

# ME 475/575 Control Systems Analysis

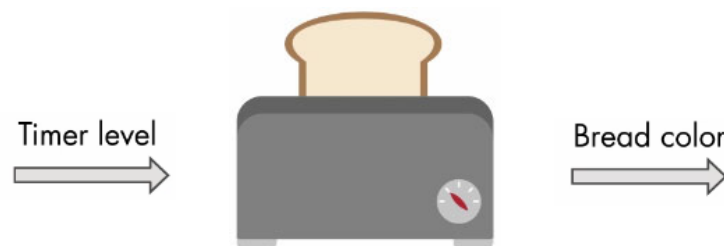
*Professor Xiangrong Shen*  
*SERC 3009: 348-6743*  
*xshen@eng.ua.edu*

1

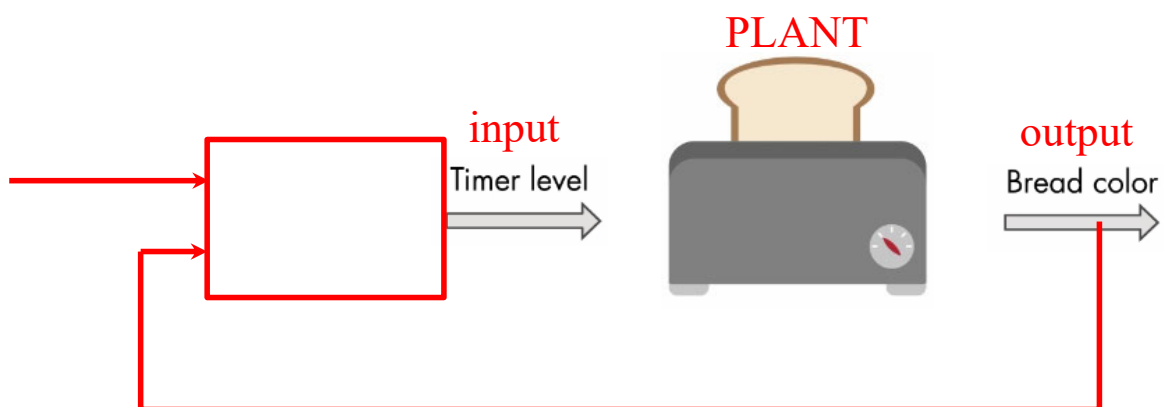
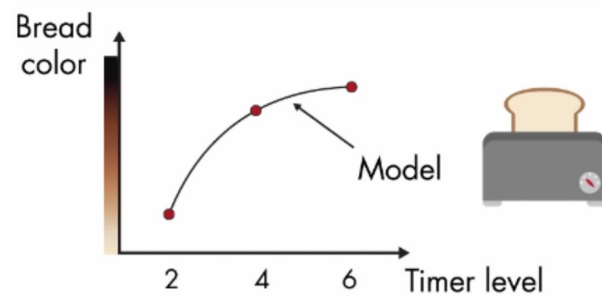
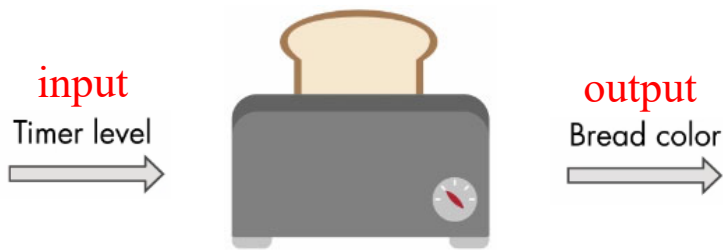
## 1. Introduction

Classical and modern feedback-control system design and analysis; and block diagrams, state variables, stability, root locus, and computerized analysis. Includes an introduction to modern control techniques.

