

# On Squares Inscribed on Continuous Embeds in the Real Plane

Benjamin Myers

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## 1 Introduction

The Inscribed Square Problem was formed in 1911 by Oliver Toeplitz. Here, Toeplitz conjectures that any continuous embedding of a circle onto the real plane  $\lambda$  always admits at least one inscribed square. While seemingly true in nature, the lack of a proof for this statement has caused the conjecture to gain popularity. In this paper, we shall consider a plane simple closed curve

$$\lambda : S^1 \hookrightarrow \mathbb{R}^2,$$

a non-self-intersecting Jordan curve that divides  $\mathbb{R}^2$  into an inner and outer region, as shown in Figure 1.

Such a curve will be proved to admit an inscribed square given a certain topological mapping of a curve on the surface of a circular cylinder onto a Mobius strip; a self-intersection that always occurs during the mapping from a non-contractible nature justifies Toeplitz' statement.

We will start by discussing a continuous existence of a certain class of right triangles along  $\lambda$ . Next, we will show that some of these triangles share edges in

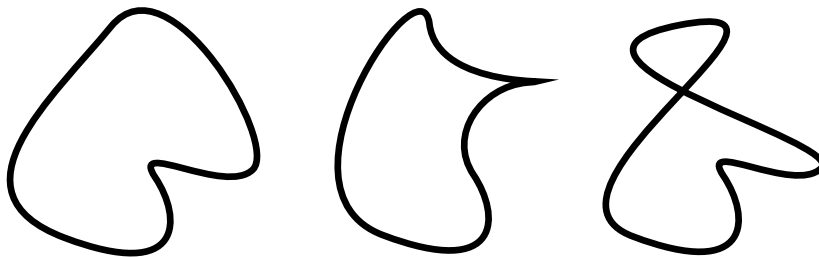


Figure 1: Three closed curves. The leftmost and middle curves can be classified as Jordan curves. The rightmost one cannot, as it crosses over itself.

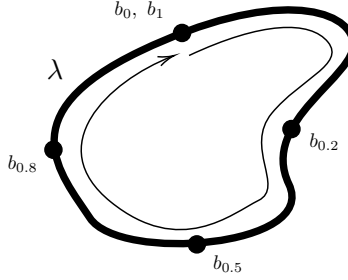


Figure 2: Each point on  $\lambda$  can be identified by a real number 0 to 1.

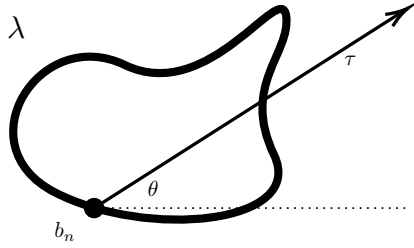


Figure 3: A ray  $\tau$  extended from  $b_n$  with an angle  $\theta$  to the horizontal.

a way that forms an inscribed square. Finally, we will use a topological mapping to show that this occurrence must always be present.

## 2 Parametrizing Distances within $\lambda$

Consider the set  $B$ , the set of all points  $b$  on  $\lambda$ . A map of all real numbers on  $n \in [0, 1]$  to each item in  $B$  allows each point  $b_n$  to be classified by a number, as shown in Figure 2. These points will be classified in such a way that  $b_{n+\Delta n}$  changes continuously. Hence,

$$b_0 \cong b_1$$

since  $\lambda$  is a closed curve; the start and end points are the same.

