

## Exam 1 is in the books

- If you have any questions or comments on the grading, please let me know, office hours tomorrow at 10
- Grading scale to the right
- Test was out of 105, graded on 100 scale
- No curve
- Planned next exam for early March
- You should have received a survey this morning, please fill out
- Exam solutions posted to the drive

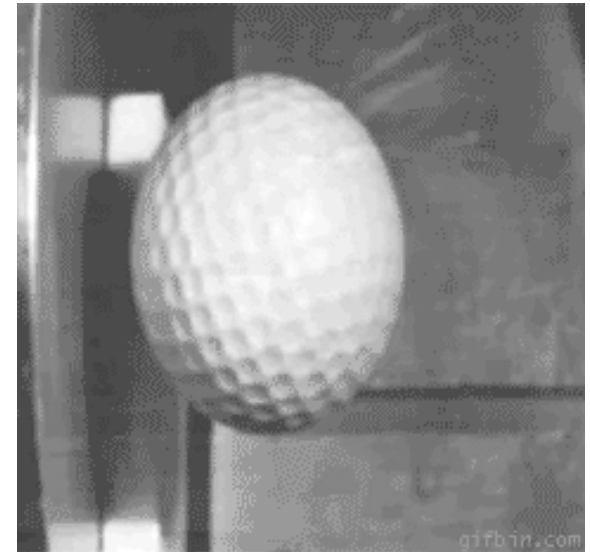
Letter Grade	Percent Grade
A+	98-100
A	93-97
A-	90-92
B+	87-89
B	83-87
B-	80-82
C+	77-79
C	73-76
C-	70-72
D+	67-69
D	63-66
D-	60-62
F	Below 60

# Fuel Mechanics

NE 591

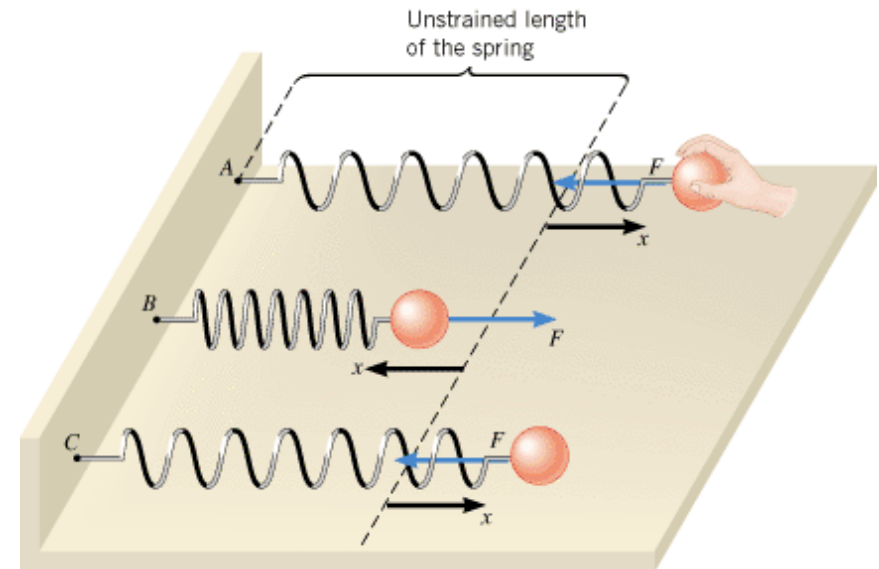
# Solid mechanics

- When a load is applied to a body, it changes shape and perhaps size
- Motions throughout a body are called **displacements**
  - $\mathbf{u}(\mathbf{r}, t)$
- Rigid body displacements do not change the shape and/or size
- Changes in shape and/or size are call **deformations**
- The objective of **Solid Mechanics** is to relate loads to deformation



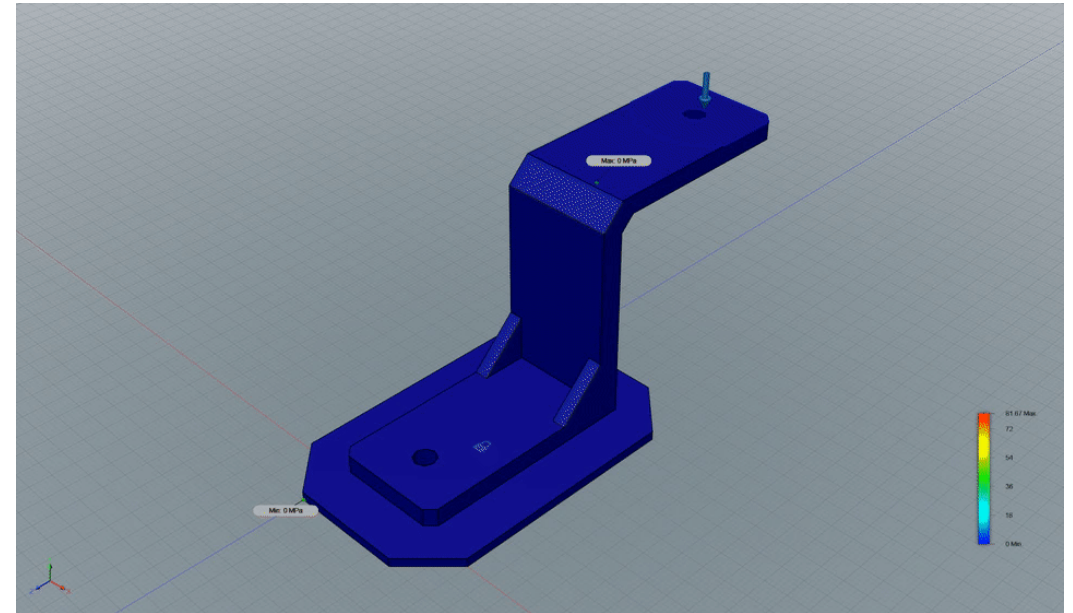
# Ideal springs

- It can be instructive to view solids as a spring
- When we apply some force  $F$ , we get some displacement  $x$ 
  - $F = k x$
- When the spring is displaced by  $x$ , there is force that responds in the opposite direction equal to  $kx$
- Due to the displacement, there is a stored energy  $E = \frac{1}{2} k x^2$



