

## Section 11.4 Cross Product

### MATH211 Calculus III

Instructor: Ben Huang



DEPARTMENT OF  
COMPUTING, MATHEMATICS  
AND PHYSICS

# Knowledge Checks

## Section 11.4

B.H.

Suppose  $\mathbf{u} = u_1\mathbf{i} + u_2\mathbf{j} + u_3\mathbf{k}$ ,  $\mathbf{v} = v_1\mathbf{i} + v_2\mathbf{j} + v_3\mathbf{k}$ . What is the cross product  $\mathbf{u} \times \mathbf{v}$ ?

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$$\mathbf{u} \times \mathbf{v} = (u_2 v_3 - u_3 v_2)\mathbf{i} + (u_3 v_1 - u_1 v_3)\mathbf{j} + (u_1 v_2 - u_2 v_1)\mathbf{k}.$$

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What is the special relation between the directions of  $\mathbf{u} \times \mathbf{v}$  and  $\mathbf{u}$  or  $\mathbf{v}$ ?

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Suppose  $\mathbf{u} = u_1\mathbf{i} + u_2\mathbf{j} + u_3\mathbf{k}$ ,  $\mathbf{v} = v_1\mathbf{i} + v_2\mathbf{j} + v_3\mathbf{k}$ . What is the cross product  $\mathbf{u} \times \mathbf{v}$ ?

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What is the special relation between the directions of  $\mathbf{u} \times \mathbf{v}$  and  $\mathbf{u}$  or  $\mathbf{v}$ ?

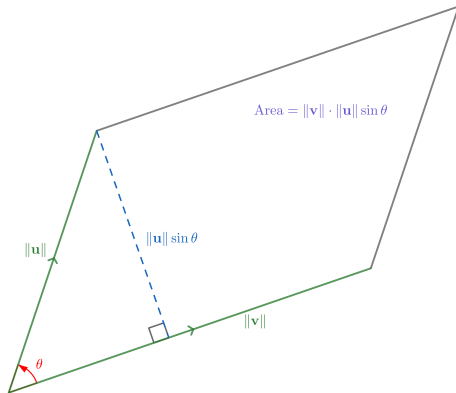
$\mathbf{u} \times \mathbf{v}$  is orthogonal to both  $\mathbf{u}$  and  $\mathbf{v}$ .

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How is  $\|\mathbf{u} \times \mathbf{v}\|$  related to  $\|\mathbf{u}\|$ ,  $\|\mathbf{v}\|$ , and  $\theta$ ?

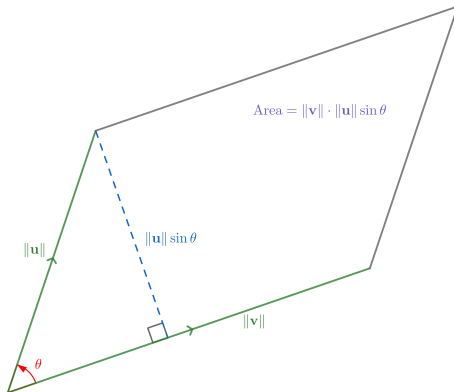


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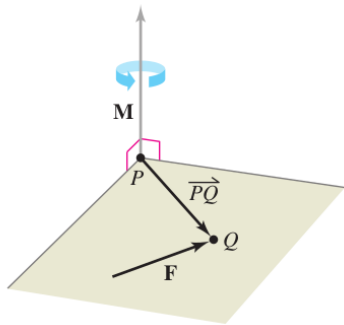
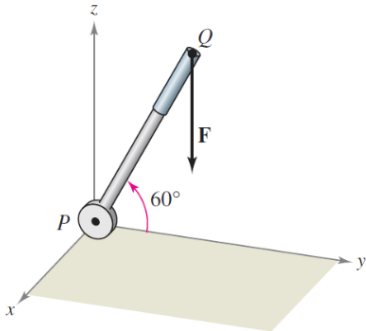
$$\|\mathbf{u} \times \mathbf{v}\| = \|\mathbf{u}\| \|\mathbf{v}\| \sin \theta = \text{the area of the parallelogram.}$$

# Knowledge Checks

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What is the torque?



