# NOTES ON MATH FOR DATA SCIENCE

### BEN HORVATH

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The following collection was compiled while studying for the degree of masters of data science at City University of New York over the years 2018–present.

#### 1 ALGEBRA

#### ARITHMETIC OPERATIONS

$$a\left(\frac{b}{c}\right) = \frac{ab}{c} \qquad \quad \frac{\frac{a}{b}}{c} = \frac{a}{bc}$$

$$\frac{a}{b} = \frac{ac}{b} \qquad \qquad \frac{a}{b} \pm \frac{c}{d} = \frac{ad \pm bc}{bd}$$

$$\frac{a-b}{c-d} = \frac{b-a}{d-c} \qquad \frac{ab+ac}{a} = b+c, \ \forall a \neq 0$$

$$\frac{a+bc}{c} = \frac{a}{c} = \frac{b}{c} \quad \frac{\frac{a}{b}}{\frac{c}{d}} = \frac{ad}{bc}$$

#### **EXPONENTS**

$$x^{a} \cdot x^{b} = x^{a+b}$$
  $\frac{x^{a}}{x^{b}} = x^{a-b}$ 

$$(xy)^{\alpha} = x^{\alpha}y^{\alpha}$$
  $\frac{x}{y}^{\alpha} = \frac{x^{\alpha}}{y^{\alpha}}$ 

$$x^0 = 1^{\dagger} \qquad \qquad x^{-n} = \frac{1}{x}^{\dagger}$$

$$x^{\frac{1}{\alpha}} = \sqrt[\alpha]{x}^{\dagger} \qquad (xy)^{\alpha} = x^{\alpha}y^{\alpha}$$

$$\chi^{-\alpha} = \frac{1}{\chi^{\alpha}} \qquad \left(\frac{\chi}{y}\right)^{-\alpha} = \left(\frac{y}{\chi}\right)^{\alpha} = \frac{y^{\alpha}}{\chi^{\alpha}}$$

 $^{\dagger} \forall x \neq 0$ 

#### RADICALS

$$\sqrt[a]{x} = x^{\frac{1}{a}}$$
  $\sqrt[a]{xy} = \sqrt[a]{x} \sqrt[a]{y}$ 

#### LOGARITHMS

Defined as  $y = log_b x \equiv x = b^y$ , with domain of x > 0

$$log_bb = 1$$

$$log_bb^x = x$$

$$log_b(x^r) = r log_bx$$

$$log_b(\frac{x}{y}) = log_bx - log_by$$

$$log_b(xy) = log_bx + log_by$$

#### FACTORING

$$x^{2} - a^{2} = (x + a)(x - a)$$

$$x^{2} \pm 2ax + a^{2} = (x \pm a)^{2}$$

$$x^{2} + (a + b)x + ab = (x + a)(x + b)$$

# FUNCTIONS

- A rule for a relationship between an input and an output quantity where each input *uniquely determines* an output value
- Must be of the form y = f(x)

TYPE	FORM
Constant	f(x) = c
Identity	f(x) = x
Absolute	f(x) =  x
Quadratic	$f(x) = x^2$
Cubic	$f(x) = x^3$
Reciprocal	$f(x) = \frac{1}{x^2}$
Square root	$f(x) = \sqrt{x}$

#### TRANSFORMATIONS OF FUNCTIONS

Transformation	Form
Vertical shift	f'(x) = f(x) + k
Horizontal shift	f'(x) = f(x - k)
Horizontal reflection	f'(x) = f(-x)
Vertical reflection	f'(x) = -f(x)
Vertical stretch	f'(x) = kf(x), k > 1
Vertical compression	f'(x) = kf(x), k0 < k < 1

#### DISTANCE FORMULA

$$d(P_1, P_2) = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$

is the distance between points  $P_1 = (x_1, y_1)$  and  $P_2 = (x_2, y_2)$ 

#### LINEAR FUNCTIONS

• Linear functions have a constant rate of change, m

$$m = \frac{\Delta y}{\Delta x} = \frac{y_2 - y_1}{x_2 - x_1} = \frac{f(x_2) - f(x_1)}{x_2 - x_1}$$

- Estimate horizontal line by solving f(x) = 0
- Find the point where two non-parallel lines meet:
   set f(x) = g(x) and solve for x
- Estimate slope from two points by solving for m:

$$y_1 - y_2 = m(x_1 - x_2)$$

# QUADRATIC FUNCTIONS

Standard form  $f(x) = \alpha x^2 + bx + c$  Vertex or transformation form  $f(x) = \alpha (x - h)^2 + k$ 

Quadratic eq.

$$\chi = \frac{-b \pm \sqrt{b^2 - 4\alpha c}}{2\alpha}$$

- $b^2 4ac > 0 \Rightarrow$  Two real unequal solutions
- $b^2 4ac = 0 \Rightarrow$  Repeated real solution
- $b^2 4ac < 0 \Rightarrow$  Two complex solutions

$$f(x) = a_0 + a_1 x + a_2 x^2 + \dots + a_n x^n = \sum_{k=0}^n a_k x^{n-k}$$

a<sub>0</sub> Constant term

a<sub>n</sub> Polynomial coefficient

 $a_n x^m$  Term (m is called *degree*)

#### RATIONAL FUNCTIONS

Can be written as a quotient of two polynomials P(x) and Q(x):

$$f(x) = \frac{P(x)}{Q(x)} = \frac{\sum_{k=0}^{n} a_k x^{n-k}}{\sum_{k=0}^{n} b_k x^{n-k}}$$

