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F A U L T # 24
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2813.0450 52 ACTUATORS 1499,1536,1560
2813.0450 52 ACTUATORS 1499,1536,1560
2813.0450 52 COMMANDS 4597,1246,2574
2813.0450 52 RC -14,116,4770,116,7299,7306,0,0,0,0,0,0,0,0,0
2813.0450 52 RC -14,116,4770,116,7299,7306,0,0,0,0,0,0,0,0,0,0
2813.0450 52 DESIRED 0.52 0.09 6.0 -55 132 279 0.9 12.0
2813.0450 52 ATTITUDE 0.534017 -0.392163 0.025543
2813.0450 52 IMU_MAG 0.000000 0.000000 0.000000
2813.0450 52 IMU_GYRO -0.089355 0.260010 0.254639
2813.0450 52 IMU_ACCEL 0.966797 -0.396484 -8.825195
2813.0450 52 SETTINGS 0.000000 1.000000 0.000000 0.000000
2813.0610 52 IMU_MAG 0.000000 0.000000 0.000000
2813.0610 52 IMU_GYRO -0.114258 0.258057 0.254639
2813.0610 52 IMU_ACCEL 1.234375 -0.439453 -9.596680
2813.0780 52 IMU MAG 0.000000 0.000000 0.000000
2813.0780 52 IMU_GYRO -0.125000 0.253662 0.257324
2813.0780 52 IMU_ACCEL 1.457031 -0.489258 -9.568359
2813.0950 52 NAVIGATION 4 0 -36.7 62.0 0.0 68.1 35 0
2813.0950 52 GPS 3 36027419 481365983 3291 271855 1825 46 1956 378498400 31 0
2813.0950 52 ACTUATORS 1499,1540,1416
2813.0950 52 ACTUATORS 1499,1540,1416
2813.0950 52 COMMANDS 4597,1313,2533
2813.0950 52 RC -14,116,4770,116,7299,7306,0,0,0,0,0,0,0,0,0
2813.0950 52 RC -14.116.4770.116.7299.7306.0.0.0.0.0.0.0.0.0
2813.0950 52 DESIRED 0.52 0.09 6.0 -55 132 279 0.9 12.0
2813.0950 52 ATTITUDE 0.529850 -0.381465 0.029789
2813.0950 52 IMU_MAG 0.000000 0.000000 0.000000
2813.0950 52 IMU_GYRO -0.119629 0.240479 0.261230
2813.0950 52 IMU_ACCEL 1.541016 -0.420898 -9.800781
2813.1110 52 IMU_MAG 0.000000 0.000000 0.000000
2813.1110 52 IMU_GYRO -0.114746 0.208496 0.267090
2813.1110 52 IMU_ACCEL 1.696289 0.000000 -11.002930
2813.1280 52 IMU_MAG 0.000000 0.000000 0.000000
2813.1280 52 IMU_GYRO -0.134521 0.132812 0.264893
2813.1280 52 IMU_ACCEL 1.583984 0.058594 -12.596680
2813.1450 52 ACTUATORS 1499,1541,1416
2813.1450 52 ACTUATORS 1499,1541,1416
2815.0990 52 DESIRED 0.52 0.36 0.2 -34 171 279 1.6 12.0
2815.0990 52 ATTITUDE -0.444056 -0.559515 -0.610577
2815.0990 52 IMU_MAG 0.000000 0.000000 0.000000
2815.1000 52 IMU_GYRO -0.610107 -0.126465 -0.329834
2815.1000 52 IMU_ACCEL -0.690430 0.520508 -3.229492
2815.1000 52 SETTINGS 0.000000 1.000000 0.000000 1521.000000
2815.1150 52 IMU_MAG 0.000000 0.000000 0.000000
2815.1150 52 IMU_GYRO -0.604248 -0.142578 -0.311279
2815.1150 52 IMU_ACCEL 0.178711 -0.672852 -5.609375
2815.1320 52 IMU_MAG 0.000000 0.000000 0.000000
2815.1320 52 IMU_GYRO -0.646484 -0.125488 -0.298340
2815.1320 52 IMU_ACCEL -0.178711 -0.291992 -6.009766
2815.1490 52 ACTUATORS 1601,1586,1492
2815.1490 52 ACTUATORS 1601,1586,1492
2815.1490 52 COMMANDS 5612,9600,9600
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2815.1490 52 ACTUATORS 1601,1586,1492
2815.1490 52 COMMANDS 5612,9600,9600
2815.1490 52 RC -14,116,4770,116,7299,7306,0,0,0,0,0,0,0,0,0
2815.1490 52 RC -14,116,4770,116,7299,7306,0,0,0,0,0,0,0,0,0
2815.1490 52 DESIRED 0.52 0.36 0.2 -34 171 279 1.6 12.0
2815.1490 52 ATTITUDE -0.469559 -0.566175 -0.619640
2815.1490 52 IMU\_MAG 0.000000 0.000000 0.000000
2815.1490 52 IMU\_GYRO -0.602295 -0.114746 -0.277100
2815.1490 52 IMU\_ACCEL -1.187500 -0.916992 -1.717773

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