Parallel computing Lab 1 - Navier Stokes

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Description of the Problem

Mathematical model so-called Navier-Stokes Equations for fluid flows ocurring in Nature.

Fluids modeled on a finite square (N+2)x(N+2).

Basic structure of the solver. Three main operations:

- ► Add forces.
- Diffuse.
- ► Move.

These operations were repeated over and over during n steps in three functions:

- react
- dens_step
- vel_step

Measurements

Goal: Compare different programs with different sizes.

Squillions of cells were updated by the procedures *react*, *dens_step*, and *vel_step*.

So we decided to use the time needed to update each cell of the grid, which is calculated as:

$$ightharpoonup$$
 time $p_cell = \frac{function_time}{grid_size}$

Since these updates lead to a huge amount of loads, and cache references, another measure we used:

► cacheref
$$p_{cell_it} = \frac{References}{(grid_{size*steps})}$$

Two contradictory hypotheses under consideration.

One assures an improvement (in terms of performance) on the previous one.

A *test of hypotheses* was used to decide if an approach provides strong support to reject the previous version.

Let us define the following random variables.

- \triangleright $X_1, X_2, ..., X_n$: ns per cell needed to perform react in step i.
- $ightharpoonup Y_1, Y_2, ..., Y_n$: ns per cell needed to perform vel_step in step i.
- $V_1, W_2, ..., W_n$: ns per cell needed to perform dens_step in step i.
- $ightharpoonup Z_1, Z_2, ..., Z_n$: ns per cell needed to perform the three functions in step i.

Where $Z_i = X_i + Y_i + W_i$.

Compare two programs by means of samples $z_i's$.

N sufficiently large.

 $H_0: \mu = \mu_0$ $H_a: \mu < \mu_0$

Where μ_0 : average ns needed to update a cell.

 H_a is the claim that the time needed to update a cell decreases with the proposed approach.

- A heuristic is proposed to make the code faster.
- 2 Two versions of our program are obtained.
- The functions react, vel_step, and dens_step will be executed during N steps.
- **4** Samples $z_i's$ are computed to obtain \overline{z} .
- The observed value is normalized and used to calculate the p-value.
- **1** If the p-value is lower than our level of significance α , H_0 is rejected. Otherwise, H_0 is not rejected.
- An output is produced according to the decision given by the test.

Scripts

Every time we had an heuristic, we had to get results, test hypotheses, plot graphics, check the profiler, etc. It's hard to do manually. How can we do them without batting an eyelid?

Scripts

We needed Python scripts which do the following:

- Run different version of the program (and with different parameters) in a bunch.
- Compare two git branches and their outcomes.
- Record in directories each result given by our tests.
- ► Take results, summarize them, and produce human-readable information.

Hardware

CPU:

- ► Intel(R) Xeon(R) CPU E5-2620 v3 @ 2.40GHz
- ▶ 2 tri-core processors with hyperthreading (12 virtual)
- Freq: min 1200mhz, base 2400mhz, max 3200mhz
- ► L1d 64 sets, 8-way, 32KiB * 12 = 384KiB
- ▶ L1i 64 sets, 8-way, 32KiB * 12 = 384KiB
- ► L2 200 sets, 8-way, 256KiB * 12 = 3MiB
- ▶ L3 12Ki sets, 20-way, shared, 15MiB * 2 = 30MiB

Memory:

- ► Capacity: 126GiB
- ► Channels: 4
- ► Speed: 1600/1866Mhz
- ► Max BW: 59GB/s

Hardware

Compiler:

▶ gcc (Debian 9.2.1-31) 9.2.1 20200306

Uname:

- Linux zx81 5.4.0-4-amd64 #1 SMP Debian 5.4.19-1 (2020-02-13) x86_64 GNU/Linux
- Linux jupiterace 5.4.0-4-amd64 #1 SMP Debian 5.4.19-1 (2020-02-13) x86_64 GNU/Linux

