. in Leb. class)

Another natural measure on \mathcal{PMF} :

Patterson–Sullivan (or, conformal) measure of $\langle \text{supp } \mu \rangle < \text{Mod}(S)$

(e.g. Athreya–Bufetov–Eskin–Mirzakhani (2012): \exists PS-meas. in Leb. class)

Conjecture (Kaimanovich–Masur, 1996)

The μ -stationary meas. ν_{Hit} is singular to all PS-meas. of $\langle \text{supp } \mu \rangle$.

Another natural measure on \mathcal{PMF} :

Patterson–Sullivan (or, conformal) measure of $\langle \text{supp } \mu \rangle < \text{Mod}(S)$

(e.g. Athreya–Bufetov–Eskin–Mirzakhani (2012): \exists PS-meas. in Leb. class)

Conjecture (Kaimanovich–Masur, 1996)

The μ -stationary meas. ν_{Hit} is singular to all PS-meas. of $\langle \text{supp } \mu \rangle$.

Theorem (Gadre, 2014)

The μ -stationary meas. ν_{Hit} is singular to Leb. on \mathcal{PMF} .

Proof: construction of a singular subset in \mathcal{PMF}

Moment condition was relaxed by Gadre–Maher–Tiozzo (2017)

For general $\langle \text{supp } \mu \rangle < \text{Mod}(S)$,

\exists PS-measure \notin Leb. class.

(e.g. Masur (1986), Kerckhoff (1990): Leb(limit set of Handlebody group) = 0)

No non-trivial example was known to satisfy Kaimanovich–Masur's conjecture in this case.

For general $\langle \text{supp } \mu \rangle < \text{Mod}(S)$,

\exists PS-measure \notin Leb. class.

(e.g. Masur (1986), Kerckhoff (1990): Leb(limit set of Handlebody group) = 0)

No non-trivial example was known to satisfy Kaimanovich–Masur's conjecture in this case.

Theorem (K.–Zimmer, 2025)

If $\langle \text{supp } \mu \rangle$ is relatively hyperbolic and contains a multitwist, then
the μ -stationary meas. ν_{Hit} is singular to all PS-meas. of $\langle \text{supp } \mu \rangle$.

Theorem (K.-Zimmer, 2025)

If $\langle \text{supp } \mu \rangle$ is relatively hyperbolic and contains a multitwist, then

the μ -stationary meas. ν_{Hit} is singular to all PS-meas. of $\langle \text{supp } \mu \rangle$.

Example

- ① When $\text{genus}(S) \geq 4$, \exists finite index $\Gamma < \pi_1(\mathbb{S}^3 \setminus \text{figure-8})$ such that

$$\Gamma \hookrightarrow \text{Mod}(S)$$

with multitwists (Kent–Leininger, 2024)

Theorem (K.-Zimmer, 2025)

If $\langle \text{supp } \mu \rangle$ is relatively hyperbolic and contains a multitwist, then

the μ -stationary meas. ν_{Hit} is singular to all PS-meas. of $\langle \text{supp } \mu \rangle$.

Example

- ① When $\text{genus}(S) \geq 4$, \exists finite index $\Gamma < \pi_1(\mathbb{S}^3 \setminus \text{figure-8})$ such that

$$\Gamma \hookrightarrow \text{Mod}(S)$$

with multitwists (Kent–Leininger, 2024)

- ② Combination theorem for Veech subgroups (Leininger–Reid, 2006)
- ③ More generally, “parabolically geometrically finite” subgroups (Dowdall–Durham–Leininger–Sisto, 2024) + (Udall, 2025)

Theorem (K.-Zimmer, 2025)

If $\langle \text{supp } \mu \rangle$ is relatively hyperbolic and contains a multitwist, then the μ -stationary meas. ν_{Hit} is singular to all PS-meas. of $\langle \text{supp } \mu \rangle$.

Proof Idea.

Establish

Tukia's generalization of Mostow's rigidity

for a wide class of group actions.

Theorem (K.-Zimmer, 2025)

If $\langle \text{supp } \mu \rangle$ is relatively hyperbolic and contains a multitwist, then
the μ -stationary meas. ν_{Hit} is singular to all PS-meas. of $\langle \text{supp } \mu \rangle$.

Proof Idea.

Establish

Tukia's generalization of Mostow's rigidity

for a wide class of group actions.

Crucial facts:

- ① Contracting property of the axis of a p-A in $\mathcal{T}(S)$ (Minsky, 1996)
- ② Linear growth in Cayley($\text{Mod}(S)$) (Farb–Lubotzky–Minsky, 2001)



Metric Structures on Groups

Robbie Lyman
Rutgers Univ-Newark

(GATSBY 2025)

We like group actions on metric spaces!

Problem: Want to study "all" $G \curvearrowright (X, d)$
(continuously) by isometries for a fixed G .

We like group actions on metric spaces!

Problem: Want to study "all" $G \curvearrowright (X, d)$ (continuously) by isometries for a fixed G .

$\forall x \in X$, define $d_{X,x} : G \times G \rightarrow \mathbb{R}$ by

$$d_{X,x}(g, h) = d_x(g \cdot x, h \cdot x)$$

this is a continuous, left-invariant pseudo-metric on G !

Solution: Consider

$$\text{PMet}(G) = \{ d : G \times G \rightarrow \mathbb{R} : d \text{ is left-inv. pseudometric} \}$$

Observe that $\text{PMet}(G)$ is preordered: say

$$d \geq d' \text{ when } id : (G, d) \longrightarrow (G, d')$$

is coarsely Lipschitz.

NB: $d + d' \in \text{PMet}(G)$, so if $\text{PMet}(G)$ has a maximal (pseudo)-metric, it has a maximum, which is an invariant of G .

Notice that if $A \subset G$ is d -bounded and $d \geq d'$, then A is d' -bounded.

Def (Rosendal) $A \subset G$ is coarsely bounded if it is d -bounded $\forall d \in \text{PMet}(G)$.

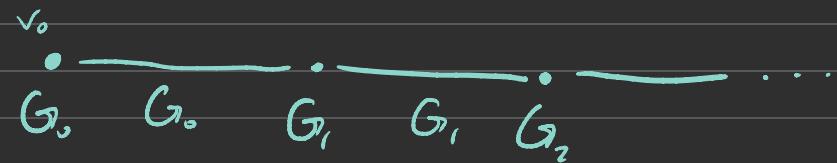
Prop (Rosendal, Milnor-Schwarz) Suppose $G \curvearrowright X$ geodesic is cobounded and $\forall x \in X, \epsilon > 0$, the set

$$\{g \in G : g.B_\epsilon(x) \cap B_\epsilon(x) \neq \emptyset\}$$

is coarsely bounded in G . Then $d_{X,x}$ is maximal in $\text{PMet}(G)$.

Prop (Rosendal, Serre) If $G_0 \subsetneq G_1 \subsetneq \dots$ is a proper ascending chain of open subgroups s.t. $G = \bigcup_{i=0}^{\infty} G_i$. Then $\text{PMet}(G)$ has no maximal metric.

Pf (Sketch) $G \cap T$ w/ quotient



but each d_{T,v_0} -bounded subset of G lives in some G_{n_k} , so no coarsely bounded set generates G !

Finite covers and A-polynomials

Youheng Yao

Yale University

joint work with Tam Cheetham-West
Apr 26th 2025

Profinite Completion

- Let M be a finite-volume hyperbolic 3-manifold.
- Consider the profinite completion

$$\widehat{\pi_1(M)} = \varprojlim \pi_1(M)/N$$

with $[\pi_1(M) : N] < \infty$.

Profinite Completion

- Let M be a finite-volume hyperbolic 3-manifold.
- Consider the profinite completion

$$\widehat{\pi_1(M)} = \varprojlim \pi_1(M)/N$$

with $[\pi_1(M) : N] < \infty$.

Question

What properties of M are determined by $\widehat{\pi_1(M)}$?