- Horizontal Intercept is the inputs where the output is o
- Vertical Intercept is where input is o (if defined)

#### ASYMPTOTES

The "line" a function approaches but never touches

*vertical* A vertical line x = a where the graph tends towards positive or negative infinity as the inputs approach a:

$$x \to a$$
,  $f(x) \to \pm \infty$ 

*horizontal* A horizontal line y = b where the graph approaches the line as the input gets larger:

$$x \to \pm \infty$$
,  $f(x) \to b$ 

### ASYMPTOTES OF RATIONAL FUNCTIONS

*vertical* Where denominator = 0 but numerator  $\neq$  0

horizontal Determined by respective degrees of numerator and denominator:

- Degree of denominator > degree of numerator ⇒ Horizontal asymptote at y = 0
- Degree of denominator < degree of numerator ⇒ No horizontal asymptote
- Degree of denominator = degree of numerator ⇒ Horizontal asymptote is ratio of leading coefficients

#### **EXPONENTIAL FUNCTIONS**

Rate of change is as a percent, i.e., not an constant (absolute) rate. Takes the form:

$$f(x) = a(1+r)^x$$

or,

$$f(x) = ab^x, b = 1 + r$$

Can always be rewritten in terms of logarithms:

$$b^{a} = c \equiv \log_{b} c = a$$

continuous growth Use e = 2.718282... for continuous growth, often natural phenomena

$$f(x) = \alpha e^{rx}$$

where

- $a \equiv initial quantity$
- $r \equiv continuous growth rate$

# ALMOST ALWAYS USE CONTINUOUS e FORM!

Solve by:

- 1. Isolate exponential expression, where possible
- 2. Take log on both sides
- 3. Use *exponent property* of logs to pull variables of out exponent
- 4. Use algebra to solve for variable

#### GRAPHING EXPONENTIAL FUNCTIONS

- $a \equiv vertical intercept$ 
  - $a > 0 \Rightarrow$  concave up
  - a < 0 ⇒ concave down
- $b \equiv rate of growth$ 
  - $b > 1 \Rightarrow$  growing
  - -0 < b < 1 ⇒ decaying
- Horizontal asymptote is where y = 0

#### LOGARITHMIC FUNCTIONS

The inverse of exponential functions; use to solve exponential functions. Commonly used to express quantities that vary widely in size. Form:

which can be rewritten in terms of exponents:

$$b^{\alpha} = c \equiv \log_b c = \alpha$$

inverse property of logs

$$log_b b^x = x \\
b^{log_b x} = x$$

exponent property

$$log_b A^r = rlog_b A$$

#### 2 PROBABILITY

#### ASSUMPTIONS

$$\begin{split} 0 \leqslant P(E) \leqslant 1 \\ P(S) = 1 \\ P(S) = \sum_{i=1}^{\infty} P(E_i) \end{split}$$

Sample space S contains each event  $E_i$ , e.g.,  $E = \{all \text{ outcomes in S starting with a 3}\}$ 

#### UNIONS AND INTERSECTIONS

 $E \cup F$ 

is the union of the two sets E and F, i.e., the event where either E or F occurs. The intersection of two events, the outcomes in both E and F is

$$E \cap F$$
.

Commutative 
$$E \cup F = F \cup E$$
  
 $E \cap F = F \cap E$ 

Associative 
$$(E \cup F) \cup G = E \cup (F \cup G)$$

$$(E \cap F) \cap G = E \cap (F \cap G)$$

Distributive 
$$(E \cup F) \cap G = (E \cap G) \cap (F \cap G)$$
  
 $(E \cap F) \cup G = (E \cup G)(F \cup G)$ 

# INDEPENDENT EVENTS

Two events are independent if knowing the outcome of one provides no useful information about the outcome of the other.

#### MUTUALLY EXCLUSIVE EVENTS

$$P(A \cap B) = 0$$

are disjoint events, when A and B are mutually exclusive and there is no intersection—it is not possible for both to happen.

#### UNION AND ADDITION RULE

$$P(A \cup B) \equiv P(A \vee B) \equiv \{x : x \in A \vee x \in B\}$$

Independent 
$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$
 Mutually exclusive 
$$P(A \cup B) = P(A) + P(B)$$

#### INTERSECTION AND MULTIPLICATION RULES

$$P(A \cap B) \equiv P(A \wedge B) \equiv \{x : x \in A \wedge x \in B\}$$

Independent 
$$P(A \cap B) = P(A) \cdot P(B)$$

Mutually exclusive 
$$P(A \cap B) = 0$$

Dependent 
$$P(A \cap B) = P(A) \cdot P(B|A)$$

#### COMPLEMENT AND SUBTRACTION RULE

$$P(A') \equiv P(A^c) \equiv P(\neg A) \equiv \{x : x \notin A\} \equiv 1 - P(A)$$
  
 $P(A') = 1 - P(A)$ 

Some implications:

$$P(A \cup A^{c}) = 1$$

$$P(A) = 1 - P(A^{c})$$

$$P(A|B) = 1 - P(A^{c}|B)$$

#### CONDITIONAL PROBABILITY RULE

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

is the probability of the outcome of event A given condition B.

