POLYPTYCH ISOTROPY WEIGHTS

GENERAL NOTES

ABSTRACT

Calculations for the isotropy data of the compactified hypertoric manifolds.

1 Example: $M = T^*\mathbb{CP}^1$

Short exact sequence for the usual Delzant construction of \mathbb{CP}^1 :

$$\{1\} \longrightarrow K \cong S^1 \stackrel{t \longmapsto (t,t)}{\longleftarrow} T^2 \xrightarrow[(a,b)\longmapsto ab^{-1}]{} T^2/K \cong T^1 \longrightarrow \{1\}.$$

The induced action of K on $T^*\mathbb{C}^2$ is thus

$$t \cdot (z|w) \longmapsto (t,t) \cdot (z_1, z_2 | w_1, w_2) = (tz_1, tz_2 | t^{-1}w_1, t^{-1}w_2),$$

which is Hamiltonian with associated moment map

$$\mu_{\mathbb{R}}: T^*\mathbb{C} \longrightarrow \mathbb{R}; \qquad \mu_{\mathbb{R}}(z \, | \, w) = |z_1|^2 + |z_2|^2 - |w_1|^2 - |w_2|^2.$$

For some $a \in \mathbb{Z}_{>0}$, take the hyperkähler quotient of $T^*\mathbb{C}$ to get

$$M:=T^*\mathbb{C} /\!\!/\!/ K$$

2 Example: $M=T^*(\mathbb{CP}^2\times\mathbb{CP}^2)$ (Non-Convex Core)

2.1 Construction

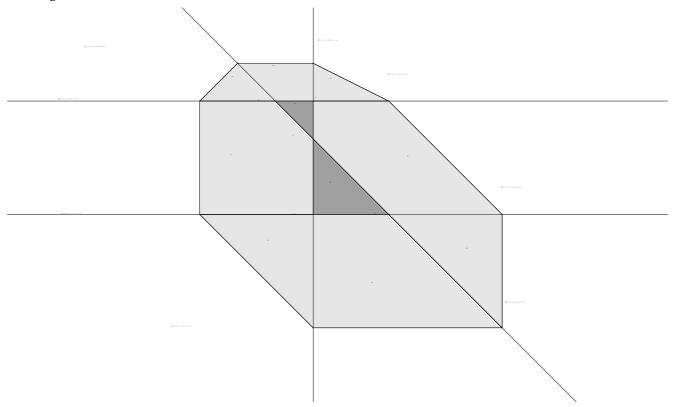
Quotient relations arising from $K \cong T^2$:

$$[sz_1:sz_2:sz_3:z_4\,|\,s^{-1}w_1:s^{-1}w_2:s^{-1}w_3:w_4] = [z_1:z_2:z_3:z_4\,|\,w_1:w_2:w_3:w_4],$$

and

$$[z_1:tz_2:z_3:tz_4\,|\,w_1:t^{-1}w_2:w_3:t^{-1}w_4]=[z_1:z_2:z_3:z_4\,|\,w_1:w_2:w_3:w_4].$$

2.2 Figure



2.3 Isotropy Weights

$$Q_{12}^{(1)}$$
:

$$Q_{12}^{(1)} = \left([0:0:z_3:z_4\,|\,0:w_2:0:0],\xi\right), \text{ with } |w_2|^2 = a,\, \xi = 0.$$

has isotropy weights

$$([sx_1:tx_2:z_3:z_4\,|\,s^{-1}y_1:t^{-1}w_2:y_3:y_4],\xi) \sim ([sx_1:tx_2:z_3:z_4\,|\,s^{-1}ty_1:w_2:ty_3:ty_4],t\xi)$$

$$\implies (sz_1,tz_2,s^{-1}tw_1,t\xi) \longleftrightarrow (s,t,s^{-1}t,t),$$

so normal weights $(s, s^{-1}t)$ from (z_1, w_1) respectively, and inwards-pointing weight t with multiplicity 2 coming from z_2 and ξ , since $|w_2|$ achieves its maximum at $Q_{12}^{(1)}$.

 $Q_{12}^{(2)}$:

$$Q_{12}^{(2)} = ([0:0:z_3:z_4 | w_1:0:0:0], \xi)$$

has isotropy weights

$$([sx_1:tx_2:z_3:z_4\,|\,s^{-1}w_1:t^{-1}y_2:y_3:y_4],\xi) \sim ([sx_1:tx_2:z_3:z_4\,|\,w_1:st^{-1}y_2:sy_3:sy_4],s\xi) \\ \Longrightarrow (sz_1,tz_2,s^{-1}tw_1,t\xi) \longleftrightarrow (s,t,st^{-1},s).$$

so normal weights (t, st^{-1}) from (z_2, w_2) respectively, and inwards-pointing weight s with multiplicity 2 coming from z_1 and ξ , since $|w_1|$ achieves its maximum at $Q_{12}^{(2)}$.

 $Q_{23}^{(2)}$:

$$Q_{23}^{(2)} = ([z_1:0:0:z_4\,|\,0:0:w_3:0],\xi)$$

has isotropy weights

$$([sz_1:tx_2:x_3:z_4\,|\,s^{-1}y_1:t^{-1}y_2:w_3:y_4],\xi) \sim ([z_1:s^{-1}tx_2:s^{-1}x_3:z_4\,|\,y_1:st^{-1}y_2:sw_3:y_4],\xi)$$

$$\sim ([z_1:s^{-1}tx_2:s^{-1}x_3:z_4\,|\,s^{-1}y_1:t^{-1}y_2:w_3:s^{-1}y_4],s^{-1}\xi)$$

$$\Longrightarrow (s^{-1}tz_2,s^{-1}w_1,t^{-1}w_2,s^{-1}\xi) \longleftrightarrow (s^{-1}t,s^{-1},t^{-1},s^{-1}).$$

so normal weights $(s^{-1}t, t^{-1})$ from (z_2, w_2) respectively, and inwards-pointing weight s^{-1} with multiplicity 2 coming from w_1 and ξ , since $|z_1|$ achieves its maximum at $Q_{23}^{(2)}$.

