

# Analysis-Based Program Transformations

Presentation for HOPL

2/3/17

	Reaching Definitions	Live Variables	Available Expressions
Domain	Sets of definitions	Sets of variables	Sets of expressions
Direction	Forwards	Backwards	Forwards
Transfer function	$gen_B \cup (x - kill_B)$	$use_B \cup (x - def_B)$	$e\_gen_B \cup (x - e\_kill_B)$
Boundary	$OUT[ENTRY] = \emptyset$	$IN[EXIT] = \emptyset$	$OUT[ENTRY] = \emptyset$
Meet ( $\wedge$ )	$\cup$	$\cup$	$\cap$
Equations	$OUT[B] = f_B(IN[B])$ $IN[B] = \bigwedge_{P, pred(B)} OUT[P]$	$IN[B] = f_B(OUT[B])$ $OUT[B] = \bigwedge_{S, succ(B)} IN[S]$	$OUT[B] = f_B(IN[B])$ $IN[B] = \bigwedge_{P, pred(B)} OUT[P]$
Initialize	$OUT[B] = \emptyset$	$IN[B] = \emptyset$	$OUT[B] = U$

Figure 9.21: Summary of three data-flow problems

# The Inn at the Crossings

## Semantics of Flow Analysis

What does a flow analysis mean?

More precisely: a locally consistent set of annotations.

Result of flow analysis is a proposition

- To optimize  $e$  to  $e'$ , want to show  $P \supset \llbracket e \rrbracket = \llbracket e' \rrbracket$   
 $e \approx e'$  (approx)

What proposition does a flow analysis represent?

How to distinguish correct from incorrect data flow equations?

Use propositions as types

- Get soundness from  $\text{msc}$  to type theory (free!)
- Need can justify optimization
- Don't get verification/analysis algorithm

vs Abstract interp

7 never

not always done

- this comes for free

- Read ab interp flow as conjunctive types

- Local consistency implies type rules

$f(x: \mathbb{D}) \{f(x)\}$  is  $\begin{matrix} *x: pos \rightarrow pos \rightarrow pos \\ *x: pos \rightarrow neg \rightarrow neg \\ etc \end{matrix}$

## Examples

Strictness Analysis

$\Delta, \{ \perp \}$

ordinary types (Known-Mishra)

Dead Code / Unused Value Anal

$\Delta, U$

PER types

Red Ct Anal

Inlet sets of types

variant PER types - correctness w/ "instrumented semantics"

Avail Exp, Redn Strang

$X = \text{int}$

invariants, not just types

not std semantics

Running Time Analysis

2-level types

Justification for optimizd?

## Open Question

- Hooker Order / Closure Analysis
- Data Structures / Abstract Locations

- This should be cleaner than Ab-Interp: eoa (?)

- Does this break down on the next example?
- Does it help?

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## Semantics of Flow Analysis

What does a flow analysis mean?

More precisely: a locally consistent set of annotations.

Result of flow analysis is a proposition - To optimize  $e$  to  $e'$ , want to show  $P \supset E[e] = E[e']$   
 $e \simeq e'$  opt eqn

What proposition does a flow analysis represent?

How to distinguish correct from incorrect data flow equations?

# Selective and Lightweight Closure Conversion

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**Definition 1** The following definitions are mutually referential.

1. An *occurrence closure*  $(i, \psi)$  is a pair consisting of an occurrence index and an occurrence environment.
2. An *occurrence environment*  $\psi$  is a finite map from variables to occurrence closures, where for each  $x \in \text{Dom}(\psi)$ ,  $\psi(x) = (i, \psi')$  implies  $\llbracket i \rrbracket$  is a value in  $\Lambda_{in}$ .

$$\begin{array}{c}
\frac{Var(i)}{(i, \psi) \xRightarrow{oc} \psi(\llbracket i \rrbracket)} \\
\\
\frac{Const(i)}{(i, \psi) \xRightarrow{oc} (i, \emptyset)} \\
\\
\frac{Abs(i)}{(i, \psi) \xRightarrow{oc} (i, \psi)} \\
\\
\frac{
\begin{array}{l}
Cond(i) \\
(i.test, \psi) \xRightarrow{oc} (j, \psi') \\
\llbracket j \rrbracket = \mathbf{true} \\
(i.then, \psi) \xRightarrow{oc} (k, \psi'')
\end{array}
}{(i, \psi) \xRightarrow{oc} (k, \psi'')} \\
\\
\frac{
\begin{array}{l}
Cond(i) \\
(i.test, \psi) \xRightarrow{oc} (j, \psi') \\
\llbracket j \rrbracket = \mathbf{false} \\
(i.else, \psi) \xRightarrow{oc} (k, \psi'')
\end{array}
}{(i, \psi) \xRightarrow{oc} (k, \psi'')} \\
\\
\frac{
\begin{array}{l}
App(i) \\
(i.rator, \psi) \xRightarrow{oc} (j, \psi'), \quad Abs(j) \\
(i.rand, \psi) \xRightarrow{oc} (k, \psi'') \\
(j.body, \psi')(\llbracket j.bv \rrbracket \mapsto (k, \psi'')) \xRightarrow{oc} (m, \psi''')
\end{array}
}{(i, \psi) \xRightarrow{oc} (m, \psi''')}
\end{array}$$

