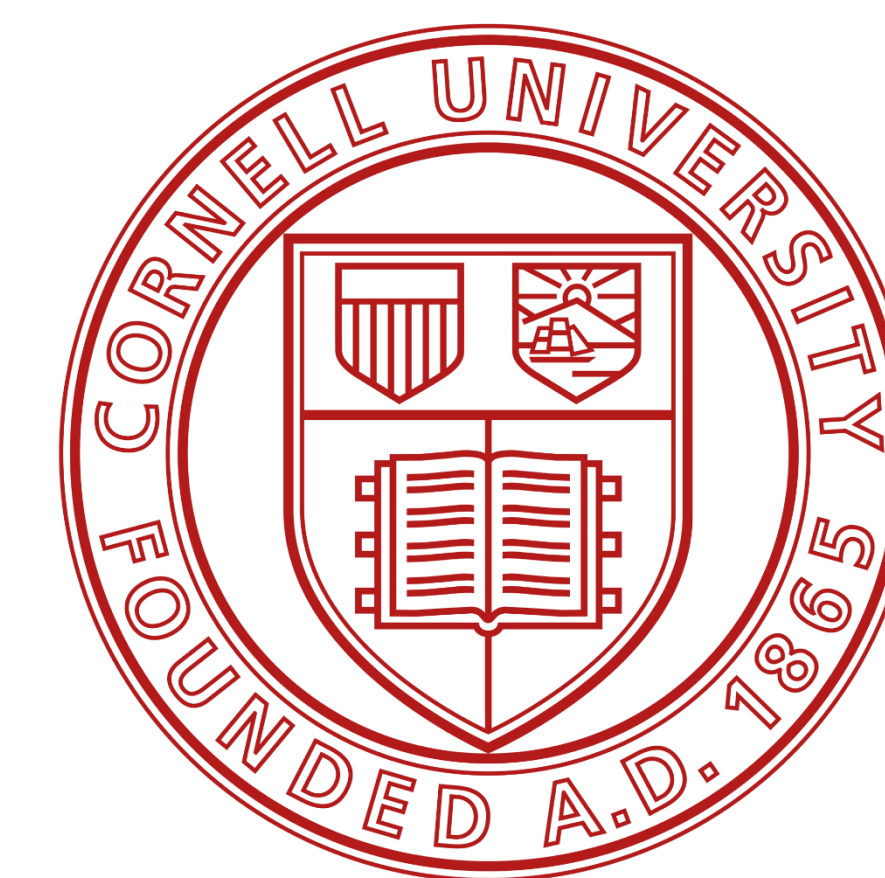




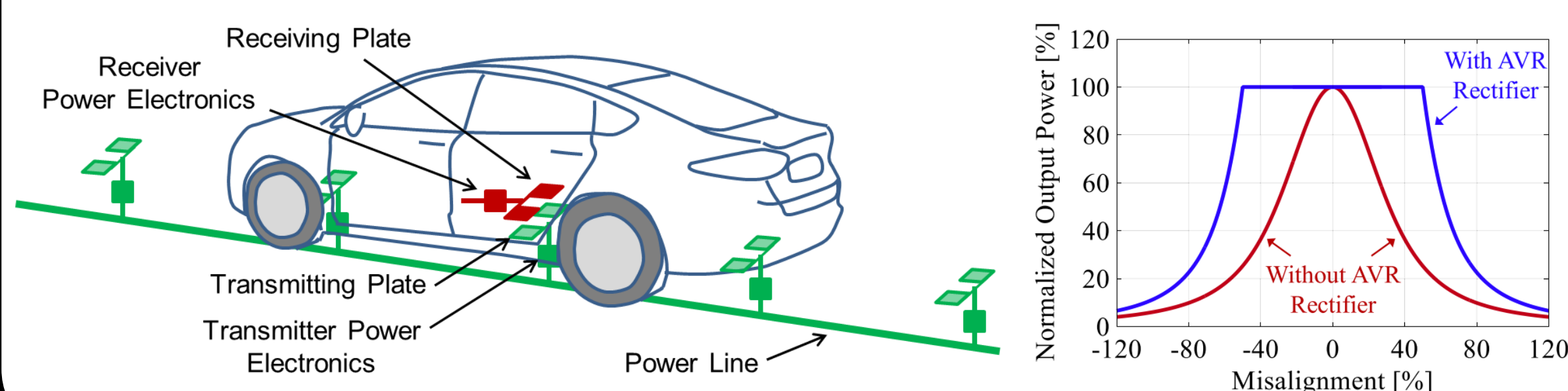
# Full State Feedback Controller for Dynamic Capacitive Wireless Power Transfer Systems

