

CENG 384 - Signals and Systems for Computer Engineers

Spring 2023

Homework 1

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1. (a) $2z + \bar{z} = -5 + j$
 $2(x + jy) + (x - jy) = -5 + j$
 $3x + jy = -5 + j$
 $x = \frac{-5}{3}, y = 1$ so, $z = \frac{-5}{3} + j$
 $|z|^2 = z\bar{z}$
 $|z|^2 = (\frac{-5}{3} + j)(\frac{-5}{3} - j) = \frac{34}{9}$

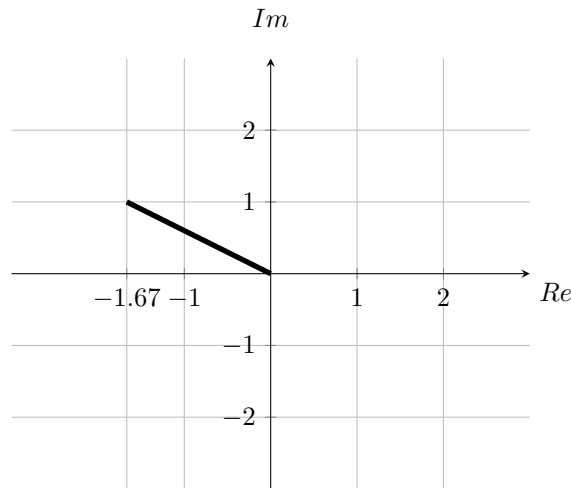


Figure 1: z

- (b) $r^5 e^{5j\theta} = 32j$
 $r^5 e^{5j\theta} = 2^5 e^{j\frac{\pi}{2}}$ $r = 2, 5\theta = \frac{\pi}{2} + 2\pi k$
 $k = -2 \hookrightarrow \theta = \frac{-7\pi}{10}$ $z_1 = 2e^{-j\frac{7\pi}{10}}$
 $k = -1 \hookrightarrow \theta = \frac{-3\pi}{10}$ $z_2 = 2e^{-j\frac{3\pi}{10}}$
 $k = 0 \hookrightarrow \theta = \frac{\pi}{10}$ $z_3 = 2e^{j\frac{\pi}{10}}$
 $k = 1 \hookrightarrow \theta = \frac{\pi}{2}$ $z_4 = 2e^{j\frac{\pi}{2}}$
 $k = 2 \hookrightarrow \theta = \frac{9\pi}{10}$ $z_5 = 2e^{j\frac{9\pi}{10}}$
- (c) $z_1 = (1 + j) = \sqrt{2}e^{j\frac{\pi}{4}}, z_2 = (\frac{1}{2} + \frac{\sqrt{3}}{2}j) = e^{j\frac{\pi}{3}}, z_3 = (j - 1) = \sqrt{2}e^{-j\frac{\pi}{4}}$
 $z = \frac{z_1 z_2}{z_3} = e^{j\frac{5\pi}{6}} \longrightarrow |z| = 1, \theta = \frac{5\pi}{6} \text{ or } -\frac{\pi}{6}$
- (d) $e^{-j\frac{\pi}{2}} = -j$
 $z = j(-j) = 1 = e^{j2\pi}$

2.

3. (a)

(b) $3\delta[n + 7] - 4\delta[n + 4] + 2\delta[n + 2] - \delta[n + 1] - \delta[n - 1] + 4\delta[n - 4]$

