**Testing**

Throughout the process dynamic white box testing was carried out. Due to the nature of the agile development Test Driven Development was used to ensure that at each milestone in development the program worked as expected and bugs were minimised. This was done in part by enforcing strict rules on how GitHub was used for version management. Each time a team member wanted to merge their code addition a review was requested from another team member, requiring that the other member check that the code ran, and review the code to make sure no obvious bugs were present and conventions were kept. Code could not be merged into the project until this review was given, and the merge was approved. This meant that at every point no broken code was placed into the repository.

Dynamic black box testing was carried out on the produce to ensure all parts worked as specified and the Moscow analysis criteria were met. This was done with no access to the code and it was both tested in a ‘test to pass’ and ‘test to fail’ approach to maximise the bug and problem reporting.

**Must haves**

First the finished product is tested against the requirements set for the project and the ‘must have’ section of the Moscow analysis.

Organism life cycle and genetic crossover– Organisms are created at first by the user. After that they need food to survive and die if their hunger reaches 0. They can mate producing an offspring of the same species and their individual attributes appear to crossover to produce the offspring attributes. Once the organism reaches its maximum age it dies.

Live edit of organisms – This is possible and editing the organisms results in them being affected while on screen. For instance, setting hunger to 0 slowly kills the organism and setting the speed increases the organisms moving speed around the map.

Herbivores and natural food sources – Plant material can be added to the map and organisms will consume it, increasing their own hunger and removing the plant from the world.

Simple 2D graphics – The graphics are good quality with 2D particle effects when food or an organism is placed into the world. The organisms do not overlap and occupy the same grid tile and when they die their sprite is replaced with meat.

Environmental impact – If the environment becomes too cold or hot, some organisms will start to die from the environment and if the temperature does not change then this can kill many the organisms on the map.

**Should have**

Advanced pathfinding algorithm – During testing and observance, when searching for food or a mate the organisms will avoid paths with take them over mountains or water. They will also avoid moving to the same tile as other organisms.

Carnivores and predator/prey organisms – when organisms die they are turned into a meat source which other organisms can eat.

Ability to pause, speed up and slow down simulation – This is possible and works as expected.

**Could Have**

\_ Natural disasters – There is no implementation of this in the simulation.

\_ Speciation (new species forming from heavily mutated organisms

over time) – The species do change over time and form new organisms through reproduction. However, there is no clustering of organisms to make set populations around the map.

Won't Have

\_ 3D graphics – not implemented

\_ Scale realism – not implemented.