

Benat Froemming-Aldanondo

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EDUCATION

University of Minnesota, Minneapolis, US

Bachelor's of Science in Data Science, Computer Science & Engineering Department

September 2021 — May 2025

Cumulative GPA: 3.712/4.00

Relevant Courses: Software Engineering, Data Structures & Algorithms, Computer and Database Systems, Machine Learning Fundamentals, Linear Algebra, Intro to AI, Data Mining, Optimization, Deep Learning, Natural Language Processing, and Computer Vision.

University of Minnesota, Minneapolis, US

Master's of Science in Computer Science, Computer Science & Engineering Department

September 2025 — 2026

SKILLS

Python, Java, C/C++, R, SQL, Algorithms, Web Development, Linux, Github, PostgreSQL, Machine Learning, ROS, OpenCV, LaTeX, Statistics, Spanish

PROFESSIONAL EXPERIENCE

Undergraduate Researcher

Minnesota Robotics Institute, Maria Gini's Group

Minneapolis, Minnesota

September 2024 – December 2024

- Developed an object-oriented simulation framework in Python to evaluate multi-agent vehicle coordination algorithms.
- Designed and implemented a novel deep reinforcement learning algorithm in PyTorch, achieving a 21% increase in traffic capacity.

Research Intern

National Science Foundation - Michigan State University & Lawrence Tech University

Detroit, Michigan

May 2024 — August 2024

- Designed, deployed, and validated lane-following and adaptive speed algorithms on real drive-by-wire vehicles using C++ with ROS, reducing acceleration and braking at intersections by up to 75.35% compared to human drivers.
- Developed novel vision-based lane-following algorithms in Python utilizing OpenCV, unsupervised clustering techniques, and deep learning models for enhanced performance.
- Collaborated with a team of research interns, leading development efforts and managing version control with GitHub, resulting in a successful submission to a top-tier conference.
- Built a cost-effective roadside unit using a Raspberry Pi (Linux Ubuntu) and Arduino for vehicle-to-everything (V2X) communication.

PROJECTS

Backend Lead, Major Planner Project, Social Coding Club

January 2024 – May 2024

- Developed a web application using Python and Flask to assist students in identifying the optimal majors based on their preferences.
- Extracted data from the university's database in JSON format and implemented a robust data cleaning pipelines in Python.
- Created a custom recommendation algorithm to provide tailored suggestions for students.

Motion & Mapping Lead, Micro Mouse Robot, IEEE Club

September 2024 – Present

- Building an autonomous robot from scratch using a microcontroller, motors, and sensors for maze traversal.
- Developing and optimizing pathfinding algorithms (Dijkstra's, A*, DFS, Floodfill) for autonomous maze-solving, both in simulation and on the real robot using Python and C++.

Flag Guessing Web App

December 2022 – Present

- Designed and developed an interactive educational website for learning world flags using HTML, CSS, and JavaScript, reaching 1000+ users.

Course Projects

September 2021 – Present

- Implemented a feed-forward neural network with backpropagation from scratch in Python, utilizing Numpy, Pandas, and Matplotlib to classify handwritten digits from the MNIST dataset, achieving 92% accuracy on test data.
- Developed the Wordle game in Java, adhering to object-oriented programming principles and providing a user-friendly interface.
- Performed exploratory data analysis with R and Python on the COVID-19 World Health Organization dataset and applied supervised and unsupervised machine learning models to predict propagation trends.
- Extracted key insights about a flight network using SQL and PostgreSQL, enhancing operational efficiency as part of an air control system and optimizing route networks and pricing strategies using Julia.
- Understood and modified PostgreSQL's backend in C to implement a custom buffer replacement policy.
- Designed and implemented a heuristic algorithm based on A* to solve the coverage path planning problem, achieving optimal results significantly faster than exhaustive search methods.