4. (a) $x(t + T) = 5\sin(3t - (\frac{\pi}{4} + 3T)) = 2\pi m$

$T = \frac{\frac{\pi}{4} - 2\pi m}{3}$ for $m=0$, $T = \frac{\pi}{12}$

The signal is periodic with the fundamental period $T_0 = \frac{\pi}{12}$

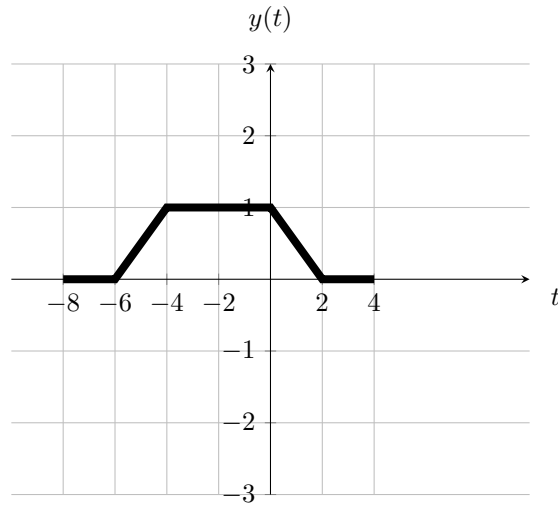


Figure 2: t vs. $y(t)$

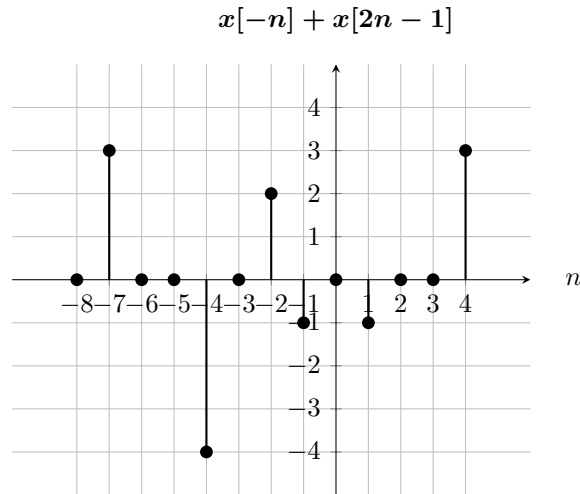


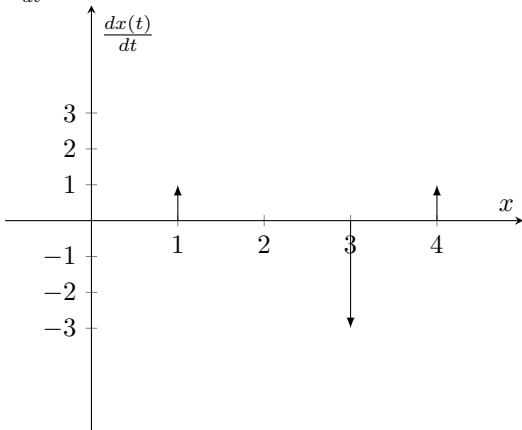
Figure 3: n vs. $x[-2n] + x[n-2]$

- (b) for x_1 $w_0 = \frac{13\pi}{10}$, $N_0 = \frac{2\pi}{w_0}m = \frac{20m}{13}$, $m = 13 \rightarrow N_0 = 20$
for x_2 $w_0 = \frac{7\pi}{10}$, $N_0 = \frac{2\pi}{w_0}m = \frac{20m}{7}$, $m = 7 \rightarrow N_0 = 20$
LCM is 20, so the signal is periodic with the fundamental period $N_0 = 20$

- (c) $7N_0 = 2\pi m$, the smallest integer number m satisfy this equation is $m=1$.
for $m=1 \rightarrow N_0 = \frac{2\pi}{7}$ Since N_0 is not an integer number, this signal is not periodic.

