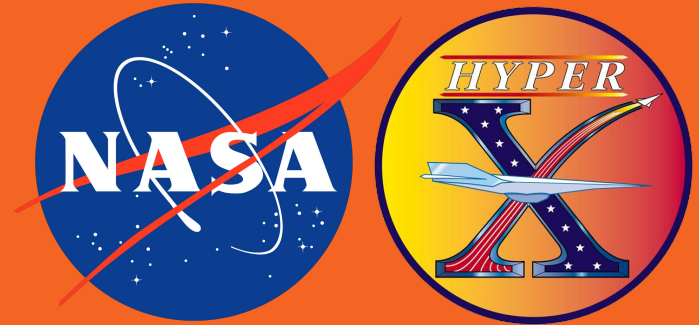

Heat Shielding for Hypersonic Vehicles



Nick Reeder • Ben Kim

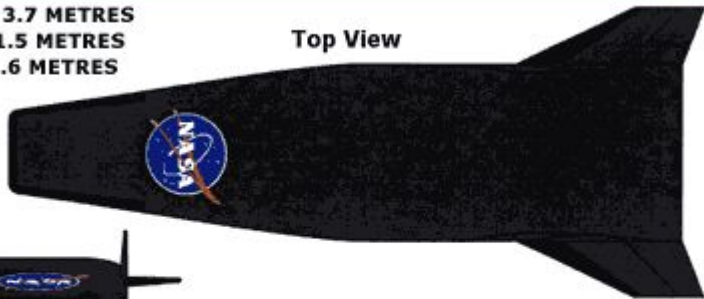
W&M • UVA

Overview

X-43A VEHICLE

LENGTH: 3.7 METRES
WIDTH: 1.5 METRES
HEIGHT: .6 METRES

Top View



Front View

Side View

NASA

X-43

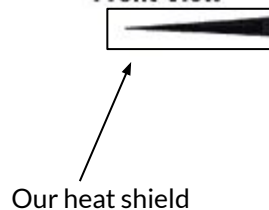
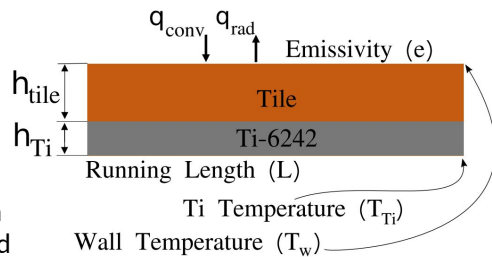


Diagram
for shield



Long term goal:

Perform uncertainty quantification

Challenges

- This requires a lot of data, simulation time, and wind tunnel testing
- Simulations are computationally and financially expensive

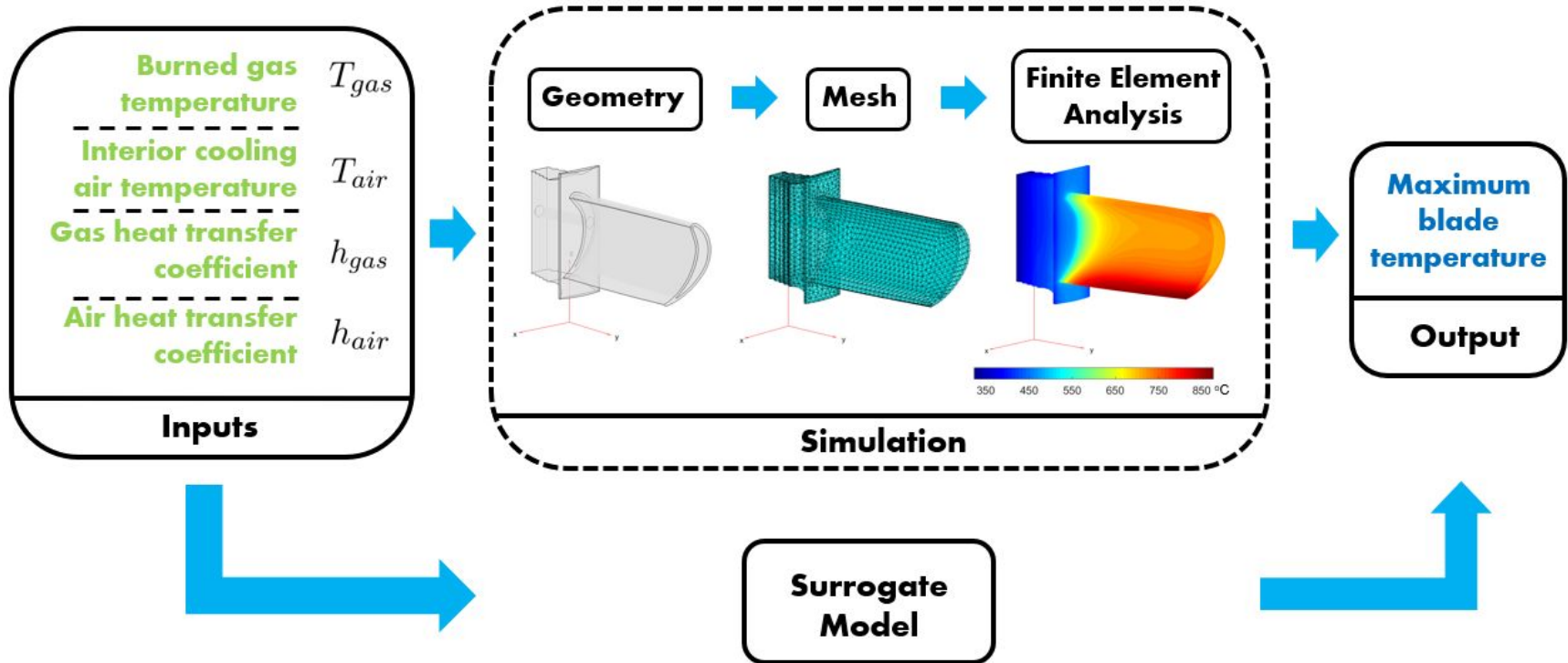
Primary goal:

Develop an effective surrogate model to estimate, for instance, temperature of a tile under certain conditions

