Complete Monitoring for Gradual Types: Supplementary Material

D

BEN GREENMAN, PLT @ Northeastern University, USA

MATTHIAS FELLEISEN, PLT @ Northeastern University, USA

CHRISTOS DIMOULAS, PLT @ Northwestern University, USA

Key concepts: path-based ownership (N 2.2, T 3.2, A 4.2), heap-based ownership (T 3.3), type soundness (N 5.1, A 7.2, T 6.6), complete monitoring (N 5.4), blame soundness + completeness (N 5.5, A 7.5), heap-based blame soundness (T 6.4).

Contents

Abstract		1
Contents		1
1	Common Definitions	2
1.1	Surface Definitions	2
1.2	Evaluation Definitions	4
1.3	Ownership Evaluation Definitions	6
1.4	Abbreviations	10
2	Natural	11
2.1	Normal Natural	11
2.2	Natural Ownership Lifting	12
3	Transient	15
3.1	Normal Transient	15
3.2	Transient (Path-Based) Ownership Lifting	19
3.3	Transient Heap-Based Ownership Lifting	21
4	Amnesic	24
4.1	Normal Amnesic	24
4.2	Amnesic Ownership Lifting	26
5	Natural Theorems, Lemmas, and Proofs	29
5.1	Natural Theorems	29
5.2	Natural Lemmas	30
6	Transient Theorems, Lemmas, and Proofs	54
6.1	Transient Theorems	54
7	Amnesic Theorems, Lemmas, and Proofs	57
7.1	Amnesic Theorems	57
7.2	Amnesic Lemmas	59
8	N/A Simulation	89
9	A/T Simulation	134

Authors' addresses: Ben Greenman, PLT @ Northeastern University, Boston, Massachusetts, USA, benjaminlgreenman@gmail.com; Matthias Felleisen, PLT @ Northeastern University, Boston, Massachusetts, USA, matthias@ccs.neu.edu; Christos Dimoulas, PLT @ Northwestern University, Evanston, Illinois, USA, chrdimo@northwestern.edu.

1 COMMON DEFINITIONS

1.1 Surface Definitions

```
Surface Language

e = x \mid n \mid i \mid \lambda x. e \mid \lambda(x:\tau). e \mid \langle e, e \rangle \mid app\{\tau?\} e e \mid unop\{\tau?\} e \mid binop\{\tau?\} e e \mid dyn b e \mid stat b e

\tau = \text{Nat} \mid \text{Int} \mid \tau \times \tau \mid \tau \Rightarrow \tau

\tau? = \tau \mid \mathcal{U}

b = (\ell \blacktriangleleft \tau \blacktriangleleft \ell)

\ell = \text{countable set of names}

unop = \text{fst} \mid \text{snd}

binop = \text{sum} \mid \text{quotient}

\Gamma = \cdot \mid (x:\tau?), \Gamma

L = \cdot \mid (x:\ell), L

n = \mathbb{N}

i = \mathbb{Z}

\overline{b} = \cdot \mid b, \overline{b}
```

 $e:\tau$? wf

```
e_0: \tau_0 \text{ wf } \text{ iff } \exists \ell_0. \ell_0 \Vdash e_0 \text{ and } \vdash e_0: \tau_0
e_0: \mathcal{U} \text{ wf } \text{ iff } \exists \ell_0. \ell_0 \Vdash e_0 \text{ and } \vdash e_0: \mathcal{U}
```

 $|L; \ell \Vdash e|$ well-named components

$$\frac{(x_0 : \ell_0) \in L_0}{L_0 ; \ell_0 \Vdash x_0} \qquad \frac{(x_0 : \ell_0), L_0 ; \ell_0 \Vdash e_0}{L_0 ; \ell_0 \Vdash \lambda x_0 . e_0} \qquad \frac{(x_0 : \ell_0), L_0 ; \ell_0 \Vdash e_0}{L_0 ; \ell_0 \Vdash \lambda (x_0 : \tau_0) . e_0} \qquad \frac{L_0 ; \ell_0 \Vdash e_0}{L_0 ; \ell_0 \Vdash e_1} \qquad \frac{L_0 ; \ell_0 \Vdash e_0}{L_0 ; \ell_0 \Vdash e_1} \qquad \frac{L_0 ; \ell_0 \Vdash e_0}{L_0 ; \ell_0 \Vdash e_1} \qquad \frac{L_0 ; \ell_0 \Vdash e_0}{L_0 ; \ell_0 \Vdash e_1} \qquad \frac{L_0 ; \ell_0 \Vdash e_0}{L_0 ; \ell_0 \Vdash e_0} \qquad \frac{L_0 ; \ell_0 \Vdash e_$$

$$\frac{L_0;\ell_0 \Vdash e_0}{L_0;\ell_0 \Vdash e_1} \qquad \frac{L_0;\ell_0 \Vdash e_0}{L_0;\ell_0 \Vdash e_0} \qquad \frac{L_0;\ell_0 \Vdash e_0}{L_0;\ell_0 \Vdash e_1} \qquad \frac{L_0;\ell_0 \Vdash e_0}{L_0;\ell_0 \Vdash binop\{\tau?\} e_0 e_1} \qquad \frac{L_0;\ell_1 \Vdash e_0}{L_0;\ell_0 \Vdash binop\{\tau?\} e_0} \qquad \frac{L_0;\ell_0 \Vdash e_0}{L_0;\ell_0 \Vdash binop\{\tau>\} e_0} \qquad \frac{L_0;\ell_0$$

$$\frac{L_0; \ell_1 \Vdash e_0}{L_0; \ell_0 \Vdash \operatorname{stat} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) e_0}$$

 $\Gamma \vdash e : \tau$ static typing

$$\frac{(x_0 : \tau_0) \in \Gamma_0}{\Gamma_0 \vdash x_0 : \tau_0} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \vdash e_0 : \tau_1}{\Gamma_0 \vdash n_0 : \mathsf{Nat}} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \vdash e_0 : \tau_1}{\Gamma_0 \vdash \lambda(x_0 : \tau_0). \ e_0 : \tau_0 \Rightarrow \tau_1} \qquad \frac{\Gamma_0 \vdash e_0 : \tau_0}{\Gamma_0 \vdash \langle e_0, e_1 \rangle : \tau_0 \times \tau_1}$$

$$\Gamma_0 \vdash e_0 : \tau_0$$

$$\frac{\tau_0 \leqslant : \tau_1}{\Gamma_0 \vdash e_0 : \tau_1}$$

 $\Gamma \vdash e : \mathcal{U}$ dynamic typing

$$\frac{x_0 \in \Gamma_0}{\Gamma_0 \vdash x_0 : \mathcal{U}} \qquad \frac{\Gamma_0 \vdash e_0 : \mathcal{U}}{\Gamma_0 \vdash i_0 : \mathcal{U}} \qquad \frac{\Gamma_0 \vdash e_0 : \mathcal{U}}{\Gamma_0 \vdash e_0 : \mathcal{U}} \qquad \frac{\Gamma_0 \vdash e_1 : \mathcal{U}}{\Gamma_0 \vdash e_0 : \mathcal{U}} \qquad \frac{\Gamma_0 \vdash e_1 : \mathcal{U}}{\Gamma_0 \vdash e_0 : \mathcal{U}} \qquad \frac{\Gamma_0 \vdash e_1 : \mathcal{U}}{\Gamma_0 \vdash e_0 : \mathcal{U}}$$

$$\frac{\Gamma_0 \vdash e_0 : \mathcal{U}}{\Gamma_0 \vdash unop\{\mathcal{U}\} e_0 : \mathcal{U}} \qquad \frac{\Gamma_0 \vdash e_0 : \mathcal{U}}{\Gamma_0 \vdash binop\{\mathcal{U}\} e_0 e_1 : \mathcal{U}} \qquad \frac{\Gamma_0 \vdash e_0 : \tau_0}{\Gamma_0 \vdash stat\left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) e_0 : \mathcal{U}}$$

τ ≼: *τ*

$$\frac{\tau_0 \leqslant : \tau_2 \qquad \tau_1 \leqslant : \tau_3}{\tau_0 \times \tau_1 \leqslant : \tau_2 \times \tau_3} \qquad \frac{\tau_2 \leqslant : \tau_0 \qquad \tau_1 \leqslant : \tau_3}{\tau_0 \Rightarrow \tau_1 \leqslant : \tau_2 \Rightarrow \tau_3} \qquad \frac{\tau_0 \leqslant : \tau_0 \Rightarrow \tau_1 \leqslant : \tau_2 \Rightarrow \tau_3}{\tau_0 \leqslant : \tau_0 \Rightarrow \tau_1 \leqslant : \tau_2 \Rightarrow \tau_3}$$

b ≤: *b*

$$\frac{\tau_0 \leqslant : \tau_1}{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \leqslant : (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)}$$

$$\Delta : unop \times \tau \longrightarrow \tau$$

$$\Delta(fst, \tau_0 \times \tau_1) = \tau_0$$

$$\Delta(snd, \tau_0 \times \tau_1) = \tau_1$$

2019-10-03 17:26. Page 3 of 1-148.

204

```
157
           \Delta: binop \times \tau \times \tau \longrightarrow \tau
158
           \Delta(sum, Nat, Nat)
                                          = Nat
159
           \Delta(sum, Int, Int)
                                          = Int
160
161
           \Delta(quotient, Nat, Nat) = Nat
162
           \Delta(quotient, Int, Int) = Int
163
164
165
168
169
170
171
172
```

1.2 Evaluation Definitions

```
176
177
                                             Base Evaluation Language
178
                                                                                       = n \mid i \mid \langle v, v \rangle \mid \lambda x. e \mid \lambda(x:\tau). e
179
                                                                                      = [] \mid \langle E, e \rangle \mid \langle v, E \rangle \mid unop\{\tau?\} E \mid app\{\tau?\} E e \mid app\{\tau?\} v E \mid binop\{\tau?\} E e \mid binop\{\tau?\} v E \mid dyn b E \mid dy
                                               Е
181
                                                                                                        stat b E
182
                                                                             = TagErr • | TagErr \circ | DivErr | BndryErr (\overline{b}, v)
183
                                                                                       = \operatorname{Err} \mid x \mid n \mid i \mid \lambda x. \ e \mid \lambda(x:\tau). \ e \mid \langle e, e \rangle \mid \operatorname{app}\{\tau?\} \ e \ e \mid \operatorname{unop}\{\tau?\} \ e \mid \operatorname{binop}\{\tau?\} \ e \ e \mid \operatorname{dyn} b \ e \mid \operatorname{stat} b \ e
184
                                                                                      = Nat | Int | Pair | Fun
185
                                               K
186
                                                                                      = Nat | Int | \tau \times \tau | \tau \Rightarrow \tau
                                                                                      = τ | U
                                               \tau?
188
                                               b
                                                                                      = (\ell \blacktriangleleft \tau \blacktriangleleft \ell)
189
                                                                                       = countable set of names
190
191
                                                 unop = fst \mid snd
                                                 binop = sum | quotient
                                               Γ
                                                                                       = \cdot | (x:\tau?), \Gamma
                                                                                       = \cdot | (x:\ell), L
195
                                               L
196
                                               n
                                                                                       = \mathbb{N}
197
                                               i
                                                                                      = \mathbb{Z}
198
                                                                                      = \cdot \mid b, \overline{b}
                                               \bar{b}
199
                                                                                      = \mathcal{P}(b)
201
                                                                                       = \mathcal{P}(\ell)
202
203
```

```
tag-match: K \times v \longrightarrow \mathcal{B}
209
210
211
                                                                        if K_0 = \text{Nat and } v_0 \in n
212
                                                                       or K_0 = \text{Int and } v_0 \in i
213
214
                                                                       or K_0 = Pair and
215
                                                                             v_0 \in \langle v, v \rangle \cup
216
                                                                                         (\text{mon} (\ell \blacktriangleleft (\tau \times \tau) \blacktriangleleft \ell) v)
217
                  tag-match(K_0, v_0) = 
                                                                    or K_0 = \text{Fun and}
218
219
                                                                             v_0 \in (\lambda x. e) \cup (\lambda(x:\tau). e) \cup
220
                                                                                         (\text{mon}(\ell \blacktriangleleft (\tau \Rightarrow \tau) \blacktriangleleft \ell) v)
221
                                                                     tag-match(K_0, v_1)
222
                                                                       if v_0 = \operatorname{trace}_{\mathbf{v}} \overline{b}_0 v_1
223
224
                                                                     False
225
                                                                        otherwise
226
227
               228
229
230
231
232
233
234
235
236
                 rev: \overline{b} \longrightarrow \overline{b}
237
                  rev((\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1), \cdot \cdot \cdot, (\ell_{2n} \blacktriangleleft \tau_n \blacktriangleleft \ell_{2n+1})) = (\ell_{2n+1} \blacktriangleleft \tau_n \blacktriangleleft \ell_{2n}), \cdot \cdot \cdot, (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_0)
238
239

\delta: unop \times v \longrightarrow e

\delta(unop, \langle v_0, v_1 \rangle) = \begin{cases}
v_0 \\
\text{if } unop = \text{fst}\{\tau?\} \\
v_1 \\
\text{if } unop = \text{snd}\{\tau?\}
\end{cases}

240
241
242
243
244
245
246
247
248
                 \delta: binop \times v \times v \longrightarrow e
249
250
                \delta(binop, i_0, i_1) = \begin{cases} & \text{DivErr} \\ & \text{if } binop = q \\ & \text{and } i_1 = 0 \\ & \lfloor i_0/i_1 \rfloor \\ & \text{:f } binop = \end{cases}
251
                                                            if binop = sum\{\tau?\}
252
253
                                                         if binop = quotient\{\tau?\}
254
255
256
257
                                                              if binop = quotient\{\tau?\}
258
                                                               and i_1 \neq 0
259
260
               2019-10-03 17:26. Page 5 of 1-148.
```

1.3 Ownership Evaluation Definitions

```
262
            Ownership Evaluation Language
263
                       = countable set of labels, with 1-1 correspondence to names
265
                       = label for the "top" of an expression
266
             \bar{\ell}
                       =\cdot | \overline{\ell}, \ell
267
                       = n \mid i \mid \langle v, v \rangle \mid \lambda x. e \mid \lambda(x:\tau). e
268
                       = [] | (E)^{\ell} | \langle E, e \rangle | \langle v, E \rangle | unop\{\tau?\} E | app\{\tau?\} E e | app\{\tau?\} v E | binop\{\tau?\} E e | binop\{\tau?\} v E |
                           dyn b E \mid stat b E
                      = TagErr • | TagErr \circ | DivErr | BndryErr (\overline{b}, v)
             Err
                       = Nat | Int | Pair | Fun
274
275
                       = Nat | Int | \tau \times \tau | \tau \Rightarrow \tau
276
                      = \tau \mid \mathcal{U}
             \tau?
                       = (\ell \blacktriangleleft \tau \blacktriangleleft \ell)
279
                       = countable set of names
280
             unop = fst \mid snd
281
             binop = sum | quotient
282
            Γ
                       = \cdot | (x:\tau?), \Gamma
                       = \cdot \mid (x : \ell), L
            L
                      = \mathbb{N}
286
                      = \mathbb{Z}
287
                       = \cdot \mid b, \overline{b}
288
                      = \mathcal{P}(b)
289
290
                       = \mathcal{P}(\ell)
293
300
301
302
303
305
            e:\tau? \overline{\mathbf{wf}} | well-formed expression
306
             (e_0)^{\ell_0}: \tau_0 \overline{\mathbf{wf}} iff \ell_0 \overline{\Vdash} (e_0)^{\ell_0} and \overline{\vdash} (e_0)^{\ell_0}: \tau_0
307
             (e_0)^{\ell_0} : \mathcal{U} \ \overline{\mathbf{wf}} \ \mathrm{iff} \ \ell_0 \ \overline{\Vdash} \ (e_0)^{\ell_0} \ \mathrm{and} \ \overline{\vdash} \ (e_0)^{\ell_0} : \mathcal{U}
308
```

```
L; \ell \Vdash e (selected rules)
```

$$\frac{L_{0}; \ell_{0} \Vdash e_{0}}{L_{0}; \ell_{0} \Vdash (e_{0})^{\ell_{0}}} \qquad \frac{(x_{0}:\ell_{0}) \in L_{0}}{L_{0}; \ell_{0} \Vdash x_{0}} \qquad \frac{(x_{0}:\ell_{0}), L_{0}; \ell_{0} \Vdash e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{(x_{0}:\ell_{0}), L_{0}; \ell_{0} \Vdash e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{(x_{0}:\ell_{0}), L_{0}; \ell_{0} \Vdash e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}}{L_{0}; \ell_{0} \Vdash \lambda x_{0}. e_{0}} \qquad \frac{L_{$$

$$\frac{L_{0};\ell_{1} \, \overline{\Vdash} \, e_{0}}{L_{0};\ell_{0} \, \overline{\Vdash} \, \mathsf{dyn} \, (\ell_{0} \blacktriangleleft \, \tau_{0} \blacktriangleleft \, \ell_{1}) \, (e_{0})^{\ell_{1}}} \qquad \frac{L_{0};\ell_{1} \, \overline{\Vdash} \, e_{0}}{L_{0};\ell_{0} \, \overline{\Vdash} \, \mathsf{stat} \, (\ell_{0} \blacktriangleleft \, \tau_{0} \blacktriangleleft \, \ell_{1}) \, (e_{0})^{\ell_{1}}} \qquad \frac{L_{0};\ell_{1} \, \overline{\Vdash} \, v_{0}}{L_{0};\ell_{0} \, \overline{\Vdash} \, \mathsf{mon} \, (\ell_{0} \blacktriangleleft \, \tau_{0} \blacktriangleleft \, \ell_{1}) \, (v_{0})^{\ell_{1}}}$$

$$\frac{L_0; \ell_0 \Vdash v_0}{L_0; \ell_0 \Vdash \operatorname{trace}_{\mathsf{v}} \overline{b_0} \, v_0} \qquad \qquad \frac{L_0; \ell_0 \Vdash e_0}{L_0; \ell_0 \Vdash \operatorname{trace} \overline{b_0} \, e_0}$$

 $\Gamma \models e : \tau$

$$\frac{\Gamma_0 \ \vdash e_0 : \tau_0}{\Gamma_0 \ \vdash (e_0)^{\ell_0} : \tau_0} \qquad \frac{(x_0 : \tau_0) \in \Gamma_0}{\Gamma_0 \ \vdash x_0 : \tau_0} \qquad \frac{(x_0 : \tau_0) \in \Gamma_0}{\Gamma_0 \ \vdash n_0 : \mathsf{Nat}} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_1}{\Gamma_0 \ \vdash i_0 : \mathsf{Int}} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_1}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0 \Rightarrow \tau_1} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_1}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0 \Rightarrow \tau_1} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_1}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0 \Rightarrow \tau_1} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_1}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0 \Rightarrow \tau_1} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_1}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0 \Rightarrow \tau_1} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_0}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0 \Rightarrow \tau_1} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_0}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0 \Rightarrow \tau_0} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_0}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0 \Rightarrow \tau_0} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_0}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0 \Rightarrow \tau_0} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_0}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0 \Rightarrow \tau_0} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_0}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_0}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0} \Rightarrow \tau_0} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_0}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0} \Rightarrow \tau_0} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_0}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0} \Rightarrow \tau_0} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_0}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0} \Rightarrow \tau_0} \Rightarrow \tau_0} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0 : \tau_0}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0 : \tau_0} \Rightarrow \tau_0} \Rightarrow \tau_0} \Rightarrow \tau_0} \qquad \frac{(x_0 : \tau_0), \Gamma_0 \ \vdash e_0}{\Gamma_0 \ \vdash \lambda(x_0 : \tau_0), e_0} \Rightarrow \tau_0} \Rightarrow \tau_0}$$

$$\frac{\Gamma_0 \; \mathsf{F} \; e_0 : \mathcal{U}}{\Gamma_0 \; \mathsf{F} \; \mathsf{dyn} \; (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \; e_0 : \tau_0} \qquad \frac{\Gamma_0 \; \mathsf{F} \; e_0 : \tau_1}{\Gamma_0 \; \mathsf{F} \; \mathsf{e}_0 : \tau_1}$$

 $\Gamma \ \overline{\vdash} \ e : \mathcal{U}$

$$\frac{\Gamma_0 \ \mathsf{F} \ e_0 : \mathcal{U}}{\Gamma_0 \ \mathsf{F} \ (e_0)^{\ell_0} : \mathcal{U}} \qquad \frac{x_0 \in \Gamma_0}{\Gamma_0 \ \mathsf{F} \ x_0 : \mathcal{U}} \qquad \frac{(x_0 \colon \mathcal{U}), \Gamma_0 \ \mathsf{F} \ e_0 : \mathcal{U}}{\Gamma_0 \ \mathsf{F} \ \lambda x_0. \ e_0 : \mathcal{U}} \qquad \frac{\Gamma_0 \ \mathsf{F} \ e_0 : \mathcal{U}}{\Gamma_0 \ \mathsf{F} \ \langle e_0, e_1 \rangle : \mathcal{U}}$$

