Conveyor Belt & Sunlight Monitoring
Embedded System Design, Lab 3

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2.1 Converyor Belt

```
' Conveyor-Belt.bs2
' {$STAMP BS2}
' {$PBASIC 2.5}
'----------------------Declare Constants---------------------------'
SHIFT_END  CON 0
CLEAR_JAM  CON 4
BOX_ALERT  CON 11
JAM_ALERT  CON 9
ACTIVE_LEVEL      CON 0
PHOTO_TRANSISTOR  CON 7
T_LIGHT_THRESHOLD CON 80
' (0.1uF || 10kOhm || photo-trans.) has max RC discharge time ~ 600 *(2us)
T_RC_CHARGE       CON 1
T_10_INCHES       CON 10
' Number of main loop iterations per 10 inch conveyor displacement
T_BLINK           CON 20
MAX_BOX_LENGTH    CON 4
MAX_GAP_LENGTH    CON 100
' MAX_ lengths are relative to the 10 inch unit length
MAX_EEPROM_SIZE   CON 4
NO_BOX       CON 0
BOX_PRESENT  CON 1
JAM_DETECTED CON 2
SHIFT_ENDED  CON 3

'------------------------Declare RAM Variables----------------------'
state VAR Nib
time  VAR Word
jam_cleared  VAR Bit
end_shift VAR Bit
box_sense  VAR Bit
ptran_time   VAR Word
blink_alarm VAR Bit

'------------------------------Start--------------------------------'
state = (1 << NO_BOX)
OUTS = $FFFF * (~ACTIVE_LEVEL)
DIRS = (1 << BOX_ALERT) | (1 << JAM_ALERT)

Main_Loop:
  '-------------------------Sense for Box----------------------------'
  ' Charge the capacitor for light measurement
  DIRS = DIRS | (1 << PHOTO_TRANSISTOR)
  OUTS = OUTS | (ACTIVE_LEVEL * (1 << PHOTO_TRANSISTOR))
  OUTS = OUTS & (~ ( (ACTIVE_LEVEL ^ 1) * (1 << PHOTO_TRANSISTOR)))
  PAUSE T_RC_CHARGE
  ' Discharge the capacitor and make binary light on/off decision
  RCTIME PHOTO_TRANSISTOR, ACTIVE_LEVEL , ptran_time
  box_sense = ptran_time / T_LIGHT_THRESHOLD
```

```
  '--------------------Read Pushbutton Inputs-----------------------'
  jam_cleared = ~(ACTIVE_LEVEL ^ ( (INS & (1 << CLEAR_JAM)) >> CLEAR_JAM))
  end_shift =   ~(ACTIVE_LEVEL ^ ( (INS & (1 << SHIFT_END)) >> SHIFT_END))

  '----------------------Set LED Outputs----------------------------'
  temp VAR Word
  temp = OUTS ^ (~($FFFF * ACTIVE_LEVEL))
  temp = temp | ((((state >> JAM_DETECTED)&1) << JAM_ALERT) * blink_alarm)
  temp = temp & (~(((((~state) >> JAM_DETECTED)&1) << JAM_ALERT))* blink_alarm)
  temp = temp |    (box_sense << BOX_ALERT)
  temp = temp & (~((~box_sense) << BOX_ALERT))
  OUTS = temp ^ (~($FFFF * ACTIVE_LEVEL))

  '--------------------Identifty the Current State------------------'
  No_Box_State:
    '---------------Identifty the Next State Transition-------------'
    IF (state <> (1 << NO_BOX)) THEN Box_Present_State
    IF (box_sense = 1) THEN No_Box_to_Box_Present
    IF (end_shift = 1) THEN No_Box_to_Shift_Ended
    IF (time > (T_10_INCHES * MAX_GAP_LENGTH)) THEN No_Box_to_Jam_Detected
    GOTO Continue
  Box_Present_State:
    '---------------Identifty the Next State Transition-------------'
    IF (state <> (1 << BOX_PRESENT)) THEN Jam_Detected_State
    IF (box_sense = 0) THEN Box_Present_to_No_Box
    IF (time > (T_10_INCHES * MAX_BOX_LENGTH)) THEN Box_Present_to_Jam_Detected
