

Action	Object	Change Document	Status
Add Components			
Add	C1	To Psocrobot.PcbDoc	
Add	C2	To Psocrobot.PcbDoc	
Add	C3	To Psocrobot.PcbDoc	
Add	C4	To Psocrobot.PcbDoc	
Add	C5	To Psocrobot.PcbDoc	
Add	C6	To Psocrobot.PcbDoc	
Add	C7	To Psocrobot.PcbDoc	
Add	C8	To Psocrobot.PcbDoc	
Add	C9	To Psocrobot.PcbDoc	
Add	C10	To Psocrobot.PcbDoc	
Add	C11	To Psocrobot.PcbDoc	
Add	C12	To Psocrobot.PcbDoc	
Add	C13	To Psocrobot.PcbDoc	
Add	C14	To Psocrobot.PcbDoc	
Add	C15	To Psocrobot.PcbDoc	
Add	C16	To Psocrobot.PcbDoc	
Add	C17	To Psocrobot.PcbDoc	
Add	CON1	To Psocrobot.PcbDoc	
Add	CON2	To Psocrobot.PcbDoc	
Add	CON4	To Psocrobot.PcbDoc	
Add	CON5	To Psocrobot.PcbDoc	
Add	CON6	To Psocrobot.PcbDoc	
Add	CON7	To Psocrobot.PcbDoc	
Add	CON8	To Psocrobot.PcbDoc	
Add	J1	To Psocrobot.PcbDoc	
Add	L1	To Psocrobot.PcbDoc	
Add	R1	To Psocrobot.PcbDoc	
Add	R2	To Psocrobot.PcbDoc	
Add	R3	To Psocrobot.PcbDoc	
Add	U1	To Psocrobot.PcbDoc	
Add	U2	To Psocrobot.PcbDoc	
Add	U3	To Psocrobot.PcbDoc	
Add	U4	To Psocrobot.PcbDoc	
Add	U5	To Psocrobot.PcbDoc	

Action	Object	Change Document	Status
Add Nets			
Add	+5V	To Psocrobot.PcbDoc	
Add	AGND	To Psocrobot.PcbDoc	
Add	GND	To Psocrobot.PcbDoc	
Add	NetC7_2	To Psocrobot.PcbDoc	
Add	NetC8_2	To Psocrobot.PcbDoc	
Add	NetC9_1	To Psocrobot.PcbDoc	
Add	NetCON1_1	To Psocrobot.PcbDoc	
Add	NetCON1_2	To Psocrobot.PcbDoc	
Add	NetCON2_1	To Psocrobot.PcbDoc	
Add	NetCON2_2	To Psocrobot.PcbDoc	
Add	NetCON3_1	To Psocrobot.PcbDoc	
Add	NetCON4_1	To Psocrobot.PcbDoc	
Add	NetCON4_2	To Psocrobot.PcbDoc	
Add	NetCON6_1	To Psocrobot.PcbDoc	
Add	NetCON7_1	To Psocrobot.PcbDoc	
Add	NetJ1_3	To Psocrobot.PcbDoc	
Add	NetJ1_4	To Psocrobot.PcbDoc	
Add	NetL1_1	To Psocrobot.PcbDoc	
Add	NetL1_2	To Psocrobot.PcbDoc	
Add	NetR1_2	To Psocrobot.PcbDoc	
Add	NetU1_15	To Psocrobot.PcbDoc	
Add	NetU1_16	To Psocrobot.PcbDoc	
Add	NetU1_17	To Psocrobot.PcbDoc	
Add	NetU1_19	To Psocrobot.PcbDoc	
Add	NetU1_21	To Psocrobot.PcbDoc	
Add	NetU1_22	To Psocrobot.PcbDoc	
Add	NetU1_23	To Psocrobot.PcbDoc	
Add	NetU2_7	To Psocrobot.PcbDoc	
Add	NetU3_3	To Psocrobot.PcbDoc	
Add	PGND	To Psocrobot.PcbDoc	
Add	VCC	To Psocrobot.PcbDoc	
Add	VMOT	To Psocrobot.PcbDoc	

Add Component Classes			
Add	top	To Psocrobot.PcbDoc	
Add	U_motor	To Psocrobot.PcbDoc	
Add	U_Psoc-robot	To Psocrobot.PcbDoc	
Add	U_PSU	To Psocrobot.PcbDoc	
Add	U_Reciever	To Psocrobot.PcbDoc	
Add	U_UltraSoonSensor	To Psocrobot.PcbDoc	

Add Rooms			
Add	Room top (Scope=InComponentClass('top')) TopLayer	To Psocrobot.PcbDoc	
Add	Room U_motor (Scope=InComponentClass('U_motor')) TopLayer	To Psocrobot.PcbDoc	
Add	Room U_Psoc-robot (Scope=InComponentClass('U_Psoc-robot')) TopLayer	To Psocrobot.PcbDoc	
Add	Room U_PSU (Scope=InComponentClass('U_PSU')) TopLayer	To Psocrobot.PcbDoc	
Add	Room U_Reciever (Scope=InComponentClass('U_Reciever')) TopLayer	To Psocrobot.PcbDoc	
Add	Room U_UltraSoonSensor (Scope=InComponentClass('U_UltraSoonSensor')) TopLayer	To Psocrobot.PcbDoc	