Comparison of Linear and Circular Products after PolConvert

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Abstract

The VGOS data are collected with the use of linearly polarized receivers. However, circular polarization has a number of benefits. The PolConvert software allows VGOS data conversion from linear to circular polarization. In this study we do a statistical comparison of the pseudo-Stokes data before and after the conversion in order to characterize the errors PolConvert introduces.

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1 Parameter Temporal Variations Before and After PolConvert

Converting linear polarization of the source data to the circular polarization with the PolConvert software introduces changes into its properties. Here we consider the changes in multi-band delays (MBD), single-band delays (SBD), and signal-to-noise ratios (SNR) for the pseudo-Stokes polarization products, of which we only select the pseudo-Stokes I parameters as functions of time, t. From the original, linearly polarized data set we read I, which we denote Lin I(t). PolConvert is applied to the original data set and generates another data set with circular polarization, from which we read I parameters denoted as Cir I(t). Of course, the data are presented in the discrete, numerical format, so instead of the continuous time, t, integer indices are used, like $k = \overline{1..N}$,

where N is the number of data points in the sample. The following Figures show temporal variations of the Lin I[k] and Cir I[k] parameters during the experiment before and after PolConvert, one graph for each baseline:

MBD variations in Fig. 1;

SBD variations in Fig. 2;

SNR variations in Fig. 3.

One can see that most of the graphs after PolConvert, Cir I[k], are significantly shifted in values with respect to Lin I[k]. However, subtracting means of each curve makes the differences far less significant:

$$\operatorname{Lin} \ I[k] = \operatorname{Lin} \ I[k] - \operatorname{mean}(\operatorname{Lin} \ I[k]) \tag{1}$$

$$Cir I[k] = Cir I[k] - mean(Cir I[k])$$
(2)

In order to compare Lin I[k] with Cir I[k], the residual (res[k]) is computed as their difference:

$$res[k] = Lin I[k] - Cir I[k]$$
(3)

The graphs of residuals with the means subtracted are shown in the following Figures:

MBD residual variations in Fig. 4;

SBD residual variations in Fig. 5;

SNR residual variations in Fig. 6.

To assess the similarity or even identity of Lin I[k] and Cir I[k], the following parameters are computed:

- Pearson correlation coefficient r_{corr} ;
- Root Mean Square Error, RMSE;

Since Lin I[k] and Cir I[k] already have their means subtracted, the correlation formula is simplified:

$$r_{corr} = \frac{\sum \text{Lin I}[k] \cdot \text{Cir I}[k]}{\sqrt{\sum \text{Lin I}[k]^2 \cdot \text{Cir I}[k]^2}}$$
(4)

The root mean square error, RMSE, in our case is actually the standard deviation of the residual, σ :

$$RMSE = \sqrt{\frac{1}{N} \sum res[k]^2}$$
 (5)

Lower RMSE indicates a better fit between the curves. However, RMSE is not an "absolute" indicator of the curves' proximity. The correlation coefficient, though, has its upper limit, unity, and if r_{corr} is very close to unity, the curves are almost identical, save their co0nstant bias. MBD and SNR demonstrate excellent correlations between Lin–I and Cir–I.

2 Parameter residual Statistics Before and After PolConvert

While in the previous Section MBD, SBD, and SNR pseudo-Stokes I parameter data were treated as functions of time, here we do their statistical study. In order to estimate the errors introduced by PolConvert, histograms of the parameter residuals (after the mean subtraction, see Eqs. (1) and (2)) are plotted. Below are the histograms for all of the baselines:

```
MBD residual histogram for all of the baselines in Fig. 7; SBD residual histogram for all of the baselines in Fig. 8; SNR residual histogram for all of the baselines in Fig. 9.
```

Note that the means of the residuals are very close to zero. In order to evaluate the significance of the error we attempted to use the Pearson's chi-squared test comparing the histograms to the normal distributions. Initially, all the histograms had 21 bins. The left-tail and right-tail bins with sparse data (frequencies smaller than 5) were grouped and the test used fewer number of bins (printed in each plot).

However, this method did not work: the residuals are grouped around their means substantially denser than the normal distributions with the same standard deviations. Calculated values of the histogram chi-squares are many times greater than the critical chi-square values for the p-values less than or equal to 0.05 (printed in each of the histogram plots).

