# Lab02: Review of Optimization with Newton's Method

# Newton's Method for root finding

One example of a root finding algorithm

▶ Given f(x) and an initial guess for the root,  $x_0$ , a better approximation for the root is:

$$x_1 = x_0 - \frac{f(x_0)}{f'(x_0)}$$

More generally, iterate until convergence:

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

Note: f needs to be differentiable and  $x_0$  needs to be close to a true root. Newton's Method can fail if initial point is chosen poorly.

# When to stop iterating?

One decision rule you could use. Stop if

$$|x_{n+1}-x_n|<\epsilon$$

### An example

Write our the first 3 iterations of Newton's method for  $f(x) = x^2 + 5x - 10$  with initial guess  $x_0 = 4$ 

#### **Answer**

Need derivative: 
$$f'(x) = 2x + 5$$
  
So,  
 $x_1 = 4 - (26/13) = 2$   
 $x_2 = 2 - (4/9) = 1.555$   
 $x_3 = 1.555 - (.193/8.11) = 1.5312$ 

#### Let's draw it out

One iteration with iterate  $x_n$ :

- 1. Find  $f(x_n)$
- 2. Draw tangent
- 3.  $x_{n+1}$  is where tangent intersects x-axis

## Newton's Method for optimization

Convert our root-finding problem into an *optimization problem* by considering the *derivative* of a one dimentional function f'(x).

- ▶ Basic idea: find where f'(x) = 0 to identify stationary point (e.g., minima & maxima).
- Our updates are now of the form:

$$x_{n+1} = x_n - \frac{f'(x_n)}{f''(x_n)}$$

Should we draw this out?

Note f must be twice differentiable.

## What we really care about: the multivariable case

For maximum likelihood estimation, we need to find the roots of the first derivative of the loglikelihood  $\ell(\theta)$ .

$$\theta_{n+1} = \theta_n - \frac{\ell'(\theta_n)}{\ell''(\theta_n)}$$

- ▶ Usually for us,  $\theta$  is a vector. For example,  $\theta = (\beta_0, ..., \beta_p)$ .
- ▶ In that case, we need to consider the *gradient* vector and the *Hessian* matrix of second partial derivatives:

$$\theta_{n+1} = \theta_n - [\nabla^2 f(\theta_n)]^{-1} \nabla f(\theta_n)$$

#### Disclaimer

A major downside to Newton's method is you have to invert a matrix. (Note for your homework it is fine to use the solve function in R.)

Other optimization methods like Fisher Scoring get around this, but that's beyond today's lab.

#### How would do this?

Consider  $X_1, ..., X_n \stackrel{\text{iid}}{\sim} Gamma(\alpha, \beta)$ 

$$f(x; \alpha, \beta) = \frac{\beta^{\alpha}}{\Gamma(\alpha)} x^{\alpha - 1} e^{-\beta x}$$

▶ Let's assume  $\alpha = 1$ , so our concern is  $\beta$ :

$$f(x; \alpha = 1, \beta) = \beta e^{-\beta x}$$

▶ Our goal is to find the MLE of  $\beta$  using Newton's Method.

# Derive the update

$$L(\beta) = \beta^n e^{-\beta \sum_{i=1}^n x_i}$$

$$\ell(\beta) = n \log(\beta) - \beta \sum_{i=1}^n x_i$$

$$\ell'(\beta) = \frac{n}{\beta} - \sum_{i=1}^n x_i$$

$$\ell''(\beta) = -\frac{n}{\beta^2}$$

#### Code it up

```
l_p <- function(beta, X) # what goes here??</pre>
1_pp <- function(beta, X) # what goes here??</pre>
newtons_method <- function(beta, X, eps){</pre>
    abs_change <- 2*eps #initial value to start while loop
    beta_old <- beta #initial value to start while loop
    # continue while absolute change in interates is still large
    while(abs_change > eps){
        # update
        beta <- # what goes here??
        # calculate change
        abs_change <- abs(beta - beta_old)
        # prep next iteration
        beta old <- beta
        # let's check out our successive iterates
        print(beta)
    return(beta)
```

#### Check our code with simulated data

```
X <- rgamma(n = 100, shape = 1, rate = 3)
newtons_method(beta = 1, X = X, eps = .001)</pre>
```