

# Sparse grids Matlab kit

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# Outline

- 1 Basic data structure
- 2 Main features
- 3 Numerical examples
- 4 Conclusions

# Contributors, release, general comments

- Lorenzo Tamellini, Fabio Nobile

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- Some ad-hoc features and integration with **parallel toolbox** gives nonetheless reasonable speed
- Geared towards **UQ**, but flexible enough for other purposes
- Aim of the talk: give rough idea of structure, show by examples features and ease of use

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1 Basic data structure

2 Main features

3 Numerical examples

4 Conclusions

## Backbone: combination technique & “reduced” sparse grid

```
N=2;  
knots=@(n) knots_CC(n,-1,1,'nonprob');  
w = 3;  
m = @lev2knots_doubling;  
Ifun = @(i) sum(i-1);  
S = smolyak_grid(N,w,knots,m,Ifun);
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- $S = \sum_{i \in \mathcal{I}} G_i \otimes_{n=1}^N \mathcal{U}^{m(i_n)}$

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- $S = \sum_{i \in \mathcal{I}} G_i \otimes_{n=1}^N \mathcal{U}^{m(i_n)}$
- $m(i) = "2^{i-1} + 1", \quad \mathcal{U}^{m(i_n)} = \text{interpolant on } m(i_n) \text{ Clenshaw-Cts pts}$

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- $S = \sum_{\mathbf{i} \in \mathcal{I}} G_{\mathbf{i}} \otimes_{n=1}^N \mathcal{U}^{m(i_n)}$
- $m(i) = "2^{i-1} + 1"$ ,  $\mathcal{U}^{m(i_n)}$  = interpolant on  $m(i_n)$  Clenshaw–Cts pts
- $\mathcal{I} = \left\{ \mathbf{i} \in \mathbb{N}_+^N : \sum_{n=1}^N (i_n - 1) \leq w \right\}$



## Backbone: combination technique & “reduced” sparse grid

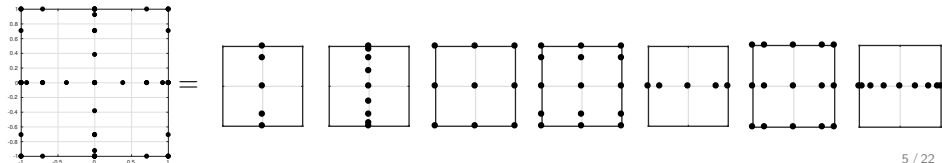
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```

```
>> S  
S =  
1 x 7 struct array with fields:  
knots  
weights  
size  
knots_per_dim  
m  
coeff  
idx
```

# Backbone: combination technique & “reduced” sparse grid

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Ifun = @(i) sum(i-1);  
S = smolyak_grid(N,w,knots,m,Ifun);
```

```
>> S(1)  
ans =  
struct with fields:  
  
    knots: [2x5 double] % points are always column vectors  
  weights: [-0.1333 -1.0667 -1.6000 -1.0667 -0.1333]  
    size: 5  
knots_per_dim: {[0] [1 0.7071 6.1232e-17 -0.7071 -1]}  
        m: [1 5]  
    coeff: -1  
    idx: [1 3] %multiidx are always row vectors
```

## Backbone: combination technique & “reduced” sparse grid

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```

```
>> Sr = reduce_sparse_grid(S)  
Sr =
```

struct with fields:

```
    knots: [2x29 double]  
        m: [29x1 double]  
weights: [1x29 double]  
        n: [67x1 double]  
    size: 29
```

# Backbone: combination technique & “reduced” sparse grid

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S = smolyak_grid(N,w,knots,m,Ifun);
```

```
>> Sr = reduce_sparse_grid(S) % robust to numerical noise  
                                % (default tol 1e-14)  
  