Baseline: The basecode compiled with -O3

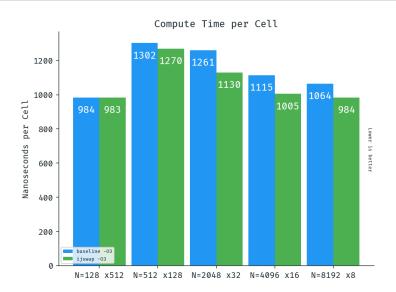
Heuristic 1: i, j swap.

```
|\#define\ IX(i,j)\ ((i)+(N+2)*(j))|
// Cache unfriendly
void expensive_loop ( int N, int *grid){
   for ( i=1 ; i<=N ; i++ ) {</pre>
        for (j=1; j \le N; j++) {
                   // Do something with grid[IX(i, j)]
#define IX(i,j) ((j)+(N+2)*(i))
// Cache friendly
void expensive_loop ( int N, int *grid){
   for ( i=1 ; i<=N ; i++ ) {</pre>
```

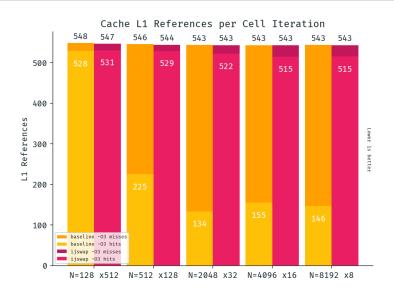
// Do something with grid[IX(i, j)]

for $(j=1; j \le N; j++)$ {

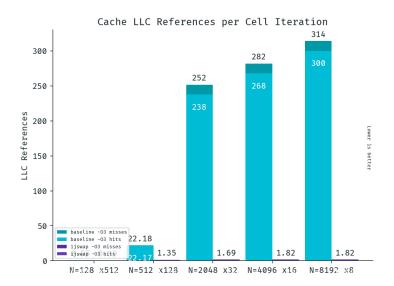
Results



Perf results



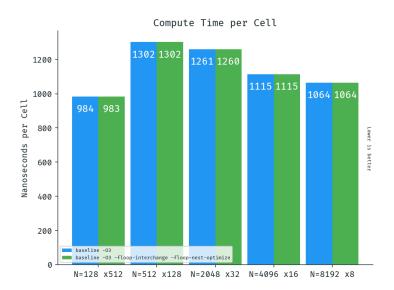
Perf Results



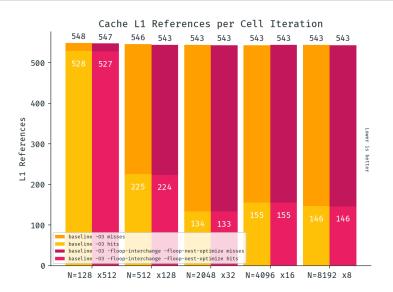
Is there a flag that interchange the loops for us? Can we do loop blocking?

 $\hbox{-floop-nest-optimize} => \hbox{-floop-block}$

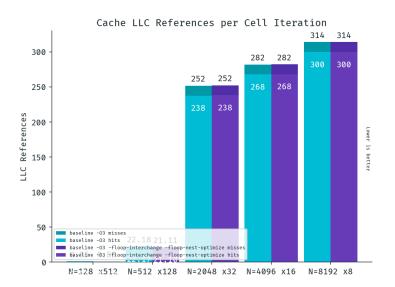
Results



Perf results



Perf Results

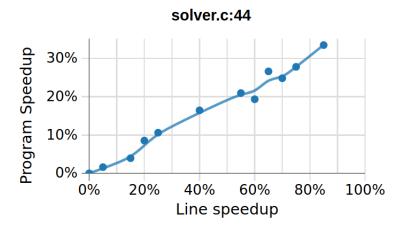


```
float square(float* x, int n) {
  // n = 32767;
float sum = 0;
for (int i = 0; i < n; i++)
  for (int j = 0; j < n; j++)
      sum += x[j * n + i];
return sum;</pre>
```

Conclusion: i, j swap in the function IX(i,j) is the best approach so far.

