Geometric Quantisation

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Classical Mechanics

- In classical mechanics, the space of all possible states of a system is given by *phase space*, *M*.
- "State" means not just the *position* but also the *momentum* (of a particle).

Example

For a particle of unit mass, energy function $E: M \to \mathbb{R}$:

$$E(x,p)=\frac{p^2}{2}+V(x).$$

$$\leadsto \frac{\partial E}{\partial x} = \frac{\partial V}{\partial x} = -\frac{\partial p}{\partial t}, \text{ and } \frac{\partial E}{\partial p} = p = \frac{\partial x}{\partial t}.$$

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Quantum Mechanics

- Still have phase space M and energy E, but replaces states with wavefunctions.
- ► Classical energy function $E: M \to \mathbb{R}$ now becomes an operator $\hat{E}: M \to M$.

Question

For a phase space M, what is Q(M)?

- ▶ Phase space M represents the position and momentum of a system, with energy function $E: M \to \mathbb{R}$.
- Quantisation Q(M) should then represent the wavefunctions $\psi: M \to \mathbb{C}$, with operators $\hat{E}: M \to M$.

Baby Quantisation

- $M = \mathbb{R}^6 \cong \mathbb{C}^3 \text{ via } (x_j, p_j) \leadsto z_j = p_j + ix_j \in \mathbb{C}^3.$
- Energy function and operator:

$$\phi(z) = \frac{\|z\|^2}{2} \leadsto \hat{\mathcal{Q}}(\phi) = \sum_{j=1}^3 \left(q_j \frac{\partial}{\partial p_j} - p_j \frac{\partial}{\partial q_j} \right).$$

- $k \in \mathbb{N}$, get level-set $E_k := \phi^{-1}(k) \cong S^5 \subseteq \mathbb{R}^6$.
- Each E_k has an S^1 -symmetry:

$$e^{i\theta}\cdot(z_1,\ldots,z_n)=(e^{i\theta}z_1,\ldots,e^{i\theta}z_n) \rightsquigarrow \phi(e^{i\theta}\cdot z)=\phi(z)=k.$$

• "Identify" the S^1 -symmetries of S^5 , *i.e.* consider points in the same orbit as identical.

Dimensions and Lattice Points

Fact

On E_k , eigenvectors for $\hat{Q}(\phi)$ are homogeneous polynomials in 3 variables of degree k:

$$\mathcal{Q}(E_k) \cong \{z_1^{n_1} z_2^{n_2} z_3^{n_3} : n_1 + n_2 + n_3 = k\},$$

 $\dim \mathcal{Q}(E_k) = \#(k \cdot \Delta \cap \mathbb{Z}^2).$

Half-Spaces and Hyperplanes

Where My Research Fits In

Before Edinburgh

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