**Definition 2.1.** Allow a ray  $\tau$  to be extended from any point  $b_n$ . Let  $\tau$  have a initial point at  $b_n$  with an angle  $\theta$  with respect to the horizontal, as shown in Figure 3. Considering the set of intersection points

$$I_{n,\theta} : \tau \cap \lambda,$$

let  $L_{n,\theta}$  be defined as the set of distances between

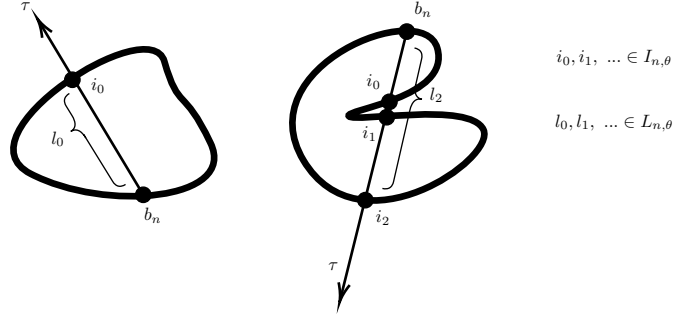


Figure 4: The lengths of the segments from  $b_n$  and  $\forall i \in I_{n,\theta}$  are visualised.

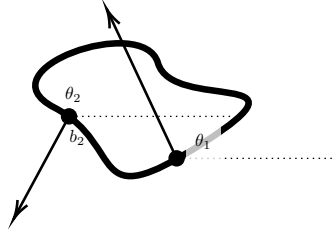


Figure 5:  $g(n_1, \theta_1)$  meets condition  $C$ ;  $g(n_2, \theta_2)$  does not.

$$b_n \text{ and } i, \forall i \in I \forall l \in L_{n,\theta}.$$

As shown in Figure 4. The function

$$g : g(n, \theta), n \in [0, 1], \theta \in [0, 2\pi] = L_{n,\theta}.$$

When  $\tau$  is extended in a fashion where it never meets with  $\lambda$ ,  $g$  returns an empty set. We will consider the converse, or the condition  $C$  when  $g$  returns a non-null set of real numbers, as shown in Figure 5.

**Lemma 2.1.** *For any chosen value  $n_0$ ,  $g(n_0, \theta)$  has a one unbroken  $\theta$  domain whose outputs meet condition  $C$  and one unbroken  $\theta$  domain whose outputs fail to meet  $C$ .*

*Proof.* The reason for this lemma is intuitive. Choosing a base point determined by  $n_0$  and revolving the terminal point of ray around  $b_{n_0}$  will have a period where it intersects  $\gamma$ , and usually a period where it does not:

- There is no instance where  $g$  will always return  $\emptyset$ , as the curve cannot be a single point.
- There is no instance where  $g$  will contain more than one range of outputs that meet  $C$ , as the curve is unbroken and occupies a limited space that can be intersected by  $\tau$ .

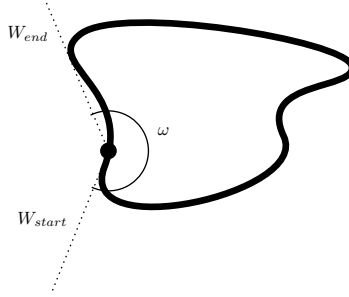


Figure 6: The width of  $W$  defined as  $\omega$  measures from  $W_{start}$  to  $W_{end}$ .

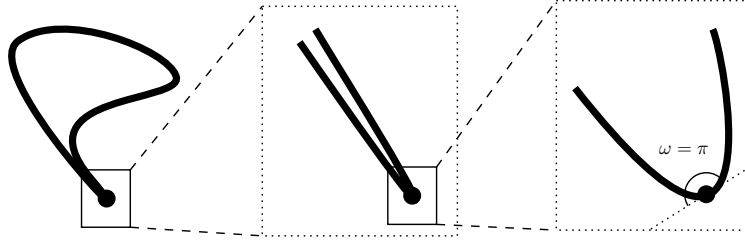


Figure 7: Base points at a sharp turn have an  $\omega_{min}$  value of  $\pi$ .

□

Hence, we will define the single continuous set of outputs from  $g$  with one  $n$  chosen  $\forall \theta \in [0, 2\pi]$ .