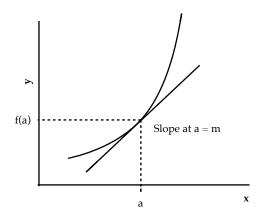
#### BAYES THEOREM

$$P(A|B) = \frac{P(A) \ P(B|A)}{P(A) \ P(B|A) + P(A) \ P(B|A)}$$

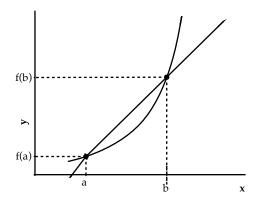
#### 3 CALCULUS

#### TANGENT AND SECANT LINES

 Tangent line is the line on f(x) at point x = α that just touches the graph of the function - The slope of a non-linear function at one point



• Secant line is the line between A and B on a curve



*Note*: As A gets closer to B the secant slope approaches the tangent line

# AVERAGE RATE OF CHANGE

$$ARC = f(\alpha, \alpha + \Delta) = \frac{\Delta y}{\Delta x} = \frac{f(\alpha + \Delta x) - f(\alpha)}{\Delta x}$$

over interval  $[a, a + \Delta x]$ 

# DERIVATIVE

The instantaneous rate of change of a function f(x) at point  $x=\alpha$ 

$$f'(\alpha) = \lim_{\Delta x \to 0} \frac{\Delta y}{\Delta x} = \lim_{\Delta x \to 0} \frac{f(\alpha + \Delta x) - f(\alpha)}{\Delta x}$$

"the derivative of y w.r.t.  $x''\equiv\frac{dy}{dx}\equiv lim_{\delta\to0}\,\frac{\delta y}{\delta x}$ 

$$x^n$$
  $nx^{n-1}$ 

$$\sqrt{x}$$
  $\frac{1}{2\sqrt{x}}$ 

$$\sqrt[n]{x} \qquad \frac{1}{n\sqrt[n]{x^{n-1}}}$$

$$\frac{1}{x}$$
  $\frac{-1}{x^2}$ 

$$e^{x}$$
  $e^{x}$ 

$$a^x$$
  $a^x \ln(a)$ 

$$x^x \qquad xx^{x-1} + x^x \ln(x)$$

$$ln(x)$$
  $\frac{1}{x}$ 

$$\log_{\alpha}(x)$$
  $\frac{1}{x}\log_{\alpha}(e)$ 

# y y'

9	9
u <sup>n</sup>	nu <sup>n-1</sup> u′
$\sqrt{u}$	$\frac{\mathfrak{u}'}{2\sqrt{\mathfrak{u}}}$
<sup>n</sup> √u	$\frac{u'}{n\sqrt[n]{u^{n-1}}}$
$\frac{1}{u}$	$\frac{-\mathfrak{u}'}{\mathfrak{u}^2}$
$e^{u}$	$e^{\mathfrak{u}}\mathfrak{u}'$
$\mathfrak{a}^{\mathfrak{u}}$	$a^{u} \ln(a) u'$
$u^{\nu}$	$vu^{v-1}u' + u^v \ln(u)v'$
$ln(\mathfrak{u})$	$\frac{\mathfrak{u}'}{\mathfrak{u}}$
$\log_{\mathfrak{a}}(\mathfrak{u})$	$\frac{\mathfrak{u}'}{\mathfrak{u}}\log_{\mathfrak{a}}(e)$

# DERIVATIVE OPERATIONS

Sum	(f(x) + g(x))' = f'(x) + g'(x)
Difference	(f-g)'(x) = f'(x) - g'(x)
Product	(fg)'(x) = f'(x)g(x) + f(x)g'(x)
Quotient	$\left(\frac{f(x)}{g(x)}\right)' = \frac{f'(x)g(x) - f(x)g'(x)}{g(x)^2}$
Chain rule	(f(g))'(x) = f'(g(x))g'(x)
Inverse	$(f^{-1})'(x) = \frac{1}{f'(x)}$

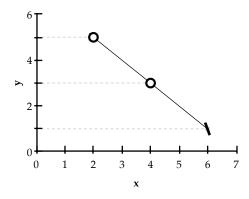
#### LIMITS

$$\lim_{x \to C} f(x) = L$$

or, "the limit of f(x), as x approaches c, is L."  $\lim_{x\to C} f(x)$  is a *single number* that describes the behavior of the function f(x) *near* but not at the point x=c.

Introduced to make calculating rate of change at o feasible, by making the  $\Delta$  so infinitesimal the difference is between it and o is negligible—"allows" division by o

# Example



where hollow points are undefined and solid points are defined

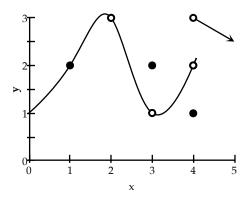
1. 
$$\lim_{x\to 6} f(x) = 1$$

2. 
$$\lim_{x\to 4} f(x) = 3$$

• *Note*: even though x = 4 is undefined, we're only concerned with the area *around* 4, so we can still find the limit

3. 
$$\lim_{x\to 2} f(x) = 5$$

Example: Determining Limits of Non-Linear Functions



where hollow points are undefined and solid points are defined

- 1.  $\lim_{x\to 1} f(x) = 2$ —values where x is close to but not equal to 1 are near 2
- 2.  $\lim_{x\to 2} f(x) = 3$ —even though f(2) is undefined, only values *near* f(2) are important
- 3.  $\lim_{x\to 3} f(x) = 1$ —even though f(3) is actually 2
- 4.  $\lim_{x\to 4} f(x) = does \ not \ exist$ : Can't determine a single number because f(4) from the right is about 2, and from the left about 3

Example: Determining Limits Using Algebra

Factor equation to simplest form and plug in c (assuming function at c is defined):

$$\lim_{x \to 5} \frac{x^2 - 6x + 8}{x - 4} = \frac{25 - 30 + 8}{1} = 3$$

#### LIMITS OF BROKEN FUNCTIONS

Some functions are continuous but in an unusual way—they appear "broken" when graphed—and so there is a *left* and *right* limit

*left* "The limit coming from the left"; values of f(x) as f(x) nears x and left of c, x < c

$$\lim_{x \to c^{-}} f(x) = L$$

*right* "This limit coming from the right"; values of f(x) as f(x) nears x and right of c, x > c

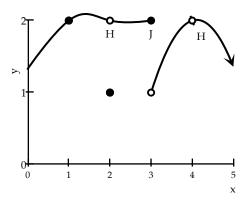
$$\lim_{x \to c^+} f(x) = L$$

*Note*: If left and rights limits are not the same, limit *doesn't exist*.

