

Geometry Helps to Compare PDs

(part 2)

11/16/2022



Plan:

- hard ways
- Recall Wasserstein distance
 - Combinatorial Methods to Compute it (auction algos)
 - Geometric Adaptations (k-d trees)
 - Experimental findings

Bottleneck Distance (∞ -Wasserstein)

$$W_\infty(X, Y) = \inf_{\eta: X \rightarrow Y} \sup_{x \in X} \|x - \eta(x)\|_\infty,$$

q -Wasserstein Distance

$$W_q(X, Y) = \left[\inf_{\eta: X \rightarrow Y} \sum_{x \in X} \|x - \eta(x)\|_\infty^q \right]^{1/q}.$$

Fix $q \geq 1$ and compute q -Wasserstein cost

6-partite weighted graph $G = (\underbrace{U \sqcup V}_{\text{}}, E, w: E \rightarrow \mathbb{R}^+)$

(Idea)

Auction Algorithm (Bertsekas, 1974)

$u \in U$ are "Bidders"

$v \in V$ are "Objects"

$w(e)$, $e \in E$, are benefits between Bidders & Objects

price $p_v = 0$ initially

$$\text{value}(u, v) = (w(u, v) - p_v)$$

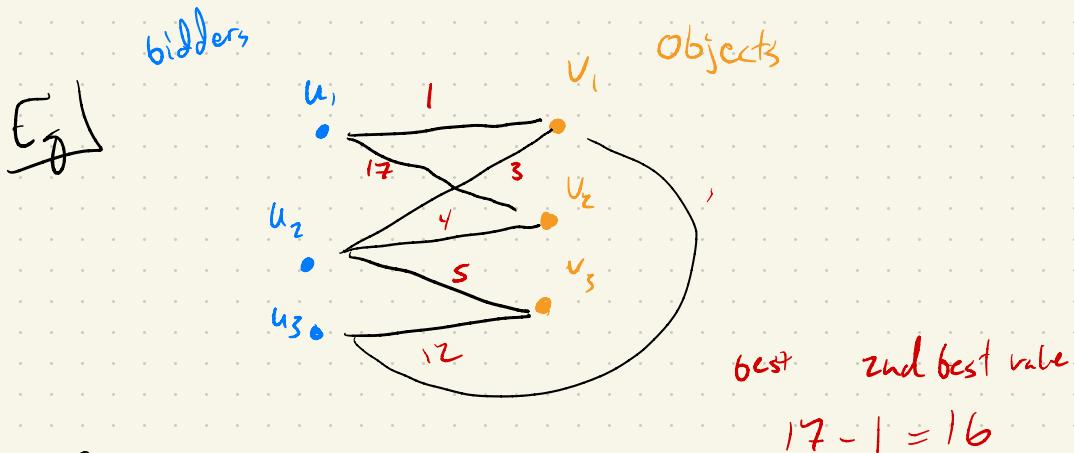
At each iteration, an unassigned bidder u

chooses object v with maximal value

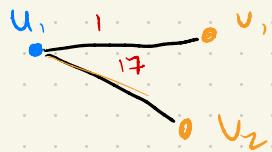
object v is assigned to u .

Let $\Delta p_{u,v}$ be the difference between highest value until and second highest.

Then $p_v = p_v + \Delta p_{u,v}$ for next iteration.



Iteration 1:



$$w(u_1, v_1) = 1$$

$$w(u_1, v_2) = 17$$

$$\underline{p_{v_1} = 0}, \underline{p_{v_2} = 0}$$

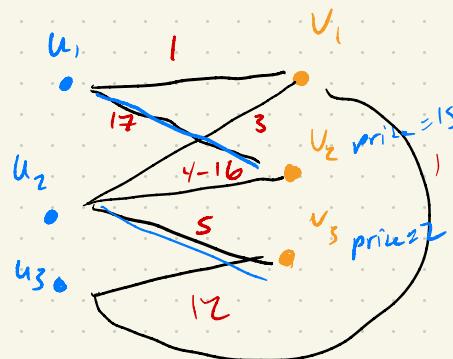
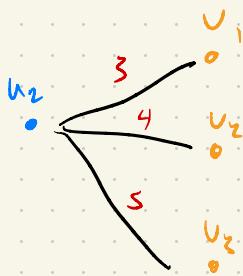
$$\text{value}(u_1, v_1) = 1$$

$$\text{value}(u_1, v_2) = 17$$

Choose u_1, v_2 .