## Observed deformation due to a force

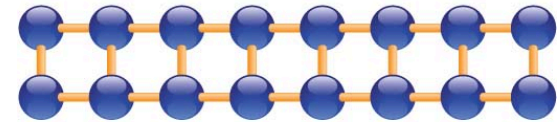
- Solid mechanics is similar to the behavior of an ideal spring but throughout a body
- An applied load results results in deformation.
- The internal **strain** is like the displacements  $x$
- The internal **stress** is like the internal force  $F$



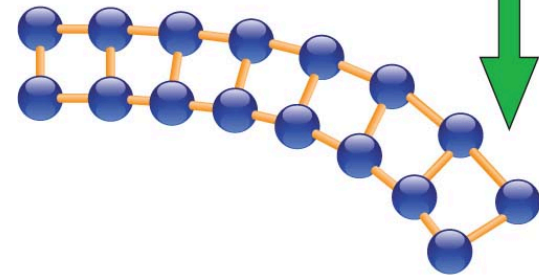
# Elasticity

- Elasticity is the ability of a body to resist a distorting influence and to return to its original size and shape when that influence or force is removed
- In elastic deformation, we are stretching the atomic bonds
- The more we stretch the bonds, the more force it takes to stretch
- When we release the load, the atoms spring back into their lattice sites

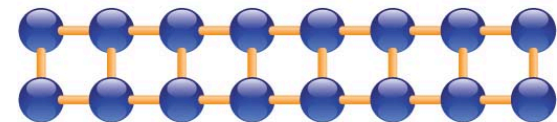
1. Original form



2. Force applied...

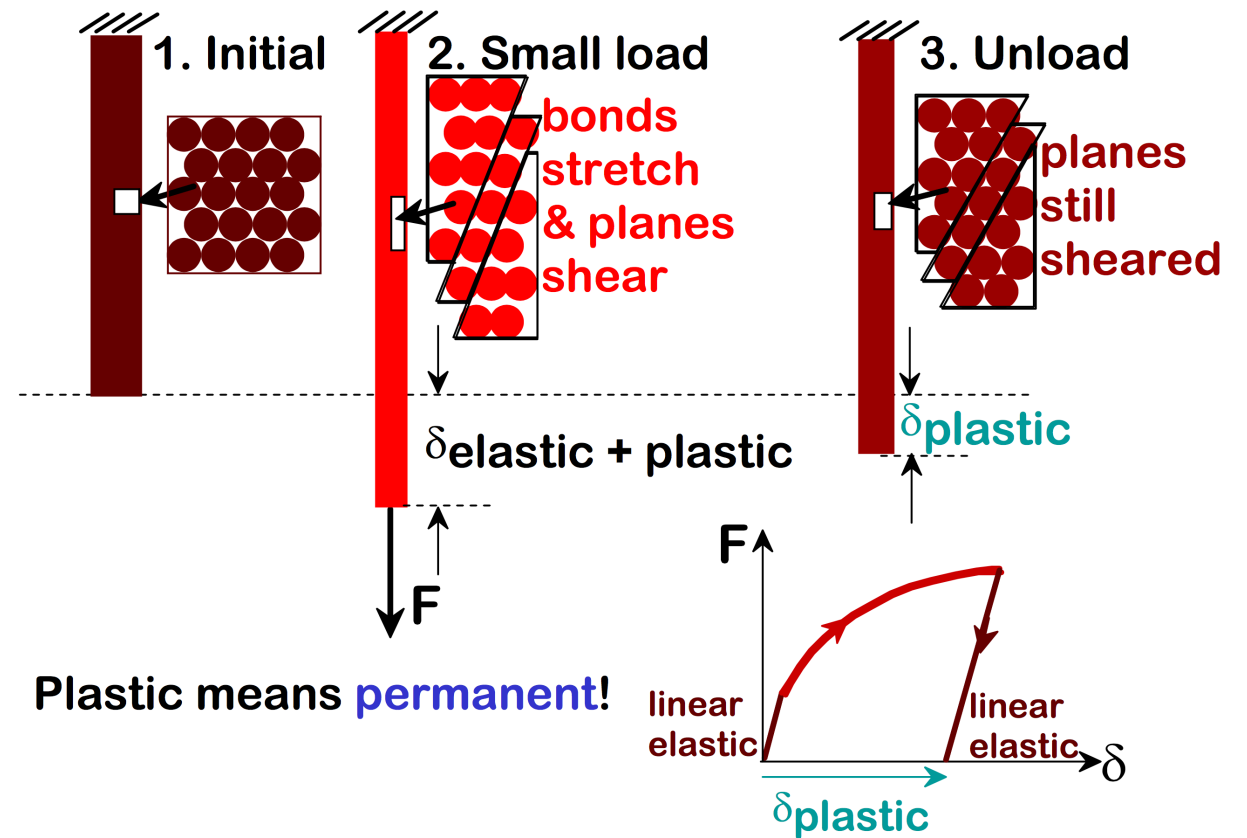


3. ...return to original form.