And now what? There is no an evident improvement that we can do.

The use of *cozprofiler* and *perf* lead to our second heuristic.



Profilers

Profilers

```
lea
                 0x0(,%rcx,4),%r8
          lea
                 (%r10,%rax,1),%ecx
          movss (%rsi,%r12,4),%xmm2
                 -0x1(%rax),%ecx
6
          lea
          lea
                 0x1(%rax),%ecx
                %rcx,%rax
          mov
                %ecx,%r8d
          mov
          sub
                %r11d,%r8d
                %r8d,%edi
          cmp
                 f0
4
          jae
```

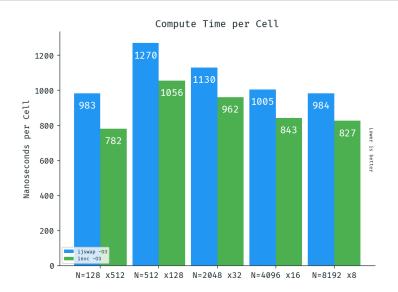
Heuristic 2: Change c for the multiplicative inverse. (invc) Procedure *lin solve*.

```
// Expensive divition repeated inside of the loop.
for k=1 to 20 do
   for i=1 to n do
        for j=1 to n do
            x[IX(i, j)] = big_operation / c;
        od
   od
od
// Cheaper multiplication.
inv_c = 1 / c;
for k=1 to 20 do
    for i=1 to n do
        for j=1 to n do
            x[IX(i, j)] = big_operation * inv_c;
        od
    od
od
```

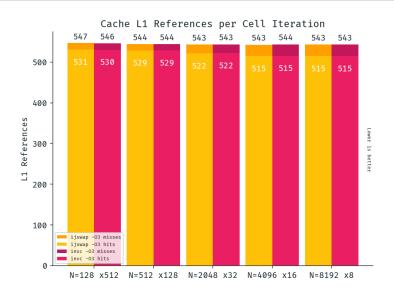
Results

| 1450 | 100: | | (%rdx,%rax,1),%r12d |
|------|------|-------|---------------------|
| 5 | | lea | 0x0(,%rcx,4),%r8 |
| 1 | | lea | (%r10,%rax,1),%ecx |
| 7 | | movss | (%rsi,%r12,4),%xmm1 |
| 1538 | | | (%rsi,%rcx,4),%xmm1 |
| 8 | | lea | -0x1(%rax),%ecx |
| 8504 | | | (%rsi,%rcx,4),%xmm1 |
| 31 | | lea | 0x1(%rax),%ecx |
| 3 | | mov | %rcx,%rax |
| 5693 | | | (%rsi,%rcx,4),%xmm1 |
| 6143 | | | %xmm0,%xmm1 |
| 5751 | | | (%rbx,%r8,1),%xmm1 |
| 6157 | | | %xmm2,%xmm1 |
| 1511 | | | %xmm1,(%rsi,%r8,1) |
| 4 | | mov | %ecx,%r8d |
| | | sub | %r11d,%r8d |
| | | cmp | %r8d,%edi |
| 1 | | jae | 100 |
| | | | |

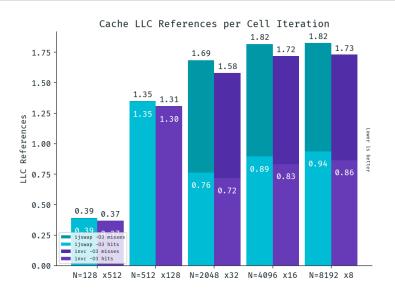
Results



Perf results

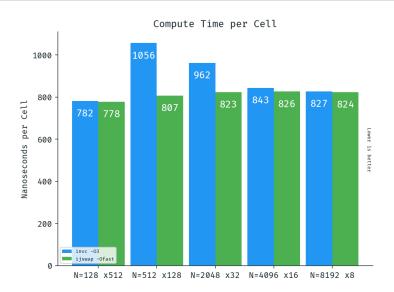


Perf Results

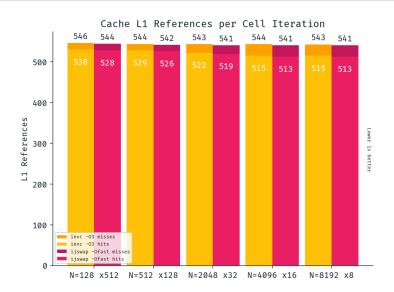


This is done by the compiler with -Ofast!