A -polynomials

- Let M be a compact 3-manifold with a single torus boundary.
- For $\rho \in R(M) = \text{Hom}(\pi_1(M), SL(2, \mathbb{C}))$, it can be conjugated so that

$$\rho(\mathcal{M}) = \begin{pmatrix} m & * \\ 0 & m^{-1} \end{pmatrix}, \quad \rho(\mathcal{L}) = \begin{pmatrix} I & * \\ 0 & I^{-1} \end{pmatrix}$$

where $\langle \mathcal{M}, \mathcal{L} \rangle$ is a basis of $\pi_1(\partial M)$.

A -polynomials

- Let M be a compact 3-manifold with a single torus boundary.
- For $\rho \in R(M) = \text{Hom}(\pi_1(M), SL(2, \mathbb{C}))$, it can be conjugated so that

$$\rho(\mathcal{M}) = \begin{pmatrix} m & * \\ 0 & m^{-1} \end{pmatrix}, \quad \rho(\mathcal{L}) = \begin{pmatrix} I & * \\ 0 & I^{-1} \end{pmatrix}$$

where $\langle \mathcal{M}, \mathcal{L} \rangle$ is a basis of $\pi_1(\partial M)$.

- Projection map

$$\begin{aligned} p : R(M) &\rightarrow \mathbb{C}^2 \\ \rho &\mapsto (I, m) \end{aligned}$$

- The A -polynomial $A^M(I, m)$ is a two-variable polynomial generating the Zariski closure of $\text{im } p$ excluding 0-dim components.

Main Result

Theorem (Cheetham-West-Y)

Let M, N be one-cusped finite-volume hyperbolic 3-manifolds. Suppose there is a regular profinite isomorphism

$$\Phi : \widehat{\pi_1(M)} \cong \widehat{\pi_1(N)}$$

Then:

Main Result

Theorem (Cheetham-West-Y)

Let M, N be one-cusped finite-volume hyperbolic 3-manifolds. Suppose there is a regular profinite isomorphism

$$\Phi : \widehat{\pi_1(M)} \cong \widehat{\pi_1(N)}$$

Then:

- Φ induces an isomorphism between $\pi_1(\partial M) \rightarrow \pi_1(\partial N)$ mapping the basis $\langle L, M \rangle$ to the basis $\langle L', M' \rangle$ such that

$$A^M(l, m) = A^N(l, m)$$

under these bases.

Main Result

Theorem (Cheetham-West-Y)

Let M, N be one-cusped finite-volume hyperbolic 3-manifolds. Suppose there is a regular profinite isomorphism

$$\Phi : \widehat{\pi_1(M)} \cong \widehat{\pi_1(N)}$$

Then:

- Φ induces an isomorphism between $\pi_1(\partial M) \rightarrow \pi_1(\partial N)$ mapping the basis $\langle L, M \rangle$ to the basis $\langle L', M' \rangle$ such that

$$A^M(l, m) = A^N(l, m)$$

under these bases.

- There is a bijection between the strongly detected boundary slopes from the $SL(2, \mathbb{C})$ -character varieties.

Main Result

In the multi-cusp case, there is a similar result.

Theorem (Cheetham-West-Y)

Let M, N be multi-cusped finite-volume hyperbolic 3-manifolds. Suppose there is a regular profinite isomorphism

$$\widehat{\Phi} : \widehat{\pi_1(M)} \cong \widehat{\pi_1(N)}$$

there is a bijection between the strongly detected boundary curves from the $SL(2, \mathbb{C})$ -character varieties.

Main Result

Thank you!

On Matroids and the 1- System of Curves on Surfaces.

Marwa A. Mosallam

Cairo Univ. & Binghamton Univ.

April 26, 2025



- 1 The 1- System of Curves on Surfaces
- 2 Matroids
- 3 Graphs, Curves & The Matroid Intersection Theorem
- 4 Our Main Question

1 The 1- System of Curves on Surfaces

Definition

Problem Setup

Open Problem

2 Matroids

3 Graphs, Curves & The Matroid Intersection Theorem

4 Our Main Question

1 The 1- System of Curves on Surfaces

Definition

Problem Setup

Open Problem

2 Matroids

3 Graphs, Curves & The Matroid Intersection Theorem

4 Our Main Question

Definition & Problem Setup

- Let S_g be a connected, closed, oriented surface of genus g .
Let Γ be a set of essential, simple closed curves on the surface S_g , such that:
 - No two curves are homotopic (or isotopic we are not strict about this yet).
 - Each two curves intersect at at most one point.

Call such a set of curves a 1-System of curves on S_g .

1 The 1- System of Curves on Surfaces

Definition

Problem Setup

Open Problem

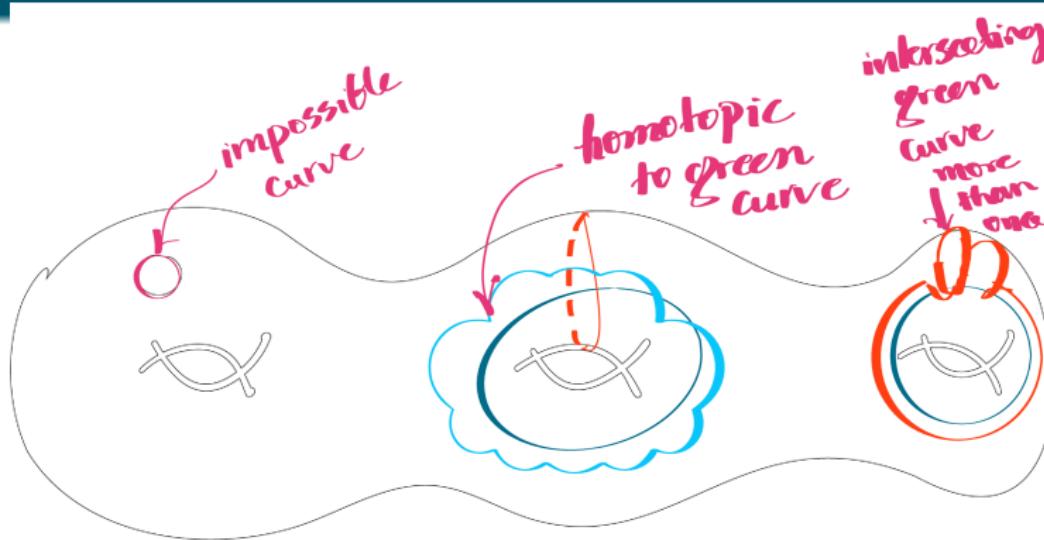
2 Matroids

3 Graphs, Curves & The Matroid Intersection Theorem

4 Our Main Question



Inessential Curves & curves intersecting more than once are not allowed





① The 1- System of Curves on Surfaces

Definition

Problem Setup

Open Problem

② Matroids

③ Graphs, Curves & The Matroid Intersection Theorem

④ Our Main Question

Open Problem

Determine or Estimate how large a 1-System of curves on a surface can be?