Figure 2: Rules for the occurrence evaluator

$$\text{Var}(i) \Rightarrow A_i(\llbracket i \rrbracket) = \mathcal{P}_i$$

$$\text{Const}(i) \Rightarrow \theta_i = \emptyset$$

$$\text{Abs}(i) \Rightarrow \begin{cases} A_{i.\text{body}} = A_i(\llbracket i.\text{bv} \rrbracket) \mapsto \mathcal{P}_{i.\text{bv}} \\ \{(i, A_i)\} \subseteq \phi_i, \text{ and} \\ \theta_i \subseteq \text{Dom}(A_i) \end{cases}$$

$$\text{App}(i) \text{ and } \text{Const}(i.\text{rator}) \Rightarrow A_{i.\text{rand}} = A_i$$

$$\text{App}(i) \text{ and } \neg \text{Const}(i.\text{rator}) \Rightarrow \begin{cases} A_{i.\text{rator}} = A_{i.\text{rand}} = A_i, \\ \theta_i \subseteq \theta_{i.\text{rator}}, \\ \pi_{i.\text{rator}} = \text{cl}_\sigma \Rightarrow [\sigma] \subseteq \theta_{i.\text{rator}}, \text{ and} \\ \forall (j, B) \in \phi_{i.\text{rator}} \\ \quad \begin{cases} \text{Abs}(j), \\ \mathcal{P}_{i.\text{rand}} \leq \mathcal{P}_{j.\text{bv}}, \\ \mathcal{P}_{j.\text{body}} \leq \mathcal{P}_i, \\ \theta_{j.\text{bv}} \subseteq \theta_{i.\text{rator}}, \text{ and} \\ \llbracket j.\text{bv} \rrbracket \notin \theta_{j.\text{bv}} \cup \theta_i \end{cases} \end{cases}$$

$$\text{Cond}(i) \Rightarrow \begin{cases} A_{i.\text{test}} = A_{i.\text{then}} = A_{i.\text{else}} = A_i, \\ \mathcal{P}_{i.\text{then}} \leq \mathcal{P}_i, \text{ and} \\ \mathcal{P}_{i.\text{else}} \leq \mathcal{P}_i, \end{cases}$$

Figure 3: Local Consistency Conditions for Annotations



$$\text{Var } (i) \Longrightarrow \Phi(i) = \llbracket i \rrbracket$$

$$\text{Const } (i) \Longrightarrow \Phi(i) = \llbracket i \rrbracket$$

$$\text{Abs } (i) \wedge \pi_i = id \Longrightarrow \Phi(i) = \lambda x. \Phi(i.body)$$

$$\text{Abs } (i) \wedge \pi_i = cl_\sigma \Longrightarrow \Phi(i) = [(\lambda e \vec{v} x. \text{destr } e \ (\lambda \vec{u}. \Phi(i.body))), [\vec{u}]]$$

where  $e$  fresh  
 and  $\vec{v} = \sigma$   
 and  $[\vec{u}] = FV(\llbracket i \rrbracket) - [\sigma]$

$$\text{App } (i) \wedge \text{Const } (i.rator) \Longrightarrow \Phi(i) = \Phi(i.rator) \ \Phi(i.rand)$$

$$\text{App } (i) \wedge \neg \text{Const } (i.rator) \wedge \pi_{i.rator} = id \Longrightarrow \Phi(i) = \Phi(i.rator) \ \Phi(i.rand)$$

$$\text{App } (i) \wedge \neg \text{Const } (i.rator) \wedge \pi_{i.rator} = cl_\sigma \Longrightarrow \Phi(i) = \text{app } \Phi(i.rator) \ v_1 \ \dots \ v_n \ \Phi(i.rand)$$

where  $\vec{v} = \sigma$

$$\text{Cond } (i) \Longrightarrow \Phi(i) = \text{if } \Phi(i.test) \ \text{then } \Phi(i.then) \ \text{else } \Phi(i.else)$$

