SONAR: Sentence-Level Multimodal and Language-Agnostic Representations

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Abstract

We introduce SONAR, a new multilingual and multimodal fixed-size sentence embedding space. Our single text encoder, covering 200 languages, substantially outperforms existing sentence embeddings such as LASER3 and LabSE on the xsim and xsim++ multilingual similarity search tasks. Speech segments can be embedded in the same SONAR embedding space using language-specific speech encoders trained in a teacher-student setting on speech transcription data. encoders outperform existing speech encoders on similarity search tasks. We also provide a text decoder for 200 languages, which allows us to perform text-to-text and speech-to-text machine translation, including for zero-shot language and modality combinations. Our text-to-text results are competitive compared to the state-of-theart NLLB 1B model, despite the fixed-size bottleneck representation. Our zero-shot speech-to-text translation results compare favorably with strong supervised baselines such as Whisper.

1 Introduction

Representation learning of sentences has been widely studied in recent years for different purposes: from classification of sentences (Devlin et al., 2018) to multilingual representations for translation purposes (Pham et al., 2019). Different pre-training objectives were explored to build contextual representations from sentences (Devlin et al., 2018; Conneau et al., 2019; Clark et al., 2020). However, these methods often lack sentence-level objectives, making it difficult to evaluate the semantic similarity between two sentences. On the other hand, several works focused on learning sentence embeddings (Cer et al., 2018; Conneau et al., 2017; Reimers and

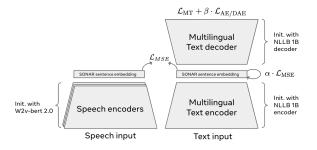


Figure 1: SONAR architecture.

Gurevych, 2019), aiming to encode sentences with similar meanings closely in the sentence embedding space. Artetxe and Schwenk (2019); Feng et al. (2020) extended this idea to multilingual sentences, enabling the semantic comparison between sentences from different languages. This was used to perform bitext mining at scale, to automatically align monolingual sentences from Common Crawl (Schwenk et al., 2021). This mined bitext data can be successfully used to train state-of-the art machine translation (MT) models (Schwenk et al., 2021; NLLB Team et al., 2022). In recent research, we may distinguish three main approaches to building multilingual fixed-size sentence representations.

Encoder-only approaches such as (Feng et al., 2020), which learn sentence embeddings for text, based on a siamese encoder architecture. Contrastive loss is often used to learn similar representations for different text translations while avoiding collapse (i.e. avoid to predict the same embedding for every input)

Encoder-decoder approaches such as (Artetxe and Schwenk, 2019), which learn sentence embeddings with a translation objective, that can be computed thanks to an additional decoder. The main difference with classical sequence-to-sequence model is the bottleneck layer, or pooling function, that computes a fixed-size sentence representation between the encoder and the decoder.

Teacher-student approaches such as (Reimers and Gurevych, 2020; Heffernan et al., 2022), which extend a (possibly monolingual) preexisting sentence embedding space to new languages with a teacher-student learning strategy. The existing embedding space is used as teacher to train student encoders for new languages. Bitext training data is used for this kind of training, where the sentence in the new language is encoded with a trained encoder, while its translation in another supported language is encoded with the pre-existing encoder as target. The same teacher-student approach can be used to extend a text-only multilingual sentence embedding space to the speech modality by training speech encoders (Duquenne et al., 2021; Khurana et al., 2022). These speech encoders can be used to perform speech-to-text or speech-to-speech translation mining (Duquenne et al., 2022a).

In this work, we used an encoder-decoder approach to build our sentence embedding space SONAR on text data only. We then used a teacher-student approach to train speech encoders for the same space.

Our motivation for using an encoder-decoder approach for the initial text-based training phase is twofold. First, a multilingual decoder is trained along the multilingual encoder, which opens possibilities such as zero-shot MT (Duquenne et al., 2022b). Second, a pre-trained state-of-the-art MT encoder-decoder model can be used to initialize the whole encoder-decoder architecture, in this work we used NLLB 1B dense model as initialization. In contrast to previous work, we study the effect of different training objective functions on the properties of the resulting embedding space. More precisely, we combine translation, auto-encoding and denoising objectives, together with a crosslingual similarity objective in the sentence embedding space.

In a second step, we train speech student encoders using our multilingual text encoder as a teacher. We demonstrate the cross-modal similarity search and speech translation¹ capabilities of the resulting SONAR framework.

In summary, the main contributions of the SONAR (Sentence-level multimOdal and laNguage-Agnostic Representations) model are as follows:

- We explore different training objectives to learn a multilingual sentence embedding space initialized from the NLLB 1B model, thoroughly comparing the different approaches on a wide range of decoding and similarity search evaluations
- This yield a single sentence encoder for 200 languages which significantly outperform state-of-the-art sentence embedding approaches;
- We trained speech encoders for 37 languages using teacher-student training
- We provide a text decoder for 200 languages enabling (zero-shot) text and speech translation
- We analyzed the cross-lingual and crossmodal similarity search and decoding capabilities of our SONAR framework.
- The SONAR text and speech encoders as well as the text decoders are freely available at https://github.com/facebookresearch/SONAR.

