

2/10/92 Notes on Control Flow Analysis

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Consider untyped C2V λ -calculus with base constants only:

Exps $M ::= c_n | x | MM | \lambda x.M | \underline{\text{choose}} MM | g M$

\nwarrow numerals

\nwarrow nondeterministic choices abstracts of

\swarrow special form (for primitive, eg add1)

Values $V ::= c_n | x | \lambda x.M$

\nwarrow optimal; mostly will consider closed values only.

Call-by-value rules: write $M \Rightarrow V$ for $\text{eval}(M) = V$: i.e. you don't take transitive closure

(1) $x \Rightarrow x$ (2) $\lambda x.M \Rightarrow \lambda x.M$ (3) $c_n \Rightarrow c_n$

(4)
$$\frac{M \Rightarrow \lambda x.P \quad N \Rightarrow N' \quad P[N'/x] \Rightarrow V}{MN \Rightarrow V}$$

note: if $M \Rightarrow c_n$, then there is no V s.t. $MN \Rightarrow V$.

so error is the same as non-termination. We can fix this later.

(5)
$$\frac{M \Rightarrow c_n}{g M \Rightarrow g(c_n)} \quad \text{or similar} \quad \frac{M \Rightarrow V}{\text{choose } MN \Rightarrow V} \quad \frac{N \Rightarrow V}{\text{choose } MN \Rightarrow V}$$

Types & Flows

$T ::= \underline{\text{int}} | (\lambda x.M)[A]$

$A ::= \epsilon | A[x:F]$

$F ::= \text{finite set of } T$

$f_v(\lambda x.M) \rightarrow F$
 $A: \text{Vars} \rightarrow F$

$\sigma: \text{Vars} \rightarrow \text{closed values}$

Define $V:T \rightarrow V:F$ recursively:

$c_n: \text{int}$

$\sigma(x_i): A(x_i) \quad \sigma(x_n): A(x_n) \Rightarrow (\lambda x.M)\sigma: (\lambda x.M)[A]$

$V:F \text{ iff } \exists T \in F \text{ s.t. } V:T$

(say $\lambda x.M\sigma$ is an A -instance of $\lambda x.M$)

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OCFA

Given a (closed?) pgm M , would like to find the possible values of all the bound vbles. But this assumes an instrumented implementation, which is dubious.

Rather, let's try to annotate the program & generate verification conditions s.t. that any solution to the VC's is a valid annotation (whatever that means, ~ we'll see this later).

So associate a flow variable with every subexpression & binding instance in the pgm. We'll write ϕ_M for the flow variable associated with {a particular occurrence of} M . Then we'll generate constraints s.t. if we have any assignment to the ϕ 's that satisfies the constraints, then the annotation is sound in the following sense:

Thm $\nVdash A \vdash M : \phi$, $\sigma : A$, and $M\sigma \Rightarrow V$, then $V : \phi$.

This says that if the inputs to M (via free variables) satisfy A , then the output satisfies ϕ .

VC rules:

We assign A via binding occurrences:

$$\frac{A[x:\phi_x] \vdash M:\phi_M}{A \vdash (\lambda x.M):\phi_{\lambda x.M}} \quad \text{if } \{(\lambda x.M)[A] \text{ for } (\lambda x.M)\} \subseteq \phi_{\lambda x.M}$$

$$A \vdash x:\phi_x$$

$$\phi_x = A(x)$$

$$A \vdash M:\phi_M$$

$$A \vdash N:\phi_N$$

$$\text{if } (\lambda x.P)[\sigma] \in \phi_M \text{ then } \phi_N \subseteq \phi_x$$

$$+ \phi_P \subseteq \phi_{M(x)}$$

$$A \vdash \dots$$

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Proof of Thm 1. Proof is by induction on derivation of $M\sigma \Rightarrow V$. (Operational Semantics!)
By cases on form of M :

- (1) If M is vble or λ , trivial (base step)
- (2) Combination: Assume we have $A:\sigma + (MN)\sigma \Rightarrow V$. $(MN)\sigma \equiv (M\sigma)(N\sigma)$,
so by defn of \Rightarrow , must have $M\sigma \Rightarrow \lambda x.P_1$, $N\sigma \Rightarrow N_1 + P_1[N_1/x] \Rightarrow V$.
Since these derivations are shorter, the IH applies, so $\lambda x.P_1:\phi_M + N_1:\phi_N$.
So there must be a $(\lambda x.P)[B] \in \phi_M$ s.t. $\lambda x.P_1$ is a B-instance of $\lambda x.P$, say
 $\lambda x.P_1 \equiv (\lambda x.P)\sigma$. Now, $N_1:\phi_N \subseteq \phi_\sigma$, $P_1[N_1/x]$ is a $B[x:\phi_N]$ -instance
of P . \therefore by IH at $P_1[N_1/x] \Rightarrow V$, $V:\phi_P \subseteq \phi_{MN}$. \square