# CONTINUITY

A function f is continuous at x = a iff  $\lim_{x \to a} f(x) = f(a)$ , i.e., if the limit of x at a is equals f(a), i.e., no breaks or jumps

Example



where H indicates a hole—where the graph is defined but could be made continuous by changing the point and J a jump—where the left and right limits are not the same.

- Continuous at 1 since  $\lim_{x\to 1} f(x) = f(1) = 2$
- Not continuous at 2, 3, or 4

$$-\lim_{x\to 2} f(x) = 2 \neq f(2) = 1$$

$$-\lim_{x\to 3} f(x) = \text{doesn't exist} \neq f(3) = 2$$

- 
$$\lim_{x\to 4} f(x) = 2 \neq f(4) =$$
undefined

#### CALCULATING DERIVATIVES

Example: Using Formal Definition

Find derivative of  $f(x) = 2x^2 - 16x + 35$ .

1. Assemble using the formal definition

$$\frac{[2(x-h)^2 - 16(x+h) + 35] - [2x^2 - 16x - 35]}{h}$$

2. Factor—cannot plug h = 0 because no division by zero!

$$= \frac{2x^2 + 4xh + 2h^2 - 16x - 16h + 35 - 2x^2 + 16x - 35}{h}$$

$$= \lim_{h \to 0} \frac{4xh + 2h^2 - 16h}{h}$$

3. Factor out h in numerator to cancel h in denominator

$$f'(x) = \lim_{h \to 0} \frac{h(4x + 2h - 16)}{h}$$
$$= \lim_{h \to 0} 4x + 2h - 16$$
$$= 4x - 16$$

#### IMPLICIT DIFFERENTIATION

The process to find y' = f'(x) when f(x) is difficult or impossible to use with explicit differentiation, by assuming y is a function of x:

Example

Implicitly differentiate  $x^2 + y^2 = 25$ 

1. Differentiate each side, treating y as a function

$$\frac{d}{dx}(x^2 + y^2) = \frac{d}{dx}25$$

$$\Rightarrow \frac{d}{dx}x^2 + \frac{d}{dx}y^2 = 0$$

$$\Rightarrow 2x + 2y\frac{dy}{dx} = 0$$

$$\Rightarrow 2x + 2yy' = 0$$

2. Algebraically solve for y'

$$2yy' = -2x$$

$$\Rightarrow y' = \frac{-2x}{2y}$$

$$\Rightarrow y' = -\frac{x}{y}$$

#### DEFINITE INTEGRAL

The definite integral of a positive function f(x) over an interval [a, b] is the area between f, the x-axis, x = a, and x = b.

$$\int_a^b f(x) dx$$

where a and b are the "limits of integration" and f(x) is the integrand

$$\int_{a}^{a} f(x) dx = 0$$

$$\int_{a}^{b} f(x) dx = -\int_{b}^{a} f(x) dx$$

$$\int_{a}^{b} f(x) dx = \int_{a}^{c} f(x) dx + \int_{c}^{b} f(x) dx$$

where a < c < b

#### INTEGRATION OPERATIONS

Sum  $\int u + v \, dx = \int u \, dx + \int v \, dx$ Difference  $\int u - v \, dx = \int u \, dx - \int v \, dx$ Product  $\int af(x) \, dx = a \int f(x) \, dx$ Parts  $\int u \, dv = uv - \int v \, du$ Substitution  $\int f(u)u' \, dx = \int f(u) \, du$ 

#### GROWTH, CONCAVITY, AND EXTREMA

growth

- $\forall x \in I \ f'(x) \ge 0 \Rightarrow f \ is increasing \ in \ I.$
- $\forall x \in I \ f'(x) \leq 0 \Rightarrow f \ is \ decreasing \ in \ I.$

concavity

- $\forall x \in I f''(x) \ge 0 \Rightarrow f$  is concave up in I.
- $\forall x \in I f''(x) \leq 0 \Rightarrow f$  is concave down in I.

extrema If f'(a) = 0 (critical point)

•  $f''(\alpha) < 0 \Rightarrow f$  has a local maximum at  $x = \alpha$ .



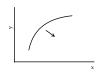


Figure 1: Concave up (left) and concave down (right)

•  $f''(a) > 0 \Rightarrow f$  has a local minimum at x = a.