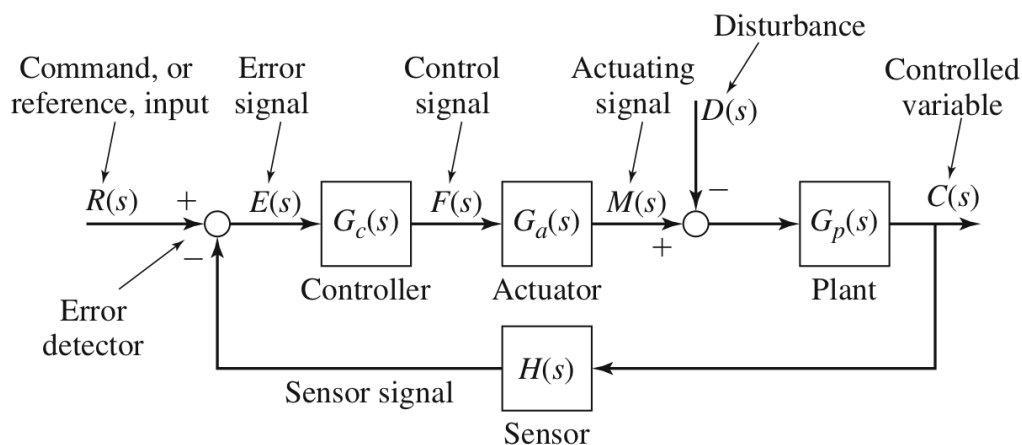
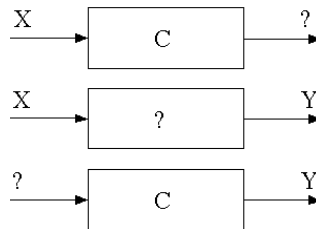
1. *Introduction*
2. *Review: Modeling in the Frequency Domain*
3. *Review: System Response in the Time Domain*
4. *Feedback and PID Controls*
5. *Root Locus Techniques*
6. *Control System Design via Root Locus*
7. *Control System Design via Frequency Response Techniques*
8. *State Space Representation of Systems*
9. *Control System Design via State Space Method*



**Find a proper input to obtain the desired output!**

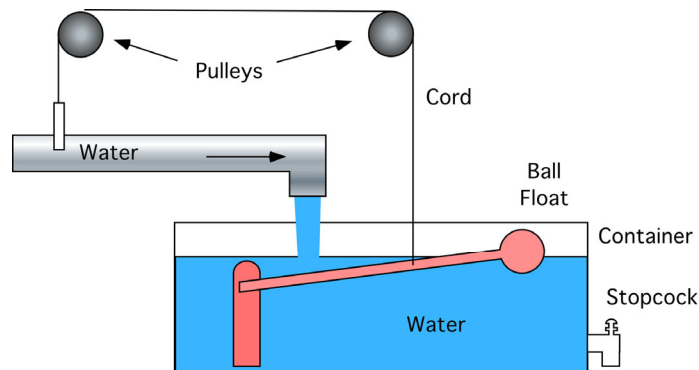


1. **Control** - the process of causing a system variable to conform to some desired value called a reference value
2. **Feedback control** - process of measuring the controlled variable and using that information to influence the controlled variable by feedback
3. **Areas of focus**
  - 1) \_\_\_\_\_: to find the system output when the system and the input to the system are known.
  - 2) \_\_\_\_\_: to find the system itself when the input and output of the system are known.
  - 3) \_\_\_\_\_: to find the shape input to the system when a desired system output is known.



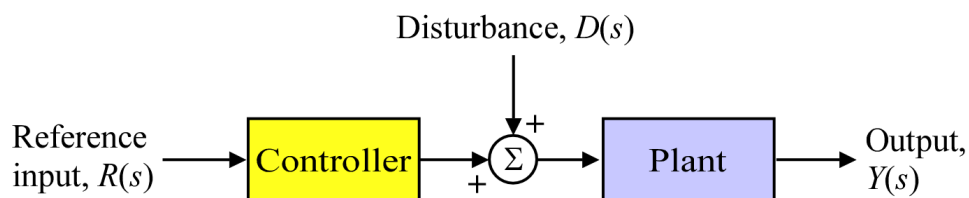
1. \_\_\_\_\_: system whose output variable is to be controlled.
2. \_\_\_\_\_: a logic element that compares the reference signal with the measurement of the output and decides what should be done.
3. \_\_\_\_\_: produces physical measures (force, torque, pressure, or heat) to influence the plant.
4. \_\_\_\_\_: measures controlled output (sensor output)

- A control system can be realized purely mechanically.



1. Plant - Container
2. Sensor - Ball Float Mechanism
3. Actuator - Stopper

1. Open loop: \_\_\_\_\_



2. Closed loop: \_\_\_\_\_

