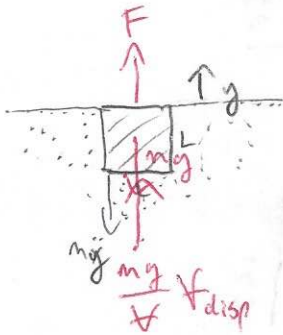


(5.3)



$$F - mg - m\ddot{y} + \frac{mg}{L}(L-y) = 0$$

$$m\ddot{y} = \frac{mg}{L}(L-y) = F - mg$$

$$m\ddot{y} - mg + \frac{mg}{L}y = F - mg$$

$$\ddot{y} + \frac{g}{L}y = \frac{F}{m}$$

$$(D^2 + \frac{g}{L})y = F/m$$

$$y_c, \lambda^2 = -\frac{g}{L}$$

$$\lambda = \pm i\sqrt{\frac{g}{L}}$$

$$\therefore y_c = (\sin(\sqrt{\frac{g}{L}}t) + \cos(\sqrt{\frac{g}{L}}t))$$

$$y_p, \frac{1}{D^2 + \frac{g}{L}} \frac{F}{m}$$

$$\frac{\frac{L}{g}}{\frac{L}{g}D^2 + 1} \frac{F}{m} = \frac{L}{g} \left(1 - \frac{L}{g}D^2\right) \frac{F}{m} = \frac{LF}{gm}$$

$$\therefore y = C_1 \sin\left(\sqrt{\frac{g}{L}} t\right) + C_2 \cos\left(\sqrt{\frac{g}{L}} t\right) + \frac{FL}{mg}, \text{ @ } t=0, y=0$$

$$0 = C_2 + \frac{FL}{mg}$$

$$C_2 = -\frac{FL}{mg}, \text{ @ time } t=0, \dot{y}=0$$

$$\dot{y} = C_1 \sqrt{\frac{g}{L}} \cos\left(\sqrt{\frac{g}{L}} t\right) = 0, \quad C_1 \sqrt{\frac{g}{L}} = 0, \therefore C_1 = 0$$

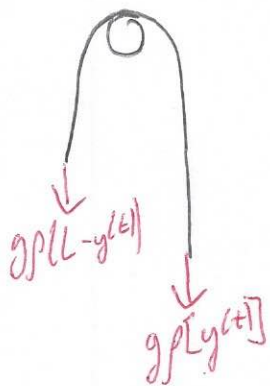
$$\therefore y(t) = \frac{FL}{mg} \left(1 - \cos\left(\sqrt{\frac{g}{L}} t\right)\right), \text{ @ } t=T, y=L$$

$$L = \frac{FL}{mg} \left(1 - \cos\left(\sqrt{\frac{g}{L}} T\right)\right)$$

$$1 - \frac{mg}{F} = \cos\left(\sqrt{\frac{g}{L}} T\right)$$

$$\sqrt{\frac{L}{g}} \cos^{-1}\left(1 - \frac{mg}{F}\right) = T$$

5.7



$$g\rho[y(t)] - g\rho[L - y(t)] = m\ddot{y}$$

$$g\rho(2y(t) - L) = m\ddot{y}$$

$$m\ddot{y} - 2y g\rho = -g\rho L$$

$$\ddot{y}L - 2y g = -gL$$

$$(\partial^2 L - 2g)y = -gL$$

$$y_c, \partial^2 L - 2g = 0$$

$$\lambda = \pm \sqrt{\frac{2g}{L}}$$

$$y_c = C_1 e^{\sqrt{\frac{2g}{L}}t} + C_2 e^{-\sqrt{\frac{2g}{L}}t} \quad \text{Since terms of constants are } e^x$$