#### INCREASING AND DECREASING FUNCTIONS

- f(x) is *increasing* iff  $\forall x_1, x_2$  in interval I is such that  $x_1 < x_2$  and  $f(x_1) < f(x_2)$
- f(x) is *decreasing* iff  $\forall x_1, x_2$  in interval I is such that  $x_1 > x_2$  and  $f(x_1) > f(x_2)$
- Determine all intervals where f(x) is in/decreasing:
  - 1. Find all critical points (via first deriative)
  - 2. For each critical point, select a number  $\mathfrak a$  in that range and see if  $\mathfrak f'(\mathfrak a)$  is positive or negative

#### INFLECTION POINTS

- Where the second derivative changes signs
- The point(s) on a graph where the concavity of a function changes from up to down
- functions can be increasing (positive derivative) or decreasing (negative derivative) regardless of concavity,

#### MAXIMA AND MINIMA

A *critical point* is a point where either  $f'(\alpha) = 0$  or  $f'(\alpha)$  is undefined, and is a *candidate* of being a local or global extreme

Local

maximum at a if  $f(a) \ge f(x) \forall x$  near a

*minimum* at a if  $f(a) \leq f(x) \forall x$  near a

extreme at a if f(a) is a local maximum or minimum

#### Global

maximum at a if  $f(a) \ge f(x) \ \forall x$  in domain of f minimum at a if  $f(a) \le f(x) \ \forall x$  in domain of f extreme at a if f(a) is a global maximum or minimum

# Example

Find the critical point of  $f(x) = x^3 - 6x^2 + 9x + 2$ 

1. Find f'(x)

$$f'(x) = 3x^{2} - 12x + 9$$

$$= 3(x^{2} - 4x + 3)$$

$$= 3(x - 1)(x - 3)$$

- 2. Find where f'(x) = 0, which is 1 and 3
- 3. Put x = 1 and x = 3 into f(x) to find the critical points

$$(1,f(1)) = (1,6)$$
  
 $(3,f(2)) = (3,2)$ 

#### ANTIDERIVATIVES

- An antiderivative of a function f(x) is any function F(x) such that F'(x) = f(x)
- The antiderivative is an entire family of functions, written F(x) + c
- Also known as the *indefinite integral* (with no limit markers):

$$\int f(x) dx$$

### Example

*An* antiderivative of  $\int 2x \, dx$  is  $x^2 - 5.2$ ; the antiderative is  $x^2 + C$ 

#### DEFINITE V. INDEFINITE INTEGRALS

Indefinite integrals do not have limits to integration where definite integrals do

#### INTEGRATION BY SUBSTITUTION

A method to algebraically manipulate an integrand so it is amenable to antiderivative rules; especially useful when there is a product in the integral. Substitute  $\mathfrak{u}$  for  $\mathfrak{g}(x)$  where necessary, making

Substitute u for 
$$g(x)$$
 where necessary, making  $\frac{du}{dx} = g'(x)$ , so  $du = g'(x) dx$ . Since

$$\frac{du}{dx} = g'(x) \equiv du = g'(x) dx$$

we can substitute so that

$$\int f'(g(x))g'(x) dx \equiv \int f'(u) du$$

Now integrate f'(u) du. (Note that  $g(x) \equiv u$  and g'(x) dx  $\equiv$  du.)

- 1. Set one part of the integrand to u, one "level" into the integral
- 2. Compute  $du = \frac{du}{dx} dx$  (the derivative of u)
- 3. Convert x's to u's in original integral, even including in dx
- 4. Integrate new u integral
- 5. Substitute u's back to x's in integral

#### Example

Integrate  $\int (x+1)^3 dx$ 

1. Rearrange so that u = x + 1 and du = 1 dx

$$= \int (x+1)^3 \cdot 1 \, \mathrm{d}x$$

2. Substitute in u and du

$$\int u^3 du$$

3. Integrate

$$=\frac{u^4}{4}+C$$

4. Add u back in

$$=\frac{(x+1)^4}{4}+C$$

# INTEGRATION BY PARTS

Integrate a complex function by rewriting it as a product of two simpler functions u and du, using two possible forms:

$$\int u \, dv = uv - \int v \, du$$

$$\int_a^b u \, dv = uv|_a^b - \int_a^b v \, du$$

# 3.1 Example: First Form

Integrate  $\int xe^x dx$ :

- 1. Break into two parts: u = x and  $dv = e^x dx$
- 2. Calculate the derivative of u, du, and v, the integral of dv

$$du = \left(\frac{d}{dx}x\right) dx = 1 dx$$

$$v = \int dv = \int e^x dx = e^x$$

3. Using the first formula, noting the prior forms from 1 and 2

$$\int u \, dv = \int x e^x \, dx$$
$$= x e^x - \int e^x \, dv$$
$$= x e^x - e^x + C$$

# 3.2 Example: Second Form

Integrate  $\int_{1}^{4} 6x^{2} \ln x \, dx$ :

- 1. Break into two parts:  $u = \ln x$  and  $dv = 6x^2$
- 2. Calculate the derivative of u, du, and the integral of dv, v:

$$du = \frac{d}{dx} \ln x = \frac{1}{x} dx$$

$$v = \int 6x^2 dx = 6 \int x^2 dx = 6 \cdot \frac{x^3}{3} = 2x^3$$

3. Use the second formula

$$\int_{1}^{4} 6x^{2} \ln x \, dx = 2x^{3} \ln x \Big|_{1}^{4} - \int_{1}^{4} 2x^{3} \frac{1}{x} \, dx$$
$$= 2x^{3} \ln x \Big|_{1}^{4} - 3x^{2} \Big|_{1}^{4}$$

4. Find the integral the usual way:

$$[(2 \cdot 4^{3} \ln(4)) - (2 \cdot 1^{3} \ln(1))] - [(3 \cdot 4^{2}) - (3 \cdot 1^{2})]$$

$$= 128 \cdot \ln(4) - 45$$

$$\approx 132.446$$

#### ANTIDERIVATIVE RULES

$$\int a \, dx \qquad ax + C$$

$$\int x^n \, dx \qquad \frac{u'}{2\sqrt{u}}$$

$$\int e^x \, dx \qquad e^x + C$$

$$\int a^x \, dx \qquad \frac{a^x}{\ln(a)} + C$$

$$\int \frac{1}{x} \, dx \qquad \ln|x| + C$$

#### 4 STATISTICS

#### EXPECTED VALUE

$$E(X) = \mu = \sum_{i=1}^{k} x_i P(X = x_i)$$

for a discrete random variable with k possible values.

