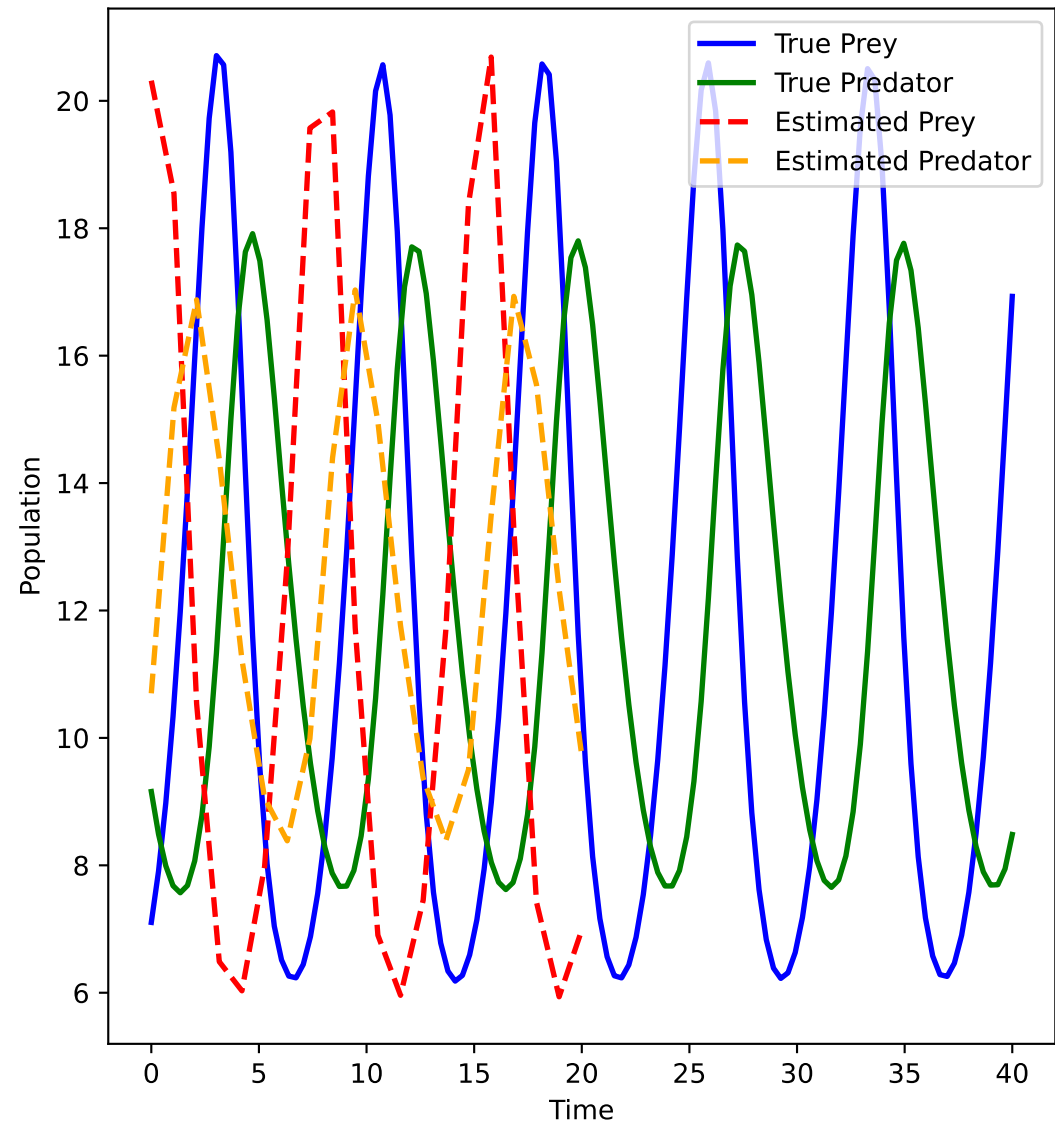


Estimated + True Trajectories (0-40)



Data + True Trajectories (0-20)