5. (a) $x(t) = u(t-1) - 3u(t-3) + u(t-4)$

(b) $\frac{dx(t)}{dt} = \delta(t-1) - 3\delta(t-3) + \delta(t-4)$



6. (a) $y(t) = tx(2t+3)$

- i. **Memory** Has memory, $y(3) = 3x(9)$
 - ii. **Stability** Not stable, t is unbounded
 - iii. **Causality** Not causal, $y(3) = 3x(9)$ output depends on future input values
 - iv. **Linearity** Superposition property hold, therefore linear
 - v. **Invertibility** Not invertible, because $x(2t-3) = \frac{y(t)}{t}$ is not defined when $t = 0$
 - vi. **Time Invariance** Not time invariant $x_2(2t+3) = x_1(t-\tau)$, $y_2(t) = tx_2(2t+3) = tx_1(2t-2\tau+3) \neq y_1(t-\tau)$
- (b) $y[n] = \sum_{k=1}^{inf} x[n-k]$
- i. **Memory** Has memory, accumulates past values of input to generate output
 - ii. **Stability** Not stable, take $x[n] = a^n$, then $y[n] = \sum_{k=1}^{\infty} a^{n-k} = a^n \sum_{k=1}^{\infty} a^{-k}$, a^n is unbounded
 - iii. **Causality** Causal, $y[n] = x[n-1] + x[n-2] + x[n-3] + \dots$, output depends on past input values
 - iv. **Linearity** Linear, Superposition property holds
 $y[n] = \sum_{k=1}^{\infty} (a_1 x_1[n-k] + a_2 x_2[n-k]) = a_1 \sum_{k=1}^{\infty} x_1[n-k] + a_2 \sum_{k=1}^{\infty} x_2[n-k] = a_1 y_1[n] + a_2 y_2[n]$
 - v. **Invertibility** Invertible, consider 2 different inputs generate same output.
Then we have $y[n] = \sum_{k=1}^{\infty} x[n-k] = \sum_{k=1}^{\infty} x'[n-k]$ and $x[n-k] \neq x'[n-k]$.
 $\sum_{k=1}^{\infty} x[n-k] - x'[n-k] = 0$
Then, $x[n-k] - x'[n-k] = 0$ must hold, but we assumed $x[n-k] \neq x'[n-k]$.
 - vi. **Time Invariance** Time invariant
 $x[n-m] = x[(n-m)-1] + x[(n-m)-2] + x[(n-m)-3] + \dots$
 $y[n-m] = \sum_{k=1}^{\infty} x[(n-1)-k-m] = y[n-1-m]$