Ben Liao, Sophia Lin, Dheeraj Etta, Khurram K. Afridi

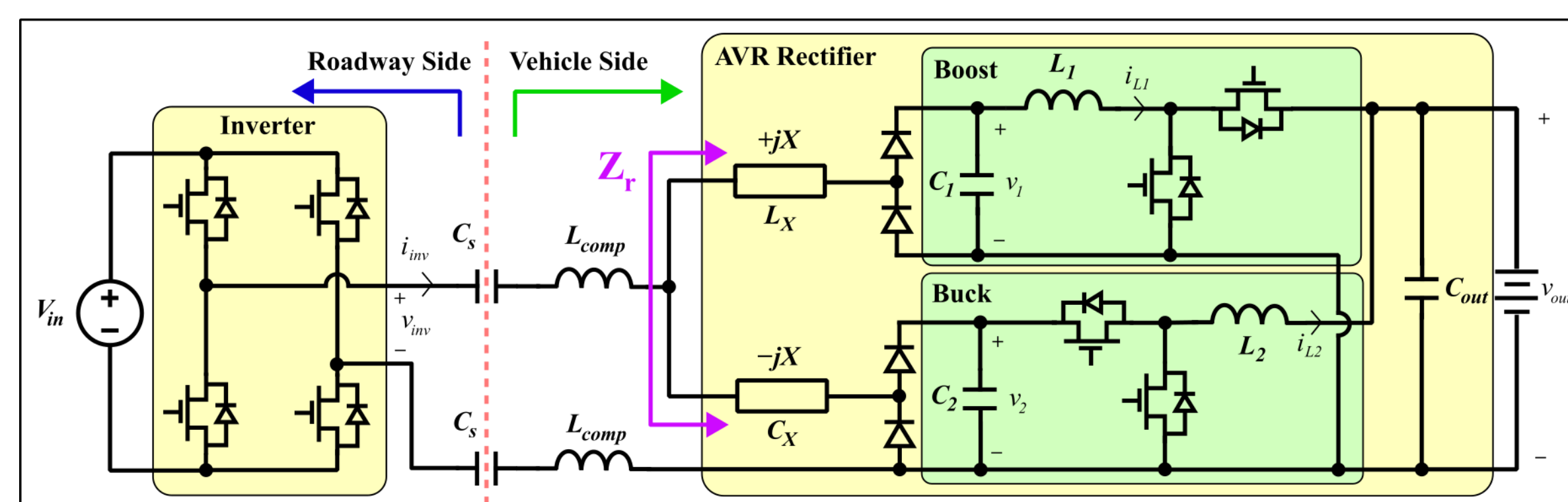


## Motivation

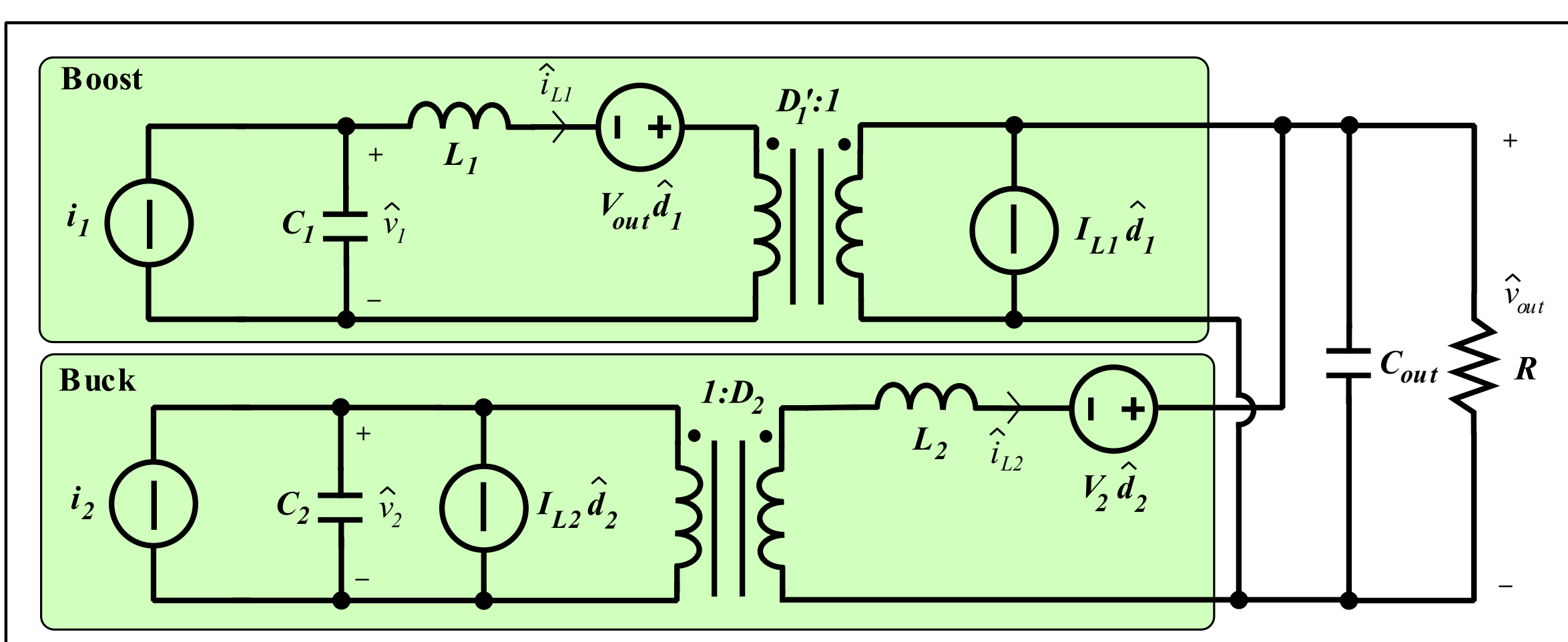
- For wireless power transfer (WPT) systems:
  - Capacitive:** cheaper, lighter, more robust
  - Dynamic:** infinite range, zero down-time, small batteries
- Must compensate high-Q resonant systems for misalignment-induced variation in coupling capacitance
- Active Variable Reactance (AVR) rectifier has these properties



## AVR Rectifier



- Provides continuously variable reactance while operating inverter at a fixed frequency
- Maintains constant output power and soft-switching of the inverter

