

DT Filters

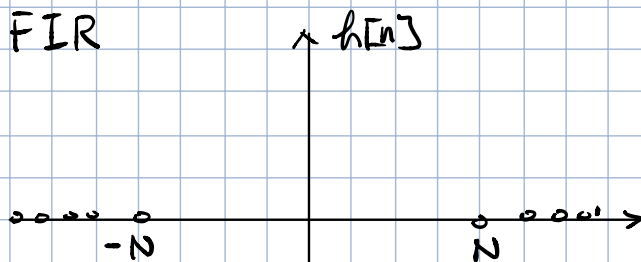
③ Non-recursive filters = The output depends on only the input, not previous outputs

Causal: $y[n] = \sum_{k=0}^N b_k x[n-k]$ ← The only filter that can be used for real-time applications

Non-Causal: $y[n] = \sum_{k=-M}^N b_k x[n-k]$

Anti-causal: $y[n] = \sum_{k=-M}^{-1} b_k x[n-k]$

The impulse response of a non-recursive filter has a finite length: FIR

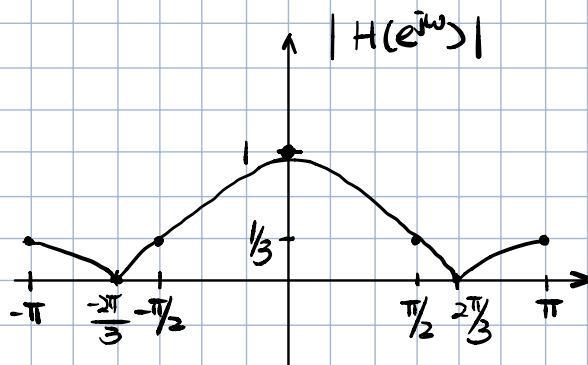


⊛ Example: Averaging system:

$$y[n] = \frac{1}{3} [x[n-1] + x[n] + x[n+1]]$$

$$h[n] = \frac{1}{3} [\delta[n-1] + \delta[n] + \delta[n+1]]$$

$$\begin{aligned} \delta[n] &\xleftrightarrow{f} 1, \\ x[n-n_0] &\xleftrightarrow{f} e^{-j\omega n_0} X(e^{j\omega}) \end{aligned} \Rightarrow H(e^{j\omega}) = \frac{1}{3} (e^{-j\omega} + 1 + e^{j\omega}) = \frac{1}{3} (1 + 2\cos(\omega))$$



For better freq. response, increase the length of the averaging window.

$$y[n] = \frac{1}{2N+1} \sum_{k=-N}^N x[n-k]$$

$$h[n] = \frac{1}{2N+1} \sum_{k=-N}^N \delta[n-k] \rightarrow H(e^{j\omega}) = \frac{1}{2N+1} \sum_{k=-N}^N e^{-j\omega k}$$

$$m = k+N \quad k = m-N$$

$$H(e^{j\omega}) = \frac{1}{2N+1} \sum_{m=0}^{2N} e^{j\omega(m-N)}$$

$$= \frac{e^{j\omega N}}{2N+1} \sum_{m=0}^{2N} e^{-j\omega m}$$

$$= \frac{e^{j\omega N}}{2N+1} \frac{1 - e^{-j\omega(2N+1)}}{1 - e^{-j\omega}}$$

$$= \frac{\cancel{e^{j\omega N}}}{2N+1} \times \frac{\cancel{e^{-j\omega \frac{2N+1}{2}}}}{\cancel{e^{-j\omega \frac{1}{2}}}} \times \frac{e^{j\omega \frac{2N+1}{2}} - e^{-j\omega \frac{2N+1}{2}}}{e^{j\omega \frac{1}{2}} - e^{-j\omega \frac{1}{2}}}$$

$$= \frac{1}{2N+1} \frac{\sin((2N+1)\omega/2)}{\sin(\omega/2)}$$

$$\rightarrow N=4, H_4(e^{j\omega}) = \frac{1}{9} \frac{\sin(9\omega/2)}{\sin(\omega/2)}$$

$$\rightarrow N=8, H_8(e^{j\omega}) = \frac{1}{17} \frac{\sin(17\omega/2)}{\sin(\omega/2)}$$