Observations

- (1) No collecting interp, no CPS. Just "program logic" (à la Floyd-Hoare!)
- (2) The constraints are closure conditions & only finitely many closure types can appear, so can solve by iteration to fixpt.
- (3) These are "funny" closure conditions, since you generate new conditions (eg $\phi_N \subseteq \phi_x$, $\phi_P \subseteq \phi_{MN}$) as you go along. Can think of this as generating the (data flow graph (cf Shivers' comments on data flow vs. control flow graph. "λ: The Ultimate Computed Go-to?")
- (4) Can use this to check that environments, continuations, etc are passed correctly & have only certain form, then can synthesize efficient reps for these closures
- (5) What other optimizations can be justified in this way? Is there a notion of equivalence i.e. $M_1 \equiv M_2 \text{ mod } \phi$?

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Variations

1. Error semantics. Add a constant error, a type T , & a flow T (top = anything) then check to see that the least solution isn't T .

2. Data Flow. Instead of using the lattice F , use $F \times D$ where D is your favorite lattice of assertions. Everything should still work as before. You can't abstract F very much, because then you won't have enough information to set up the data constraints. Or use CFA to set up the flow constraints (eg $\phi_N \subseteq \phi_x$) & solve those later.

3. Finer CFA variants. In OCFA, we provide a single ^{assertion} annotation for every program phrase. But you might want some polymorphism e.g.

$$f(n) = \text{choose } \Box (g \text{ "a" } (g \text{ "n" } (f(n-1))))$$

$$g(x,y) = \text{Cons}(x,y)$$

You might have 2 assertions for g , depending on what its input is. (ie where it's called from)

Pure Abstract Interpretation

$$\frac{A \vdash M : \phi_1 \quad A \vdash N : \phi_2}{A \vdash MN : \phi}$$

$$\text{if } (x.x.P)[B] \in \phi_1 \text{ + } B[x:\phi_2] \vdash P : \phi_3, \text{ then } \phi_3 \subseteq \phi$$

But how to control the proliferation of subgoals?

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1 CFA

Let C be the set of call sites in the pgm. Have a C -indexed family of assertions about each expression $A_{M,c} \vdash M: \phi_{M,c}$

$$\frac{A_{M,c} \vdash M: \phi_{M,c} \quad A_{N,c} \vdash N: \phi_{N,c}}{A_{MN,c} \vdash MN: \phi_{MN,c}}$$

$$A_{MN,c} \vdash MN: \phi_{MN,c}$$

↑
This is call site c'

$$\forall y, A_{M,c}(y) = A_{N,c}(y) = A_{MN,c}(y)$$

If $(\lambda x. P)[B] \in \phi_{M,c}$, use the c' -th assertion about $\lambda x. P$

$$\text{i.e. set } \phi_{N,c} \subseteq \phi_{x,c'}$$

$$\phi_{P,c'} \subseteq \phi_{MN,c}$$

But how to set the B 's?

$$A_{\lambda x.M,c} \vdash (\lambda x.M): \phi_{\lambda x.M,c}$$

Need to create assertions $A_{M,c'}[x: \phi_{M,c'}] \vdash M: \phi_{M,c'}$ for all $c' \in C$.

$$\text{So set } A_{\lambda x.M,c} \subseteq A_{M,c'}$$

So in c' -th assertion about M , we merge information about the context in which $\lambda x.M$ was closed.

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More variations

1. Let Q be a finite automaton & let $\delta: Q \times C \rightarrow Q$. Have Q -indexed family of assertions about each expression. To compute the g -th assertion about call c' use the $\delta(g, c')$ -th assertion about the operator:

$$\frac{A \vdash M: \phi_{M,g} \quad A \vdash N: \phi_{N,g}}{A \vdash c': MN: \phi_{MN,g}} \quad \text{if } (\lambda x. P)[B] \in \phi_{M,g}, \text{ set}$$

$$\phi_{N,g} \subseteq \phi_{x, \delta(g, c)}$$

$$\phi_{P, \delta(g, c')} \subseteq \phi_{MN,g}$$

2. Keep track of call site for each bound variable. This avoids merging mfs. in a CFA. So environments look like

$$[x_1: \phi_{x_1, c_1}, \dots, x_n: \phi_{x_n, c_n}] \vdash M: \phi_{M, c_1, \dots, c_n}$$

meaning each x_i got its value at call site c_i . And we'll index the assertions on all of these guys. Then we have something like

$$\frac{A[x: \phi_{x, c'}] \vdash M: \phi_{M, c, c'}}{A \vdash (\lambda x. M): \phi_{\lambda x. M, c}}$$

This is going to be very fine analysis.

3. Can clearly combine these ideas. This way madness lies.