$$fst: \tau \longrightarrow \tau$$
$$fst(\tau_0 \times \tau_1) = \tau_0$$

2019-10-03 17:26. Page 7 of 1-148.

```
snd: \tau \longrightarrow \tau
365
366
                  snd(\tau_0 \times \tau_1) = \tau_1
367
                dom: \tau \longrightarrow \tau
368
                 dom(\tau_0 \Rightarrow \tau_1) = \tau_0
369
370
                cod: \tau \longrightarrow \tau
371
                 cod(\tau_0 \Rightarrow \tau_1) = \tau_1
372
                \cdots: \overline{\ell} \times \overline{\ell} \longrightarrow \overline{\ell} append labels, but remove consecutive duplicates
373
                 (\ell_0, \dots, \ell_n)(\ell_m, \dots, \ell_k) = \ell_0, \dots, \ell_n, \ell_m, \dots, \ell_k
                      if \ell_n \neq \ell_m
376
                 (\ell_0, \dots, \ell_n)(\ell_n, \dots, \ell_k) = \ell_0, \dots, \ell_n, \dots, \ell_k
377

\begin{array}{ccc}
 & \cdot : \overline{b} \times \overline{b} \longrightarrow \overline{b} \\
 & \cdot \overline{b}_1 & = \overline{b}_1
\end{array}
 append boundaries
378
379
380
                 (b_0, \overline{b}_0)\overline{b}_1 = b_0, (\overline{b}_0\overline{b}_1)
381
382
                \overline{rev:\overline{\ell}\longrightarrow\overline{\ell}} reverse a list of ownership labels
                 rev(\ell_0, \dots, \ell_n) = \ell_n, \dots, \ell_0
384
385
                \overline{b} \simeq \overline{\ell}
386
387
                                                                                                                                                        \frac{\overline{b}_1 \simeq \overline{\ell}_2, \ell_1}{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1), \overline{b}_1 \simeq \overline{\ell}_2, \ell_1, \ell_0}
                                                                 \overline{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1), \cdot \simeq \cdot, \ell_1, \ell_0}
390
                hole-owner : E \longrightarrow \ell | return the ownership label that surrounds the hole
391
                  hole\text{-}owner(E_0) = h\text{-}own(\ell_{\bullet}, E_0)
392
393
                 h-own: \ell \times E \longrightarrow \ell
394
                 h-own (\ell_0, [])
                                                                                  =\ell_0
                 h-own (\ell_0, \langle E_0, e_1 \rangle)
                                                                                  = h-own (\ell_0, E_0)
396
397
                 h-own (\ell_0, \langle v_0, E_1 \rangle)
                                                                                   = h-own (\ell_0, E_1)
                 h-own (\ell_0, app{\tau?} E_0 e_1)
                                                                                   = h-own (\ell_0, E_0)
                 h-own (\ell_0, app{\tau?} v_0 E_1)
                                                                                  = h-own (\ell_0, E_1)
                 h-own (\ell_0, unop\{\tau?\}E_0)
                                                                                  = h-own (\ell_0, E_0)
402
                 h-own (\ell_0, binop\{\tau?\} E_0 e_1)
                                                                                  = h-own (\ell_0, E_0)
403
                 h-own (\ell_0, binop\{\tau?\} v_0 E_1)
                                                                                   = h-own (\ell_0, E_1)
404
                 h-own (\ell_0, \text{dyn } (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) E_0) = h-own (\ell_0, E_0)
405
                 h-own (\ell_0, \operatorname{stat}(\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) E_0) = h-own (\ell_0, E_0)
406
407
                 h-own (\ell_0, (E_0)^{\ell_1})
                                                                                   = h-own (\ell_1, E_0)
408
409
```

```
has-boundary (e, b) check if a boundary appears in an expression
417
418
419
                             has-boundary(e_0,b_0)
                                                                                            has-boundary(e_0, b_0)
                                                                                                                                                           has-boundary(e_0, b_0)
420
                         has-boundary (\lambda x_0, e_0, b_0)
                                                                                    has-boundary (\lambda(x_0:\tau_0). e_0, b_0)
                                                                                                                                                       has-boundary (\langle e_0, e_1 \rangle, b_0)
421
422
423
                        has-boundary(e_1, b_0)
                                                                                       has-boundary (e_0, b_0)
                                                                                                                                                           has-boundary (e_1, b_0)
424
                    has-boundary (\langle e_0, e_1 \rangle, b_0)
                                                                             has-boundary (app\{\tau?\} e_0 e_1, b_0)
                                                                                                                                                 has-boundary (app\{\tau?\} e_0 e_1, b_0)
425
                        has-boundary (e_0, b_0)
                                                                                          has-boundary (e_0, b_0)
                                                                                                                                                              has-boundary(e_1,b_0)
427
428
                has-boundary (unop\{\tau?\} e_0, b_0)
                                                                               has-boundary (binop\{\tau?\} e_0 e_1, b_0)
                                                                                                                                                   has-boundary(binop\{\tau?\} e_0 e_1, b_0)
429
430
                                                                                            has-boundary (e_0, b_0)
431
432
                       has-boundary (dyn b_0 e_0, b_0)
                                                                                      has-boundary (dyn b_1 e_0, b_0)
                                                                                                                                                     has-boundary(stat b_0 e_0, b_0)
433
434
                                                                                            has-boundary(e_0, b_0)
435
                                                                                      has-boundary(stat b_1 e_0, b_0)
436
437
             add-trace: \overline{b} \times v \longrightarrow v extend existing trace (if any), otherwise start a new one
438
439
              add-trace(\cdot, v_1)
440
              add-trace (\overline{b}_0, ((\operatorname{trace}_{V} \overline{b}_1 \ v_1))^{\overline{\ell}_2}) = \operatorname{trace}_{V} \overline{b}_0 \overline{b}_1 ((v_1))^{\overline{\ell}_2}
441
                 if \overline{b}_0 \neq \cdot
442
              add-trace (\overline{b}_0, v_1)
                                                                 = trace<sub>v</sub> \bar{b}_0 v_1
443
444
                 if \overline{b_0} \neq \cdot and v_1 \notin ((\operatorname{trace}_{\mathbf{v}} \overline{b} v))^{\overline{\ell}}
445
             get-trace: v \longrightarrow \overline{b} get trace (if any) from a value
446
447
              get-trace (trace, \overline{b}_0 ((v_0))^{\overline{\ell}_1} = \overline{b}_0
448
              get-trace(v_0)
449
                  if v_0 \notin \text{trace}_{v} \overline{b} ((v))^{\overline{\ell}}
450
451
             rem-trace: v \longrightarrow v remove trace (if any) from a value
452
              \mathit{rem-trace}\,(((\mathsf{trace}_{\mathsf{v}}\,\overline{b}_0\,((v_0))^{\overline{\ell}_1}))^{\overline{\ell}_2})=((v_0))^{\overline{\ell}_1\overline{\ell}_2}
453
454
              rem-trace(v_0)
                                                                    = v_0
455

\underbrace{\text{if } v_0 \notin ((\text{trace}_{\mathbf{v}} \overline{b}((v))^{\overline{\ell}}))^{\overline{\ell}}}_{}

456
             owners: \upsilon \longrightarrow \overline{\ell}
457
458
              \mathit{owners}(v_0) = \{\ell_0\} \cup \mathit{owners}(v_1)
459
                  if v_0 = (v_1)^{\ell_0}
460
461
              owners(v_0) = owners(v_1)
462
                  if v_0 = \operatorname{trace}_{\mathbf{v}} \overline{b_0} v_1
463
              owners (v_0) = \{\}
464
                  otherwise
465
466
```

```
senders: \overline{b} \longrightarrow \overline{\ell}
469
470
             senders(\cdot) = \{\}
471
             senders(\overline{b}_0) = \{\ell_1\} \cup senders(\overline{b}_1)
472
                 if \overline{b}_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1), \overline{b}_1
473
474
            forget: e \longrightarrow e
475
             forget((e_0)^{\ell_0})
                                                  = forget(e_0)
476
             forget(x_0)
477
                                                  = x_0
             forget(i_0)
                                                  =i_0
             forget(\lambda x_0. e_0)
                                                 = \lambda x_0. forget(e_0)
                                                 = \lambda(x_0 : \tau_0). \, forget(e_0)
             forget(\lambda(x_0:\tau_0).e_0)
481
             forget(\langle e_0, e_1 \rangle)
                                                  = \langle forget(e_0), forget(e_1) \rangle
482
483
             forget(app\{\tau?\} e_0 e_1) = app\{\tau?\} forget(e_0) forget(e_1)
484
             forget(unop\{\tau?\}e_0)
                                                = unop\{\tau?\} forget(e_0)
485
             forget(binop\{\tau?\} e_0 e_1) = binop\{\tau?\} forget(e_0) forget(e_1)
486
487
             forget(dyn b_0 e_0)
                                                  = dyn b_0 forget(e_0)
488
             forget(stat b_0 e_0)
                                                  = stat b_0 forget (e_0)
489
             mon-depth: v \longrightarrow n count monitors around a value
490
             mon-depth(i)
             mon-depth(\langle v_0, v_1 \rangle)
                                                                                         0
             mon-depth(\lambda x_0.e_0)
                                                                                         0
494
              mon-depth(\lambda(x_0:\tau_0).e_0)
                                                                                         0
495
496
             mon-depth(trace_{v} \bar{b}_{0} v_{0})
                                                                                         mon-depth(v_0)
497
             mon\text{-}depth(mon\ b_0\ v_0)\ = *1 + mon\text{-}depth(v_0)
498
             last: \overline{\ell} \longrightarrow \ell count monitors around a value
499
500
             last(\ell_0 \cdots \ell_n) = \ell_n
501
           1.4 Abbreviations
502
503
             e_0 = ((e_1))^{\overline{\ell}_0} \iff e_0 = (\cdots (e_1)^{\ell_n} \cdots)^{\ell_1}
             (\operatorname{trace}_{v}^{?} \overline{b_0} v_1) = v_0 \iff \operatorname{rem-trace}(v_0) = v_1 \text{ and } \operatorname{get-trace}(v_0) = \overline{b_0}
             (\text{mon}^? b_0 v_1) = v_0 \iff \text{if } v_0 = \text{mon } b_0 v_1 \text{ or } v_0 \notin \text{mon } b v
507
             (\mathsf{mon}^{+?} b_0 \dots b_n \ v_1) = v_0 \iff v_0 = \mathsf{mon} \ b_0 \ (\dots \mathsf{mon} \ b_n \ v_0 \dots)
508
             E_0[e_0]^{\ell_0} \iff hole\text{-}owner(E_0) = \ell_0
509
510
511
513
514
515
516
517
```

```
2 Natural
```

522

```
2.1 Normal Natural
```

```
523
524
                     Natural Language extends Base Evaluation Language
525
                      v = n \mid i \mid \langle v, v \rangle \mid \lambda x. e \mid \lambda(x:\tau). e \mid \text{mon} (\ell \blacktriangleleft \tau \Rightarrow \tau \blacktriangleleft \ell) v
526
                    \Gamma \vdash_{\mathsf{N}} e : \tau \mid \text{extends } \Gamma \vdash e : \tau
527
528
                                                                                          \frac{\Gamma \vdash_{\mathsf{N}} v_1 : \mathcal{U}}{\Gamma \vdash_{\mathsf{N}} \mathsf{mon} \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) v_1 : \tau_0}
529
530
                                                                                                                                                                                                                             \Gamma \vdash_{\mathsf{N}} \mathsf{Err} : \tau_0
531
532
                    \Gamma \vdash_{\mathsf{N}} e : \mathcal{U} \mid \text{extends } \Gamma \vdash e : \mathcal{U}
533
534
                                                                                          \frac{\Gamma \vdash_{\mathsf{N}} v_1 : \tau_0}{\Gamma \vdash_{\mathsf{N}} \mathsf{mon} \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) v_1 : \mathcal{U}}
535
                                                                                                                                                                                                                             \Gamma \vdash_{\mathsf{N}} \mathsf{Err} : \mathcal{U}
536
537
                      \rightarrow_{\mathsf{N}}^* | reflexive-transitive closure of \rightarrow_{\mathsf{N}}
538
539
                      \rightarrow_{\mathsf{N}} compatible closure of \triangleright_{\mathsf{N}} \cup \blacktriangleright_{\mathsf{N}}
540
541
                    e \triangleright_{\mathsf{N}} e
542
543
                      unop\{\tau_0\} v_0
                                                                                                                \triangleright_{N} TagErr \circ
544
                            if \delta(unop, v_0) is undefined
545
546
                                                                                                                \triangleright_{\mathsf{N}} \delta(\mathit{unop}, v_0)
                      unop\{\tau_0\} v_0
547
                            if \delta(unop, v_0) is defined
548
                                                                                                                \triangleright_{N} TagErr \circ
                      binop\{\tau_0\} v_0 v_1
549
                            if \delta(binop, v_0, v_1) is undefined
550
551
                      binop\{\tau_0\} v_0 v_1
                                                                                                                \triangleright_{\mathsf{N}} \delta(\mathit{binop}, v_0, v_1)
552
                            if \delta(binop, v_0, v_1) is defined
553
                                                                                                                ⊳<sub>N</sub> TagErr∘
                      app\{\tau_0\} v_0 v_1
554
                            if v_0 \notin (\lambda x. e) \cup (\text{mon } b \ v)
555
                                                                                                                \triangleright_{\mathsf{N}} e_0[x_0 \leftarrow v_1]
556
                      app\{\tau_0\} (\lambda(x_0:\tau_1). e_0) v_1
557
                      \mathsf{app}\{\tau_0\} \left(\mathsf{mon} \left(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1\right) v_0\right) v_1 \; \rhd_{\mathsf{N}} \; \mathsf{dyn} \; b_0 \left(\mathsf{app}\{\mathcal{U}\} \; v_0 \; (\mathsf{stat} \; b_1 \; v_1)\right)
558
                            where b_0 = (\ell_0 \blacktriangleleft cod(\tau_1) \blacktriangleleft \ell_1) and b_1 = (\ell_1 \blacktriangleleft dom(\tau_1) \blacktriangleleft \ell_0)
559
                      \mathsf{dyn} \left( \ell_0 \blacktriangleleft (\tau_0 \Longrightarrow \tau_1) \blacktriangleleft \ell_1 \right) v_0
                                                                                                                \triangleright_{\mathsf{N}} \mod (\ell_0 \blacktriangleleft (\tau_0 \Rightarrow \tau_1) \blacktriangleleft \ell_1) v_0
560
                            if tag\text{-}match([\tau_0 \Rightarrow \tau_1], \upsilon_0)
561
562
                                                                                                                \triangleright_{\mathsf{N}} \langle \mathsf{dyn} \, b_0 \, v_0, \mathsf{dyn} \, b_1 \, v_1 \rangle
                      dyn (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \langle v_0, v_1 \rangle
563
                            \text{if } \textit{tag-match}(\lfloor \tau_0 \rfloor, \langle v_0, v_1 \rangle) \text{ and } b_0 = (\ell_0 \blacktriangleleft \textit{fst}(\tau_0) \blacktriangleleft \ell_1) \text{ and } b_1 = (\ell_0 \blacktriangleleft \textit{snd}(\tau_0) \blacktriangleleft \ell_1)
```

 $\triangleright_{\mathsf{N}} i_0$

 $\triangleright_{\mathsf{N}} \mathsf{BndryErr}\left((\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1), v_0\right)$

 $dyn (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) i_0$

 $\operatorname{dyn}\left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) v_0$

if tag- $match(\lfloor \tau_0 \rfloor, i_0)$

if $\neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)$

564

565

566 567

568

610

611 612

613

614

615

624

```
573
                   e ►<sub>N</sub> e
574
                     unop\{\mathcal{U}\} v_0
                                                                                                            ►<sub>N</sub> TagErr •
575
                          if \delta(\mathit{unop}, v_0) is undefined
576
577
                                                                                                            \triangleright_{\mathsf{N}} \delta(\mathit{unop}, v_0)
                     unop\{\mathcal{U}\} v_0
578
                           if \delta(unop, v_0) is defined
579
                                                                                                            ►<sub>N</sub> TagErr •
                     binop\{\mathcal{U}\} v_0 v_1
580
                          if \delta(binop, v_0, v_1) is undefined
581
                     binop\{\mathcal{U}\} v_0 v_1
                                                                                                            \triangleright_{\mathsf{N}} \delta(\mathit{binop}, v_0, v_1)
                          if \delta(binop, v_0, v_1) is defined
                     app{\mathcal{U}} v_0 v_1
                                                                                                            ►<sub>N</sub> TagErr •
                          if v_0 \notin (\lambda x. e) \cup (\text{mon } b \ v)
586
587
                                                                                                            \triangleright_{\mathsf{N}} e_0[x_0 \leftarrow v_1]
                     app{U} (\lambda x_0. e_0) v_1
588
                     \mathsf{app}\{\mathcal{U}\} \left(\mathsf{mon} \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) v_0\right) v_1 \ \blacktriangleright_{\mathsf{N}} \ \mathsf{stat} \ b_0 \left(\mathsf{app}\{\tau_1\} \ v_0 \ (\mathsf{dyn} \ b_1 \ v_1)\right)
589
                           where b_0 = (\ell_0 \blacktriangleleft cod(\tau_0) \blacktriangleleft \ell_1) and b_1 = (\ell_1 \blacktriangleleft dom(\tau_0) \blacktriangleleft \ell_0) and \tau_1 = cod(\tau_0)
590
                     \operatorname{stat} (\ell_0 \blacktriangleleft (\tau_0 \Longrightarrow \tau_1) \blacktriangleleft \ell_1) v_0

ightharpoonup_{N} \mod (\ell_0 \blacktriangleleft (\tau_0 \Longrightarrow \tau_1) \blacktriangleleft \ell_1) v_0
591
592
                           if tag-match (\lfloor \tau_0 \Rightarrow \tau_1 \rfloor, v_0) and v_0 \in (\lambda(x : \tau), e) \cup (\text{mon } b \ v)
593
                     stat (\ell_0 \blacktriangleleft (\tau_0 \times \tau_1) \blacktriangleleft \ell_1) \langle v_0, v_1 \rangle
                                                                                                            \blacktriangleright_{\mathsf{N}} \langle \mathsf{stat} \left( \ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1 \right) v_0, \mathsf{stat} \left( \ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1 \right) v_1 \rangle
594
                     stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) i_0
                           if tag-match(\lfloor \tau_0 \rfloor, i_0)
                                                                                                            ►<sub>N</sub> TagErr∘
                     stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_0
598
                           if \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)
599
600
```

2.2 Natural Ownership Lifting

```
Natural Ownership Language extends Ownership Evaluation Language \begin{array}{c} v = \ldots \mid \text{mon} \left( \ell \blacktriangleleft \tau \Rightarrow \tau \blacktriangleleft \ell \right) v \\ \\ \longrightarrow_{\overline{\mathbb{N}}}^* \end{array} reflexive-transitive closure of \longrightarrow_{\overline{\mathbb{N}}} compatible closure of \triangleright_{\overline{\mathbb{N}}} \cup \blacktriangleright_{\overline{\mathbb{N}}}
```

```
(e)^{\ell} \rhd_{\overline{\mathbb{N}}} (e)^{\ell}
625
626
                                (unop\{\tau_0\} (v_0))^{\overline{\ell}_0})^{\ell_0}
                                                                                                                                                                                                           \rhd_{\overline{N}} (\mathsf{TagErr} \, \circ)^{\ell_0}
627
628
                                          if v_0 \notin (v)^{\ell} and \delta(\textit{unop}, v_0) is undefined
629
                                (unop\{\tau_0\} (v_0)^{\overline{\ell}_0})^{\ell_0}
                                                                                                                                                                                                           \rhd_{\overline{\mathbb{N}}} (\delta(unop, v_0))^{\overline{\ell}_0 \ell_0}
630
631
                                          if \delta(unop, v_0) is defined
632
                                (\mathit{binop}\{\tau_0\}\,(\!(\upsilon_0)\!)^{\overline{\ell}_0}\,(\!(\upsilon_1)\!)^{\overline{\ell}_1})^{\ell_0}
                                                                                                                                                                                                           \rhd_{\overline{N}} (\mathsf{TagErr} \, \circ)^{\ell_0}
633
                                          if v_0 \notin (v)^\ell and v_1 \notin (v)^\ell and \delta(\mathit{binop}, v_0, v_1) is undefined
634
635
                                 (binop\{\tau_0\} ((v_0))^{\overline{\ell}_0} ((v_1))^{\overline{\ell}_1})^{\ell_0}
                                                                                                                                                                                                            \triangleright_{\overline{N}} (\delta(binop, v_0, v_1))^{\ell_0}
636
637
                                          if \delta(binop, v_0, v_1) is defined
                                \left(\mathsf{app}\{\tau_0\}\left(\!\left(\upsilon_0\right)\!\right)^{\overline{\ell}_0}\,\upsilon_1\right)^{\ell_0}
638

ho_{\overline{N}} (\mathsf{TagErr} \circ)^{\ell_0}
639
                                          if v_0 \notin (v)^{\ell} \cup (\lambda x. e) \cup (\text{mon } b \ v)
640
641
                                \begin{split} & (\mathsf{app}\{\tau_{0}\} \, (\!(\lambda(x_{0}\!:\!\tau_{1})\!.\,e_{0}\!)\!)^{\overline{\ell}_{0}} \,\, \upsilon_{1})^{\ell_{0}} \\ & (\mathsf{app}\{\tau_{0}\} \, (\!(\mathsf{mon} \, (\ell_{0} \blacktriangleleft \,\tau_{1} \blacktriangleleft \,\ell_{1}) \, (\upsilon_{0})^{\ell_{2}}\!)^{\overline{\ell}_{0}} \,\, \upsilon_{1})^{\ell_{3}} \\ & (\mathsf{app}\{\tau_{0}\} \, (\!(\mathsf{mon} \, (\ell_{0} \blacktriangleleft \,\tau_{1} \blacktriangleleft \,\ell_{1}) \, (\upsilon_{0})^{\ell_{2}}\!)^{\overline{\ell}_{0}} \,\, \upsilon_{1})^{\ell_{3}} \\ & \triangleright_{\overline{\mathsf{N}}} \, (\!(\mathsf{dyn} \, b_{0} \, (\mathsf{app}\{\mathcal{U}\} \, \upsilon_{0} \, (\mathsf{stat} \, b_{1} \, (\!(\upsilon_{1})\!)^{\ell_{3} \mathit{rev}(\overline{\ell}_{0})\ell_{2}}))^{\ell_{2}} )^{\overline{\ell}_{0}\ell_{3}} \end{split}
642
643
644
                                          where b_0 = (\ell_0 \blacktriangleleft cod(\tau_1) \blacktriangleleft \ell_1) and b_1 = (\ell_1 \blacktriangleleft dom(\tau_1) \blacktriangleleft \ell_0)
645
                                         \operatorname{lyn}\left(\ell_{0} \blacktriangleleft (\tau_{0} \Rightarrow \tau_{1}) \blacktriangleleft \ell_{1}\right) ((v_{0}))^{\overline{\ell_{0}}} \stackrel{\ell_{2}}{\stackrel{}{=}} \qquad \qquad \triangleright_{\overline{N}} \left(\operatorname{mon}\left(\ell_{0} \blacktriangleleft (\tau_{0} \Rightarrow \tau_{1}) \blacktriangleleft \ell_{1}\right) ((v_{0}))^{\overline{\ell_{0}}}\right)^{\ell_{2}}
if \operatorname{tag-match}\left(\lfloor \tau_{0} \Rightarrow \tau_{1} \rfloor, v_{0}\right) and v_{0} \in (\lambda x. e) \cup (\operatorname{mon} b \ v)
                               \left(\operatorname{dyn}\left(\ell_{0} \blacktriangleleft (\tau_{0} \Rightarrow \tau_{1}) \blacktriangleleft \ell_{1}\right) \left(\!\!\left(v_{0}\right)\!\!\right)^{\overline{\ell}_{0}}\right)^{\ell_{2}}
646
647
648
                                                                                                                                                                                                           \rhd_{\overline{\mathbb{N}}} \left( \langle \operatorname{dyn} b_0 ((v_0))^{\overline{\ell}_0}, \operatorname{dyn} b_1 ((v_1))^{\overline{\ell}_0} \rangle \right)^{\ell_2}
                                \left(\operatorname{dyn}\left(\ell_{0} \blacktriangleleft \tau_{0} \blacktriangleleft \ell_{1}\right) \left(\!\left\langle \left\langle v_{0}, v_{1} \right\rangle \right)\!\right)^{\overline{\ell}_{0}}\right)^{\ell_{2}}
649
650
                                          if tag\text{-}match(\lfloor \tau_0 \rfloor, \langle v_0, v_1 \rangle) and b_0 = (\ell_0 \blacktriangleleft fst(\tau_0) \blacktriangleleft \ell_1) and b_1 = (\ell_0 \blacktriangleleft snd(\tau_0) \blacktriangleleft \ell_1)
651
                                (\operatorname{dyn}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) ((i_0))^{\overline{\ell}_0})^{\ell_2}
                                                                                                                                                                                                           \triangleright_{\overline{\mathbf{N}}} (i_0)^{\ell_2}
652
653
                                          if tag-match(|\tau_0|, i_0)
654
                                                                                                                                                                                                           \rhd_{\overline{\mathbf{N}}} \left(\mathsf{BndryErr}\left((\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1), (\!(\upsilon_0)\!)^{\overline{\ell_0}}\right)\right)^{\ell_2}
                                \left(\operatorname{dyn}\left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) \left(\!\left(v_0\right)\!\right)^{\overline{\ell}_0}\right)^{\ell_2}
655
656
                                          if \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)
657
```

```
(e)^{\ell} \blacktriangleright_{\overline{N}} (e)^{\ell}
677
678
                                  (\mathit{unop}\{\mathcal{U}\}\,(\!(v_0)\!)^{\overline{\ell}_0})^{\ell_0}
                                                                                                                                                                                                                          ▶ (TagErr •)^{\ell_0}
679
680
                                             if v_0 \notin (v)^{\ell} and \delta(\textit{unop}, v_0) is undefined
681
                                                                                                                                                                                                                           \blacktriangleright_{\overline{N}} (\delta(unop, v_0))^{\overline{\ell}_0 \ell_0}
                                  (unop\{\mathcal{U}\}((v_0))^{\overline{\ell}_0})^{\ell_0}
682
683
                                             if \delta(unop, v_0) is defined
684
                                  (\mathit{binop}\{\mathcal{U}\}\,(\!(v_0)\!)^{\overline{\ell}_0}\,(\!(v_1)\!)^{\overline{\ell}_1})^{\ell_0}
                                                                                                                                                                                                                           ▶ (TagErr •)^{\ell_0}
685
                                            if v_0 \notin (v)^\ell and v_1 \notin (v)^\ell and \delta(\mathit{binop}, v_0, v_1) is undefined
686
                                  (\mathit{binop}\{\mathcal{U}\}\,(\!(v_0)\!)^{\overline{\ell}_0}\,(\!(v_1)\!)^{\overline{\ell}_1})^{\ell_0}
                                                                                                                                                                                                                           \blacktriangleright_{\overline{N}} (\delta(binop, v_0, v_1))^{\ell_0}
689
                                             if \delta(binop, v_0, v_1) is defined
                                  (\mathsf{app}\{\mathcal{U}\} (\!(v_0)\!)^{\overline{\ell}_0} \ v_1)^{\ell_0}
690
                                                                                                                                                                                                                           \blacktriangleright_{\overline{N}} (\mathsf{TagErr} \bullet)^{\ell_0}
691
                                             if v_0 \notin (v)^{\ell} \cup (\lambda x. e) \cup (\text{mon } b \ v)
692
693
                                  (\mathsf{app}\{\mathcal{U}\}\,(\!(\lambda x_0.\,e_0)\!)^{\overline{\ell}_0}\,\,v_1)^{\ell_0}
                                                                                                                                                                                                                          \blacktriangleright_{\overline{N}} ((e_0[x_0 \leftarrow ((v_1))^{\ell_0 rev(\overline{\ell}_0)}]))^{\overline{\ell}_0 \ell_0}
                                  (\operatorname{app}\{\mathcal{U}\} ((\operatorname{mon} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (\upsilon_0)^{\ell_2}))^{\overline{\ell_0}} \upsilon_1) \xrightarrow{P_{\overline{N}}} ((\operatorname{stat} b_0 (\operatorname{app}\{\tau_1\} \upsilon_0 (\operatorname{dyn} b_1 ((\upsilon_1))^{\ell_3 \operatorname{rev}(\overline{\ell_0})\ell_2}))^{\ell_2}))^{\overline{\ell_0}\ell_3})) \times \operatorname{where} b_0 = (\ell_0 \blacktriangleleft \operatorname{cod}(\tau_0) \blacktriangleleft \ell_1) \text{ and } b_1 = (\ell_1 \blacktriangleleft \operatorname{dom}(\tau_0) \blacktriangleleft \ell_0) \text{ and } \tau_1 = \operatorname{cod}(\tau_0))
695
696
697
                                            \operatorname{tat}\left(\ell_{0} \blacktriangleleft (\tau_{0} \Rightarrow \tau_{1}) \blacktriangleleft \ell_{1}\right) \left(\!\!\left(v_{0}\right)\!\!\right)^{\overline{\ell_{0}}}\right)^{\ell_{2}}  \blacktriangleright_{\overline{N}} \left(\operatorname{mon}\left(\ell_{0} \blacktriangleleft (\tau_{0} \Rightarrow \tau_{1}) \blacktriangleleft \ell_{1}\right) \left(\!\!\left(v_{0}\right)\!\!\right)^{\overline{\ell_{0}}}\right)^{\ell_{2}} 
\operatorname{if} tag-match}\left(\left\lfloor \tau_{0} \Rightarrow \tau_{1} \right\rfloor, v_{0}\right) \text{ and } v_{0} \in (\lambda x. \, e) \cup (\operatorname{mon} b \, v)
                                  (\operatorname{stat}(\ell_0 \blacktriangleleft (\tau_0 \Rightarrow \tau_1) \blacktriangleleft \ell_1) ((v_0))^{\overline{\ell_0}})^{\ell_2}
698
699
700
                                            \operatorname{tat}\left(\ell_{0} \blacktriangleleft \tau_{0} \blacktriangleleft \ell_{1}\right) \left(\left\langle \left\langle v_{0}, v_{1} \right\rangle \right)\right)^{\overline{\ell}_{0}}\right)^{\ell_{2}} \qquad \blacktriangleright_{\overline{N}} \left(\left\langle \operatorname{dyn} b_{0} \left(\left\langle v_{0} \right\rangle \right)\right)^{\overline{\ell}_{0}}, \operatorname{dyn} b_{1} \left(\left\langle v_{1} \right\rangle \right)^{\overline{\ell}_{0}}\right)^{\ell_{2}}
if \operatorname{tag-match}\left(\left\langle v_{0}, v_{1} \right\rangle, \tau_{0}\right) and b_{0} = (\ell_{0} \blacktriangleleft \operatorname{fst}(\tau_{0}) \blacktriangleleft \ell_{1}) and b_{1} = (\ell_{0} \blacktriangleleft \operatorname{snd}(\tau_{0}) \blacktriangleleft \ell_{1})
                                  \left(\operatorname{stat}\left(\ell_{0}\blacktriangleleft\tau_{0}\blacktriangleleft\ell_{1}\right)\left(\!\left(\langle v_{0},v_{1}\rangle\right)\!\right)^{\overline{\ell}_{0}}\right)^{\ell_{2}}
701
702
703
                                  (\operatorname{stat}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) ((i_0))^{\overline{\ell}_2})^{\ell_3}
                                                                                                                                                                                                                          \blacktriangleright_{\overline{N}} (i_0)^{\ell_3}
704
705
                                             if tag-match(i_0, \tau_0)
706
                                  (\mathsf{stat}\,(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\,(\!(v_0)\!)^{\overline{\ell}_2})^{\ell_2}
                                                                                                                                                                                                                           \blacktriangleright_{\overline{N}} (\mathsf{TagErr} \circ)^{\ell_2}
707
708
                                             if \neg tag\text{-}match(v_0, \tau_0)
709
```

