#### **Master Thesis Presentation**

Comparison of Disparity Algorithms for Stereoscopic Videos

Ben John

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University of Mannheim

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### Motivation

#### **Applications**

- Kinect
- Sunlight
- not good, medical surgery, 3DTV

## Disparity Algorithms

#### **Foundations**

- bit of epipolar geometry
- constraints

#### Classification

- local and global ones
- explain basics

**Related Work** 

#### **ELAS**

ullet explain basic ELAS approach

## Implementation

#### **Overview**

explain what was implemented and why

# Evaluation \_\_\_\_\_

#### **Overview**

- datasets (shortly)
- what was evaluated
- results

## Conclusion

#### Outlook

- conclusion
- short future outlook



#### References I