$$y_c = A \sinh(\sqrt{\frac{2g}{L}}t) + B \cosh(\sqrt{\frac{2g}{L}}t)$$

$$y_p = \frac{1}{\partial^2 L - 2g} (-gL)$$

$$= \frac{-1/2}{1 - \frac{\partial^2 L}{2g}} - gL$$

$$= \frac{1}{2g} \left(1 + \frac{\partial^2 L}{2g}\right) gL$$

$$= L/2$$

$$y = A \sinh(\sqrt{\frac{2g}{L}}t) + B \cosh(\sqrt{\frac{2g}{L}}t) + L/2, \text{ when } t=0, y=l$$

$$l = B + L/2$$

$$B = l - L/2$$

$$\dot{y} = A \cosh(\sqrt{\frac{2g}{L}}t) \sqrt{\frac{2g}{L}} + B \sinh(\sqrt{\frac{2g}{L}}t) \sqrt{\frac{2g}{L}} + L/2, \text{ when } t=0, \dot{y}=0$$

$$0 = A = 0$$

$$\therefore y = (l - L/2) \cosh\left(\sqrt{\frac{2g}{L}} t\right) + L/2, \text{ when } t = T, y = L$$

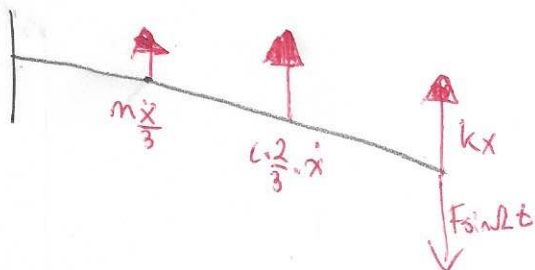
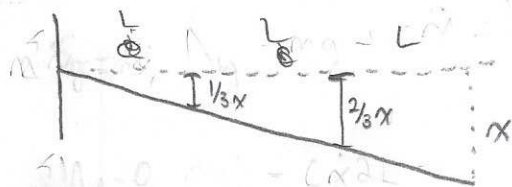
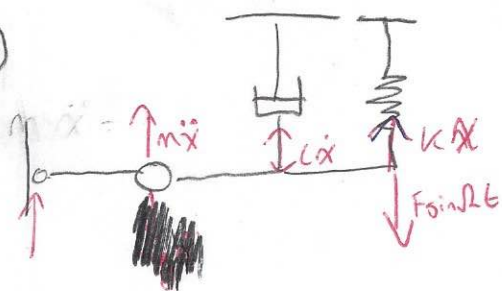
$$\frac{L - L/2}{l - L/2} = \cosh\left(\sqrt{\frac{2g}{L}} t\right)$$

$$\cosh^{-1}\left(\frac{L/2}{l - L/2}\right) = \sqrt{\frac{2g}{L}} T$$

$$T = \cosh^{-1}\left(\frac{L/2}{l - L/2}\right) \sqrt{\frac{L}{2g}}$$



5.10



$$\textcircled{1} \sum M_A = 0, \frac{m}{3} \ddot{x} L + \frac{4c}{3} \dot{x} L + kx \cdot 3L - F \sin(\Omega t) (3L) = 0$$

$$m \ddot{x} + 4c \dot{x} + kx = 9F \sin(\Omega t)$$

$$\textcircled{2} \ddot{x} + 4 \frac{c}{m} \dot{x} + \frac{k}{m} x = \frac{9F}{m} \sin(\Omega t)$$

$$\therefore \frac{9k}{m} = \omega_0^2, \omega_0 = 3 \sqrt{\frac{k}{m}}$$

$$\omega_d = \omega_0 \sqrt{1 - \beta^2}$$

$$2\beta \omega_0 = 4 \frac{c}{m}$$

$$2\beta 3 \sqrt{\frac{k}{m}} = 4 \frac{c}{m}$$

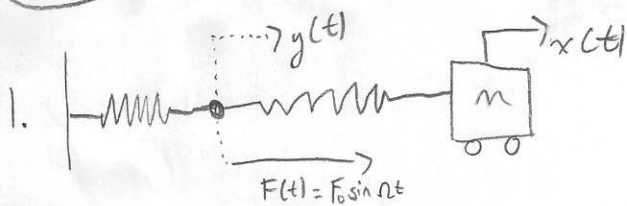
$$\beta = \frac{2}{3} \frac{c \sqrt{m}}{\sqrt{k} m}$$