3 Transient

Normal Transient

Transient Language extends Base Evaluation Language

p = countable set of heap locations

$$v = i \mid n \mid p$$

$$\mathbf{w} = \lambda x. e \mid \lambda(x:\tau). e \mid \langle v, v \rangle$$

$$e = \ldots | p | \text{check } \tau? e p$$

$$E = \ldots \mid \operatorname{check} \tau ? E p$$

$$\mathcal{H} = \mathcal{P}((p \mapsto w))$$

$$\mathcal{B} = \mathcal{P}((\mathsf{p} \mapsto b^*))$$

$$\mathcal{T} = \cdot | (\mathbf{p} : \tau?), \mathcal{T}$$

$$(\cdot): \mathcal{H} \times v \longrightarrow v$$
 heap dereference

$$\begin{array}{|c|c|} \hline (\cdot): \mathcal{H} \times v \longrightarrow v \\ \hline \\ \mathcal{H}_0(v_0) = \left\{ \begin{array}{ll} w_0 & \text{if } v_0 \in p \text{ and } (v_0 \mapsto w_0) \in \mathcal{H}_0 \\ v_0 & \text{if } v_0 \notin p \end{array} \right. \end{array}$$

$$\boxed{\cdot(\cdot):\mathcal{B}\times v\longrightarrow b^*} \text{ blame map dereference}$$

$$\boxed{ \begin{array}{c} \underbrace{\cdot(\cdot):\mathcal{B}\times v \longrightarrow b^*} \\ \\ \mathcal{B}_0(v_0) = \left\{ \begin{array}{c} b_0^* & \text{if } v_0 \in \mathsf{p} \text{ and } (v_0 \mapsto b_0^*) \in \mathcal{B}_0 \\ \\ \emptyset & \text{otherwise} \end{array} \right.$$

$$[\cdot \mapsto \cdot]: \mathcal{B} \times v \times b^* \longrightarrow \mathcal{B}$$
 blame map replace

$$\begin{array}{c} \hline [\cdot [\cdot \mapsto \cdot] : \mathcal{B} \times v \times b^* \longrightarrow \mathcal{B}] \text{ blame map replace} \\ \\ \mathcal{B}_0[v_0 \mapsto b_0^*] = \left\{ \begin{array}{c} \{v_0 \mapsto b_0^*\} \cup (\mathcal{B}_0 \setminus (v_0 \mapsto b_1^*)) \\ \\ \text{if } v_0 \in \mathsf{p} \text{ and } (v_0 \mapsto b_1^*) \in \mathcal{B}_0 \\ \\ \mathcal{B}_0 \text{ otherwise} \end{array} \right.$$

$$\boxed{ \begin{bmatrix} \cdot [\cdot \cup \cdot] : \mathcal{B} \times v \longrightarrow b^* \\ \mathcal{B}_0[v_0 \cup b_0^*] = & \mathcal{B}_0[v_0 \mapsto b_0^* \cup \mathcal{B}_0(v_0)] \end{bmatrix} }$$
blame map update

$$\mathcal{B}_0[v_0 \cup b_0^*] = \mathcal{B}_0[v_0 \mapsto b_0^* \cup \mathcal{B}_0(v_0)]$$

2019-10-03 17:26. Page 15 of 1-148.

```
\mathcal{T};\Gamma \vdash_\mathsf{T} e:K
781
782
783
                                  (p_0:\tau_0)\in\mathcal{T}_0
                                                                                                                        \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : K_0
                                                                                                                                                                                                                                     \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : \mathcal{U}
                                                                                                                                                                                                                                                                                                                                     (x_0:\tau_0)\in\Gamma_0
784
                                                                                                                                                                                                                                                                                                                             \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} x_0 : \lfloor \tau_0 \rfloor
                           \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} \mathsf{p}_0 : \lfloor \tau_0 \rfloor
                                                                                                     \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} \mathsf{check}\, \tau_0 \, e_0 \, \mathsf{p}_0 : \lfloor \tau_0 \rfloor
                                                                                                                                                                                                                 \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} \mathsf{check} \, \tau_0 \, e_0 \, \mathsf{p}_0 : \lfloor \tau_0 \rfloor
785
786
787
                                                                                                                                                                                                                                                                                                 \mathcal{T}_0; (x_0:\mathcal{U}), \Gamma_0 \vdash_\mathsf{T} e_0:\mathcal{U}
                                                                                                                                                                                            \mathcal{T}_0; (x_0:\tau_0), \Gamma_0 \vdash_{\mathsf{T}} e_0: K_0
788
                                                                                                                \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} i_0: Int
                                                                                                                                                                                        \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} \lambda(x_0 : \tau_0). e_0 : \mathsf{Fun}
                                                                                                                                                                                                                                                                                                    \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} \lambda x_0. e_0: Fun
                                   \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} n_0 : \mathsf{Nat}
789
                                                                                                                                                                                                                                                                                           \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : K_0
792
                                                                                                                                                                     \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0: Fun
                                                                                                                                                                                                                                                                                        \Delta(unop, K_0) = K_1
                                                           \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : K_0
793
                                                           \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_1 : K_1
                                                                                                                                                                       \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_1 : K_0
                                                                                                                                                                                                                                                                                                  K_1 \leqslant : \lfloor \tau_2 \rfloor
794
                                                 \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} \langle e_0, e_1 \rangle : Pair
                                                                                                                                                    \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} \mathsf{app}\{\tau_1\} e_0 e_1 : \lfloor \tau_1 \rfloor
                                                                                                                                                                                                                                                                         \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} unop\{\tau_2\} e_0 : \lfloor \tau_2 \rfloor
795
796
797
                                                                   \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : K_0
                                                                   \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_1 : K_1
                                                           \Delta(binop, K_0, K_1) = K_2
                                                                                                                                                                                                                                                                                                              \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : K_0
800
                                                                                                                                                                                                    \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : \mathcal{U}
                                                                                                                                                                                                                                                                                                                      K_0 \leqslant : K_1
                                                                           K_2 \leqslant : |\tau_3|
801
802
                                                                                                                                                                                                                                                                                                              \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : K_1
                                               \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} binop\{\tau_3\} e_0 e_1 : |\tau_3|
                                                                                                                                                                       \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} \mathsf{dyn} \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) e_0 : |\tau_0|
805
                        \mathcal{T};\Gamma \vdash_{\mathsf{T}} e:\mathcal{U}
806
807
                                                                                               \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : \mathcal{U} \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : K_0
                              (p_0:\mathcal{U})\in\mathcal{T}_0
808
809
                                                                                               \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} \mathsf{check}\, \mathcal{U} \, e_0 \, \mathsf{p}_0 : \mathcal{U} \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} \mathsf{check}\, \mathcal{U} \, e_0 \, \mathsf{p}_0 : \mathcal{U}
810
811
                                                                                                                                                                                        \mathcal{T}_0; (x_0:\tau_0), \Gamma_0 \vdash_\mathsf{T} e_0:K_0
                                                                                                                                                                                                                                                                                             \mathcal{T}_0; (x_0 : \mathcal{U}), \Gamma_0 \vdash_\mathsf{T} e_0 : \mathcal{U}
812
813
                                      \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} n_0 : \mathcal{U}
                                                                                                                \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} i_0 : \mathcal{U}
                                                                                                                                                                                        \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} \lambda(x_0 : \tau_0). e_0 : \mathcal{U}
                                                                                                                                                                                                                                                                                                   \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} \lambda x_0. e_0 : \mathcal{U}
814
815
                                                              \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : \mathcal{U}
                                                                                                                                                                        \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : \mathcal{U}
                                                              \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_1 : \mathcal{U}
                                                                                                                                                                        \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_1 : \mathcal{U}
                                                                                                                                                                                                                                                                                        \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : \mathcal{U}
818
                                                      \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} \langle e_0, e_1 \rangle : \mathcal{U}
                                                                                                                                                       \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} \mathsf{app}\{\tau_1\} e_0 e_1 : \mathcal{U}
                                                                                                                                                                                                                                                                          \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} unop\{\tau_2\} e_0 : \mathcal{U}
819
820
                                                                                                      \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : \mathcal{U}
821
                                                                                                                                                                                                                                          \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : K_0
                                                                                                      \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_1 : \mathcal{U}
822
823
                                                                                                                                                                                                                        \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} \mathsf{stat} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) e_0 : \mathcal{U}
                                                                                  \mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} binop\{\tau_3\} \ e_0 \ e_1 : \mathcal{U}
824
825
826
                        \mathcal{T} \vdash_T \mathcal{H}
827
828
                                                                                                                                              \forall (p_0 \mapsto v_0) \in \mathcal{H}_0 . \mathcal{T}_0; \cdot \vdash_T v_0 : \mathcal{T}_0(p_0)
829
                                                                                                                                                                                        \mathcal{T}_0 \vdash_\mathsf{T} \mathcal{H}_0
```

```
K \leqslant : K
```

Nat ≤: Int

 $K_0 \leqslant : K_0$

 $\xrightarrow{*}_{T}$ reflexive-transitive closure of $\xrightarrow{}_{T}$

 $e;\mathcal{H};\mathcal{B}\to_\mathsf{T} e;\mathcal{H};\mathcal{B}$

 $E[e_0]; \mathcal{H}_0; \mathcal{B}_0 \longrightarrow_{\mathsf{T}} E[e_1]; \mathcal{H}_1; \mathcal{B}_1$

if $e_0; \mathcal{H}_0; \mathcal{B}_0 \bowtie_{\mathsf{T}} e_1; \mathcal{H}_1; \mathcal{B}_1$ $\mathit{E}[\mathsf{Err}];\mathcal{H}_0;\mathcal{B}_0 \ \to_\mathsf{T} \ \mathsf{Err};\mathcal{H}_0;\mathcal{B}_0$

```
e; \mathcal{H}; \mathcal{B} \bowtie_{\mathsf{T}} e; \mathcal{H}; \mathcal{B}
885
886
                   w_0;\mathcal{H}_0;\mathcal{B}_0
                                                                                           887
                         where p_0 fresh in \mathcal{H}_0 and \mathcal{B}_0
888
889
                    (unop\{\tau_0\} v_0); \mathcal{H}_0; \mathcal{B}_0
                                                                                           \triangleright_{\mathsf{T}} \mathsf{TagErr} \circ : \mathcal{H}_0 : \mathcal{B}_0
890
                         if \delta(unop, \mathcal{H}_0(v_0)) is undefined
891
                                                                                           \triangleright_{\!\mathsf{T}} \mathsf{TagErr} \bullet; \mathcal{H}_0; \mathcal{B}_0
                   (unop{U} v_0); \mathcal{H}_0; \mathcal{B}_0
892
                         if \delta(unop, \mathcal{H}_0(v_0)) is undefined
                   (\textit{unop}\{\tau?\}\:p_0);\mathcal{H}_0;\mathcal{B}_0
                                                                                           \triangleright_{\mathsf{T}} (\mathsf{check}\, \tau? \, \delta(\mathit{unop}, \mathcal{H}_0(\mathsf{p}_0)) \, \mathsf{p}_0); \mathcal{H}_0; \mathcal{B}_0
                         if \delta(unop, \mathcal{H}_0(p_0)) is defined
                    (binop\{\tau_0\} v_0 v_1); \mathcal{H}_0; \mathcal{B}_0
                                                                                           \triangleright_{\mathsf{T}} \mathsf{TagErr} \circ; \mathcal{H}_0; \mathcal{B}_0
                         if \delta(binop, v_0, v_1) is undefined
898
899
                   (binop\{\mathcal{U}\}\ v_0\ v_1);\mathcal{H}_0;\mathcal{B}_0
                                                                                           \triangleright_{\mathsf{T}} \mathsf{TagErr} \bullet; \mathcal{H}_0; \mathcal{B}_0
900
                         if \delta(binop, v_0, v_1) is undefined
901
                    (binop\{\tau?\} i_0 i_1); \mathcal{H}_0; \mathcal{B}_0
                                                                                           \triangleright_{\mathsf{T}} \delta(binop, i_0, i_1); \mathcal{H}_0; \mathcal{B}_0
902
                         if \delta(binop, i_0, i_1) is defined
903
904
                   (app\{\tau_0\} v_0 v_1); \mathcal{H}_0; \mathcal{B}_0
                                                                                           \triangleright_{\mathsf{T}} \mathsf{TagErr} \circ ; \mathcal{H}_0 ; \mathcal{B}_0
905
                         if \mathcal{H}_0(v_0) \notin (\lambda x. e) \cup (\lambda(x:\tau). e)
906
                   (app{\mathcal{U}} v_0 v_1); \mathcal{H}_0; \mathcal{B}_0
                                                                                           \triangleright_{\mathsf{T}} \mathsf{TagErr} \bullet; \mathcal{H}_0; \mathcal{B}_0
907
                         if \mathcal{H}_0(v_0) \notin (\lambda x. e) \cup (\lambda(x:\tau). e)
                    (app\{\tau?\} p_0 v_0); \mathcal{H}_0; \mathcal{B}_0
                                                                                           \triangleright_{\mathsf{T}} (\mathsf{check}\, \tau? e_0[x_0 \leftarrow v_0] \, \mathsf{p}_0); \mathcal{H}_0; \mathcal{B}_0[v_0 \cup \mathit{rev}(\mathcal{B}_0(\mathsf{p}_0))]
910
                         if \mathcal{H}_0(\mathsf{p}_0) = \lambda(x_0 : \tau_0). e_0 and tag\text{-}match(\lfloor \tau_0 \rfloor, \mathcal{H}_0(\upsilon_0))
911
                                                                                           (app\{\tau?\} p_0 v_0); \mathcal{H}_0; \mathcal{B}_0
912
                         if \mathcal{H}_0(p_0) = \lambda(x_0 : \tau_0). e_0 and \neg tag-match(\lfloor \tau_0 \rfloor, \mathcal{H}_0(v_0))
913
914
                    (app\{\tau_0\} p_0 v_0); \mathcal{H}_0; \mathcal{B}_0
                                                                                           \triangleright_{\mathsf{T}} \left( \mathsf{check} \, \tau_0 \, e_0[x_0 \leftarrow v_0] \, \mathsf{p}_0 \right) ; \mathcal{H}_0; \mathcal{B}_0[v_0 \cup \mathit{rev}(\mathcal{B}_0(\mathsf{p}_0))]
915
                         if \mathcal{H}_0(p_0) = \lambda x_0. e_0
916
                                                                                           \triangleright_{\mathsf{T}} (e_0[x_0 \leftarrow v_0]); \mathcal{H}_0; \mathcal{B}_0
                   (app{U} p_0 v_0); \mathcal{H}_0; \mathcal{B}_0
917
                         if \mathcal{H}_0(\mathsf{p}_0) = \lambda x_0. e_0
918
919
                   920
                         if tag-match(\lfloor \tau_0 \rfloor, \mathcal{H}_0(v_0))
921
                    (\operatorname{dyn}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_0); \mathcal{H}_0; \mathcal{B}_0 \bowtie_{\mathsf{T}} \operatorname{BndryErr}(\{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\}, v_0); \mathcal{H}_0; \mathcal{B}_0
                         if \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \mathcal{H}_0(\upsilon_0))
923
924
                   (\operatorname{stat}(\ell_0 \triangleleft \tau_0 \triangleleft \ell_1) v_0); \mathcal{H}_0; \mathcal{B}_0 \bowtie_{\mathsf{T}} v_0; \mathcal{H}_0; (\mathcal{B}_0[v_0 \cup \{(\ell_0 \triangleleft \tau_0 \triangleleft \ell_1)\}])
925
                         if tag-match(\lfloor \tau_0 \rfloor, \mathcal{H}_0(v_0))
926
                   (\text{stat} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_0); \mathcal{H}_0; \mathcal{B}_0 \ \triangleright_{\mathsf{T}} \ \mathsf{TagErr} \circ; \mathcal{H}_0; \mathcal{B}_0
927
                         if \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \mathcal{H}_0(v_0))
928
929
                    (\operatorname{check} \mathcal{U} v_0 p_0); \mathcal{H}_0; \mathcal{B}_0
                                                                                           \triangleright_{\mathsf{T}} v_0; \mathcal{H}_0; \mathcal{B}_0
930
                    (check \tau_0 v_0 p_0); \mathcal{H}_0; \mathcal{B}_0
                                                                                           931
                         if tag\text{-}match(\lfloor \tau_0 \rfloor, \mathcal{H}_0(\upsilon_0))
932

hildsymbol{\triangleright}_{\!\mathsf{T}} \; \mathsf{BndryErr} \left( \mathcal{B}_0(v_0) \cup \mathcal{B}_0(\mathsf{p}_0), v_0 \right) ; \mathcal{H}_0 ; \mathcal{B}_0
                   (check \tau_0 v_0 p_0); \mathcal{H}_0; \mathcal{B}_0
933
934
                         if \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \mathcal{H}_0(v_0))
```

3.2 Transient (Path-Based) Ownership Lifting

Transient Language extends Ownership Evaluation Language

p = countable set of heap locations

$$v = i \mid n \mid p \mid (v)^{\ell}$$

$$\mathbf{w} = \lambda x. e \mid \lambda(x:\tau). e \mid \langle v, v \rangle$$

$$e = \dots | p | \operatorname{check} \tau ? e p | (e)^{\ell}$$

$$E = \dots \mid \operatorname{check} \tau ? E p \mid (E)^{\ell}$$

$$\mathcal{H} = \mathcal{P}((p \mapsto w))$$

$$\mathcal{B} = \mathcal{P}((p \mapsto b^*))$$

$$O = \mathcal{P}((p \mapsto \overline{\ell}))$$

$$\mathcal{T} = \cdot | (\mathbf{p} : \tau?), \mathcal{T}$$

$$\cdot [\cdot \mapsto \cdot] : O \times v \times \ell^* \longrightarrow O$$
 ownership map replace

$$\begin{aligned} \boxed{ \cdot [\cdot \mapsto \cdot] : O \times v \times \ell^* \longrightarrow O } & \text{ ownership map replace } \\ O_0[v_0 \mapsto \ell_0^*] = \left\{ \begin{array}{l} \{v_0 \mapsto \ell_0^*\} \cup (O_0 \setminus (v_0 \mapsto \ell_1^*)) \\ & \text{ if } v_0 \in \text{p and } (v_0 \mapsto \ell_1^*) \in O_0 \\ O_0[v_1 \mapsto \ell_0^*] \\ & \text{ if } v_0 = (\!(v_1)\!)^{\overline{\ell}_0} \\ O_0 & \text{ otherwise} \end{array} \right.$$

 $\boxed{ \begin{bmatrix} \cdot [\cdot \cup \cdot] : O \times v \longrightarrow \ell^* \\ O_0[v_0 \cup \ell_0^*] = & O_0[v_0 \mapsto \ell_0^* \cup O_0(v_0)] \end{bmatrix}}$ ownership map update

$$O_0[v_0 \cup \ell_0^*] = O_0[v_0 \mapsto \ell_0^* \cup O_0(v_0)]$$

$$\mathcal{T}; \Gamma \vdash_{\mathsf{T}} e : K$$
 extends \vdash_{T}

$$\frac{\mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : K_0}{\mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} (e_0)^{\ell_0} : K_0}$$

$$\mathcal{T};\Gamma \vdash_{\mathsf{T}} e:\mathcal{U}$$
 extends \vdash_{T}

$$\frac{\mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} e_0 : \mathcal{U}}{\mathcal{T}_0; \Gamma_0 \vdash_\mathsf{T} (e_0)^{\ell_0} : \mathcal{U}}$$

 $O; L; \ell \Vdash_T e$ lifts and extends \Vdash and enforces ownership consistency

$$\begin{array}{c} O_0; L_0; \ell_0 \ \overline{\Vdash}_{\mathsf{T}} \ e_0 \\ \\ O_0; L_0; \ell_0 \ \overline{\Vdash}_{\mathsf{T}} \ (e_0)^{\ell_0} \end{array} \qquad \qquad \begin{array}{c} O_0; L_0; \ell_0 \ \overline{\Vdash}_{\mathsf{T}} \ e_0 \\ \\ O_0; L_0; \ell_0 \ \overline{\Vdash}_{\mathsf{T}} \ \operatorname{check} \tau ? e_0 \ p_0 \end{array}$$

 $\rightarrow_{\overline{T}}^*$ reflexive-transitive closure of $\longrightarrow_{\overline{T}}$