2 Related work

Multilingual sentence representations Many works have studied how to efficiently learn multilingual representations of sentences. Some of them focused on variable-length representations of sentences, learning high-level contextual representations for each sub-word like multilingual BERT (Devlin et al., 2018) or XLM-R (Conneau et al., 2020). Others learnt fixed-size sentence representations by integrating sentence-level objectives in the training. It is the case for example of sentence-BERT (Reimers and Gurevych, 2019), which was initially trained on English text only, and later extended to other languages with a teacher-student approach (Reimers and Gurevych, 2020). The English model behaves as a teacher to train a multilingual encoder covering other languages. The student model is initialized with the XLM-R pretrained encoder and fine-tuned using bitext training data. The original English encoder, which is kept frozen, is used to generate an embedding for the English translation of each sentence, which then serves as a target for the student encoder via a regression loss.

¹The term "speech translation" customarily denotes speech-to-text translation.

Bitexts can also be used in other ways to train multilingual sentence embedding spaces. LASER (Artetxe and Schwenk, 2019) is an encoderdecoder architecture, with a fixed-size sentence representation between the encoder and the decoder, trained with a translation objective. The orginal LASER covers 93 languages. Its decoder was originally used for training only, as the encoder itself defines the sentence embedding space. However, recent work such as (Duquenne et al., 2022b) showed that it is possible to learn high quality decoders for LASER representations into multiple languages, thereby enabling zero-shot MT on unseen languages directions. Similarly to Reimers and Gurevych (2020), Heffernan et al. (2022) introduced LASER3, extending LASER to new languages, including low-resource languages, using a teacher-student approach. Finally, LaBSE (Feng et al., 2020) uses a dual-encoder approach with and additive margin softmax objective (Yang et al., 2019). It highlights the benefits of initializing encoders with multilingual pre-trained models and covers 109 languages.

Joint speech/text sentence representations There has been a large body or research on unsupervised representation learning for monolingual (Baevski et al., 2020) and multilingual speech (Babu et al., 2021), with recently w2v-bert (Chung et al., 2021) that combines contrastive learning and masked language modeling to learn selfsupervised representations from speech. Other works explored multilingual and multimodal (speech/text) pre-training methods, including mSLAM (Bapna et al., 2022). Finally, Duquenne et al. (2021), followed by Khurana et al. (2022), introduced multilingual and multimodal sentence embeddings, extending a pre-existing multilingual text sentence embedding space to the speech modality with a distillation approach. Duquenne et al. (2022b, 2023) also showed that it is possible to efficiently decode multilingual speech sentence embeddings with decoders trained on text sentence embeddings into different languages, to perform zero-shot speech translation.

3 Methodology

To build our multilingual and multimodal sentence embedding space SONAR, we follow a two-step training strategy, inspired by Duquenne et al. (2021, 2022b). The first step is to build a sentence embedding space for text: we are building a

multilingual sentence embedding space based on an encoder-decoder approach. The second step extends the multilingual text sentence embedding space to the speech modality, using a teacherstudent approach.

3.1 Multilingual sentence representations for text

Contrarily to LASER's bidirectional LSTM architecture (Artetxe and Schwenk, 2019), SONAR relies on a Transformer encoder-decoder architecture, initialized with pre-trained MT model However, as opposed to standard weights. sequence-to-sequence architectures for MT, the architecture we use to train SONAR on parallel text data goes through a single vector bottleneck that represents the full sentence and does not use token-level cross-attention. The fixed-size sentence representation is computed by pooling the token-level outputs of the encoder. Instead of doing cross-attention on a variable-length sequence of encoder outputs, the decoder only attends to this single vector at each decoding step. Different pooling methods can be used to compute this fixed-size representation, including max- and mean-pooling on token-level encoder outputs, as well as the encoder output for a special BOS to-

Contrarily to LASER (Artetxe and Schwenk, 2019), we do not only train our encoder-decoder architecture using an MT objective only. We investigated several other objectives and combinations thereof and analyzed their effect on the sentence embedding space and the decoding performance of the resulting model. We introduce below the different objectives used to train our encoder-decoder architecture.

Translation objective Following (Artetxe and Schwenk, 2019) work, we used parallel data to train our encoder-decoder architecture with a translation objective. To better understand the motivation behind this objective, let us take this example: Given a triplet of translations x, y, z, where z is the English translation, decoding x and y into English may be easily achieved by the decoder if the sentence representation of these two input sentences are similar in the sentence embedding space. Training a encoder-decoder architecture on a translation objective may end up in this potential local minimum where translations are encoded closely to one another, so as to be

English sentence from FLORES:

Dr. Ehud Ur, professor of medicine at Dalhousie University in Halifax, Nova Scotia and chair of the clinical and scientific division of the Canadian Diabetes Association cautioned that the research is still in its early days.