    GOTO Continue
  Jam_Detected_State:
    '---------------Identifty the Next State Transition-------------'
    IF (state <> (1 << JAM_DETECTED)) THEN Shift_Ended_State
    IF (jam_cleared = 1) THEN Jam_Detected_to_No_Box
    IF (end_shift = 1) THEN Jam_Detected_to_Shift_Ended
    IF (0 = (time // T_BLINK)) THEN Jam_Detected_to_Jam_Detected
    GOTO Continue
  Shift_Ended_State:
    '---------------Next State Transition is Automatic--------------'
    DEBUG "End of Shift Status Report:", CR
    READ 0, temp
    DEBUG "10 inch boxes: ", DEC temp, CR
    READ 4, temp
    DEBUG "Number of Jams: ", DEC temp, CR
    GOTO Shift_Ended_to_No_Box
'-----------------Iterate Time for Next Loop Iteration--------------'
Continue:
  time = time + 1
GOTO Main_Loop


'--------------------State Transition Subroutines-------------------'
No_Box_to_Box_Present:
  time = 0
  state = 1 << BOX_PRESENT
GOTO Main_Loop
```

```
No_Box_to_Shift_Ended:
Jam_Detected_to_Shift_Ended:
  state = 1 << SHIFT_ENDED
GOTO Main_Loop

No_Box_to_Jam_Detected:
Box_Present_to_Jam_Detected:
  DEBUG "Jam Detected, time=", DEC time, CR
  time = 0
  state = 1 << JAM_DETECTED
GOTO Main_Loop

Box_Present_to_No_Box:
  READ (time / T_10_INCHES), temp
  WRITE (time / T_10_INCHES), (temp + 1)
  time = 0
  state = 1 << NO_BOX
GOTO Main_Loop

Jam_Detected_to_No_Box:
  DEBUG "Jam Cleared by User", CR
  READ 4, temp
  WRITE 4, (temp + 1)
  IF (temp > MAX_EEPROM_SIZE) THEN Protect_Program_Memory
    WRITE (5 + (2*(temp + 1))), time
  Protect_Program_Memory:
  time = 0
  state = 1 << NO_BOX
GOTO Main_Loop

Shift_Ended_to_No_Box:
  FOR temp = 0 TO MAX_EEPROM_SIZE
    WRITE temp, 0
  NEXT
  time = 0
  state = 1 << NO_BOX
GOTO Main_Loop

Jam_Detected_to_Jam_Detected:
  blink_alarm = (blink_alarm ^ 1)
GOTO Continue
```

2.2 Sunshine Monitoring

```
' Sunshine-on-Planet-Alpha.bs2
' {$STAMP BS2}
' {$PBASIC 2.5}

SLEEP_TIME CON  900
CHARGE_TIME CON 10
MAX_DATAPOINTS CON 96
LED_PIN CON 15

DIRS = (1 << LED_PIN)

rc_time VAR Word
ram_index VAR Byte
eeprom_index VAR Word
restart_test VAR Byte

' Print Data from EEPROM
READ MAX_DATAPOINTS, eeprom_index
FOR ram_index = (eeprom_index + 1) TO (MAX_DATAPOINTS - 1)
  READ ram_index, rc_time
  DEBUG DEC3 (ram_index - (eeprom_index + 1)), 9, DEC3 rc_time, CR
NEXT
FOR ram_index = 0 TO eeprom_index
  READ ram_index, rc_time
  DEBUG DEC3 (ram_index + (MAX_DATAPOINTS - eeprom_index)), 9, DEC3 rc_time, CR
NEXT

' Ask User: Restart Test?
DEBUG "Restart Test? (y/n): "
DEBUGIN STR restart_test \1
DEBUG CR
IF (restart_test <> 121) THEN Break
  WRITE MAX_DATAPOINTS, 0
Break:

DO
  LOW LED_PIN
  PAUSE CHARGE_TIME
  RCTIME LED_PIN, 0, rc_time
  rc_time = (rc_time >> 8)
  READ MAX_DATAPOINTS, eeprom_index
  DEBUG "Writing ", DEC rc_time, " to EEPROM ", DEC (eeprom_index // MAX_DATAPOINTS), CR
  WRITE (eeprom_index // MAX_DATAPOINTS), rc_time
  WRITE MAX_DATAPOINTS, ((eeprom_index + 1) // MAX_DATAPOINTS)

  SLEEP SLEEP_TIME
LOOP
```