$$\Psi(i, \psi) \xRightarrow[t]{} \Psi(j, \psi')$$

**Theorem 3 (Correctness)** *Let  $\Gamma$  be a monovariant locally consistent annotation map, and  $\Pi$  the protocol assignment defined by  $\forall i, \Pi(i) = \pi_i$ . Let  $\psi$  be an occurrence environment such that  $\psi \stackrel{\Pi}{\models} A_i$ . If*

$$(i, \psi) \xRightarrow{oc} (j, \psi')$$

*then*

$$\hat{\Phi}(i, \psi) \xRightarrow[t]{} \hat{\Phi}(j, \psi')$$

**Proof:** (Sketch) The proof is by induction on the size of the derivation that  $(i, \psi) \xRightarrow{oc} (j, \psi')$ . The soundness theorem is used to guarantee that for each invocation of the induction hypothesis for an occurrence closure  $(k, \psi'')$ , the needed condition  $\psi'' \stackrel{\Pi}{\models} A_k$  is satisfied. ■

# Order-of-evaluation Analysis for Destructive Updates in Strict Functional Languages with Flat Aggregates

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# Set Constraints for Destructive Array Update Optimization

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$$\begin{aligned}
& \langle \alpha, \rho, \theta: \phi(v_1, \dots, v_{i-1}, E_i, E_{i+1}, \dots, E_n), K \rangle \\
& \rightarrow \langle \alpha.i, \rho, E_i, \langle \alpha, \rho, \theta: \phi(v_1, \dots, v_{i-1}, [ \ ], E_{i+1} | \dots, E_n) K, \rangle \rangle
\end{aligned}
\quad \text{[push]}$$

$$\begin{aligned}
& \langle \alpha, \rho, v, \langle \alpha', \rho', R, K \rangle \rangle \\
& \rightarrow \langle \alpha', \rho', R[v], K \rangle
\end{aligned}
\quad \text{[return]}$$

### Definition 5 (Live Location)

- No location is live in **halt**.
- $l$  is live in  $\langle \alpha, \rho, R, K \rangle$  iff either:
  1.  $l$  occurs in  $R$ , or
  2. there exists  $x \in \text{fv}(R)$  such that  $\rho(x) = l$ , or
  3.  $l$  is live in  $K$ .

We can now state the soundness condition for a live variable analysis  $\mathcal{L}[\![ - ]\!]$ .

### Definition 6 (Live Variable Analysis)

A live variable analysis  $\mathcal{L}[\![ - ]\!]$  is a map from expression labels  $\theta$  to sets of variables.  $\mathcal{L}[\![ - ]\!]$  is sound iff for each label  $\theta$ ,  $\mathcal{L}[\![ \theta ]\!]$  is a set of variables such that for all reachable configurations of the form  $\langle \alpha, \rho, \theta: T, K, \Sigma \rangle$ ,  $\rho(x)$  live in  $K$  implies  $x \in \mathcal{L}[\![ \theta ]\!]$ .

### Theorem 9 (Correctness of Transformation)

*If  $\mathcal{L}[-]$  is a sound live variable analysis, and  $\langle \alpha_0, \rho_0, F_0, \mathbf{halt}, \Sigma_0 \rangle$  is an initial configuration, then*

$$\langle \alpha_0, \rho_0, F_0, \mathbf{halt}, \Sigma_0 \rangle \rightarrow^n \langle \mathbf{halted}, v \rangle$$

*if and only if*

$$\langle \alpha_0, \rho_0, F_0^*, \mathbf{halt}, \Sigma_0 \rangle \Rightarrow^n \langle \mathbf{halted}, v \rangle$$

$F_0^*$  is the transformed version of  $F_0$ , based on  $\mathcal{L}$

**Definition 12 (Alias Analysis)** An alias set  $\mathcal{A}$  is a subset of  $Var \times Var$ . For  $S \subseteq Var$ , define  $\mathcal{A} \star S = \{x \mid (x, y) \in \mathcal{A} \wedge y \in S\}$ .

Each alias set  $\mathcal{A}$  induces a proposition  $\langle \alpha, \rho, G, K \rangle \models \mathcal{A}$  on configurations of the environment semantics. Again, lack of space prevents us from giving a formal definition. Informally, however, this proposition means that if  $x$  is reachable in  $\alpha$  and

**Definition 13 (Soundness of  $\mathcal{A}$ )**

$\mathcal{A}$  is a sound alias analysis iff  $\langle \alpha, \rho, G, K \rangle \models \mathcal{A}$  for every reachable configuration  $\langle \alpha, \rho, G, K \rangle$ .

**Theorem 14 (Correctness of  $\mathcal{A}$ )** If  $\mathcal{P}[-]$  is a sound propagation analysis and  $\mathcal{A}$  satisfies the constraints A1–A2, then  $\mathcal{A}$  is a sound alias analysis.