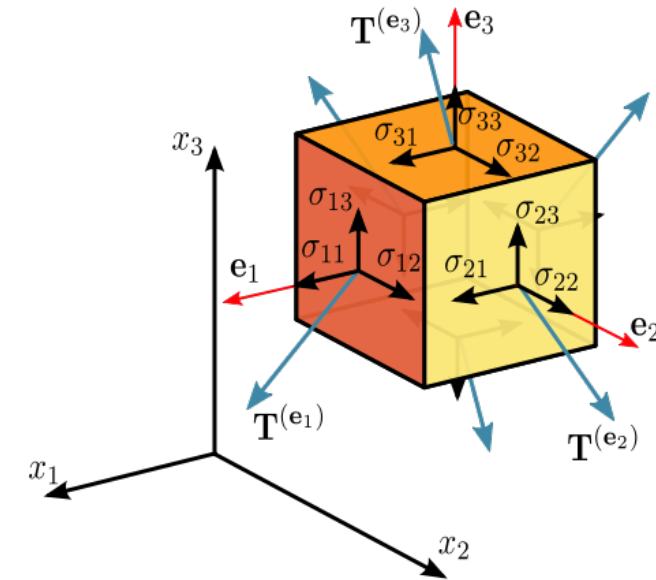
# Plasticity

- Plasticity is the ability of a solid material to undergo permanent deformation, a non-reversible change of shape in response to applied forces
- Plastic deformation is observed in most materials
- The transition from elastic behavior to plastic behavior is known as yielding



# Stress

- Stress is a physical quantity that expresses the internal forces that neighboring particles of a continuous material exert on each other
- Stress is a force per unit area with SI units of  $\text{Pa} = \text{N/m}^2$
- The stress is a 2<sup>nd</sup> order tensor (a 3 by 3 matrix): Cauchy stress tensor
- $\sigma_{ij} = F_{ij}/A_i$ 
  - $i$  is the face the force is applied and  $j$  is the direction it is applied
- Sigmas are normal stress components, taus are shear stress components

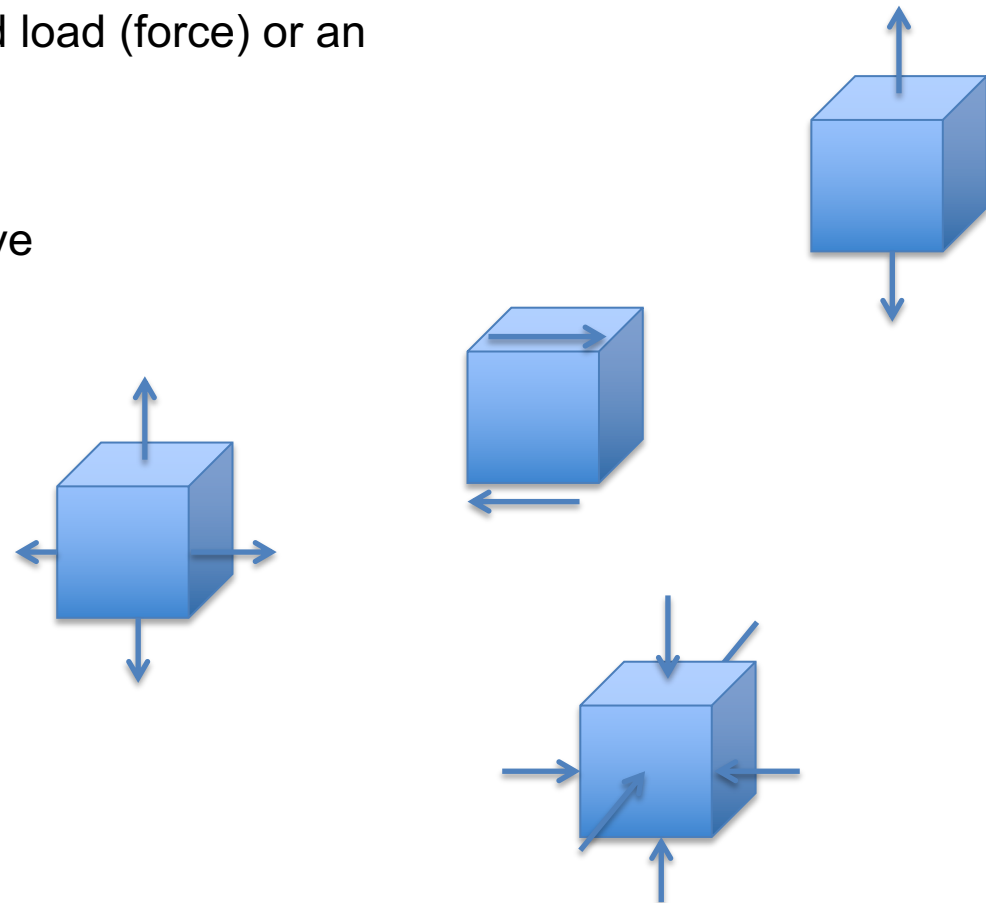


$$\sigma = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{bmatrix} \equiv \begin{bmatrix} \sigma_{xx} & \sigma_{xy} & \sigma_{xz} \\ \sigma_{yx} & \sigma_{yy} & \sigma_{yz} \\ \sigma_{zx} & \sigma_{zy} & \sigma_{zz} \end{bmatrix} \equiv \begin{bmatrix} \sigma_x & \tau_{xy} & \tau_{xz} \\ \tau_{yx} & \sigma_y & \tau_{yz} \\ \tau_{zx} & \tau_{zy} & \sigma_z \end{bmatrix}$$



