

11 Oct 2021

Why is the greedy algo for trick-or-treating optimal?

• $Y_{\text{Greedy}} = [y_1^G, y_2^G, \dots, y_n^G]$

↗ this is the sol'n from our greedy algorithm

• $Y_{\text{OPT}} = [y_1^O, y_2^O, \dots, y_m^O]$

↗ this is an optimal sol'n.

of all sol'n's,
smallest # of
houses to stop at
 $\Rightarrow m \leq n$

$y_m^O = \text{home}$
no 2 houses are ≥ 30 m
adjacent

We want to show $m = n$. Already know $m \leq n$.

Claim: $\forall i, \quad y_i^G \geq y_i^O$

Proof: Base case $i=1$. By choice of y_1^G , we selected the furthest possible $\Rightarrow y_1^G \geq y_1^O$.
Let $i \geq 1$. Assume $y_i^G \geq y_i^O$ and $i \leq n, i < m$.

Assume, by contradiction that $y_{i+1}^O > y_{i+1}^G$.

Since Y_{OPT} is a sol'n, we know $y_{i+1}^O - y_i^O \leq 30$.

~~Since $y_{i+1}^O > y_{i+1}^G$, we know $y_{i+1}^O - y_i^O \leq 30$.~~

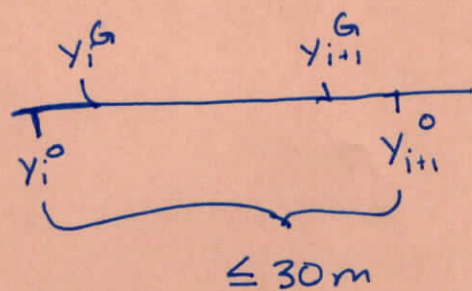
If $y_i^G > y_{i+1}^O$, this is a

contradiction to $y_{i+1}^O > y_{i+1}^G$.

\therefore we know $y_i^O < y_i^G < y_{i+1}^O$

$\Rightarrow y_{i+1}^O - y_i^G \leq 30 \Rightarrow y_{i+1}^O \leq y_{i+1}^G$ so, $y_{i+1}^G \geq y_{i+1}^O$, awhs.

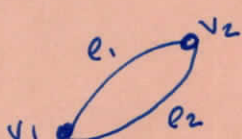
Scratch work

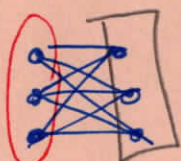


①

Graphs

a graph $G = (V, E)$ is two sets, V is a set of vertices and E is a set of pairs of vertices that we call edges or arcs

 } is a multigraph: allows multiple edges + self-loops.

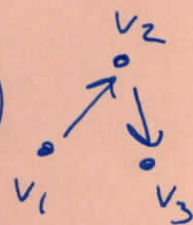


$K_{\boxed{3}\boxed{3}}$: the bipartite graph on sets of size $\boxed{3}$ and $\boxed{3}$

• a graph is directed if we make our edges ordered pairs of vertices instead of just pairs

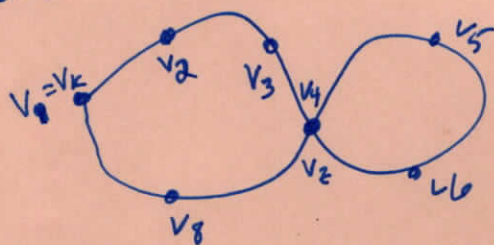
ex:

$$G = (\{v_1, v_2, v_3\}, \{[v_1, v_2], [v_2, v_3]\})$$



• a path is a sequence of vertices $[p_1, p_2, \dots, p_k]$ such that $\{p_i, p_{i+1}\} \in E$ for all $i = 1, \dots, k-1$.

• a cycle is a path that starts & ends at the same vertex (aka a "closed path")



$v_7 = v_4$, so not a cycle according to JE but is a cycle according to BTF

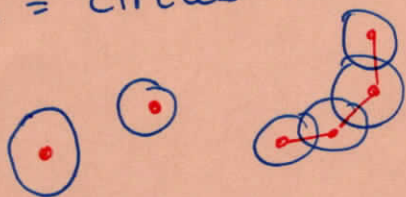
• a graph is acyclic iff it does not contain any simple cycles (those w/out repeated ~~edges~~ vertices) (2)

Examples of where we use

- road networks
- resource delivery logistics (directed, weighted graph)
- databases / ER diagrams
every set of ~~data~~ data is its own node
- circuits
- ecology
- social networks
- flow networks
 - fish in streams
 - network traffic
 - actual traffic
- neural networks
- neighborhood graphs

→ nodes: data + we know the complete weighted graph, where weights = distances btwn data pts.
→ nbhd graph: includes all edges $\leq t$, where t is some threshold

e.g., data = circles in the plane

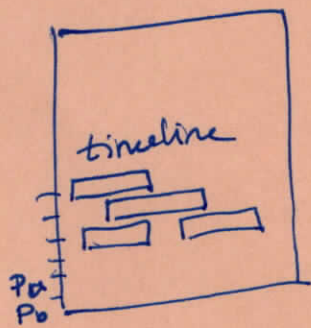


} node for each circle
edge if 2 circles intersect

graphs to solve problems:
problems/algorithms

- Eulerian tour: a path that ~~does not use an~~ uses each edge exactly once
(e.g., bridges of Königsberg)
- Hamiltonian path: a path that uses each vertex exactly once.
- vertex cover
- 4-colorability / k -colorability
- traveling salesman (NPC)
- minimum spanning tree
(= a tree that contains all nodes of the graph)

example at a start-up



Q: how do I best color-code the timeline so adjacent rows are not the same color?

transformed this into a graph coloring problem!

The four color theorem

Given a plane graph, the vertices can be colored by 4 colors where no 2 adjacent vertices are the same color.

More generally

- A graph is k -colorable iff \exists an assignment of vertices to k colors such that no 2 adjacent vertices are the same color.