$$= \frac{2}{3} \cdot \frac{c}{\sqrt{km}}$$

$$\omega_d = \omega_0 \sqrt{1 - \frac{4}{9} \frac{c^2}{km}}$$

$$= \omega_0 \sqrt{1 - \frac{4c^2}{9km}}$$

5.15



①  $\begin{array}{c} \xrightarrow{k_2 y} \\ \xrightarrow{F_0 \sin \omega t} \\ \xleftarrow{k_2(x-y)} \end{array}$

②  $\begin{array}{c} \xleftarrow{k_2(x-y)} \\ \boxed{m} \end{array}$

From ①,  $F + k_2(x-y) - k_1 y = m \ddot{y}$  From ②,

$$F + k_2 x - y(k_2 + k_1) = 0$$

$$y = \frac{F + k_2 x}{k_2 + k_1}$$

From ②,  $-k_2(x-y) = m \ddot{x}$

Subbing ① into ②

$$m \ddot{x} = -k_2 \left( x - \frac{F + k_2 x}{k_2 + k_1} \right)$$

$$m \ddot{x} = -k_2 x \left( 1 - \frac{k_2}{k_2 + k_1} \right) + \frac{k_2 F}{k_1 + k_2}$$

$$\therefore \ddot{x} + \left[ \frac{k_2 - \frac{k_2^2}{k_2 + k_1}}{m} \right] x = \frac{k_2 F}{k_1 + k_2}$$

From original,  $\frac{k_2}{m} - \frac{k_2}{m(k_2 + k_1)} = \omega_0^2$

$$\frac{k_2(k_2 + k_1)}{m(k_2 + k_1)} - \frac{k_2}{m(k_2 + k_1)} = \omega_0^2$$

$$\frac{k_2^2 + k_1 k_2 - k_2^2}{m(k_2 + k_1)} = \omega_0^2$$

$$\omega_0 = \sqrt{\frac{k_1 k_2}{m(k_2 + k_1)}}$$

Also,  $RS = f \sin \Omega t$

$$\therefore f = \frac{k_2}{m(k_1 + k_2)} F_0$$

2.  $x_c$ ,  $(D^2 + \omega_0^2)x = 0$

$$\lambda^2 = -\omega_0^2$$

$$\lambda = 0 \pm i\omega_0$$

$$x_c = A \cos \omega_0 t + B \sin \omega_0 t$$

$x_p$ ,  $(D^2 + \omega_0^2)x = f \sin \Omega t$

$$x_p = \frac{1}{D^2 + \omega_0^2} f \sin \Omega t$$

$$= f \frac{1}{D^2 + \omega_0^2} \sin \Omega t$$

$$= f \frac{1}{-\Omega^2 + \omega_0^2} \sin \Omega t$$

$\therefore x(t) = A \cos \omega_0 t + B \sin \omega_0 t + f \cdot \frac{1}{\omega_0^2 - \Omega^2} \sin \Omega t$ , when  $t=0$ ,  $x(t)=0$ ,  $\dot{x}(t)=0$

$$x(0) = A, \therefore A = 0$$

$$\dot{x}(0) = \omega_0 A \sin \omega_0 t + \omega_0 B \cos \omega_0 t + f \Omega \cdot \frac{1}{\omega_0^2 - \Omega^2} \cos \Omega t$$

$$0 = B + \frac{f \Omega}{\omega_0^2 - \Omega^2}, \quad B = -\frac{f \Omega}{\omega_0^2 - \Omega^2} \frac{1}{\omega_0}$$

$$\therefore x(t) = \frac{f}{\omega_0^2 - \Omega^2} \left( \sin \Omega t - \frac{\Omega}{\omega_0} \sin \omega_0 t \right)$$



