view\_frames Result Recorded at time: 2024.387 map Broadcaster: /amcl Average rate: 15.139 Hz Most recent transform: 2024.876 (-0.489 sec old) Buffer length: 4.690 sec odom Broadcaster: /gazebo Average rate: 100.212 Hz Most recent transform: 2024.379 ( 0.008 sec old) Buffer length: 4.710 sec base\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 100.214 Hz Average rate: 41.469 Hz Average rate: 100.214 Hz Average rate: 41.469 Hz Average rate: 100.214 Hz Average rate: 41.469 Hz Most recent transform: 2024.842 (-0.455 sec old) Most recent transform: 2024.309 ( 0.078 sec old) Most recent transform: 2024.309 (0.078 sec old) Most recent transform: 2024.309 (0.078 sec old) Most recent transform: 2024.842 (-0.455 sec old) Most recent transform: 2024.842 (-0.455 sec old) Buffer length: 4.630 sec Buffer length: 4.630 sec Buffer length: 4.670 sec Buffer length: 4.670 sec Buffer length: 4.670 sec Buffer length: 4.630 sec torso\_lift\_link estop\_link laser\_link torso\_fixed\_link r\_wheel\_link l\_wheel\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 41.469 Hz Average rate: 100.214 Hz Average rate: 41.469 Hz Average rate: 41.469 Hz Most recent transform: 2024.842 (-0.455 sec old) Most recent transform: 2024.309 (0.078 sec old) Most recent transform: 2024.309 (0.078 sec old) Most recent transform: 2024.309 (0.078 sec old) Buffer length: 4.670 sec Buffer length: 4.630 sec Buffer length: 4.630 sec Buffer length: 4.630 sec bellows\_link2 bellows\_link shoulder\_pan\_link head\_pan\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 41.469 Hz Average rate: 41.469 Hz Most recent transform: 2024.309 (0.078 sec old) Most recent transform: 2024.309 (0.078 sec old) Buffer length: 4.630 sec Buffer length: 4.630 sec shoulder\_lift\_link head\_tilt\_link Broadcaster: /robot state publisher Broadcaster: /robot\_state\_publisher Average rate: 100.214 Hz Average rate: 41.469 Hz Most recent transform: 2024.842 (-0.455 sec old) Most recent transform: 2024.309 (0.078 sec old) Buffer length: 4.670 sec Buffer length: 4.630 sec head\_camera\_link upperarm\_roll\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 100.214 Hz Average rate: 41.469 Hz Average rate: 100.214 Hz Most recent transform: 2024.842 (-0.455 sec old) Most recent transform: 2024.842 (-0.455 sec old) Most recent transform: 2024.309 (0.078 sec old) Buffer length: 4.670 sec Buffer length: 4.670 sec Buffer length: 4.630 sec elbow\_flex\_link head\_camera\_depth\_frame head\_camera\_rgb\_frame Broadcaster: /robot\_state\_publisher Broadcaster: /robot state publisher Broadcaster: /robot\_state\_publisher Average rate: 100.214 Hz Average rate: 100.214 Hz Average rate: 41.469 Hz Most recent transform: 2024.842 (-0.455 sec old) Most recent transform: 2024.309 (0.078 sec old) Most recent transform: 2024.842 (-0.455 sec old) Buffer length: 4.670 sec Buffer length: 4.670 sec Buffer length: 4.630 sec head\_camera\_rgb\_optical\_frame head\_camera\_depth\_optical\_frame forearm\_roll\_link Broadcaster: /ar\_track\_alvar Broadcaster: /ar\_track\_alvar Broadcaster: /ar\_track\_alvar Broadcaster: /ar\_track\_alvar Broadcaster: /robot\_state\_publisher Average rate: 10.217 Hz Average rate: 10.217 Hz Average rate: 10.217 Hz Average rate: 9.783 Hz Average rate: 41.469 Hz Most recent transform: 2024.247 (0.140 sec old) Most recent transform: 2024.247 (0.140 sec old) Most recent transform: 2024.247 ( 0.140 sec old) Most recent transform: 2024.309 (0.078 sec old) Most recent transform: 2024.247 (0.140 sec old) Buffer length: 4.600 sec Buffer length: 4.600 sec Buffer length: 4.600 sec Buffer length: 4.600 sec Buffer length: 4.630 sec ar\_marker\_4 ar\_marker\_3 ar\_marker\_255 wrist\_flex\_link ar\_marker\_2 Broadcaster: /robot\_state\_publisher Average rate: 41.469 Hz Most recent transform: 2024.309 (0.078 sec old) Buffer length: 4.630 sec wrist\_roll\_link Broadcaster: /robot\_state\_publisher Average rate: 100.214 Hz Most recent transform: 2024.842 (-0.455 sec old) Buffer length: 4.670 sec gripper\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 41.469 Hz Average rate: 41.469 Hz Most recent transform: 2024.309 ( 0.078 sec old) Most recent transform: 2024.309 ( 0.078 sec old) Buffer length: 4.630 sec Buffer length: 4.630 sec l\_gripper\_finger\_link r\_gripper\_finger\_link