$$\underline{\underline{p(v_2) = 0 + 16 = 16}} \text{ for next round.}$$

Iteration 2:



$$\text{Value}(u_2, v_1) = 3 - 0 = 3$$

$$\text{Value}(u_2, v_2) = 4 - \underline{16} = -\underline{12}$$

$$\text{Value}(u_2, v_3) = 5 - 0 = 5$$

choose
 best 2nd best

$$p(v_3) = 5 - 3 = 2 + \epsilon$$

$$p(u) = 0 + 2 + \epsilon$$

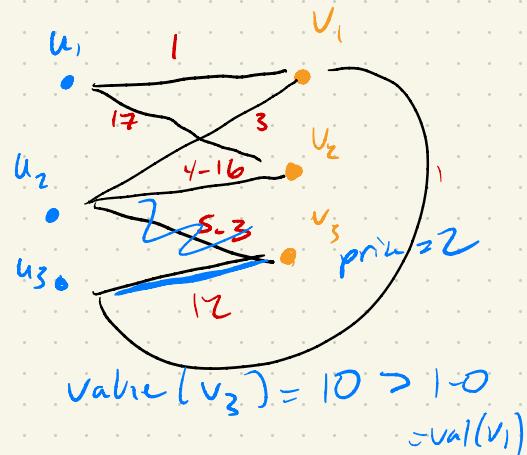
initial

Iteration 3:

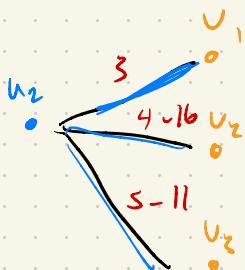


$$p_{v_3} = 12 - 1 = 11 \text{ for next iteration,}$$

u_2 is now at bid

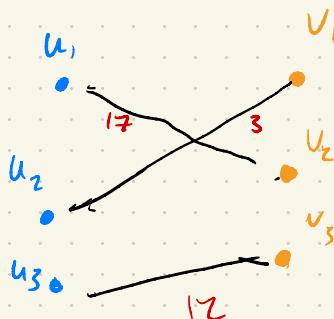


Iteration 4:



pair u_2, v_1

and we're done!



Remarks:

Another version: Jacobi Auction, every unassigned bidder makes a bid at each iteration. If several bidders want the same object, it goes to whoever has highest price increase.

This version is more expensive on average

(eg) many objects have same price for
many bidders.



X auction algo from
1974 is way 2 go!

Choosing ϵ : Note, the smaller the ϵ , the

longer the time of convergence for the auction.

But, the more precise a solution.

can compute q -Wasserstein distance with this procedure.

Fixing an approximation parameter $\delta \in (0, 1)$, let d denote the q th root of the value of an obtained matching in the algorithm.

Conclude algorithm if:

$$d^q \leq (1 + \delta)^q / (d^q - n\epsilon),$$

and return d .

We can turn these matchings into q -Wasserstein distance by taking q th roots + q th powers of L_∞ distances.

Conclude algorithm when matching is optimal, up to error term δ .