7. (a)

```
import matplotlib.pyplot as plt

def even_odd(x, s_i):
    x_odd = [0]*len(x)
    x_even = [0]*len(x)

    for n in range(s_i, len(x)+s_i):
        x_odd[n-s_i] = 0.5*(x[n-s_i] - x[-n+s_i-1])
        x_even[n-s_i] = 0.5*(x[n-s_i] + x[-n+s_i-1])

    plt.subplot(3,1,1)
    plt.stem(range(s_i, len(x)+s_i), x, use_line_collection=1)
    plt.title('Signal')

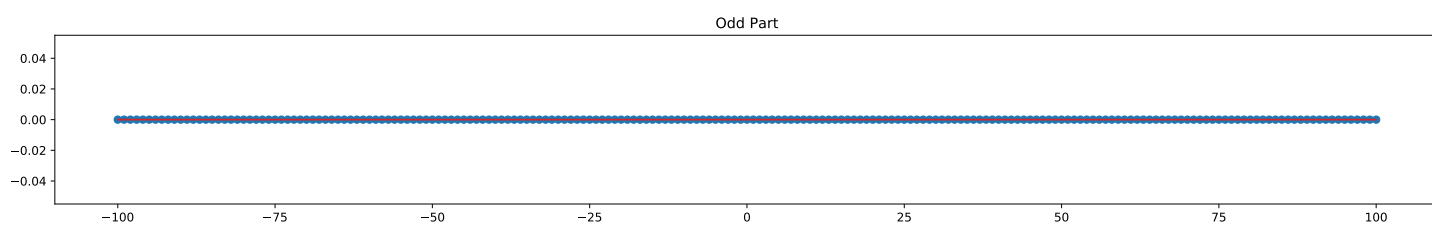