**Definition 2.2.** *Let  $W$  be the unbroken domain where  $g(n_0, \theta)$  meets condition  $C$  when varying  $\theta$ . Allow  $\omega$ , then, to represent the "width" of  $W$ , regarding the fact that  $\omega$  is an angle width, as shown in Figure 6.*

When a ray is extended from a base point  $b_n$ , the range  $\omega$  where  $\tau$  meets  $C$  is quite large, with respect to all of the possible angle values of  $\theta$ . In fact, we can make a conclusion about the minimum angle width  $\omega_{min}$  for any  $b_n$  on any  $\gamma$ .

**Lemma 2.2.** *The angle width  $\omega$  as a result of any base point  $b_n$  on any  $\lambda$  must always have a value of  $\pi$  or greater.*

*Proof.* Any point given by  $b_n$  on a smooth part of the curve has tangent lines along the curve that extend in both directions from  $b_n$ . Hence the angle between them is  $\pi$  radians, and there must always be curve on at least one side of the tangent line due to the nature of  $\lambda$ .

If  $b_n$  is located at a sharp turn, one can assume that the curve is smooth once infinitely zoomed in upon, meaning the above situation occurs. See Figure 7.

□

### 3 Establishing a 3-Dimensional Relationship

Since  $g$  is defined as a two-variable function, it can be graphed in an three-dimensional space.

Consider the collection of surfaces  $\Phi$  in  $x - y - z$  space, where

$$(n, \theta, g_0 \forall g_0 \in g(n, \theta) \hookrightarrow (x, y, z).$$

$\Phi$  is a *collection* of surfaces since  $g$  results in a set of real numbers. See Figure 8.

If  $\gamma$  is convex, then  $\Phi$  has only one  $z$  value for every pair of  $x$  and  $y$  values  $(n, \theta)$ . Conversely, if  $\gamma$  is non-convex,  $\Phi$  may have multiple  $z$  values for pairs of inputs.

Regardless of whether  $\Phi$  contains multiple  $z$  values, we can find a special class of triangles by transforming  $\Phi$  by  $\frac{\pi}{2}$  radians.

This transformation, in turn, represents extending another ray  $\tau'$  perpendicular to  $\tau$ . All  $g'$  outputs from the newly transformed  $\theta'$  value form the surface  $\Phi'$ .

$$\begin{aligned} \Phi' : (n, \theta + \frac{\pi}{2}, g_0 \forall g_0 \in g(n, \theta + \frac{\pi}{2}) \hookrightarrow (x, y, z) \\ \implies (n, \theta', l) \hookrightarrow (x, y, z) \end{aligned}$$

And because  $W \geq \pi$  for all  $x$ -slices of  $\Phi$ , all  $x$ -slices of  $\Phi'$  must also have this same width. We will now consider the intersection of  $\Phi$  and  $\Phi'$ .

Any intersection point of these two surfaces represents an isosceles right triangle whose congruent legs extend from  $b_n$  with angles  $\theta$  and  $\theta' := \theta + \frac{\pi}{2}$  from the horizontal.

**Definition 3.1.** *If the two surfaces intersect at a point  $(n, \theta, l)$ , then an isosceles right triangle with base legs of length  $l$  can be defined as  $T_{n, \theta}$ . See Figure 9.*