Formally,

ALGORITHM 1: AUCTION ALGORITHM

Input: Two persistence diagrams X, Y with $|X|, |Y| \leq n$, $q \geq 1$, $\delta > 0$ (maximal relative error)

Output: δ -approximate q -Wasserstein distance $W_q(X, Y)$

Initialize $d \leftarrow 0$ and $\varepsilon \leftarrow \frac{5}{4} \cdot (\text{max. edge length})$

while $d^q > (1 + \delta)^q(d^q - n\varepsilon)$ **do**

$$\varepsilon \leftarrow \varepsilon/5$$

Let M be an empty matching

while there exists some unassigned bidder i **do**

Find the best object j with value v_{ij} and the second best object k with value v_{ik} for i

Assign j to i in M and increase the price of j by $(v_{ij} - v_{ik}) + \varepsilon$

$d \leftarrow q$ -th root of the cost of the (perfect) matching M

return d

What is the crux?

Bidding:

Comparing max value object +
price increase is tricky!

Brute Force:

Exhaustive search over all objects per bidder

Lazy heaps: Keep a heap for each bidder of object values

uses $O(n^2)$ space

Geometry: Use a k-d tree with $O(n)$ space

Geometry:

Need to configure a k-d tree

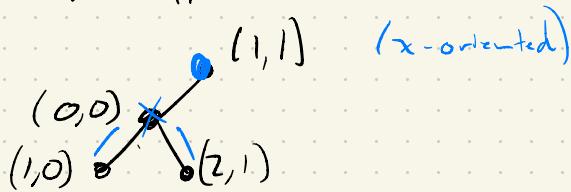
- Initially, when prices are zero,

U find best two objects by proximity search.

Eg. $(1, 1)$ $(2, 1)$

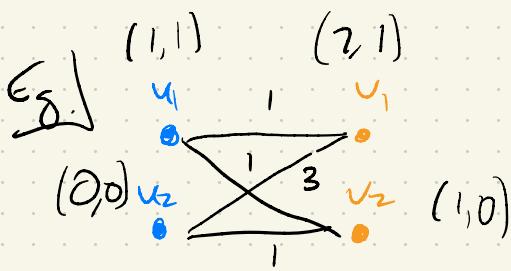
$(0, 0)$ v_1 v_2 $(1, 0)$

k-d tree

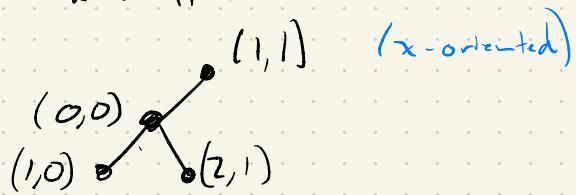


(when all prices are
zero)

Need to take changing prices
into account

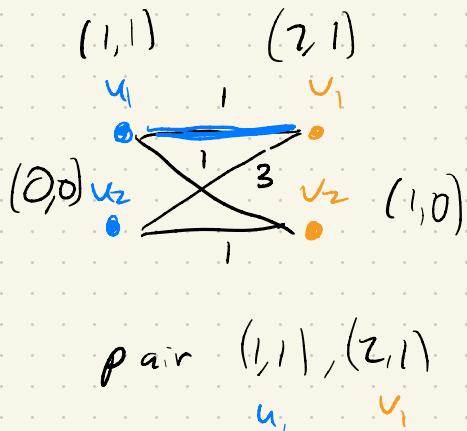


K-d tree

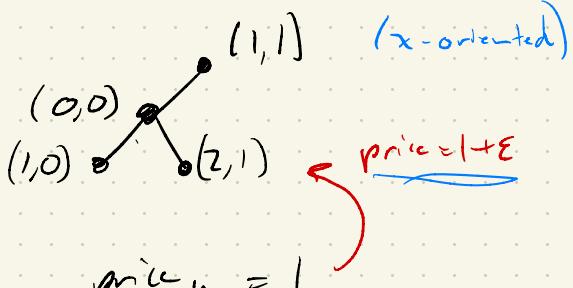


Store prices as weights in K-d tree!

Record minimum weight of any node
in subtree of internal nodes.