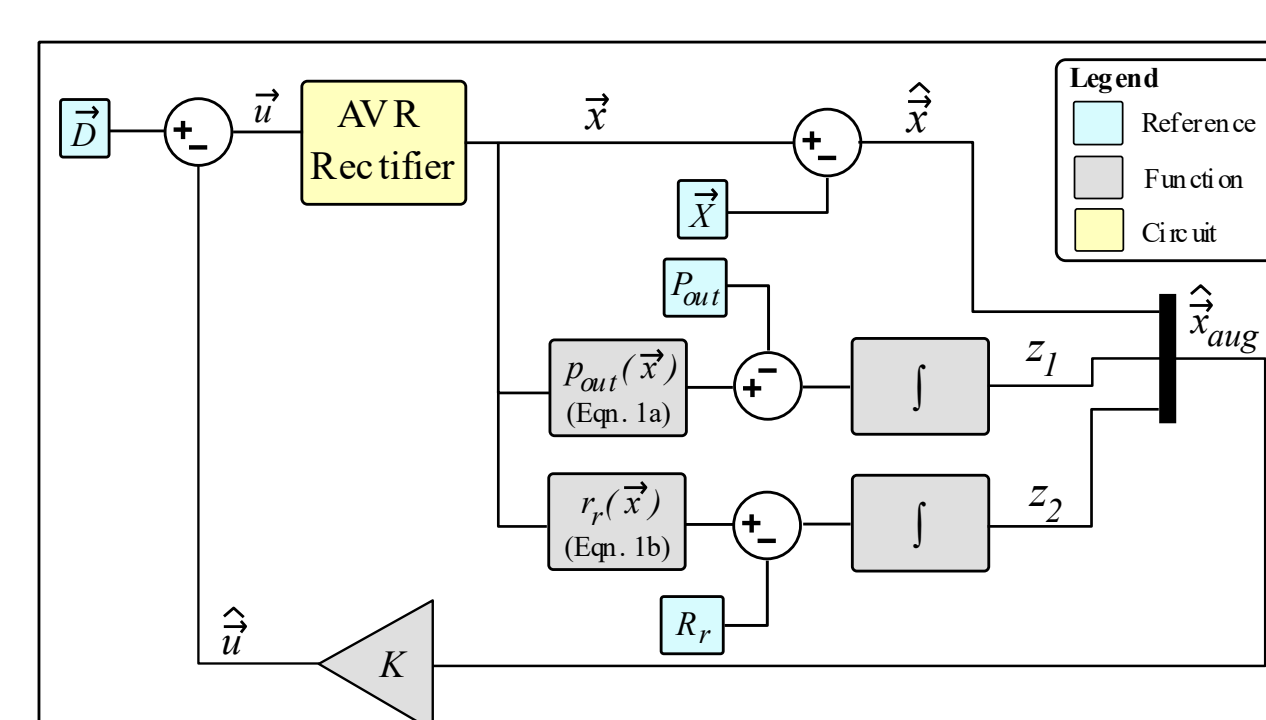


Linearized small-signal model of AVR rectifier

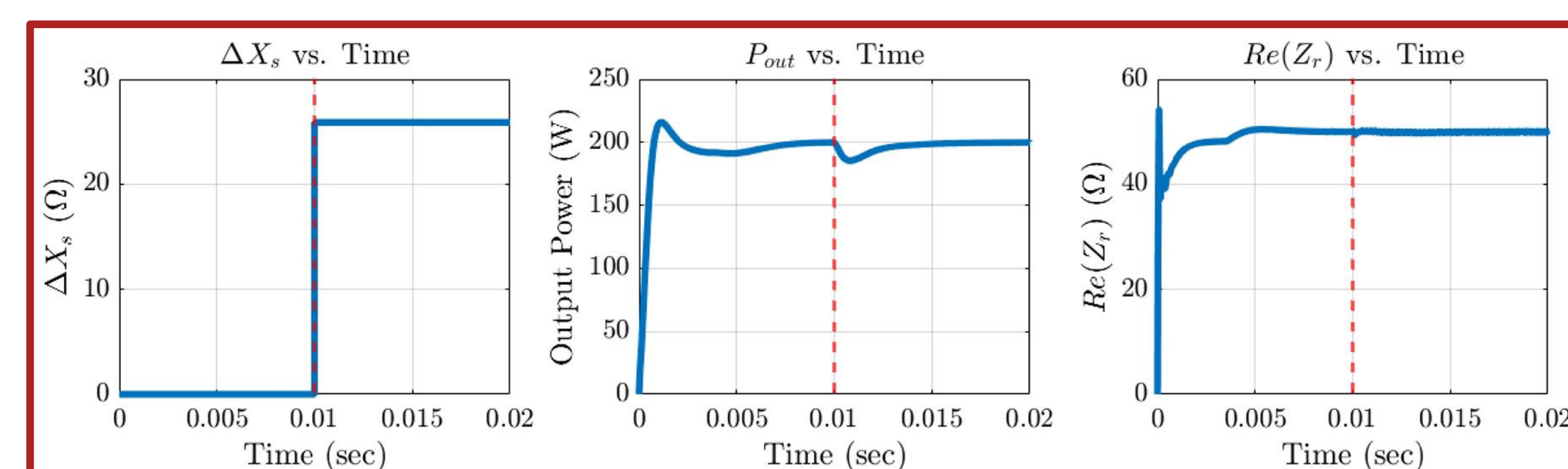
$$\frac{d}{dt} \begin{bmatrix} \hat{v}_{out} \\ \hat{v}_1 \\ \hat{v}_2 \\ \hat{i}_{L1} \\ \hat{i}_{L2} \\ \hat{z}_1 \\ \hat{z}_2 \end{bmatrix} = \begin{bmatrix} -\frac{1}{RC_{out}} & 0 & 0 & \frac{D'_1}{C_{out}} & \frac{1}{C_1} & 0 & 0 \\ 0 & 0 & 0 & -\frac{1}{C_1} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -\frac{D_2}{C_2} & 0 & 0 \\ -\frac{D'_1}{L_1} & \frac{1}{L_1} & 0 & 0 & 0 & 0 & 0 \\ -\frac{1}{L_2} & 0 & \frac{D_2}{L_2} & 0 & 0 & 0 & 0 \\ -\frac{\partial p_{out}}{\partial v_1} & -\frac{\partial p_{out}}{\partial v_2} & -\frac{\partial p_{out}}{\partial v_{out}} & -\frac{\partial p_{out}}{\partial i_{L1}} & -\frac{\partial p_{out}}{\partial i_{L2}} & 0 & 0 \\ -\frac{\partial r_1}{\partial v_{out}} & -\frac{\partial r_2}{\partial v_1} & -\frac{\partial r_2}{\partial v_2} & -\frac{\partial r_1}{\partial i_{L1}} & -\frac{\partial r_1}{\partial i_{L2}} & 0 & 0 \end{bmatrix} \begin{bmatrix} \hat{v}_{out} \\ \hat{v}_1 \\ \hat{v}_2 \\ \hat{i}_{L1} \\ \hat{i}_{L2} \\ \hat{z}_1 \\ \hat{z}_2 \end{bmatrix} + \begin{bmatrix} -\frac{I_{L1}}{C_{out}} & 0 \\ 0 & 0 \\ 0 & -\frac{I_{L2}}{C_2} \\ \frac{V_{out}}{L_1} & 0 \\ 0 & \frac{V_2}{L_2} \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \hat{d}_1 \\ \hat{d}_2 \end{bmatrix}$$