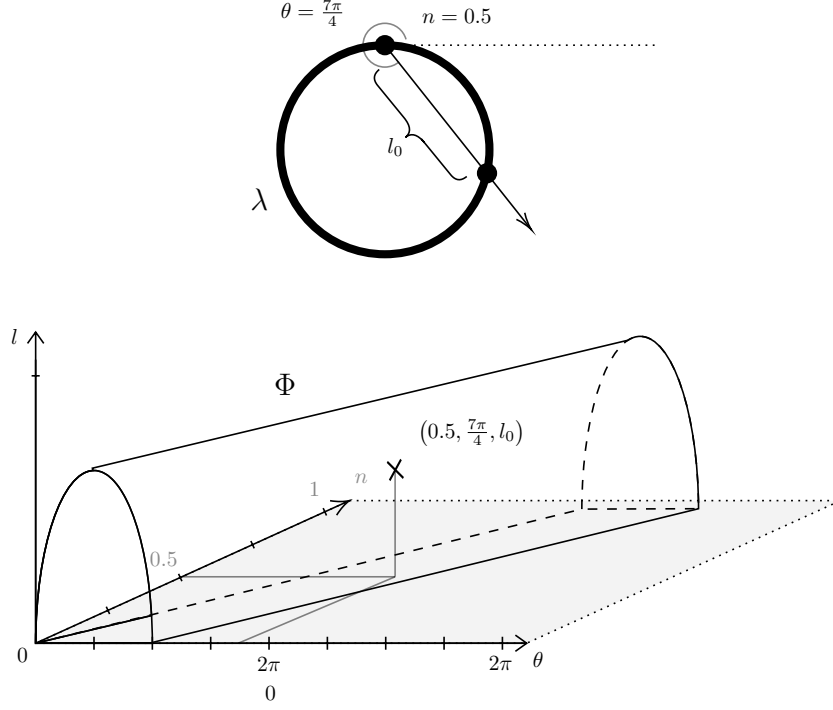


Figure 8: Surface  $\Phi$  formed by  $z = g(n, \theta)$ . This surface is an example when  $\lambda$  is a circle. We have chosen two sample inputs and shown the output on  $\Phi$  for reference.

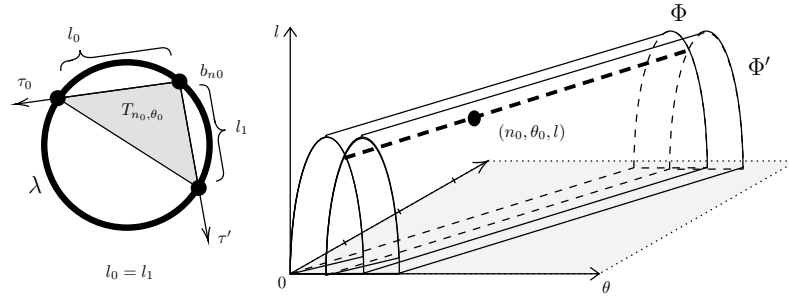


Figure 9: Any point where  $\Phi$  and  $\Phi'$  intersect is representative of one isosceles right triangle  $T_{n, \theta}$ .

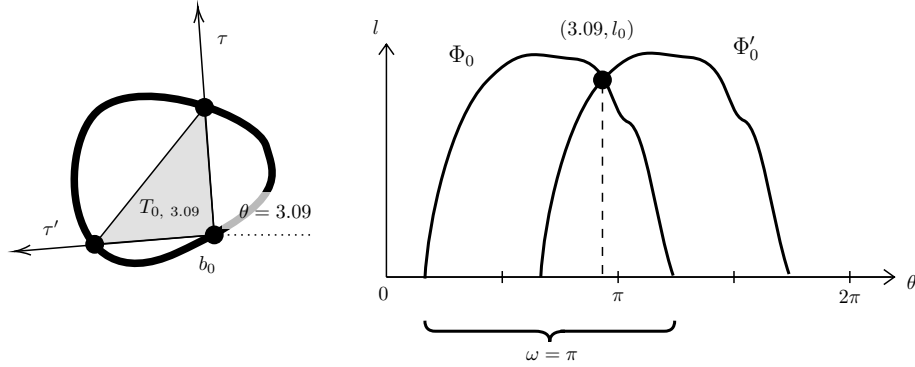


Figure 10: Consider a cross-section of  $\Phi$  when  $n = 0$ .  $\Phi_0$  and  $\Phi'_0$  must intersect since  $\omega > 0 \forall b_n \in B$ . The point  $(3.09, l_0)$  is such an intersection; it represents  $T_{0,3.09}$ .