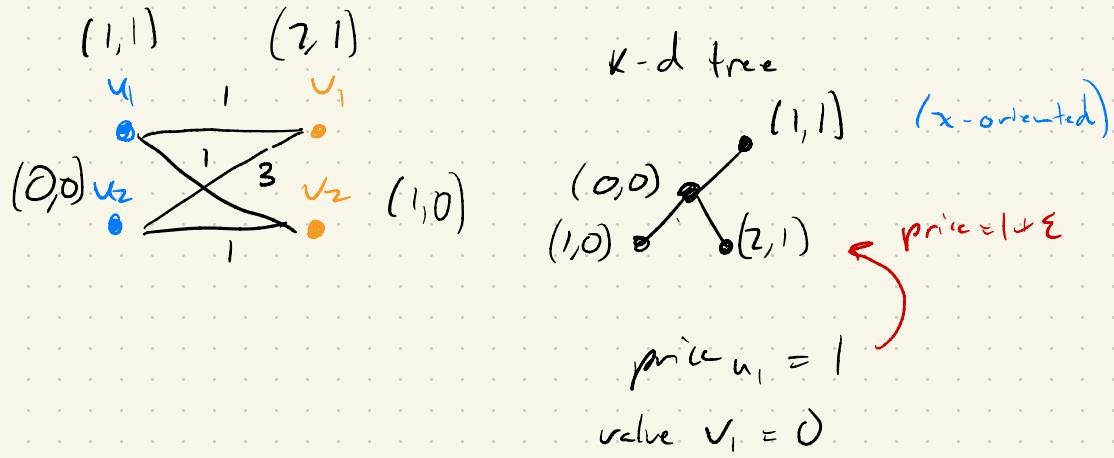


K-d tree

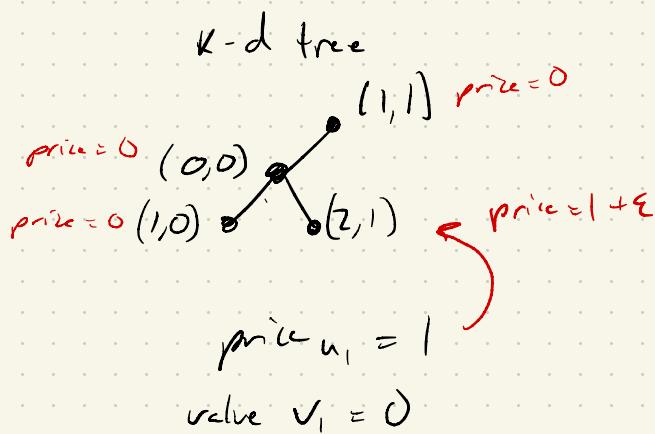


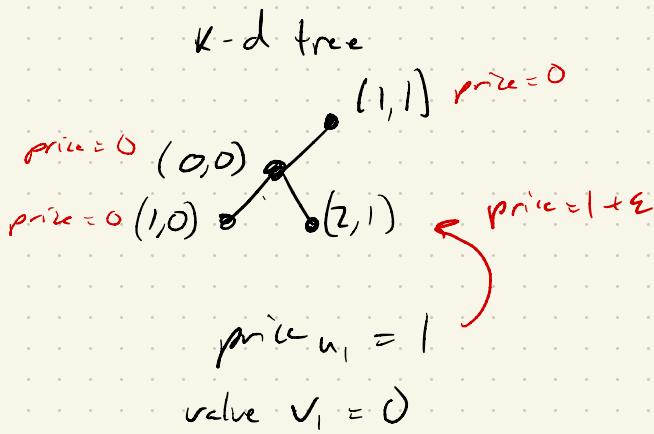
pair $(1,1), (2,1)$

price $u_1 = 1$
value $v_1 = 0$



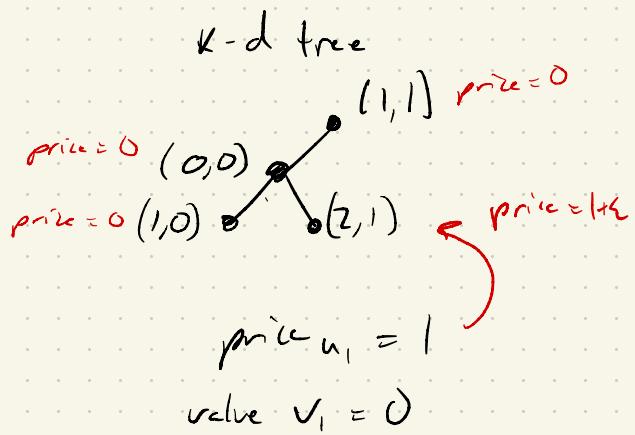