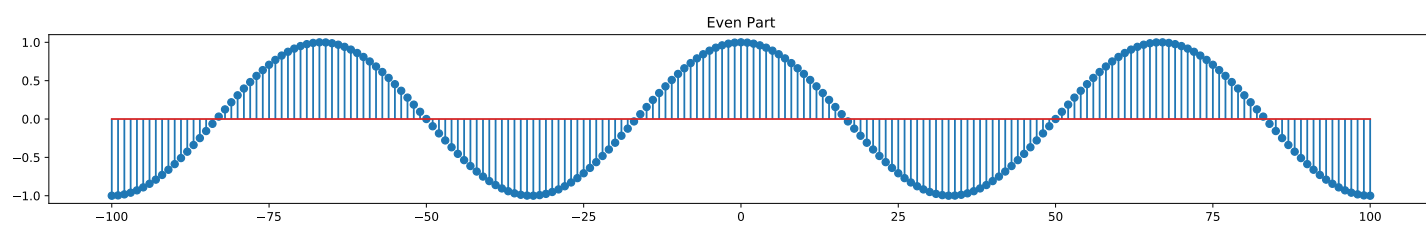
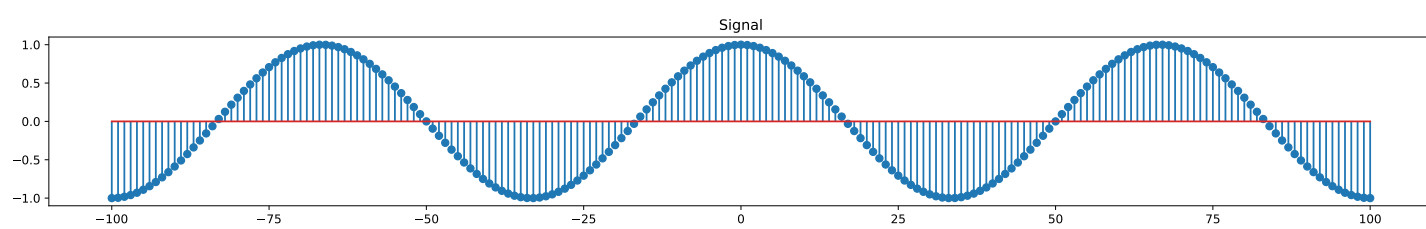
    plt.subplot(3,1,2)
    plt.stem(range(s_i, len(x)+s_i), x_even, use_line_collection=1)
    plt.title('Even Part')

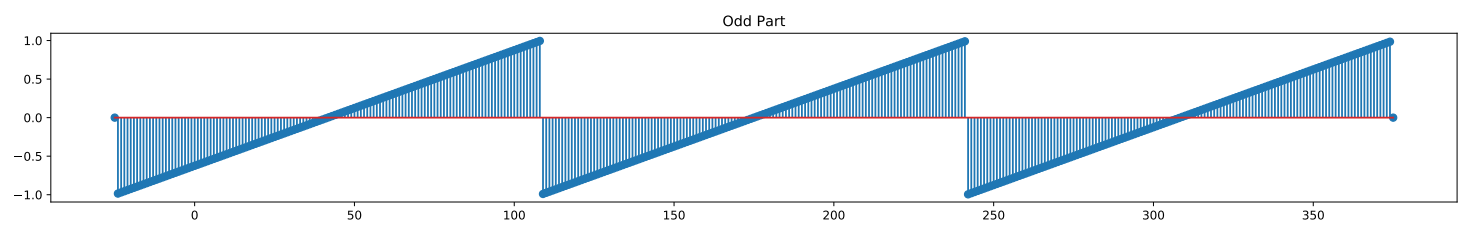
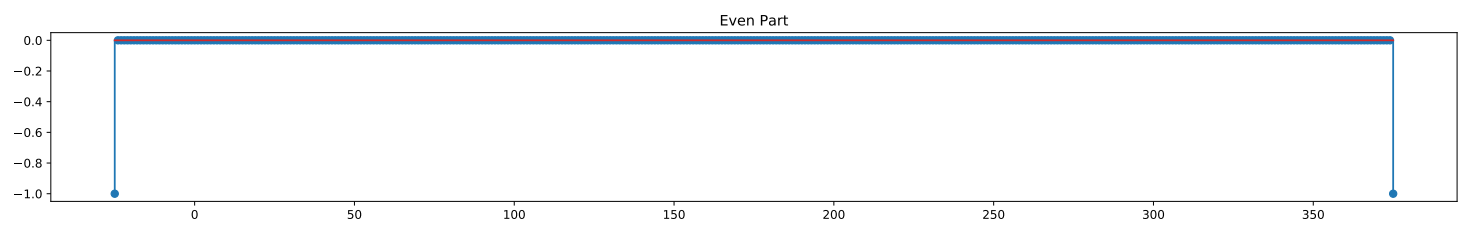
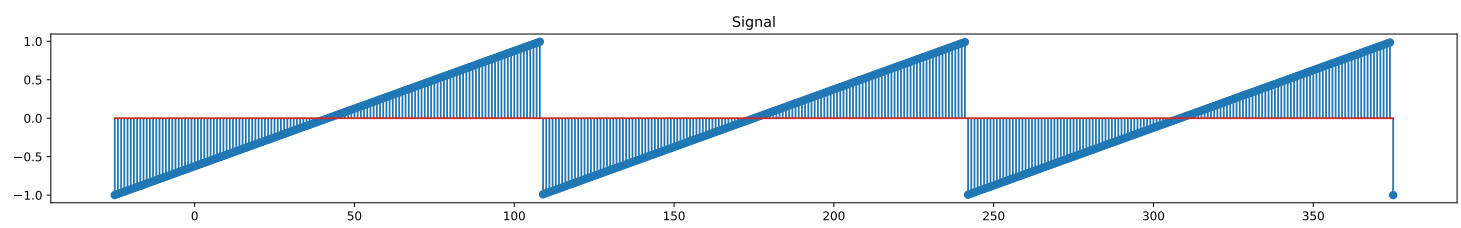
    plt.subplot(3,1,3)
    plt.stem(range(s_i, len(x)+s_i), x_odd, use_line_collection=1)