$$= kM \frac{(k+K - m\Omega^2 u^2) - cD}{[(k+K - m\Omega^2 u^2) + cD][(k+K - m\Omega^2 u^2) - cD]} \sin \Omega u t$$

$$= kM \frac{(k+K - m\Omega^2 u^2) - cD}{(k+K - m\Omega^2 u^2)^2 - c^2 D^2} \sin \Omega u t$$

$$= kM \frac{(k+K - m\Omega^2 u^2) \overset{A}{\sin \Omega u t} - cD \overset{B}{\cos \Omega u t}}{(k+K - m\Omega^2 u^2)^2 + c^2 D^2}$$

$$= kM \frac{1}{A^2 + B^2} \sqrt{A^2 + B^2} \left( \frac{A}{\sqrt{A^2 + B^2}} \sin \Omega u t - \frac{B}{\sqrt{A^2 + B^2}} \cos \Omega u t \right)$$

amplitude of steady state response

 $\cos \theta$ 
 $\sin \theta$

$$= kM \frac{1}{\sqrt{(k+K - m\Omega^2 u^2)^2 + c^2 D^2}} \sin(\Omega u t - \theta)$$



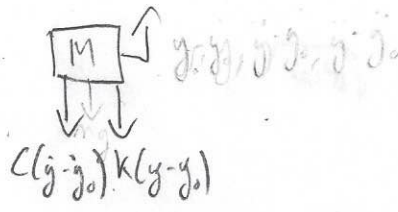
5.16

$y(t)$   
M



$x = \Omega t, \therefore \sin x = \sin \Omega t$

(1)



$\sum F = ma, \ddot{y} = -c(y - y_0) - k(y - y_0)$

$u = \frac{\omega_0}{\Omega}$

$m(\ddot{z} + \ddot{y}_0) = -cz - kz$

$m\ddot{z} + m\ddot{y}_0 = -cz - kz$

$\ddot{z} - \Omega^2 \sin \Omega t = -\frac{c}{m}z - \frac{k}{m}z$

$\ddot{z} + \frac{c}{m}\dot{z} + \frac{k}{m}z = \Omega^2 \sin \Omega t$

$\therefore c/m = 2\gamma \omega_0, \omega_0 = \sqrt{\frac{k}{m}}$

$(D^2 + 2\gamma \omega_0 D + \omega_0^2)z = \Omega^2 \sin(\Omega t)$

$z_p = \frac{1}{D^2 - 2\gamma \omega_0 D + \omega_0^2} \Omega^2 \sin(\Omega t)$

$z_p = \Omega^2 \cdot \frac{1}{-\Omega^2 - 2\gamma \omega_0 D + \omega_0^2} \sin(\Omega t)$

$z_p = \Omega^2 \frac{[(\omega_0^2 - \Omega^2) + 2\gamma \omega_0 D]}{[(\omega_0^2 - \Omega^2) - 2\gamma \omega_0 D][(\omega_0^2 - \Omega^2) + 2\gamma \omega_0 D]} \sin \Omega t$

$$z_p = m u^2 \Omega^2 \cdot \frac{[(\omega_0^2 - u^2 \Omega^2) + 2 \delta \omega_0 D]}{(\omega_0^2 - \Omega^2 u^2)^2 - 4 \delta^2 \omega_0^2 D^2} \sin \Omega u t \quad (a-b)(c-d)$$

$$z_p = m u^2 \Omega^2 \cdot \frac{\overset{A}{(\omega_0^2 - u^2 \Omega^2)} \overset{B}{\sin \Omega u t} + 2 \delta \omega_0 \Omega u \cos(\Omega u t)}{(\sqrt{(\omega_0^2 - \Omega^2 u^2)^2 + (2 \delta \omega_0 \Omega u)^2})^2} \leftarrow \sqrt{A^2 + B^2}$$

$$z_p = m u^2 \Omega^2 \frac{[\cos(\Omega u t - \phi)]}{\sqrt{(\omega_0^2 - \Omega^2 u^2)^2 + (2 \delta \omega_0 \Omega u)^2}}, \text{ maximized when cos term} = 1$$

$$\therefore |z_p(t)|_{\max} = \frac{m u^2 \Omega^2}{\sqrt{(\omega_0^2 - \Omega^2 u^2)^2 + (2 \delta \omega_0 \Omega u)^2}}$$