Auto-encoding of the sentence with SONAR:

Dr. Ehud Ur, professor of medicine at Dalhousie University in Halifax, Nova Scotia and chairman of the clinical and scientific division of the Canadian Diabetes Association warned that the research is still in its early stages.

Figure 2: Example of a long sentence with named entities auto-encoded with SONAR.

decoded into the same target language sentence. However, there is no guarantee to converge to this local minimum. Nothing explicitly constrains a sentence in a language and its translation in another language to be encoded closely to one another. As a result, other local minima are possible, where translations are not encoded closely but still decoded into the same sentence for a given target language. To mitigate this, shallow decoders were used by Artetxe and Schwenk (2019): a deeper decoder can more easily decode different points into the same sentence, whereas a shallower decoder is more likely to need two vectors to be very similar whenever they must be decoded into the same sentence.

Auto-encoding and denoising auto-encoding objective Auto-encoders have been widely used to build representations. It has the advantage to encourage encoding fine-grained details of the input. However, this objective by itself is not likely to learn semantic representation of sentences. Moreover, this objective is much simpler to learn compared to a translation objective, which makes the combination of these two objectives difficult. To mitigate these issues, Liu et al. (2020) introduce a *denoising* auto-encoding task, which has proven to be a good pre-training objective for translation tasks.

MSE loss objective in the sentence embedding space Teacher-student approaches to multilingual sentence embedding space learning have shown that ensuring that translations of a same sentence are embedded close to one another in the sentence embedding space with an MSE loss works really well (Reimers and Gurevych, 2020; Heffernan et al., 2022). However, using this kind of loss without a frozen pre-existing teacher embedding space would lead to collapse (all inputs mapped to the same embedding), which is why contrastive learning methods were introduced to learn multilingual sentence embeddings from scratch (Feng et al., 2020). However, combining

an MSE loss with a translation objective and/or a denoising auto-encoding objective could also prevent collapse from happening, as the model is forced to keep embeddings distinct to encode and decode different sentences.

Decoder finetuning Duquenne et al. (2022b) demonstrated that learning deep decoders for an existing sentence embedding space (in their case, LASER) can significantly improve translation and auto-encoding performance. While keeping the existing embedding space unchanged, such decoders greatly improve the decoding of sentence embeddings, therefore significantly improving auto-encoding and translation performance when combined with compatible encoders. This is of great interest for zero-shot (possibly crossmodal) translation, as shown by Duquenne et al. (2023). In this paper, we introduce a decoder fine-tuning method called random interpolation decoding. Based on a trained encoder-decoder model with a bottleneck representation between the encoder and the decoder, we freeze the encoder weights and fine-tune the decoder weights only on a specific decoding task: Given a bitext x, y, we encode x and y with the frozen encoder, randomly draw z as a random interpolation of x and y embeddings, and learn to decode sentence embedding z into y. This can be viewed as a continuous combination of translation and auto-encoding tasks.

3.2 Multilingual sentence representations for speech

Duquenne et al. (2021) introduced the first semantic sentence embeddings for multilingual speech. Their method follows a teacher-student approach, where the teacher model is an encoder for multilingual sentence embeddings trained on text. We follow the same approach but using our newly trained text sentence embedding space as teacher: we trained a speech student encoder to encode audios into fixed-size representations and minimize the MSE loss between the transcription sentence embeddings and the trained speech sentence em-

beddings. Written translation embeddings could also be used as targets in this teacher-student approach (Duquenne et al., 2021). However, in this work, we only focus on transcriptions as targets, using written translations is left for future work. As in previous work, we leveraged self-supervised pre-trained models, for our speech encoders training, using a w2v-bert pretrained model as initialization.

4 Evaluations

To evaluate the semantic properties of the resulting sentence embedding space, we relied on a number of evaluation tasks on both text and speech modalities:

4.1 Evaluations on text

xsim Cross-lingual similarity search, also called xsim,² evaluates the similarity between sentence embeddings across languages. Given a test dataset of bitexts, translations are encoded into the multilingual sentence embedding space and cosine similarity between all embeddings are computed. For each test instance, if the two corresponding translations are not the closest, we count it as an error in order to compute an error rate on the whole test set.

xsim++ More recently, xsim++ was introduced as a more semantically challenging similarity search task (Chen et al., 2023).² It augments the test set with hard negative examples for the similarity search, generating several modified versions of ground truth examples based on causality alternation, entity replacement and number replacement.

Translation tasks Multilingual embeddings are decoded into other target languages to perform MT. We report spBLEU (flores200) scores and COMET scores on the generated translations. Decoding sentence embeddings into other languages partially evaluates how much information is encoded in sentence embeddings, which is complementary to xsim and xsim++ evaluations. However, please note that information may also be restored from the internal language modeling capabilities of the decoder, and not from the sentence embeddings themselves.

Auto-encoding task Similarly to translation tasks, we decode sentence embedding in the same language to perform auto-encoding and evaluate the content preservation of this operation.

All these evaluations for text were performed on FLORES-200 devtest set,³ which provides an N-way parallel corpus of translations in 200 languages.