Sr =  
  
struct with fields:  
  
    knots: [2x29 double]  
        m: [29x1 double] % map from Sr.knots to [S.knots]  
weights: [1x29 double]  
        n: [67x1 double] % map from [S.knots] to Sr.knots  
    size: 29             % nb of points in the sparse grids
```

## Sparse grids “ingredients”: nodes, $m$ , $\mathcal{I}$

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- `[x,w]=knots_CC(n,a,b) %Clenshaw-Curtis`

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- `[x,w]=knots_CC(n,a,b) %Clenshaw-Curtis`
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- `[x,w]=knots_leja(n,a,b,'line')`

$$x_1 = b$$

$$x_2 = a$$

$$x_3 = (a + b)/2$$

$$x_n = \operatorname{argmax}_{[a,b]} \prod_{k=1}^{n-1} (x - x_k)$$

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- `[x,w]=knots_leja(n,a,b,'sym_line')`

$$x_1 = b$$

$$x_2 = a$$

$$x_3 = (a + b)/2$$

$$x_{2n} = \operatorname{argmax}_{[a,b]} \prod_{k=1}^{2n-1} (x - x_k)$$

$$x_{2n+1} = \text{symmetric of } x_{2n} \text{ wrt } (a + b)/2$$

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compute Leja pts on the complex unit ball, and project on the real line

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- `[x,w]=knots_gaussian(n,mi,sigma)` %Gauss-Hermite

for gaussian weights with mean  $\mu$  and st. dev.  $\sigma$

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- `[x,w]=knots_gaussian(n,mi,sigma)` %Gauss-Hermite
- `[x,w]=knots_kpn(n)` %Kronrod Patteron Normal, Genz-Keister

Tabulated sequence of nested extensions of  $(n+1)$  Gauss-Hermite with maximal exactness degree:  $m = 1, 3, 9, 19, 35$

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- `[x,w]=knots_normal_leja(n) %Narayan-Jakeman`

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- $m = \text{lev2knots\_lin}(i)$

$$m(i) = i$$

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```

- $m = \text{lev2knots\_lin}(i)$
- $m = \text{lev2knots\_2step}(i)$

$$m(i) = 2(i - 1) + 1$$



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$$m(1) = 1, m(i) = 2^{i-1} + 1$$

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it is possible to specify different `m` and `knots` in each direction

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presets for  $m$ ,  $Ifun$  are available:

```
[m,Ifun]=define_functions_for_rule(<'TP','TD','HC','SM'>,<N,g>)
```

where for  $g \in \mathbb{R}_+^N$ ,  $w \in \mathbb{N}$

- **'TP'** = tensor prod.,  $\mathcal{I} = \{i \in \mathbb{N}_+^N : \max_n g_n(i_n - 1) \leq w\}$ ,  $m(i) = i$

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- **'HC'** = hyperbolic cross,  $\mathcal{I} = \{\mathbf{i} \in \mathbb{N}_+^N : \prod_{n=1}^N i_n^{g_n} \leq w\}$ ,  $m(i) = i$

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- **'HC'** = hyperbolic cross,  $\mathcal{I} = \{\mathbf{i} \in \mathbb{N}_+^N : \prod_{n=1}^N i_n^{g_n} \leq w\}$ ,  $m(i) = i$
- **'SM'** = Smolyak,  $\mathcal{I} = \{\mathbf{i} \in \mathbb{N}_+^N : \sum_{n=1}^N g_n(i_n - 1) \leq w\}$ ,  $m(i) = 2^{i-1} + 1$

## Sparse grids “ingredients”: nodes, $m$ , $\mathcal{I}$

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Ifun = @(i) sum(i-1);  
S = smolyak_grid(N,w,knots,m,Ifun);
```

It is also possible to define sparse grids directly by a multi-idx set

```
% ex. 1) 'hand-typed' set  
C=[1 1; 1 3; 4 1]; % non downward-closed set  
[adm,C_compl] = check_set_admissibility(C); % fix C  
S_M = smolyak_grid_multiidx_set(C_compl,knots,m);  
  
%ex. 2) create a box in  $N^2$  with top-right corner at [2 3]  
jj=[2 3];  
D=multiidx_box_set([2 3],1);  
T_M = smolyak_grid_multiidx_set(D,knots,m);
```



# Outline

1 Basic data structure

**2 Main features**

3 Numerical examples

4 Conclusions

# Main functions

```
f=@(x) x.^2; %vector-valued function
N=2; w=3;
S=smolyak_grid(N,w,@(n) knots_uniform(n,-1,1),@lev2knots_lin);
Sr= reduce_sparse_grid(S);
```