# Stress as a response

- The stress in a material is the RESPONSE to an applied load (force) or an applied displacement
- Uniaxial tension or compression
  - Only one non-zero stress:  $\sigma_{ii}$  ( $\sigma_{11}$ ,  $\sigma_{22}$ ,  $\sigma_{33}$ )
  - Tension means positive stress, compression negative
  - Examples: Cables, tension tests
- Pure shear
  - Only one non-zero stress: ( $\sigma_{12}$ ,  $\sigma_{13}$ ,  $\sigma_{23}$ )
  - Examples: drive shaft
- Biaxial tension
  - Two non-zero stress (e.g.  $\sigma_{11} = 1$ ,  $\sigma_{22} = 2$ )
  - Examples: Pressure cylinder or vessel
- Hydrostatic compression (pressure)
  - $\sigma_{11} = \sigma_{22} = \sigma_{33} = -p$
  - Anything underwater



# Strain

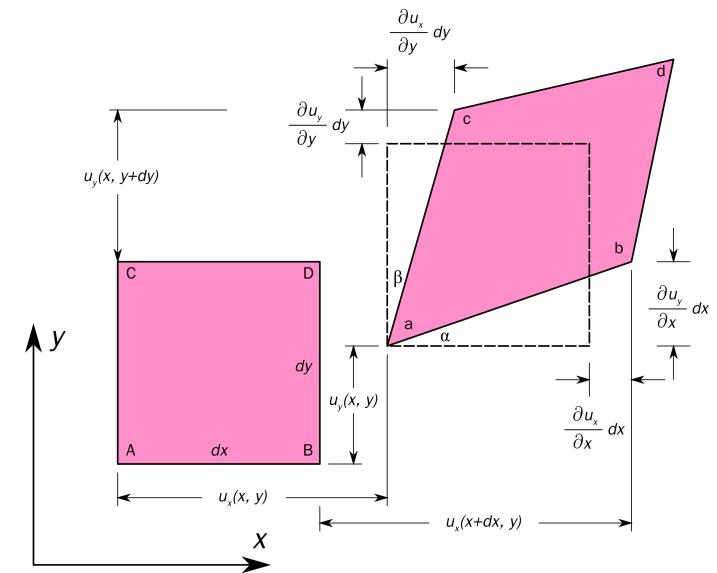
- Strain is a geometrical measure of deformation representing the relative displacement between particles in a material body
- The strain in a tensile test is the deformation divided by a representative length

$$e = \frac{\Delta L}{L} = \frac{\ell - L}{L}$$

- Strain is a second order tensor, like the stress and is computed using gradients
  - Let  $\mathbf{u}$  be a vector of the displacements
  - The small strain tensor is

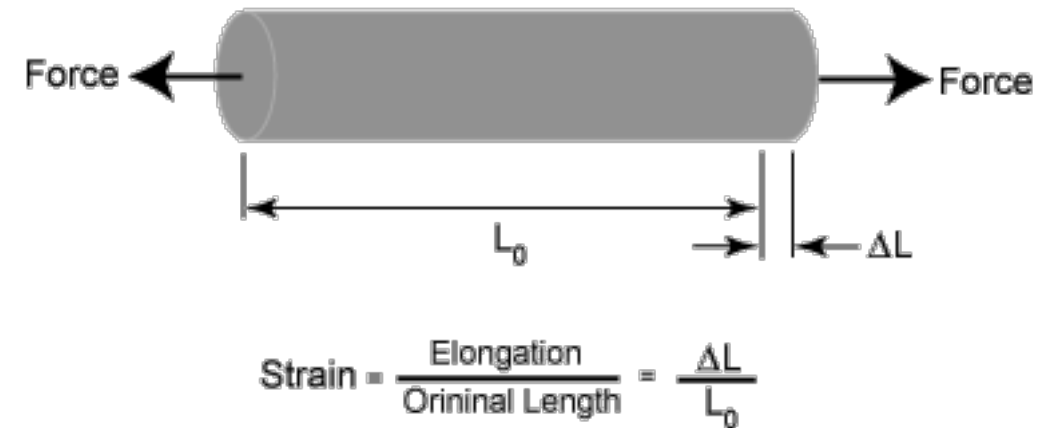
$$\epsilon = \frac{1}{2} (\nabla \mathbf{u} + \nabla \mathbf{u}^T)$$

- The common strain states are the same as the stress (uniaxial tension, etc.)

