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The following line creates an 'anonymous' function that will return the cost (i.e., the model fitting error) given a set of parameters. There are some technical reasons for setting this up in this way. Feel free to peruse the MATLAB help at <a href="https://www.mathworks.com/help/optim/ug/fmincon.html">https://www.mathworks.com/help/optim/ug/fmincon.html</a> and see the section on 'passing extra arguments' Basically, 'sirafun' is being set as the function siroutput (which you will be designing) but with t and coviddata specified.

```
sirafun= @(x)siroutput(x,t,coviddata);
```

## set up rate and initial condition constraints

Set A and b to impose a parameter inequality constraint of the form A\*x < b Note that this is imposed element-wise If you don't want such a constraint, keep these matrices empty.

```
A = [0 1 0 0 0 0 0;

0 0 1 0 0 0 0;

1 0 0 0 0 0 0;

0 0 0 0 0 1 0;

0 0 0 0 0 0 1;

0 0 0 1 0 0 0];

b = [.16, 0.92, 0.7, 0.85, 0.15, 1];
```

## set up some fixed constraints

Set Af and bf to impose a parameter constraint of the form  $Af^*x = bf$  Hint: For example, the sum of the initial conditions should be constrained If you don't want such a constraint, keep these matrices empty.

```
Af = [0 \ 0 \ 0 \ 1 \ 1 \ 1];

bf = [1];
```

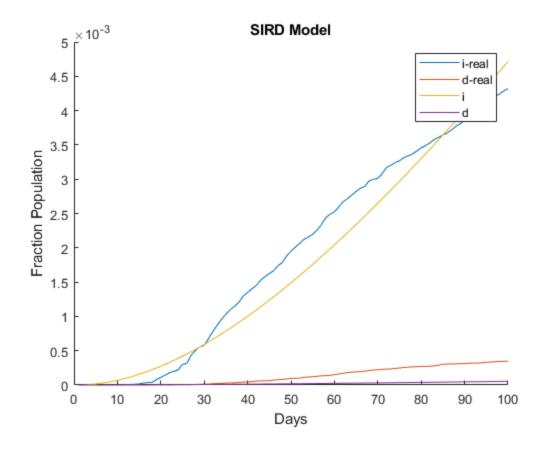
## set up upper and lower bound constraints

Set upper and lower bounds on the parameters lb < x < ub here, the inequality is imposed element-wise If you don't want such a constraint, keep these matrices empty.

```
ub = [1 \ 1]
              1
                  1
                     .7 .7 .3]';
lb = [.015 \ 0.01 \ .3 \ .1 \ .01 \ .01 \ .01]';
% Specify some initial parameters for the optimizer to start from
x0 = [.2 \ 0 \ 0 \ 1 \ 0 \ 0];
x = fmincon(sirafun, x0, A, b, Af, bf, lb, ub)
Y_fit = siroutput_full(x,t);
% Make some plots that illustrate your findings.
cumlsum = cumsum(Y_fit);
figure();
cumlsumFinal = cumlsum(: , [3,4]).*7; % extracting and scaling model
 data.
hold on;
plot(coviddata./2805473); % make numbers fractional & plot
plot(1:t, cumlsumFinal./2805473); % make numbers fractional & plot
%Plot labling:
legend("i-real", "d-real", "i", "d");
xlabel("Days");
ylabel("Fraction Population");
title("SIRD Model");
hold off;
Local minimum found that satisfies the constraints.
Optimization completed because the objective function is non-
decreasing in
feasible directions, to within the value of the optimality tolerance,
and constraints are satisfied to within the value of the constraint
 tolerance.
x =
    0.0150
              0.0100
                         0.9200
                                   0.2800
                                              0.7000
                                                        0.0100
                                                                   0.0100
sys sir base =
  A =
```

```
x1
            x2
                    x3
                           x4
x1 0.985
             0
                     0
                            0
x2
    0.015 0.975
                     0
                            0
          0.92
x3
      0
                     1
                            0
x4
        0
            0.01
                     0
                            1
B =
    u1
     0
x1
x2
     0
x3
     0
x4
     0
C =
    x1 x2 x3 x4
     1
         0
            0
                0
у1
y2
     0
         1
            0
                0
     0
        0
           1 0
у3
     0
         0
           0 1
y4
D =
    и1
у1
     0
     0
у2
у3
     0
y4
     0
```

Sample time: 1 seconds
Discrete-time state-space model.



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