**Theorem 3.1.** *For any base point  $b_n$  chosen on  $\lambda$ , it must act as the point between two base legs of an inscribed isosceles right triangle  $T_{n,\theta}$  for one or more  $\theta$  values.*

*Proof.* Since a chosen base point  $b_n$  restricts  $\Phi$  and  $\Phi'$  to a  $x$ -cross-section  $\Phi_x$  where  $x = n$ , and since the width of  $\Phi_x$  and  $\Phi'_x$  is always greater than or equal to  $\pi$ ,  $\Phi_x$  and  $\Phi'_x$  must always intersect at a minimum of one point because  $\Phi'$  is a translation of  $\frac{\pi}{2}$  radians in the  $y$ -direction. Every intersection point of these two surfaces represents the existence of an isosceles right triangle. See Figure 10. □

And since the intersections of  $\Phi$  and  $\Phi'$  form a line or set of lines, we can make conclusions about the continuity of these triangles.

**Theorem 3.2.** *As  $n$  increments continuously,  $b_n$  acts as the base point between two congruent base legs of a continually existing inscribed isosceles right triangle.*

*Proof.* Each intersection of  $\Phi$  and  $\Phi'$  represents one inscribed isosceles right triangle. The intersection of these two surfaces always results in a continuous curve or set of curve. □

At this point, we will aim to use these continually existing triangles to locate an inscribed square.

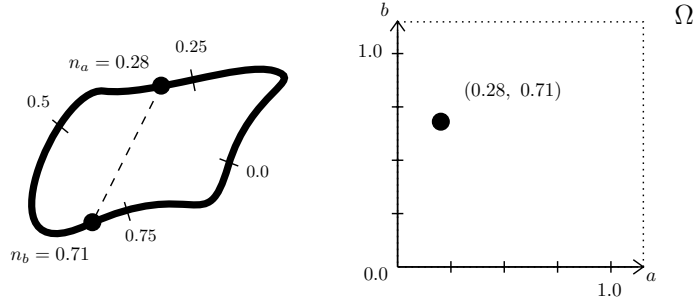


Figure 11: Any ordered pair  $(a, b)$  on  $\Omega$  represents an pair of points on  $\lambda$ .

## 4 Forming an Inscribed Square from Triangles

Consider an inscribed isosceles right triangle  $T_{n,\theta}$ . We will observe the three vertices of

$$T_{n,\theta}: b_n, i_m, j_p,$$

where  $i_m$  and  $j_p$  are the vertices on the ends of hypotenuse of

$$\triangle b_n i_m j_p.$$

Each of these points can be represented by an  $n$  value, as each point on the curve corresponds to a real number on  $[0, 1]$ .

Consider the 2-dimensional plane  $\Omega$  with axis  $x \in [0, 1]$  and  $y \in [0, 1]$  where values for  $x$  and  $y$  wrap at 0 and 1. Each of these axes, then, can represent the number line where points exist on  $\lambda$ . Any point in this 2-dimensional plane, therefore, represents a pair of points on  $\lambda$ , where order matters. See Figure 11.

We will now consider the entire domain of  $\Omega$ , restricting it down to order-dependent pairs of points that acts as vertices on the ends of legs of an ambiguous triangle  $T_{n,\theta}$ .

Hence, if the domain of  $\Omega$  is restricted to curves where all points  $(n, m)$  and  $(n, p)$  represent inscribed isosceles right triangles  $\triangle b_n i_m j_p$ , then two primary curves  $\alpha$  and  $\beta$  (some that can branch off and merge if  $\lambda$  is not convex) are the only objects graphed on  $\Omega$ , as shown in Figure 12.

**Lemma 4.1.** *Since each point on  $\alpha$  and  $\beta$  represent side legs of some  $\triangle b_n i_m j_p$ ,  $\alpha$  and  $\beta$  have certain properties:*

- *They cannot cross the line given by  $a = b$ , as points that lie on this line represent a pair of points that occupy the same  $n$  value.*
- *The curves wrap around  $a$ . Any  $n$ -value at  $a = 1$  is the same at  $a = 0$ .*



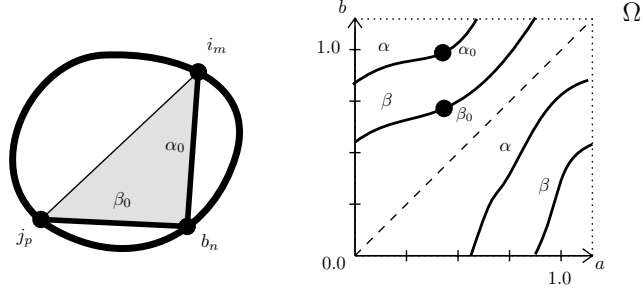


Figure 12: Triangle  $\triangle b_n i_m j_p$  has sides  $\alpha_0$  and  $\beta_0$  that are represented by two points on  $\omega$  that share the same  $a$ -coordinate.

