

Multi-core RISC SoC Design & Implementation

Demonstration Viva

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201280376
ELEC5881M - Main Project

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Quick Links

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- GitHub repository: <https://github.com/bendl/vmicro16>
- Full Report: https://github.com/bendl/vmicro16/blob/master/docs/reports/build/ELEC5881M_Ben_Lancaster_201280376_Final.pdf
- This presentation: https://github.com/bendl/vmicro16/blob/master/docs/reports/build/ELEC5881M_Ben_Lancaster_201280376_viva.pdf
- About me: <https://bendl.me/>

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Why a project on CPUs?

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- **CPUs will be used for the rest of humanity**
1000s of years
- **Understand design constraints and considerations**
Be a better engineer
- **Prepare myself for future employment/work**

Why Multi-core?

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- **Rate of single-core speed improvements slowing**
Pipelining, register renaming, branch predictions, OoOE, clock speeds
- **Future of computing = parallel**
 - Identifying parallel opportunities
 - Massively parallel (NoC's)
 - Higher throughput

Why RISC?

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- Easier design & impl
- Smaller = fit more cores on a chip
- FPGA size limitations
- Previous experience + future work
- I'm a RISC purist

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What this project produces:

- **System-on-Chip with multi-processor functionality**
Tested on FPGA hardware with 1-96 CPU cores.

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What this project produces:

- **System-on-Chip with multi-processor functionality**
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- **Custom 16-bit RISC CPU**
With interrupts and its own Instruction Set Architecture (ISA).

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With interrupts and its own Instruction Set Architecture (ISA).
- **Software/Assembly compiler**
PRCO304 programming language/Intel assembly syntax.

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- **Custom 16-bit RISC CPU**
With interrupts and its own Instruction Set Architecture (ISA).
- **Software/Assembly compiler**
PRCO304 programming language/Intel assembly syntax.
- **Aimed at Design Engineers, not end users**
Project is provided as source code/design files for Design Engineers to customise and implement in hardware themselves.

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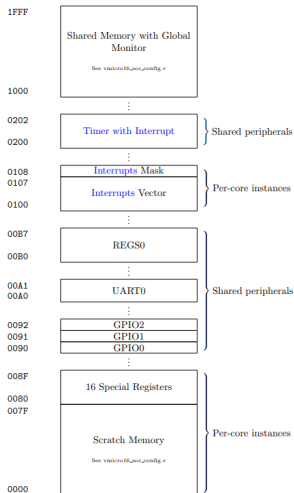
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- **Shared Memory with Global Monitor**
- Timer with Interrupt
- Per-core Interrupt Vector and Mask
- Shared Register Set
- UART Transceiver
- Multiple GPIO ports
- Per-core scratch memory
- **Per-core Special Registers**
- Customisable by designers

Interconnect

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- AMBA APB Bus
- Tristate & Non-tristate (mux) impl
- Originally Wishbone, now APB
- AHB too complex (limited time)
- Various schedulers

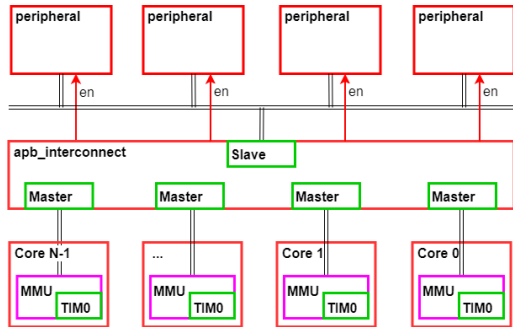


Figure: Vmicro16 interconnect

Interconnect Schematic

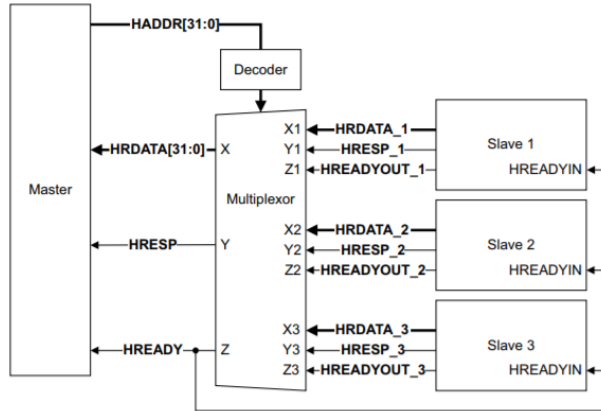


Figure: Source: ARM AHB-Lite Protocol Specification Figure 4-2.

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Instruction Set Architecture

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- + 16-bits, 38 instructions
- + Simple load/store arch
- + (Un)signed instructions
- + Compact
- + Optional hardware multiply instruction
- Only 8 registers
- No good compiler support

| | | | | | |
|-------------|-------|---------|------|-----------|--|
| | 15-11 | 10-8 | 7-5 | 4-0 | rd ra simm5 |
| | 15-11 | 10-8 | 7-0 | | rd imm8 |
| | 15-11 | 10-0 | | | nop |
| | 15 | 14:12 | 11:0 | | extended immediate |
| SPCL | 00000 | 11 bits | | | NOP |
| SPCL | 00000 | 11h'000 | | | NOP |
| SPCL | 00000 | 11h'001 | | | HALT |
| SPCL | 00000 | 11h'002 | | | Return from interrupt |
| LW | 00001 | Rd | Ra | s5 | Rd <= RAM[Ra+s5] |
| SW | 00010 | Rd | Ra | s5 | RAM[Ra+s5] <= Rd |
| BIT | 00011 | Rd | Ra | s5 | bitwise operations |
| BIT_OR | 00011 | Rd | Ra | 00000 | Rd <= Rd Ra |
| BIT_XOR | 00011 | Rd | Ra | 00001 | Rd <= Rd ^ Ra |
| BIT_AND | 00011 | Rd | Ra | 00010 | Rd <= Rd & Ra |
| BIT_NOT | 00011 | Rd | Ra | 00011 | Rd <= ~Ra |
| BIT_LSHFT | 00011 | Rd | Ra | 00100 | Rd <= Rd << Ra |
| BIT_RSHFT | 00011 | Rd | Ra | 00101 | Rd <= Rd >> Ra |
| MOV | 00100 | Rd | Ra | X | Rd <= Ra |
| MOVI | 00101 | Rd | | i8 | Rd <= i8 |
| ARITH_U | 00110 | Rd | Ra | s5 | unsigned arithmetic |
| ARITH_UADD | 00110 | Rd | Ra | 11111 | Rd <= uRd + uRa |
| ARITH_USUB | 00110 | Rd | Ra | 10000 | Rd <= uRd - uRa |
| ARITH_UADDI | 00110 | Rd | Ra | 0AAAA | Rd <= uRd + Ra + AAAA |
| ARITH_S | 00111 | Rd | Ra | s5 | signed arithmetic |
| ARITH_SADD | 00111 | Rd | Ra | 11111 | Rd <= sRd + sRa |
| ARITH_SSUB | 00111 | Rd | Ra | 10000 | Rd <= sRd - sRa |
| ARITH_SSUBI | 00111 | Rd | Ra | 0AAAA | Rd <= sRd - sRa + AAAA |
| BR | 01000 | Rd | | i8 | conditional branch |
| BR_U | 01000 | Rd | | 0000 0000 | Any |
| BR_E | 01000 | Rd | | 0000 0001 | Z=1 |
| BR_NE | 01000 | Rd | | 0000 0010 | Z=0 |
| BR_G | 01000 | Rd | | 0000 0011 | Z=0 and S=0 |
| BR_GE | 01000 | Rd | | 0000 0100 | S=0 |
| BR_L | 01000 | Rd | | 0000 0101 | S != 0 |
| BR_LE | 01000 | Rd | | 0000 0110 | Z=1 or (S != 0) |
| BR_S | 01000 | Rd | | 0000 0111 | S=1 |
| BR_NS | 01000 | Rd | | 0000 1000 | S=0 |
| CMP | 01001 | Rd | Ra | X | SZO <= CMP(Rd, Ra) |
| SETC | 01010 | Rd | | Imm8 | Rd <= (Imm8_f_ SZO) ? 1 : 0 |
| MULT | 01011 | Rd | Ra | X | Rd <= uRd * uRa |
| HALT | 01100 | | | X | |
| LWEX | 01101 | Rd | Ra | s5 | Rd <= RAM[Ra+s5] |
| SWEX | 01110 | Rd | Ra | s5 | RAM[Ra+s5] <= Rd Rd <= 0 1 if success |

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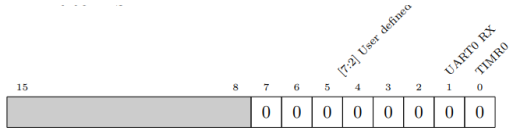
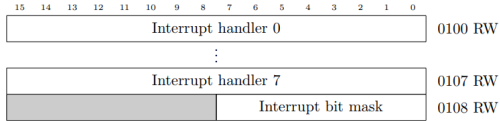
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```
1 entry:
2     // Set interrupt vector at 0x100
3     // Move address of isr0 function to vector[0]
4     movi    r0, isr0
5     // create 0x100 value by left shifting 1 8 bits
6     movi    r1, #0x1
7     movi    r2, #0x8
8     lshft   r1, r2
9     // write isr0 address to vector[0]
10    sw      r0, r1
11
12    // enable all interrupts by writing 0x0f to 0x108
13    movi    r0, #0x0f
14    sw      r0, r1 + #0x8
15    halt    // enter low power idle state
16
17 isr0:
18     movi    r0, #0xff // arbitrary name
19     intr    // do something
20     intr    // return from interrupt
```

Demo: 2 Core LED toggle (GPIO0) with TIMR0 1s interrupt (interrupts_2.s)

Timer Interrupt Example

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Figure: TIMR0 1us interrupt with context switching

Timer Peripheral Registers

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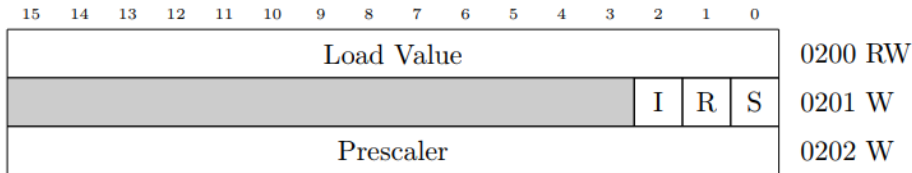


Figure: $t = 20ns * load * prescaler$

Resolution (32-bit timer): 20ns to 85s.

Examples:

- For 1us: Load = 0x32, Prescaler = 0 ($20ns * 0x32 = 1000ns$)
- For 1s: Load = 0x1000, Prescaler = 0x3000 (demo)
($20ns * 0x1000 * 0x3000 = \text{approx. } 1s$)

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Hardware:

Software:

- **Bus Arbitration**
(scheduling: priority, rotating, etc.)

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(atomic versions of load/store to prevent race conditions)

Software:

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Software:

- **Semaphores/Mutexes**
(exclusive memory access)

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Software:

- **Semaphores/Mutexes**
(exclusive memory access)
- **Thread synchronisation**
(memory barriers)

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Hardware:

- **Bus Arbitration**
(scheduling: priority, rotating, etc.)
- **Atomic functions**
(atomic versions of load/store to prevent race conditions)
- Per-core instruction memory
- Per-core context-switching for interrupt handling

Software:

- **Semaphores/Mutexes**
(exclusive memory access)
- **Thread synchronisation**
(memory barriers)
- **Context identification**
What core am I?
How many cores?
How much memory?

Context Identification

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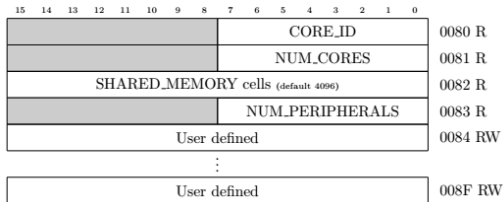


Figure: Special Registers 0x0080 to 0x008F

```
entry:
    // get core idx 0x80 in r7
    movi    r7, #0x80
    lw      r7, r7

    // Branch away if not core 0
    cmp     r7, r0
    movi    r0, exit
    br      r0, BR_NE

    // Core 0 only instructions
    nop
    nop
    nop

exit:
    halt
```

Atomic Instructions

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- Enables semaphores, mutexes, memory barriers
- Prevent race conditions between threads/cores
- LW[EX] and SW[EX]
- Implementation in next slide

```
try_inc:
    // load and lock
    // (if not already locked)
    lwex    r0, r1
    // do something
    // (i.e. add 1 (semaphore))
    addi    r0, #0x01
    // attempt store
    swex    r0, r1

    // check success (== 0)
    cmp     r0, r3

    // if not equal (NE), retry
    movi    r4, try_inc
    br      r4, BR_NE

critical:
    // r0 is latest value
```

Exclusive Access Flow Chart

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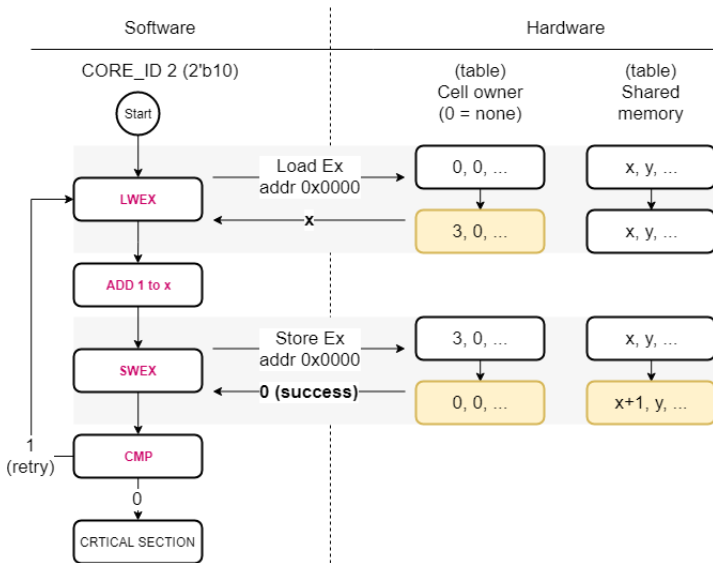
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HW - How do I know which core this lwex/swex is from?

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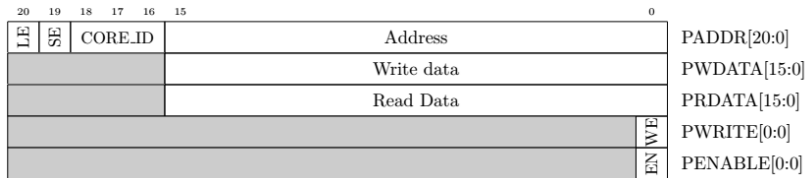
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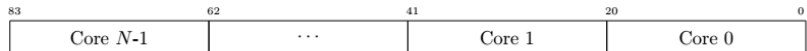
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The Core Idx is sent with each MMU request to the shared bus.



PADDR*NUMCORES-1:0 interconnect input.

Exclusive Access

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```
mutex_claim:
    // load and lock
    // (if not already locked)
    lwex    r0, r1
    // do something
    // (i.e. add 1 (semaphore))
    addi    r0, #0x01
    // attempt store
    swex    r0, r1

    // check success (== 0)
    cmp     r0, r3

    // if not equal (NE), retry
    movi    r4, mutex_claim
    br      r4, BR_NE

critical:
    nop
```

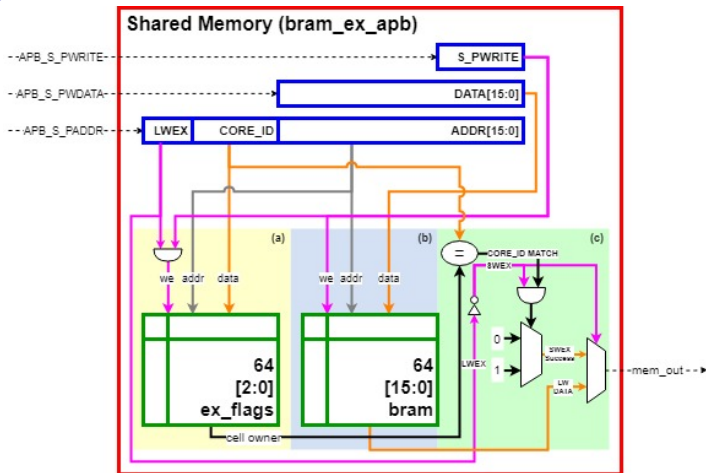


Figure: HW impl

Demo: 8 core number summation (sum.s)

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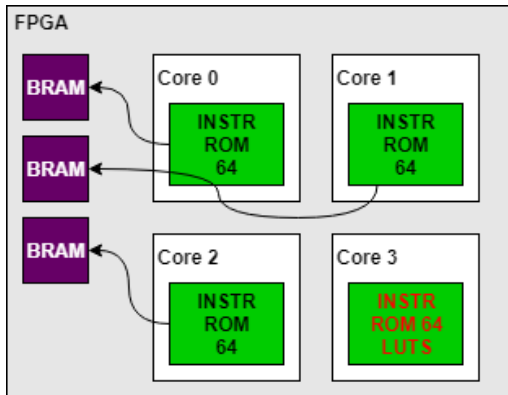
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Memory Limitations

Each core has it's own instruction memory

- + Fast fetching and branching
- Requires a dedicated BRAM (FPGA) per core
- Limited BRAM blocks available
 - Low consumption (DEF_MEM_INSTR_DEPTH)
 - More cores = some implemented in LUT/regs (distributed)
- **Reduces maximum core count**

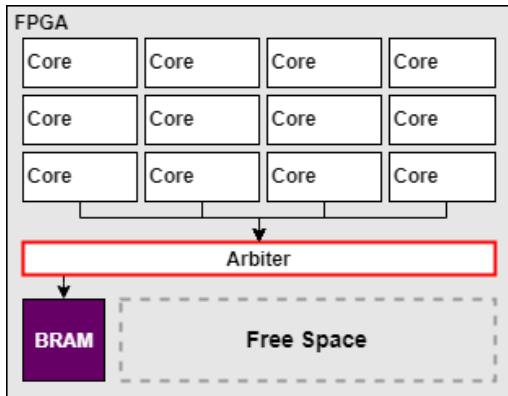


Design Challenges

Memory Limitations - Solution

Global instruction ROM

- + Reduce duplicate ROMs
- + Single BRAM requirement (expandable)
- + Smaller core size
- **Slow access times** (exponential)
 - Requires another interconnect/arbiter/scheduler = logic
- + **Increases maximum core count**



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Summation - Multi-core vs Single-Core

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- Each core has low work load
 - Sum subset of numbers in for loop
- Ideal scenario for parallelism
 - Highly parallelisable
 - Few inter-thread dependencies

Summation - Multi-core vs Single-Core

240 samples (@30 cores = 8 samples per core)

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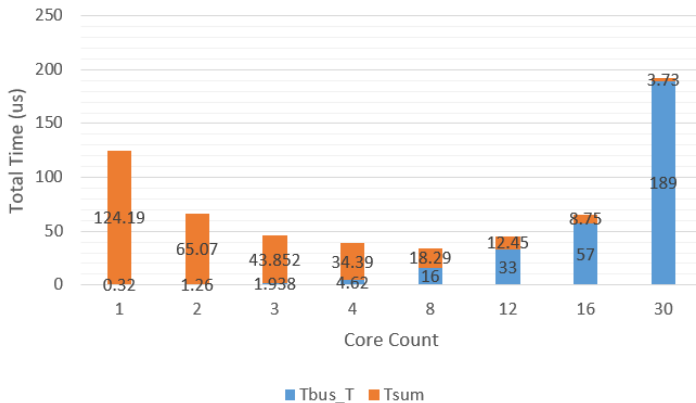
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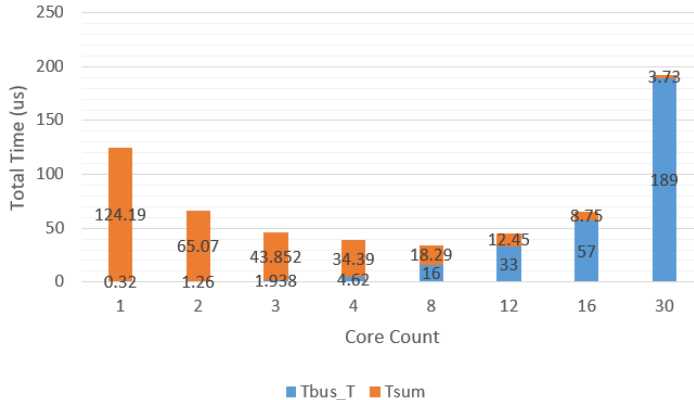
Algorithm Time vs Core Count (N = 240)



Multi-core vs Single-Core for Summation

240 samples (@30 cores = 8 samples per core)

Algorithm Time vs Core Count (N = 240)



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Accomplishments

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- **Near complete System-on-Chip design with various peripherals**
Timers, GPIO, UART, Registers, Memory
- **Common multi-thread/core synchronisation primitives**
Semaphores, Mutexes, Memory Barriers, Atomic Instructions
- **AMBA APB bus interface with Global Monitor**
Timers, GPIO, UART, Registers, Memory
- **Working shared bus arbitration**
Schedules access to shared resources
- **Working FPGA implementation for a 96 core design**
Nearly fills Cyclone V FPGA on the DE1-SoC
- **Interrupts with hardware context-switching**
Low latency to react to interrupt
- **Acknowledges design limitations and attempts to overcome**
LUT resources, block memories, power and temperature requirements

Future Improvements

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- **Working Global Reset**

Global resets are expensive (LUT resources)

Resetting block memories is not trivial

- **On-chip Programming**

Use the UART0 receiver to program each cores flash memory

- **Per-core gating/enabling**

Improve power efficiency for ASIC implementation by disabling cores at run-time via software.

- **Improve memory bottleneck**

Each core requires it's own memory - reduce by multiplexing access to a single large memory.

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- Full Report: https://github.com/bendl/vmicro16/blob/master/docs/reports/build/ELEC5881M_Ben_Lancaster_201280376_Final.pdf
- Presentation tools:
 - Latex Beamer
 - `\usecolortheme{orchid}`
 - `\useoutertheme[hideothersubsections]{sidebar}`