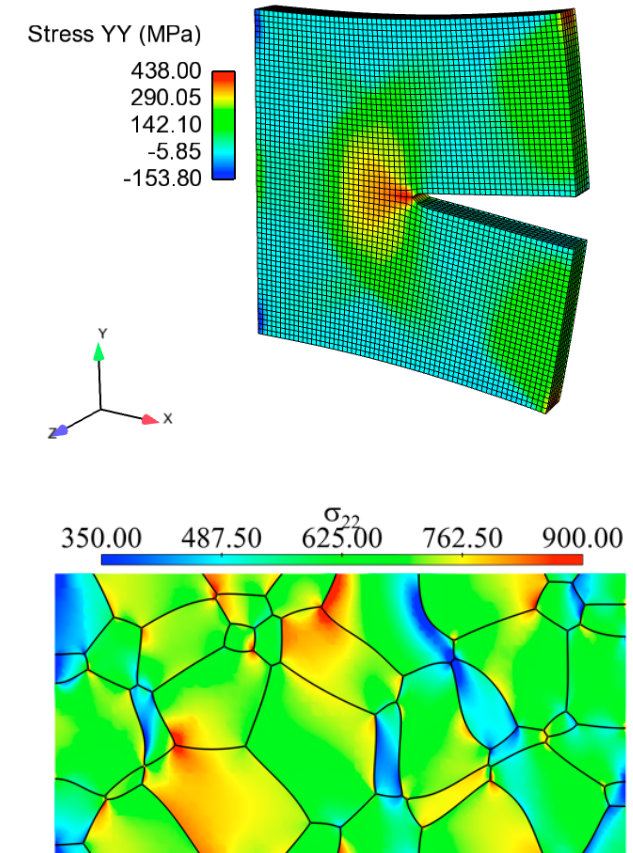
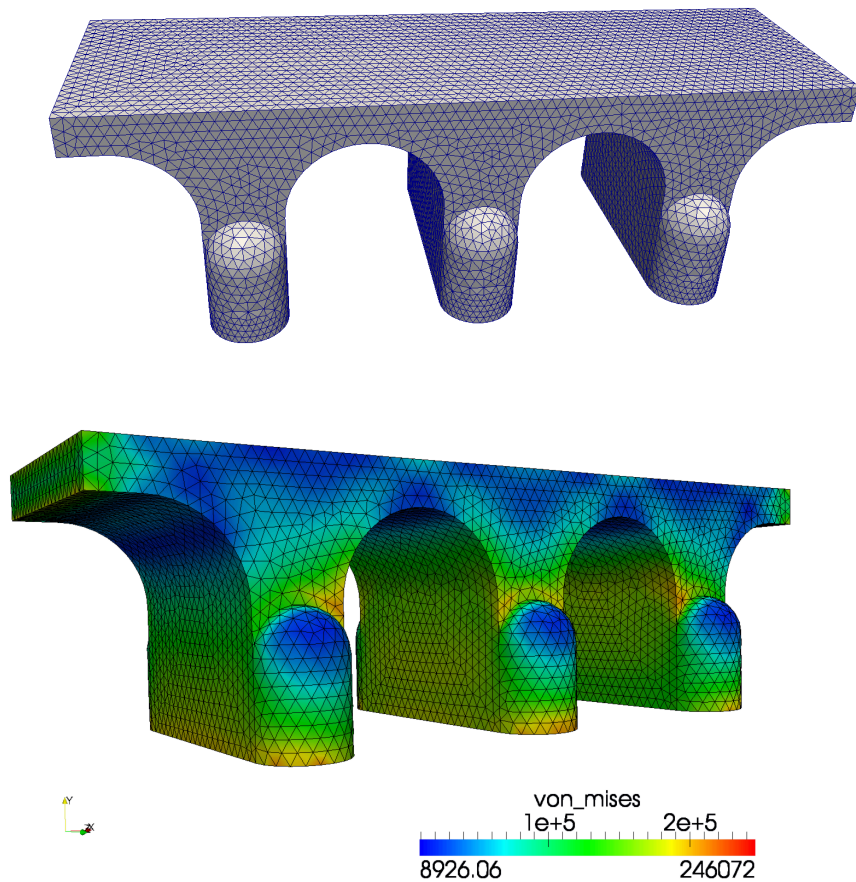


## Strain produces stress

- A deformation (strain) results in stress within a material
- $\sigma = F(\epsilon)$
- For small strains, the stress is elastic and is a linear function of the strain
  - $\sigma = \mathcal{C}(\epsilon)$
- For larger deformation, some of the strain is elastic and increases the stress. The rest is plastic and does NOT contribute to the stress.
  - $\epsilon = \epsilon_e + \epsilon_p$
  - $\sigma = \mathcal{C}\epsilon_e$
- The elastic energy density in a material is a scalar quantity equal to
 
$$E_{el} = \frac{1}{2} \epsilon_e \cdot \sigma$$

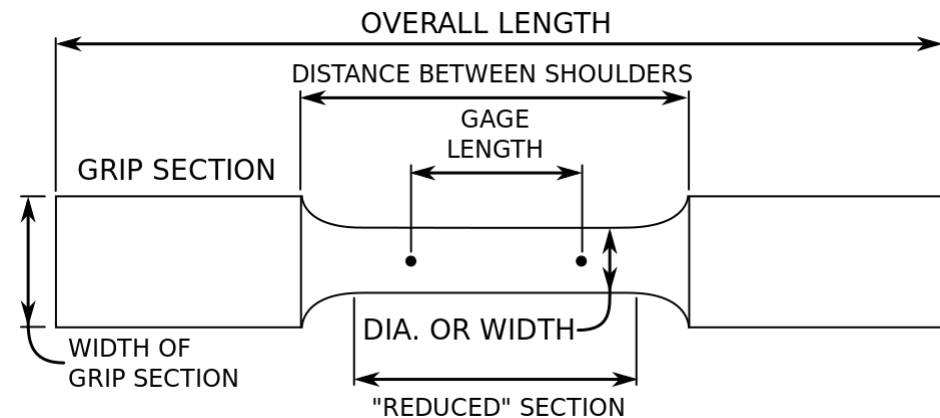
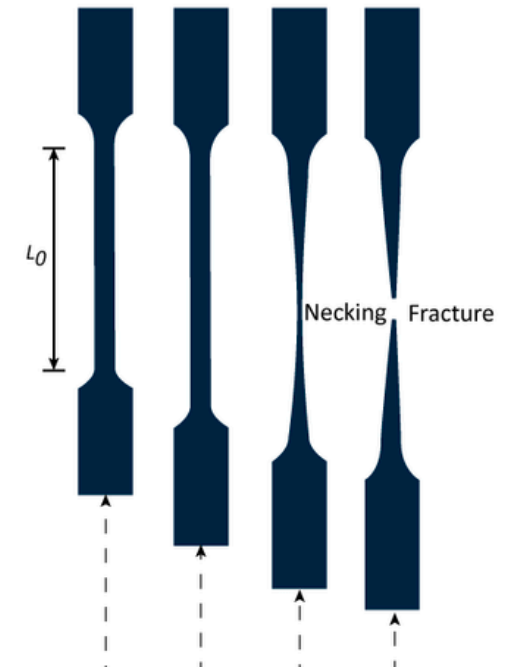