Augmented state-space model of AVR rectifier

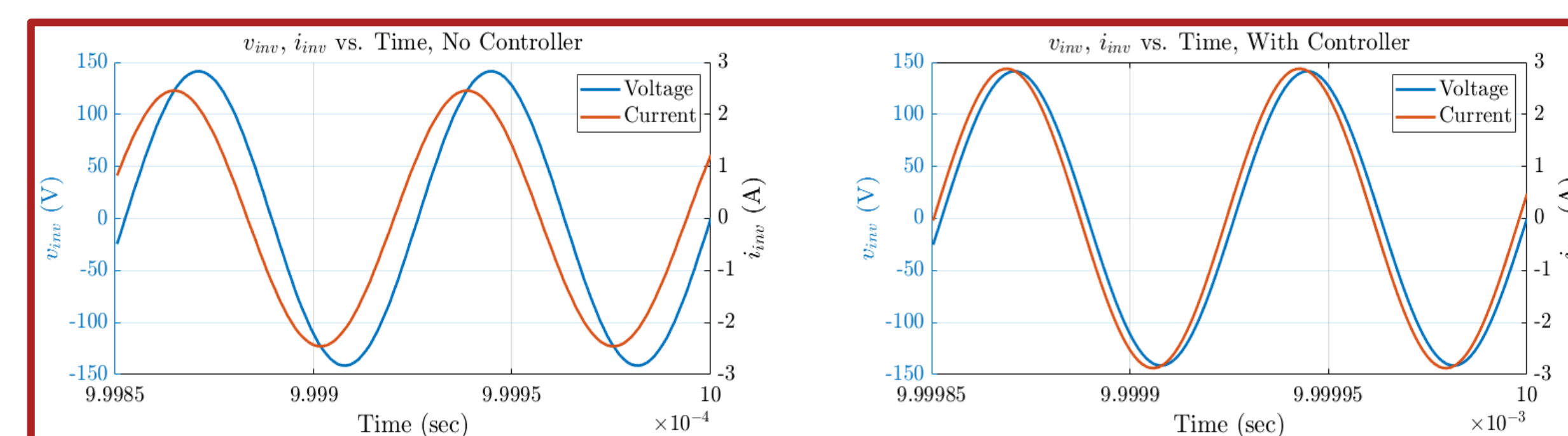
## Full State Feedback Controller



$$\vec{x} = \begin{bmatrix} V_{out} \\ V_1 \\ V_2 \\ I_{L1} \\ I_{L2} \end{bmatrix} \quad P_{out} = \text{nominal } P_{out} \\ R_r = \text{nominal } Re(Z_r) \\ K = \text{LQR gains} \\ \hat{u} = K * \hat{x}_{aug} \\ \vec{x} = \text{nominal values of } \vec{x} \\ \hat{x}_{aug} = \begin{bmatrix} \hat{x} \\ z_1 \\ z_2 \end{bmatrix} \quad \bar{D} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \\ \hat{u} = \begin{bmatrix} D_{Boost} \\ D_{Buck} \end{bmatrix}$$



