

PROPOSITIONAL BIMODAL LOGIC: TASK SEMANTICS

Language: The *bimodal language* \mathcal{L}^B extends propositional logic with modal and temporal operators:

$$\mathcal{L}^B = \langle \mathbb{L}, \perp, \rightarrow, \Box, \Box^P, \Box^F \rangle$$

where $\mathbb{L} = \{p_i \mid i \in \mathbb{N}\}$ is the set of sentence letters.

Well-Formed Sentences: The set of well-formed sentences $\text{wfs}(\mathcal{L}^B)$ is defined inductively:

$$\varphi ::= p_i \mid \perp \mid \varphi \rightarrow \varphi \mid \Box \varphi \mid \Box^P \varphi \mid \Box^F \varphi$$

where $p_i \in \mathbb{L}$.

Abbreviations: We define the following derived operators:

- (a) $\Diamond \varphi := \neg \Box \neg \varphi$ (possibility)
- (b) $\Diamond^P \varphi := \neg \Box^P \neg \varphi$ (past possibility)
- (c) $\Diamond^F \varphi := \neg \Box^F \neg \varphi$ (future possibility)
- (d) $\Delta \varphi := \Box^P \varphi \wedge \varphi \wedge \Box^F \varphi$ (always)
- (e) $\nabla \varphi := \Diamond \varphi \vee \varphi \vee \Diamond^P \varphi$ (sometimes)
- (f) $\neg \varphi, \varphi \vee \psi, \varphi \wedge \psi, \varphi \leftrightarrow \psi$ as usual.

Scope: As in modal logic, \Box , \Box^P , and \Box^F bind more tightly than connectives. Thus:

- (a) $\Box \varphi \rightarrow \psi$ means $(\Box \varphi) \rightarrow \psi$
- (b) $\Box^F \varphi \vee \psi$ means $(\Box^F \varphi) \vee \psi$
- (c) $\Delta \varphi \wedge \psi$ means $(\Delta \varphi) \wedge \psi$

Task Frame: A **task frame** is a triple $\mathcal{F}_T = \langle \mathcal{W}, \mathcal{T}, \Rightarrow \rangle$ where:

- \mathcal{W} is a non-empty set of **world states**
- $\mathcal{T} = \langle T, +, \leqslant \rangle$ is a totally ordered abelian group of times
- $\Rightarrow \subseteq \mathcal{W} \times T \times \mathcal{W}$ is a parameterized task relation

satisfying **nullity** ($w \Rightarrow_0 w$ for all $w \in \mathcal{W}$) and **compositionality** (if $w \Rightarrow_x u$ and $u \Rightarrow_y v$, then $w \Rightarrow_{x+y} v$).

World History: A **world history** over frame \mathcal{F}_T is a function $\tau : X \rightarrow \mathcal{W}$ where $X \subseteq T$ is convex (if $x_1, x_2 \in X$ and $x_1 \leqslant z \leqslant x_2$, then $z \in X$) satisfying **task coherence**: for all $x, y \in T$ where $x, x+y \in X$, we have $\tau(x) \Rightarrow_y \tau(x+y)$. We write \mathcal{H} for the set of all world histories over a given frame.

Task Model: A **task model** is a tuple $\mathcal{M}_T = \langle \mathcal{W}, \mathcal{T}, \Rightarrow, ' \cdot ' \rangle$ where $\langle \mathcal{W}, \mathcal{T}, \Rightarrow \rangle$ is a task frame and $'p_i' \subseteq \mathcal{W}$ is the interpretation of sentence letter p_i .

Semantics: Given task model \mathcal{M}_T , world history τ , and time x , we define truth at \mathcal{M}_T, τ, x (written $\mathcal{M}_T, \tau, x \models \varphi$) inductively:

$$\begin{aligned} \mathcal{M}_T, \tau, x \models p_i &\text{ iff } x \in \text{dom}(\tau) \text{ and } \tau(x) \in 'p_i' \\ \mathcal{M}_T, \tau, x \models \perp & \\ \mathcal{M}_T, \tau, x \models \varphi \rightarrow \psi &\text{ iff } \mathcal{M}_T, \tau, x \models \varphi \text{ or } \mathcal{M}_T, \tau, x \models \psi \\ \mathcal{M}_T, \tau, x \models \Box \varphi &\text{ iff } \mathcal{M}_T, \sigma, x \models \varphi \text{ for all } \sigma \in \mathcal{H} \\ \mathcal{M}_T, \tau, x \models \Box^p \varphi &\text{ iff } \mathcal{M}_T, \tau, y \models \varphi \text{ for all } y \in \text{dom}(\tau) \text{ with } y < x \\ \mathcal{M}_T, \tau, x \models \Box^F \varphi &\text{ iff } \mathcal{M}_T, \tau, y \models \varphi \text{ for all } y \in \text{dom}(\tau) \text{ with } y > x \end{aligned}$$

Logical Consequence: $\Gamma \models \varphi$ just in case for all task models \mathcal{M}_T , all world histories τ , and all times $x \in \text{dom}(\tau)$, if $\mathcal{M}_T, \tau, x \models \gamma$ for all $\gamma \in \Gamma$, then $\mathcal{M}_T, \tau, x \models \varphi$.