# Main functions

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- `ev_f = evaluate_on_sparse_grid(f, Sr)`

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can **recycle evaluations** from previous results if available (regardless of nestedness)

```
ev_f = evaluate_on_sparse_grid(f,S,Sr,ev_f_old,S_old,Sr_old)
```

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- `ev_f = evaluate_on_sparse_grid(f,Sr)`

evaluate `f` in **parallel** if more than `X` evals are required, uses **Matlab parallel toolbox**

```
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```

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same features as `evaluate`

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`P` is a matrix of eval. points (stored as columns)



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      - for **nested** points: identical to max between sparse grid and true fun.
      - works for **non-nested** points too
      - over the last added tensor grid

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the algorithm starts with  $N_{curr} = N_b \text{ dim.}$ ; as soon as points are placed in one dim., a new one is taken into account, i.e.,  $N_{curr} = N_{curr} + 1$ .  
In this way, there are always  $N_b \text{ dim.}$  whose “initial profit” is computed but along which no point is placed

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  - ▶ a **buffer** of  $N_b$  “explored but unused variables” can be set
  - ▶ support **vector-valued functions**, appropriate profits can be set

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Compare as much as possible indices instead of coordinates, for efficiency

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  - ▶ Converts a sparse grid into its **equivalent Polynomial Chaos Exp.**
  - ▶ **Idea:** For each tensor grid in the combination technique, compute the equivalent PCE by solving a **Vandermonde system**



# Main functions

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  - ▶ **Idea:** For each tensor grid in the combination technique, compute the equivalent PCE by solving a **Vandermonde system**
  - ▶ Vandermonde matrix is orthogonal for Gaussian quadrature points
  - ▶ several orthogonal polynomials: **'Legendre', 'Hermite', 'Chebyshev'**

# Outline

1 Basic data structure

2 Main features

**3 Numerical examples**

4 Conclusions

# Examples of applications

- ① Convergence of sparse grids approximation of lognormal problem:
  - ▶ `adapt_sparse_grid` with non-nested knots on unbounded domains
  - ▶ `smolyak_grid_multiidx_set`
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## ① Convergence of sparse grids approximation of lognormal problem:

- ▶ `adapt_sparse_grid` with non-nested knots on unbounded domains
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## ② More on geochemical compaction

- ▶ `convert_to_modal`
- ▶ very easy connection with built-in Matlab routines (`fminsearch`, `polyder`)

## Ex. 1) Elliptic PDE with lognormal diffusion coefficient

$$\left\{ \begin{array}{l} -\frac{d}{dx} \left( a(x, \xi) \frac{d}{dx} u(x, \xi) \right) = 0.03 \sin(2\pi x), \quad u(0, \xi) = u(1, \xi) = 0 \\ \log a(x, \xi) = 0.1 \sum_{m=1}^{\infty} \underbrace{\frac{\sqrt{2}}{(\pi m)^q} \sin(m\pi x)}_{=: \phi_m(x)} \xi_m, \end{array} \right. \quad q \geq 1, \text{ smoothed Brownian bridge}$$

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## Convergence Theorem

- Under assumptions on  $a(x, \xi)$  and knots,  $\exists$  a multiidx set  $\Lambda_N$  with  $|\Lambda_N| = N$  st

$$\|u - U_{\Lambda_N} u\|_{L^2_\mu} \leq CN^{-(q-1.5)} \leq C|\Xi_{\Lambda_N}|^{-\left(\frac{q-1.5}{2}\right)}.$$



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- technical assumptions on knots proved for Gauss–Hermite knots (so far).

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```
% code snippet, a-priori heuristic
Lambda = buildLambdaPrior(..);
for iter = 1:P
    C = Lambda(1:P, :);
    C = sortrows(C);
    S = smolyak_grid_multiidx_set(C, ..);
    Sr = reduce_sparse_grid(S);
    f_grid = evaluate_on_sparse_grid(f, S, Sr, evals_old, ..);
    evals_old = f_grid;
    err = ... % calls interpolate_on_sparse_grid over an MC sample
end
```