Video of Mach 10 Flight



Surrogate Modeling



Our Application

- Modeling temperature of a thermal protection system

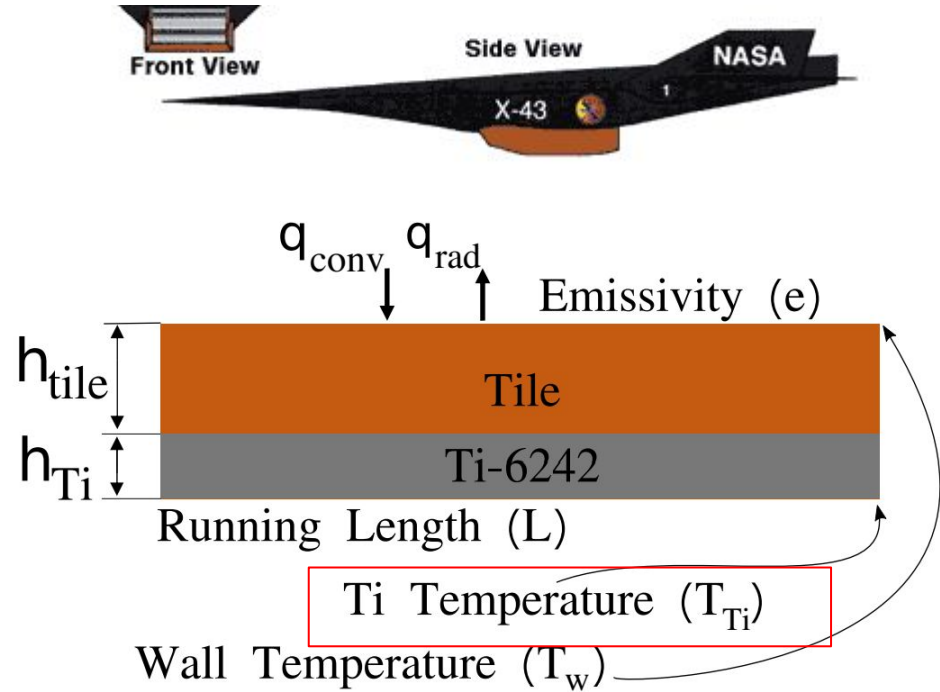
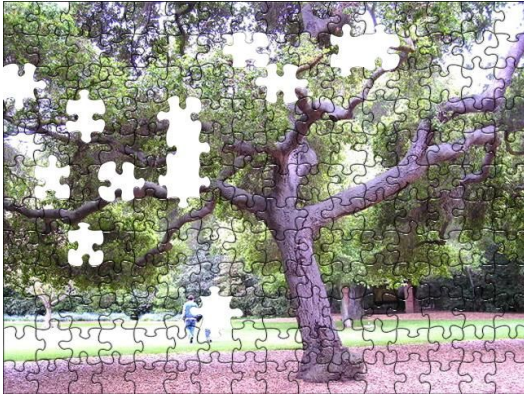


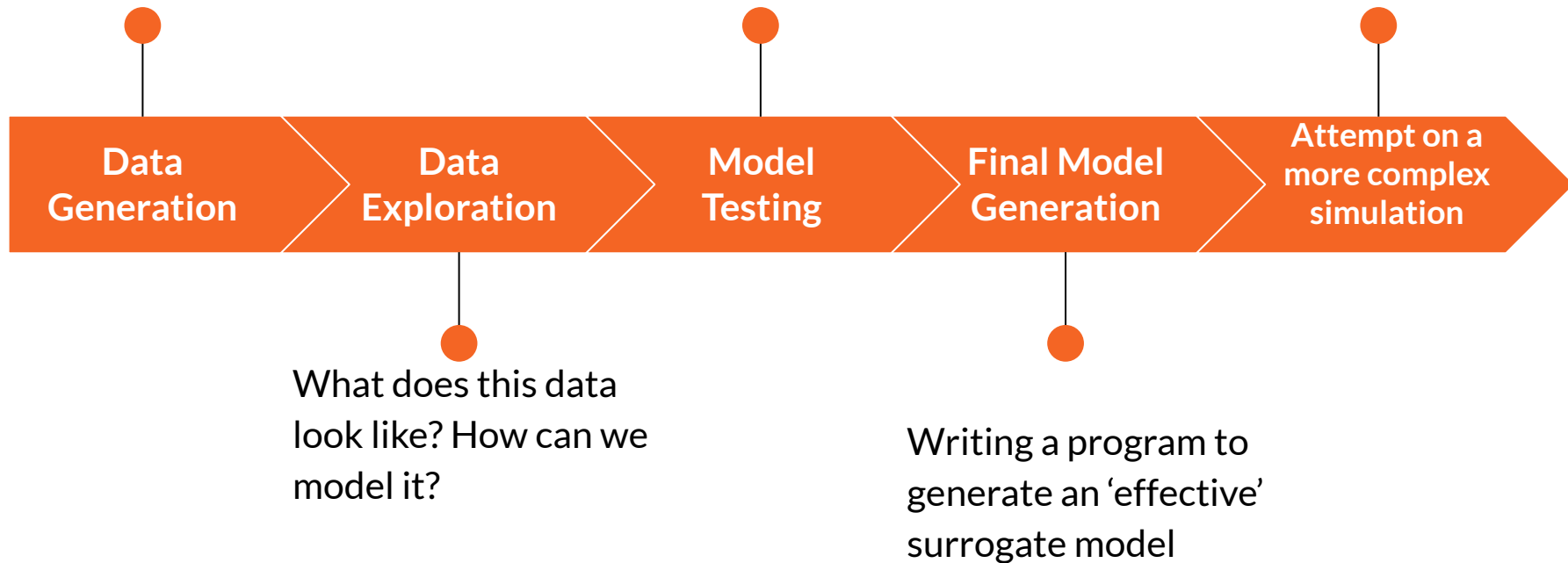
Diagram from Dr. Hunt's paper

Simulate a simple
dataset to work on

What models are good?

Expand this program to
a real simulation

We are here



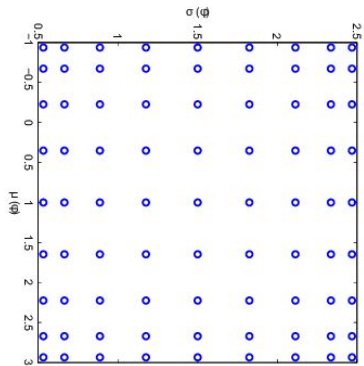
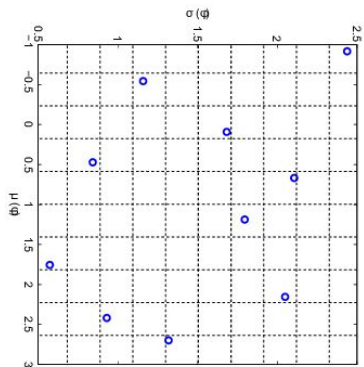
Specifics of the problem

What makes the model complex?

- Things act very strange at these speeds
- There are a TON of variables to consider, and lots of things that can go wrong

Why don't we just test it?