- The curves wrap around  $b$ . Any  $m$ - or  $p$ -value at  $b = 1$  is that same at  $b = 0$ .

*Proof.* The second and third properties of  $\alpha$  and  $\beta$  are implied, given the nature of  $\Omega$ . Since the line  $a = b$  represents all pairs of points where  $n = m$  or  $n = p$ ,  $\alpha$  and  $\beta$  cannot cross this line, as a point on this line implies a triangle with a side length of 0. □

Recall that each point on  $\alpha$  represents the most counterclockwise leg of any inscribed isosceles right triangle  $T_1$ . If we find another inscribed isosceles right triangle  $T_2$  that shares a leg with  $T_1$ , we can show that a square exists if we meet a few conditions.

**Theorem 4.1.** *At any point where the graph of  $\alpha^{-1}$  intersects  $\beta$ , a square exists on  $\lambda$ .*

*Proof.* Allow two inscribed isosceles right triangles to be defined as

$$T_1 : \triangle b_{n1} i_{m1} j_{p1}, \text{ and}$$

$$T_2 : \triangle b_{n2} i_{m2} j_{p2}$$

where any point  $b$  is between the two legs of  $T$ .

inscribed on  $\lambda$ . If  $T_1$  and  $T_2$  share a leg in opposing directions from the base points such that

$$\overline{b_{n1} j_{p1}} \cong \overline{b_{n2} i_{m2}},$$

then the points form an inscribed square, shown in Figure 13, defined as

$$S : \square b_{n1} i_{m1} j_{p2} b_{n2}$$

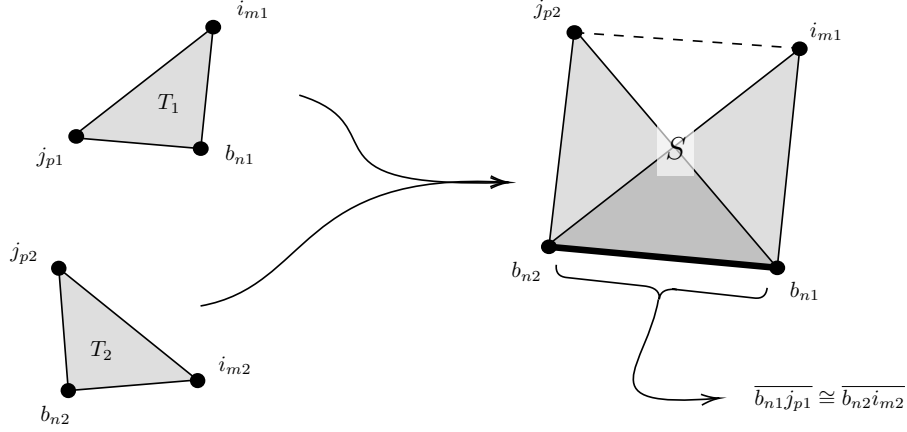


Figure 13: Square  $S : \square_{b_{n1}i_{m1}j_{p2}b_{n2}}$  is formed from two isosceles right triangles. Note that  $\overline{b_{n1}i_{m1}}$  and  $\overline{b_{n2}j_{p2}}$  are on the same side of  $b_{n1}b_{n2}$ .