2019-10-03 17:26. Page 19 of 1-148.

```
e; \mathcal{H}; \mathcal{B} \longrightarrow_{\overline{\tau}} e; \mathcal{H}; \mathcal{B}
989
990
                                           \overline{E[e_0]^{\ell_0}; \mathcal{H}_0; \mathcal{B}_0 \longrightarrow_{\overline{\mathsf{T}}} E[e_1]^{\ell_0}; \mathcal{H}_1; \mathcal{B}_1}
991
                                                        if (e_0)^{\ell_0}; \mathcal{H}_0; \mathcal{B}_0 \triangleright_{\overline{\tau}} (e_1)^{\ell_0}; \mathcal{H}_1; \mathcal{B}_1
 992
                                           E[\mathsf{Err}]; \mathcal{H}_0; \mathcal{B}_0 \longrightarrow_{\overline{\mathsf{T}}} \mathsf{Err}; \mathcal{H}_0; \mathcal{B}_0
 994
                                          (e)^{\ell};\mathcal{H};\mathcal{B} \bowtie_{\overline{\mathsf{T}}} (e)^{\ell};\mathcal{H};\mathcal{B}
 995
 996
                                             (\mathbf{w}_0)^{\ell_0}: \mathcal{H}_0: \mathcal{B}_0
                                                                                                                                                                                                                                               \rhd_{\overline{\tau}} \ (p_0)^{\ell_0}; (\{p_0 \mapsto w_0\} \cup \mathcal{H}_0); (\{p_0 \mapsto \emptyset\} \cup \mathcal{B}_0)
 997
                                                          where p_0 fresh in \mathcal{H}_0 and \mathcal{B}_0
                                             (unop\{\tau_0\}((v_0))^{\overline{\ell}_0})^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                                                                                                                              \triangleright_{\overline{\tau}} (\mathsf{TagErr} \circ)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0
 1000
1001
                                                          if \delta(unop, \mathcal{H}_0(v_0)) is undefined
1002
                                                                                                                                                                                                                                              \triangleright_{\overline{\mathsf{T}}} (\mathsf{TagErr} \bullet)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0
                                             (unop\{\mathcal{U}\}((v_0))^{\overline{\ell}_0})^{\ell_1};\mathcal{H}_0;\mathcal{B}_0
1003
                                                         if \delta(unop, \mathcal{H}_0(v_0)) is undefined
1004
1005
                                            (unop\{\tau?\}((p_0))^{\overline{\ell}_0})^{\ell_1};\mathcal{H}_0;\mathcal{B}_0
                                                                                                                                                                                                                                               1006
                                                          if \delta(unop, \mathcal{H}_0(p_0)) is defined
1007
                                            (\mathit{binop}\{\tau_0\}\,(\!(v_0)\!)^{\overline{\ell}_0}\,(\!(v_1)\!)^{\overline{\ell}_1})^{\ell_2};\mathcal{H}_0;\mathcal{B}_0\  \, \triangleright_{\overline{\mathsf{T}}}\  \, (\mathsf{TagErr}\,\circ)^{\ell_2};\mathcal{H}_0;\mathcal{B}_0
1008
1009
                                                          if \delta(binop, v_0, v_1) is undefined
1010
                                            (binop\{\mathcal{U}\} ((v_0))^{\overline{\ell}_0} ((v_1))^{\overline{\ell}_1})^{\ell_2}; \mathcal{H}_0; \mathcal{B}_0 \geqslant_{\overline{\tau}} (TagErr \bullet)^{\ell_2}; \mathcal{H}_0; \mathcal{B}_0
1011
1012
                                                         if \delta(binop, v_0, v_1) is undefined
1013
                                            (\mathit{binop}\{\tau?\} (\!(i_0)\!)^{\overline{\ell}_0} (\!(i_1)\!)^{\overline{\ell}_1})^{\ell_2}; \mathcal{H}_0; \mathcal{B}_0 \quad \triangleright_{\overline{\mathsf{T}}} (\delta(\mathit{binop},i_0,i_1))^{\ell_2}; \mathcal{H}_0; \mathcal{B}_0
1014
1015
                                                         if \delta(binop, i_0, i_1) is defined
1016
                                            (app\{\tau_0\} ((v_0))^{\overline{\ell}_0} v_1)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0

ightharpoonup_{\overline{1}} (\mathsf{TagErr} \circ)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0
1017
1018
                                                         if \mathcal{H}_0(v_0) \notin (\lambda x. e) \cup (\lambda(x:\tau). e)
1019
                                            (\operatorname{\mathsf{app}}\{\mathcal{U}\}((v_0))^{\overline{\ell}_0} \ v_1)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                                                                                                                              \triangleright_{\overline{\mathsf{T}}} (\mathsf{TagErr} \bullet)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0
1020
1021
                                                         if \mathcal{H}_0(v_0) \notin (\lambda x. e) \cup (\lambda(x:\tau). e)
1022
                                                                                                                                                                                                                                               \blacktriangleright_{\overline{1}} (\mathsf{check}\, \tau?\, e_0[x_0 \leftarrow (\!(v_0)\!)^{\overline{\ell}_1 rev(\overline{\ell}_0)}] \, \mathsf{p}_0)^{\overline{\ell}_0 \ell_1}; \mathcal{H}_0; \mathcal{B}_0[v_0 \cup rev(\mathcal{B}_0(\mathsf{p}_0))]
                                             (\operatorname{app}\{\tau?\} ((p_0))^{\overline{\ell}_0} v_0)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0
1023
                                                         if \mathcal{H}_0(\mathsf{p}_0) = \lambda(x_0 : \tau_0). e_0 and tag\text{-}match(\lfloor \tau_0 \rfloor, \mathcal{H}_0(\upsilon_0))
1024
 1025
                                                                                                                                                                                                                                               \blacktriangleright_{\overline{\mathsf{T}}} \; (\mathsf{BndryErr} \left( \! \left( \! \left( \mathcal{B}_0(\mathsf{p}_0) \right) \! \right)^{\overline{\ell}_0}, v_0) \right)^{\ell_1} ; \mathcal{H}_0; \mathcal{B}_0
                                            (\operatorname{app}\{\tau?\}((p_0))^{\overline{\ell}_0} v_0)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0
1026
                                                         if \mathcal{H}_0(p_0) = \lambda(x_0 : \tau_0). e_0 and \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \mathcal{H}_0(v_0))
1027
1028
                                                                                                                                                                                                                                              \Vdash_{\overline{1}} (\mathsf{check}\, \tau_0\, e_0[x_0 \!\leftarrow\! (\!(v_0)\!)^{\overline{\ell}_1 rev(\overline{\ell}_0)}]\, p_0)^{\overline{\ell}_0 \ell_1}; \mathcal{H}_0; \mathcal{B}_0[v_0 \cup \mathit{rev}(\mathcal{B}_0(p_0))]
                                             (\operatorname{app}\{\tau_0\} ((p_0))^{\overline{\ell}_0} v_0)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0
1029
                                                         if \mathcal{H}_0(p_0) = \lambda x_0. e_0
1030
1031
                                                                                                                                                                                                                                             \triangleright_{\overline{\mathsf{T}}} (e_0[x_0 \leftarrow ((v_0))^{\overline{\ell}_1 rev(\overline{\ell}_0)}])^{\overline{\ell}_0 \ell_1}; \mathcal{H}_0; \mathcal{B}_0
                                            (\operatorname{app}\{\mathcal{U}\}((p_0))^{\overline{\ell}_0} v_0)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0
1032
                                                          if \mathcal{H}_0(p_0) = \lambda x_0. e_0
1033
1034
                                            (\operatorname{dyn}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) ((v_0))^{\overline{\ell}_0})^{\ell_2}; \mathcal{H}_0; \mathcal{B}_0 \quad \triangleright_{\overline{\tau}} (v_0)^{\overline{\ell}_0 \ell_2}; \mathcal{H}_0; (\mathcal{B}_0[v_0 \cup \{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\}])
1035
                                                          if tag-match(\lfloor \tau_0 \rfloor, \mathcal{H}_0(v_0))
1036
                                            \left(\operatorname{dyn}\left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) (\!(v_0)\!)^{\overline{\ell}_0}\right)^{\ell_2} ; \mathcal{H}_0; \mathcal{B}_0 \quad \triangleright_{\overline{\mathbb{T}}} \ \left(\operatorname{BndryErr}\left(\{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\}, (\!(v_0)\!)^{\overline{\ell}_0}\right)\right)^{\ell_2} ; \mathcal{H}_0; \mathcal{B}_0 \right)^{\ell_2} + \left(\operatorname{BndryErr}\left(\{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\}, (\!(v_0)\!)^{\overline{\ell}_0}\right)\right)^{\ell_2} + \left(\operatorname{BndryErr}\left(\{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\}, (\!(v_0)\!)^{\overline{\ell}_0}\right)\right)^{\ell_2} \right)^{\ell_2} + \left(\operatorname{BndryErr}\left(\{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\}, (\!(v_0)\!)^{\overline{\ell}_0}\right)\right)^{\ell_2} + \left(\operatorname{BndryErr}\left(\{(\ell_0 \blacktriangleleft \tau_0 + \ell_0\}, (\!(v_0)\!)^{\overline{\ell}_0}\right)\right)^{\ell_2} + \left(\operatorname{BndryErr}\left(\{(\ell_0 + \ell_0\}, (\!(v_0)\!)^{\overline{\ell}_0}\right)\right)^{\ell_2} + \left(\operatorname{BndryErr}\left(\{(\ell_0 + \ell_0\}, (\!(v_0)\!)^{\overline{\ell}_0}\right)\right)^{\ell_2} + \left(\operatorname{BndryErr}\left(\{(\ell_0 + \ell_0\}, (\!(v_0)\!)
1037
1038
                                                          if \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \mathcal{H}_0(\upsilon_0))
1039
```

3.3 Transient Heap-Based Ownership Lifting

Transient Language extends Transient Ownership Evaluation Language
$$O = \mathcal{P}((\mathsf{p} \mapsto \ell^*))$$

 $O \overline{\Vdash}_{\mathsf{T}} \mathcal{H}$ enforces ownership consistency for the heap

$$\frac{\forall (p_0 \mapsto v_0) \in \mathcal{H}_0 . O_0; \cdot; O(p_0) \ \overline{\Vdash}_T \ v_0}{O_0 \ \overline{\Vdash}_T \ \mathcal{H}_0}$$

2019-10-03 17:26. Page 21 of 1-148.

```
\overline{(e)^{\ell}; \mathcal{H}; \mathcal{B}; O} \bowtie_{\overline{T}_{2}} (e)^{\ell}; \mathcal{H}; \mathcal{B}; O

1093
1094
                                                                                                                                                         \rhd_{\overline{T}_2} \ (p_0)^{\ell_0}; (\{p_0 \mapsto w_0\} \cup \mathcal{H}_0); (\{p_0 \mapsto \emptyset\} \cup \mathcal{B}_0); (\{p_0 \mapsto \ell_0\} \cup \mathcal{O}_0)
                          (\mathbf{w}_0)^{\ell_0}; \mathcal{H}_0; \mathcal{B}_0; O_0
1095
1096
                                  where p_0 fresh in \mathcal{H}_0 and \mathcal{B}_0 and O_0
1097
                          (unop\{\tau_0\} ((v_0))^{\overline{\ell}_0})^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0
                                                                                                                                                         \triangleright_{\overline{T}_2} (\mathsf{TagErr} \circ)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; \mathcal{O}_0
1098
1099
                                  if \delta(unop, \mathcal{H}_0(v_0)) is undefined
1100
                          (unop\{\mathcal{U}\}((v_0))^{\overline{\ell}_0})^{\ell_1};\mathcal{H}_0;\mathcal{B}_0;O_0
                                                                                                                                                         \triangleright_{\overline{T}_2} (\mathsf{TagErr} \bullet)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0
1101
                                  if \delta(unop, \mathcal{H}_0(v_0)) is undefined
1102
1103
                          (unop\{\tau?\} ((p_0))^{\overline{\ell}_0})^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0
                                                                                                                                                         \triangleright_{\overline{T}_2} (\text{check } \tau? \delta(unop, \mathcal{H}_0(p_0)) p_0)^{\overline{\ell}_0 \ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0
1104
                                 if \delta(unop, \mathcal{H}_0(p_0)) is defined
1105
                          (\mathit{binop}\{\tau_0\}\,(\!(v_0)\!)^{\overline{\ell}_0}\,(\!(v_1)\!)^{\overline{\ell}_1})^{\ell_2};\mathcal{H}_0;\mathcal{B}_0;O_0 \  \, \blacktriangleright_{\overline{\mathsf{T}}_2} \  \, (\mathsf{TagErr}\,\circ)^{\ell_2};\mathcal{H}_0;\mathcal{B}_0;O_0
1106
1107
                                 if \delta(binop, v_0, v_1) is undefined
1108
                          (\mathit{binop}\{\mathcal{U}\}\,(\!(v_0)\!)^{\overline{\ell}_0}\,(\!(v_1)\!)^{\overline{\ell}_1})^{\ell_2};\mathcal{H}_0;\mathcal{B}_0;O_0\  \,  \triangleright_{\overline{\mathsf{T}}_2}\  \, (\mathsf{TagErr}\,\bullet)^{\ell_2};\mathcal{H}_0;\mathcal{B}_0;O_0
1109
1110
                                 if \delta(binop, v_0, v_1) is undefined
1111
                          (\mathit{binop}\{\tau?\}((i_0))^{\overline{\ell}_0}((i_1))^{\overline{\ell}_1})^{\ell_2};\mathcal{H}_0;\mathcal{B}_0;O_0 \quad \triangleright_{\overline{\tau}_2} (\delta(\mathit{binop},i_0,i_1))^{\ell_2};\mathcal{H}_0;\mathcal{B}_0;O_0)
1112
1113
                                  if \delta(binop, i_0, i_1) is defined
1114
                                                                                                                                                       \triangleright_{\overline{T}_2} (\mathsf{TagErr} \circ)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0
                          (app\{\tau_0\} ((v_0))^{\overline{\ell}_0} v_1)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0
1115
                                  if \mathcal{H}_0(v_0) \notin (\lambda x. e) \cup (\lambda(x:\tau). e)
1117
                                                                                                                                                         \triangleright_{\overline{T}_2} (\mathsf{TagErr} \bullet)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0
                          (\operatorname{app}\{\mathcal{U}\}((v_0))^{\overline{\ell}_0} v_1)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0
1118
1119
                                  if \mathcal{H}_0(v_0) \notin (\lambda x. e) \cup (\lambda(x:\tau). e)
1120
                          (app\{\tau?\} ((p_0))^{\overline{\ell}_0} v_0)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0
                                        \begin{split} & \{\tau?\} \, (\!(\mathsf{p}_0)\!)^{\ell_0} \, v_0)^{\tau_1}; \mathcal{H}_0; \mathcal{B}_0; O_0 & \trianglerighteq_{\overline{\mathsf{1}}2} \\ & (\mathsf{check} \, \tau? \, e_0[x_0 \leftarrow (\!(v_0)\!)^{\ell_1 rev(\overline{\ell_0})}] \, \mathsf{p}_0)^{-\overline{\ell_0}\ell_1}; \mathcal{H}_0; \mathcal{B}_0[v_0 \cup rev(\mathcal{B}_0(\mathsf{p}_0))]; O_0[v_1 \cup O_0(\mathsf{p}_0) \cup \{\ell_1\}] \end{split}
1121
1122
1123
                                 if \mathcal{H}_0(p_0) = \lambda(x_0 : \tau_0). e_0 and tag\text{-}match(|\tau_0|, \mathcal{H}_0(v_0))
1124
                          (\operatorname{app}\{\tau?\} ((p_0))^{\overline{\ell}_0} v_0)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0
1125
                                          \begin{aligned} & \{\tau?\} \left(\!\!\left(\mathsf{p}_0\right)\!\!\right)^{\ell_0} v_0\right) \, \dot{}; \mathcal{H}_0; \mathcal{B}_0; O_0 & \triangleright_{\overline{\mathsf{T}}_2} \\ & \left(\mathsf{BndryErr} \left(\!\!\left(\!\!\left(\mathcal{B}_0(\mathsf{p}_0)\right)\!\!\right)^{\overline{\ell}_0}, \left(\!\!\left(v_0\right)\!\!\right)^{\ell_1 rev(\overline{\ell}_0)}\right)\!\!\right)^{\overline{\ell}_1}; \mathcal{H}_0; \mathcal{B}_0; O_0[v_0 \cup O_0(\mathsf{p}_0) \cup \ell_1] \end{aligned}
1126
1127
                                 if \mathcal{H}_0(p_0) = \lambda(x_0 : \tau_0). e_0 and \neg tag\text{-}match(|\tau_0|, \mathcal{H}_0(v_0))
1128
                          (\operatorname{app}\{\tau_0\} ((p_0))^{\overline{\ell}_0} v_0)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0
                                         \begin{split} & \{\tau_0\} \left(\!\!\left(\mathsf{p}_0\right)\!\!\right)^{\!t_0} v_0\right) \; ; \mathcal{H}_0; \mathcal{B}_0; O_0 & \triangleright_{\overline{\mathsf{T}}2} \\ & \left(\mathsf{check} \; \tau_0 \; e_0[x_0 \leftarrow \left(\!\!\left(v_0\right)\!\!\right)^{\!\ell_1 rev(\overline{\ell_0})}] \; \mathsf{p}_0\right)^{\!-\overline{\ell_0}\ell_1} ; \mathcal{H}_0; \mathcal{B}_0[v_0 \cup \mathit{rev}(\mathcal{B}_0(\mathsf{p}_0))]; O_0[v_0 \cup O_0(\mathsf{p}_0) \cup \{\ell_0\}] \end{split}
1130
1131
1132
                                 if \mathcal{H}_0(p_0) = \lambda x_0. e_0
1133
                                                                                                                                                    \triangleright_{\overline{t}_2} (e_0[x_0 \leftarrow ((v_0))^{\ell_1 rev(\overline{\ell}_0)}])^{\overline{\ell}_0 \ell_1}; \mathcal{H}_0; \mathcal{B}_0; \mathcal{O}_0[v_0 \cup \mathcal{O}_0(p_0) \cup \{\ell_0\}]
                          (\operatorname{app}\{\mathcal{U}\}((p_0))^{\overline{\ell}_0} \ v_0)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0
1134
1135
                                   if \mathcal{H}_0(p_0) = \lambda x_0. e_0
                          (\operatorname{dyn}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) ((v_0))^{\overline{\ell}_0})^{\ell_2}; \mathcal{H}_0; \mathcal{B}_0; O_0 \quad \triangleright_{\overline{T}_2} (v_0)^{\overline{\ell}_0 \ell_2}; \mathcal{H}_0; (\mathcal{B}_0[v_0 \cup \{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\}]); O_0[v_0 \cup \ell_2])^{\ell_0}
1137
1138
                                  if tag-match (\lfloor \tau_0 \rfloor, \mathcal{H}_0(\upsilon_0))
1139
                          (\operatorname{dyn}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \, (\!(v_0)\!)^{\overline{\ell}_0})^{\ell_2}; \mathcal{H}_0; \mathcal{B}_0; O_0 \quad \triangleright_{\overline{T}_2} \, (\operatorname{BndryErr}(\{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\}, (\!(v_0)\!)^{\overline{\ell}_0}))^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0)^{\ell_2})^{\ell_3}
1140
1141
                                  if \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \mathcal{H}_0(\upsilon_0))
1142
```

```
(\operatorname{stat}\left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) (\!(v_0)\!)^{\overline{\ell}_0}\big)^{\ell_2}; \mathcal{H}_0; \mathcal{B}_0; O_0 \  \, \bowtie_{\overline{\mathbb{T}}_2} \  \, (v_0)^{\overline{\ell}_0\ell_2}; \mathcal{H}_0; (\mathcal{B}_0[v_0 \cup \{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\}]); O_0[v_0 \cup \{\ell_2\}]
1145
1146
                                    if tag-match (\lfloor \tau_0 \rfloor, \mathcal{H}_0(v_0))
1147
                           (\operatorname{stat}(\ell_{0} \blacktriangleleft \tau_{0} \blacktriangleleft \ell_{1}) ((v_{0}))^{\overline{\ell_{0}}})^{\ell_{2}}; \mathcal{H}_{0}; \mathcal{B}_{0}; O_{0} \bowtie_{\overline{\mathsf{T}}_{2}} (\operatorname{\mathsf{TagErr}} \circ)^{\ell_{1}}; \mathcal{H}_{0}; \mathcal{B}_{0}; O_{0}
1148
1149
                                  if \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \mathcal{H}_0(v_0))
1150

\triangleright_{\overline{1}2} (v_0)^{\overline{\ell}_0 \ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0[v_0 \cup O_0(p_0)]

\triangleright_{\overline{1}2} (v_0)^{\overline{\ell}_0 \ell_1}; \mathcal{H}_0; (\mathcal{B}_0[v_0 \cup \mathcal{B}_0(p_0)]); O_0[v_0 \cup O_0(p_0)]

                           (\operatorname{check} \mathcal{U}(v_0))^{\overline{\ell}_0} \operatorname{p}_0)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0
1151
1152
                           (\operatorname{check} \tau_0 ((v_0))^{\overline{\ell}_0} p_0)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0
1153
                                    if tag-match (\lfloor \tau_0 \rfloor, \mathcal{H}_0(v_0))
1154
                                                                                                                                                               \Vdash_{\overline{\mathbb{T}^2}} \left(\mathsf{BndryErr}\left(\mathcal{B}_0(v_0) \cup \mathcal{B}_0(\mathsf{p}_0), (\!(v_0)\!)^{\overline{\ell}_0}\right)\right)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0[v_0 \cup O_0(\mathsf{p}_0)]
1155
                           (\operatorname{check} \tau_0 ((v_0))^{\overline{\ell}_0} p_0)^{\ell_1}; \mathcal{H}_0; \mathcal{B}_0; O_0
1156
                                    if \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \mathcal{H}_0(\upsilon_0))
1157
1158
```

```
1197
                    4 Amnesic
1198
                    4.1 Normal Amnesic
1199
1200
                      Amnesic Language extends Base Evaluation Language
1201
                       v = \dots \mid \operatorname{trace}_{v} \overline{b} v \mid \operatorname{mon} (\ell \blacktriangleleft \tau \Rightarrow \tau \blacktriangleleft \ell) (v)^{\ell} \mid \operatorname{mon} (\ell \blacktriangleleft \tau \times \tau \blacktriangleleft \ell) (v)^{\ell}
1202
                       e = \dots \mid \operatorname{trace} \overline{b} e
1203
                       E = \dots \mid \operatorname{trace} \overline{b} E
1204
1205
                      \Gamma \vdash_{\mathsf{A}} e : \tau extends \Gamma \vdash e : \tau
1206
1207
                                                                                                 \frac{\Gamma \vdash_{\mathsf{A}} v_0 : \mathcal{U}}{\Gamma \vdash_{\mathsf{A}} \mathsf{mon} \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) v_0 : \tau_0} \qquad \qquad \frac{\Gamma \vdash_{\mathsf{A}} \mathsf{Err} : \tau_0}{\Gamma \vdash_{\mathsf{A}} \mathsf{Err} : \tau_0}
1208
1209
1210
                      \Gamma \vdash_{\mathsf{A}} e : \mathcal{U} extends \Gamma \vdash e : \mathcal{U}
1211
1212
                               \frac{\Gamma \vdash_{\mathsf{A}} v_0 : \tau_0}{\Gamma \vdash_{\mathsf{A}} \mathsf{mon} \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) v_0 : \mathcal{U}} \qquad \frac{\Gamma \vdash_{\mathsf{A}} e_0 : \mathcal{U}}{\Gamma \vdash_{\mathsf{A}} \mathsf{trace} \overline{b}_0 \, e_0 : \mathcal{U}} \qquad \frac{\Gamma \vdash_{\mathsf{A}} e_0 : \mathcal{U}}{\Gamma \vdash_{\mathsf{A}} \mathsf{trace}_{\mathsf{v}} \overline{b}_0 \, e_0 : \mathcal{U}} \qquad \frac{\Gamma \vdash_{\mathsf{A}} \mathsf{Err} : \mathcal{U}}{\Gamma \vdash_{\mathsf{A}} \mathsf{trace}_{\mathsf{v}} \overline{b}_0 \, e_0 : \mathcal{U}}
1213
1214
1215
1216
                      trace, \overline{b_0} v_0 short for a v_1 such that get-trace (v_1) = \overline{b_0} and rem-trace (v_1) = v_0
1217
1218
                       \rightarrow_{A}^{*} reflexive-transitive closure of \rightarrow_{A}
1219
                       \rightarrow_{\mathsf{N}} compatible closure of \triangleright_{\mathsf{A}} \cup \blacktriangleright_{\mathsf{A}}
1221
1222
1223
1224
1225
1226
```

```
1249
                   e \triangleright_{\!\!\mathsf{A}} e
1250
                     unop\{\tau_0\}\ v_0
                                                                                                           \triangleright_{\!\!\!A} \mathsf{TagErr} \circ
1251
                           if v_0 \notin (\text{mon}(\ell \blacktriangleleft (\tau \times \tau) \blacktriangleleft \ell) v) and \delta(unop, v_0) is undefined
1252
1253
                                                                                                           \triangleright_{A} \delta(unop, v_0)
                     unop\{\tau_0\} v_0
1254
                           if \delta(unop, v_0) is defined
1255
                     fst\{\tau_0\} (mon (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) v_0)
                                                                                                           \rhd_{\mathsf{A}} \ \mathsf{dyn} \ b_0 \ (\mathsf{fst}\{\mathcal{U}\} \ v_0)
1256
                           where \tau_2 = fst(\tau_1) and b_0 = (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1)
1257
1258
                     \operatorname{snd}\{\tau_0\} \left(\operatorname{mon}\left(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1\right) \upsilon_0\right)
                                                                                                          \triangleright_{\!\!\!\!A} \; \mathsf{dyn} \; b_0 \; (\mathsf{snd}\{\mathcal{U}\} \, v_0)
1259
                           where \tau_2 = snd(\tau_1) and b_0 = (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1)
1260
                                                                                                           \triangleright_{A} TagErr \circ
                     binop\{\tau_0\} v_0 v_1
1261
                           if \delta(binop, v_0, v_1) is undefined
1262
1263
                                                                                                           \triangleright_{\Delta} \delta(binop, v_0, v_1)
                     binop\{\tau_0\} v_0 v_1
1264
                           if \delta(binop, v_0, v_1) is defined
1265
                     app\{\tau_0\} v_0 v_1
                                                                                                           \triangleright_{\!\!\!A} \mathsf{TagErr} \circ
1266
                           if v_0 \notin (\lambda(x:\tau). e) \cup (\text{mon } (\ell \blacktriangleleft (\tau \Rightarrow \tau) \blacktriangleleft \ell) v)
1267
1268
                                                                                                           \triangleright_{\mathsf{A}} e_0[x_0 \leftarrow v_1]
                     app\{\tau_0\} (\lambda(x_0:\tau_1). e_0) v_1
1269
                     \mathsf{app}\{\tau_0\} \left(\mathsf{mon} \ (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) \ v_0 \right) v_1 \ \rhd_{\!_{\mathbf{A}}} \ \mathsf{dyn} \ b_0 \ (\mathsf{app}\{\mathcal{U}\} \ v_0 \ (\mathsf{stat} \ b_1 \ v_1))
1270
                           where b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) and b_1 = (\ell_1 \blacktriangleleft dom(\tau_1) \blacktriangleleft \ell_0)
1271
                     dyn (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_0
                                                                                                           \triangleright_{\mathsf{A}} \mod (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_0
1272
                           if tag\text{-}match([\tau_0], v_0) and v_0 \in (\operatorname{trace}_v^? \bar{b}(\lambda(x : \tau). e)) \cup (\operatorname{trace}_v^? \bar{b}(\operatorname{mon}(\ell \blacktriangleleft (\tau \Rightarrow \tau) \blacktriangleleft \ell) v))
1273
1274
                     dyn (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (trace_v^? \overline{b_0} i_0)
                                                                                                          \triangleright_{\mathsf{A}} i_0
1275
                           if tag-match(\lfloor \tau_0 \rfloor, i_0)
1276
                                                                                                          \rhd_{\mathsf{A}} \; \mathsf{BndryErr} \left( (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \overline{b}_0, \upsilon_0 \right)
                     \operatorname{dyn}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_0
1277
1278
                           if \neg tag\text{-}match([\tau_0], \upsilon_0) and \overline{b}_0 = get\text{-}trace(\upsilon_0)
1279
1280
1281
1282
1283
1284
1285
1286
1287
1288
1289
1290
1291
1292
1293
1294
1295
1296
1297
1298
1299
```