- Testing is very expensive and hard
 - It's much easier to run a program than risk your many million dollar plane
-



Data Creation and Exploration

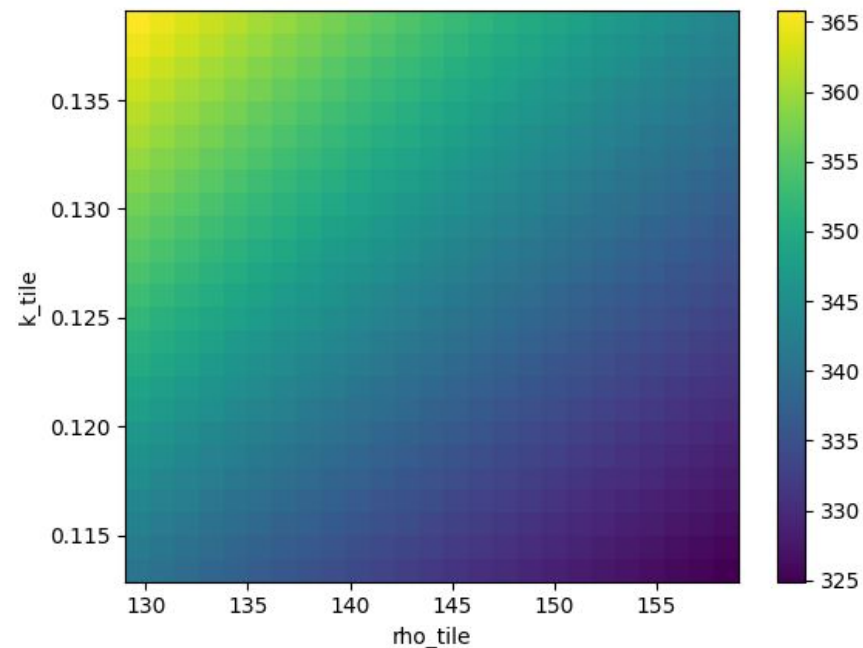
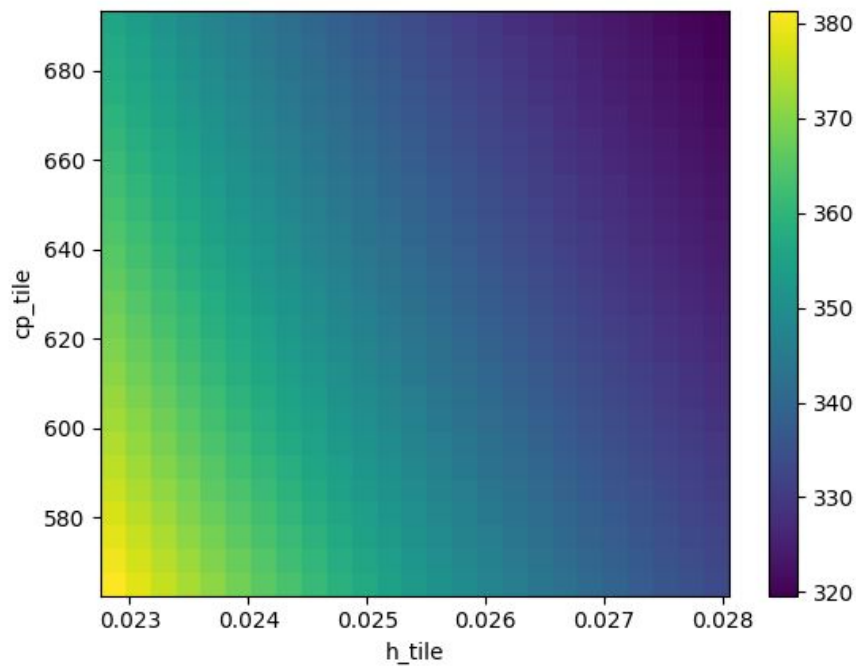
Random Data

- 1000 data points where each parameter was randomly sampled from a $\pm 10\%$ range of baseline

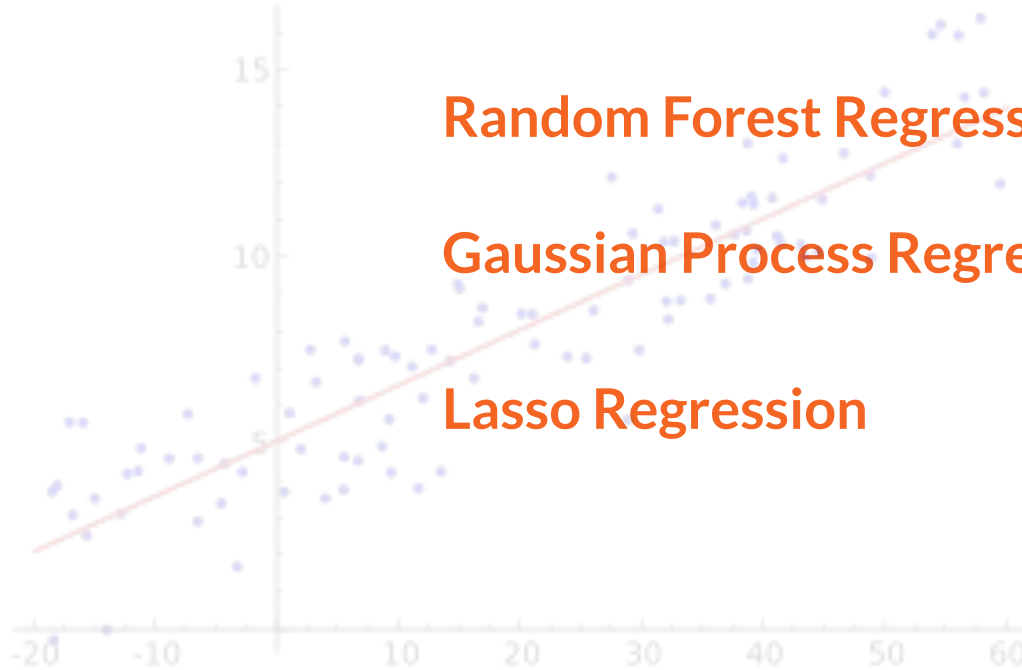
Latin Hypercube Data

- Build a latin hypercube to generate specific data points
 - This should lead to less data points that each provide more information
-

Heatmaps: Show linear shape



Three ML Models



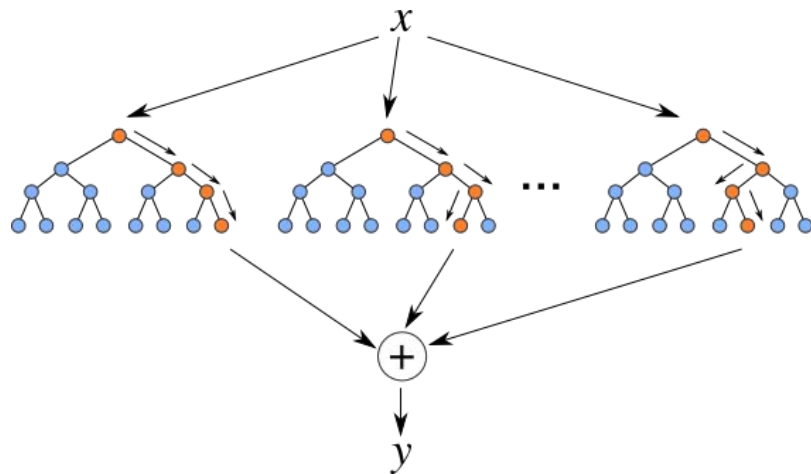
Random Forest Regression (RFR)