Since each point on  $\alpha$  represents a segment  $\overline{b_{n1}j_{p2}}$  and each point on  $\beta$  represents a segment  $\overline{b_{n2}i_{m2}}$ , then  $\alpha^{-1} \cap \beta$  represents an instance where  $T_1$  and  $T_2$  share a leg such that  $\overline{b_{n2}j_{p2}}$  and  $\overline{b_{n1}i_{m1}}$  are parallel and on the same side of  $\overline{b_{n1}b_{n2}}$ .

□

## 5 Intersections in Topological Mappings

At this point, the intersection of  $\alpha^{-1}$  and  $\beta$  must be proven for any  $\lambda$ . We will map the curves  $\alpha$  and  $\beta$  to various topological structures, showing that a particular map always forces an intersection of the two curves.

Since  $\Omega$  can be split along the line  $y = x$ , it can be represented topologically as a circular cylinder. See Figure 14.

And since we are looking for an inverse-independent intersection of curves  $\alpha^{-1}$  and  $\beta$ , we can map one-half of  $\Omega$ , divided by the symmetry  $y = x$ , to a Mobius strip. See Figure 15.

Due to the nature of its representation in topological space,  $\alpha$  and  $\beta$  can be said to be non-contractible when represented on a topological circular cylinder.  $\alpha$  and  $\beta$  are both continuous collections of curves, and they must wrap their  $a$ - and  $b$ -values.

**Theorem 5.1.** *Toeplitz' conjecture holds for any given continuous embedding  $\lambda : S^1 \hookrightarrow \mathbb{R}^2$ .*

*Proof.* The mapping of two non-contractible curves  $\alpha$  and  $\beta$  must intersect one another due to the nature of a map from a order-dependent circular cylinder to

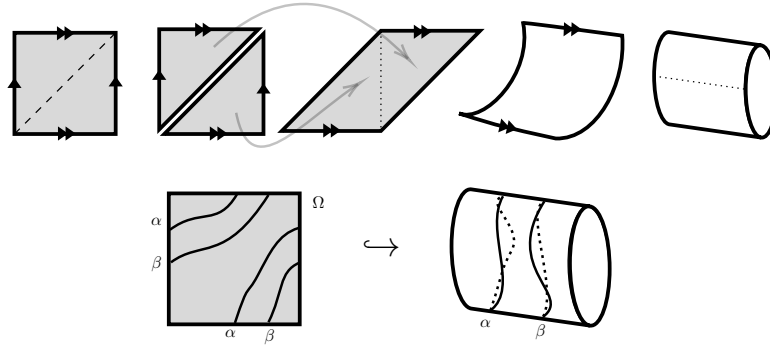


Figure 14:  $\Omega$  is mapped from  $\mathbb{R}^2$  to a circular cylinder.

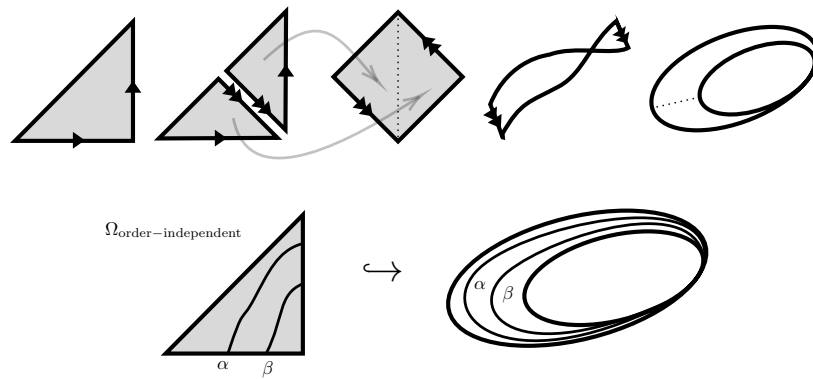


Figure 15:  $\Omega_{\text{order-independent}}$  is mapped from  $\mathbb{R}^2$  to a Mobius strip.

an order-independent Mobius strip. Hence, this intersection must occur for any  $\lambda$  given, as a intersection of  $\alpha^{-1}$  and  $\beta$  through the topological mapping must always occur.  $\square$