4.2 Evaluations on speech

xsim for speech We follow Duquenne et al. (2021) and calculate cross-modal and -lingual similarity search on the FLEURS speech translation test set (Conneau et al., 2023). It follows the xsim evaluation presented above, but xsim is run on speech embeddings against English text translation embeddings.

xsim++ for speech In addition to xsim computation for speech, we augment the English texts with challenging negative examples from the xsim++ modified English sentences of FLORES.

Zero-shot speech-to-text translation Following Duquenne et al. (2022b), speech student encoders can be combined with text decoders at inference time. Since the speech encoder were trained on ASR data only and the SONAR text decoder was only trained on text and has never seen speech embeddings during training, this corresponds to zero-shot speech-to-text translation. Similarly to text, it enables evaluating the content encoding in the speech embeddings. It also evaluates the compatibility between speech and text representations.

Zero-shot Automatic Speech Recognition: we also decode speech embeddings in the same language to perform speech recognition.

All these evaluations for speech were performed on FLEURS test set (Conneau et al., 2023), a N-way parallel speech dataset in 102 languages built on top of the text FLORES-101 benchmark.

5 Experiments on text

In this paper, we first trained a multilingual sentence embedding space using an encoder-decoder architecture on text, with fixed-representation of sentences between the encoder and the decoder.

²https://github.com/facebookresearch/ LASER

³https://github.com/facebookresearch/ flores/tree/main/flores200

Method	X-eng↑	eng-X↑	AE↑	xsim↓	xsim++↓
$\mathcal{L}_{ ext{MT}}$	33.2	21.1	28.6	1.3	19.6
$\mathcal{L}_{ ext{MT}} + \mathcal{L}_{ ext{AE}}$	17.6	18.6	94.6	15.9	65.7
$\mathcal{L}_{ ext{MT}} + 0.1 \cdot \mathcal{L}_{ ext{DAE}}$	31.6	20.9	41.6	2.6	26.2
$\mathcal{L}_{ ext{MT}} + 0.1 \cdot \mathcal{L}_{ ext{MSE}}$	31.7	20.2	27.2	1.3	14.3
SONAR sentence embedding space					
$\mathcal{L}_{\mathrm{MT}} + 0.1 \cdot \mathcal{L}_{\mathrm{MSE}} + 0.01 \cdot \mathcal{L}_{\mathrm{DAE}}$	32.9	20.7	32.4	1.4	15.2
$\mathcal{L}_{\mathrm{MT}} + 0.1 \cdot \mathcal{L}_{\mathrm{MSE}} + 0.01 \cdot \mathcal{L}_{\mathrm{DAE}}$ & fine-tuned dec.	32.7	21.6	41.7	1.4	15.2
MT topline					
NLLB 1B	35.2	24.9	39.0*	3.7*	49.6*
Similarity search baselines					
LaBSE	_	—	—	10.7	36.1
LASER3	_	_	_	5.1	36.4

Table 1: Text evaluations on FLORES200 devtest set, averaged on the 200 languages supported by NLLB 1B: translation spBLEU for X-eng and eng-X directions, auto-encoding spBLEU, xsim and xsim++ similarity search results on X-eng pairs. Results with * are zero-shot evaluations of NLLB 1B model which was not trained to optimize these tasks.

5.1 Training setup

We initialized our model with the NLLB 1B dense model (NLLB Team et al., 2022), that was trained on translation tasks with full cross-attention on variable length encoder outputs as it is commonly done for sequence-to-sequence MT model training. The model is composed of a 24 layers Transformer encoder and a 24 layers Transformer decoder and trained on a combination of human labeled data, back-translated data and mined data (NLLB Team et al., 2022). In order to build our fixed-size sentence representation, we added a pooling operation on the encoder outputs. Several pooling methods are possible: max-pooling as done in (Artetxe and Schwenk, 2019), meanpooling as done in (Reimers and Gurevych, 2019), or EOS pooling which use the output representation of the EOS special token appended at the end of sentences during NLLB training. Contrary to mean-pooling or EOS-pooling, max-pooling outputs a vector with a different range of values compared to NLLB training (due to the max operation), leading to worse results in our initial experiments. Since for EOS-pooling the training happened to be unstable during initial experiments, we focused on mean-pooling for the rest of our experiments. We trained our encoder-decoder model for 100k updates with same learning rate and batch size as NLLB training in the following experiments, unless explicitly specified. We used all bitext data used in the NLLB training, human labeled bitexts, back-translated data and mined data. This training dataset involves 200 target languages which contrasts with LASER training that only used English and Spanish as target languages. As presented in Section 3, we ran an extensive study on the use of different training objectives, namely translation objective (MT), auto-encoding objective (AE), denoising auto-encoding objective (DAE) and Mean Squared Error loss (MSE) in the sentence embedding space:

$$\mathcal{L} = \mathcal{L}_{MT} + \alpha \cdot \mathcal{L}_{MSE} + \beta \cdot \mathcal{L}_{AE/DAE}$$

We are using the same training data for autoencoding and translation objectives, inputting the target sentences instead of the source sentences to perform auto-encoding of target sentences only. Incorporating more monolingual data in the training for the auto-encoding task is left to future work.