    plt.title('Odd Part')

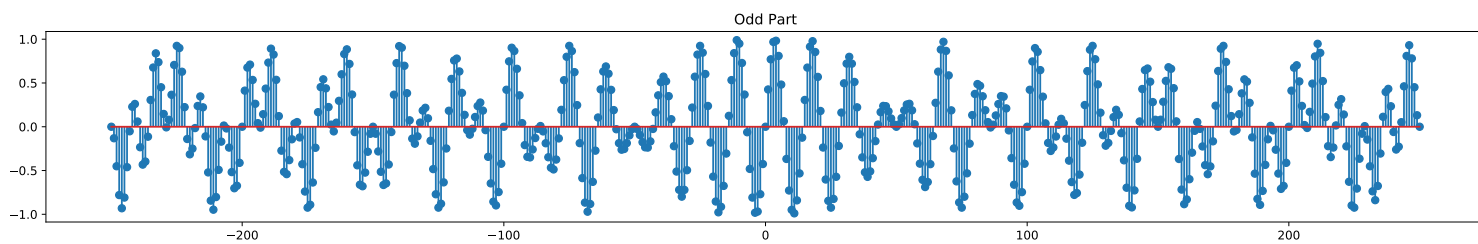
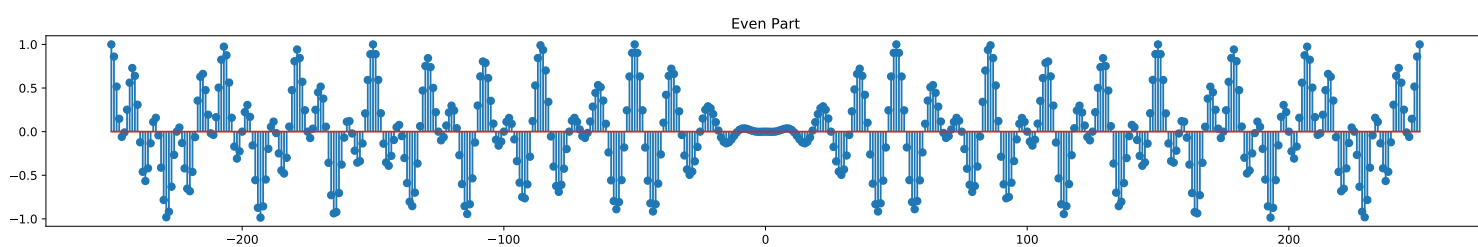
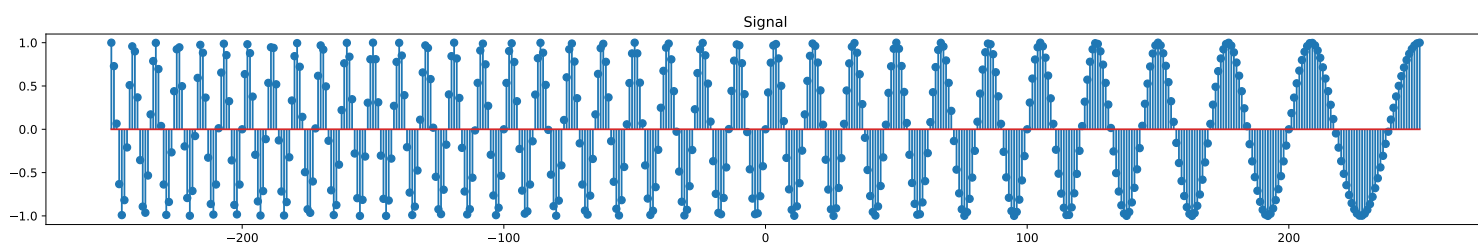
    plt.tight_layout()
    plt.show()

f = 'shifted_sawtooth_part_a.csv'
with open(f, 'r') as file:
    data = file.read().splitlines()
    s_i, x = data[0].split(',') [0], data[0].split(',') [1:]
x = [float(i) for i in x]

even_odd(x, int(s_i))
```