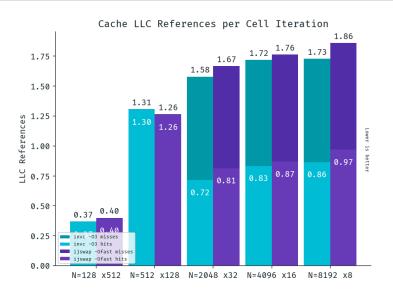
- ▶ Does -Ofast improve our heuristic?
- ► Can our approach avoid the use of dangerous flags?



Perf results

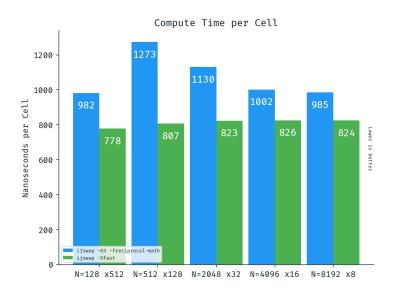


Perf Results

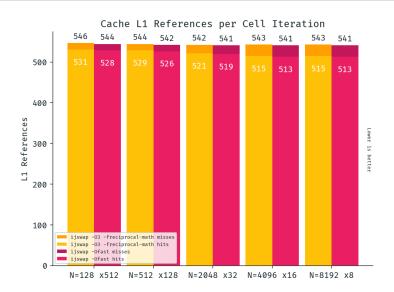


Every step the performance tend to decrease with -O3 up to certain threshold.

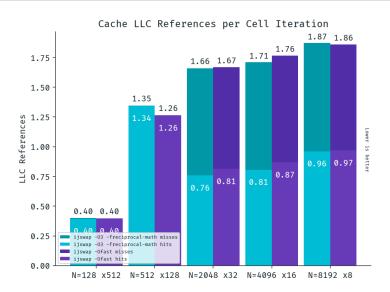
Can we use -freciprocal-math instead of -Ofast?



Perf results



Perf Results

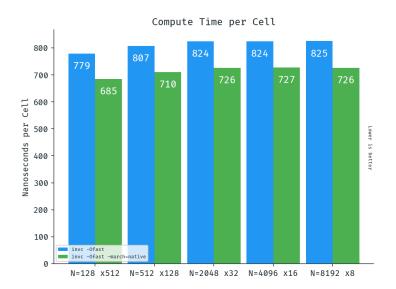


Conclusion:

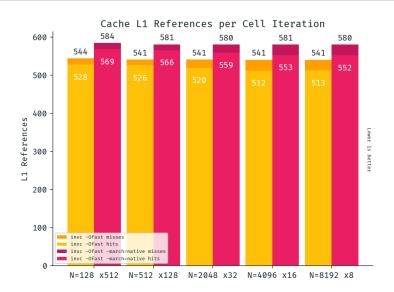
- ▶ Ofast increases the performance in comparison with -O3. Unfortunately we could not trace the reason.
- ► Therefore, we could not trace the flag of Ofast which does the optimization.
- ► Know your flags!

