# Master Thesis Presentation

Comparison of Disparity Algorithms for Stereoscopic Videos

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# Motivation

## Applications

- Kinect
- Sunlight
- not good, medical surgery, 3DTV

# Disparity Algorithms

## Foundations

- bit of epipolar geometry
- constraints

## Classification

- local and global ones
- explain basics

# Implementation

- explain what was implemented and why

# Evaluation

## Overview

- datasets (shortly)
- what was evaluated
- results

# Conclusion

# Outlook

- conclusion
- short future outlook

**Questions?**