$$\omega = \pi: H_1(e^{j\pi}) = \frac{1}{3}$$

$$H_4(e^{j\pi}) = \frac{1}{9}$$

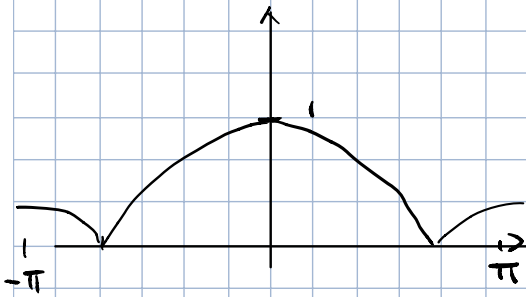
$$H_8(e^{j\pi}) = \frac{1}{17}$$

for $0 < \omega < \pi$ $H_1(e^{j\omega}) = 0$ for $\omega = \frac{2\pi}{3}$

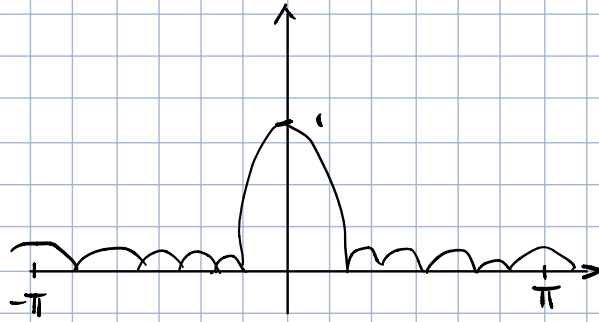
for $0 < \omega < \pi$ $H_4(e^{j\omega}) = 0$ for $\omega = \frac{2\pi}{9}, \frac{4\pi}{9}, \frac{6\pi}{9}, \frac{8\pi}{9}$

$H_8(e^{j\omega}) = 0$ for $\omega = \frac{2\pi}{17}, \frac{4\pi}{17}, \frac{6\pi}{17}, \frac{8\pi}{17}, \dots, \frac{16\pi}{17}$

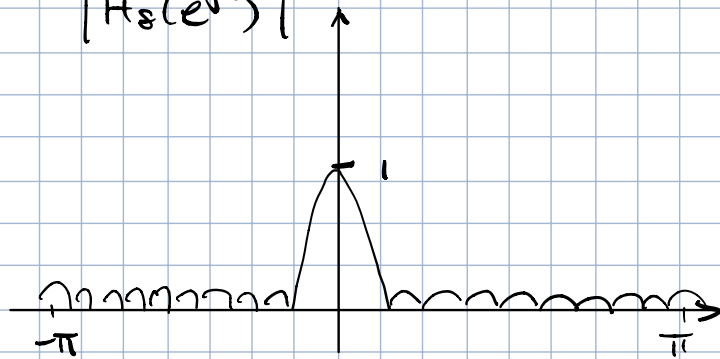
$|H_1(e^{j\omega})|$



$|H_4(e^{j\omega})|$



$|H_8(e^{j\omega})|$



⊗ High-pass filter

$$y[n] = \frac{1}{2} x[n] - \frac{1}{2} x[n-1]$$

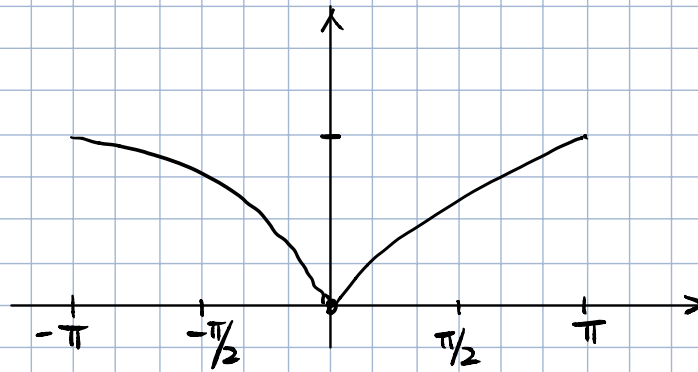
$$h[n] = \frac{1}{2} \delta[n] - \frac{1}{2} \delta[n-1]$$

$$H(e^{j\omega}) = \frac{1}{2} - \frac{1}{2} e^{-j\omega} = \frac{1}{2} (1 - e^{-j\omega}) = \frac{e^{-j\omega/2}}{2} (e^{j\omega/2} - e^{-j\omega/2})$$

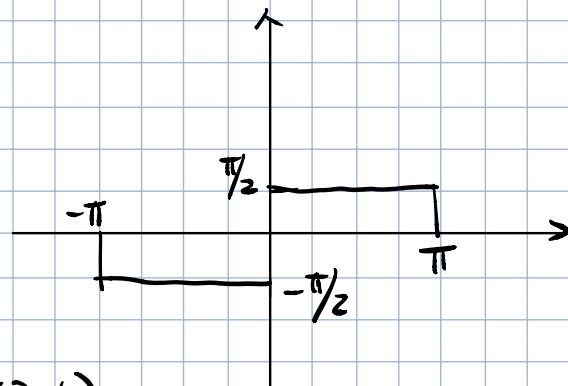
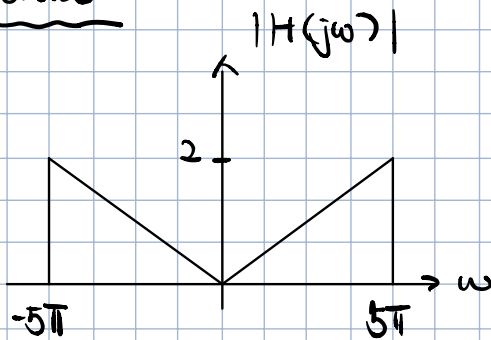
$$= \frac{1}{2} e^{-j\omega/2} (j2 \sin(\omega/2))$$

$$= j e^{-j\omega/2} \sin(\omega/2)$$

$$|H(e^{j\omega})| = \left| \sin\left(\frac{\omega}{2}\right) \right|$$



Exercise:



$$x(t) = 30 \cos(10t) + 10 \sin(30t)$$

$$y(t) = ?$$