2019-10-03 17:26. Page 26 of 1-148.

```
1301
                    e ►<sub>A</sub> e
1302
                      unop\{U\}v_0
                                                                                                                                          ► TagErr •
1303
                            if v_1 = rem\text{-}trace(v_0) and v_1 \notin mon(\ell \blacktriangleleft (\tau \times \tau) \blacktriangleleft \ell) v and \delta(unop, v_1) is undefined
1304
1305
                                                                                                                                           \blacktriangleright_{A} add-trace (get-trace (v_0), \delta(unop, v_1))
1306
                            if v_1 = rem\text{-}trace(v_0) and \delta(unop, v_1) is defined
1307
                      fst\{\mathcal{U}\}\ (trace_{v}^{?} \overline{b}_{0} \ (mon \ (\ell_{0} \blacktriangleleft \tau_{0} \blacktriangleleft \ell_{1}) \ v_{0}))
                                                                                                                                          \blacktriangleright_{\Delta} trace \bar{b}_0 (stat b_0 (fst\{\tau_1\} v_0))
1308
                            where \tau_1 = fst(\tau_0) and b_0 = (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)
1309
                                                                                                                                          \blacktriangleright_{\mathbf{A}} \operatorname{trace} \overline{b}_0 \left( \operatorname{stat} b_0 \left( \operatorname{snd} \{ \tau_1 \} v_0 \right) \right)
1310
                     \operatorname{snd}\{\mathcal{U}\}\left(\operatorname{trace}_{v}^{?} \overline{b}_{0}\left(\operatorname{mon}\left(\ell_{0} \blacktriangleleft \tau_{0} \blacktriangleleft \ell_{1}\right) v_{0}\right)\right)
                            where \tau_1 = snd(\tau_0) and b_0 = (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)
1312
                                                                                                                                           ► TagErr •
                      binop\{\mathcal{U}\} v_0 v_1
1313
                            if v_2 = rem\text{-}trace(v_0) and v_3 = rem\text{-}trace(v_1) and \delta(binop, v_2, v_3) is undefined
1314

ightharpoonup_A \delta(binop, v_2, v_3)
1315
                      binop\{U\} v_0 v_1
1316
                            if v_2 = rem\text{-}trace(v_0) and v_3 = rem\text{-}trace(v_1) and \delta(binop, v_2, v_3) is defined
1317
                     app{\mathcal{U}} v_0 v_1
                                                                                                                                           ► TagErr •
1318
                            if v_0 \notin (\operatorname{trace}_{v}^{?} \overline{b}(\lambda x. e)) \cup (\operatorname{trace}_{v}^{?} \overline{b}(\operatorname{mon}(\ell \triangleleft (\tau \Rightarrow \tau) \triangleleft \ell) v))
1319
1320
                      \operatorname{app}\{\mathcal{U}\}\left(\operatorname{trace}_{v}^{?} \overline{b}_{0}\left(\lambda x_{0}, e_{0}\right)\right) v_{0}
                                                                                                                                          \blacktriangleright_{\Lambda} trace \bar{b}_0 (e_0[x_0 \leftarrow v_1])
1321
                            where v_1 = add-trace (rev(\overline{b_0}), v_0)
1322
                     \mathsf{app}\{\mathcal{U}\}\left(\mathsf{trace}_{\mathsf{v}}^{?}\bar{b}_{0}\left(\mathsf{mon}\left(\ell_{0}\blacktriangleleft\tau_{0}\blacktriangleleft\ell_{1}\right)\upsilon_{0}\right)\right)\upsilon_{1}\ \blacktriangleright_{\mathsf{A}}\ \mathsf{trace}\,\bar{b}_{0}\left(\mathsf{stat}\;b_{0}\left(\mathsf{app}\{\tau_{2}\}\,\upsilon_{0}\left(\mathsf{dyn}\;b_{1}\;\upsilon_{2}\right)\right)\right)
1323
                            where \tau_2 = cod(\tau_0) and b_0 = (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) and b_1 = (\ell_1 \blacktriangleleft dom(\tau_0) \blacktriangleleft \ell_0)
1324
1325
                            and v_2 = add-trace(rev(\overline{b_0}), v_1)
1326
                      stat (\ell_0 \triangleleft \tau_0 \triangleleft \ell_1) v_0

ightharpoonup_{A} \mod (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_0
1327
                            if tag-match (\lfloor \tau_0 \rfloor, v_0) and v_0 \in (\lambda(x : \tau). e) \cup \langle v, v \rangle
1328
                                                                                                                                          \blacktriangleright_{\Delta} trace (b_0b_1\overline{b}_0)v_0
                     stat b_0 (mon b_1 (trace, \overline{b_0} v_0))
1329
1330
                            if b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) and tag-match(\lfloor \tau_0 \rfloor, v_0) and v_0 \in (\lambda x. e) \cup (\langle v, v \rangle) \cup (\text{mon } b \ (\lambda (x : \tau). e)) \cup (\text{mon } b \ \langle v, v \rangle)
1331
                      stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) i_0
                                                                                                                                           \triangleright_{\mathsf{A}} i_0
1332
                            if tag\text{-}match(\lfloor \tau_0 \rfloor i_0) and b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)
1333
                     stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_0
                                                                                                                                           ► TagErr ∘
1334
1335
                            if \neg tag\text{-}match(|\tau_0|v_0,)
1336
                     trace \bar{b}_0 v_0
1337
                            where v_1 = add-trace (\overline{b}_0, v_0)
1338
1339
                   4.2 Amnesic Ownership Lifting
1340
1341
                    Amnesic Ownership Language extends Ownership Evaluation Language
1342
                     v = \dots \mid \operatorname{trace}_{v} \overline{b} v \mid \operatorname{mon} (\ell \blacktriangleleft \tau \Rightarrow \tau \blacktriangleleft \ell) v \mid \operatorname{mon} (\ell \blacktriangleleft \tau \times \tau \blacktriangleleft \ell) v
1343
1344
                     e = \dots \mid \operatorname{trace} \overline{b} e
1345
                      E = \dots \mid \operatorname{trace} \overline{b} E
1346
                     L; \ell \Vdash_A e extends L; \ell \Vdash e enforces sound and complete blame
1347
1348
                       \frac{L_0; \ell_1 \ \mathbb{F}_{\mathsf{A}} \ v_0}{L_0; \ell_0 \ \mathbb{F}_{\mathsf{A}} \ \mathsf{mon} \ (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ (v_0)^{\ell_1}} \qquad \frac{\overline{b}_0 \simeq (\ell_n \cdots \ell_0) \qquad L_0; \ell_n \ \mathbb{F}_{\mathsf{A}} \ e_0}{L_0; \ell_0 \ \mathbb{F}_{\mathsf{A}} \ \mathsf{trace} \ \overline{b}_0 \ (e_0))^{(\ell_n \cdots \ell_0)}} \qquad \frac{\overline{b}_0 \simeq (\ell_n \cdots \ell_0) \qquad L_0; \ell_n \ \mathbb{F}_{\mathsf{A}} \ e_0}{L_0; \ell_0 \ \mathbb{F}_{\mathsf{A}} \ \mathsf{trace}_{\mathsf{V}} \ \overline{b}_0 \ (e_0))^{(\ell_n \cdots \ell_0)}} \qquad \frac{\overline{b}_0 \simeq (\ell_n \cdots \ell_0) \qquad L_0; \ell_n \ \mathbb{F}_{\mathsf{A}} \ e_0}{L_0; \ell_0 \ \mathbb{F}_{\mathsf{A}} \ \mathsf{trace}_{\mathsf{V}} \ \overline{b}_0 \ (e_0))^{(\ell_n \cdots \ell_0)}}
1349
1350
1351
```

```
\longrightarrow_{\overline{A}}^* reflexive-transitive closure of \longrightarrow_{\overline{A}}
1353
1354
                   e \longrightarrow_{\overline{\mathbf{N}}} e reflexive-transitive closure of \triangleright_{\overline{\mathbf{N}}} \cup \blacktriangleright_{\overline{\mathbf{N}}}
1355
1356
1357
                   (e)^{\ell} \rhd_{\mathsf{A}} (e)^{\ell}
1358
                     (unop\{\tau_0\} v_0)^{\ell_0}
                                                                                                                                     \triangleright_{\Delta} (\mathsf{TagErr} \circ)^{\ell_0}
1359
1360
                           if v_0 \notin (\text{mon}(\ell \blacktriangleleft (\tau \times \tau) \blacktriangleleft \ell) v) and \delta(unop, v_0) is undefined
1361
                     (unop\{\tau_0\}\ v_0)^{\ell_0}
                                                                                                                                     \triangleright_{\mathsf{A}} (\delta(\mathit{unop}, v_0))^{\ell_0}
1362
                           if \delta(unop, v_0) is defined
1363
                     (fst\{\tau_0\} ((mon (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) (v_0)^{\ell_2}))^{\ell_3^*})^{\ell_4}
1364
                                                                                                                                    \triangleright_{\mathsf{A}} ((\mathsf{dyn} \ b_0 \ (\mathsf{fst} \{\mathcal{U}\} \ v_0)^{\ell_2}))^{\ell_3^* \ell_4}
1365
                            where b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)
1366
                    (\operatorname{snd}\{\tau_0\} ((\operatorname{mon} (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) (v_0)^{\ell_2}))^{\ell_3^*})^{\ell_4})

ho_{\mathsf{A}} \ (\!(\mathsf{dyn}\, b_0 \, (\mathsf{snd}\{\mathcal{U}\}\, v_0)^{\ell_2})\!)^{\ell_3^*\ell_4}
1367
1368
                           where b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)
1369
                                                                                                                                     \triangleright_{\!_{\mathbf{A}}} (\mathsf{TagErr} \circ)^{\ell_0}
                     (binop\{\tau_0\} v_0 v_1)^{\ell_0}
1370
                           if \delta(binop, v_0, v_1) is undefined
1371
1372
                     (\mathit{binop}\{\tau_0\}\,\upsilon_0\,\upsilon_1)^{\ell_0}
                                                                                                                                     \triangleright_{\Delta} (\delta(binop, v_0, v_1))^{\ell_0}
1373
                           if \delta(binop, v_0, v_1) is defined
1374
                           \vdash_{\mathsf{A}} (\mathsf{TagErr} \circ)^{\ell_0} 
\text{if } v_0 \notin ((\lambda(x : \tau). e))^{\ell^*} \cup ((\mathsf{mon} (\ell \blacktriangleleft (\tau \Rightarrow \tau) \blacktriangleleft \ell) v))^{\ell^*}
                     (app\{\tau_0\} v_0 v_1)^{\ell_0}
1375
1376
                     1377
1378
1379
                           where b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) and b_1 = (\ell_1 \blacktriangleleft dom(\tau_1) \blacktriangleleft \ell_0)
1380
1381
                                                                                                                                    \triangleright_{\mathsf{A}} \left( \mathsf{mon} \left( \ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1 \right) \left( \left( v_0 \right) \right)^{\ell_2^*} \right)^{\ell_3}
                     (\text{dyn} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) ((v_0))^{\ell_2^*})^{\ell_3}
1382
                           if tag\text{-}match(\lfloor \tau_0 \rfloor, v_0) and rem\text{-}trace(v_0) \in ((\lambda x. e))^{\ell^*} \cup ((\langle v, v \rangle))^{\ell^*} \cup ((mon \ b \ v))^{\ell^*}
1383
                    (\mathsf{dyn}\,(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\,((\mathsf{trace}_{\mathsf{V}}^? \overline{b_0}\,((i_0))^{\ell_2^*})^{\ell_3^*})^{\ell_3^*})^{\ell_4}
1384
                                                                                                                                    \triangleright_{\mathsf{A}} (i_0)^{\ell_4}
1385
                           if tag-match(|\tau_0|, i_0)
1386
                                                                                                                                    \triangleright_{\mathsf{A}} (\mathsf{BndryErr}((\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \overline{b}_0, ((v_0))^{\ell_2^*}))^{\ell_3}
                     (\text{dyn} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) ((v_0))^{\ell_2^*})^{\ell_3}
1387
1388
                           if \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0) and \overline{b}_0 = get\text{-}trace(\upsilon_0)
1389
1390
```

```
(e)^{\ell} \blacktriangleright_{\mathsf{A}} (e)^{\ell}
1405
1406

ightharpoonup_{A} (\mathsf{TagErr} ullet)^{\ell_0}
                                  (unop\{\mathcal{U}\}\,v_0)^{\ell_0}
1407
1408
                                           if v_1 = rem\text{-}trace(v_0) and v_1 \notin mon(\ell \blacktriangleleft (\tau \times \tau) \blacktriangleleft \ell) v and \delta(unop, v_1) is undefined
1409
                                 (unop\{\mathcal{U}\}\,v_0)^{\ell_0}
                                                                                                                                                                                                                                                                          \blacktriangleright_{\Lambda} (add-trace(get-trace(v_0), \delta(unop, v_1)))\ell_0
1410
                                           if v_1 = rem\text{-}trace(v_0) and \delta(unop, v_1) is defined
1411
                                (\mathsf{fst}\{\mathcal{U}\}\,(\!(\mathsf{trace}_{\mathsf{v}}^?\,\overline{b}_0\,(\!(\mathsf{mon}\,(\ell_0\!\blacktriangleleft\!\tau_0\!\blacktriangleleft\!\ell_1)\,(v_1)^{\ell_2}\!)\!)^{\ell_3^*})\!)^{\ell_3^*}\ell_4^{\ell_4}\ell_5
                                                                                                                                                                                                                                                                         \blacktriangleright_{\mathsf{A}} \ (\mathsf{trace} \, \overline{b}_0 \, (\!(\mathsf{stat} \, b_1 \, (\mathsf{fst}\{\tau_1\} \, v_1)^{\ell_2})\!)^{\ell_3^*})^{\ell_3^* \, \ell_4^* \ell_5}
1412
1413
                                            where \tau_1 = fst(\tau_0) and b_1 = (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)
1414
                                (\operatorname{snd}\{\mathcal{U}\}\,(\!(\operatorname{trace}_{\mathbf{v}}^?\,\overline{b}_0\,(\!(\operatorname{mon}\,(\ell_0\blacktriangleleft\tau_0\blacktriangleleft\ell_1)\,(\upsilon_1)^{\ell_2}\!)\!)^{\ell_3^*})\!)^{\ell_3^*}\ell_4^{\ell_4}\ell_5^{1}
                                                                                                                                                                                                                                                                         \blacktriangleright_{\mathsf{A}} (\mathsf{trace}\,\overline{b}_0\,(\!(\mathsf{stat}\,b_1\,(\mathsf{snd}\{\tau_1\}\,v_1)^{\ell_2})\!)^{\ell_3^*})^{\ell_3^*\ell_5^*}
1416
                                           where \tau_1 = snd(\tau_0) and b_1 = (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)
1417
                                                                                                                                                                                                                                                                         ►<sub>\Delta</sub> (TagErr •)\ell_0
                                  (binop\{\mathcal{U}\} v_0 v_1)^{\ell_0}
1418
                                           if v_2 = rem\text{-}trace(v_0) and v_3 = rem\text{-}trace(v_1) and \delta(binop, v_2, v_3) is undefined
1419
1420
                                                                                                                                                                                                                                                                         \blacktriangleright_{\mathsf{A}} (\delta(\mathit{binop}, v_2, v_3))^{\ell_0}
                                 (binop\{\mathcal{U}\} v_0 v_1)^{\ell_0}
1421
                                           if v_2 = rem\text{-}trace(v_0) and v_3 = rem\text{-}trace(v_1) and \delta(binop, v_2, v_3) is defined
1422
                                (\mathsf{app}\{\mathcal{U}\} ((\mathsf{trace}_{\mathsf{v}}^? \bar{b_0} ((v_0))^{\ell_0^*}))^{\ell_1^*} v_1)^{\ell_2}
1423
                                                                                                                                                                                                                                                                         \blacktriangleright_{\Lambda} (\mathsf{TagErr} \bullet)^{\ell_0}
1424
                                           if v_0 \notin (\lambda x. e) \cup (\text{mon } (\ell \blacktriangleleft (\tau \Rightarrow \tau)^{\ell} \blacktriangleleft \ell) v)
1425
                                \{\mathsf{app}\{\mathcal{U}\}\ (\!(\mathsf{trace}_{\mathsf{v}}^? ar{b_0}\ (\!(\lambda x_0.\,e_0)\!)^{\ell_0^*}\!)\!)^{\ell_1^*} v_1)^{\ell_2}
                                                                                                                                                                                                                                                                        \blacktriangleright_{A} (\text{trace } \overline{b}_0 ((e_0[x_0 \leftarrow v_2]))^{\ell_0^*})^{\ell_1^* \ell_2}
1426
                                           where v_2 = add\text{-}trace(rev(\overline{b}_0), ((v_1))^{\ell_2 rev(\ell_1^*)rev(\ell_0^*)})
1427
                                (\mathsf{app}\{\mathcal{U}\}\,(\!(\mathsf{trace}_{\mathsf{v}}^?\,\overline{b_0}\,(\!(\mathsf{mon}\,(\ell_0\,\blacktriangleleft\,\tau_0\,\blacktriangleleft\,\ell_1)\,(v_0)^{\ell_2})\!)^{\ell_3^*}\!)^{\ell_4^*}\,\ell_2^*\\ \bullet_{\mathsf{A}} \quad (\!(\mathsf{trace}\,\overline{b_0}\,(\!(\mathsf{stat}\,b_1\,(\mathsf{app}\{\tau_3\}\,v_0\,(\mathsf{dyn}\,b_2\,v_2))^{\ell_2})\!)^{\ell_3^*}\!)^{\ell_4^*}\ell_2^*\\ \bullet_{\mathsf{A}} \quad (\!(\mathsf{trace}\,\overline{b_0}\,(\!(\mathsf{stat}\,b_1\,(\mathsf{app}\{\tau_3\}\,v_0\,(\mathsf{dyn}\,b_2\,v_2))^{\ell_2})\!)^{\ell_3^*}\!)^{\ell_4^*}\ell_2^*\\ \bullet_{\mathsf{A}} \quad (\!(\mathsf{trace}\,\overline{b_0}\,(\!(\mathsf{stat}\,b_1\,(\mathsf{app}\{\tau_3\}\,v_0\,(\mathsf{dyn}\,b_2\,v_2))^{\ell_2})\!)^{\ell_3^*})^{\ell_4^*}\ell_2^*\\ \bullet_{\mathsf{A}} \quad (\!(\mathsf{trace}\,\overline{b_0}\,(\!(\mathsf{stat}\,b_1\,(\mathsf{app}\{\tau_3\}\,v_0\,(\mathsf{dyn}\,b_2\,v_2))^{\ell_2})\!)^{\ell_3^*}\ell_2^*\\ \bullet_{\mathsf{A}} \quad (\!(\mathsf{trace}\,\overline{b_0}\,(\!(\mathsf{stat}\,b_1\,(\mathsf{app}\{\tau_3\}\,v_0\,(\mathsf{dyn}\,b_2\,v_2))^{\ell_2})\!)^{\ell_3^*}\ell_2^*\\ \bullet_{\mathsf{A}} \quad (\!(\mathsf{trace}\,\overline{b_0}\,(\!(\mathsf{stat}\,b_1\,(\mathsf{app}\{\tau_3\}\,v_0\,(\mathsf{dyn}\,b_2\,v_2))^{\ell_2})\!)^{\ell_3^*}\ell_2^*\\ \bullet_{\mathsf{A}} \quad (\!(\mathsf{trace}\,b_0\,(\!(\mathsf{stat}\,b_1\,(\mathsf{app}\{\tau_3\}\,v_0\,(\mathsf{dyn}\,b_2\,v_2))^{\ell_2})\!)^{\ell_3^*}\ell_2^*\\ \bullet_{\mathsf{A}} \quad (\!(\mathsf{trace}\,b_0\,(\!(\mathsf{stat}\,b_1\,(\mathsf{app}\{\tau_3\}\,v_0\,(\mathsf{dyn}\,b_2\,v_2))^{\ell_2})\!)^{\ell_3^*}\ell_2^*\\ \bullet_{\mathsf{A}} \quad (\!(\mathsf{trace}\,b_0\,(\!(\mathsf{stat}\,b_1\,(\mathsf{app}\{\tau_3\}\,v_0\,(\mathsf{dyn}\,b_2\,v_2))^{\ell_2})\!)^{\ell_3^*}\ell_2^*\\ \bullet_{\mathsf{A}} \quad (\!(\mathsf{trace}\,b_0\,(\!(\mathsf{stat}\,b_1\,(\mathsf{app}\{\tau_3\}\,v_0\,(\mathsf{dyn}\,b_2\,v_2))^{\ell_2})\!)^{\ell_3^*}\ell_2^*\\ \bullet_{\mathsf{A}} \quad (\!(\mathsf{trace}\,b_0\,(\!(\mathsf{stat}\,b_1\,(\mathsf{app}\{\tau_3\}\,v_0\,(\mathsf{dyn}\,b_2\,v_2))^{\ell_3^*})\!)^{\ell_3^*}\ell_2^*\\ \bullet_{\mathsf{A}} \quad (\!(\mathsf{trace}\,b_0\,(\!(\mathsf{stat}\,b_1\,(\mathsf{app}\{\tau_3\}\,v_0\,(\mathsf{dyn}\,b_2\,v_2))^{\ell_3^*}))^{\ell_3^*}\ell_2^*\\ \bullet_{\mathsf{A}} \quad (\!(\mathsf{trace}\,b_0\,(\!(\mathsf{app}\,b_1\,(\mathsf{app}\{\tau_3\}\,v_0\,(\mathsf{dyn}\,b_2\,v_2))^{\ell_3^*}))^{\ell_3^*}\ell_2^*\\ \bullet_{\mathsf{A}} \quad (\!(\mathsf{trace}\,b_0\,(\!(\mathsf{app}\,b_1\,(\mathsf{app}\{\tau_3\}\,v_0\,(\mathsf{dyn}\,b_2\,v_2))^{\ell_3^*}))^{\ell_3^*}\ell_2^*\\ \bullet_{\mathsf{A}} \quad (\!(\mathsf{app}\,b_1\,(\mathsf{app}\,b_1\,(\mathsf{app}\,b_2\,v_2))^{\ell_3^*}\ell_2^*))^{\ell_3^*}\ell_2^*
1429
1430
                                            where \tau_2 = cod(\tau_0) and b_1 = (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) and b_2 = (\ell_1 \blacktriangleleft dom(\tau_0) \blacktriangleleft \ell_0) and \tau_3 = forget(\tau_2)
1431
                                            and v_2 = (add\text{-}trace(rev(\overline{b}_0), ((v_1))^{\ell_5}rev(\ell_3^*\ell_4^*)))^{\ell_2}
1432
                                           \blacktriangleright_{\mathsf{A}} (\mathsf{mon} \, (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \, v_0)^{\ell_2}  if tag\text{-}match(\lfloor \tau_0 \rfloor, v_0) and v_0 \in ((\lambda(x : \tau). \, e))^{\ell^*} \cup ((\langle v, v \rangle))^{\ell^*} 
                                 (\operatorname{stat}(\ell_0 \triangleleft \tau_0 \triangleleft \ell_1) v_0)^{\ell_2}
1433
1434
1435
                                                                                                                                                                                                                                                                         \blacktriangleright_{A} (\operatorname{trace}(b_0 b_1 \overline{b}_2) ((v_0))^{\ell_0^* \ell_1^* \ell_2})^{\ell_2}
                                 (\text{stat } b_0 \text{ ((mon } b_1 \text{ ((trace}_v^? \bar{b}_2 v_0))^{\ell_0^*})^{\ell_1^*})^{\ell_2^*})
1436
1437
                                           if b_0 = (\ell_3 \blacktriangleleft \tau_0 \blacktriangleleft \ell_4) and tag\text{-}match(|\tau_0|, v_0)
1438
                                           and v_0 \in ((\lambda x. e))^{\ell^*} \cup ((\langle v, v \rangle))^{\ell^*} \cup ((\text{mon } b \ (\lambda(x:\tau). e)))^{\ell^*} \cup ((\text{mon } b \ \langle v, v \rangle))^{\ell^*}
1439
                                  (\operatorname{stat}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) ((i_0))^{\ell_2^*})^{\ell_3}
                                                                                                                                                                                                                                                                         \blacktriangleright_{\Lambda} (i_0)^{\ell_3}
                                           if tag-match(|\tau_0|, v_0)
1442

ightharpoonup_{A} (TagErr \circ)^{\ell_3}
                                 \left(\operatorname{stat}\left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) \left(\left(\upsilon_0\right)\right)^{\ell_2^*}\right)^{\ell_3}
                                           if \neg tag\text{-}match(|\tau_0|, v_0)
1444

ightharpoonup_{\mathsf{A}} (v_1)^{\ell_0}
                                  (\operatorname{trace} \overline{b_0} v_0)^{\ell_0}
1445
                                           where v_1 = add\text{-}trace(\overline{b}_0, v_0)
1446
1447
```

5 Natural THEOREMS, LEMMAS, AND PROOFS

Natural Theorems

 Theorem 5.1 (type soundness). If $e_0:\tau_0$ wf then one of the following holds:

- $e_0 \rightarrow_{\mathsf{N}}^* v_0 \ and \cdot \vdash_{\mathsf{N}} v_0 : \tau_0$
- \bullet e_0 diverges
- $e_0 \rightarrow_N^* E_0[\mathsf{dyn}\ b_1\ E[e_1]]\ and\ e_1 \blacktriangleright_N \mathsf{TagErr}$ •
- $e_0 \xrightarrow[N]{}^* \text{DivErr}$ $e_0 \xrightarrow[N]{}^* \text{BndryErr}(\overline{b}_1, v_1)$

PROOF. By progress and preservation lemmas (lemma 5.6 & lemma 5.7).

Theorem 5.2 (Dynamic soundness). If $e_0: \mathcal{U}$ wf then one of the following holds:

- $e_0 \rightarrow_{\mathsf{N}}^* v_0 \ and \cdot \vdash_{\mathsf{N}} v_0 : \mathcal{U}$
- e₀ diverges
 - $e_0 \rightarrow_N^* E_0[e_1]$ and $e_1 \blacktriangleright_N TagErr$ $e_0 \rightarrow_N^* DivErr$ $e_0 \rightarrow_N^* BndryErr(\overline{b}_1, v_1)$

PROOF. By progress and preservation lemmas (lemma 5.6 & lemma 5.7).

Theorem 5.3. If $e_0:\tau$? $\overline{\mathbf{wf}}$ then $forget(e_0):\tau$? \mathbf{wf} and $e_0\longrightarrow_{\overline{N}} e_1$ iff $forget(e_0)\to_{\overline{N}} forget(e_1)$

Proof. By the definition of $\longrightarrow_{\overline{N}}$.

Theorem 5.4 (complete monitoring). If $e_0:\tau$? $\overline{\mathbf{wf}}$ and $e_0 \longrightarrow_{\overline{N}}^* e_1$ then \cdot ; $\ell \Vdash e_1$.

PROOF. By lemma 5.20 and lemma 5.21.