We have used another method. Since the residuals are mostly within $\pm \sigma$ (standard deviation), we compute their proportion and compare it to the expected proportion under a normal distribution, which is about 68.27%. The proportion is printed near each histogram. It is at the level of about 80%, which is better the standard normal.

It is interesting to see which of the individual stations contribute to the errors. We plotted histograms of the parameter residuals for the baselines involving each particular station. They are shown in the following Figures:

```
MBD residual histograms for the baselines including one station in Fig. 10; SBD residual histograms for the baselines including one station in Fig. 11; SNR residual histograms for the baselines including one station in Fig. 12.
```

3 Software

3.1 make sorted idx.py: Saving VGOS data in Python dictionaries

The VLBI Global Observing System (VGOS) database is organized as a tree-like directory structure. For our purpose of statistical analysis of a small number of parameters scattered across many directories and files below the root directory of the experiment, this implies significant overhead in opening multiple files and accessing the parameters within each of them. The data files in their names only provide the station or baseline names, and no time or polarization information. For example, extraction of, say, SNR data for a particular polarization product and within a specific time range would require opening *all* the files and accessing their times and polarizations using HOPS API calls.

We wrote a script, make sorted idx.py, to extract the parameters for statistical analysis for

the whole experiment and to put it in a Python dictionary, preserving the temporal order. We call such dictionaries "indices". The index can be "pickled" and saved on disk. Interestingly, these files are small, in the hundreds of kilobytes. The other data analisys and plotting scripts read the index files, unpickle them into the Python dictionaries, and use data from the dictionaries.

The script make sorted idx.py should be run on the demi.haystack.mit.edu server where the VGOS data are stored under the directory /data-sc16/geodesy/. Current version of the script works on the experiment 3819 data located under /data-sc16/geodesy/3819. It creates three dictionaries pickled in the files idx38191.pkl, idx3819c.pkl, and idx3819cI.pkl in the directory where the script was run.

- idx38191.pkl: linear polarization products immediately from the /data-sc16/geodesy/3819/ directory;
- idx3819c.pkl: circular polarization products generated by PolConvertwithout the pseudo-Stokes 'I' data, only 'LL', 'LR', 'RL', 'RR'.

 The data are found in /data-sc16/geodesy/3819/polconvert/3819/scratch/pol prods1/3819 directory.
- idx3819cI.pkl: pseudo-Stokes 'I' only for the circular polarization products generated by PolConvert. The data are taken from /data-sc16/geodesy/3819/polconvert/3819/scratch/pcphase stokes test/3819

A pickle file can be unpickled into a dictionary using the pickle.load() function. For example:

```
import pickle
with open('idx3819c.pkl', 'rb') as finp:
  idx3819c 1 = pickle.load(finp)
```

The script make sorted idx.py is also a Python module defining the function

make idx(base dir, pol='lin', max depth=2) with parameters:

base dir: the directory containing the VGOS data. For example, it may be /data-sc16/geodesy/3819/.

pol: polarization, 'lin' - linear, 'cir' - circular.

This parameter is used for the data generated by PolConvert.

It converts the polarization product names

'XX', 'XY', 'YX', 'YY', and the lists ['XX', 'YY'] into the correct names 'LL', 'LR', 'RL', 'RR', and 'I', respectively.

max depth: Limits the maximum depth of recursing into the subdirectories of base dir.

make idx() creates and returns the index dictionary with the data from base dir.

The index dictionary has three dimensions: the baseline name, the polarization, and the data proper, including 'time', 'file', 'mbdelay', 'sbdelay', and 'snr'. Consider a particular index named idx38191 1 (experiment 3819, linear polarization). Its first dimension is indexed with the baseline

Each of the baselines is associated with the cross-corellation products and the pseudo-Stokes I parameter. Thus the second index is one of the products. For example, for the 'ME' baseline: idx38191 1['ME'].keys() dict keys(['XX', 'XY', 'YX', 'YY', 'I'])

For example, the times, the full data file names, SNRs, multi- and single-band delays for the 'SY' baseline and the 'XY' polarization products from this baseline are contained in the index dictionary under

idx3819l 1['SY']['XY']:

```
idx38191 1['SY']['XY'].keys() prints
dict keys(['time', 'file', 'mbdelay', 'sbdelay', 'snr']).
```

For example, in order to access the multi-band delay data list in the ascending temporal order for the baseline 'SV' and the pseudo-Stokes I, one should issue the following command: mbd = idx38191 1['SV']['I']['mbdelay'].