# In actual materials, the stress and the strain change throughout the material



# Tensile testing

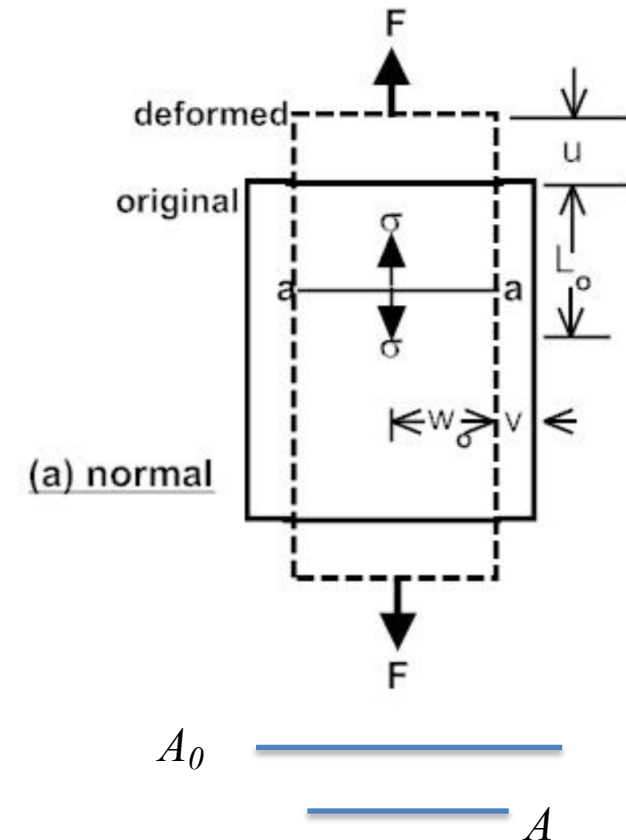
- The most common means of determining mechanical properties is a uniaxial tension test
- Apply a uniaxial load until failure
- Properties that are directly measured via a tensile test include ultimate tensile strength, maximum elongation, etc., which can be utilized to determine Young's modulus, Poisson's ratio, etc.



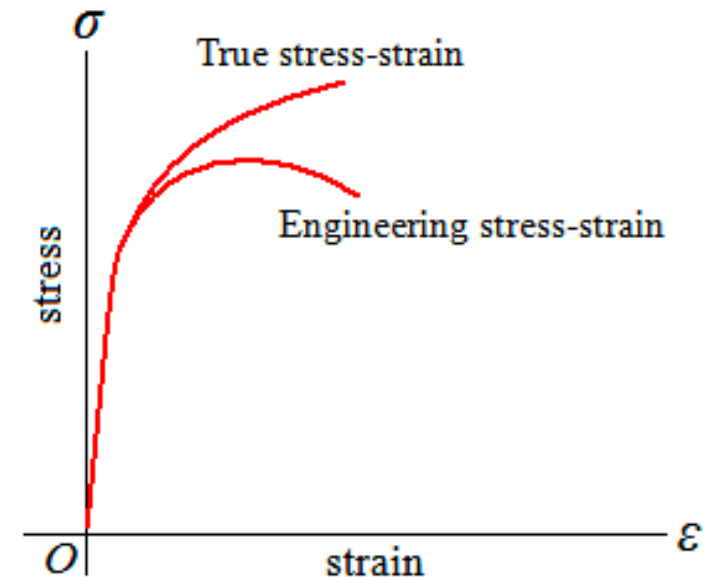
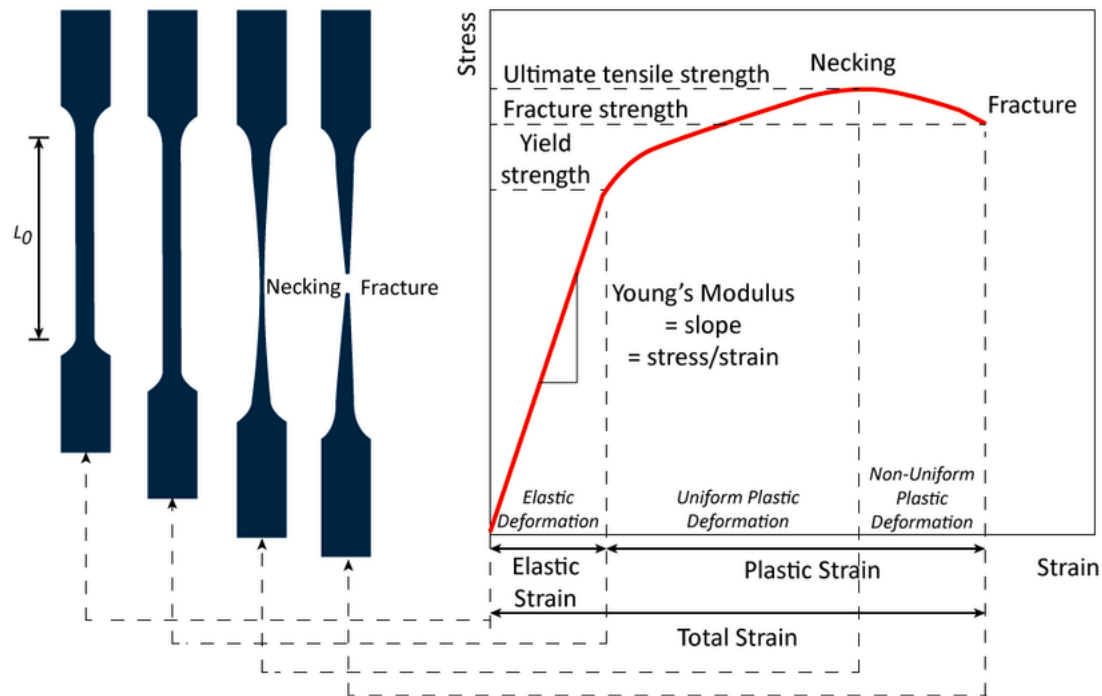
# Stress/strain from a tensile test