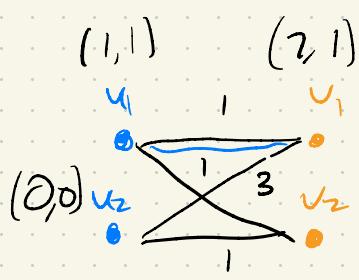
Save minimum weight of any node
in subtree of internal nodes



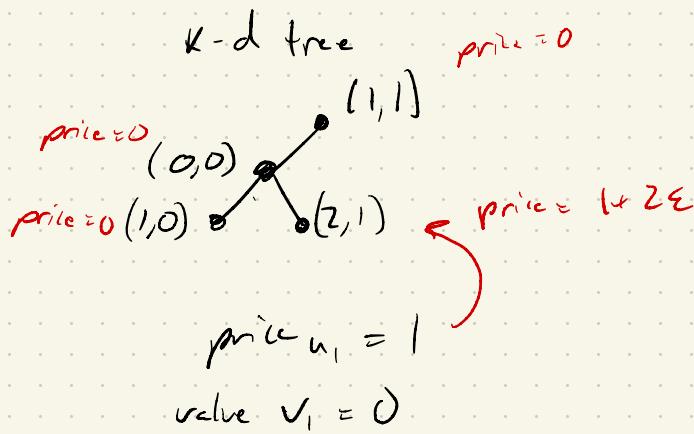


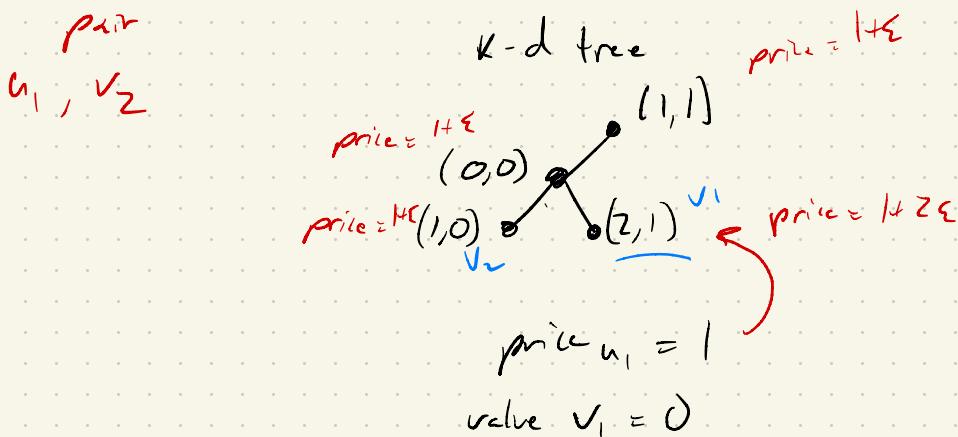
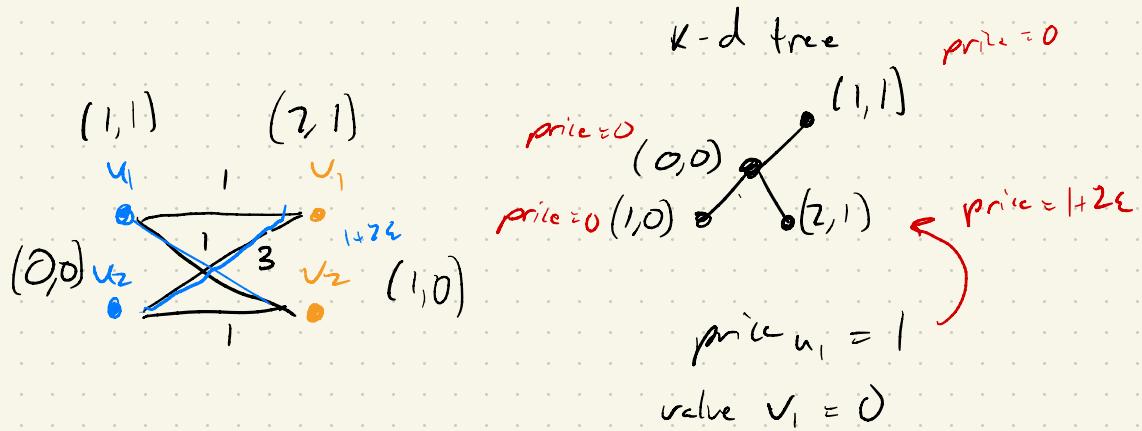
prune subtrees if qth power of distance