(b)

```
import matplotlib.pyplot as plt

def shifted_scaled_signal(x, s_i, a, b):
    xnew = [0]*len(x)
    for n in range(s_i, len(x)+s_i):
        if (n-a-b) >= s_i and (n-a-b) < s_i+len(x):
            xnew[n-s_i] = x[n-a-b]

    plt.subplot(2,1,1)
    plt.stem(range(s_i, len(x)+s_i), x, use_line_collection=1)
    plt.title('Signal')

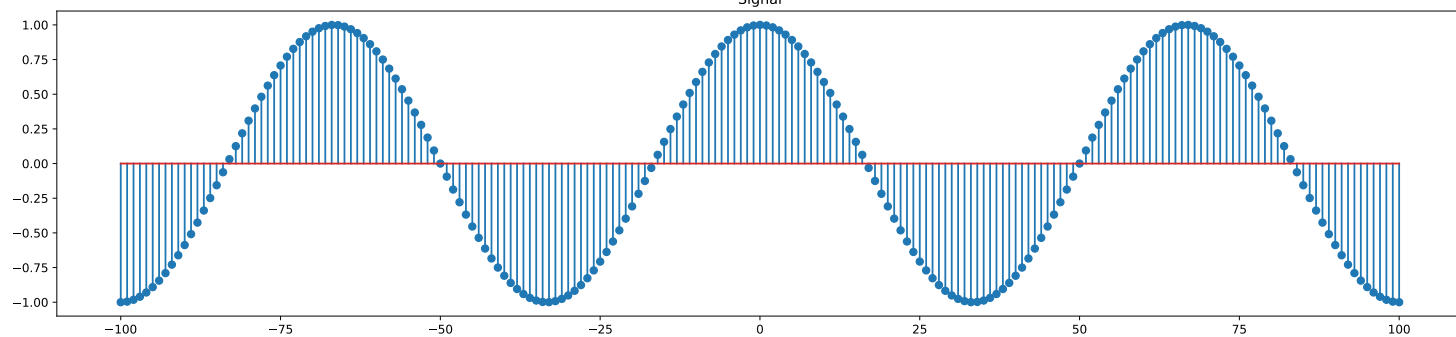
    plt.subplot(2,1,2)
    plt.stem(range(s_i, len(x)+s_i), xnew, use_line_collection=1)
    plt.title('Shifted and Scaled Signal')

    plt.tight_layout()
    plt.show()

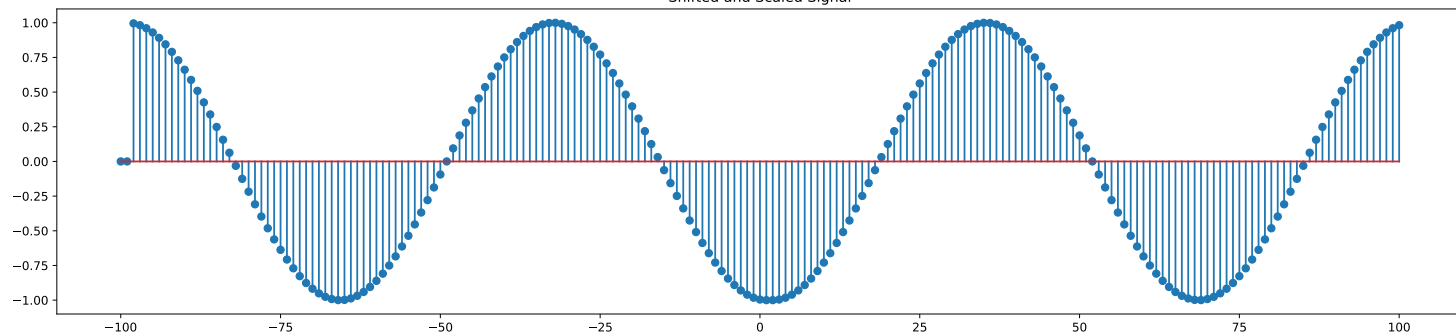
f = 'chirp_part_b.csv'
with open(f, 'r') as file:
    data = file.read().splitlines()
    s_i, a, b, x = data[0].split(',')[0], data[0].split(',')[1], data[0].split(',')[2], data[0].split(',')[3]
x = [float(i) for i in x]

shifted_scaled_signal(x, int(s_i), int(a), int(b))
```