Gaussian Process Regression (GPR)

Lasso Regression

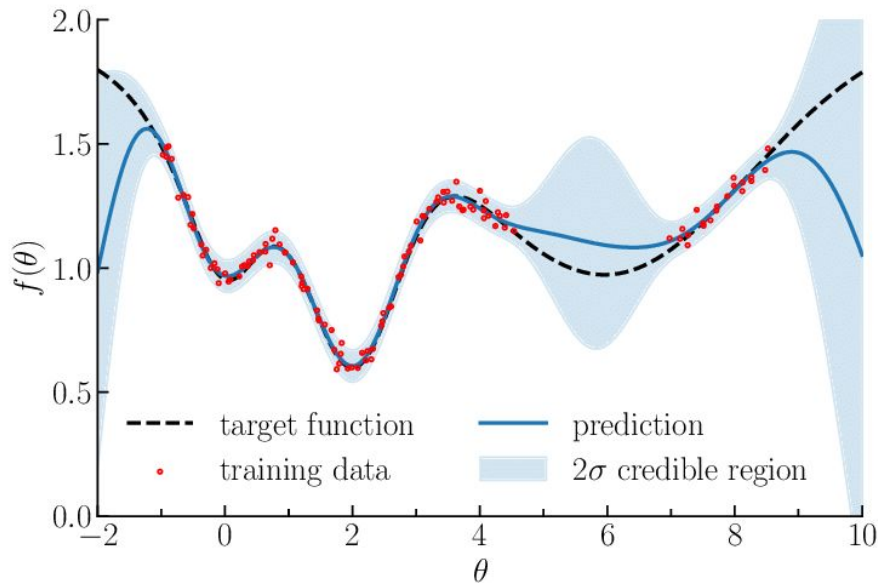
Random Forests

- A 'forest' of decision trees that are each trained on bootstrapped data
- Each tree is unique and random
- Pros:
 - VERY hard to overfit
 - Does not suffer strongly from high dimensions
- Cons:
 - Slower*
 - 'Greybox'
 - Hard to select out dimensions



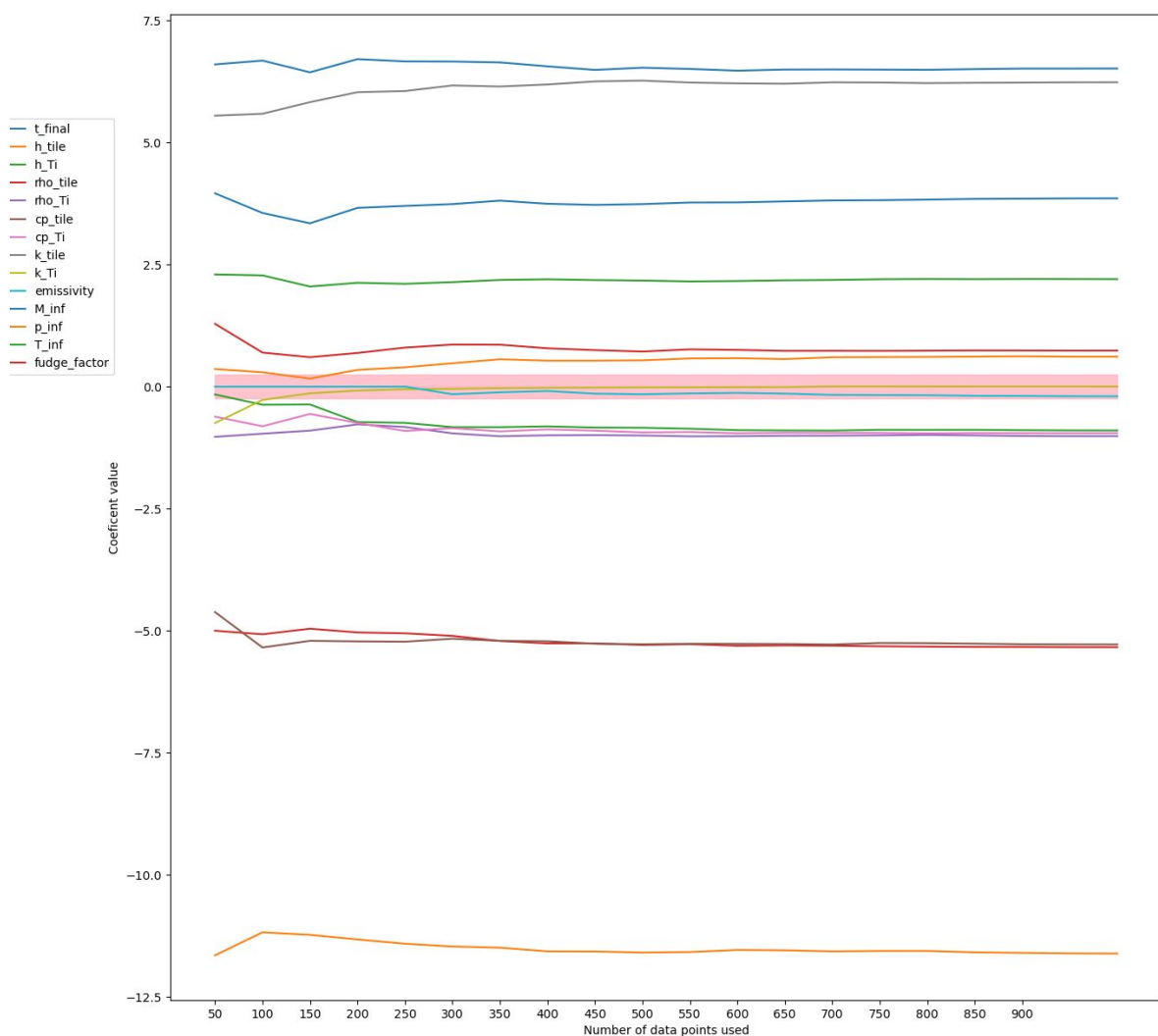
Gaussian Processes

- Used Radial Basis Functions
- Very flexible, can fit many functions
- Pros:
 - Creates automatic uncertainties for each point
 - Interpolation between points
 - Doesn't need a lot of training data
- Dimensionality concerns