from query point to the box containing
 Subtree plus minimum weight a subtree
 exceeds second best candidate



pair
 u_i, v_i
 price v_i
 $= 1 + \epsilon + \epsilon$





Persistence Diagrams Need Extra Care

↳ Diagonal bidders can only bid for one object

↳ Off-diagonal bidders can bid for every off-diagonal object

but only one on-diagonal object
(its projection)

Experimental Results

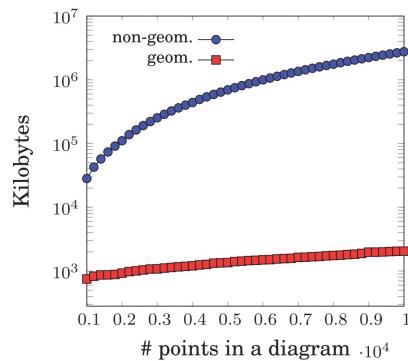


Fig. 6. Comparison of memory consumption of geometric and non-geometric versions of auction algorithm on normal instances.

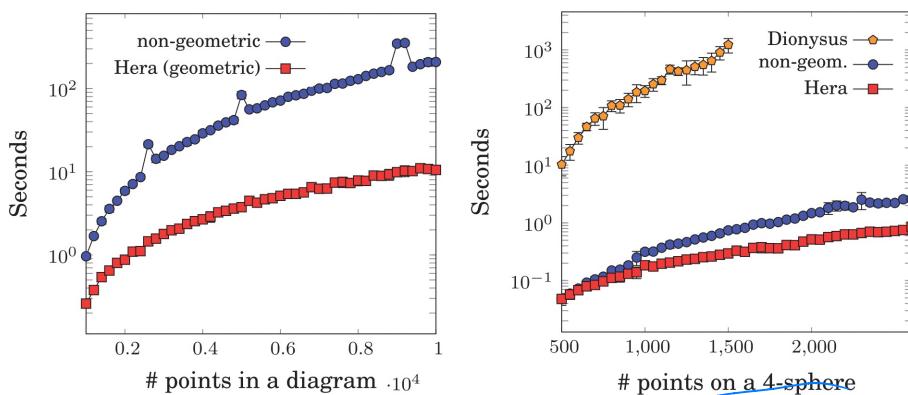


Fig. 7. Comparison of non-geometric and geometric variants of the auction algorithm on normal (left) and real (right) input, also with DIONYSUS on the real input.

More on repeated parts in paper.

Similar techniques implemented using kd trees

Takeaways:

- In matching-related problems, kd trees are a great data structure to use if matching occurs in a metric space
- We can tweak kd trees to consider changing variables relevant for matching (price, for example)
- The best algorithms on paper might be awful to implement!