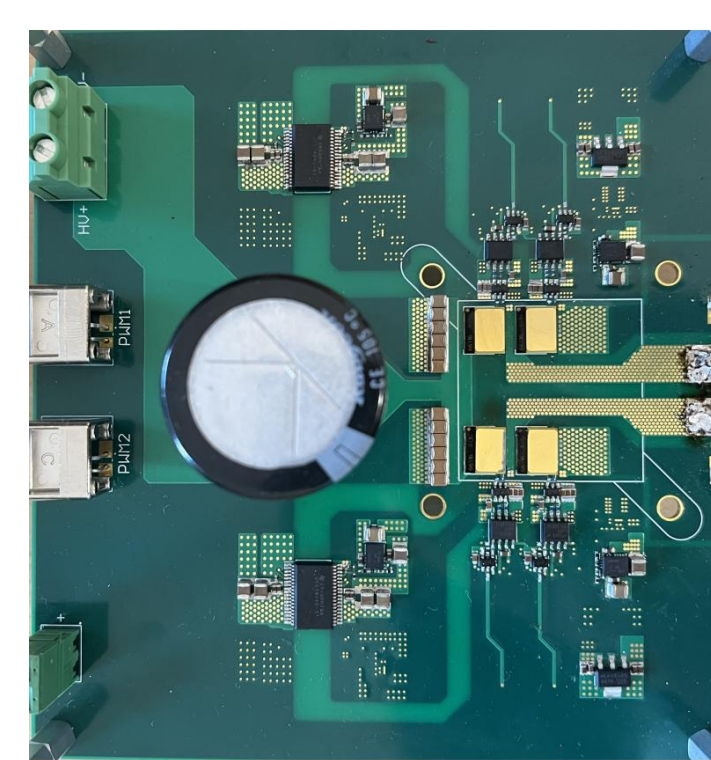
$P_{out}$  and  $Re(Z_r)$  Step Response