#### GENERAL VARIANCE FORMULA

$$Var(X) = \sigma^2 = \sum_{i=1}^k (x_j - \mu)^2 \ P(X = x_j),$$

or, the sum of the squared deviations  $(x_j - \mu)^2$  weighted by the corresponding probabilities  $P(X = x_1), \dots, P(X = x_k)$ .

#### GENERAL STANDARD DEVIATION

$$\sigma = \sqrt{\sigma^2} = \sqrt{Var(X)}$$

#### LINEAR COMBINATIONS OF VARIABLES

$$Z = aX + bY$$

is a linear combination of the independent, random variables X and Y (often  $\alpha$  and  $\beta$  are 1 or -1).

$$E(Z) = \alpha \times E(X) + b \times E(Y)$$

$$Var(Z) = \alpha^{2} \times Var(X) + b^{2} \times Var(Y)$$

### PROBABILITY DENSITY FUNCTION (PDF)

$$P(a \leqslant X \leqslant b) = \int_{a}^{b} f(x) dx$$

is a PDF of X, for any two numbers  $\alpha$  and b where  $\alpha \le b$ . I.e., the probability that X takes on a value in the interval  $[\alpha, b]$  is the area above this interval and below the graph of the density curve.

- P(X = c) = 0 for any constant (bins are infinitesimally small)
- $\sum P(x_i) = 1$

#### NORMAL DISTRIBUTION V. STANDARD NORMAL

There is any entire family of distributions that can be called normal, but the prototypical distribution with mean of 0 and standard deviation of 1 is called the standard normal. Formally defined by its PDF as:

$$f(x \mid \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{\frac{-(x-\mu)^2}{2\sigma^2}}$$

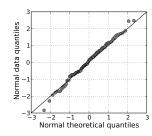
# Properties

- 1. Symmetric around mean
- 2. Mean = mode = median
- 3. Denser at center than in tails

# Consequently,

- 68 percent of distribution is within one standard deviation of the mean
- 95 percent of distribution is within approximately two standard deviations of the mean

#### **EVALUATING NORMALITY**



- A normal probability plot using quartiles can be used to evaluate how closely a given distribution adheres to normality, where the straight line is a perfect normal curve
- As N increases, the deviation from normality will decrease

#### Z SCORES

$$Z = \frac{x - \mu}{\sigma}$$

converts any value from a normal distribution to its corresponding value on the standard normal distribution

- Describes the number of standard deviations a point is from the mean  $\mu$
- Z scores to the left of  $\mu$  are negative, and positive to the right of  $\mu$

# Z SCORES: PROBABILITIES ON NORMAL DISTRIBUTION

Ex. What is the probability X > A, given  $X \sim N(\mu = 1500, \sigma = 300)$ ?

$$Z = \frac{x - \mu}{\sigma} = \frac{1630 - 1500}{300} = 0.43$$

This is 0.6664 on Z table, so 66.64 percent of X is to the left of A so:

$$1 - 0.6664 = 0.3336$$

The probability X > A is 33.36 percent.

Ex. Given A = 1400 and  $X \sim N(\mu = 1500, \sigma = 300)$ , what is the percentile corresponding to A?

$$Z = \frac{x - \mu}{\sigma} = \frac{1400 - 1500}{300} = -0.33$$

The corresponding value on the Z table is 0.3707, so A is the 37th percentile.

Ex. Given p = .40 and  $X \sim N(\mu = 70, \sigma = 3.3)$ , what is the value corresponding to percentile p?

Lookup p on Z table, getting a Z = -0.25. Work backwards:

$$-0.25 = Z = \frac{x - \mu}{\sigma} = \frac{x - 70}{3.3}$$

and solve for x = 69.18.

Ex. What is the probability X is between A and B, given  $X \sim N(\mu, \sigma)$ ?

Using Z-scores method, find the area to the left of A and to the right of B, then A - B = 1 area left of A are to right of B.

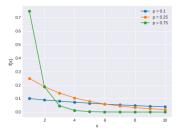
$$P(X = x) = \begin{cases} p \text{ for } x = 1\\ 1 - p \text{ for } x = 0 \end{cases}$$

describes the distribution of individual trials with two possible outcomes, success or failure, described by proportion of successes  $0 \le p \le 1$ :

$$\begin{array}{rcl} \hat{p} & = & \frac{\mid successes \mid}{\mid failures \mid} \\ \mu & = & p \\ \sigma^2 & = & p(1-p) \end{array}$$

• The probability of success after n trials is  $(1-p)^{n-1} \times p$ 

#### BERNOULLI: GEOMETRIC DISTRIBUTION

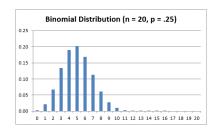


describes the wait time until a success for *independent* Bernoulli random variables; or, the probability of observing the k-th success by the n-th trial

$$\begin{array}{rcl} \mu & = & \displaystyle \frac{1}{p} \\ \\ \sigma^2 & = & \displaystyle \frac{1-p}{p^2} \end{array}$$

- Higher p means fewer trials until success
- Can never be approximated by a normal distribution