Therefore, we decided to try many flags:

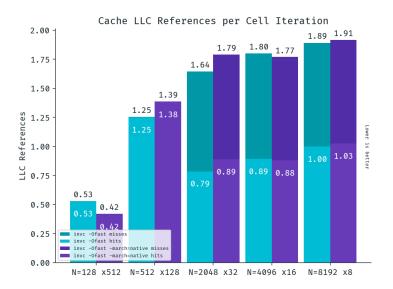
- -Ofast
- -Ofast -march=native
- Ofast -march=native -funroll-loops
- Ofast -march=native -funroll-loops -floop-nest-optimize
- Ofast -march=native -funroll-loops -floop-nest-optimize -flto



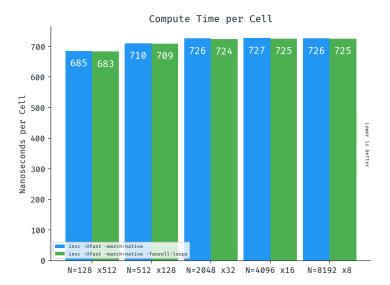
Perf results



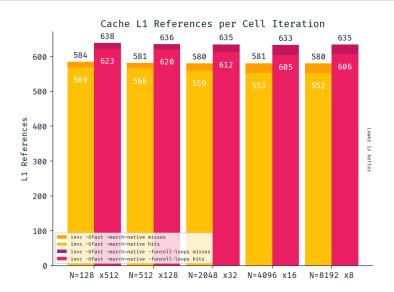
Perf Results



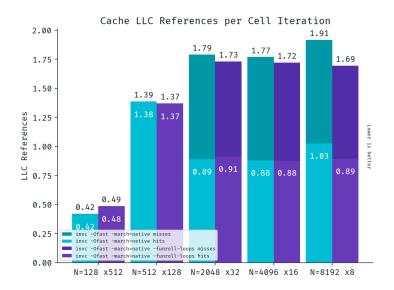
-march=native increases the performance by itself.



Perf Results

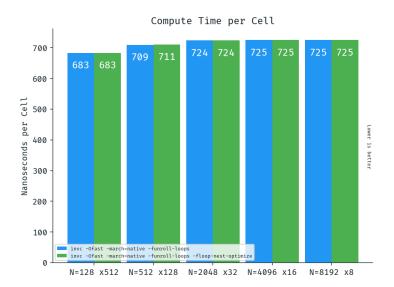


Perf results

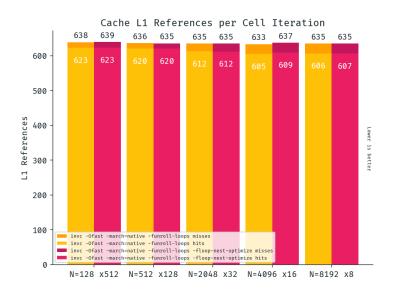


No improvement with -funroll-loops.

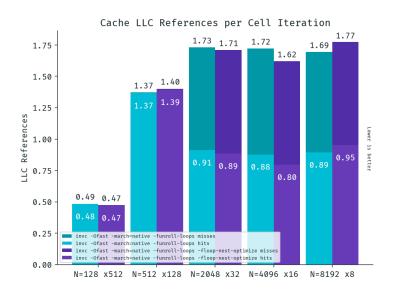
```
i,j swap (Flags=-Ofast -march=native -funroll-loops)
vs
invc (Flags= -Ofast -march=native -funroll-loops
-floop-nest-optimize)
```



Perf Results

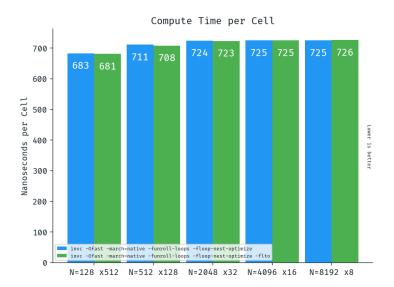


Perf results

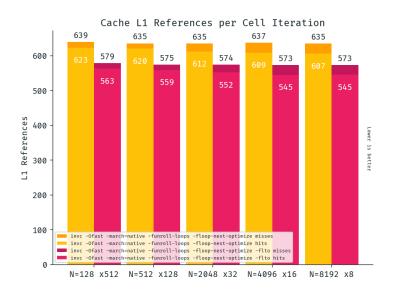


No improvement with -floop-nest-optimize. Remember that -floop-nest-optimize \Rightarrow -floop-block