3. Since  $f=0$ ,  $\ddot{z} + \omega_0^2 z = m \Omega^2 u^2 \sin(u_0)$

Thus, from sin term,  $\omega_0 = \Omega u$

$$u = \frac{\omega_0}{\Omega}$$

$$= \frac{1}{\Omega} \sqrt{\frac{k}{m}}$$

(5.18)

$$\ddot{y}(t) + 2\zeta\omega_0 \dot{y}(t) + \omega_0^2 y = -\dot{x}_0(t)$$

$$(D^2 + 2\zeta\omega_0 D + \omega_0^2)y = -\dot{x}_0 \sin \Omega t$$

$$x_0 = a \sin \Omega t$$

$$\dot{x}_0 = a\Omega \cos \Omega t$$

$$\ddot{x}_0 = -a\Omega^2 \sin \Omega t$$

$$y_p = \frac{1}{D^2 + 2\zeta\omega_0 D + \omega_0^2} (-a \sin \Omega t)$$

$$y_p = -a \frac{1}{-\Omega^2 + \omega_0^2 + 2\zeta\omega_0 D} \sin \Omega t$$

$$y_p = a\Omega^2 \frac{(\omega_0^2 - \Omega^2) - 2\zeta\omega_0 D}{[(\omega_0^2 - \Omega^2) + 2\zeta\omega_0 D][(\omega_0^2 - \Omega^2) - 2\zeta\omega_0 D]} \sin \Omega t$$

$$y_p = a\Omega^2 \frac{(\omega_0^2 - \Omega^2) - 2\zeta\omega_0 D}{(\omega_0^2 - \Omega^2)^2 - 2^2 \zeta^2 \omega_0^2 D^2} \sin \Omega t$$

$$= a\Omega^2 \frac{(\omega_0^2 - \Omega^2) \overset{\text{cos}}{\downarrow} \sin \Omega t + 2\zeta\omega_0 \Omega \overset{\text{sin}}{\downarrow} \cos \Omega t}{\sqrt{(\omega_0^2 - \Omega^2)^2 + 2^2 \zeta^2 \omega_0^2 \Omega^2} \sqrt{(\omega_0^2 - \Omega^2)^2 + 2^2 \zeta^2 \omega_0^2 \Omega^2}}$$

$$= a\Omega^2 \frac{\sin(\Omega t - \gamma)}{\sqrt{(\omega_0^2 - \Omega^2)^2 + 2^2 \zeta^2 \omega_0^2 \Omega^2}}, \text{ when maximized, } \sin(\Omega t - \gamma) = 1$$

$$\therefore y_p = \frac{a\Omega^2}{\sqrt{(\omega_0^2 - \Omega^2)^2 + 2^2 \zeta^2 \omega_0^2 \Omega^2}}, \quad X_{0 \max} = a$$

$$\therefore DMF = \frac{\Omega^2}{\sqrt{(\omega_0^2 - \Omega^2)^2 + 2^2 \zeta^2 \omega_0^2 \Omega^2}} \cdot \frac{1}{\omega_0^2} = \frac{r^2}{\sqrt{(\omega_0^2 - \Omega^2)^2 + (2\zeta\omega_0 \Omega)^2}} \cdot \sqrt{\frac{1}{\omega_0^4}}$$

$$= \frac{r^2}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}}, \quad r = \frac{\Omega}{\omega_0}$$

DMF as a Function of  $r$  and  $\zeta$