4 Conclusion

5 Appendix: Figures

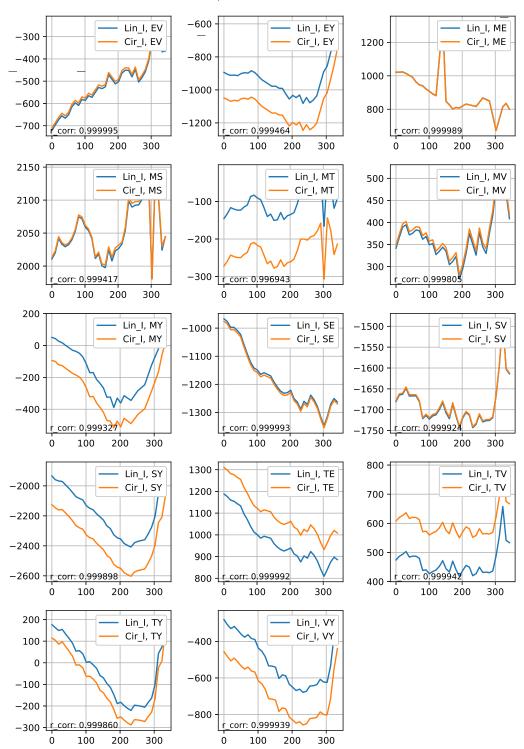


Figure 1: Evolution of Multi-Band Delays (in picoseconds) during the experiment (time in minutes) for the pseudo-Stokes I parameter for every baseline. Each panel shows two curves: Lin I, I from the original, linearly polarized data set and Cir I, I from the circularly polarized data set obtained by applying PolConvert to the original data. Graphs have large biases. However, the coefficients of correlation r corr between Lin I and Cir I are so close to unity that the curves can be considered identical (except for the biases).

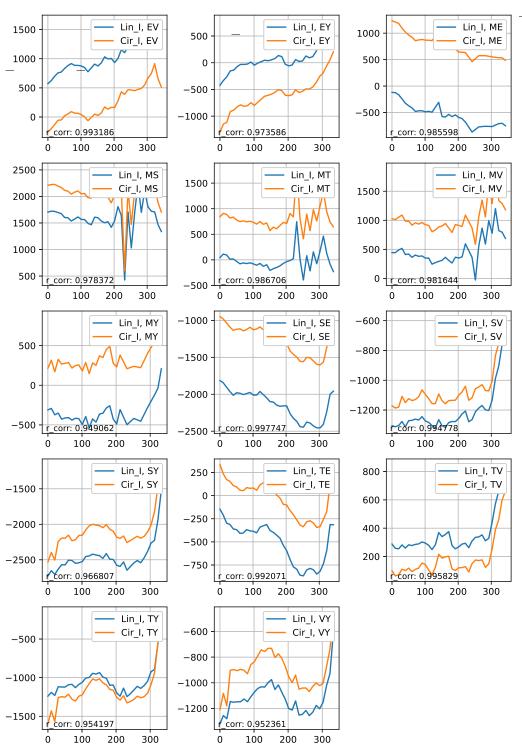


Figure 2: Evolution of Single-Band Delays (inpicoseconds) during the experiment (time in minutes) for the pseudo-Stokes I parameter for every baseline. Each panel shows two curves: Lin I, I from the original, linearly polarized data set and Cir I, I from the circularly polarized data set obtained by applying PolConvert to the original data. Graphs have large biases. The coefficients of correlation r corr between Lin I and Cir I for most of the baselines are close to unity. If it were not for the biases, the curves could be considered close to identical.