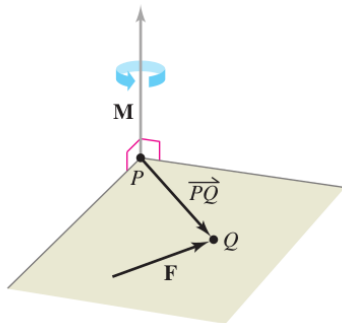
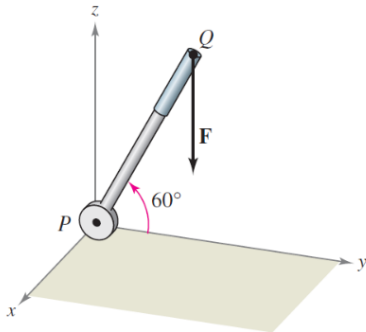


# Knowledge Checks

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What is the torque?



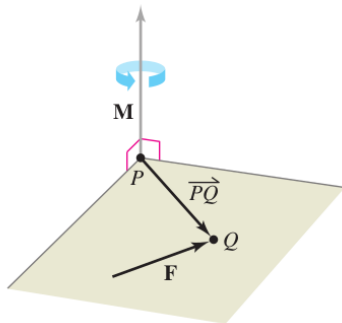
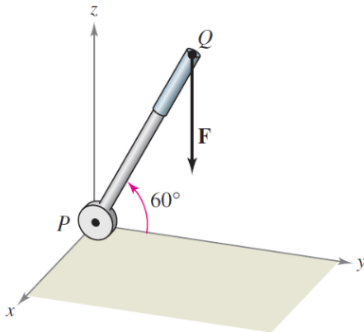
$$\mathbf{M} \text{ (or } \tau) = \overrightarrow{PQ} \times \mathbf{F}.$$

# Knowledge Checks

## Section 11.4

B.H.

What is the torque?



$$\mathbf{M} \text{ (or } \tau) = \vec{PQ} \times \mathbf{F}.$$

**Remark: The torque is a vector, NOT a number.**

# Knowledge Check

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B.H.

**Determinants:**

$$\begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix} =$$

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**Determinants:**

$$\begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix} = u_1 v_2 - u_2 v_1.$$

$$\begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix} =$$

# Knowledge Check

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**Determinants:**

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$$\begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix} = u_1 \begin{vmatrix} v_2 & v_3 \\ w_2 & w_3 \end{vmatrix} - u_2 \begin{vmatrix} v_1 & v_3 \\ w_1 & w_3 \end{vmatrix} + u_3 \begin{vmatrix} v_1 & v_2 \\ w_1 & w_2 \end{vmatrix}$$

$$=$$

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**Determinants:**

$$\begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix} = u_1 v_2 - u_2 v_1.$$

$$\begin{aligned} \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix} &= u_1 \begin{vmatrix} v_2 & v_3 \\ w_2 & w_3 \end{vmatrix} - u_2 \begin{vmatrix} v_1 & v_3 \\ w_1 & w_3 \end{vmatrix} + u_3 \begin{vmatrix} v_1 & v_2 \\ w_1 & w_2 \end{vmatrix} \\ &= u_1(v_2 w_3 - v_3 w_2) - u_2(v_1 w_3 - v_3 w_1) \\ &\quad + u_3(v_1 w_2 - v_2 w_1). \end{aligned}$$