Theorem 5.5 (correct blame). If $e_0:\tau$? $\overline{\mathbf{wf}}$ and $e_0 \longrightarrow_{\overline{\mathbf{N}}}^* \mathsf{BndryErr}(\overline{b_0},v_0)$ then:

- $senders(\overline{b}_0) = owners(v_0)$
- $\overline{b}_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)$
- either has-boundary $((\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1), e_0)$ or has-boundary $((\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_0), e_0)$

- 1. Either $e_0 \longrightarrow_{\overline{N}}^* v_0$ where $v_0 : \tau$? $\overline{\mathbf{wf}}$ or e_0 diverges, or $e_0 \longrightarrow_{\overline{N}}^* \mathsf{Err}$ by lemma 5.20 and lemma 5.21
- 2. Assume $e_0 \longrightarrow_{\overline{N}}^* \operatorname{BndryErr}(\overline{b}_0, v_0)$ 2.1. $\exists \ell_0, \tau_0, \ell_1 .\overline{b}_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)$

2.1.
$$\exists \ell_0, \tau_0, \ell_1 . \overline{b}_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)$$

2.1.1. QED

2019-10-03 17:26. Page 29 of 1-148.

```
by definition of \longrightarrow_{\overline{N}}^*
1509
1510
                  2.2. owners(v_0) = \ell_1
1511
                      2.2.1. QED
1512
                           by lemma 5.21
1513
                 2.3. \exists v_1, E_0 \text{ such that } e_0 \longrightarrow_{\overline{N}}^* E_0[\mathsf{dyn} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_1]
1514
1515
                      by lemma 5.24
1516
                  2.4. (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \in e_0 or (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_0) \in e_0
1517
                      by lemma 5.35
1518
1519
             3. QED
1520
                                                                                                                                                                                                                                        1521
1522
             5.2 Natural Lemmas
1523
1524
                  Lemma 5.6 (\vdash_N progress). If \cdot \vdash_N e_0 : \tau? then one of the following holds:
1525
                      • e_0 \in v
1526
1527
                     • e_0 \in Err
1528
                     • \exists e_1 \text{ such that } e_0 \rightarrow_{\mathsf{N}} e_1
1529
1530
                  PROOF. By case analysis of e_0.
1531
             By lemma 5.10 it suffices to consider the following cases.
1532
             1. Case e_0 \in v
1533
                  1.1. QED
1534
1535
             2. CASE e_0 = E_0[Err]
1536
                  2.1. QED
1537
             3. CASE e_0 = E_0[app\{\tau_1\} v_0 v_1]
1538
                  3.1. v_0 \in (\lambda(x : \tau). e) \cup (\text{mon } b \ v)
1539
1540
                      by inversion \vdash_N
1541
                 3.2. Scase v_0 = \lambda(x_2 : \tau_2). e_2
1542
                      3.2.1. QED
1543
                           e_0 \triangleright_{\mathsf{N}} E_0[e_2[x_2 \leftarrow v_1]]
                 3.3. SCASE v_0 = \text{mon} (\ell_0 \blacktriangleleft (\tau_1 \Rightarrow \tau_2) \blacktriangleleft \ell_1) v_2
1546
                      3.3.1. QED
                           e_0 \rhd_{\mathsf{N}} E_0[\mathsf{dyn}\,(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1)\,(\mathsf{app}\{\mathcal{U}\}\,v_2\,(\mathsf{stat}\,(\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0)\,v_1))]
1548
             4. Case e_0 = E_0[\mathsf{app}\{\mathcal{U}\} \ v_0 \ v_1]
1549
1550
                  4.1. SCASE v_0 = \lambda x_2 . e_2
1551
                      4.1.1. QED
1552
                           e_0 \triangleright_{\mathsf{N}} E_0[e_2[x_2 \leftarrow v_1]]
1553
                  4.2. SCASE v_0 = \text{mon} (\ell_0 \blacktriangleleft (\tau_1 \Rightarrow \tau_2) \blacktriangleleft \ell_1) v_2
1554
1555
1556
                           e_0 \blacktriangleright_{\mathsf{N}} E_0[\mathsf{stat}\ (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1)\ (\mathsf{app}\{\tau_2\}\ v_2\ (\mathsf{dyn}\ (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0)\ v_1))]
1557
                  4.3. SCASE v_0 \notin (\lambda(x:\tau).e) \cup (\text{mon } b \ v)
1558
                      4.3.1. QED
```

```
e_0 \triangleright_{\mathsf{N}} E_0[\mathsf{TagErr} \bullet]
1561
1562
              5. CASE e_0 = E_0[unop\{\tau?\} v_0]
1563
1564
                       by lemma 5.11 and lemma 5.13
1565
1566
             6. CASE e_0 = E_0[binop\{\tau?\} v_0 v_1]
1567
                   6.1. QED
1568
                       by lemma 5.11 and lemma 5.13
1569
             7. CASE e_0 = E_0[\text{dyn}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_0]
1570
                   7.1. QED
1572
                       by lemma 5.11 and lemma 5.15
1573
             8. CASE e_0 = E_0[\text{stat}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \upsilon_0]
1574
                   8.1. QED
1575
                       by lemma 5.11 and lemma 5.16
1576
1577
1578
1579
                   Lemma 5.7 (\vdash_N static preservation). If \cdot \vdash_N e_0 : \tau? and e_0 \rightarrow_N e_1 then \cdot \vdash_N e_1 : \tau?.
1580
1581
                   PROOF. By lemma 5.8 and lemma 5.9.
1582
1583
1584
1585
                   Lemma 5.8 (\triangleright_{N} preservation). If \cdot \vdash_{N} e_0 : \tau_0 and e_0 \triangleright_{N} e_1 then \cdot \vdash_{N} e_1 : \tau_0.
1586
                   PROOF. By case analysis of \triangleright_{N}.
1587
1588
              1. Case unop\{\tau_0\}\ v_0 \rhd_{\mathsf{N}} \delta_N(unop, v_0)
1589
                   1.1. QED
1590
                       by lemma 5.14
1591
1592
              2. Case binop\{\tau_0\} v_0 v_1 \rhd_N \delta_N(binop, v_0, v_1)
1593
1594
                       by lemma 5.14
1595
             3. Case app\{\tau_0\} (\lambda(x_1:\tau_1).e_1) v_2 \triangleright_{N} e_1[x_1 \leftarrow v_2]
1596
1597
                   3.1. QED
1598
                       by lemma 5.19
1599
              4. CASE app\{\tau_0\} (mon (\ell_0 \blacktriangleleft (\tau_1 \Rightarrow \tau_0) \blacktriangleleft \ell_1) v_0) v_1
1600
                               \rhd_{\mathsf{N}} \, \mathsf{dyn} \, (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \, (\mathsf{app} \{\mathcal{U}\} \, v_0 \, (\mathsf{stat} \, (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \, v_1))
1601
1602
                   4.1. QED
1603
1604
                                                                                                                                     by inversion \vdash_N
1605
                                                                              by inversion \vdash_N
                                                                                                                                          \cdot \vdash_{\mathsf{N}} v_1 : \tau_1
1606
1607
                                                                                  \cdot \vdash_{\mathsf{N}} v_0 : \mathcal{U}
                                                                                                                        \cdot \vdash_{\mathsf{N}} \mathsf{stat} \left(\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0\right) v_1 : \mathcal{U}
1608
                                                                                       \cdot \vdash_{\mathsf{N}} \mathsf{app}\{\mathcal{U}\} v_0 \; (\mathsf{stat} \; (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \; v_1) : \mathcal{U}
1609
1610
                                                                      \cdot \vdash_{\mathsf{N}} \mathsf{dyn} \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) \left(\mathsf{app}\{\mathcal{U}\} \ v_0 \left(\mathsf{stat} \left(\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0\right) \ v_1\right)\right) : \tau_0
1611
```

```
1613
               5. case dyn b_0 v_0 \triangleright_{\mathbb{N}} v_1
1614
                    5.1. QED
1615
                         by lemma 5.17
1616
1617
                                                                                                                                                                                                                                                                         1618
                    Lemma 5.9 (\blacktriangleright_N preservation). If \cdot \vdash_N e_0 : \mathcal{U} and e_0 \blacktriangleright_N e_1 then \cdot \vdash_N e_1 : \mathcal{U}.
1619
1620
                    PROOF. By case analysis of \triangleright_{N}.
1621
               1. CASE unop\{\mathcal{U}\} v_0 \blacktriangleright_{\mathsf{N}} \mathsf{TagErr} \bullet
                    1.1. QED
1624
                         \cdot \vdash_{\mathsf{N}} \mathsf{TagErr} \bullet : \mathcal{U}
1625
               2. Case \delta_N(\textit{unop}, v_0) is defined and \textit{unop}\{\mathcal{U}\}\ v_0 \blacktriangleright_N \delta_N(\textit{unop}, v_0)
1626
1627
                    2.1. QED
1628
                         by lemma 5.14
1629
               3. Case binop\{\mathcal{U}\}\ v_0\ v_1 \blacktriangleright_{\mathsf{N}} \mathsf{TagErr} \bullet
1630
                    3.1. QED
1631
1632
                          \cdot \vdash_{\mathsf{N}} \mathsf{TagErr} \bullet : \mathcal{U}
1633
               4. Case \delta_N(\mathit{binop}, v_0, v_1) is defined and \mathit{binop}\{\mathcal{U}\}\ v_0\ v_1 \blacktriangleright_N \delta_N(\mathit{binop}, v_0, v_1)
1634
                    4.1. QED
1635
                         by lemma 5.14
1637
               5. Case app\{\mathcal{U}\} (\lambda x_1. e_1) v_2 \blacktriangleright_{\mathsf{N}} e_1[x_1 \leftarrow v_2]
1638
                    5.1. QED
1639
                         by lemma 5.19
1640
               6. Case app\{\mathcal{U}\} (mon (\ell_0 \blacktriangleleft (\tau_1 \Rightarrow \tau_0) \blacktriangleleft \ell_1) v_0) v_1
1641
1642
                                  \blacktriangleright_{\mathsf{N}} \mathsf{stat} \left( \ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1 \right) \left( \mathsf{app} \{ \tau_0 \} \, v_0 \, \left( \mathsf{dyn} \left( \ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0 \right) \, v_1 \right) \right)
1643
                    6.1. QED
1644
1645
                                                                                                                                                  by inversion \vdash_N
1646
1647
                                                                                      by inversion \vdash_N
                                                                                                                                                      \cdot \vdash_N v_1 : \mathcal{U}
                                                                                      \cdot \vdash_{\mathsf{N}} v_0 : \tau_1 \Rightarrow \tau_0
                                                                                                                                     \cdot \vdash_{\mathsf{N}} \mathsf{dyn} \left(\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0\right) v_1 : \tau_1
                                                                                                \cdot \vdash_{\mathsf{N}} \mathsf{app}\{\tau_0\} \, v_0 \; (\mathsf{dyn} \, (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \, v_1) : \tau_0
1651
                                                                             \cdot \vdash_{\mathsf{N}} \mathsf{stat} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (\mathsf{app} \{\tau_0\} v_0 (\mathsf{dyn} (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) v_1)) : \mathcal{U}
1652
1653
               7. CASE stat b_0 v_0 \triangleright_{\mathsf{N}} v_1
1654
                    7.1. QED
1655
                         by lemma 5.18
1656
1657
                                                                                                                                                                                                                                                                         1658
1659
                    Lemma 5.10 (unique decomposition). If \cdot \vdash_{\mathsf{N}} e_0 : \tau? then either:
1660
                         • e_0 \in v
1661
                        • e_0 = E_0[app\{\tau?\} v_0 v_1]
                        • e_0 = E_0[unop\{\tau?\} v_0]
                                                                                                                                                                                                                  2019-10-03 17:26. Page 32 of 1-148.
```

```
• e_0 = E_0[binop\{\tau?\} v_0 v_1]
1665
1666
              • e_0 = E_0[\mathsf{dyn}\ b_1\ v_1]
1667
              • e_0 = E_0[\text{stat } b_1 \ v_1]
1668
             • e_0 = E_0[Err]
1669
1670
1671
           PROOF. By induction on the structure of e_0.
1672
        1. CASE e_0 = x_0
1673
           1.1. Contradiction:
1674
              \cdot \vdash_{\mathsf{N}} e_0 : \tau?
1675
1676
        2. CASE e_0 = v_0
1677
           2.1. QED
1678
        3. CASE e_0 = \langle e_1, e_2 \rangle
1679
           3.1. Scase e_1 \notin v
1680
1681
              3.1.1. QED
1682
                 by the induction hypothesis
1683
           3.2. SCASE e_1 \in v and e_2 \notin v
1684
              3.2.1. QED
1685
                 by the induction hypothesis
1686
1687
           3.3. SCASE e_1 \in v and e_2 \in v
              3.3.1. QED
1689
                 e_0\in v
1690
1691
        4. CASE e_0 = app\{\tau?\} e_1 e_2
1692
           4.1. QED
1693
              by the induction hypothesis
1694
        5. CASE e_0 = unop\{\tau?\} e_1
1695
1696
           5.1. QED
1697
              by the induction hypothesis
1698
        6. CASE e_0 = binop\{\tau?\} e_1 e_2
1699
           6.1. QED
1700
              by the induction hypothesis
1702
        7. CASE e_0 = \text{dyn } b_1 e_1
1703
           7.1. QED
1704
              by the induction hypothesis
1705
        8. CASE e_0 = \text{stat } b_1 e_1
1706
1707
           8.1. QED
1708
              by the induction hypothesis
1709
        9. Case e_0 \in Err
1710
1711
           9.1. QED
1712
1713
1714
1715
```

Lemma 5.11. If $\cdot \vdash_N E_0[e_0] : \tau$? then one of the following holds: 2019-10-03 17:26. Page 33 of 1–148.

```
\bullet · \vdash_{\mathsf{N}} e_0 : \mathcal{U}
1717
1718
               • \exists \tau_0 ... \vdash_{\mathsf{N}} e_0 : \tau_0
1719
1720
            PROOF. By induction on the structure of E_0 and case analysis of \vdash_N.
1721
         1. Case E_0 = []
1722
            1.1. QED
1723
         2. Case E_0 = \langle E_1, e_2 \rangle
1724
1725
            2.1. \cdot \vdash_{\mathsf{N}} E_1[e_0] : \tau?
               by inversion \vdash_N
            2.2. QED
1728
               by the induction hypothesis
1729
1730
         3. Case E_0 = \langle v_1, E_2 \rangle
1731
            3.1. QED
1732
               by the induction hypothesis
1733
         4. CASE E_0 = app\{\tau?\} E_1 e_2
1734
1735
            4.1. QED
1736
               by the induction hypothesis
1737
         5. Case E_0 = app\{\tau?\} v_1 E_2
1738
            5.1. QED
1739
               by the induction hypothesis
1741
         6. CASE E_0 = unop\{\tau?\} E_1
1742
            6.1. QED
1743
               by the induction hypothesis
1744
1745
         7. Case E_0 = binop\{\tau?\} E_1 e_2
1746
            7.1. QED
1747
               by the induction hypothesis
1748
         8. CASE E_0 = binop\{\tau?\} v_1 E_2
1749
1750
            8.1. QED
1751
               by the induction hypothesis
1752
         9. CASE E_0 = \text{dyn } b_1 E_1
1753
            9.1. QED
1754
1755
               by the induction hypothesis
1756
         10. CASE E_0 = \text{stat } b_1 E_1
1757
            10.1. QED
1758
               by the induction hypothesis
1759
1760
                                                                                                                                                                    1761
1762
            Lemma 5.12 (\vdash_N replacement).
1763
               • If \cdot \vdash_N E_0[e_0] : \tau? and the derivation contains a proof of \cdot \vdash_N e_0 : \tau_0 and \cdot \vdash_N e_1 : \tau_0 then \cdot \vdash_N E_0[e_1] : \tau?.
1764
1765
               • If \cdot \vdash_N E_0[e_0] : \tau? and the derivation contains a proof of \cdot \vdash_N e_0 : \mathcal{U} and \cdot \vdash_N e_1 : \mathcal{U} then \cdot \vdash_N E_0[e_1] : \tau?.
            PROOF. By induction on E_0.
1767
```

```
1. CASE E_0 = []
1769
1770
              1.1. QED
1771
          2. Case E_0 = \langle E_1, e_2 \rangle
1772
             2.1. QED
1773
1774
                 by the induction hypothesis
1775
          3. Case E_0 = \langle v_1, E_2 \rangle
1776
              3.1. QED
1777
                 by the induction hypothesis
1778
          4. CASE E_0 = app\{\tau?\} E_1 e_2
1779
1780
              4.1. QED
1781
                 by the induction hypothesis
1782
          5. CASE E_0 = app\{\tau?\} v_1 E_2
1783
              5.1. QED
1784
1785
                 by the induction hypothesis
1786
          6. CASE E_0 = unop\{\tau?\} E_1
1787
             6.1. QED
1788
                 by the induction hypothesis
1789
1790
          7. CASE E_0 = binop\{\tau?\} E_1 e_2
1791
             7.1. QED
1792
                 by the induction hypothesis
1793
          8. Case E_0 = binop\{\tau?\} v_1 E_2
1794
1795
             8.1. QED
1796
                 by the induction hypothesis
1797
          9. CASE E_0 = \text{dyn } b_1 E_1
1798
1799
             9.1. OED
1800
                 by the induction hypothesis
1801
          10. CASE E_0 = \text{stat } b_1 E_1
1802
              10.1. QED
1803
1804
                 by the induction hypothesis
1806
1807
              Lemma 5.13 (\delta_N type progress).
1808
1809
                 • If \cdot \vdash_{\mathsf{N}} unop\{\tau_1\} v_0 : \tau_0 \text{ then } \delta_N(unop, v_0) \text{ is defined.}
1810
                • if \cdot \vdash_N binop\{\tau_1\} \ v_0 \ v_1 : \tau_0 \ then \ \delta_N(binop, v_0, v_1) is defined.
1811
                • If \cdot \vdash_{\mathsf{N}} unop\{\mathcal{U}\} v_0 : \mathcal{U} \text{ then } unop\{\mathcal{U}\} v_0 \blacktriangleright_{\mathsf{N}} e_1.
1812
                • if \cdot \vdash_{\mathsf{N}} binop\{\mathcal{U}\} \ v_0 \ v_1 : \mathcal{U} \ then \ binop\{\mathcal{U}\} \ v_0 \ v_1 \blacktriangleright_{\mathsf{N}} e_1.
1813
1814
1815
              PROOF. By case analysis of \delta_N, \vdash_N, and \blacktriangleright_N.
1816
          1. CASE \cdot \vdash_{\mathsf{N}} \mathsf{fst}\{\tau_1\} \, v_0 : \tau_0
1817
              1.1. v_0 = \langle v_1, v_2 \rangle
1818
                 by \vdash_N canonical forms
1819
1820
```