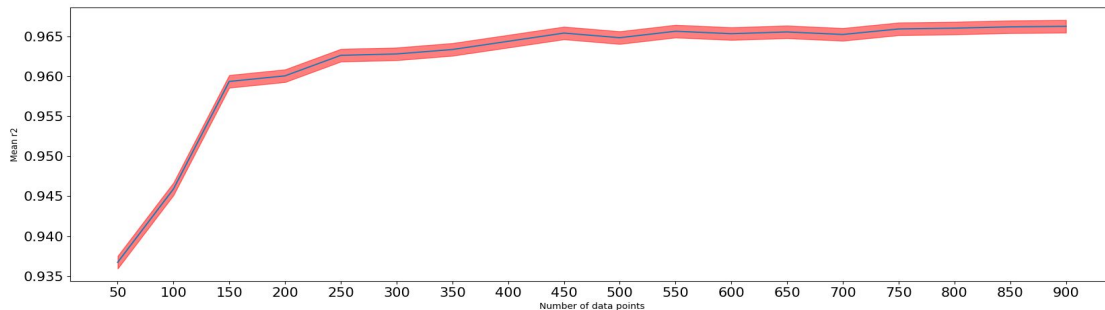
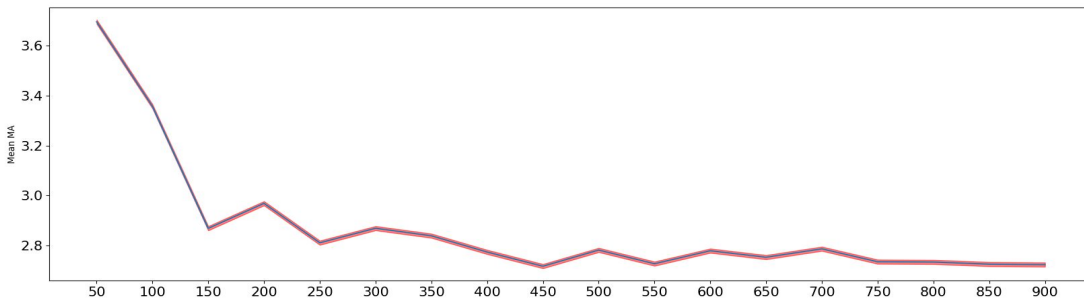
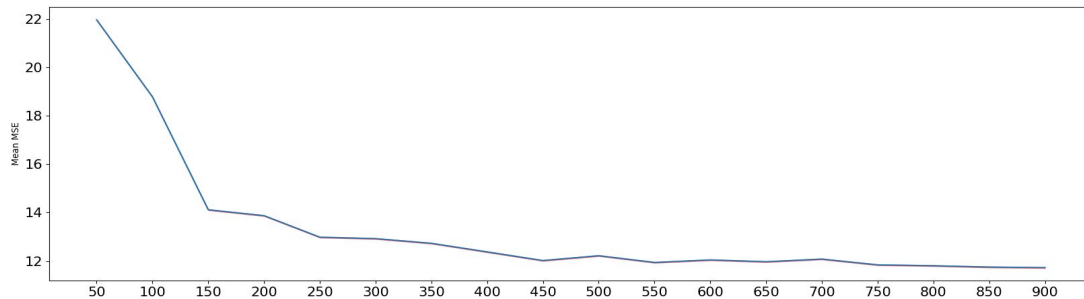
Lasso

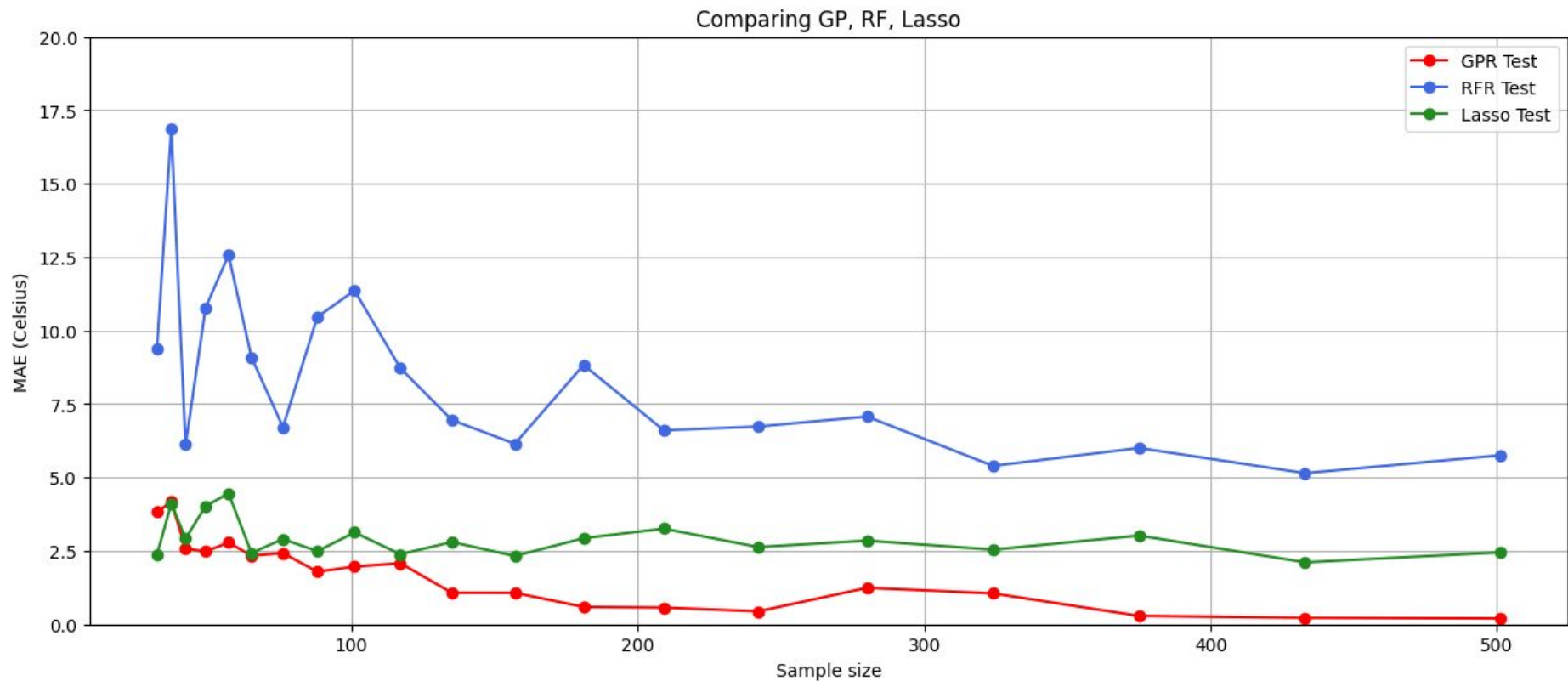
- Extensions of OLS that adds a penalty to minimize RSS
- Requires standardization
 - We used a Standard Scalar ($z = [x - u] / s$)
- Pros:
 - Coefficients can be 0
 - Very easy to plot and interpret
 - Does not need much data
- Cons:
 - Can be overfit easily
 - Suffers at higher dimensions



