

Bin SHI

PERSONAL DATA

PLACE AND DATE OF BIRTH: Hubei Province, China | 17th May 1994
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PROJECT EXPERIENCE

- | | |
|-------------------------|---|
| Current
SEPT. 2016 | <p>Graduate Student, Hangzhou
<i>Quantum Control and Quantum Information</i></p> <ol style="list-style-type: none">1. Quantum Optimal Control. Time scaling transformation was introduced into GRAPE to improve the theoretical fidelity of quantum states and to shorten the numerical optimal time, by which the time period was unequally divided.2. Quantum Parametric Oscillators. The harmonic oscillators were studied which were connected by a periodic or quasi-periodic coupling and interacting with a common heat bath. Parametric excitation with multiple driving terms could determine whether entanglement survived. Role of frequencies was also studied.3. Other research includes the optimal control of NMR, superconducting quantum system and NV center. The underway research includes the Quantum Zermelo Navigation, the systems with switched potential wells. |
| JUNE 2016
SEPT. 2015 | <p>Senior Project, Hangzhou
<i>Tip Control of the Flexible Beam Driven by Linear Motors</i></p> <p>Modeled the flexible beam driven by linear motors, linearized the nonlinear cantilever system by modal analysis and truncation, identified the parameters of the hardware platform by frequency-domain analysis and designed a controller (<i>PID and fuzzy control</i>). The paper was rated as excellent graduation thesis of Zhejiang University.</p> |
| AUG. 2015
JULY. 2015 | <p>Summer Intern at GOOGOLTECH, Shenzhen
<i>Singularity Analysis based on Product of Exponentials (POE)</i></p> <p>Analyzed the singularities of the industrial robot arm, built the kinematics and inverse kinematics of the robot arms in Googoltech using DH and POE respectively, on Matlab and compared the two modeling methods.</p> |
| JUNE 2015
SEPT. 2014 | <p>ZJUDancer Participator, Hangzhou
<i>Robocup Humanoid League Kidsize Soccer Competition</i></p> <p>Calibrated the exterior parameters of the soccer robots as a member of the gait group of ZJUDancer, designed new postures and checked parameters to make sure that robots could fulfill the designated movements accurately.</p> |
| JAN. 2015
SEPT. 2013 | <p>PROW Participator, Hangzhou
<i>Painting Robots On Web (PROW)</i></p> <p>Modeled the self-designed 4-dof robot arm and planned the trajectories. The project aimed at drawing a portrait of a person after taking a picture. The project was rated as excellent Student Research Training Program of Zhejiang University.</p> |

EDUCATION

- MAR. 2019 (EXPECTED) Master's Degree in CONTROL SCIENCE AND ENGINEERING
Zhejiang University, Hangzhou
Field of Research: Quantum Optimal Control | Advisor: Prof. Chao Xu
GPA: 90.77/100
- JUNE 2016 Bachelor's Degree in MECHATRONICS, **Zhejiang University**, Hangzhou
Thesis: "Tip control of the flexible beam driven by linear motor based on vibration modal analysis" | Advisor: Prof. XiaoCong ZHU
Overall GPA: 3.67/4.0 (83.88/100)
The last two years GPA: 3.86/4.0 (87.16/100)
Rank: Top 5% among the 80 students in Mechatronics Engineering

PUBLICATIONS AND WORKING PAPERS

B.Shi, C.Xu, et al. Frequency Control of Entanglement in Quantum Parametric Oscillators with Dissipation, *Journal of Physics A: Mathematical and Theoretical*, under review.
B.Shi, C.Xu, R.Wu, Time Scaling Transformation in Quantum Optimal Control Computation, *37th IEEE Chinese Control Conference*, 2018, accepted. (Finalists of IEEE Control Systems Society (CSS) Beijing Chapter Young Author Prize)

CERTIFICATES AND MAJOR HONORS

- JUNE 2018 TOEFL®: 96 (R:28; L:20; S:23; W:25)
JULY 2017 GRE®: 318 (Q:170;V:148) 97;39th percentile; AWA: 4.0/6.0 (60th percentile)
JUNE 2016 Certificate of Chu Kochen Honors Program, Zhejiang University
DEC. 2015 Scholarship for Excellence in Research and Innovation, ZJU
JULY 2015 Robocup Humanoid League Kidsize Soccer Competition **2nd place**
FEB. 2015 Mathematical Contest In Modeling (MCM) **Meritorious Winner**
SEPT. 2011 Chinese Mathematical Olympiad In Senior **Provincial 1st division**

LANGUAGES

CHINESE: Mothertongue
ENGLISH: Fluent

COMPUTER SKILLS

Basic Knowledge: PYTHON, LINUX, Adams, Ansys, Proteus
Intermediate Knowledge: MATLAB, L^AT_EX, C/C++, CAD, Solidworks, Photoshop

INTERESTS AND ACTIVITIES

- Academic Interests: Quantum control and quantum information;
Dynamic systems and control; Robotics
- Potential Interests: Artificial Intelligence; Biophysics
- Hobbies: Cinematographic and Literature Art, Swimming, Badminton
- Social Activity: Two-Star Volunteer, Zhejiang University
Vice-monitor (2013-2015)
- Teaching Assistant: Object Oriented Programming (C++), undergraduate level