Lagrangian and Hamiltonian Dynamics

Final project proposal

BENJAMIN HOWE

I. Description

The pendulum on a rotating rim. A simple pendulum of length b and mass m moves on a mass-less rim of radius a rotating with constant angular velocity ω . Find the equation of motion for the mass.

II. DIAGRAM

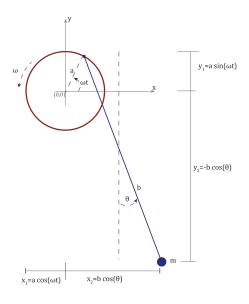


Figure 1: Diagram of setup

III. Pre-Analysis

1. The rim is mass-less, so all energy the terms are only for the pendulum mass

2. The pendulum, however, has both linear and angular momentum

$$T = 1/2mv^2 + 1/2I\omega^2 \tag{1}$$

- 3. A change of coordinates from Cartesian to polar is probably the most efficient way to proceed.
- 4. The plan is to get a differential equation, or two, in just θ and $\dot{\theta}$.
- 5. Using python code we can run a 4th order Runge-Kutta numerical analysis and plot the pendulum's position x(t) and y(t).
- 6. I'm going to need some initial values for this

IV. Equations

$$x = a\cos(\omega t) + b\sin\theta \qquad \dot{x} = -a\omega\sin(\omega t) + b\sin(\theta)\dot{\theta}$$

$$y = a\sin(\omega t) - b\cos\theta \qquad \dot{y} = a\omega\cos(\omega t) + b\sin(\theta)\dot{\theta}$$
(2)

$$\mathbf{T} = \frac{1}{2}m\left(a^{2}\omega^{2} + b^{2}\dot{\theta}^{2} + 2ab\omega\dot{\theta}\left[\sin\theta\cos\omega t - \sin\omega t\cos\theta\right]\right)$$
$$= \frac{1}{2}m\left(m^{2}\omega^{2} + b^{2}\dot{\theta}^{2} + 2ab\omega\dot{\theta}\sin\left(\theta - \omega t\right)\right)$$
(3)

$$\mathbf{U} = mg\left(a\sin\omega t - b\cos\theta\right) \tag{4}$$

$$\mathcal{L} = \mathbf{T} - \mathbf{U}$$

$$= \frac{1}{2} m \left(m^2 \omega^2 + b^2 \dot{\theta}^2 + 2ab\omega \dot{\theta} \sin \left(\theta - \omega t \right) \right) - mg \left(a \sin \omega t - b \cos \theta \right)$$
(5)

V. Code outline

REFERENCES

- [1] Rovelli, Carlo, et al. *Reality Is Not What It Seems: the Journey to Quantum Gravity.* Riverhead Books, 2018.
- [2] "Physics and Astronomy Western University." Western University Physics And Astronomy, www.physics.uwo.ca/.
- [3] "Chapter 7: Hamilton's Principle." Classical Dynamics of Particles and Systems, by Stephen T. Thornton and Jerry B. Marion, Brooks/Cole, 2004.