Lasso Performance

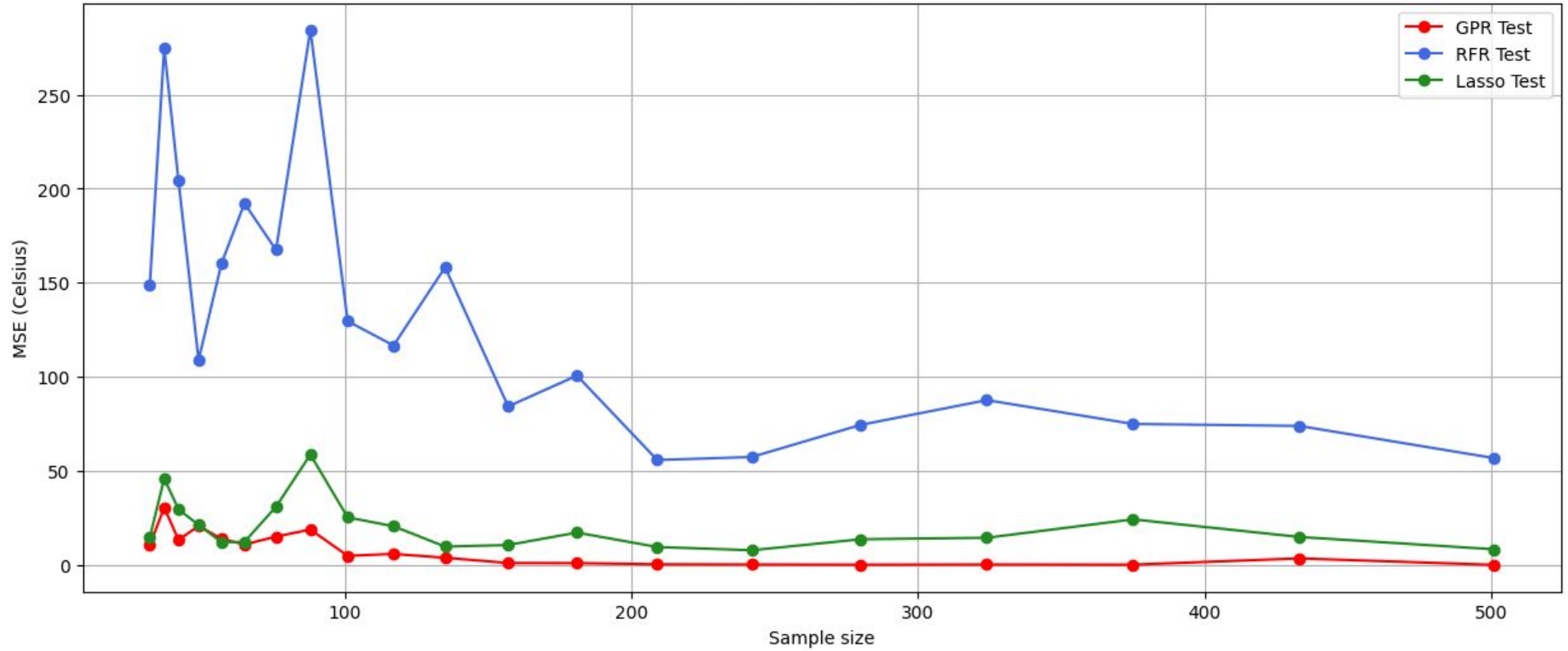
- Model Performance
 - MSE: 11.72 °C
 - MA: 2.72 °C
 - r^2 : 0.95
- Monte Carlo Performance
 - KS: 0.045 / 0.621
 - Wasserstein distance 0.670





