

Total NEES (0.0 inside 95.0 confidence interval)

Position NEES (0.2 inside 95.0 confidence interval)

Velocity NEES (0.2 inside 95.0 confidence interval)

Attitude NEES (0.2 inside 95.0 confidence interval)

Accelerometer NEES (0.2 inside 95.0 confidence interval)

Gyro bias NEES (0.2 inside 95.0 confidence interval)

NIS (0.1 inside 95.0 confidence interval)