# BINOMIAL DISTRIBUTION



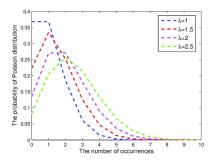
describes the probability of having exactly k successes in n independent Bernoulli trials (with probability of success p):

$$P(x = k \mid n, \mu, \sigma) = \binom{n}{k} p^{k} (1 - p)^{n - k}$$
$$= \frac{n!}{k!(n - k)!} p^{k} (1 - p)^{n - k}$$

Parameters, can be used to approximate to normal when n is sufficiently large and np and n(1-p) are both greater than or equal to 10:

$$\begin{array}{rcl} \mu & = & np \\ \sigma^2 & = & np(1-p) \end{array}$$

#### POISSON DISTRIBUTION



$$P(X = x \mid \lambda) = \frac{\lambda^{x} e^{-\lambda}}{x!}$$

Describes the number of events in a larger population over a unit of time with rate  $\lambda$ :

$$\mu = \lambda$$
 $\sigma^2 = \lambda$ 

### INFERENTIAL STATISTICS

The body of thought governing the inferences of populations from samples, and how these sample statistics can vary.

#### STANDARD ERROR

$$SE = \frac{\sigma}{\sqrt{n}}$$

is the standard deviation of distributions of sample statistics, when population  $\sigma$  is known. If it is unknown, and if n>30, substitute sample standard deviation s

- SE decreases as n increases
- SE decreases as  $\sigma$  (or s) decreases

#### CONFIDENCE INTERVALS

$$\bar{\mathbf{x}} \pm \mathbf{z} \times \mathsf{SE}$$

- $\bar{x}$  is the sample statistic, such as sample mean
- $z \times SE$  is the margin of error
- z is the desired confidence level, e.g., z = 1.96 for a 95 percent confidence interval

*Interpretation.* "We are Z percent confident the true population *statistic* is between A and B"; or, "Z percent of samples will have a *sample statistic* between A and B."

#### CENTRAL LIMIT THEOREM

Given a population with a finite mean  $\mu$  and a finite non-zero variance  $\sigma^2$ , the sampling distribution of the mean approaches a normal distribution with a mean of  $\mu$  and a variance of  $\frac{\sigma^2}{N}$ , as N, the sample size, increases—regardless of the shape of the parent population.

#### HYPOTHESIS TESTING

$$\begin{tabular}{ll} One-Sided & Two-Sided \\ \hline $H_0:x=A$ & $H_0:x=A$ \\ $H_A:x>/$$

The process of comparing two point estimates, to determine if any difference between them is "real" or the result of natural variance in samples.

- *Type I* errors, or false positives, occur when H<sub>0</sub> is true, but rejected
- Type II errors, or false negatives, occur when  $H_A$  is true, and  $H_0$  is not rejected

# Quantifying Risk

- The risk of Type I errors is quantified by  $\alpha$ , i.e., the probability the point estimate is more than  $z^*$  standard deviations away from the true population parameter
- The p-value is the probability of observing data at least as favorable to the alternative hypothesis, i.e., as "extreme," as the present data set, if H<sub>0</sub> is actually true
- If the p-value is less than the chosen  $\alpha$ , data is sufficient to reject  $H_0$

#### P-VALUE CALCULATIONS

One-Sided

Two-Sided

#### SAMPLE PROPORTIONS

Population parameter  $\pi$  is sampled:

$$\begin{array}{rcl} \mu & = & \hat{p} = \frac{\sum_n^{i=1} x_i}{n} \\ SE_{\hat{p}} & = & \sqrt{\frac{p(1-p)}{n}} \end{array}$$

where  $0 \le \hat{p} \le 1$  and  $x_i = \{0, 1\}$ 

#### SAMPLE PROPORTIONS: CONFIDENCE INTERVALS

- 1. Assess normality:
  - At least 10 observations for each {0, 1}
  - Sample is less than 10 percent of population and observations are independent
- 2. Calculate standard error  $SE_{\hat{p}} = \sqrt{\frac{p(1-p)}{n}}$
- 3. Determine  $z^*$ , e.g., 1.96
- 4. Put together point estimate and margin of error:

$$\hat{p} \pm z^* \times SE_{\hat{p}}$$

FIX

$$\begin{split} H_0: \hat{p} = 0.5 \\ H_A: \hat{p} > / \neq 0.5 \end{split}$$

- 1. Evaluate normality
- 2. Compute  $SE_{\hat{p}}$  using null hypothesis:

$$SE_{\hat{p}} = \sqrt{\frac{p(1-p)}{n}},$$

often 
$$\sqrt{\frac{0.5(1-0.5)}{n}}$$

3. Calculate Z-score using hypotheses:

$$\frac{\hat{p} - \hat{p}_0}{SE_{\hat{p}}}$$

4. Convert Z to p-value and decide whether to reject the null or fail to

SAMPLE PROPORTIONS: SAMPLE SIZE

#### DIFFERENCE OF PROPORTIONS

DIFFERENCE OF PROPORTIONS: CONFIDENCE INTERVALS

DIFFERENCE OF PROPORTIONS: HYPOTHESIS TESTS

DIFFERENCE OF PROPORTIONS: POOLED PROPORTION

 $\chi^2$  goodness of fit

$$\chi^2 = \sum_{k=1}^{N} \frac{(observed_k - expected_k)^2}{expected_k}$$

- k mutually exclusive classes
- n observations of x<sub>i</sub>
- one parameter, degrees of freedom df
- follows the chi-square distribution if null hypothesis is true

Summarizes how strongly observed count data deviates from the expected, or null, counts—larger values of  $\chi^2$  indicate stronger deviation

Does a statistical model fit this sample?