Comparison: Mean Absolute Error

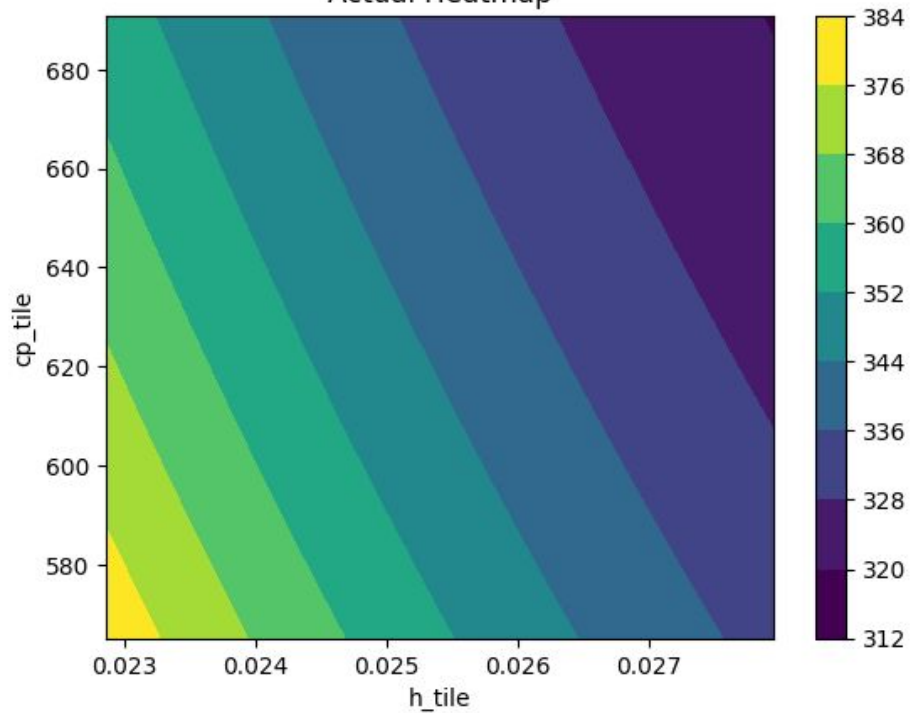
Comparing GP, RF, Lasso



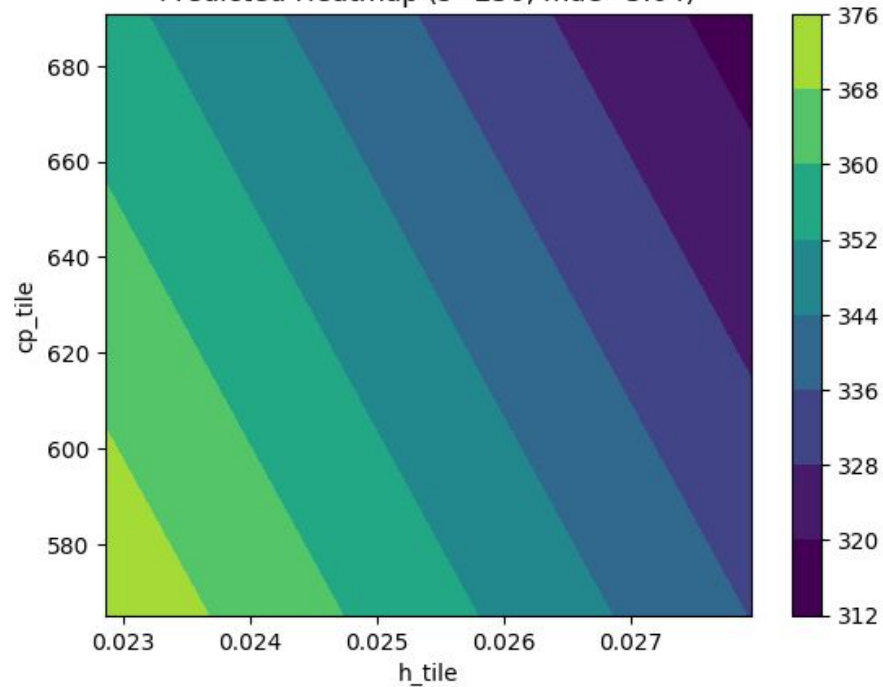
Comparison: Mean Squared Error

Heatmaps: Lasso

Actual Heatmap

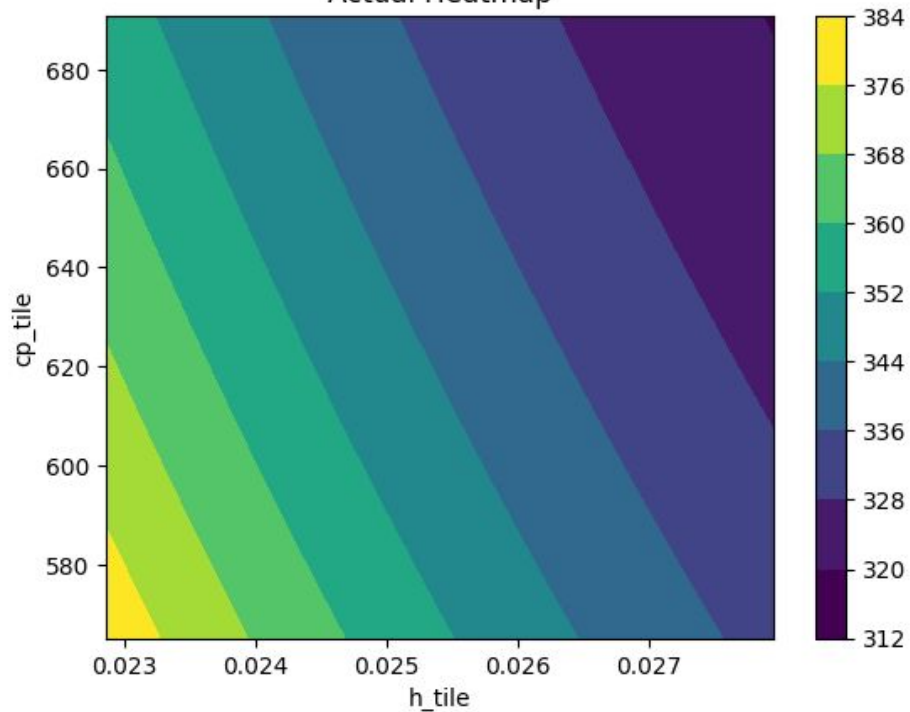


Predicted Heatmap (s=250, mae=3.04)