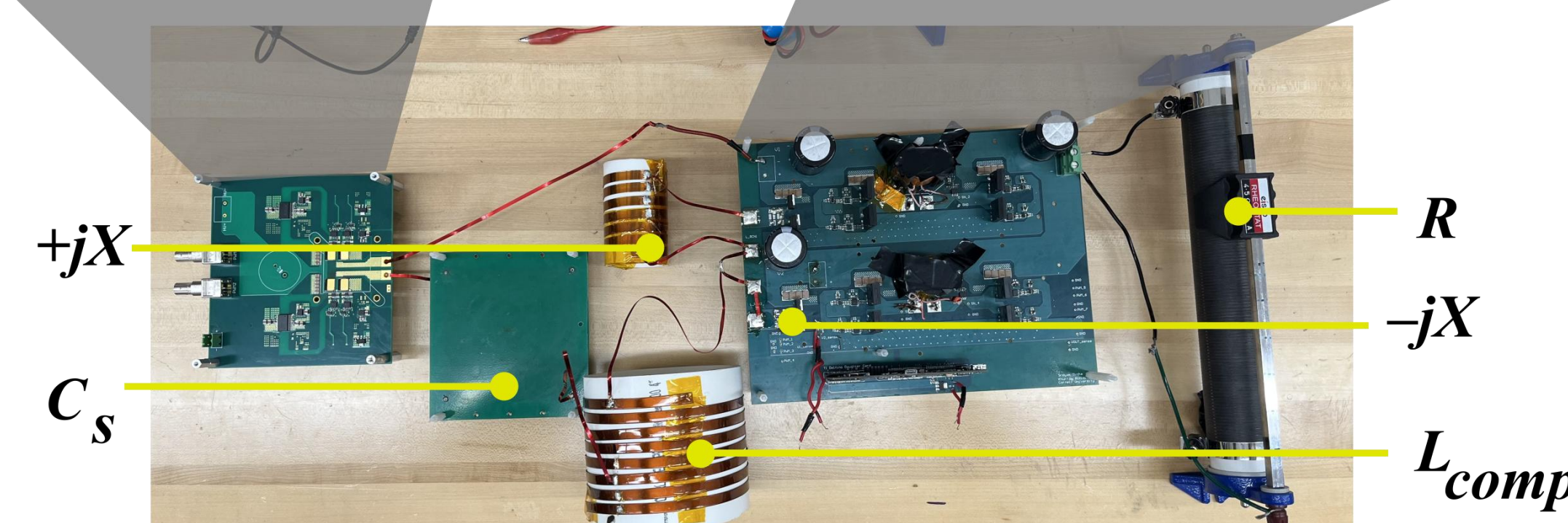
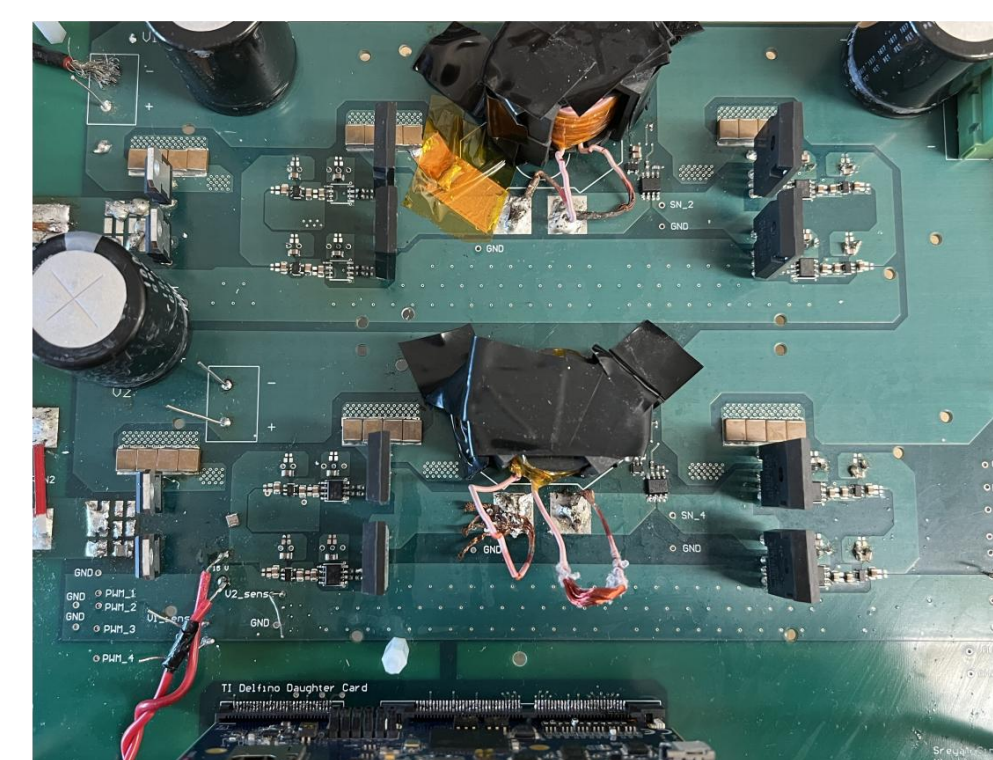
Phase shift between  $v_{inv}$  and  $i_{inv}$

