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DEPARTMENT OF COMPUTER SCIENCE
NEURAL NETWORKS

Exercise 5

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1 Read Chapter 3.1-3.5 from Haykin's book; summarize or sketch your insights in mind-map or an outline or a summary.

- Rosenblatt proved that given linearly separable data, a perceptron is proven to converge.
- Least mean square algorithm is the backbone of linear adaptive filters
- Adaptive filtering

  m dimensional input produces scalar output

  data equally distributed

  data can be spread over space (snapshot) or over time (uniformly spaced in time)

  Filtering process produces the output and error signals

  Adaptive process involves adjustments based on errors

  Error correction is an optimization problem
- Unconstrained optimization techniques

  Optimal solution is gradient of cost function equal to 0
- Steepest descent

  converges slowly

  size of eta produces overdamped response when small, under when large
- Newton method

  needs to be twice continuously differentiable wrt w to form hessian

  converges quickly and generally not subject to underdamped behavior of steepest descent

  Needs to be positive definite matrix, however there is no gaurantee of that.

- Gauss Newton method

  Only requires jacobian of the error vector as opposed to hessian of cost function

  Jacobian product must be non singular

- Least mean squares

  Inverse of the learning rate eta is the

  weight vector traverses random trajectory in contrast with steepest descent

  The stability of the system is determined by choosing an appropriate eta for x

  Model independent, therefore robust

  Needs approx 10x the dimensionality iterations to converge

2 (3.1)

2.1 (a)

2.2 (b)

3 (3.2)

4 (3.4)

5 (3.8)

5.1 (a)

5.2 (b)

5.3 (c)