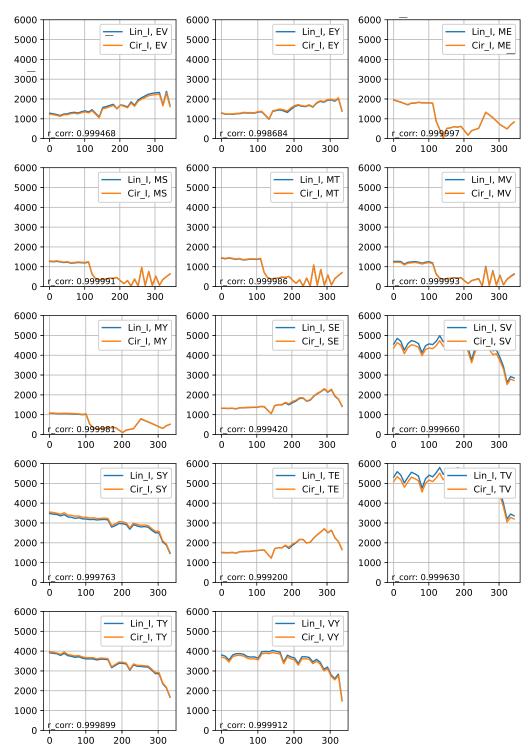


Figure 3: Evolution of Signal-to-Noise Ratios during the experiment (time in minutes) for the pseudo-Stokes I parameter for every baseline. Each panel shows two curves: Lin I, I from the original, linearly polarized data set and Cir I, I from the circularly polarized data set obtained by applying PolConvert to the original data. Graphs have large biases. However, the coefficients of correlation r corr between Lin I and Cir I are so close to unity that the curves can be considered identical (except for the biases).

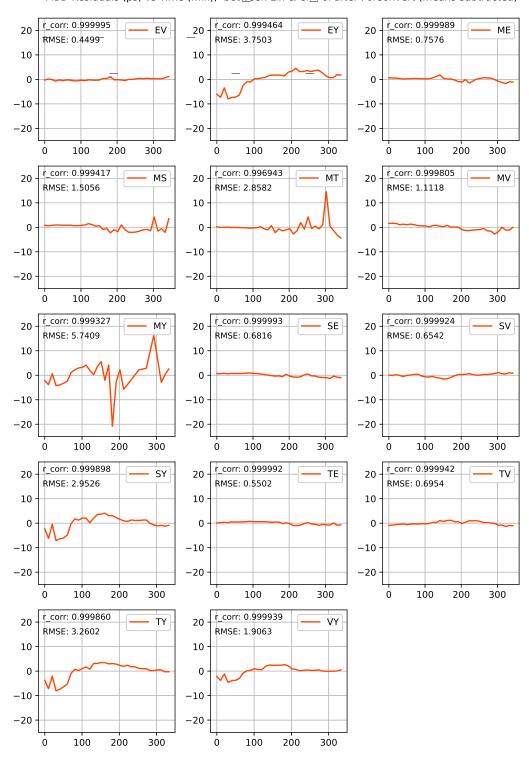


Figure 4: Evolution of the residuals between Lin I and Cir I Multi-Band Delays (in picoseconds) during the experiment (time in minutes) for the pseudo-Stokes I parameter for every baseline. Each panel shows one curve of Lin I - Cir I, where Lin I is I from the original, linearly polarized data set and Cir I is I from the circularly polarized data set obtained by applying PolConvert to the original data. The coefficients of correlation r corr between Lin I and Cir I are very close to unity. The Root Mean Square Error (RMSE) shows the standard deviation of the residuals.