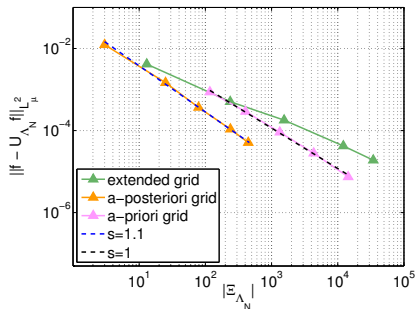


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```
% code snippet, a-posteriori heuristic
f = @(y) sol(a_coef(y));
controls.op_vect = @(A,B) H1normALL(A-B); % profit for functions
controls.var_buffer_size = 5;
for nb_pts = [10 100 1000..]
    controls.max_pts = nb_pts;
    adapt = adapt_sparse_grid(f,dim,...,prev_adapt,controls);
    prev_adapt = adapt;
    err = .. % calls interpolate_on_sparse_grid over an MC sample
end
```

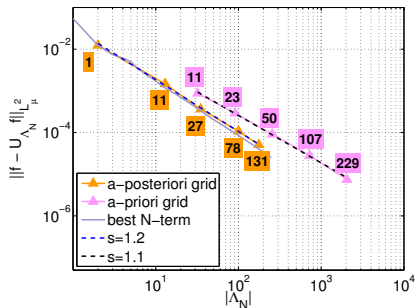
convergence wrt  $|\Xi_{\Lambda_N}|$



$q = 2$   
expect  $s = 0.25$ ;  
a-priori  $s = 1.0$ ;  
a-posteriori  $s = 1.1$

- Extended grid = a-posteriori with evaluations in the neighbourhood
- Expected rate smaller than observed:
  - summability argument could be improved
  - bound between number of elements and points not sharp

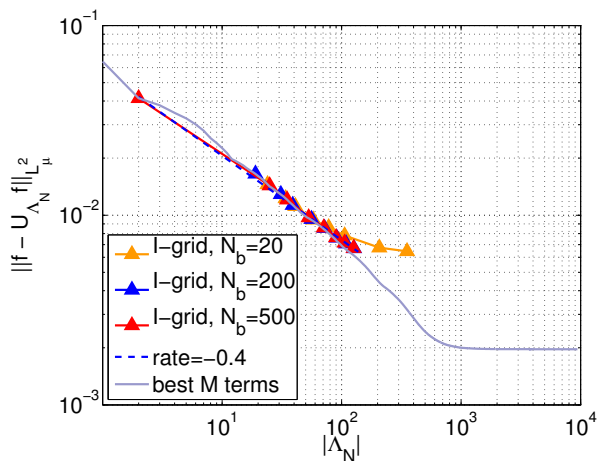
## convergence wrt $|\Lambda_N|$



$q = 2$   
expect  $s = 0.5$ ;  
a-priori  $s = 1.1$ ;  
a-posteriori  $s = 1.2$

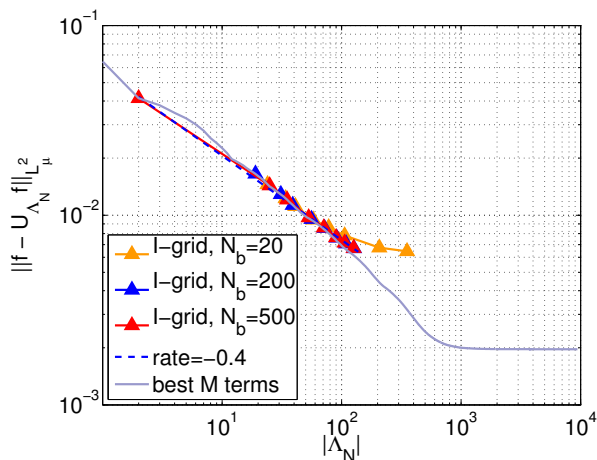
- Labels show the number of activated random variables
- Similar rate to before  $\Rightarrow$  growth of points linear in  $|\Lambda_N|$
- best- $N$ -terms obtained by converting sparse grid into Hermite polynomials with **convert\_to\_modal** and sorting the coefficients

