

$$x(t) = A \sin(\omega_0 t + \alpha)$$

$$P_{av} = \frac{1}{T} \int_0^T |A \sin(\omega_0 t + \alpha)|^2 dt \quad T = \frac{2\pi}{\omega_0}$$

$$= \frac{A^2}{2\pi/\omega_0} \int_0^{2\pi/\omega_0} \sin^2(\omega_0 t + \alpha) dt$$

$$P_{av} = \frac{A^2 \omega_0}{2\pi} \int_0^{2\pi/\omega_0} \left( \frac{1}{2} - \frac{1}{2} \cos(2\omega_0 t + 2\alpha) \right) dt.$$

$$\sin^2(\beta) = \frac{1}{2} - \frac{1}{2} \cos(2\beta)$$

becomes 0

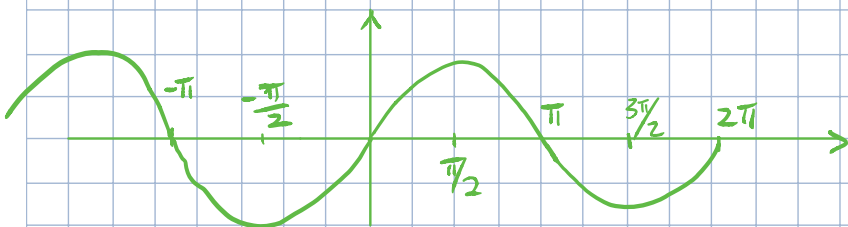
$$= \frac{A^2 \omega_0}{2\pi} \cdot \left( \frac{1}{2} \left( \frac{2\pi}{\omega_0} - 0 \right) \right)$$

$$= \frac{A^2}{2} //$$

④ odd & even signal:

$x(t)$  is an odd signal if  $x(-t) = -x(t)$

eg.  $x(t) = \sin(t)$ ,  $\sin(-t) = -\sin(t)$

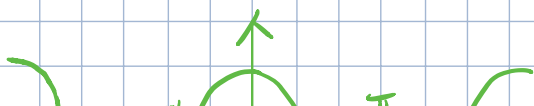


Odd signals are symmetrical w.r.t. the origin.

$x(t)$  is an even signal if  $x(-t) = x(t)$

eg.  $x(t) = \cos(t)$

$\cos(-t) = \cos(t)$



even signals are symmetrical.

w.r.t. the y-axis.

Most real-world signals are neither odd or even. However, all signals can be written as the sum of an even signal & an odd signal.

$$x(t) = \underbrace{x_e(t)}_{\text{even part of } x(t)} + \underbrace{x_o(t)}_{\text{odd part of } x(t)}$$

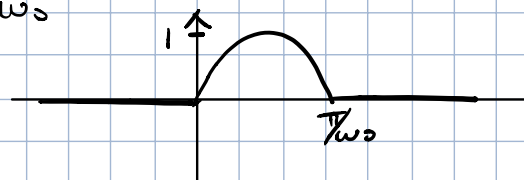
$$x_o(t) = \frac{1}{2}(x(t) - x(-t))$$

$$x_e(t) = \frac{1}{2}(x(t) + x(-t))$$

Example

Find the odd & even parts of :

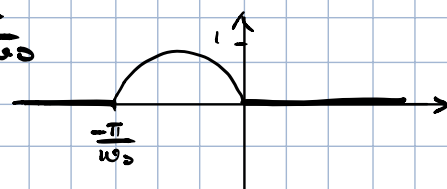
$$x(t) = \begin{cases} \sin(\omega_0 t) & 0 < t < \frac{\pi}{\omega_0} \\ 0 & \text{else.} \end{cases}$$



First, find time reversal of  $x(t)$

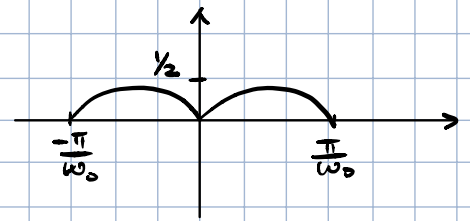
$$x(-t) = \begin{cases} \sin(-\omega_0 t) & 0 < -t < \frac{\pi}{\omega_0} \\ 0 & \text{else.} \end{cases}$$

$$x(-t) = \begin{cases} -\sin(\omega_0 t) & 0 > t > -\frac{\pi}{\omega_0} \\ 0 & \text{else.} \end{cases}$$

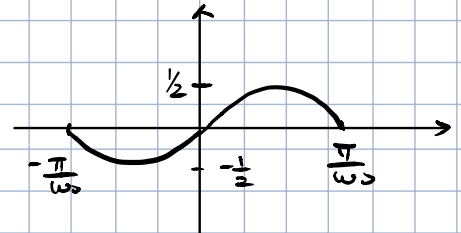


Then, use  $\begin{cases} x_o(t) = \frac{1}{2}(x(t) - x(-t)) \\ x_e(t) = \frac{1}{2}(x(t) + x(-t)) \end{cases}$  for each interval.

$$\Rightarrow x_e(t) = \begin{cases} -\frac{1}{2} \sin(\omega_0 t) & -\frac{\pi}{\omega_0} < t < 0 \\ \frac{1}{2} \sin(\omega_0 t) & 0 < t < \frac{\pi}{\omega_0} \\ 0 & \text{else.} \end{cases}$$



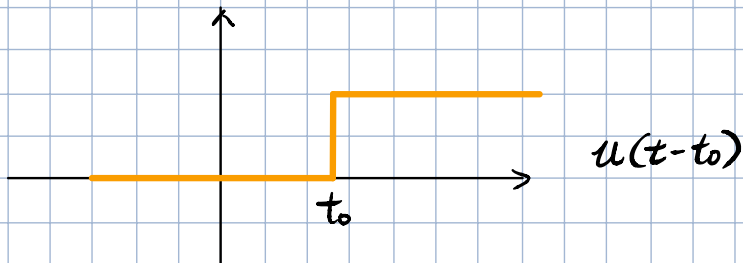
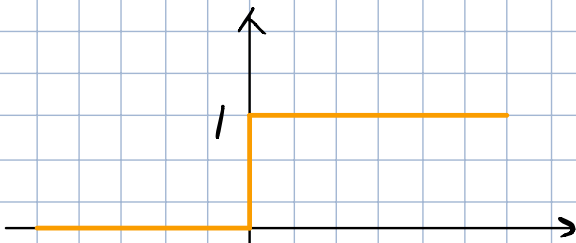
$$x_o(t) = \begin{cases} \frac{1}{2} \sin(\omega_0 t) & -\frac{\pi}{\omega_0} < t < 0 \\ -\frac{1}{2} \sin(\omega_0 t) & 0 < t < \frac{\pi}{\omega_0} \\ 0 & \text{else.} \end{cases}$$



## Basic Signals.

① Unit Step Function.

$$u(t) = \begin{cases} 1 & t \geq 0 \\ 0 & t < 0 \end{cases}$$



② Pulse.  $P(t) = u(t) - u(t-1)$