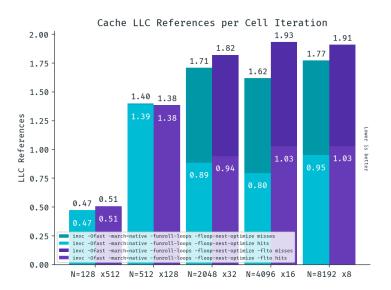
```
i,j swap (Flags=-Ofast -march=native -funroll-loops -floop-nest-optimize) vs invc (Flags= -Ofast -march=native -funroll-loops -floop-nest-optimize -flto)
```



Perf Results



Perf results



It seems not working! But why? These results lead to our third heuristic.

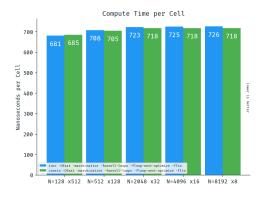
Heuristic 3: Declare N, which is the size of the grid, as const.

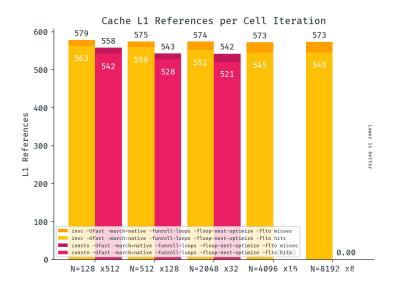
const int N = 2048;

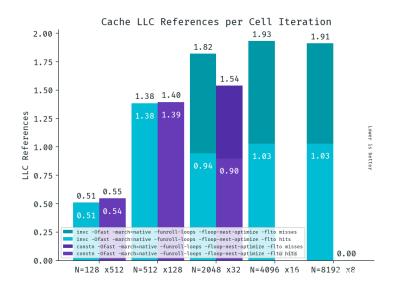
```
invc(Flags= -Ofast -march=native -funroll-loops
-floop-nest-optimize -flto)
vs
constn (Flags= -Ofast -march=native -funroll-loops
-floop-nest-optimize -flto)
```

Results - i7 7700HQ

Mateo's results





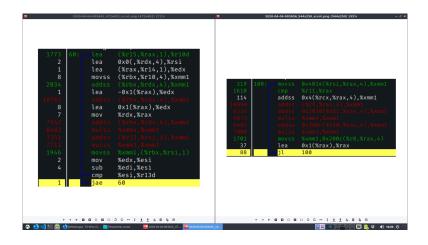


Huge differences. Why?

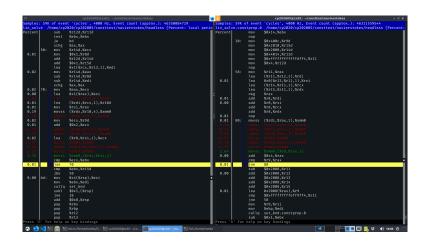
Heuristics

If we take a look at the assembler with perf.

Results - Left: no constn, Right: constn - i7 7700HQ



Results - Left: no constn, Right: constn - zx81



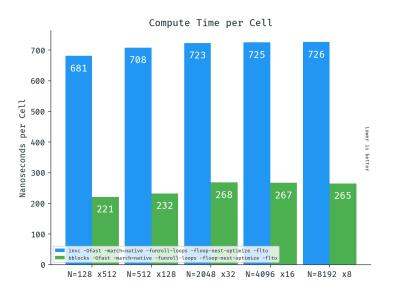
Heuristics

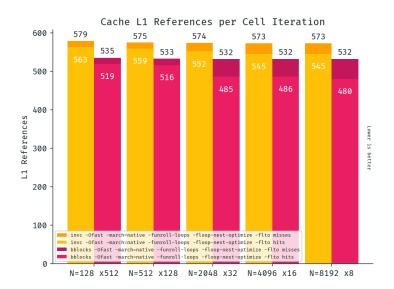
More on lin solve:

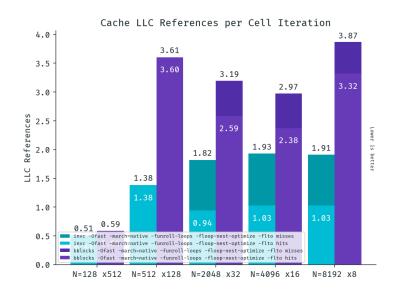
- ► Gauss-Seidel? $x_{i,j}^{n+1} = x_{i,j}^0 + \frac{a(x_{i-1,j}^{n+1} + x_{i,j-1}^{n+1} + x_{i+1,j}^n + x_{i,j+1}^n)}{1+4a}$
- ► Jacobi?
- Ad-hoc idea

Heuristic 4: Basic blocking

```
for (unsigned int k = 0; k < 20; k++)
   for (int ti = 0; ti < N - 2; ti += tile width) {
```



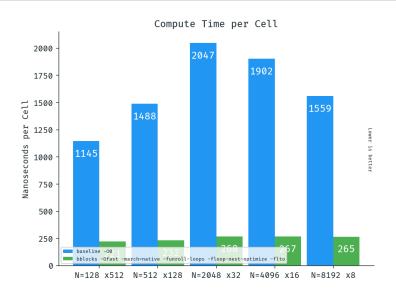


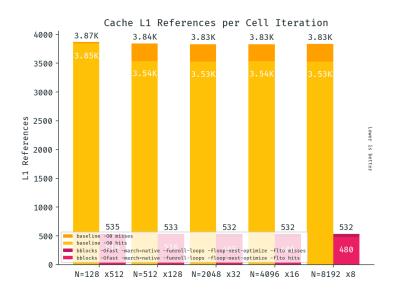


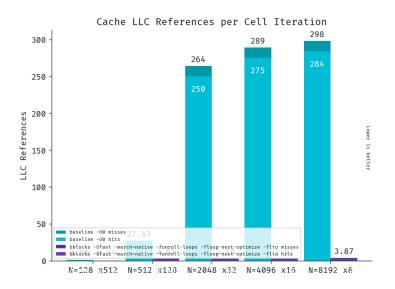
Heuristics

How much have we improved?

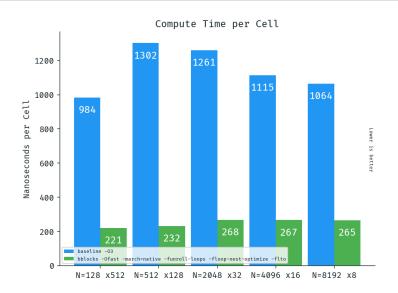
```
\label{eq:baseline} Baseline \ (Flags - O0) \\ vs \\ bblock \ (Flags = -Ofast\_-march=native\_-funroll-loops\_-\\ floop-nest-optimize\_-flto)
```

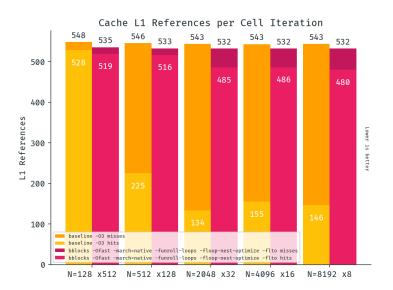


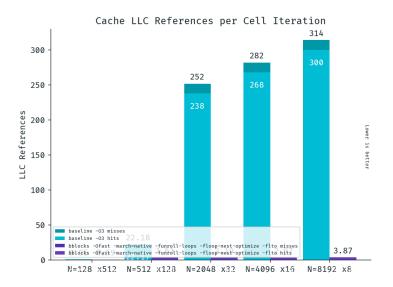




```
Baseline (Flags -O3)
vs
bblock (Flags = -Ofast_-march=native_-funroll-loops_-
floop-nest-optimize_-flto)
```







Things that never were

- ▶ llvm-mca
- autofdo
- cachegrind
- ▶ flto crashes
- ► Array of Structures