1 The 1- System of Curves on Surfaces

2 Matroids

Tropical Manifolds & Bergman Fan of a Matroid

Definition

3 Graphs, Curves & The Matroid Intersection Theorem

4 Our Main Question

1 The 1- System of Curves on Surfaces

2 Matroids

Tropical Manifolds & Bergman Fan of a Matroid

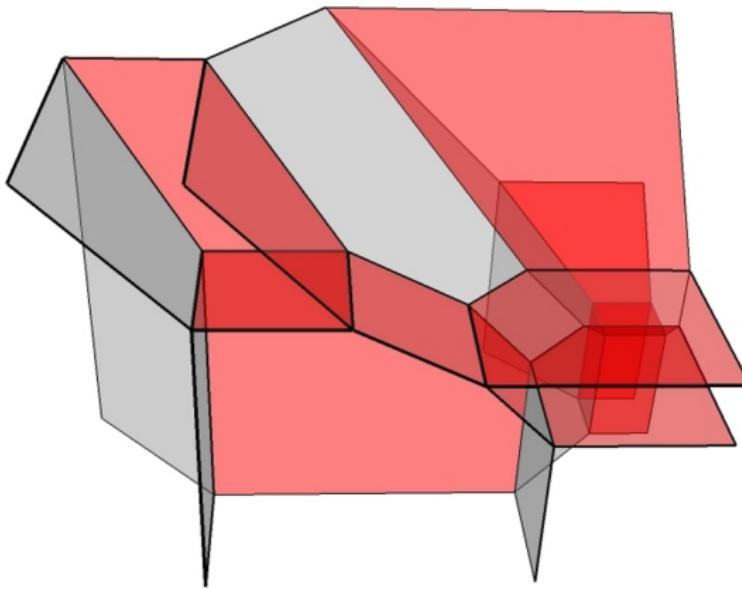
Definition

3 Graphs, Curves & The Matroid Intersection Theorem

4 Our Main Question



Tropical Manifolds & Bergman Fan of a matroid



1 The 1- System of Curves on Surfaces

2 Matroids

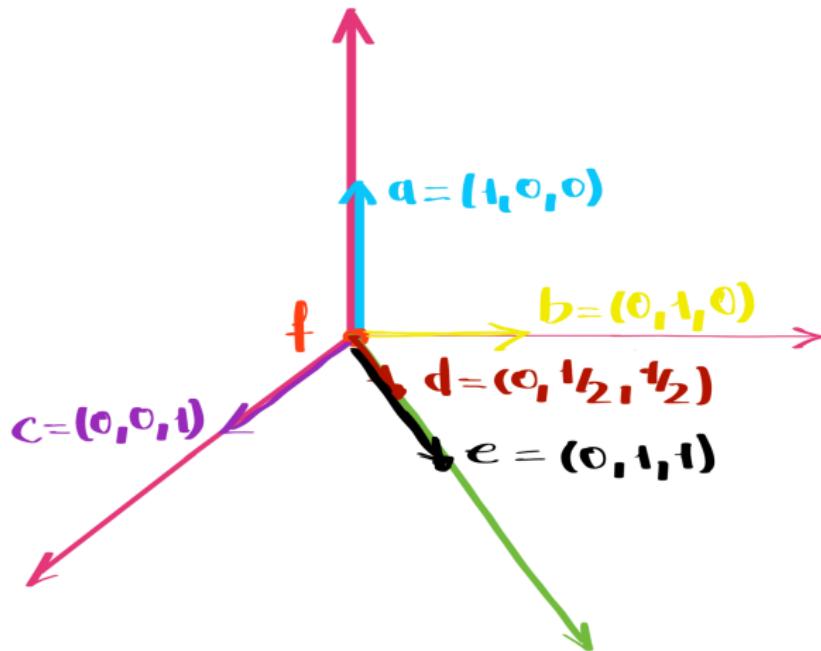
Tropical Manifolds & Bergman Fan of a Matroid

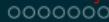
Definition

3 Graphs, Curves & The Matroid Intersection Theorem

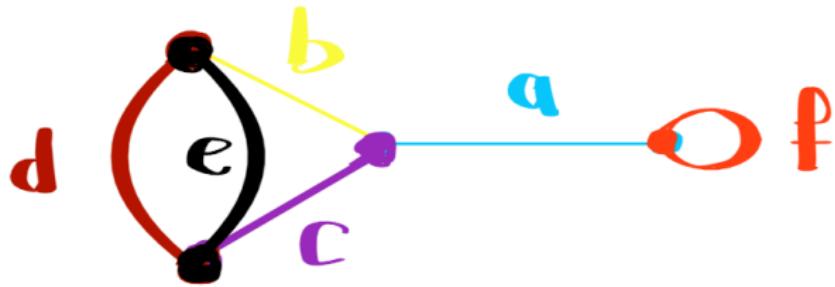
4 Our Main Question

Some Motivating Examples for Matroids





Some Motivating Examples for Matroids



Independent Sets in case of the V.C. & the Graph

Matroid theory will give us a background to attack both problems at the same time as one matroid. The list of independent sets in case of V.C. is:

- \emptyset, a, b, c, d, e
- ab, ac, ad, ae, bc, bd, be, ad, ce
- abc, abd, abe, acd, ace

Notice that this independent list is the same for the previous V.C. and Graph.

1 The 1- System of Curves on Surfaces

2 Matroids

Tropical Manifolds & Bergman Fan of a Matroid

Definition

3 Graphs, Curves & The Matroid Intersection Theorem

4 Our Main Question



Definition

A matroid M is an ordered pair (E, \mathcal{I}) consisting of a finite (not necessarily but for the sake of our purposes it is finite) set E and a collection \mathcal{I} of subsets of E (its members are the independent sets of M) having the following three properties:

- (I1) $\emptyset \in \mathcal{I}$
- (I2) If $I \subset J$ and $J \in \mathcal{I}$, then $I \in \mathcal{I}$.
- (I3) If $I, J \in \mathcal{I}$, and $|I| < |J|$, then there is $j \in J - I$ such that $I \cup \{j\} \in \mathcal{I}$. "Exchange Axiom"

① The 1- System of Curves on Surfaces

② Matroids

③ Graphs, Curves & The Matroid Intersection Theorem

Edmonds' Matroid Intersection Theorem

T. Aougab, T. Huynh & The Matroid Intersection Theorem

④ Our Main Question

1 The 1- System of Curves on Surfaces

2 Matroids

3 Graphs, Curves & The Matroid Intersection Theorem

Edmonds' Matroid Intersection Theorem

T. Aougab, T. Huynh & The Matroid Intersection Theorem

4 Our Main Question

Edmonds' Matroid Intersection Theorem

- If M_1 and M_2 are two matroids on the same ground set E . We attempt to define a new matroid $M_1 \cap M_2$ as follows: $I \subseteq E$ is independent in $M_1 \cap M_2$ if $I = I_1 \cap I_2$, where I_1 is independent in M_1 and I_2 is independent in M_2 . Note, in general, the intersection of two matroids is not necessarily a matroid but still if

$$\mathcal{I}_1 \cap \mathcal{I}_2 := \{I_1 \cap I_2 \mid I_1 \in \mathcal{I}_1 \text{ and } I_2 \in \mathcal{I}_2\},$$

it is an important problem to find the largest independent set in $\mathcal{I}_1 \cap \mathcal{I}_2$ (**In our problem this refers to the total number of colors**).

- Let $I \in \mathcal{I}_1 \cap \mathcal{I}_2$ and let $A \subseteq E$, then we can show that

$$|I| \leq r_1(A) + r_2(E \setminus A)$$

where r_1 is the rank function (the size of the largest independent subset) for M_1 and r_2 is the rank function for M_2 .





Edmonds' Matroid Intersection Theorem

- And from the previous bullet we can conclude that

$$\max_{I \in \mathcal{I}_1 \cap \mathcal{I}_2} |I| \leq \min_{A \subseteq E} (r_1(A) + r_2(E \setminus A))$$

The equality above is **Edmonds' Matroid Intersection Theorem**.

- we are actually using the following version in our research, for every $A \subseteq E$

$$\max_{I \in \mathcal{I}_1 \cap \mathcal{I}_2} |I| \leq (r_1(A) + r_2(E \setminus A)) \quad (*)$$

where **total number of colors** $t = \max_{I \in \mathcal{I}_1 \cap \mathcal{I}_2} |I|$.

1 The 1- System of Curves on Surfaces

2 Matroids

3 Graphs, Curves & The Matroid Intersection Theorem

Edmonds' Matroid Intersection Theorem

T. Aougab, T. Huynh & The Matroid Intersection Theorem

4 Our Main Question

- T. Aougab *Existence of a connected total rainbow subgraph.*
 - T. Huynh *Matroid Intersection Theorem*

by defining a set to be independent in the first matroid M_1 iff it contains at most one edge of each color and a set to be independent in the second matroid M_2 iff it does not contain a cycle.



1 The 1- System of Curves on Surfaces

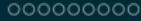
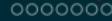
2 Matroids

3 Graphs, Curves & The Matroid Intersection Theorem

4 Our Main Question

Our Main Question

Given t and K_n for some n ,
when do edge colored complete
graphs satisfy relation (*)
above?



Thanks For Your Attention!
Questions?