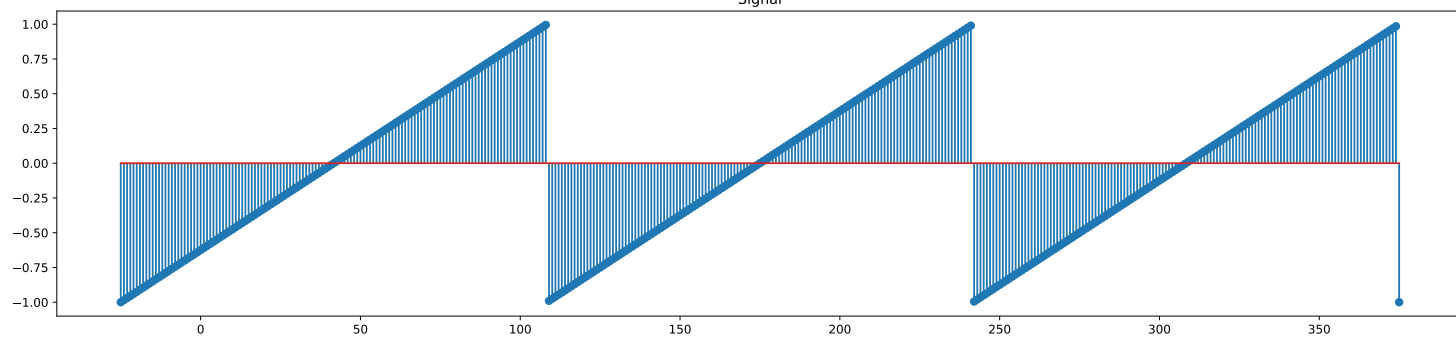
Signal



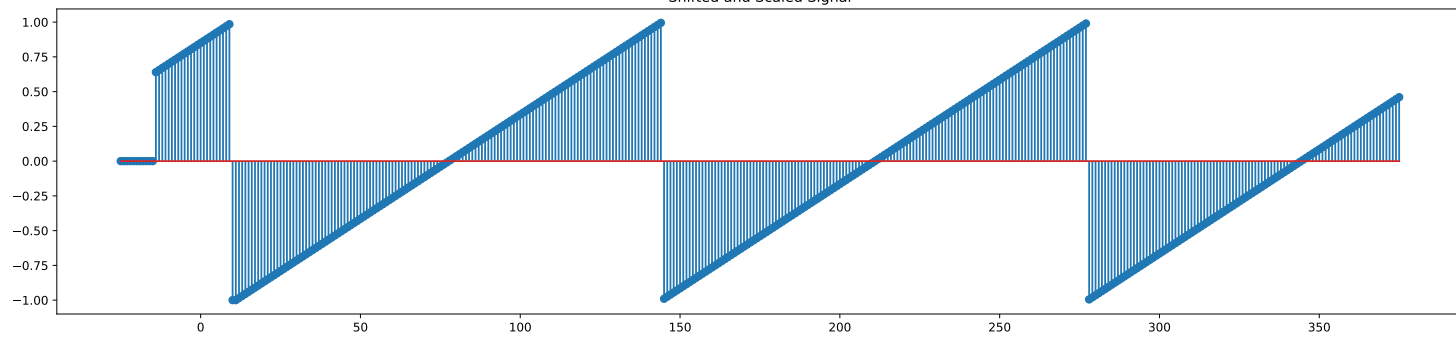
Shifted and Scaled Signal



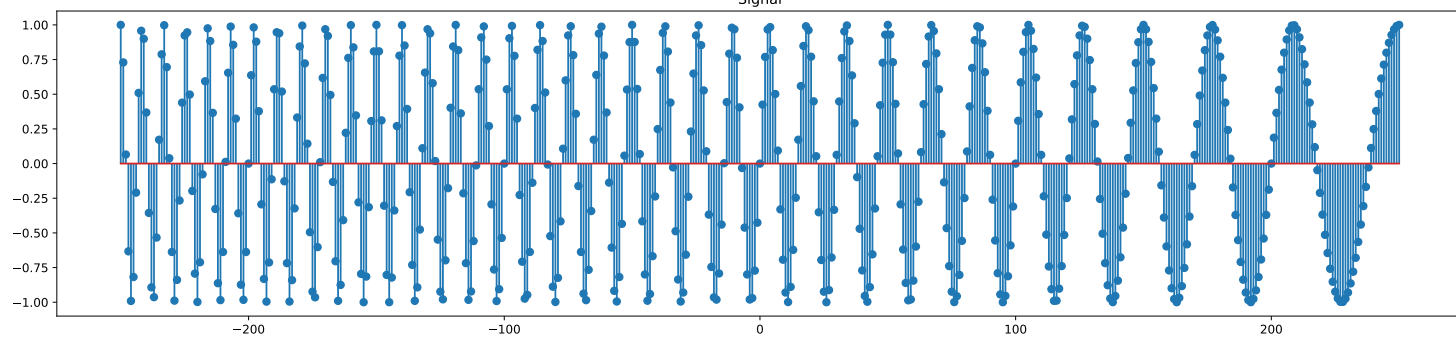
Signal



Shifted and Scaled Signal



Signal



Shifted and Scaled Signal