2019-10-03 17:26. Page 35 of 1-148.

```
1821
                 1.2. QED
1822
                      \delta_N(unop, v_0) = v_1
1823
             2. CASE \cdot \vdash_{\mathsf{N}} \mathsf{snd}\{\tau_1\} v_0 : \tau_0
1824
                 2.1. v_0 = \langle v_1, v_2 \rangle
1825
1826
                     by \vdash_N canonical forms
1827
                 2.2. QED
1828
                      \delta_N(unop, v_0) = v_2
1829
            3. CASE \cdot \vdash_{\mathsf{N}} \mathsf{sum}\{\tau_1\} v_0 v_1 : \tau_0
                 3.1. v_0 \in i and v_1 \in i
1832
                     by \vdash_N canonical forms
1833
                 3.2. QED
1834
                      \delta_N(unop, v_0, v_1) \in i
1835
1836
             4. CASE \cdot \vdash_{\mathsf{N}} \mathsf{quotient}\{\tau_1\} v_0 v_1 : \tau_0
1837
                 4.1. v_0 \in i and v_1 \in i
1838
                     by \vdash_N canonical forms
1839
                 4.2. QED
1840
                      \delta_N(unop, v_0, v_1) \in i \cup DivErr
1841
1842
             5. CASE \cdot \vdash_{\mathsf{N}} unop\{\mathcal{U}\} v_0 : \mathcal{U}
1843
                 5.1. SCASE \delta_N(unop, v_0) is defined
1844
                     5.1.1. QED
1845
1846
                          unop\{\mathcal{U}\}\ v_0 \blacktriangleright_{\mathsf{N}} \delta_N(unop, v_0)
1847
                 5.2. SCASE \delta_N(\textit{unop}, v_0) is not defined
1848
                     5.2.1. QED
1849
                          unop\{\mathcal{U}\} v_0 \blacktriangleright_{N} TagErr \bullet
1850
1851
             6. CASE \cdot \vdash_{\mathsf{N}} binop\{\mathcal{U}\} v_0 v_1 : \mathcal{U}
1852
                 6.1. SCASE \delta_N(binop, v_0, v_1) is defined
1853
                     6.1.1. QED
1854
                          \mathit{binop}\{\mathcal{U}\}\,v_0\,v_1\,\blacktriangleright_{\!\mathsf{N}}\,\delta_N(\mathit{binop},v_0,v_1)
1855
                 6.2. SCASE \delta_N(binop, v_0, v_1) is not defined
                     6.2.1. QED
                          binop\{\mathcal{U}\} v_0 v_1 \blacktriangleright_{\mathsf{N}} \mathsf{TagErr} \bullet
1860
                                                                                                                                                                                                                               1861
1862
                 Lemma 5.14 (\delta_N type preservation).
1863
                    • If \cdot \vdash_{\mathsf{N}} unop\{\tau_1\} v_0 : \tau_0 then \cdot \vdash_{\mathsf{N}} \delta_N(unop, v_0) : \tau_0.
1864
                     • If \cdot \vdash_{\mathsf{N}} binop\{\tau_1\} \upsilon_0 \upsilon_1 : \tau_0 then \cdot \vdash_{\mathsf{N}} \delta_N(binop, \upsilon_0, \upsilon_1) : \tau_0.
1865
1866
                     • If \cdot \vdash_{\mathsf{N}} \mathsf{unop}\{\mathcal{U}\}\ v_0 : \mathcal{U} \ and \ \delta_N(\mathsf{unop}, v_0) \ is \ defined \ then \cdot \vdash_{\mathsf{N}} \delta_N(\mathsf{unop}, v_0) : \mathcal{U}.
1867
                     • If \cdot \vdash_N binop\{\mathcal{U}\} \ v_0 \ v_1 : \mathcal{U} \ and \ \delta_N(binop, v_0, v_1) \ is \ defined \ then \cdot \vdash_N \delta_N(binop, v_0, v_1) : \mathcal{U}.
1868
1869
                  PROOF. By case analysis of \delta_N and \vdash_N.
1870
             1. CASE \cdot \vdash_{\mathsf{N}} \mathsf{fst}\{\tau_0\} \, \upsilon_0 : \tau_0
1871
```

```
1873
                1.1. v_0 = \langle v_1, v_2 \rangle and \cdot \vdash_{N} v_1 : \tau_0
1874
                    by inversion \vdash_N
1875
                1.2. QED
1876
            2. CASE \cdot \vdash_{\mathsf{N}} \mathsf{snd}\{\tau_0\} \, v_0 : \tau_0
1877
1878
                2.1. v_0 = \langle v_1, v_2 \rangle and \cdot \vdash_{\mathsf{N}} v_2 : \tau_0
1879
                    by \vdash_N canonical forms and \vdash_N inversion
1880
                2.2. QED
1881
            3. CASE \cdot \vdash_{\mathsf{N}} \mathsf{sum}\{\tau_1\} v_0 v_1 : \tau_0
1882
                3.1. \tau<sup>0</sup> ∈ Int ∪ Nat
1884
                    by inversion \vdash_N
1885
                3.2. scase \tau_0 = \text{Int}
1886
                    3.2.1. \cdot \vdash_{\mathsf{N}} v_0 : \mathsf{Int} \; \mathsf{and} \; \cdot \vdash_{\mathsf{N}} v_1 : \mathsf{Int}
1887
1888
                         by inversion \vdash_{N}
1889
                    3.2.2. v_0 \in i \text{ and } v_1 \in i
1890
                         by \vdash_N canonical forms
1891
                    3.2.3. QED
1892
1893
                         \delta_N(binop, v_0, v_1) \in i
1894
                3.3. scase \tau_0 = \text{Nat}
1895
                    3.3.1. \cdot \vdash_{\mathsf{N}} v_0 : \mathsf{Nat} \ \mathsf{and} \cdot \vdash_{\mathsf{N}} v_1 : \mathsf{Nat}
                         by inversion \vdash_N
1897
1898
                    3.3.2. v_0 \in n \text{ and } v_1 \in n
1899
                         by \vdash_N canonical forms
1900
                    3.3.3. QED
1901
                         \delta_N(\mathit{binop}, v_0, v_1) \in \mathit{n}
1902
1903
            4. CASE \cdot \vdash_{\mathsf{N}} \mathsf{quotient}\{\tau_1\} v_0 v_1 : \tau_0
1904
                4.1. \tau<sup>0</sup> ∈ Int ∪ Nat
1905
                    by inversion \vdash_N
1906
                4.2. SCASE \tau_0 = \text{Int}
1907
1908
                    4.2.1. \cdot \vdash_{\mathsf{N}} v_0 : \mathsf{Int} \; \mathsf{and} \; \cdot \vdash_{\mathsf{N}} v_1 : \mathsf{Int}
                         by inversion \vdash_N
1910
                    4.2.2. v_0 \in i \text{ and } v_1 \in i
1911
                         by \vdash_N canonical forms
1912
                    4.2.3. QED
1913
1914
                         \delta_N(\textit{binop}, v_0, v_1) \in i \cup \mathsf{DivErr}
1915
                4.3. scase \tau_0 = \text{Nat}
1916
                    4.3.1. \cdot ⊢<sub>N</sub> v_0 : Nat and \cdot ⊢<sub>N</sub> v_1 : Nat
1917
1918
                         by inversion \vdash_N
1919
                    4.3.2. v_0 \in n and v_1 \in n
1920
                         by \vdash_N canonical forms
1921
                    4.3.3. QED
1922
                         \delta_N(\textit{binop}, v_0, v_1) \in n \cup \mathsf{DivErr}
1924
            2019-10-03 17:26. Page 37 of 1-148.
```

```
5. CASE \cdot \vdash_{\mathsf{N}} \mathsf{fst}\{\mathcal{U}\} v_0 : \mathcal{U}
1925
1926
                  5.1. v_0 = \langle v_1, v_2 \rangle
1927
                      because \delta_N(unop, v_0) is defined
1928
                  5.2. \cdot \vdash_{\mathsf{N}} v_1 : \mathcal{U}
1929
1930
                      by inversion \vdash_N
1931
                  5.3. QED
1932
                      \delta_N(unop, v_0) = v_1
1933
             6. CASE \cdot \vdash_{\mathsf{N}} \mathsf{snd}\{\mathcal{U}\} \, v_0 : \mathcal{U}
1934
1935
                  6.1. v_0 = \langle v_1, v_2 \rangle
1936
                      because \delta_N(unop, v_0) is defined
1937
                  6.2. \cdot \vdash_{\mathsf{N}} v_2 : \mathcal{U}
1938
                      by inversion \vdash_N
1939
1940
                  6.3. QED
1941
                      \delta_N(unop, v_0) = v_2
1942
             7. CASE \cdot \vdash_{\mathsf{N}} \mathsf{sum}\{\mathcal{U}\} v_0 v_1 : \mathcal{U}
1943
                  7.1. \delta_N(binop, v_0, v_1) \in i
1944
                      by definition \delta_N
1945
1946
                  7.2. QED
1947
                       \cdot \vdash_{\mathsf{N}} \delta_N(\mathit{binop}, v_0, v_1) : \mathcal{U}
             8. CASE \cdot \vdash_{\mathsf{N}} \mathsf{quotient}\{\mathcal{U}\} v_0 v_1 : \mathcal{U}
1950
                  8.1. \delta_N(binop, v_0, v_1) \in i \cup DivErr
1951
                      by definition \delta_N
1952
                  8.2. QED
1953
                       \cdot \vdash_{\mathsf{N}} \delta_N(\mathit{binop}, v_0, v_1) : \mathcal{U}
1954
1955
                                                                                                                                                                                                                                          1956
1957
                  Lemma 5.15. If \cdot \vdash_{\mathsf{N}} \mathsf{dyn} \ b_0 \ v_0 : \tau_0 \ and \ b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ then \ \exists \ e_1 \ such \ that \ \mathsf{dyn} \ b_0 \ v_0 \ \triangleright_{\mathsf{N}} \ e_1.
1958
                  PROOF. By case analysis of tag-match(\lfloor \tau_0 \rfloor, \upsilon_0).
1959
             1. CASE tag-match(|\tau_0|, \lambda x_1. e_1)
                  1.1. QED
                       dyn b_0 v_0 \triangleright_N mon b_0 v_0
1963
             2. Case tag-match(\lfloor \tau_0 \rfloor, \lambda(x_1 : \tau_1). e_1)
1964
                  2.1. Contradiction:
1965
1966
                       \cdot \vdash_{\mathsf{N}} \mathsf{dyn}\ b_0\ v_0 : \tau_0
1967
             3. CASE tag-match(\lfloor \tau_0 \rfloor, mon b_1 v_1)
1968
                  3.1. QED
1969
1970
                       dyn b_0 v_0 \triangleright_{N} mon b_0 v_0
1971
             4. Case tag-match(\lfloor(\tau_1 \times \tau_2)\rfloor, \langle v_1, v_2\rangle)
1972
1973
                       \mathsf{dyn}\,b_0\,v_0\,\rhd_{\mathsf{N}}\,\langle\mathsf{dyn}\,(\ell_0\,\blacktriangleleft\,\tau_1\,\blacktriangleleft\,\ell_1)\,v_1,\mathsf{dyn}\,(\ell_0\,\blacktriangleleft\,\tau_2\,\blacktriangleleft\,\ell_1)\,v_2\rangle
1974
1975
             5. CASE tag-match([Int], v_0)
                                                                                                                                                                                         2019-10-03 17:26. Page 38 of 1-148.
```

```
5.1. QED
1977
1978
                        dyn b_0 v_0 \triangleright_{N} v_0
1979
              6. CASE tag-match([Nat], v_0)
1980
                   6.1. QED
1981
1982
                        dyn b_0 v_0 \triangleright_{N} v_0
1983
              7. CASE \neg tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
1984
                   7.1. QED
1985
                        \mathsf{dyn}\ b_0\ v_0\ \triangleright_{\mathsf{N}}\ \mathsf{BndryErr}\ (b_0,v_0)
                                                                                                                                                                                                                                                            1988
1989
                   Lemma 5.16. If \cdot \vdash_N stat b_0 \ v_0 : \mathcal{U} and b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) then \exists \ e_1 \ such \ that \ stat \ b_0 \ v_0 \blacktriangleright_N \ e_1.
1990
                   PROOF. By case analysis on v_0.
1991
1992
              1. Case v_0 \in \lambda x.e
1993
                   1.1. Contradiction:
1994
                        \cdot \vdash_{\mathsf{N}} \mathsf{stat}\ b_0\ v_0 : \mathcal{U}
1995
1996
              2. Case v_0 \in \lambda(x:\tau). e
1997
                   2.1. QED
1998
                        stat b_0 \ v_0 \blacktriangleright_{\mathsf{N}} \ \mathsf{mon} \ b_0 \ v_0
1999
              3. Case v_0 \in \text{mon } b \ e
2000
2001
                   3.1. QED
2002
                        \operatorname{stat} b_0 v_0 \blacktriangleright_{\mathsf{N}} \operatorname{\mathsf{mon}} b_0 v_0
2003
              4. CASE v_0 = \langle v_1, v_2 \rangle
2004
                   4.1. \tau_0 = \tau_1 \times \tau_2
2005
2006
                        by inversion \vdash_N
                   4.2. QED
2008
                        \mathsf{stat}\; b_0\; v_0 \blacktriangleright_{\mathsf{N}} \; \langle \mathsf{stat}\; (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)\; v_1, \mathsf{stat}\; (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1)\; v_2 \rangle
2009
              5. Case v_0 \in i
2010
                   5.1. QED
2011
2012
                        stat b_0 v_0 \triangleright_{\mathsf{N}} v_0
2013
2014
2015
                    \text{Lemma 5.17 (N-dyn preservation)}. \  \  \textit{If} \ \cdot \vdash_{\mathsf{N}} \ \mathsf{dyn} \ b_0 \ v_0 : \tau_0 \ \textit{and} \ b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ \textit{and} \ \mathsf{dyn} \ b_0 \ v_0 \ \rhd_{\mathsf{N}} \ e_1 \ \textit{then} \cdot \vdash_{\mathsf{N}} e_1 : \tau_0. 
2016
2017
                   PROOF. By case analysis of \triangleright_{N}.
2018
               1. Case dyn b_0 \ v_0 \rhd_{\mathbb{N}} \ \mathsf{mon} \ b_0 \ v_0
2019
                                and v_0 \in (\lambda x. e) \cup (\text{mon } b \ v)
2021
                   1.1. QED
2022
2023
                                                                                                                     by inversion \vdash_N
2024
2025
                                                                                                                         \cdot \vdash_N v_0 : \mathcal{U}
                                                                                                                   \cdot \vdash_{\mathsf{N}} \mathsf{mon}\ b_0\ v_0 : \tau_0
```

2019-10-03 17:26. Page 39 of 1-148.

```
2029
                     2. Case \tau_0 = \tau_1 \times \tau_2
2030
                                              \text{ and dyn } (\ell_0 \blacktriangleleft (\tau_1 \times \tau_2) \blacktriangleleft \ell_1) \; \langle v_1, v_2 \rangle \; \rhd_{\mathsf{N}} \; \langle \mathsf{dyn} \; (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) \; v_1, \mathsf{dyn} \; (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \; v_2 \rangle
2031
                            2.1. QED
2032
2033
                                                                                                                    by inversion \vdash_N
                                                                                                                                                                                                                         by inversion \vdash_N
2034
2035
                                                                                                                                                                                                                          \cdot \vdash_{\mathsf{N}} v_2 : \mathcal{U}
                                                                                                                           \cdot \vdash_{\mathsf{N}} v_1 : \mathcal{U}
2036
                                                                                                     \overline{ \cdot \vdash_{\mathsf{N}} \mathsf{dyn} \left( \ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1 \right) v_1 : \tau_1 }    \cdot \vdash_{\mathsf{N}} \mathsf{dyn} \left( \ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1 \right) v_2 : \tau_2 
2037
                                                                                                                \cdot \vdash_{\mathsf{N}} \langle \mathsf{dyn} \left( \ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1 \right) v_1, \mathsf{dyn} \left( \ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1 \right) v_2 \rangle : \tau_1 \times \tau_2
                    3. Case dyn b_0 i_0 \triangleright_N i_0
2041
                                             and tag-match(\lfloor \tau_0 \rfloor, i_0)
2042
2043
                                   by case analysis of tag-match([\tau_0], i_0)
2044
                     4. CASE dyn b_0 v_0 \rhd_{\mathsf{N}} \mathsf{BndryErr}(b_0, v_0)
2045
2046
2047
                                  \cdot \vdash_{\mathsf{N}} \mathsf{BndryErr}(b_0, v_0) : \tau_0
2048
                                                                                                                                                                                                                                                                                                                                                                        2049
2050
                             \text{Lemma 5.18 (N-stat preservation)}. \  \, \textit{If} \, \cdot \vdash_{\mathsf{N}} \, \mathsf{stat} \, \textit{b}_0 \, \, \textit{v}_0 : \mathcal{U} \, \, \textit{and} \, \textit{b}_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \, \, \textit{and} \, \, \mathsf{stat} \, \textit{b}_0 \, \, \textit{v}_0 \, \blacktriangleright_{\mathsf{N}} \, \textit{e}_1 \, \, \textit{then} \, \cdot \vdash_{\mathsf{N}} \, \textit{e}_1. 
2051
                            PROOF. By case analysis of \triangleright_{N}.
2054
                     1. CASE v_0 \in (\lambda(x:\tau).e) \cup (\text{mon } b \ v)
2055
                                             and stat b_0 v_0 \triangleright_{\mathbb{N}} \text{mon } b_0 v_0
2056
                            1.1. QED
2057
2058
                                                                                                                                                                       by inversion \vdash_N
2060
                                                                                                                                                                               \cdot \vdash_{\mathsf{N}} v_0 : \tau_0
2061
                                                                                                                                                                    \cdot \vdash_{\mathsf{N}} \mathsf{mon}\ b_0\ v_0 : \mathcal{U}
2062
2063
                     2. Case \tau_0 = \tau_1 \times \tau_2
2064
                                              \text{ and stat } (\ell_0 \blacktriangleleft (\tau_1 \times \tau_2) \blacktriangleleft \ell_1) \ \langle v_1, v_2 \rangle \ \blacktriangleright_{\mathsf{N}} \ \langle \text{stat } (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) \ v_1, \text{ stat } (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_2 \rangle
                            2.1. QED
                                                                                                                    by inversion \vdash_N
2068
                                                                                                                                                                                                                         by inversion \vdash_N
2069
                                                                                                                           \cdot \vdash_{\mathsf{N}} v_1 : \tau_1
                                                                                                                                                                                                                               \cdot \vdash_{\mathsf{N}} v_2 : \tau_2
2070
                                                                                                   \frac{\cdot \cdot \cdot \cdot \cdot \cdot}{\cdot \vdash_{\mathsf{N}} \mathsf{stat} \left(\ell_{0} \blacktriangleleft \tau_{1} \blacktriangleleft \ell_{1}\right) v_{1} : \mathcal{U}} \qquad \frac{\cdot \vdash_{\mathsf{N}} \mathsf{stat} \left(\ell_{0} \blacktriangleleft \tau_{2} \blacktriangleleft \ell_{1}\right) v_{2} : \mathcal{U}}{\cdot \vdash_{\mathsf{N}} \mathsf{stat} \left(\ell_{0} \blacktriangleleft \tau_{2} \blacktriangleleft \ell_{1}\right) v_{2} : \mathcal{U}}
2071
2072
                                                                                                                     \cdot \vdash_{\mathsf{N}} \langle \mathsf{stat} \left( \ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1 \right) v_1, \mathsf{stat} \left( \ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1 \right) v_2 \rangle : \mathcal{U}
2073
                    3. Case stat b_0 i_0 \triangleright_N i_0
2074
2075
                           3.1. QED
2076
                                   \cdot \vdash_{\mathsf{N}} i_0 : \mathcal{U}
2077
                     4. Case stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_0 ►N TagErr \circ
2078
2079
                            4.1. Contradiction:
```

```
2081
                \cdot \vdash_{\mathsf{N}} v_0 : \tau_0
2082
2083
             Lемма 5.19.
2085
2086
                • If (x_0:\tau_0), \Gamma_0 \vdash_N e_1:\tau? and \cdot \vdash_N v_0:\tau_0 then \Gamma_0 \vdash_N e_1[x_0 \leftarrow v_0]:\tau?
2087
                • If (x_0:\mathcal{U}), \Gamma_0 \vdash_{\mathsf{N}} e_1 : \tau? and \cdot \vdash_{\mathsf{N}} v_0 : \mathcal{U} then \Gamma_0 \vdash_{\mathsf{N}} e_1[x_0 \leftarrow v_0] : \tau?
2088
             PROOF. By induction on e_1.
          1. Case e_1 = x_2
2092
             1.1. SCASE x_0 = x_2
2093
                1.1.1. QED
2094
                    e_1[x_0 \leftarrow v_0] = v_0
2095
             1.2. Scase x_0 \neq x_2
2096
2097
                1.2.1. QED
2098
                    e_1[x_0\!\leftarrow\!v_0]=e_1
2099
         2. Case e_1 = i_0
2100
             2.1. QED
2101
2102
                e_1[x_0 \leftarrow v_0] = e_1
2103
         3. CASE e_1 = \lambda x_2 . e_2
2104
             3.1. SCASE x_0 = x_2
2105
                3.1.1. QED
2106
                    by the induction hypothesis
2107
2108
             3.2. SCASE x_0 \neq x_2
2109
                3.2.1. QED
2110
                    e_1[x_0\!\leftarrow\!v_0]=e_1
2111
2112
         4. CASE e_1 = \lambda(x_2 : \tau_2). e_2
2113
             4.1. SCASE x_0 = x_2
2114
                4.1.1. QED
2115
                    by the induction hypothesis
2116
2117
             4.2. SCASE x_0 \neq x_2
2118
                4.2.1. QED
2119
                    e_1[x_0 \leftarrow v_0] = e_1
2120
          5. Case e_1 = \langle e_2, e_3 \rangle
2121
             5.1. QED
2122
2123
                by the induction hypothesis
2124
         6. Case e_1 = app\{\tau?\} e_2 e_3
2125
             6.1. QED
2126
2127
                by the induction hypothesis
2128
         7. CASE e_1 = unop\{\tau?\} e_2
2129
             7.1. QED
2130
                by the induction hypothesis
2131
2132
         2019-10-03 17:26. Page 41 of 1-148.
```

```
2133
            8. CASE e_1 = binop\{\tau?\} e_2 e_3
2134
2135
                     by the induction hypothesis
2136
             9. CASE e_1 = \text{dyn } b_2 e_2
2137
2138
                 9.1. QED
2139
                     by the induction hypothesis
2140
             10. CASE e_1 = \text{stat } b_2 e_2
2141
                 10.1. QED
2142
                     by the induction hypothesis
2144
                                                                                                                                                                                                                                 2145
2146
                 Lemma 5.20 (\overline{\Vdash}-progress). If (e_0)^{\ell_0}:\tau? \overline{\mathbf{wf}} and \cdot; \ell_0 \overline{\Vdash} e_0 then one of the following holds:
2147
                     • e_0 \in ((v))^{\ell}
2148
2149
                    • e_0 \in E[\mathsf{Err}]^\ell
2150
                    • \exists e_1 \text{ such that } e_0 \longrightarrow_{\overline{N}} e_1
2151
2152
                  PROOF. By case analysis of e_0.
2153
             By lemma 5.25, it suffices to consider the following cases.
2154
2155
             1. CASE e_0 \in ((v))^{\ell}
2156
                 1.1. QED
2157
            2. Case e_0 \in E[\mathsf{Err}]^\ell
2158
                 2.1. QED
2159
            3. Case e_0 = E[\mathsf{app}\{\tau_1\}\,(\!(\upsilon_0)\!)^{\ell_0}\,(\!(\upsilon_1)\!)^{\ell_0}]^{\ell_0}
2160
2161
                 3.1. v_0 \in (\lambda(x:\tau).e) \cup (\text{mon } b \ v)
2162
                     by \vdash_N canonical forms and \vdash_N inversion
2163
                 3.2. Scase v_0 = \lambda(x_2 : \tau_2). e_2
2164
2165
                     3.2.1. QED
2166
                          e_0 \triangleright_{\overline{\mathbb{N}}} E[e_2[x_2 \leftarrow (v_1)^{\ell_0 \ell_0 \ell_0}]]^{\ell_0}
2167
                 3.3. SCASE v_0 = \text{mon} (\ell_0 \blacktriangleleft (\tau_2 \Rightarrow \tau_3) \blacktriangleleft \ell_1) v_2
2168
                     3.3.1. Let b_3 = (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1)
                                         and b_4 = (\ell_1 \blacktriangleleft \tau_2 \blacktriangleleft \ell_0)
2171
                     3.3.2. QED
2172
                          e_0 \rhd_{\overline{N}} E[\mathsf{dyn}\,b_3\ (\mathsf{app}\{\mathcal{U}\}\,v_2\ (\mathsf{stat}\,b_4\ (\!(v_1)\!)^{\ell_0\ell_0\ell_0}))^{\ell_2}]^{\ell_0}
2173
             4. CASE e_0 = E[app{\{U\} ((v_0))^{\ell_0} ((v_1))^{\ell_0}}]^{\ell_0}
2174
2175
                 4.1. SCASE v_0 = \lambda x_2 . e_2
2176
                     4.1.1. QED
2177
                          e_0 \blacktriangleright_{\overline{N}} E[e_2[x_2 \leftarrow (v_0)^{\ell_0 \ell_0 \ell_0}]]^{\ell_0}
2178
                 4.2. SCASE v_0 = \text{mon} (\ell_0 \blacktriangleleft (\tau_2 \Rightarrow \tau_3) \blacktriangleleft \ell_1) v_2
2179
2180
                      4.2.1. LET b_3 = (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1)
2181
                                         and b_4 = (\ell_1 \blacktriangleleft \tau_2 \blacktriangleleft \ell_0)
                                         and \tau_4 = forget(\tau_3)
```

```
4.2.2. QED
2185
                             e_0 \blacktriangleright_{\overline{\mathbb{N}}} E[\mathsf{stat}\ b_3\ (\mathsf{app}\{\tau_4\}\ v_2\ (\mathsf{dyn}\ b_4\ (\!(v_1)\!)^{\ell_0\ell_0\ell_0}))^{\ell_2}]^{\ell_0}
2186
2187
                    4.3. SCASE v_0 \notin (\lambda x. e) \cup (\text{mon } b \ v)
2188
                        4.3.1. QED
2189
                             e_0 \blacktriangleright_{\overline{N}} E[\mathsf{TagErr} \bullet]^{\ell_0}
2190
2191
               5. CASE e_0 = E[unop\{\tau?\} ((v_0))^{\ell_0}]^{\ell_0}
2192
                    5.1. QED
2193
                        by lemma 5.11 and lemma 5.28
2194
              6. Case e_0 = E[binop\{\tau?\} ((v_0))^{\ell_0} ((v_1))^{\ell_0}]^{\ell_0}
2196
                    6.1. QED
2197
                         by lemma 5.11 and lemma 5.28
2198
              7. CASE e_0 = E[\text{dyn } b_1 ((v_1))^{\ell_0}]^{\ell_0}
2199
2200
                    7.1. OED
2201
                         by lemma 5.11 and lemma 5.30
2202
              8. CASE e_0 = E[\text{stat } b_1 ((v_1))^{\ell_0}]^{\ell_0}
2203
2204
2205
                        by lemma 5.11 and lemma 5.31
2206
2207
                    Lemma 5.21 (\overline{\Vdash}-preservation). If (e_0)^{\ell_0}: \tau? \overline{\mathbf{wf}} and e_0 \longrightarrow_{\overline{\mathbf{N}}} e_1 then \cdot; \ell_0 \ \overline{\Vdash} \ e_1
2209
2210
                    PROOF. By lemma 5.22 and lemma 5.23.
2211
2212
2213
                    LEMMA 5.22. If (e_0)^{\ell_0}: \tau_0 \overline{\mathbf{wf}} and e_0 \rhd_{\overline{\mathbf{N}}} e_1 then \cdot; \ell_0 \Vdash e_1
2214
2215
                    PROOF. By case analysis of \triangleright_{\overline{N}}.
2216
2217
               1. CASE \delta_N(unop, ((v_0))^{\ell_0}) is defined
                                \text{ and } (\mathit{unop}\{\tau^?\} \left(\!\!\left(v_0\right)\!\!\right)^{\ell_0})^{\ell_0} \rhd_{\overline{\mathbf{N}}} \left(\delta_N(\mathit{unop}, \left(\!\!\left(v_0\right)\!\!\right)^{\ell_0})\right)^{\ell_0}
2218
2219
                    1.1. QED
2220
                        by lemma 5.29
              2. CASE \delta_N(binop, ((v_0))^{\ell_0}, ((v_1))^{\ell_0}) is defined
2222
2223
                                and (binop\{\tau?\} ((v_0))^{\ell_0} ((v_1))^{\ell_0})^{\ell_0} >_{\overline{N}} (\delta_N(binop, ((v_0))^{\ell_0}, ((v_1))^{\ell_0}))^{\ell_0}
2224
2225
                        by lemma 5.29
2226
              3. Case (app\{\tau_0\} ((\lambda(x_0:\tau_1).e_0))^{\ell_0} ((v_1))^{\ell_0})^{\ell_0} \rhd_{\overline{N}} (e_0[x_0 \leftarrow ((v_1))^{\ell_0\ell_0\ell_0}])^{\ell_0}
2227
                    3.1. QED
2229
                        by lemma 5.34
2230
              4. Case (app\{\tau_0\} ((mon (\ell_0 \blacktriangleleft (\tau_1 \Rightarrow \tau_2)^{\ell_1} \blacktriangleleft \ell_1) (\upsilon_0)^{\ell_2}))^{\ell_0} ((\upsilon_1))^{\ell_0})^{\ell_0}
2231
                                \rhd_{\overline{\mathbf{N}}} \left( \mathsf{dyn} \left( \ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1 \right) \left( \mathsf{app} \{ \mathcal{U} \} \, v_0 \, \left( \mathsf{stat} \left( \ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0 \right) \left( \! \left( v_1 \right) \! \right)^{\! \ell_0 \ell_0 \ell_0} \right) \right)^{\! \ell_2} \right)^{\! \ell_0}
2232
2233
                         4.0.1. \ell_1 = \ell_2
2234
                             by inversion \overline{\Vdash}
2236
              2019-10-03 17:26. Page 43 of 1-148.
```

```
2237
                                4.0.2. QED
2238
2239
                                                                                                                                                                                     by inversion  □
2240
                                                                                                                                                                                            \cdot; \ell_0 \ \overline{\Vdash} \ v_1
2241
                                                                                                                                                                                 \overline{\cdot;\ell_0 \Vdash ((v_1))^{\ell_0\ell_0\ell_0}}
2242
                                                                                                   by inversion \overline{\Vdash}
2243
                                                                                                                                                  \vdots : \ell_1 \stackrel{\text{$\downarrow$}}{\vdash} \operatorname{stat} \left( \ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0 \right) ((v_1))^{\ell_0 \ell_0 \ell_0}
                                                                                                           \cdot; \ell_1 \Vdash v_0
2244
2245
                                                                                                              \cdot; \ell_1 \Vdash \mathsf{app}\{\mathcal{U}\} v_0 \ (\mathsf{stat} \ (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \ (\!(v_1)\!)^{\ell_0 \ell_0 \ell_0})
                                                                                                          \cdot; \ell_1 \ \overline{\vdash} \ (\mathsf{app}\{\mathcal{U}\} \ v_0 \ (\mathsf{stat} \ (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \ (\!(v_1)\!)^{\ell_0 \overline{\ell_0} \ell_0}))^{\ell_2}
2248
                                                                                   \cdot ; \ell_0 \ \overline{\vdash} \ \mathsf{dyn} \ (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ (\mathsf{app} \overline{\{\mathcal{U}\}} \ v_0 \ (\mathsf{stat} \ (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \ (\!(v_1)\!)^{\ell_0 \ell_0 \ell_0}))^{\ell_2}
2249
                                                                                \cdot ; \ell_0 \stackrel{\mathbb{H}}{\Vdash} (\operatorname{dyn} (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) (\operatorname{app} \{\mathcal{U}\} v_0 (\operatorname{stat} (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) ((v_1))^{\ell_0 \ell_0 \ell_0}))^{\ell_2})^{\ell_0}
2250
2251
                   5. CASE (\text{dyn} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) ((v_0))^{\ell_2})^{\ell_0} \rhd_{\overline{N}} e_2
2252
2253
                          by lemma 5.32
2254
2255
                                                                                                                                                                                                                                                                                                                                             2256
                          LEMMA 5.23. If (e_0)^{\ell_0}: \mathcal{U} \ \overline{\mathbf{wf}} \ and \ e_0 \blacktriangleright_{\overline{\mathbf{N}}} e_1 \ then \cdot; \ell_0 \ \overline{\Vdash} \ e_1
2257
2258
                          PROOF. By case analysis of \triangleright_{\mathbb{N}}.
2259
                    1. Case \delta_N(\mathit{unop}, (\!(v_0)\!)^{\ell_0}) is not defined
                                          and (unop\{\tau?\} ((v_0))^{\ell_0})^{\ell_0} \blacktriangleright_{\overline{\Lambda}} (\mathsf{TagErr} \bullet)^{\ell_0}
2262
                          1.1. QED
2263
                    2. CASE \delta_N(unop, ((v_0))^{\ell_0}) is defined
2264
                                          \text{ and } (\mathit{unop}\{\tau?\}\,(\!(v_0)\!)^{\ell_0})^{\ell_0} \blacktriangleright_{\overline{\mathbb{N}}} (\delta_N(\mathit{unop},(\!(v_0)\!)^{\ell_0}))^{\ell_0}
2265
2266
                          2.1. QED
2267
                                by lemma 5.29
2268
                    3. CASE \delta_N(binop, ((v_0))^{\ell_0}, ((v_1))^{\ell_0}) is not defined
2269
                                          and (binop\{\tau?\} ((v_0))^{\ell_0} ((v_1))^{\ell_0})^{\ell_0} \blacktriangleright_{\overline{N}} (\mathsf{TagErr} \bullet)^{\ell_0}
2270
2271
2272
                    4. CASE \delta_N(binop, ((v_0))^{\ell_0}, ((v_1))^{\ell_0}) is defined
2273
                                          \text{ and } (binop\{\tau?\} (\!(v_0)\!)^{\ell_0} (\!(v_1)\!)^{\ell_0})^{\ell_0} \blacktriangleright_{\overline{\mathbf{N}}} (\delta_N(binop, (\!(v_0)\!)^{\ell_0}, (\!(v_1)\!)^{\ell_0}))^{\ell_0}
2274
2275
2276
                                by lemma 5.29
2277
                   5. Case (app\{\mathcal{U}\}((\lambda x_0. e_0))^{\ell_0}((v_1))^{\ell_0})^{\ell_0} \blacktriangleright_{\overline{N}} (e_0[x_0 \leftarrow ((v_1))^{\ell_0}\ell_0\ell_0])^{\ell_0}
2278
2279
2280
                               by lemma 5.34
2281
                  6. CASE (app\{\mathcal{U}\} ((mon (\ell_0 \blacktriangleleft (\tau_0 \Rightarrow \tau_1)^{\ell_1} \blacktriangleleft \ell_1) (v_0)^{\ell_2}))^{\ell_0} ((v_1))^{\ell_0})^{\ell_0})
2282
                                          \left(\operatorname{stat}\left(\ell_{0} \blacktriangleleft \tau_{1} \blacktriangleleft \ell_{1}\right) \left(\operatorname{app}\left\{forget(\tau_{1})\right\} v_{0} \left(\operatorname{dyn}\left(\ell_{1} \blacktriangleleft \tau_{0} \blacktriangleleft \ell_{0}\right) \left(\!\left(v_{1}\right)\!\right)^{\!\ell_{0} \ell_{0} \ell_{0}}\right)\right)^{\!\ell_{2}}\right)^{\!\ell_{0}}
2283
2284
                          6.1. \ell_1 = \ell_2
2285
                                by inversion  □
2286
                          6.2. QED
```

```
by inversion  □
2290
2291
                                                                                                                                                 \frac{\overline{\cdot ; \ell_0 \Vdash v_1}}{\cdot ; \ell_0 \Vdash ((v_1))^{\ell_0 \ell_0 \ell_0}}
                                                                                  by inversion \overline{\Vdash}
                                                                                                                      \cdot; \ell_0 \Vdash \operatorname{dyn} (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_0) ((v_1))^{\ell_0 \ell_0 \ell_0}
                                                                                        \cdot; \ell_0 \Vdash v_0
2295
                                                                                  \cdot; \ell_0 \Vdash \operatorname{app} \{ forget(\tau_1) \} v_0 (\operatorname{dyn} (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_0) ((v_1))^{\ell_0 \ell_0 \ell_0} )
                                                                               \cdot ; \ell_0 \ \overline{\vdash} \ (\mathsf{app} \{ \mathit{forget}(\tau_1) \} \ v_0 \ (\mathsf{dyn} \ (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_0) \ (\!(v_1)\!)^{\ell_0 \ell_0 \ell_0}))^{\ell_2}
                                                            \cdot ; \ell_0 \Vdash \mathsf{stat} \left(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1\right) \overline{\left(\mathsf{app} \{ \mathit{forget}(\tau_1) \} \ v_0 \ (\mathsf{dyn} \ (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_0) \ (\!(v_1)\!)^{\ell_0 \ell_0 \ell_0} \right)\right)^{\ell_2}}
2300
                                                         \cdot ; \ell_0 \stackrel{\sqsubseteq}{\vdash} (\mathsf{stat} \ (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) \ (\mathsf{app} \{ \mathit{forget}(\tau_1) \} \ v_0 \ (\mathsf{dyn} \ \overline{(\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_0) \ (\!(v_1)\!)^{\ell_0 \ell_0 \ell_0}}))^{\ell_2})^{\ell_0 \ell_0 \ell_0})
2301
2302
               7. CASE (stat (\ell_0 \triangleleft \tau_0 \triangleleft \ell_1) ((v_0))^{\ell_2})^{\ell_0} \blacktriangleright_{\Sigma} e_2
2303
2304
                     7.1. QED
2305
                          by lemma 5.33
2306
2307
2308
                     Lemma 5.24 (unwind boundary error). If \cdot \vdash_{\mathsf{N}} e_0 : \tau? and e_0 \to_{\mathsf{N}}^* \mathsf{BndryErr}(b_0, v_1) then \exists v_1, E such that
2309
2310
                e_0 \rightarrow_{\mathsf{N}}^* E_0[\mathsf{dyn}\ b_0\ v_1] \rightarrow_{\mathsf{N}} E_0[\mathsf{BndryErr}\ (b_0, v_1)]
2311
                     Proof. By the definitions of \triangleright_N and \blacktriangleright_N, only dyn expression can step to a boundary error.
2312
2313
2314
2315
                     LEMMA 5.25. If \cdot \vdash_{\mathsf{N}} e_0 : \tau? and \cdot ; \ell_0 \Vdash e_0 then either:
2316
                          • e_0 \in ((v))^{\ell}
2317
                          • e_0 = E_0[\mathsf{app}\{\tau?\} ((v_0))^{\ell_0} ((v_1))^{\ell_0}]^{\ell_0}
                         • e_0 = E_0[unop\{\tau?\}((v_0))^{\ell_0}]^{\ell_0}
2320
                         • e_0 = E_0[binop\{\tau?\} ((v_0))^{\ell_0} ((v_1))^{\ell_0}]^{\ell_0}
2321
                          • e_0 = E_0[\mathsf{dyn}\ b_1\ ((v_1))^{\ell_0}]^{\ell_0}
2322
2323
                          • e_0 = E_0[\text{stat } b_1 ((v_1))^{\ell_0}]^{\ell_0}
2324
                          • e_0 = E_0[\mathsf{Err}]^{\ell_0}
2326
                     PROOF. By induction on the structure of e_0.
2327
                1. CASE e_0 = ((x_0))^{\ell_0}
2328
                     1.1. Contradiction:
2329
2330
                          \cdot; \ell_0 \Vdash e_0
2331
               2. Case e_0 \in ((v))^{\ell_0}
2332
                     2.1. QED
2333
               3. CASE e_0 = ((\langle e_1, e_2 \rangle))^{\ell_0}
2334
                     3.1. \cdot \vdash_{N} e_{1} : \tau? and \cdot \vdash_{N} e_{2} : \tau?
2335
2336
                          by inversion \vdash_N
2337
                     3.2. \cdot; \ell_0 \Vdash e_1 and \cdot; \ell_0 \Vdash e_2
2338
                          by inversion  □
2339
2340
               2019-10-03 17:26. Page 45 of 1-148.
```

```
3.3. Scase e_1 \notin (v)^{\overline{\ell}}
2341
2342
                3.3.1. QED
2343
                    by the induction hypothesis
2344
             3.4. SCASE e_1 \in (v)^{\overline{\ell}} and e_2 \notin (v)^{\overline{\ell}}
2345
                3.4.1. OED
2346
2347
                    by the induction hypothesis
2348
             3.5. SCASE e_1 \in ((v))^{\overline{\ell}} and e_2 \in ((v))^{\overline{\ell}}
2349
                3.5.1. QED
2350
                    e_0 \in ((v))^{\overline{\ell}}
2352
          4. CASE e_0 = app\{\tau?\} e_1 e_2
2353
             4.1. QED
2354
                by the induction hypothesis
2355
          5. CASE e_0 = unop\{\tau?\} e_1
2356
2357
             5.1. QED
2358
                by the induction hypothesis
2359
          6. Case e_0 = binop\{\tau?\} e_1 e_2
2360
             6.1. QED
2361
2362
                by the induction hypothesis
2363
         7. CASE e_0 = \text{dyn} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (e_1)^{\ell_1}
2364
             7.1. \cdot; \ell_1 \overline{\Vdash} e_1
                by inversion \overline{\Vdash}
2366
2367
             7.2. QED
2368
                by the induction hypothesis
2369
          8. CASE e_0 = \text{stat } b_1 e_1
2370
             8.1. QED
2371
2372
                by the induction hypothesis
2373
2374
2375
             Lemma 5.26. If \cdot; \ell_0 \Vdash E_0[e_0] then \exists \ell_1 such that \cdot; \ell_1 \Vdash e_0
2376
             PROOF. By induction on the structure of E_0.
          1. E_0 = []
             1.1. QED
2380
         2. E_0 = \langle E_1, e_2 \rangle
2381
2382
             2.1. QED
2383
                by the induction hypothesis
2384
         3. E_0 = \langle e_1, E_2 \rangle
2385
2386
             3.1. QED
2387
                by the induction hypothesis
2388
          4. E_0 = unop\{\tau?\} E_1
2389
             4.1. QED
2390
2391
                by the induction hypothesis
```

```
5. E_0 = binop\{\tau?\} E_1 e_2
2393
2394
              5.1. QED
2395
                 by the induction hypothesis
2396
          6. E_0 = binop\{\tau?\} e_1 E_2
2397
2398
             6.1. QED
2399
                 by the induction hypothesis
2400
          7. E_0 = \text{dyn} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) (E_1)^{\ell_3}
2401
             7.1. \cdot; \ell_2 \overline{\Vdash} E_1[e_0]
2402
2403
              7.2. QED
2404
                 by the induction hypothesis
2405
          8. E_0 = \text{stat} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) (E_1)^{\ell_3}
2406
              8.1. QED
2407
                 by the induction hypothesis
2408
2409
          9. E_0 = (E_1)^{\ell_0}
2410
              9.1. QED
2411
                 by the induction hypothesis
2412
2413
2414
              Lemma 5.27 (\overline{\Vdash} replacement). If \cdot; \ell_0 \ \overline{\Vdash} \ E_0[e_0] and the derivation contains a proof of \cdot; \ell_1 \ \overline{\Vdash} \ e_0 and \cdot; \ell_1 \ \overline{\Vdash} \ e_1 then
2415
2416
          L_0; \ell_0 \ \overline{\Vdash} \ E_0[e_1]
2417
2418
              PROOF. By induction on the structure of E_0.
2419
          1. E_0 = []
2420
              1.1. QED
2421
          2. E_0 = \langle E_1, e_2 \rangle
2422
2423
             2.1. QED
2424
                 by the induction hypothesis
2425
          3. E_0 = \langle e_1, E_2 \rangle
2426
             3.1. QED
2427
                 by the induction hypothesis
2428
          4. E_0 = unop\{\tau?\} E_1
2430
             4.1. QED
2431
                 by the induction hypothesis
2432
          5. E_0 = binop\{\tau?\} E_1 e_2
2433
2434
              5.1. QED
2435
                 by the induction hypothesis
2436
          6. E_0 = binop\{\tau?\} e_1 E_2
2437
2438
             6.1. QED
2439
                 by the induction hypothesis
2440
          7. E_0 = \text{dyn} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) (E_1)^{\ell_3}
2441
             7.1. \cdot; \ell_2 \Vdash E_1[e_0]
2442
2443
             7.2. QED
2444
          2019-10-03 17:26. Page 47 of 1-148.
```