# The importance of the buffer size $N_b$



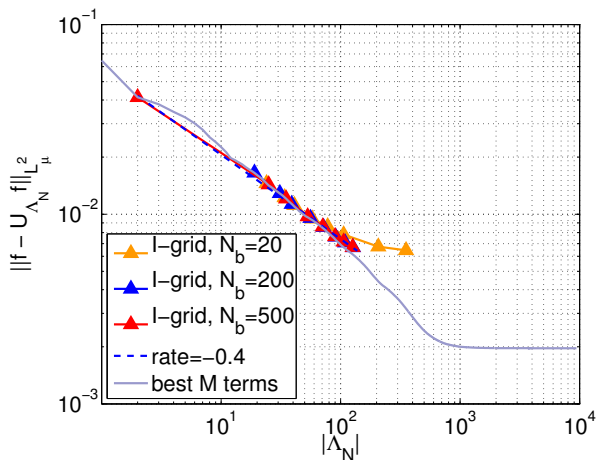
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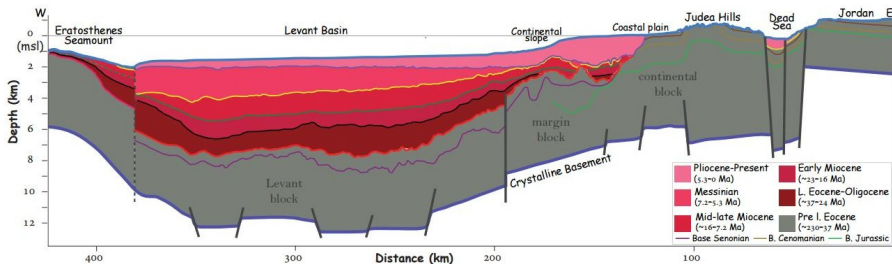
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- a-posteriori grid departs from best-M-terms: **unsignificant modes** have been added to the a-posteriori grid.

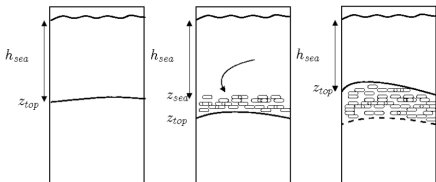
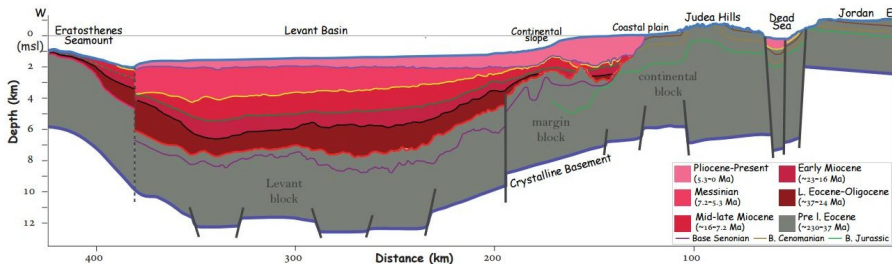
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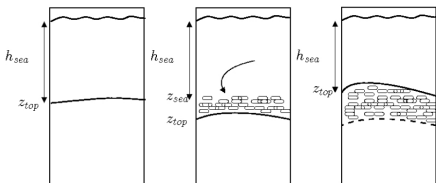
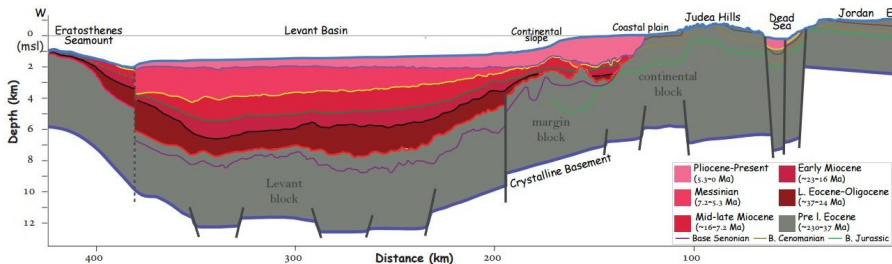


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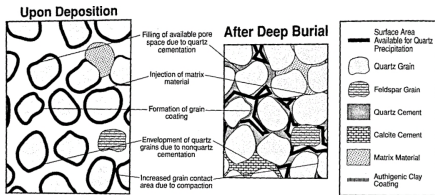


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As temperature, increase chemical reactions which glue grains together are triggered (quartz precipitation)

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- Underlying fundamental question: is it better to have porosity or temperature data?

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Then, a MLE procedure to estimate  $\mathbf{y}, \sigma, s$  is

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- ▶  $C = \sigma^2 (D_y \phi^\top D_y \phi + \lambda D_y T^\top D_y T)^{-1}$
- ▶  $D_y \phi, D_y T$  Jacobian matrices of  $\phi$  and  $T$  wrt to  $\mathbf{y}$ , evaluated at  $\mathbf{y}^*$  (sensitivity)

