

Setting index	Fault # 23 index	Gyro index	Faulty Gyro index	
0	0	0	0	2813.0450 52 ACTUATORS 1499,1536,1560
0	0	0	0	2813.0450 52 ACTUATORS 1499,1536,1560
0	0	0	0	2813.0450 52 COMMANDS 4597,1246,2574
0	0	0	0	2813.0450 52 RC -14,116,4770,116,7299,7306,0,0,0,0,0,0,0,0,0
0	0	0	0	2813.0450 52 RC -14,116,4770,116,7299,7306,0,0,0,0,0,0,0,0,0
0	0	0	0	2813.0450 52 DESIRED 0.52 0.09 6.0 -55 132 279 0.9 12.0
0	0	0	0	2813.0450 52 ATTITUDE 0.534017 -0.392163 0.025543
0	0	0	0	2813.0450 52 IMU_MAG 0.000000 0.000000 0.000000
0	0	1	0	2813.0450 52 IMU_GYRO -0.089355 0.260010 0.254639
0	0	0	0	2813.0450 52 IMU_ACCEL 0.966797 -0.396484 -8.825195
1	1	0	0	2813.0450 52 SETTINGS 0.000000 1.000000 0.000000 0.000000
0	1	0	0	2813.0610 52 IMU_MAG 0.000000 0.000000 0.000000
0	1	1	1	2813.0610 52 IMU_GYRO -0.114258 0.258057 0.254639
0	1	0	0	2813.0610 52 IMU_ACCEL 1.234375 -0.439453 -9.596680
0	1	0	0	2813.0780 52 IMU_MAG 0.000000 0.000000 0.000000
0	1	1	1	2813.0780 52 IMU_GYRO -0.125000 0.253662 0.257324
0	1	0	0	2813.0780 52 IMU_ACCEL 1.457031 -0.489258 -9.568359
0	1	0	0	2813.0950 52 NAVIGATION 4 0 -36.7 62.0 0.0 68.1 35 0
0	1	0	0	2813.0950 52 GPS 3 36027419 481365983 3291 271855 1825 46 1956 378498400 31 0
0	1	0	0	2813.0950 52 ACTUATORS 1499,1540,1416
0	1	0	0	2813.0950 52 ACTUATORS 1499,1540,1416
0	1	0	0	2813.0950 52 COMMANDS 4597,1313,2533
0	1	0	0	2813.0950 52 RC -14,116,4770,116,7299,7306,0,0,0,0,0,0,0,0,0
0	1	0	0	2813.0950 52 RC -14,116,4770,116,7299,7306,0,0,0,0,0,0,0,0,0
0	1	0	0	2813.0950 52 DESIRED 0.52 0.09 6.0 -55 132 279 0.9 12.0
0	1	0	0	2813.0950 52 ATTITUDE 0.529850 -0.381465 0.029789
0	1	0	0	2813.0950 52 IMU_MAG 0.000000 0.000000 0.000000
0	1	1	1	2813.0950 52 IMU_GYRO -0.119629 0.240479 0.261230
0	1	0	0	2813.0950 52 IMU_ACCEL 1.541016 -0.420898 -9.800781
0	1	0	0	2813.1110 52 IMU_MAG 0.000000 0.000000 0.000000
0	1	1	1	2813.1110 52 IMU_GYRO -0.114746 0.208496 0.267090
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				▪
				▪
1	0	0	0	2815.1000 52 SETTINGS 0.000000 1.000000 0.000000 1521.000000
0	0	0	0	2815.1150 52 IMU_MAG 0.000000 0.000000 0.000000
0	0	1	0	2815.1150 52 IMU_GYRO -0.604248 -0.142578 -0.311279
0	0	0	0	2815.1150 52 IMU_ACCEL 0.178711 -0.672852 -5.609375
0	0	0	0	2815.1320 52 IMU_MAG 0.000000 0.000000 0.000000
0	0	1	0	2815.1320 52 IMU_GYRO -0.646484 -0.125488 -0.298340
0	0	0	0	2815.1320 52 IMU_ACCEL -0.178711 -0.291992 -6.009766