Skinning Maps of Geometric Limits

Sungjin Park (Yale)

April 2025

Brief Deformation Theory of Kleinian Groups

Let M be a compact oriented hyperbolizable 3-manifold with incompressible boundary components S_1, \dots, S_k with $\chi(S_i) < 0$ for all i .

Theorem (Ahlfors, Bers, Marden, Sullivan, \dots)

The set of convex cocompact hyperbolic structures on the interior of M is parametrized by $\prod_{i=1}^k \mathcal{T}(S_i)$.

Example (quasi-Fuchsian group, Bers parametrization)

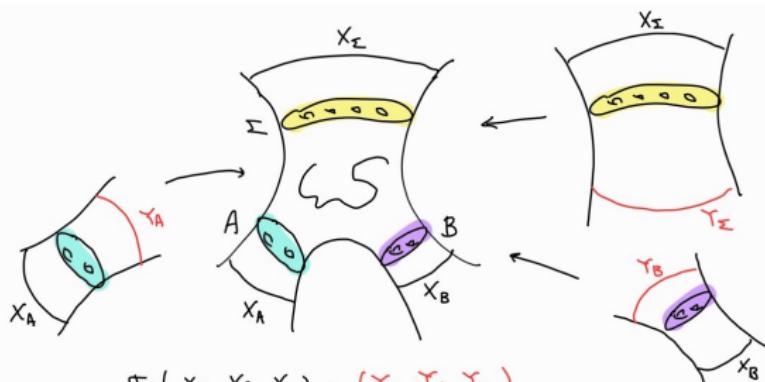
If $M = S \times [0, 1]$, $\text{QF}(S) \cong \mathcal{T}(S) \times \mathcal{T}(\bar{S})$.

Skinning Map

Definition (Skinning map)

The **skinning map** $\sigma_M : \prod_{i=1}^k \mathcal{T}(S_i) \rightarrow \prod_{i=1}^k \mathcal{T}(\overline{S_i})$ is defined as follows:
Let $M(X)$ be the hyperbolic structure of M determined by
 $X \in \prod_{i=1}^k \mathcal{T}(S_i)$. Then, $\sigma_M(X)$ is the tuple of conformal structures of
'inward-pointing' end of covers of $M(X)$ associated to each $\pi_1(S_i)$.

The cover associated to $\pi_1(S_i)$ is quasi-Fuchsian by Thurston's covering theorem.



Skinning Map

Theorem (Bounded Image Theorem, Thurston, Kent)

If M is acylindrical, the image of σ_M has compact closure.

Conjecture (Minsky)

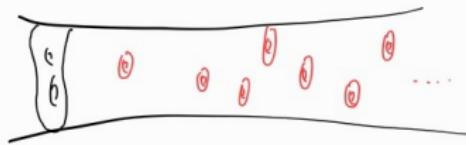
The Teichmüller diameter of the image of σ_M is bounded by the constant only depends on the topology of ∂M .

Geometric Limit

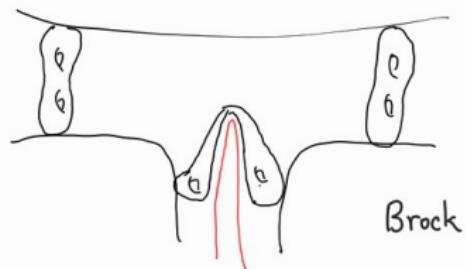
Definition

A sequence (M_n, p_n) of manifolds with base points converges geometrically to (M, p) if there exist $K_n \rightarrow 1$, $r_n \rightarrow \infty$ such that there exist smooth maps $\psi_n : (B_M(p, r_n), p) \rightarrow (M_n, p_n)$ which is K_n -bilipschitz to the image.

Examples (geometric limits of Kleinian surface groups)



Kerckhoff - Thurston



Brock

Setting for the theorem

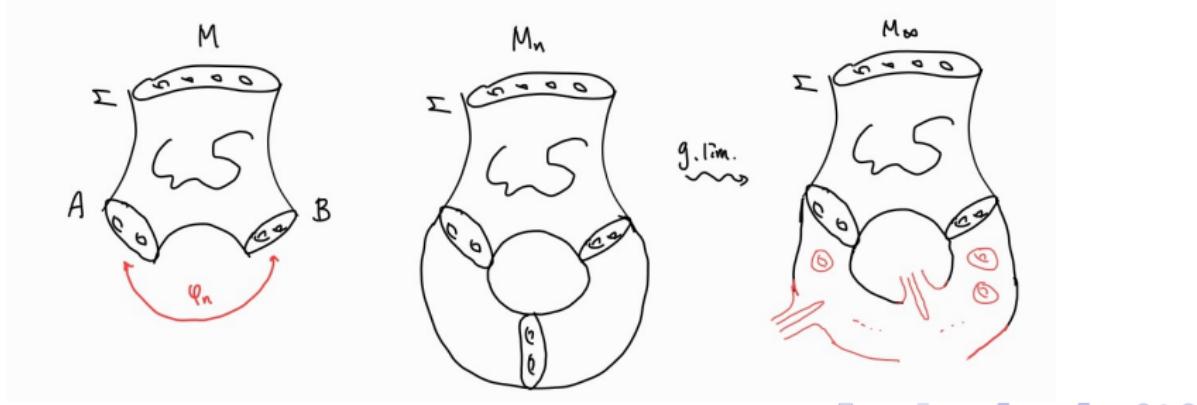
Setting

M : compact oriented hyperbolizable 3-manifold with three incompressible boundary components Σ , A and B , where A and B have same genus.

φ_n : gluing maps between A and B .

M_n : the manifold constructed from M by gluing A and B by φ_n .

M_∞ : a geometric limit of $M_n(X)$ with a fixed conformal structure X on Σ .

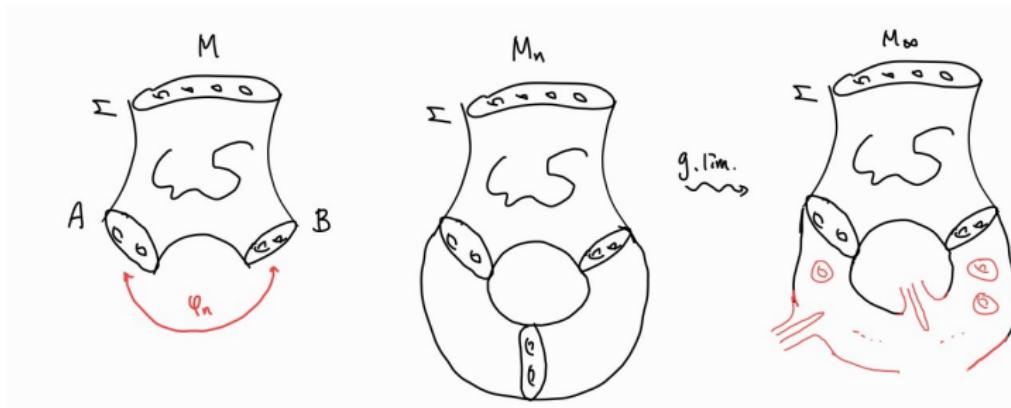


Main Result (In Progress)

Theorem

Assume that $\sigma_{M_n}, \sigma_{M_\infty} : \mathcal{T}(\Sigma) \rightarrow \mathcal{T}(\overline{\Sigma})$ are ‘well-defined’. Then,

- (a) σ_{M_n} converges pointwise to σ_{M_∞} .
- (b) If M is acylindrical, $\overline{\text{image}(\sigma_{M_n})} \rightarrow \overline{\text{image}(\sigma_{M_\infty})}$.
- (c) If M is a book of I-bundle and each M_n is acylindrical, then
 $\overline{\text{image}(\sigma_{M_n})} \rightarrow \overline{\text{image}(\sigma_{M_\infty})}$.



The Mapping Class Group of Graphs

From Tree Branches to Spiderwebs

Rocky Klein

Brandeis University

klein@brandeis.edu

April 26, 2025

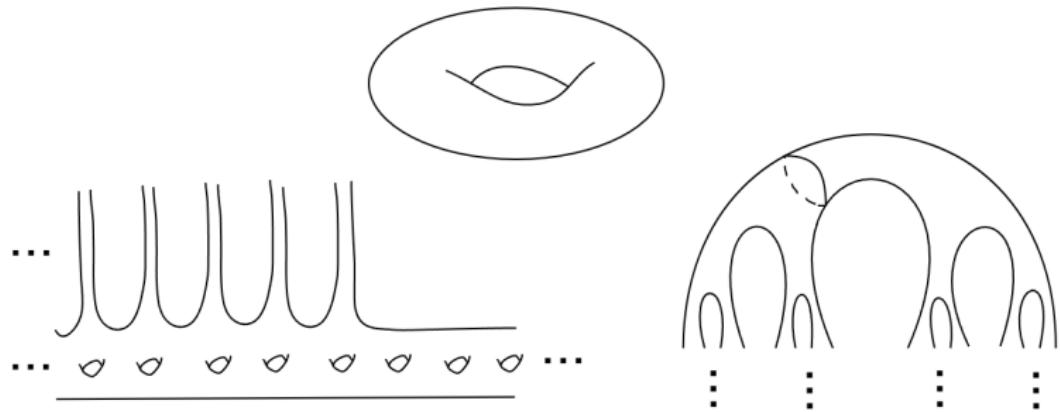
Mapping class group for surfaces

Definition (Mapping class group for surfaces)

The *mapping class group* of a closed orientable surface S is

$$\text{Mod}(S) = \text{Homeo}^+(S)/\text{Homeo}_0(S)$$

Orientation-preserving homeomorphisms modulo isotopy.

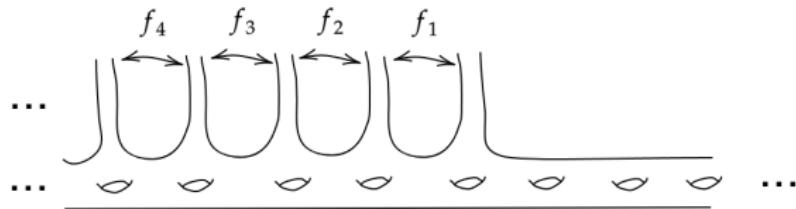


Topology

Definition

We endow $\text{Homeo}^+(S)$ with the compact-open topology, and equip $\text{Mod}(S)$ with the quotient topology.

Elements of $\text{Maps}(S)$ are closer together if they agree on larger compact sets.



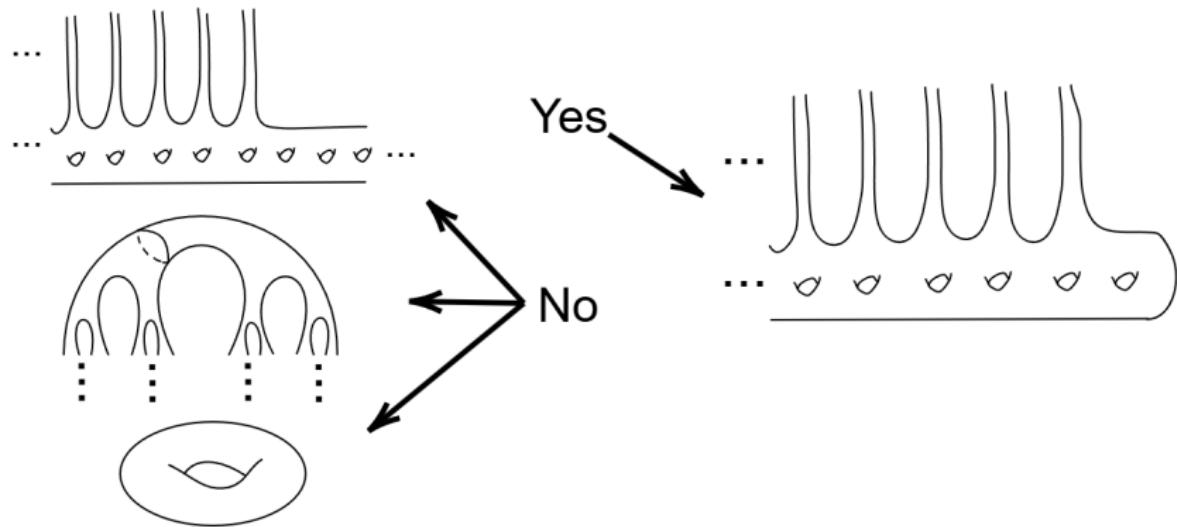
$f_i \rightarrow id$ since the ends swapped get further away.

Dense Conjugacy Classes of Surfaces

Question

Given S , does $\text{Mod}(S)$ have a dense conjugacy class?

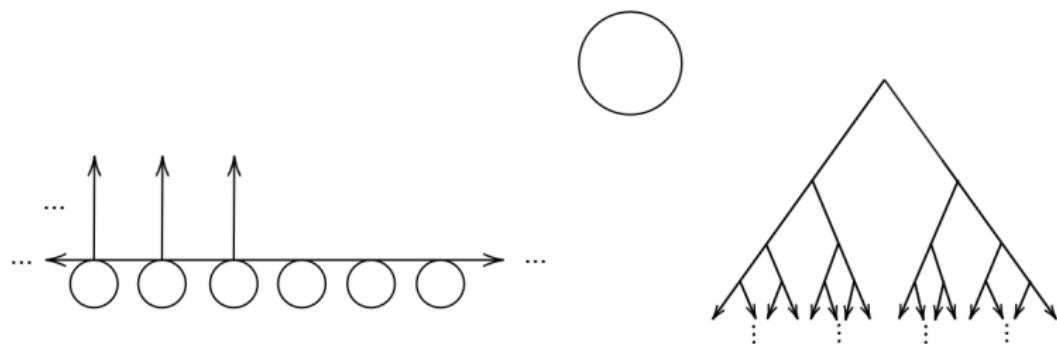
A complete classification was obtained by Lanier and Vlamis, and also by Hernández Hernández, Hrušák, Morales, Randecker, Sedano, and Valdez.



Mapping class group for graphs

Definition (Mapping class group for graphs)

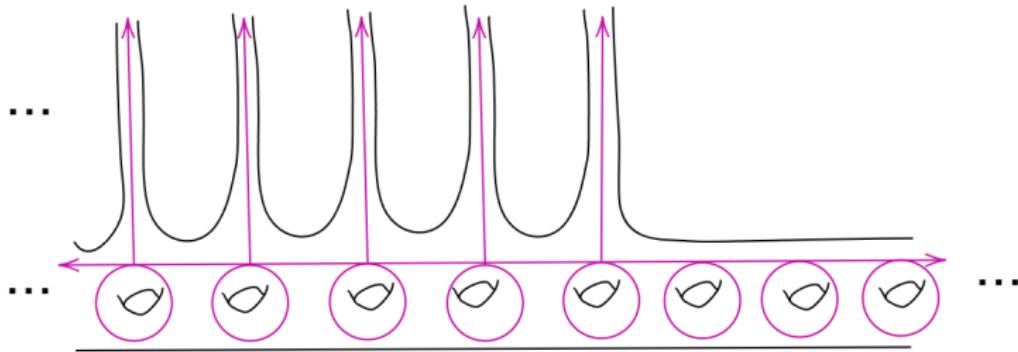
Let X be a locally finite graph. The *mapping class group of X* , denoted $\text{Maps}(X)$, is the group of proper homotopy equivalences of X , modulo proper homotopy.



The topology is similar to a quotient of the compact-open topology, but a little more work is required.

Locally Finite Graphs Mirror Surfaces and $\text{Out}(F_n)$

Surfaces: “A 1-D version of $\text{Mod}(S)$ ”



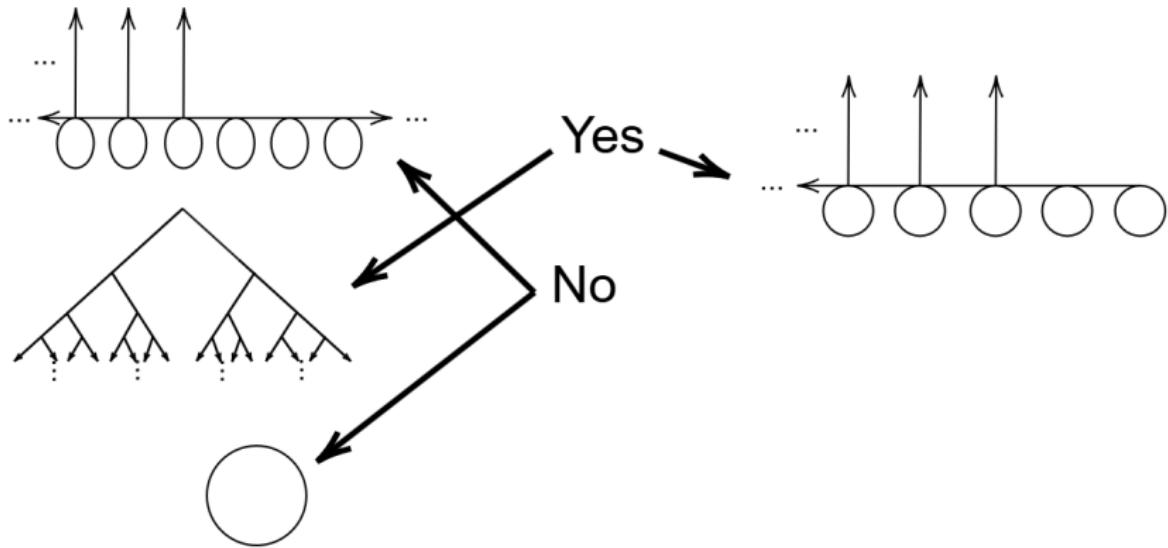
$\text{Out}(F_n)$: “A BIG version of $\text{Out}(F_n)$ ” (Colloquially named **Big Out**)

If a graph X is finite, then $\text{Maps}(X) \cong \text{Out}(F_{\text{rk}(\pi_1(X))})$

Dense Conjugacy Classes of Graphs

Question

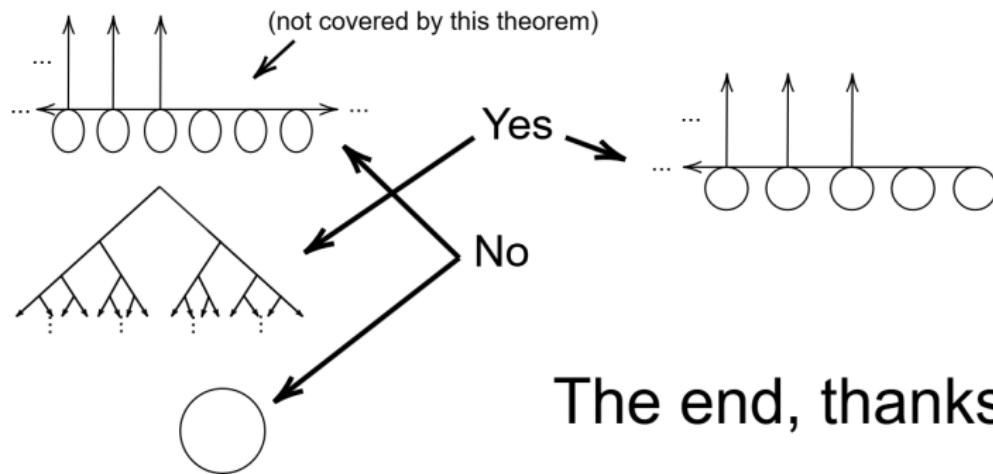
Given X , does $\text{Maps}(X)$ have a dense conjugacy class?



Given X , does $\text{Maps}(X)$ have a dense conjugacy class?

Theorem (K, trying to generalize)

Let X be a stable self-similar locally finite graph. Then $\text{Maps}(X)$ has a dense conjugacy class if and only if X is proper homotopy equivalent to the Cantor tree, or both the genus of X is zero or infinite, and the graph X has a unique maximal end.



The transitivity of pure Hurwitz classes of dynamical branched covers of the sphere



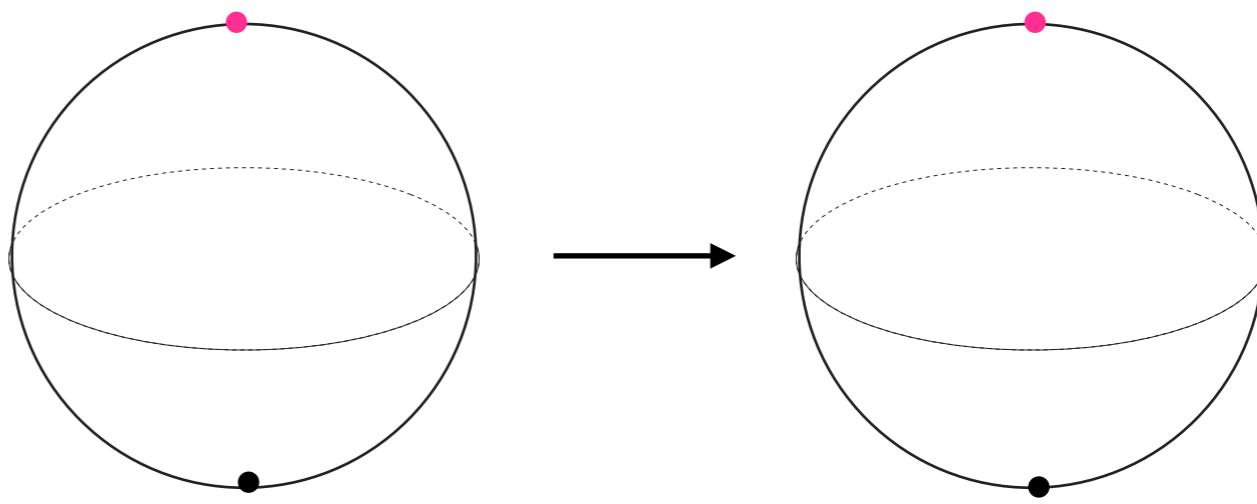
Becca Winarski
College of the Holy Cross

Joint with Yvon Verberne

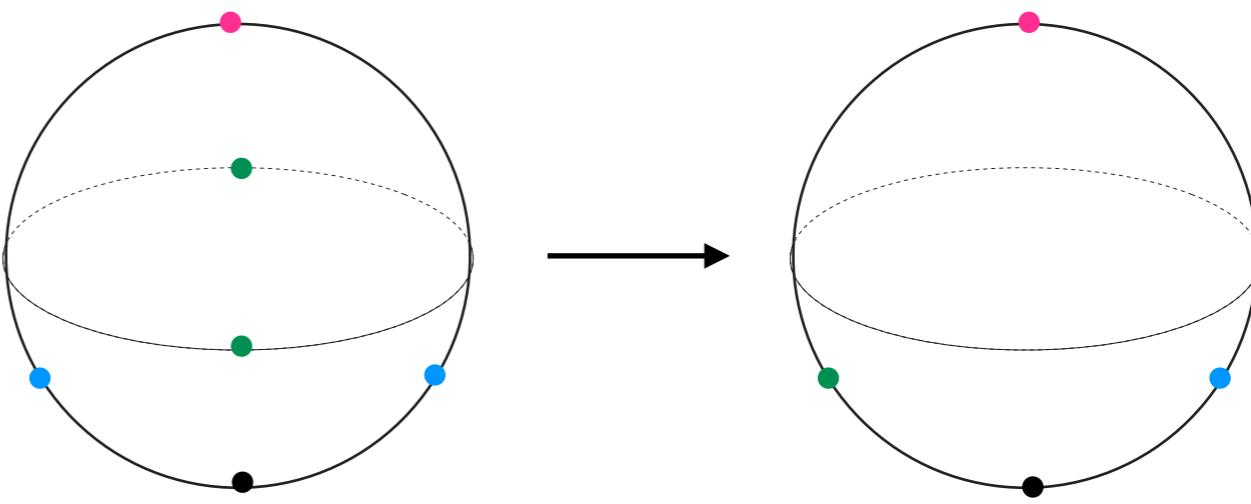
Goal

Invitation: Translate your favorite questions and techniques about mapping classes and branched covers to a dynamical setting

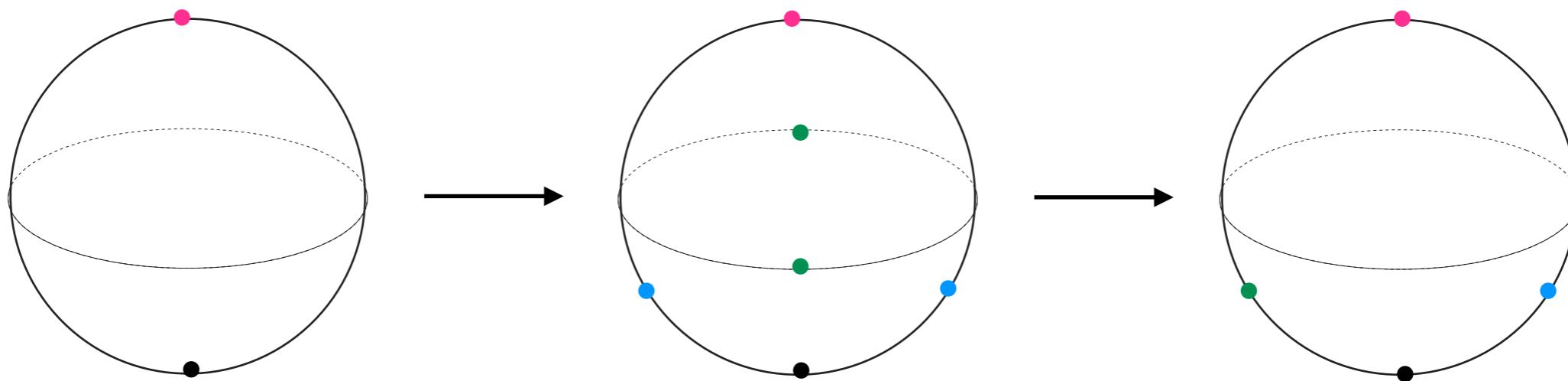
Dynamical Branched Covers



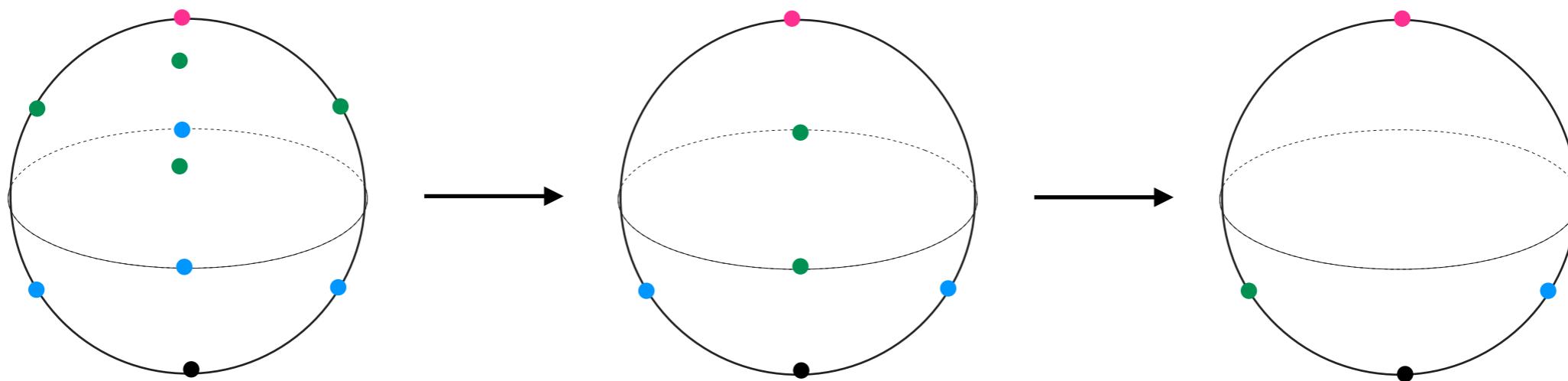
Dynamical Branched Covers



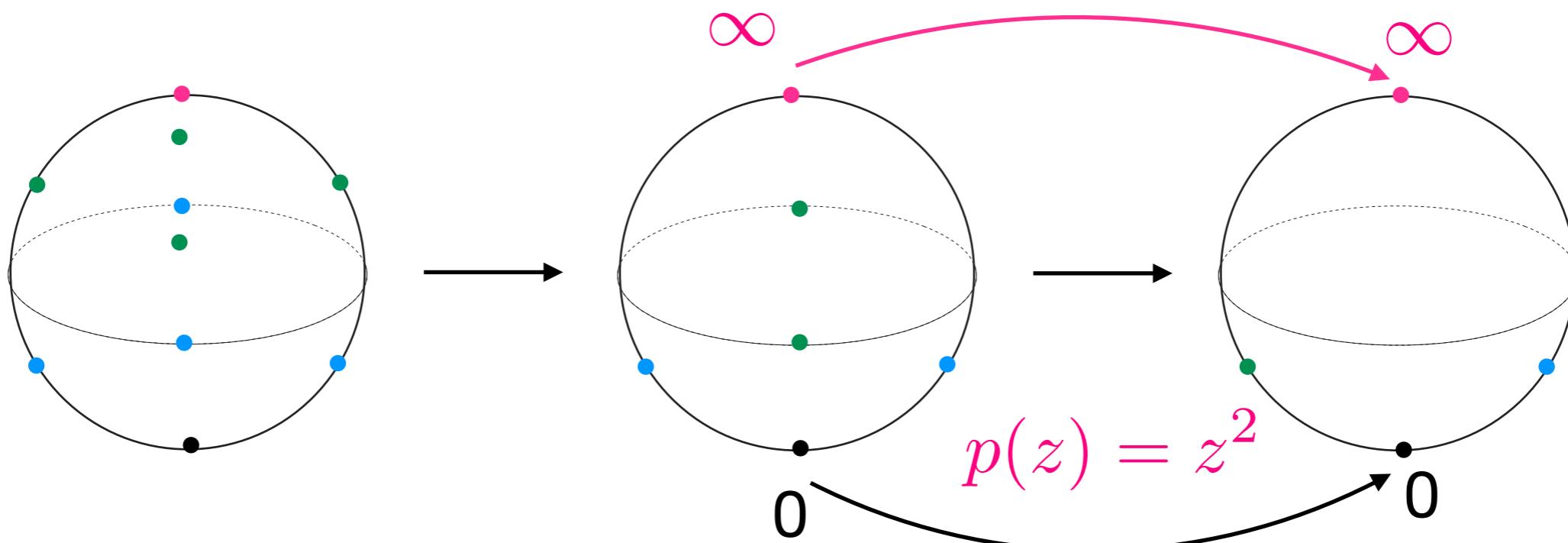
Dynamical Branched Covers



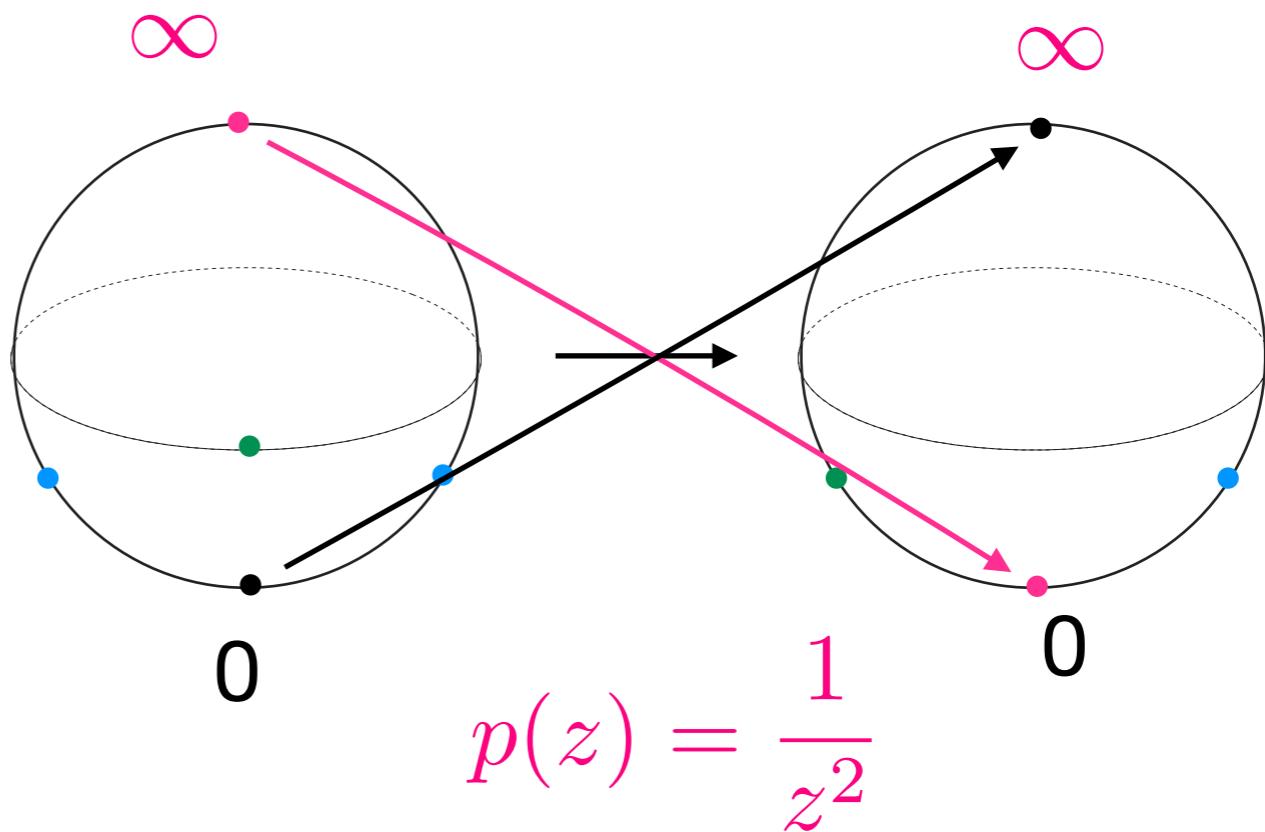
Dynamical Branched Covers



More examples: polynomials!



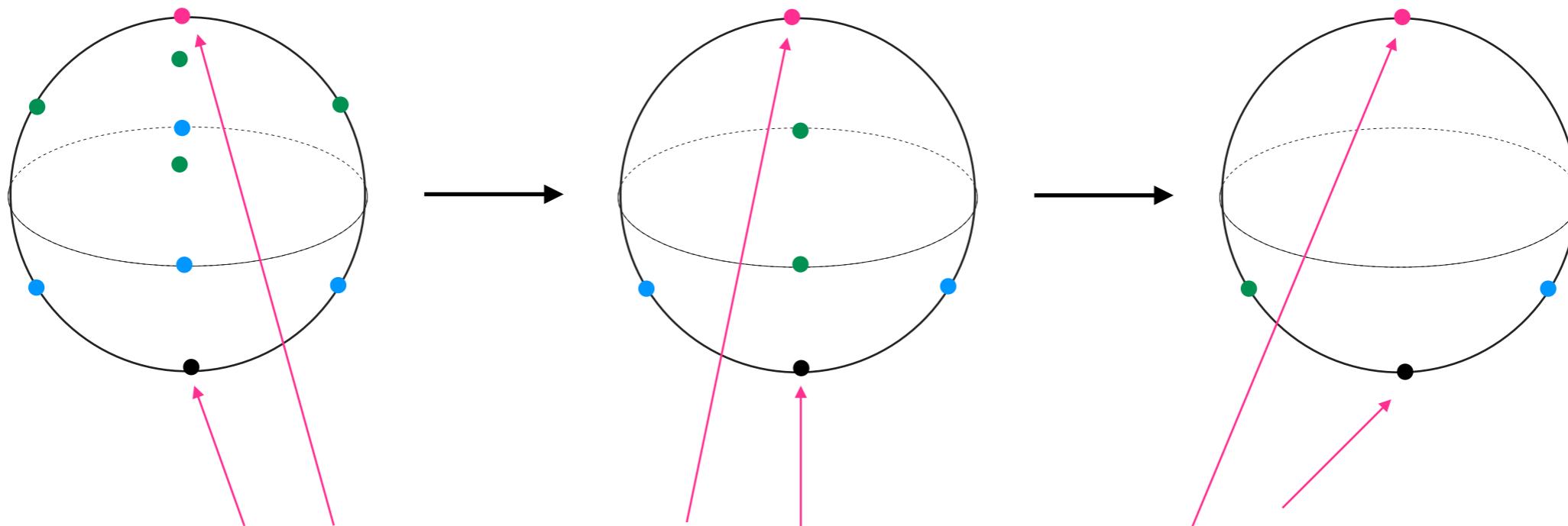
More examples: rational maps



$\infty \mapsto 0$

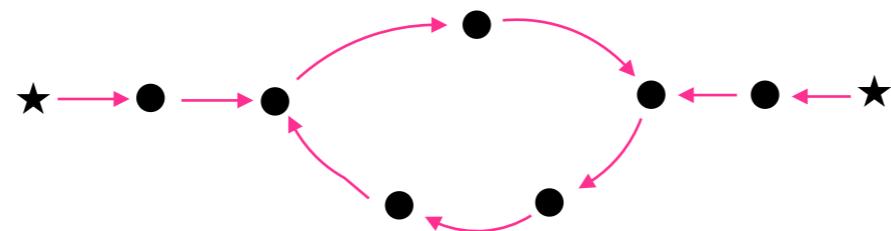
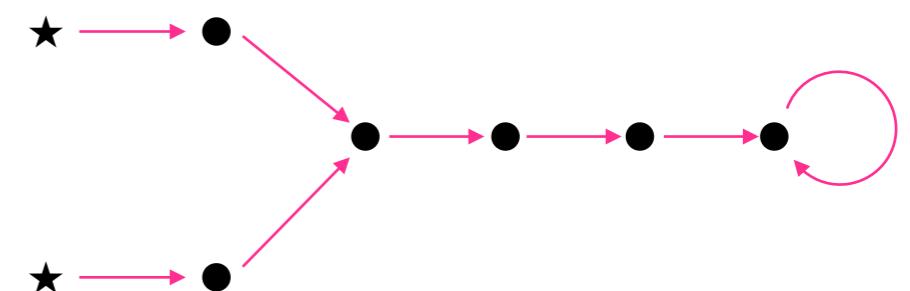
$0 \mapsto \infty$

Dynamical Branched Covers



Post-critical set=(entire) forward orbit of critical (ramified) points

Dynamical Portraits



Main Result

Theorem (Verberne–W)

$f, g : S^2 \rightarrow S^2$ degree 2 branched covers. Then there exists some finite set of points M and mapping class $\phi \in \text{Mod}(S^2, M)$ so that g and $f\phi$ have the same portrait.

Main Result

Theorem (Verberne–W)

$f, g : S^2 \rightarrow S^2$ degree 2 branched covers. Then there exists some finite set of points M and mapping class $\phi \in \text{Mod}(S^2, M)$ so that g and $f\phi$ have the same portrait.

In particular, we develop an algorithm to find M and ϕ

What's new?

Complex dynamics usually focuses on the action of *pure* mapping classes on post-critically finite branched covers because they don't change the portrait.

This is a tool to pursue the study of the action of *all* mapping classes on post-critically finite branched covers.

This is the beginning

Our result: Composing by mapping classes allows you to move between (all) portrait classes.

Purely combinatorial (symmetric groups not braid groups)

Questions:

If you track the braid, not just the permutation, can you move between combinatorial classes (a finer relation)?

Which portraits (sometimes/never) have obstructions?

Are there certain twists that lead to obstructions – can we predict them?