```
for i=1:nb_z_nodes
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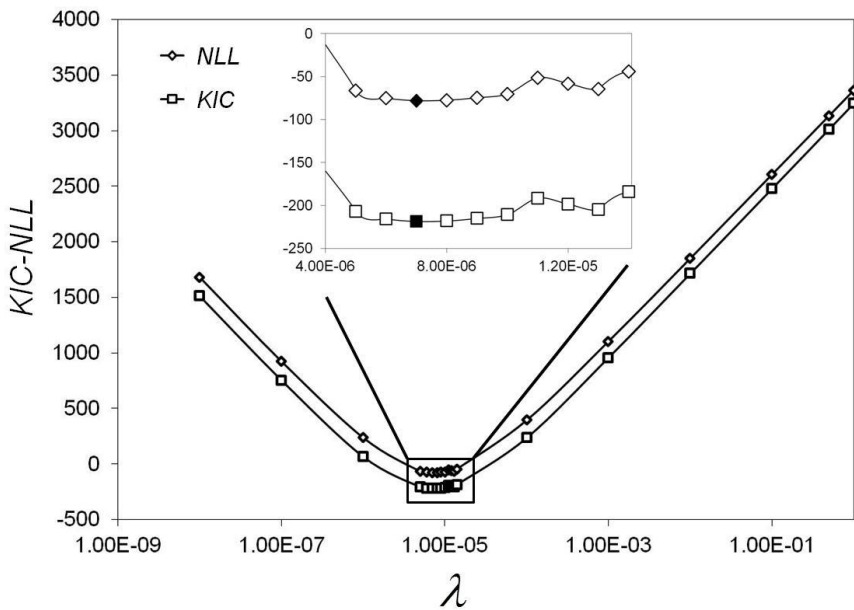
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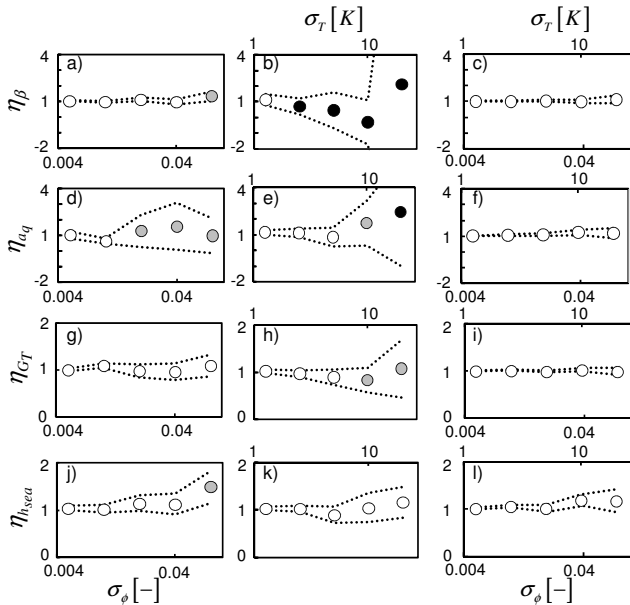
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**Choose**  $(\sigma, s, \mathbf{y})$  that yield the minimum  $KIC$



# Results



# Outline

- 1 Basic data structure
- 2 Main features
- 3 Numerical examples
- 4 Conclusions**

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**Thanks for your attention**