5.2 Initial experiment with translation objective only

We report the results of our experiments on text sentence embedding modeling in Table 1. Our first experiment using only the translation objective for our encoder-decoder model with fixed-size intermediate representation gives surprisingly good translation performance, given the bottleneck between the encoder and the decoder. It yields -2 BLEU on X-eng direction and -3.8 BLEU on eng-X direction compared to NLLB 1B model with full-cross attention.

We notice that auto-encoding evaluation (AE) significantly lags behind NLLB 1B model. This result may come from an inductive bias of the

sequence-to-sequence architecture with full crossattention, that could bias the model towards copying encoder inputs.

xsim and xsim++ results are significantly better compared to previous work, namely LaBSE and LASER3, on our 200 languages of focus, with approximately 45% relative reduction of xsim++ error rate compared to the baseline models. Note that averaging NLLB 1B encoder outputs to perform similarity search already gives good xsim scores. This directly comes from the translation objective used during NLLB 1B training that encourages to encode multilingual sentences in similar ways for efficient cross-lingual transfer. However, the more difficult xsim++ evaluation remains challenging, in this zero-shot setting, for the original NLLB 1B model.

5.3 Experiments with auto-encoding objectives

Noticing the gap in the auto-encoding performance between the fixed-size bottleneck encoderdecoder model and NLLB 1B, we integrated an auto-encoding objective, hoping to close the gap with the NLLB 1B model. This model was only trained for 50k steps, as it converged quickly compared to other variants. We notice that autoencoding task is easy to learn, even with a fixedsize bottleneck between the encoder and the decoder, almost reaching 95 BLEU in average on the 200 languages of NLLB. This shows that a lot of information can be efficiently stored in a fixed-size representation and that the bottleneck should not be seen as an hard limitation. While the translation performance on eng-X tranlation directions is not that much impacted, we see a big drop in translation performance for X-eng directions (-15,6 BLEU) compared to the fixed-size bottleneck encoder-decoder model trained only on a translation task. Moreover, we see a big drop in both xsim and xsim++ evaluations showing that the model is not learning language-agnostic representations anymore, due to the auto-encoding objective that seems more easily optimized compared to the translation objective.

To mitigate the negative effects of the autoencoding objective, while improving the autoencoding performance at inference time, we switched to a denoising auto-encoding criterion, to avoid that the model overfits on the *copy* task. That would also make the task harder compared

Method	X-eng	eng-X
SONAR SONAR & fine-tuned dec.	85.9 85.9	83.4 84.2
Topline NLLB 1B	86.5	85.2

Table 2: Translation evaluations for X-eng and eng-X directions on FLORES200 devtest set: COMET scores averaged on 89 languages supported by both COMET and NLLB 1B models.

to simple auto-encoding and could be better combined with the non-trivial translation task. We also scaled down this denoising auto-encoding objective by a factor 0.1. This mostly mitigated the performance drops on translation tasks, while significantly boosting the auto-encoding task (+13 BLEU) compared to the translation-only model. However, the denoising auto-encoding criterion significantly affects the xsim and xsim++ scores. This again shows that auto-encoding affects the organization of the sentence embedding space, learning distinct representations for different languages to optimize auto-encoding.

5.4 Experiments with cross-lingual similarity objective

Motivated by the recent distillation approaches to extend a sentence embedding space to new languages, explicitly aligning languages with an MSE criterion in the embedding space, we explored the use of an auxiliary MSE loss in the sentence embedding space. This is in addition to the translation loss, with the hope to explicitly make translations closer in the embedding space. In Table 1, we notice that this new constraint degrades the decoding performance of the encoder-decoder model for both translation and auto-encoding tasks. However, it significantly boosts the xsim++ scores compared to the encoder-decoder model trained only on a translation task, with -5.3 xsim++ error rate reduction.

5.5 Training the SONAR embedding space

Based on the conclusions of the previously trained models, we combined the translation loss, the auxiliary MSE loss and the denoising auto-encoding loss, to create the SONAR embedding space. In this run, the denoising auto-encoding loss is further downscaled, motivated by the high xsim++

	fra	spa	swh	rus
X-eng BLEU				
SONAR & fine-tuned dec.	46.1	34.5	42.4	37.1
LASER3 $_{\mathrm{MSE}}$ & T-mod.	40.4	29.6	27.2	29.7
xsim++				
SONAR	4.8	7.9	7.1	6.5
Laser3 _{mse}	7.6	12.6	15.2	12.4

Table 3: Comparison to T-modules framework based on LASER embedding space. spBLEU scores for X-eng translation directions on FLORES200 devtest set and xsim++ for X-eng pairs on FLORES200 devtest set.