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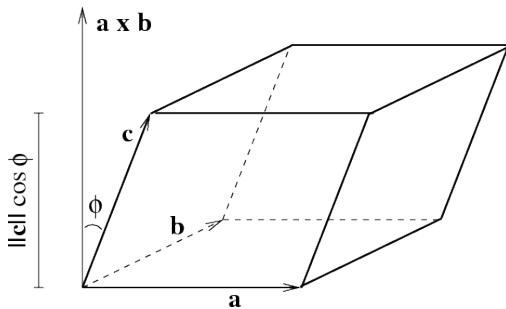
Let  $\mathbf{u} = u_1\mathbf{i} + u_2\mathbf{j} + u_3\mathbf{k}$  and  $\mathbf{v} = v_1\mathbf{i} + v_2\mathbf{j} + v_3\mathbf{k}$  be vectors in space.

$$\begin{aligned}\mathbf{u} \times \mathbf{v} &:= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} = \begin{vmatrix} u_2 & u_3 \\ v_2 & v_3 \end{vmatrix} \mathbf{i} - \begin{vmatrix} u_1 & u_3 \\ v_1 & v_3 \end{vmatrix} \mathbf{j} + \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix} \mathbf{k} \\ &= (u_2 v_3 - u_3 v_2)\mathbf{i} - (u_1 v_3 - u_3 v_1)\mathbf{j} + (u_1 v_2 - u_2 v_1)\mathbf{k}.\end{aligned}$$

# Triple scalar product

## Section 11.4

B.H.



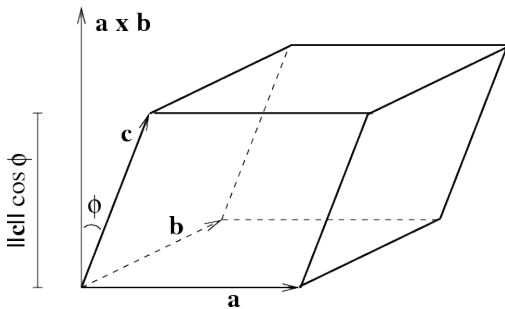
Volume(parallelepiped)



# Triple scalar product

## Section 11.4

B.H.

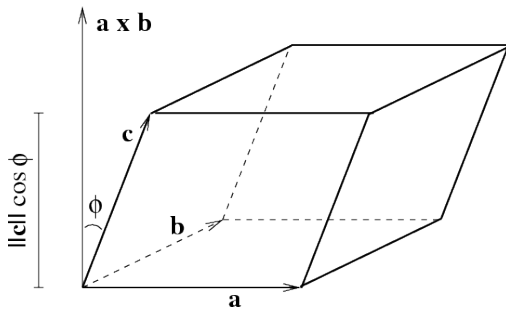


$$\text{Volume}(\text{parallelepiped}) = \| \mathbf{a} \times \mathbf{b} \| \| \mathbf{c} \| \cos \phi$$

# Triple scalar product

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B.H.

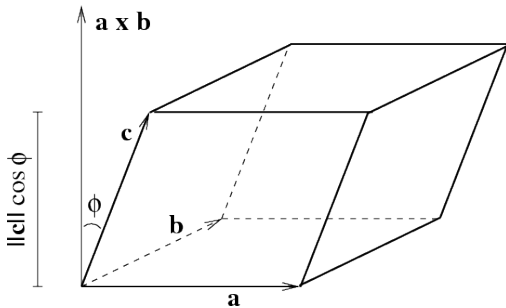


$$\text{Volume}(\text{parallelepiped}) = \|\mathbf{a} \times \mathbf{b}\| \|\mathbf{c}\| \cos \phi = |\mathbf{c} \cdot (\mathbf{a} \times \mathbf{b})|$$