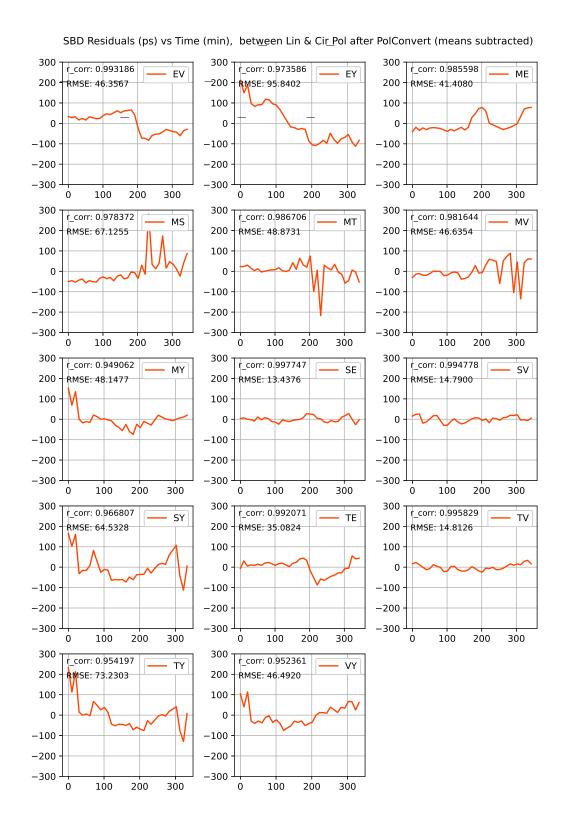


Figure 5: Evolution of the residuals between Lin I and Cir I Single-Band Delays (in picoseconds) during the experiment (time in minutes) for the pseudo-Stokes I parameter for every baseline. Each panel shows one curve of Lin I - Cir I, where Lin I is I from the original, linearly polarized data set and Cir I is I from the circularly polarized data set obtained by applying PolConvert to the original data. The coefficients of correlation r corr between Lin I and Cir I are reasonably close to unity. The Root Mean Square Error (RMSE) shows the standard deviation of the residuals.

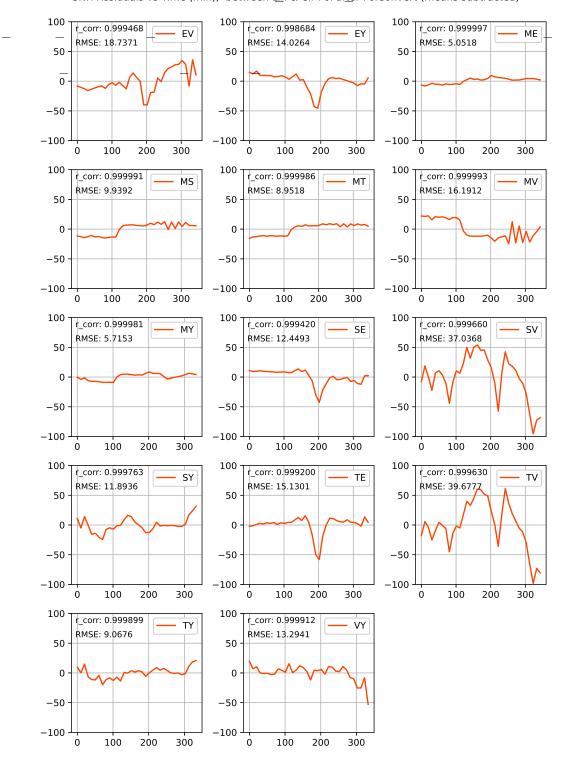


Figure 6: Evolution of the residuals between Lin I and Cir I Signal-to-Noise Ratios during the experiment (time in minutes) for the pseudo-Stokes I parameter for every baseline. Each panel shows one curve of Lin I - Cir I, where Lin I is I from the original, linearly polarized data set and Cir I is I from the circularly polarized data set obtained by applying PolConvert to the original data. The coefficients of correlation r corr between Lin I and Cir I are very close to unity. The Root Mean Square Error (RMSE) shows the standard deviation of the residuals.

Distribution of MBD Residuals Lin_I-Cir_I for All Baselines Within ±std: 83.80% μ =0.0000, σ = 2.39 N = 469; bins: 8 For Normal: 68.27% 200 df = 8-2-1= 5 $\chi^2 = 183.48$ $\chi^2 \gg \chi_{cr}^2 = 11.07$ RMSE: 2.3949 150 r_corr: 0.999753 100 50 -10 ò 10 +σ 5 ps

Figure 7: Histogram of the residuals (see Eq. (3)) for all of the baselines

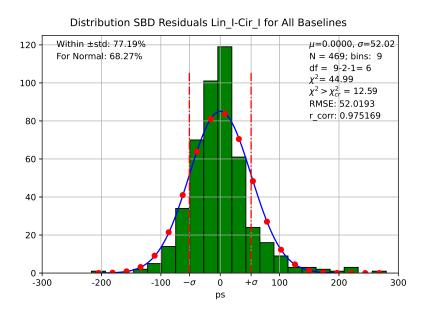


Figure 8:

