# Spatially structured models of phage infection

Benjamin R. Jack

October 31, 2016

## 1 Gillespie-multi-particle model

The Gillespie-multi-particle model (GMP) [1] is a particle-based spatial stochastic simulation algorithm. Let M be a 2D lattice of dimensions  $L \times L$  patches. Each patch within the lattice has dimensions  $\lambda \times \lambda$ . Each patch can contain multiple healthy cells, infected cells, newly-replicated cells, phage particles, and goo (EPS) particles. Phage particles diffuse freely across patches. Newly-replicated cells diffuse exactly once to a patch in the Von Nuemann neighborhood. The GMP algorithm alternates between the execution of reaction and diffusion processes, where diffusion occurs at predetermined intervals of time. For each diffusing species S, the time at which a diffusion event will occur is given by

$$t_S = n_S \tau_{D_S},\tag{1}$$

where  $n_S$  is the iteration number and  $\tau_{D_S}$  is given by

$$\tau_{D_S} = \frac{\lambda^2}{4D_S} \tag{2}$$

according to a Weiner process or random walk in two dimensions, with a diffusion constant  $D_S$ .

Each diffusion event is executed locally at every patch. When a diffusion event occurs, each particle of species S is randomly distributed with equal probability among all patches in the Von Neumann neighborhood. Newly-replicated cells only undergo one diffusion event and then immediately convert to healthy cells, which do not diffuse.

The GMP algorithm proceeds as follows:

- 1. Initialize  $t_s = \min\{\tau_{D_S}\}$  for all species S, set  $t_{\rm sim} = 0$  and  $n_S = 1$  for all S.
- 2. While  $t_{\rm sim} < t_{\rm S}$ , execute reactions according to Gillespie SSA at every patch in grid. Advance  $t_{\rm sim} = t_{\rm sim} + \tau_R$ .
- 3. Diffuse species for which  $t_S = t_{sim}$ .
- 4. Increment iteration  $n_S$  for diffused species

- 5. Set  $t_S = \min\{\tau_{D_S} n_S\}$ .
- 6. Repeat steps 2–4 until  $t_{\text{sim}} = t_{\text{end}}$ .

In between each diffussion event, reactions proceed independently in each patch according to the Gillespie SSA, where  $\mu$  is the next reaction to occur in a given patch, and  $\tau_R$  is the time until that reaction occurs.

## 1.1 Reactions in the Gillespie SSA

Each patch, indepdent of the other patches, will execute the following reactions until the next diffusion event:

- Convert cells to newly-replicated cells, a first order reaction.
- Convert phage and cells to infected cells, a second order reaction.
- Convert phage and goo to just goo (i.e. kill phage), a second order reaction.
- Convert infected cells to new phage particles (i.e. lyse cell), a first order reaction.

#### 1.2 Pros/cons

Cell replication and cell lysis after infection are modeled as reactions that occur probabilisitically with a given propensity. These two events do not occur at fixed intervals. Therefore, cell replication times and lysis times are represented as reaction rate constants. Under the Gillespsie SSA, these reaction times are assumed to follow an exponential distribution. This exponential distribution may not accurately reflect lysis and replication events.

Conversely, when the number of particles in a patch is small (i.e. there may only be a few cells per patch), a Gillepsie SSA may more accurately capture the stochasticity of infection. The Gillespie SSA framework also makes it trivial to add more reactions (e.g. phage attachment/detachment). Additionally, each patch can contain multiple cells.

### 2 Heilmann model

The Heilmann model [2] simulates phage infections and diffusion events over discrete, predetermined time steps. Again, assume a  $L \times L$  grid of patches. Each patch can contain only one cell (which may be healthy or infected) and any number of phage particles. [Note: Most of the following description is taken verbatim from the supplementary materials of [2]]. Cells replicate and lyse after a fixed amount of time. At each time step, for each patch in the grid (the order of choosing patches is random), the following steps are executed:

- 1. If the patch contains an infected bacterium and the current time matches the time of lysis stored in the lytic counter, then for the next time step, the site is labeled empty (given a value of -1), and the number of phage is increased by the burst size.
- 2. If the patch contains a healthy bacterium and the current time matches the replication counter, then for the next time step, an empty patch in the Von Neumann neighborhood is randomly (according to a uniform distribution) selected and a new cell is placed there. Replication timers for both the original and daughter cell are reset. An infected cell does not replicate. If the daughter cell has nowhere to move, it dies.
- 3. If the patch contains a healthy bacterium and a non-zero number of phage  $N_0$ , then in the next time step it becomes infected with a probability

$$p_{\alpha} = 1 - \exp\left(-N_0 \alpha \left(\frac{1 - \exp(-\delta \Delta t)}{\delta}\right)\right),$$
 (3)

where  $\alpha$  is the rate of infection,  $\delta$  is the rate of phage decay, and  $\Delta t$  is the time step. The number of phage is decreased by 1, and the lytic counter is set.

- 4. Each phage in a patch decays with the probability of  $p_{\delta} = 1 e^{-\delta t}$ .
- 5. Each phage in the patch jumps to a neighboring patch (chosen randomly from the Von Neumann neighborhood) with a probability of  $p_{\lambda} = 1 e^{-\lambda t}$ .

#### 2.1 Pros/cons

Each patch can only contain a single cell. Adding new reactions is not as simple as in the GMP model.

This is model that was already previously used to study phage/bacteria spatial dynamics, whereas the GMP model has not been used for phage before (to my knowledge).

#### 2.2 Performance

The model is implemented in Python (it could be further optimized or rewritten in C). The average runtime on my laptop for a 100×100 grid for 1000 iterations (1000 minutes), using the default parameters, took 2min 34s.

#### References

[1] J. Vidal Rodrguez, Jaap A. Kaandorp, Maciej Dobrzyski, and Joke G. Blom. Spatial stochastic modelling of the phosphoenolpyruvate-dependent phosphotransferase (PTS) pathway in Escherichia coli. Bioinformatics (2006) 22 (15): 1895-1901 first published online May 26, 2006, doi:10.1093/bioinformatics/btl271

[2] Silja Heilmann, Kim Sneppen, and Sandeep Krishna. Coexistence of phage and bacteria on the boundary of self-organized refuges. PNAS 2012 109 (31) 12828-12833; published ahead of print July 17, 2012, doi:10.1073/pnas.1200771109