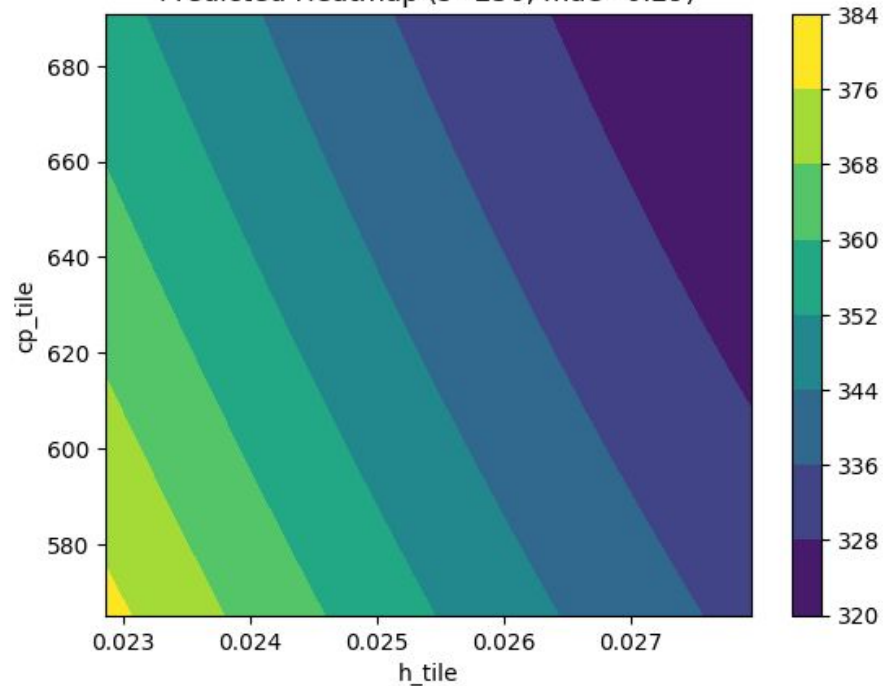


Heatmaps: GPR

Actual Heatmap

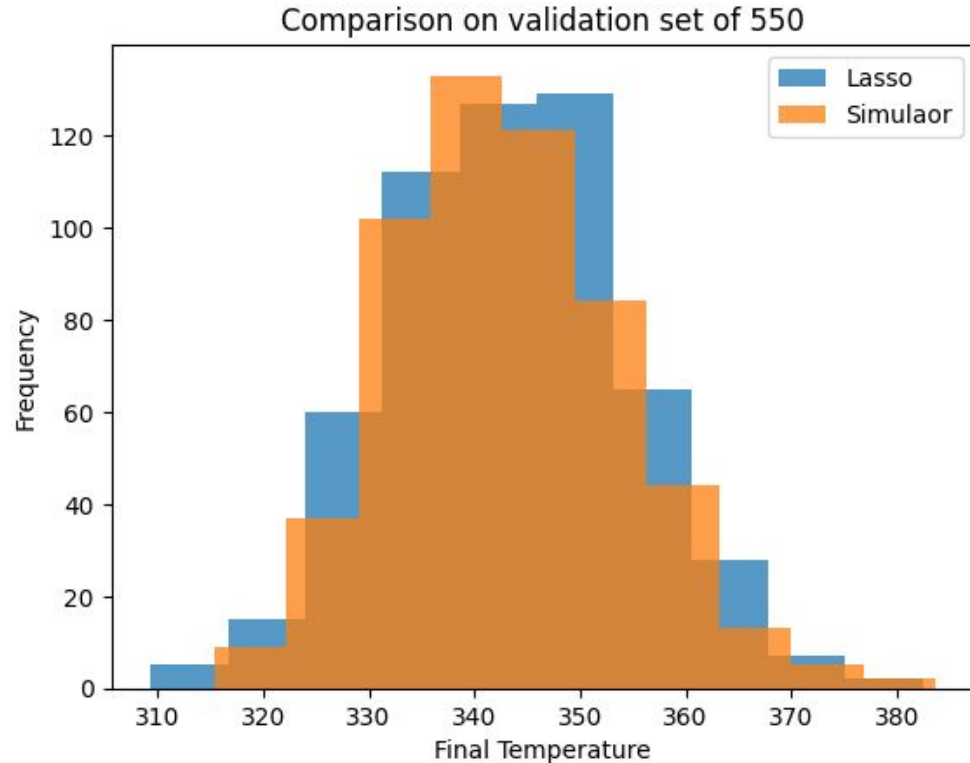


Predicted Heatmap (s=250, mae=0.29)



Lasso UQ Performance

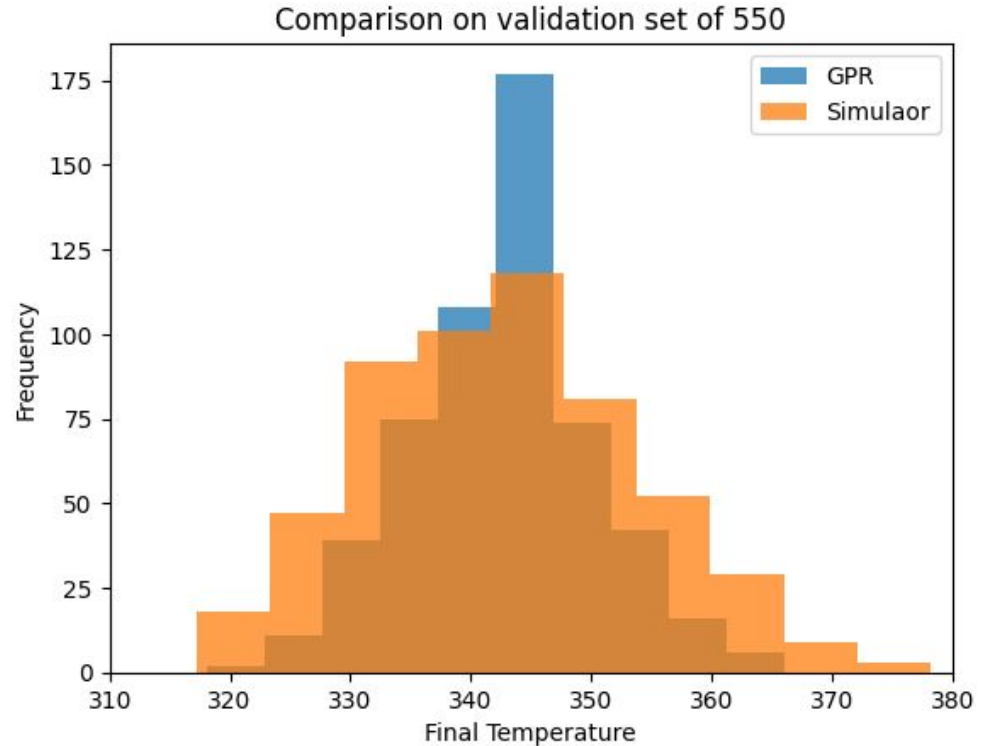
- Monte Carlo Performance
 - KS: 0.045 / 0.621
 - Wasserstein Distance: 0.671



With time exposure ('t_final') as the uncertain variable

GPR UQ Performance

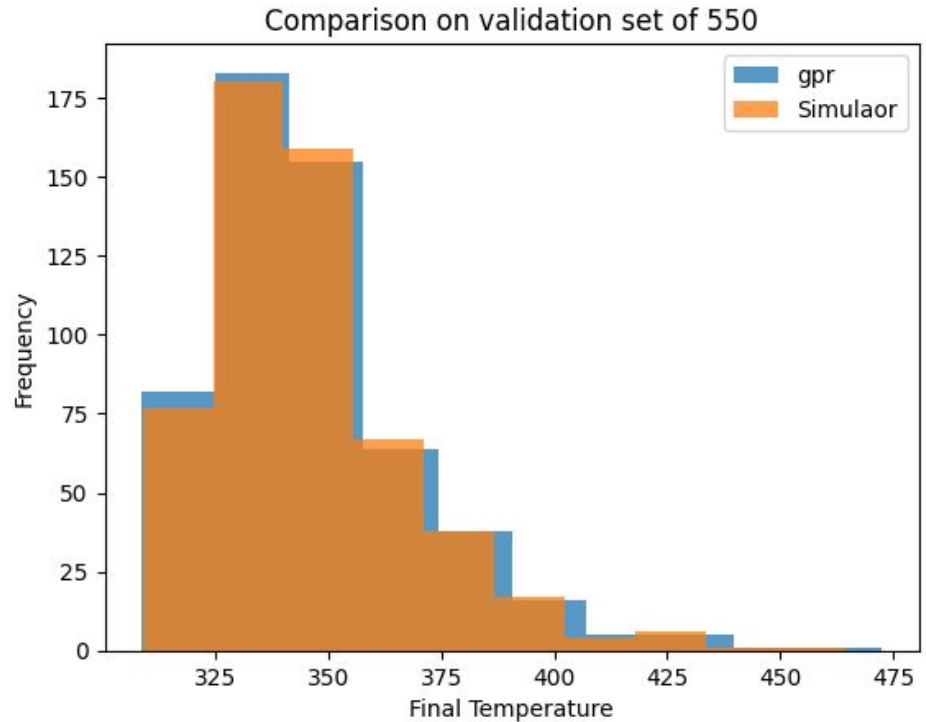
- Monte Carlo Performance
 - P-value=0.001 (they are different)
 - Wasserstein Distance: 3.3
- Hypothesis:
 - GPR will perform better with variables that result in non-normally distributed temperatures.



With time exposure ('t_final') as the uncertain variable

GPR UQ Performance

- Monte Carlo Performance
 - P-value=0.96 (they are the same)
 - Wasserstein Distance: 1.07
- GPR is more accurate depending on the uncertain variable. This leads us to believe that UQ vary based on the variables and models used.



With exterior tile height ('h_tile') as the uncertain variable

What comes next

1. Compare and finalize model
2. Perform uncertainty analysis on mini-simulator
3. Expand process to more complex models