score of the previously trained sentence embedding space trained on denoising auto-encoding. First, in the same tendency from previous training with (denoising) auto-encoding objective, we notice a slight degradation in xsim++ scores when adding the denoising auto-encoding in addition to the MSE loss. However, this degradation is only 0.9% which can be considered as acceptable. Initial experiments on larger scaling factors for the denoising auto-encoding criterion further increased, as expected, the xsim++ degradation, and we thus decided to stick with a 0.01 scaling factor for the denoising auto-encoding objective. On the other hand, for our new SONAR model, we see improvements on translation tasks compared to the model trained on MT and MSE loss. This may be due to efficient mitigation of collapse that could happen with MSE loss, thanks to the denoising auto-encoding objective. also see big improvements in auto-encoding task (>+3.8 BLEU) compared to all models not trained with auto-encoding objectives. This variant seems to be the best setup in terms of sentence embedding space organization (following xsim and xsim++ scores) and decoding performance (following translation and auto-encoding evaluations). We also report the xsim and xsim++ results on the intersection of languages handled by LaBSE, LASER3 and SONAR in Table 4, and notice again that SONAR outperforms previous state-of-the-art sentence embedding spaces for multilingual similarity search.

Finally, we tried to improve the decoding performances of our architecture, freezing the embedding space and our multilingual encoder, while fine-tuning only the decoder. We used the *random interpolation decoding* method introduced in section 3, where we compute a random interpo-

	98 languages				
	xsim↓	$xsim++\downarrow$			
SONAR	0.1	9.3			
Laser3	1.1	27.5			
LaBSE	1.5	15.4			

Table 4: Comparison of similarity search results (error rates) on the intersection of languages handled by LaBSE, LASER3 and SONAR.

lation of the source and target sentence embeddings and learn to decode the target sentence tokens. As the encoder is frozen, the xsim and xsim++ scores won't change, but the decoding results will. With this decoder fine-tuning step, we notice similar translation results on the X-eng direction, while noticing a +0.9BLEU gain on the eng-X translation directions. More importantly, the auto-encoding performance is boosted by 9.3 BLEU with decoder fine-tuning method while the sentence embedding space was not affected. This finetuning step is trained for 50k additional steps.

We also evaluated the best performing models on translation tasks with COMET, which has proven to better correlate with human judgments compared to BLEU scores. We evaluated the two X-eng and eng-X directions involving the languages on which XLM-R was trained on, which are the languages supported by COMET (see Table 2). We see less that 1 point difference between our SONAR encoder-decoder model (with fine-tuned decoder) compared to NLLB 1B model for both eng-X and X-eng directions, showing the good quality of the translations.

The NLLB 1B model still represents a topline, and to evaluate our SONAR framework against a more fair baseline involving a fixed-size sentence representation between the encoder and the decoder, we compared our results to the decoding of LASER embeddings, recently introduced in T-modules (Duquenne et al., 2022b, 2023). As LASER3 encoders were trained with a cosine loss, the sentence embeddings cannot be efficiently decoded with T-modules decoder. This is why we trained new LASER3 encoders with MSE loss, and added back-translated data from NLLB project in addition to the original training data of LASER3 encoders. These newly trained LASER3 MSE encoders can be combined with T-modules decoder (Duquenne et al., 2023) to perform X-eng translation. We report the results on 4 languages French,

BLEU	fra-eng	spa-eng
SONAR mean-pooling	25.2	20.6
SONAR max-pooling	31.6	24.5
SONAR attention-pooling	33.3	25.5

Table 5: spBLEU X-eng zero-shot speech translation on FLEURS test set for different pooling methods.

Spanish, Swahili and Russian in Table 3 and notice big improvements using SONAR on both X-eng translation task and xsim++ evaluation. Please note that compared to previous work (Duquenne et al., 2022b), we are able to encode and decode 200 languages with a single encoder and a single decoder.

6 Experiments on speech

Based on the experiments and evaluations of multilingual sentence embedding spaces for text, we chose to focus only on the embedding space learnt with translation, denoising auto-encoding and MSE objectives which seems to be a good trade-off between good semantic representation (xsim and xsim++) and good decoding performance (translation and auto-encoding). We follow a teacher-student approach to extend this space to the speech modality for several languages. We first performed an initial extensive study on five languages only: English (eng), Spanish (spa), French (fra), Russian (rus) and Swahili (swh). We then scale to 37 languages.

6.1 Experiments on 5 languages

We use a pre-trained w2v-bert 600 million parameter model to initialize the speech encoders and train them on Common Voice 12 ASR training set (Ardila et al., 2019). For our English speech encoder, we also used ASR training data from Must-C (Di Gangi et al., 2019), Voxpopuli

	fra	spa	swh	rus
xsim				
SONAR	0.0	0.0	0.0	0.0
Laser3 $_{\mathrm{MSE}}$	0.0	0.0	0.0	0.3
xsim++				
SONAR	12.3	13.9	22.8	24.6
Laser3 mse	17.5	24.9	40.7	42.1

Table 6: Multilingual and multimodal similarity search evaluations on FLEURS test set: xsim and xsim++ error rates on speech translation X-eng pairs.

	fra	spa	swh	rus
Training hours				
SONAR/LASER ASR	0.8k	0.4k	0.3k	0.2k
Whisper ASR	10k	11k	0.01k	10k
Whisper ST	4k	7k	0.3k	8k
SONAR zero-shot ST				
SONAR	33.3	25.5	14.9	15.0
SONAR & fine-tuned dec.	33.4	24.8	15.6	14.6
Zero-shot ST baseline				
LASER3 MSE & T-mod	30.7	22.9	3.7	16.2
Supervised ST toplines				
Whisper Large v1	33.8	27.0	5.2	30.2
Whisper Large v2	34.9	27.2	7.6	31.1

Table 7: spBLEU scores on FLEURS test set for zeroshot Speech Translation on X-eng directions.

(Wang et al., 2021) and Librispeech (Panayotov et al., 2015). We tested different pooling methods, namely mean-pooling, max-pooling and attention-pooling. Attention-pooling is performed with a three layer transformer decoder architecture with cross-attention on the speech encoder outputs, in order to output a single vector as our speech sentence embedding. Best results are achieved with attention-pooling (see Table 5).

As a baseline, we compared our SONAR speech encoders to speech encoders trained with LASER as teacher (using our newly trained LASER3 MSE text encoders as teacher), with exact same training data and pre-trained w2v-bert model. We report the xsim and xsim++ cross-lingual and cross-modal results in Table 6 on FLEURS test set for foreign speech embeddings against English text embeddings. Similarly to what Chen et al. (2023) noticed on FLORES, xsim scores saturate to zero error rate on FLEURS test set, not providing useful insights on the multimodal sentence em-

src\tgt	eng	fra	spa	swh	rus	200 langs
eng	69.7	44.3	26.9	27.8	29.8	17.7
fra	33.4	64.1	21.5	18.2	23.3	13.4
spa	24.8	25.1	58.9	16.0	16.8	11.7
swh	15.6	13.5	9.0	25.7	9.8	7.0
rus	14.6	17.3	11.0	10.4	35.0	8.0

Table 8: spBLEU scores on FLEURS test set for zeroshot Speech Translation on {eng,fra,spa,swh,rus}-X directions. Last column is the average spBLEU Speech Translation scores for decoding in the 200 languages supported by SONAR text decoder.

	eng	fra	spa	swh	rus
Training hours					
SONAR/LASER ASR	4k	0.8k	0.4k	0.3k	0.2k
Whisper ASR	438k	10k	11k	0.01k	10k
Whisper ST	_	4k	7k	0.3k	8k
BLEU					
SONAR	64.7	54.3	50.0	17.7	29.1
SONAR & fine-tuned dec	69.7	64.1	58.9	25.7	35.0
Whisper v1	80.8	79.8	84.8	26.9	84.3
Whisper v2	81.3	82.0	85.3	36.0	85.3
Bert-score					
SONAR	0.948	0.926	0.923	0.808	0.853
SONAR & fine-tuned dec	0.951	0.939	0.936	0.831	0.870
Whisper v1	0.972	0.965	0.977	0.837	0.975
Whisper v2	0.972	0.969	0.979	0.865	0.978

Table 9: Speech recognition spBLEU scores and Bert-scores on FLEURS test set.

bedding space organization. Therefore, we also report xsim++ scores, augmenting the FLEURS test set with hard negatives generated in (Chen et al., 2023) based on FLORES which composes the source sentences of FLEURS. We notice 41% xsim++ relative reduction when switching from LASER as teacher to SONAR as teacher.

Following (Duquenne et al., 2022b), we decoded the speech sentence embeddings with our SONAR text decoder, performing zero-shot speech-to-text translation. Indeed, the text decoder has never seen speech sentence embeddings during training. Moreover, speech representations were only trained to match their transcription representations but never translations. In Table 7, we report our zero-shot speech-to-text translation results on FLEURS test set for X-eng directions and compare it to the baseline trained on LASER space. We also report the state-of-theart results for speech-to-text translation, trained in a supervised way on significantly more training data. First, we notice big improvements in the BLEU scores compared to the LASER baseline on French, Spanish an Swahili, with an average 5.5 BLEU gain on these languages, while being slightly behind on Russian to English translation (-1.2 BLEU). This last result is surprising, as our SONAR speech encoder have much better xsim++ score on Russian compared to the LASER speech encoder. Second, we notice that for our two high resource languages, namely French and Spanish, our zero-shot speech-to-text results are close to Whisper Large v1 supervised

results, while being trained on much less training data. As for Swahili, our framework significantly outperforms Whisper models. We notice much better results for Russian-to-English for Whisper which was expected given the amount of training data and the supervised setting.

Thanks to the compatibility across modalities and across languages, we decoded English, French, Spanish, Swahili and Russian speech sentence embeddings into the 200 text languages supported by our SONAR decoders. We report the zero-shot speech translation results using the finetuned SONAR decoder in Table 8. We notice that BLEU scores remain high for other languages than English, still in a zero-shot setting, highlighting again the compatibility between representations.