1. Develop hypotheses:

a) H<sub>0</sub>: Sample follows distribution D

b)  $H_A$ : Sample does not follow distribution D

2. Check assumptions

a) Each expected count must be at least 5

b) Can use binning to get around this

3. Establish expected counts (expected proportion of total count in each bin):

$$E_k = expected_k \times n$$

4. Compute  $\chi^2$  statistic

5. Validate assumptions hold to apply  $\chi^2$  to  $\chi^2$  distribution

6. Using k-1 degrees of freedom, use  $\chi^2$  table to compute a p-value

7. Decide to reject or fail to reject  $H_0$ 

$$\chi^2$$
: p-value

# TWO-WAY TABLES: INDEPENDENCE

#### SAMPLE STATISTICS: MEAN AND VARIANCE

- $\mu_M = \mu$  is the mean of the sampling distribution of means
- $\sigma_M^2 = \frac{\sigma^2}{N}$  is the variance of the sampling distribution of the mean
- $\sigma_M = \frac{\sigma}{\sqrt{N}}$  is the standard error of the sampling distribution of the mean

As N increases, variance of sample mean decreases

#### SAMPLE STATISTICS: DIFFERENCE IN MEAN

Two samples from a population the size  $n_1$  and  $n_2$ , calculate the means  $M_1$  and  $M_2$ , and the difference is  $M_1-M_2$ 

$$\begin{array}{rcl} \mu_{M_1-M_2} & = & M_1-M_2 \\ \sigma_{M_1-M_2}^2 & = & \sigma_{M_1}^2+\sigma_{M_2}^2 \\ \sigma_{M_1-M_2} & = & \sqrt{\frac{\sigma_1^2}{n_1}+\frac{\sigma_2^2}{n_2}} \end{array}$$

When variance and sample size are the same, standard error becomes:

$$\sigma_{M_1-M_2} = \sqrt{\frac{\sigma_1^2}{n_1} + \frac{\sigma_2^2}{n_2}} i = \sqrt{\frac{\sigma^2}{n} + \frac{\sigma^2}{n}} = \sqrt{\frac{2\sigma^2}{n}}$$

If  $n_1 \neq n_2$  then variance becomes:

$$\sigma_{M_1 - M2}^2 = \frac{\sigma_1^2}{n_1} + \frac{\sigma_2^2}{n_2}$$

What is the probability that the mean of sample 1 will exceed that of sample 2 by N or more?

1. Find mean:  $\mu_{M_1-M_2} = M_1 - M_2$ 

2. Find standard error:  $\sigma_{M_1-M_2}$ 

3. Find area underneath distribution of sample 1 to the right of the mean of sample 2 plus N

#### SAMPLE STATISTICS: r AND ρ

- Not normally distributed—right-skewed—because correlation cannot exceed 1
- As ρ increases, the more right-skewed the distribution

# sample statistics: Proportion $\pi$

Sampling proportion is closely related to the binomial distribution—the total number of successes—where p is the distribution of the mean number of successes

$$\begin{array}{lcl} \mu_p & = & \pi \\ \\ \sigma_p & = & \frac{\sqrt{N\pi(1-\pi)}}{N} = \sqrt{\frac{\pi(1-\pi)}{N}} \end{array}$$

Find probability p is greater than A

Given N and population proportion  $\pi$ :

- 1. Find mean of  $p = \pi$
- 2. Calculate standard error as above
- 3. Conduct as normal distribution given N is sufficiently large and  $\pi$  is not too close to 0 or 1

#### **ESTIMATION**

The process of estimating population parameters from sample statistics. Usually results in a point estimate as well as interval estimates called confidence intervals.

#### DEGREES OF FREEDOM

### 5 REGRESSION: OLS

FORM

$$y = \beta_0 + \beta_1 x$$

describes the true, unobserved model, while

$$\hat{\mathbf{y}} = \mathbf{b}_0 + \mathbf{b}_1 \mathbf{x}$$

describes the estimated model. The estimate  $\hat{y}$  describes the average value around which subjects where  $x=x_i$  will cluster.

#### RESIDUALS

$$e_i = y_i - \hat{y}_i$$

is the residual of the ith observations  $(x_i, y_i)$ , the differences between the observed response  $(y_i)$  and the prediction  $\hat{y}$ 

#### CORRELATION

$$r = \frac{1}{n-1} \sum_{i=1}^{n} \frac{x_i - \bar{x}}{s_x} \frac{y_i - \bar{y}}{s_y}$$

describes the strength of the linear relationship between two variables x and y, where  $0 \le r \le 1$ , and s is sample standard deviation

# LEAST SQUARES CRITERION

$$\arg\min \sum_{i=1}^{n} e_{i}^{2} \equiv e_{1}^{2} + e_{2}^{2} + \ldots + e_{n}^{2}$$

describes the best fitting line, the *least squares line*, i.e., minimizes the sum of squared residuals. To calculate:

$$b_1 = \frac{s_y}{s_x} r$$

$$y - \hat{y} = b_1(x - \hat{x})$$

where  $x_0 = \bar{x}$  and  $y_0 = \bar{y}$ 

# Assumptions

- 1. Linearity. Data must show a linear trend
- 2. Near normal residuals

- 3. *Constant variability*. The variability of points around the least-squares line must be constant, e.g., the scale of *e* cannot increase as x increases producing a fanning pattern
- 4. Independent observations.