# Triple scalar product

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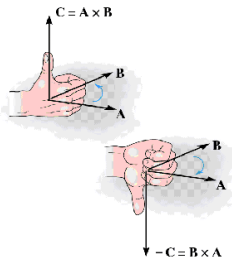
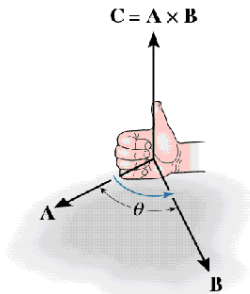
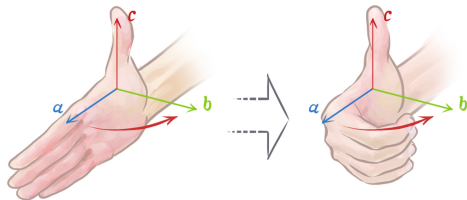


$$\begin{aligned} \text{Volume}(\text{parallelepiped}) &= \|\mathbf{a} \times \mathbf{b}\| \|\mathbf{c}\| \cos \phi = |\mathbf{c} \cdot (\mathbf{a} \times \mathbf{b})| \\ &= |c_1(a_2b_3 - a_3b_2) - c_2(a_1b_3 - a_3b_1) + c_3(a_1b_2 - a_2b_1)| \\ &= \text{absolute value} \left( \begin{vmatrix} c_1 & c_2 & c_3 \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} \right) \end{aligned}$$

# The Right Hand Rule

## Section 11.4

B.H.



# The Cross Product of the Standard Unit Vectors

## Section 11.4

B.H.

**Exercise.** According to the right hand rule and the magnitude formula, find

- $\mathbf{i} \times \mathbf{j}$ .
- $\mathbf{j} \times \mathbf{i}$ .
- $\mathbf{j} \times \mathbf{k}$ .
- $\mathbf{k} \times \mathbf{j}$ .
- $\mathbf{k} \times \mathbf{i}$ .
- $\mathbf{i} \times \mathbf{k}$ .
- $\mathbf{i} \times \mathbf{i}$ .
- $\mathbf{j} \times \mathbf{j}$ .
- $\mathbf{k} \times \mathbf{k}$ .

# The Cross Product of the Standard Unit Vectors

## Section 11.4

B.H.

**Exercise.** According to the right hand rule and the magnitude formula, find

- $\mathbf{i} \times \mathbf{j} = \mathbf{k}.$
- $\mathbf{j} \times \mathbf{i} = -\mathbf{k}.$
- $\mathbf{j} \times \mathbf{k} = \mathbf{i}.$
- $\mathbf{k} \times \mathbf{j} = -\mathbf{i}.$
- $\mathbf{k} \times \mathbf{i} = \mathbf{j}.$
- $\mathbf{i} \times \mathbf{k} = -\mathbf{j}.$
- $\mathbf{i} \times \mathbf{i} = \mathbf{0}.$
- $\mathbf{j} \times \mathbf{j} = \mathbf{0}.$
- $\mathbf{k} \times \mathbf{k} = \mathbf{0}.$

# The General Formula

## Section 11.4

B.H.

Suppose  $\mathbf{u} = u_1\mathbf{i} + u_2\mathbf{j} + u_3\mathbf{k}$ ,  $\mathbf{v} = v_1\mathbf{i} + v_2\mathbf{j} + v_3\mathbf{k}$ . If distributivity is to be respected, we must have the following.

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$$\begin{aligned}\mathbf{u} \times \mathbf{v} &= (u_1\mathbf{i} + u_2\mathbf{j} + u_3\mathbf{k}) \times (v_1\mathbf{i} + v_2\mathbf{j} + v_3\mathbf{k}) \\ &= \end{aligned}$$



# The General Formula

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$$\begin{aligned}\mathbf{u} \times \mathbf{v} &= (u_1\mathbf{i} + u_2\mathbf{j} + u_3\mathbf{k}) \times (v_1\mathbf{i} + v_2\mathbf{j} + v_3\mathbf{k}) \\ &= u_1v_1\mathbf{i} \times \mathbf{i} + u_1v_2\mathbf{i} \times \mathbf{j} + u_1v_3\mathbf{i} \times \mathbf{k}\end{aligned}$$

# The General Formula

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Suppose  $\mathbf{u} = u_1\mathbf{i} + u_2\mathbf{j} + u_3\mathbf{k}$ ,  $\mathbf{v} = v_1\mathbf{i} + v_2\mathbf{j} + v_3\mathbf{k}$ . If distributivity is to be respected, we must have the following.

$$\begin{aligned}\mathbf{u} \times \mathbf{v} &= (u_1\mathbf{i} + u_2\mathbf{j} + u_3\mathbf{k}) \times (v_1\mathbf{i} + v_2\mathbf{j} + v_3\mathbf{k}) \\ &= u_1v_1\mathbf{i} \times \mathbf{i} + u_1v_2\mathbf{i} \times \mathbf{j} + u_1v_3\mathbf{i} \times \mathbf{k} \\ &\quad + u_2v_1\mathbf{j} \times \mathbf{i} + u_2v_2\mathbf{j} \times \mathbf{j} + u_2v_3\mathbf{j} \times \mathbf{k}\end{aligned}$$

# The General Formula

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$$\begin{aligned}\mathbf{u} \times \mathbf{v} &= (u_1\mathbf{i} + u_2\mathbf{j} + u_3\mathbf{k}) \times (v_1\mathbf{i} + v_2\mathbf{j} + v_3\mathbf{k}) \\ &= u_1v_1\mathbf{i} \times \mathbf{i} + u_1v_2\mathbf{i} \times \mathbf{j} + u_1v_3\mathbf{i} \times \mathbf{k} \\ &\quad + u_2v_1\mathbf{j} \times \mathbf{i} + u_2v_2\mathbf{j} \times \mathbf{j} + u_2v_3\mathbf{j} \times \mathbf{k} \\ &\quad + u_3v_1\mathbf{k} \times \mathbf{i} + u_3v_2\mathbf{k} \times \mathbf{j} + u_3v_3\mathbf{k} \times \mathbf{k}\end{aligned}$$

# The General Formula

## Section 11.4

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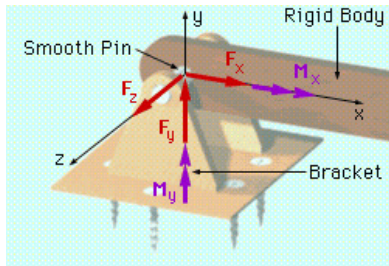
Suppose  $\mathbf{u} = u_1\mathbf{i} + u_2\mathbf{j} + u_3\mathbf{k}$ ,  $\mathbf{v} = v_1\mathbf{i} + v_2\mathbf{j} + v_3\mathbf{k}$ . If distributivity is to be respected, we must have the following.

$$\begin{aligned}\mathbf{u} \times \mathbf{v} &= (u_1\mathbf{i} + u_2\mathbf{j} + u_3\mathbf{k}) \times (v_1\mathbf{i} + v_2\mathbf{j} + v_3\mathbf{k}) \\&= u_1v_1\mathbf{i} \times \mathbf{i} + u_1v_2\mathbf{i} \times \mathbf{j} + u_1v_3\mathbf{i} \times \mathbf{k} \\&\quad + u_2v_1\mathbf{j} \times \mathbf{i} + u_2v_2\mathbf{j} \times \mathbf{j} + u_2v_3\mathbf{j} \times \mathbf{k} \\&\quad + u_3v_1\mathbf{k} \times \mathbf{i} + u_3v_2\mathbf{k} \times \mathbf{j} + u_3v_3\mathbf{k} \times \mathbf{k} \\&= (u_2v_3 - u_3v_2)\mathbf{i} + (u_3v_1 - u_1v_3)\mathbf{j} + (u_1v_2 - u_2v_1)\mathbf{k}.\end{aligned}$$

# Pin Support

## Section 11.4

B.H.



Suppose a force  $\mathbf{F} = 2\mathbf{i} - 3\mathbf{j} + \mathbf{k}$  is acting on the lever at  $(1, 1, 1)$ .

- Find the torque of  $\mathbf{F}$  about the origin.
- If the lever is stuck, find the force  $\langle F_x, F_y, F_z \rangle$  at the pin support.
- If the lever can rotate freely about pin, find the couple moment  $\langle M_x, M_y, M_z \rangle$  at the pin support.