- $A_0$  = Initial cross section area
- $A$  = deformed cross section area

	Engineering	True
stress $\sigma$	$\frac{P}{A_0}$	$\frac{P}{A}$
strain $\varepsilon$	$\frac{l - l_0}{l_0}$	$\int_{l_0}^l \frac{dl}{l} = \ln\left(\frac{l}{l_0}\right)$



# Stress vs strain curves

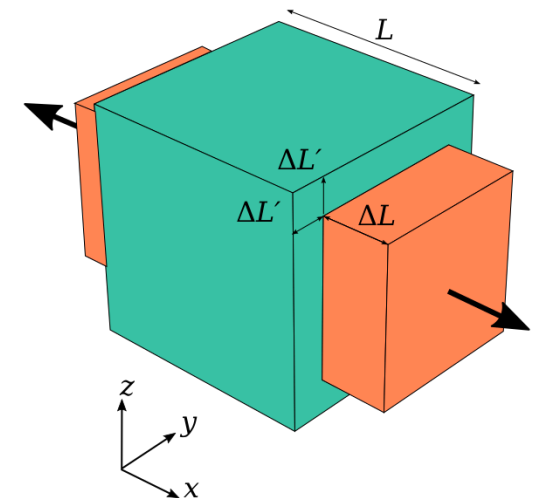
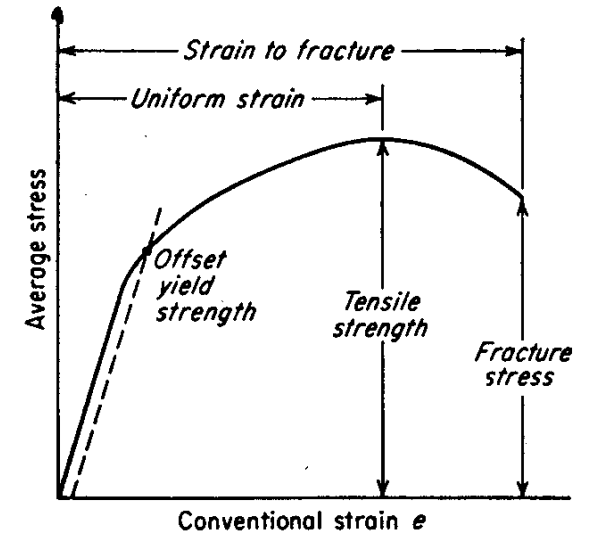


## Using stress/strain curves

- In the elastic portion of the stress-strain curve, the stress varies linearly with strain
- The slope of the line is Young's Modulus,  $E$ :  $\sigma = E \varepsilon$
- Young's modulus is an elastic constant
- Another elastic constant is Poisson's ratio,  $\nu$
- Poisson's ratio is the ratio of the shrinkage in cross section due to the extension in the pulling direction

$$\nu = -\frac{d\varepsilon_{\text{trans}}}{d\varepsilon_{\text{axial}}} = -\frac{d\varepsilon_y}{d\varepsilon_x} = -\frac{d\varepsilon_z}{d\varepsilon_x} \quad \nu \approx \frac{\Delta L'}{\Delta L}$$

$$G = \frac{E}{2(1 + \nu)}$$





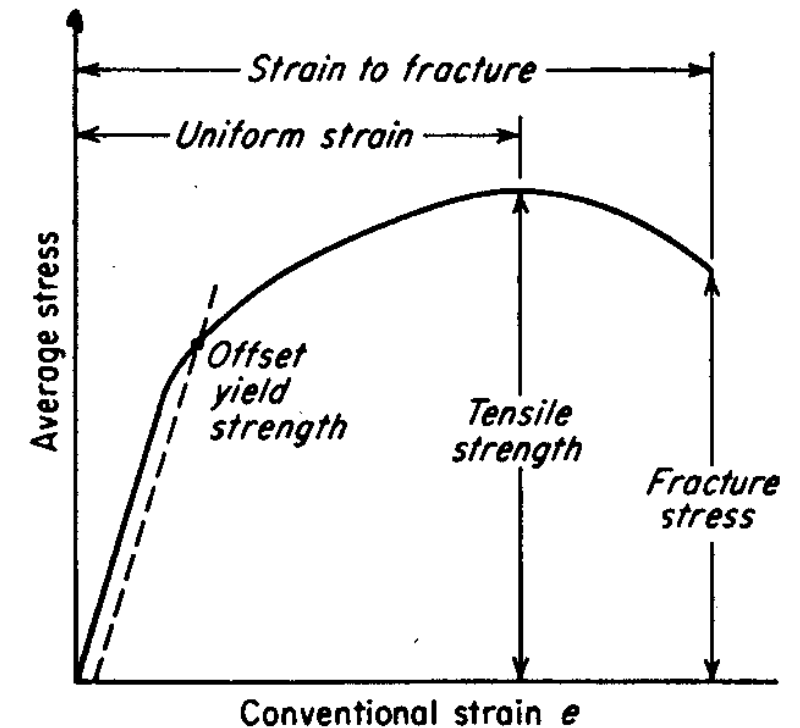
## Using stress/strain curves

- The shear modulus,  $G$ , defines the stress to strain ratio in shear

$$\sigma_{12} = G\epsilon_{12}$$

- For isotropic materials,  $G = E / (2(1 + \nu))$
- In matrix form, Hooke's law for isotropic materials can be written as