## Hardware Prototype

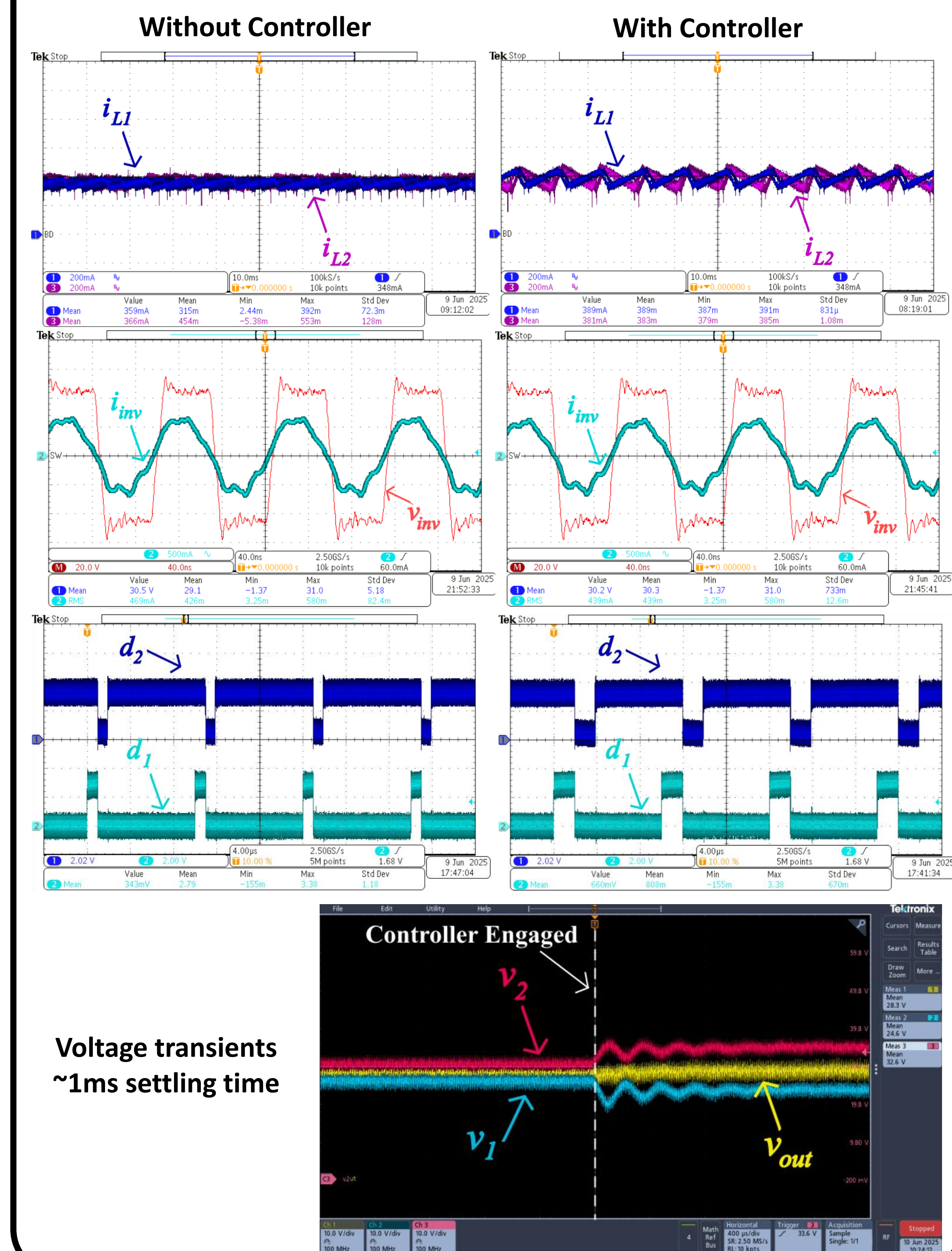
Inverter PCB



AVR Rectifier PCB



## Results



Voltage transients  
~1ms settling time

## Summary and Conclusions

- In dynamic settings, capacitive WPT systems will have variation in coupling capacitance, resulting in reduced overall power transfer
- AVR rectifier can be used to transfer nominal power at high efficiencies across changes in coupling capacitance
- Full-state feedback controller can adjust the duty ratios of the two dc-dc converters to regulate output power and enable ZVS
- Series-L-compensated capacitive WPT system with full-state feedback controller is tested in simulation
- 60 V, 25 W prototype used to validate proposed controller

### Selected References

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- [3] S. Sinha and K. K. Afridi, "Closed-loop control of a dynamic capacitive wireless power transfer system," in *2019 20th Workshop on Control and Modeling for Power Electronics (COMPEL)*, pp. 1–6, 2019.
- [4] J. C. Mayo-Maldonado et al., "State space modeling and control of the dc-dc multilevel boost converter," *2010 20th International Conference on Electronics Communications and Computers (CONIELECOMP)*, Cholula, Puebla, Mexico, 2010, pp. 232–236.