Distribution of SNR Residuals Lin_I-Cir_I for All Baselines

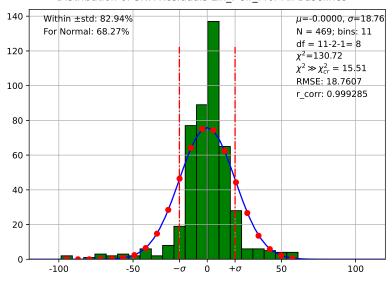


Figure 9:

Distributions of MBD Residuals Lin_I-Cir_I for Stations

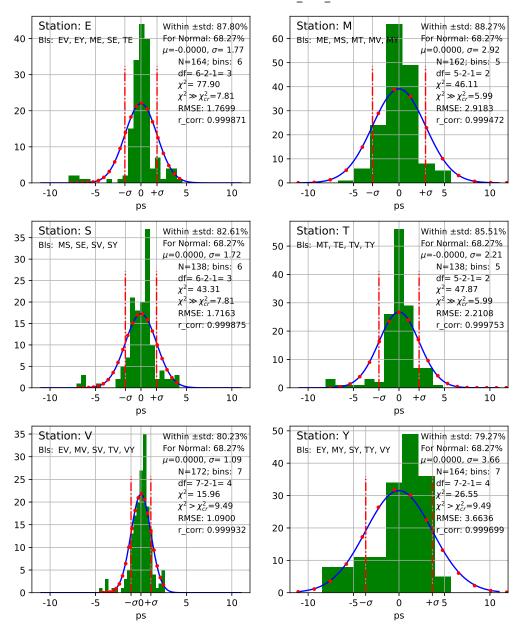


Figure 10:

Distributions of SBD Residuals Lin_I-Cir_I for Stations

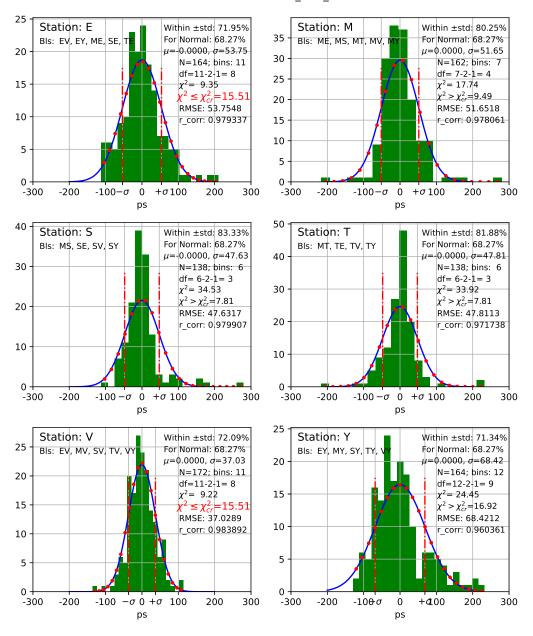


Figure 11:

Distributions of SNR Residuals Lin_I-Cir_I for Stations

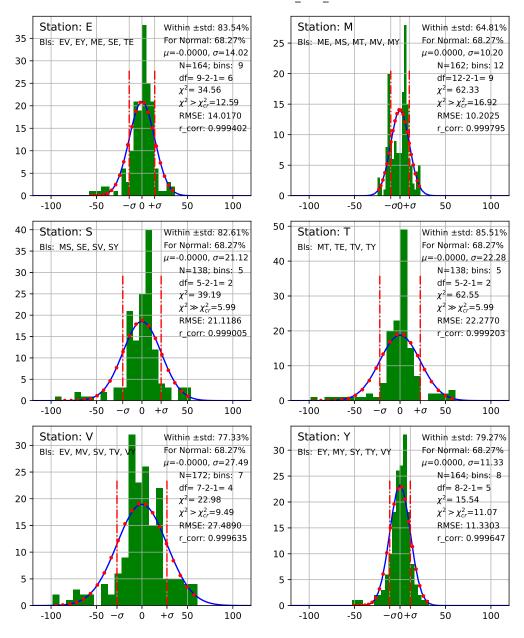


Figure 12: