

Experimental Validation of Controllers For Human-Robot Cooperative Swinging of Complex Pendulum-Like Objects

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Forschungspraxis

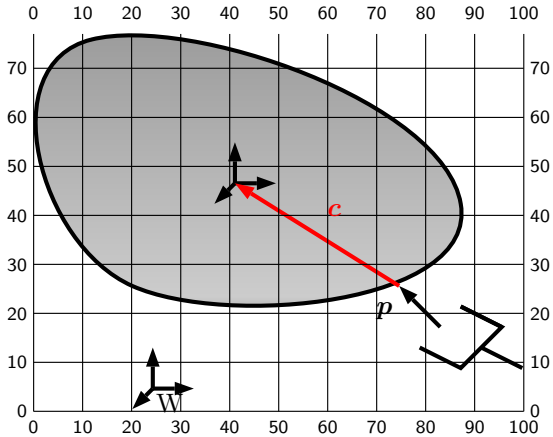
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Content

Task



Load Identification - State of the Art

Load Identification with Human

Persistent Excitation

Cooperative Excitation

Time Schedule I

Time Schedule II

References