 $Q_{23}^{(3)}$:

$$Q_{23}^{(3)} = ([z_1:0:0:z_4\,|\,0:w_2:0:0],\xi)$$

has isotropy weights

$$([sz_1:tx_2:x_3:z_4\,|\,s^{-1}y_1:t^{-1}w_2:y_3:y_4],\xi) \sim ([z_1:s^{-1}tx_2:s^{-1}x_3:z_4\,|\,y_1:st^{-1}w_2:sy_3:y_4],\xi)$$

$$\sim ([z_1:s^{-1}tx_2:s^{-1}x_3:z_4\,|\,s^{-1}ty_1:w_2:ty_3:s^{-1}ty_4],s^{-1}t\xi)$$

$$\Longrightarrow (s^{-1}z_3,s^{-1}tw_1,tw_3,s^{-1}t\xi) \longleftrightarrow (s^{-1},s^{-1}t,t,s^{-1}t).$$

so normal weights (s^{-1}, t) from (z_3, w_3) respectively, and inwards-pointing weight $s^{-1}t$ with multiplicity 2 coming from w_1 and ξ , since $|z_1|$ and $|z_4|$ achieve their maximum at $Q_{23}^{(3)}$. (???)

 $Q_{14}^{(4)}$:

$$Q_{14}^{(4)} = ([z_1 : z_2 : 0 : 0 | 0 : 0 : w_3 : 0], \xi)$$

has isotropy weights

$$([sz_1:tz_2:x_3:x_4\,|\,s^{-1}y_1:t^{-1}y_2:w_3:y_4],\xi) \sim ([z_1:s^{-1}tz_2:s^{-1}x_3:x_4\,|\,y_1:st^{-1}y_2:sw_3:y_4],\xi) \\ \sim ([z_1:z_2:s^{-1}x_3:st^{-1}x_4\,|\,y_1:y_2:sw_3:s^{-1}ty_4],\xi) \\ \sim ([z_1:z_2:s^{-1}x_3:st^{-1}x_4\,|\,s^{-1}y_1:s^{-1}y_2:w_3:s^{-2}ty_4],s^{-1}\xi) \\ \Longrightarrow (st^{-1}z_4,s^{-1}w_1,s^{-2}tw_4,s^{-1}\xi) \longleftrightarrow (st^{-1},s^{-1},s^{-2}t,s^{-1}).$$

so normal weights $(st^{-1}, s^{-2}t)$ from (z_4, w_4) respectively, and inwards-pointing weight s^{-1} with multiplicity 2 coming from w_1 and ξ , since $|z_1|$ achieves its maximum at $Q_{14}^{(4)}$.

 $Q_{34}^{(4)}$:

$$Q_{34}^{(4)} = ([0:z_2:z_3:0 | w_1:0:0:0], \xi)$$

has isotropy weights

$$([sx_1:tz_2:z_3:x_4\,|\,s^{-1}w_1:t^{-1}y_2:y_3:y_4],\xi) \sim ([sx_1:z_2:z_3:t^{-1}x_4\,|\,s^{-1}w_1:y_2:y_3:ty_4],\xi)$$

$$\sim ([sx_1:z_2:z_3:t^{-1}x_4\,|\,w_1:sy_2:sy_3:sty_4],s\xi)$$

$$\implies (sz_1,t^{-1}z_4,stw_4,s\xi) \longleftrightarrow (s,t^{-1},st,s).$$

so normal weights (t^{-1}, st) from (z_4, w_4) respectively, and inwards-pointing weight s with multiplicity 2 coming from z_1 and ξ , since $|w_1|$ achieves its maximum at $Q_{34}^{(4)}$.

 $Q_{34}^{(3)}$:

$$Q_{34}^{(3)} = ([0:z_2:0:0|w_1:0:0:w_4],\xi)$$

has isotropy weights

$$([sx_1:tz_2:x_3:x_4\,|\,s^{-1}w_1:t^{-1}y_2:y_3:w_4],\xi) \sim ([sx_1:tz_2:x_3:x_4\,|\,s^{-1}w_1:t^{-1}y_2:y_3:w_4],\xi)$$
$$\sim ([sx_1:tz_2:x_3:x_4\,|\,s^{-1}w_1:t^{-1}y_2:y_3:w_4],\xi)$$
$$\Longrightarrow () \longleftrightarrow ().$$

so normal weights () from () respectively, and inwards-pointing weight? with multiplicity 2 coming from? and ξ , since |?| achieves its maximum at $Q_{34}^{(3)}$.

$$Q_{14}^{(1)}$$
:

$$Q_{14}^{(1)} = ([0:z_2:0:0\,|\,0:0:w_3:w_4],\xi)$$

has isotropy weights

$$([sx_1:tz_2:x_3:x_4 | s^{-1}y_1:t^{-1}y_2:w_3:w_4],\xi) \sim ([sx_1:tz_2:x_3:x_4 | s^{-1}y_1:t^{-1}y_2:w_3:w_4],\xi)$$
$$\sim ([sx_1:tz_2:x_3:x_4 | s^{-1}y_1:t^{-1}y_2:w_3:w_4],\xi)$$
$$\Longrightarrow () \longleftrightarrow ().$$

so normal weights () from () respectively, and inwards-pointing weight ? with multiplicity 2 coming from ? and ξ , since |?| achieves its maximum at $Q_{14}^{(1)}$.

References