Finally, speech embeddings can be decoded into text in the same language, which can be seen as speech transcription. Since our model can often paraphrase transcriptions, we report in Table 9 BLEU scores as well as bert-scores for this zero-shot transcription task. While being significantly behind on BLEU scores, which is expected as our model often paraphrases transcriptions, we see much less gap with Whisper transcriptions with the bert-score metric (which still advantages real transcriptions compared to paraphrases, but less than BLEU). Training data amount is also significantly different between the two setups, but it's interesting to notice that the gap in terms of bert-score remains reasonable.

6.2 Scaling to 37 languages

We use the same recipe than described above to extend the coverage of the speech encoders to 37 languages. These speech encoders were trained by linguistic language family, e.g. Romance or Indian languages, using speech transcriptions only, from public and licensed sources. Table 10 column "Train" gives statistics on the amount of training data. As in Section 6.1, we evaluate the speech encoders by connecting them to the SONAR text decoder and calculate speech-to-text translation performance, as measured by BLEU. Although our results are fully zero-shot speech translation, we achieve very competitive performance compared to the state-of-the-art model Whisper v2 large (Radford et al., 2022). The average on BLEU scores are slightly better for SONAR compared to Whisper, while being zero-shot speech translation. Our model performs less well on some highresource languages like Mandarin Chinese, German or French, but outperforms Whisper for others like Spanish or Dutch and for several less common languages, like Swahili or Uzbek. Our modular approach seems to achieve particular good results on Indian languages: Bengali, Hindi, Kannada, Telugu, Tamil and Urdu.

7 Discussion

From all the experiments present in Section 5 and Section 6, we can draw a couple of high-level conclusions:

First, we have seen that the auto-encoding task can be greatly solved even with a fixed-size bottleneck between the encoder an the decoder, showing that a fixed-size representation should not be seen as a hard limitation, as a lot of information can be stored in a single vector. Then, similarly to Artetxe and Schwenk (2019), we noticed that a translation objective is well suited to build language-agnostic representations while making sure that the encoder model encodes enough information in the sentence embedding to be efficiently decoded (in another language). Adding an MSE loss in the training, which explicitly encourages to align languages in the sentence embedding space, leads to better language-agnostic representations. Moreover, denoising auto-encoding combined with MSE loss, can bring gains for decoding tasks, but too much of it affects the language-agnostic representations. Finally, teacher-student approach to extend to the speech modality has once again proven to be effec-

ISO	Language	Train	Ours	Whisper
arb	MS Arabic	822	30.9	26.9
ben	Bengali	335	21.3	14.1
cat	Catalan	1738	37.7	36.9
cmn	Mandarin Chinese	9320	18.6	20.8
ces	Czech	181	32.0	30.3
cym	Welsh	99	14.5	13.4
dan	Danish	115	34.9	36.0
deu	German	3329	36.2	38.8
est	Estonian	131	26.1	21.2
fin	Finish	184	24.9	25.2
fra	French	2057	33.7	34.9
hin	Hindi	150	22.6	24.2
ind	Indonesian	269	28.7	31.9
ita	Italian	588	29.3	27.5
jpn	Japanese	17319	20.2	20.8
kan	Kannada	114	21.4	13.1
kor	Korean	316	17.1	24.2
mlt	Maltese	106	24.4	16.2
nld	Dutch	1723	29.3	28.4
pes	Western Persian	386	24.4	20.9
por	Portuguese	269	38.3	41.4
pol	Polish	304	21.1	25.8
ron	Romanian	135	34.7	34.1
rus	Russian	259	28.4	31.1
slk	Slovak	102	32.3	29.3
spa	Spanish	1511	28.0	27.2
swh	Swahili	361	23.5	7.6
tam	Tamil	245	16.2	10.0
tel	Telugu	84	18.0	14.7
tgl	Tagalog	108	14.6	26.8
tha	Thai	195	16.9	17.8
tur	Turkish	174	22.7	29.9
ukr	Ukrainian	105	30.7	32.5
urd	Urdu	185	19.7	18.1
uzn	Uzbek	115	20.0	6.6
vie	Vietnamese	194	19.1	21.9
Tota	l/avg	43628	25.3	24.5

Table 10: spBLEU evaluation of S2T into English on FLEURS test set. Our models were trained on ASR transcriptions only, compared to the Whisper large v2.

tive and the mutual compatibility between speech and text multilingual embeddings is greatly highlighted by the fact that speech embeddings can be decoded in foreign text in a zero-shot way.

8 Conclusion

To conclude, we introduced a new multilingual and multimodal sentence embedding space called SONAR. We conducted an extensive study on objective functions to build our multilingual teacher sentence embedding space for text, and an extensive evaluation of our SONAR framework for both similarity search and decoding tasks. We extended this new text sentence embedding space to the speech modality to introduce Sentence-level multimOdal and laNguage-Agnostic Representations (SONAR). The SONAR text and speech encoders as well as the text decoders are freely available at https://github.com/facebookresearch/SONAR.

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