$$\begin{bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ 2\epsilon_{23} \\ 2\epsilon_{13} \\ 2\epsilon_{12} \end{bmatrix} = \begin{bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ \gamma_{23} \\ \gamma_{13} \\ \gamma_{12} \end{bmatrix} = \frac{1}{E} \begin{bmatrix} 1 & -\nu & -\nu & 0 & 0 & 0 \\ -\nu & 1 & -\nu & 0 & 0 & 0 \\ -\nu & -\nu & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2+2\nu & 0 & 0 \\ 0 & 0 & 0 & 0 & 2+2\nu & 0 \\ 0 & 0 & 0 & 0 & 0 & 2+2\nu \end{bmatrix} \begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{23} \\ \sigma_{13} \\ \sigma_{12} \end{bmatrix}$$



$$\epsilon_{yy} = \frac{1}{E} [\sigma_{yy} - \nu(\sigma_{xx} + \sigma_{zz})]$$

# Isotropic and Anisotropic

- Isotropic materials deform the same way no matter in what direction you deform them.
  - They have 2 unique elastic constants,  $C_{11}$  and  $C_{12}$
- Anisotropic materials behave differently in different directions
  - The elasticity tensor can have 21 unique components defining anisotropy
  - Cubic structured materials have 3 unique elastic constants ( $\text{UO}_2$ )
  - Hexagonal structured materials have 5 unique elastic constants
- Polycrystalline anisotropic materials can behave as isotropic, because the various grains average out

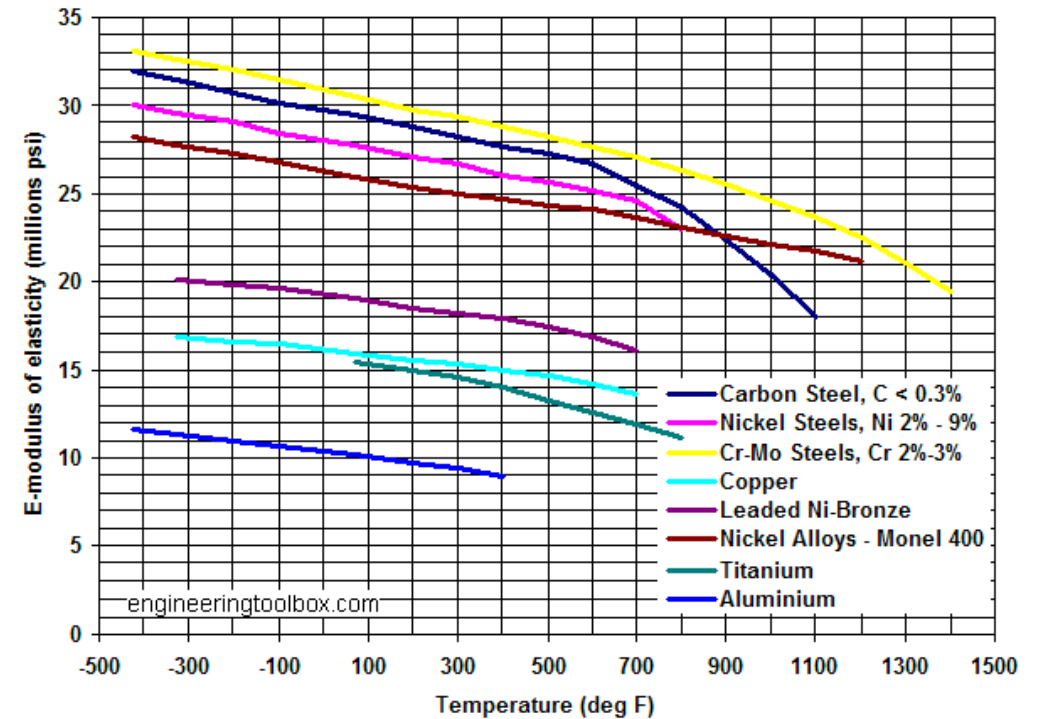
$$\begin{bmatrix}
 C_{11} & C_{12} & C_{13} & C_{14} & C_{15} & C_{16} \\
 C_{12} & C_{22} & C_{23} & C_{24} & C_{25} & C_{26} \\
 C_{13} & C_{23} & C_{33} & C_{34} & C_{35} & C_{36} \\
 C_{14} & C_{24} & C_{34} & C_{44} & C_{45} & C_{46} \\
 C_{15} & C_{25} & C_{35} & C_{45} & C_{55} & C_{56} \\
 C_{16} & C_{26} & C_{36} & C_{46} & C_{56} & C_{66}
 \end{bmatrix}$$

# Isotropic elastic constants for some materials

Material	E (Gpa)	$\nu$
Aluminum	70.3	0.345
Gold	78.0	0.44
Iron	211.4	0.293
Nickel	199.5	0.312
Tungsten	411.0	0.28
Zircaloy	80.0	0.41
UO <sub>2</sub>	200.0	0.345

## Elastic constants are not “constant”

- Properties change with temperature
- Softening can be referred to as the decrease in elastic constants with temperature
- Young's modulus is typically a function of temperature, decreasing with increasing temperature
- Shear Modulus and Poisson's ratio can also change with T



## Summary

- Solid mechanics predicts the deformation of a body from its applied load
- The strain defines the deformation
- The stress defines the material's response to the strain
- Materials can have recoverable and permanent deformation
  - Elastic deformation is recoverable and occurs due to the stretching of the atomic lattice
  - Plastic deformation is permanent and results from the breaking of bonds