2019-10-03 17:26. Page 48 of 1-148.

```
by the induction hypothesis
2445
2446
                        8. E_0 = \text{stat} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) (E_1)^{\ell_3}
2447
2448
                                        by the induction hypothesis
2449
                        9. E_0 = (E_1)^{\ell_0}
2450
2451
                                 9.1. QED
2452
                                        by the induction hypothesis
2453
2454
                                                                                                                                                                                                                                                                                                                                                                                                                                    2456
                                 Lemma 5.28 (\delta_N label progress).
2457
                                       \bullet \ \ \textit{If} \ \cdot \vdash_{\mathsf{N}} \textit{unop}\{\tau_1\} \ \upsilon_0 : \tau_0 \ \textit{and} \ \cdot ; \ell_0 \ \overline{\vdash} \ \textit{unop}\{\tau_1\} \ \upsilon_0 \ \textit{then} \ \delta_N(\textit{unop}, \upsilon_0) \ \textit{is defined and unop}\{\tau_1\} \ \upsilon_0 \ \rhd_{\overline{\mathsf{N}}} \ \delta_N(\textit{unop}, \upsilon_0).
2458
                                       • if \cdot \vdash_{\mathsf{N}} binop\{\tau_1\} \ v_0 \ v_1 : \tau_0 \ and \ \cdot; \ell_0 \ \overline{\vdash} \ binop\{\tau_1\} \ v_0 \ v_1 \ then \ \delta_N(binop, v_0, v_1) \ is \ defined \ and \ binop\{\tau_1\} \ v_0 \ v_1 \ \triangleright_{\overline{\mathsf{N}}} \ (v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1 \ v_0 \ v_1 \ v_0 \ v_1) \ (v_0 \ v_1
2459
2460
                                               \delta_N(binop, v_0, v_1).
2461
                                       • If \cdot \vdash_{\mathsf{N}} unop\{\mathcal{U}\} v_0 : \mathcal{U} \ and \cdot ; \ell_0 \ \overline{\Vdash} \ unop\{\mathcal{U}\} v_0 \ then \ unop\{\mathcal{U}\} v_0 \blacktriangleright_{\overline{\mathsf{N}}} e_1.
2462
                                       • if \cdot \vdash_{\mathsf{N}} binop\{\mathcal{U}\} v_0 v_1 : \mathcal{U} \text{ and } \cdot ; \ell_0 \Vdash binop\{\mathcal{U}\} v_0 v_1 \text{ then } binop\{\mathcal{U}\} v_0 v_1 \blacktriangleright_{\mathsf{N}} e_1.
2463
2464
                                 PROOF. By case analysis of \delta_N, \vdash_N, \overline{\vdash}, and \blacktriangleright_{\overline{N}}.
2465
                         1. CASE \cdot \vdash_{\mathsf{N}} unop\{\tau_1\} v_0 : \tau_0
2466
2467
                                 1.1. v_0 = ((v_1))^{\ell_0}
2468
                                        by inversion  □
2469
                                 1.2. v_1 = \langle v_2, v_3 \rangle
2470
                                        by inversion \vdash_N
2471
2472
                                 1.3. QED
2473
                                        by definition \delta_N
2474
                        2. CASE \cdot \vdash_{\mathsf{N}} binop\{\tau_1\} v_0 v_1 : \tau_0
2475
                                 2.1. v_0 = ((v_2))^{\ell_0} and v_1 = ((v_3))^{\ell_0}
2476
2477
                                        by inversion \overline{\Vdash}
2478
                                 2.2. v_0 \in i and v_1 \in i
2479
                                        by inversion \vdash_N
                                 2.3. QED
                                        by definition \delta_N
2483
                        3. CASE \cdot \vdash_{\mathsf{N}} unop\{\mathcal{U}\} v_0 : \mathcal{U}
2484
                                 3.1. QED
2485
                                        by inversion \overline{\Vdash}
2486
2487
                        4. CASE \cdot \vdash_{\mathsf{N}} binop\{\mathcal{U}\} v_0 v_1 : \mathcal{U}
2488
                                 4.1. QED
2489
                                        by inversion  □
2490
2491
                                                                                                                                                                                                                                                                                                                                                                                                                                    2492
2493
                                 Lemma 5.29 (\delta_N label preservation).
2494
                                      • If \cdot; \ell_0 \Vdash unop\{\tau?\} v_0 and (unop\{\tau?\} v_0)^{\ell_0} (\triangleright_{\overline{N}} \cup \blacktriangleright_{\overline{N}}) (e_1)^{\ell_0} then \cdot; \ell_0 \Vdash e_1.
```

```
• If \cdot; \ell_0 \Vdash binop\{\tau?\} \ v_0 \ v_1 \ and \ (binop\{\tau?\} \ v_0 \ v_1)^{\ell_0} \ (\triangleright_{\overline{N}} \cup \blacktriangleright_{\overline{N}}) \ (e_1)^{\ell_0} \ then \ \cdot; \ell_0 \Vdash e_1.
2497
2498
                       Proof. By case analysis of (\triangleright_{\overline{N}} \cup \blacktriangleright_{\overline{N}}).
2499
                 1. (\operatorname{fst}\{\tau?\} (\!(\langle v_1, v_2 \rangle)\!)^{\ell_0})^{\ell_0} (\triangleright_{\overline{N}} \cup \blacktriangleright_{\overline{N}}) (\!(v_1)\!)^{\ell_0}
2501
                       1.1. \cdot; \ell_0 \Vdash v_1
2502
                             by inversion \overline{\Vdash}
2503
2504
                       1.2. QED
2505
                 2. (\operatorname{snd}\{\tau?\} ((\langle v_1, v_2 \rangle))^{\ell_0})^{\ell_0} (\triangleright_{\overline{N}} \cup \blacktriangleright_{\overline{N}}) ((v_2))^{\ell_0}
2506
                       2.1. \cdot; \ell_0 \Vdash v_2
                             by inversion  □
2508
2509
                 3. (\operatorname{sum}\{\tau?\} ((i_1))^{\ell_1} ((i_2))^{\ell_2})^{\ell_0} (\triangleright_{\overline{N}} \cup \blacktriangleright_{\overline{N}}) (i_1 + i_2)^{\ell_0}
2510
2511
2512
                 4. (\operatorname{quotient}\{\tau?\} ((i_1))^{\ell_1} ((i_2))^{\ell_2})^{\ell_0} (\triangleright_{\overline{N}} \cup \blacktriangleright_{\overline{N}}) (\operatorname{DivErr})^{\ell_0}
2513
2514
                 5. (\operatorname{quotient}\{\tau?\} ((i_1))^{\ell_1} ((i_2))^{\ell_2})^{\ell_0} (\triangleright_{\overline{N}} \cup \blacktriangleright_{\overline{N}}) (\lfloor i_1/i_2 \rfloor)^{\ell_0}
2515
2516
                       5.1. QED
2517
2518
2519
                        \text{LEMMA 5.30. } \textit{If} \cdot \vdash_{\mathsf{N}} \mathsf{dyn} \ b_0 \ v_0 : \tau_0 \ \textit{and} \ \cdot ; \ell_0 \ \overline{\Vdash} \ \mathsf{dyn} \ b_0 \ v_0 \ \textit{then} \ \exists \ e_1 \ \textit{such that} \ (\mathsf{dyn} \ b_0 \ v_0)^{\ell_0} \ \rhd_{\overline{\mathsf{N}}} \ (e_1)^{\ell_0}. 
2521
                        PROOF. By inversion of \overline{\Vdash} and case analysis of tag-match(\lfloor \tau_0 \rfloor, \upsilon_0).
2522
                  1. b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)
2523
2524
                        and \cdot; \ell_1 \overline{\Vdash} v_0
2525
                       by inversion  □
2526
                 2. v_0 = ((v_1))^{\ell_1}
2527
                       by inversion  □
2528
2529
                 3. Case v_1 = \lambda x_1. e_1 and tag\text{-}match(\lfloor \tau_0 \rfloor, v_1)
2530
                       3.1. QED
2531
                             (\operatorname{\mathsf{dyn}} b_0 \ v_0)^{\ell_0} \rhd_{\overline{\mathsf{N}}} (\operatorname{\mathsf{mon}} b_0 \ v_0)^{\ell_0}
2532
                 4. CASE v_1 = \lambda(x_1 : \tau_1). e_1 and tag-match(\lfloor \tau_0 \rfloor, v_1)
2533
2534
                       4.1. Contradiction:
2535
                             \cdot \vdash_{\mathsf{N}} \mathsf{dyn} \ b_0 \ v_0 : \tau_0
2536
                 5. CASE v_1 = \text{mon } b_1 v_2 \text{ and } tag\text{-}match(\lfloor \tau_0 \rfloor, v_1)
2537
2538
2539
                             (\operatorname{dyn} b_0 \ v_0)^{\ell_0} \rhd_{\overline{N}} (\operatorname{mon} b_0 \ v_0)^{\ell_0}
2540
                 6. Case v_1 = \langle v_2, v_3 \rangle and tag\text{-}match(\lfloor (\tau_1 \times \tau_2)^{\ell_1} \rfloor, v_1)
2541
2542
                             (\operatorname{dyn} b_0 \ v_0)^{\ell_0} \rhd_{\overline{N}} (\langle \operatorname{dyn} (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) \ v_2, \operatorname{dyn} (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_3 \rangle)^{\ell_0}
2543
2544
                 7. CASE v_1 \in i and tag\text{-}match(\lfloor Int \rfloor, v_1)
2545
                       7.1. QED
2546
                             (\operatorname{dyn} b_0 \ v_0)^{\ell_0} \rhd_{\overline{N}} (v_1)^{\ell_0}
2547
2548
                 2019-10-03 17:26. Page 49 of 1-148.
```

```
8. CASE v_1 \in n and tag\text{-}match(\lfloor Nat \rfloor, v_1)
2549
2550
2551
                            (\mathsf{dyn}\ b_0\ v_0)^{\ell_0} \rhd_{\overline{\mathsf{N}}} (v_1)^{\ell_0}
2552
                 9. Case \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_1)
2553
2554
                      9.1. QED
                           (\mathsf{dyn}\,b_0\,v_0)^{\ell_0} \rhd_{\overline{\mathsf{N}}} (\mathsf{BndryErr}\,(b_0,v_0))^{\ell_0}
2555
2556
                                                                                                                                                                                                                                                                                                   \text{Lemma 5.31. } \textit{If} \cdot \vdash_{\mathsf{N}} \mathsf{stat} \ b_0 \ v_0 : \mathcal{U} \ \textit{and} \cdot ; \ell_0 \ \overline{\vdash} \ \mathsf{stat} \ b_0 \ v_0 \ \textit{then} \ \exists \ e_1 \ \textit{such that} \ (\mathsf{stat} \ b_0 \ v_0)^{\ell_0} \blacktriangleright_{\overline{\mathsf{N}}} (e_1)^{\ell_0}. 
                      PROOF. By case analysis on v_0.
2561
                 1. b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)
2562
2563
                       and \cdot; \ell_1 \Vdash v_0
2564
                      by inversion \overline{\Vdash}
2565
                 2. v_0 = ((v_1))^{\ell_1}
2566
2567
                      by inversion  □
2568
                 3. Case v_1 \in \lambda x. e
2569
                      3.1. Contradiction:
2570
                            \cdot \vdash_{\mathsf{N}} \mathsf{stat}\ b_0\ v_0 : \mathcal{U}
2571
                 4. Case v_1 \in \lambda(x:\tau). e
                      4.1. QED
2574
                           (\text{stat } b_0 \ v_0)^{\ell_0} \blacktriangleright_{\overline{N}} (\text{mon } b_0 \ v_0)^{\ell_0}
2575
                 5. Case v_1 \in \text{mon } b \stackrel{\frown}{e}
2576
                      5.1. QED
2577
                           (\mathsf{stat}\ b_0\ v_0)^{\ell_0} \blacktriangleright_{\overline{\mathsf{N}}} (\mathsf{mon}\ b_0\ v_0)^{\ell_0}
2578
2579
                 6. CASE v_1 = \langle v_2, v_3 \rangle
2580
                      6.1. \tau_0 = (\tau_1 \times \tau_2)^{\ell_1}
2581
2582
                           by inversion \vdash_N
2583
2584
                            (\mathsf{stat}\ b_0\ v_0)^{\ell_0} \blacktriangleright_{\overline{\mathsf{N}}} (\langle \mathsf{stat}\ (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)\ v_2, \mathsf{stat}\ (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1)\ v_3 \rangle)^{\ell_0}
                 7. Case v_1 \in i
                      7.1. QED
2588
                           (\text{stat } b_0 \ v_0)^{\ell_0} \blacktriangleright_{\overline{N}} (v_1)^{\ell_0}
2589
                                                                                                                                                                                                                                                                                                  2590
2591
                      \text{Lemma 5.32. } \textit{If} \cdot \vdash_{\mathsf{N}} \mathsf{dyn} \ b_0 \ v_0 : \tau_0 \ \textit{and} \ \cdot ; \ell_0 \ \overline{\vdash} \ \mathsf{dyn} \ b_0 \ v_0 \ \textit{and} \ (\mathsf{dyn} \ b_0 \ v_0)^{\ell_0} \ \rhd_{\overline{\mathsf{N}}} \ (e_1)^{\ell_0} \ \textit{then} \ \cdot ; \ell_0 \ \overline{\vdash} \ e_1.
2592
2593
                       PROOF. By case analysis of \triangleright_{\overline{N}}.
2594
2595
                 1. b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)
2596
                       and \cdot; \ell_1 \Vdash v_0
2597
                      by inversion  □
2598
                 2. v_0 = ((v_1))^{\ell_1}
2599
```

2019-10-03 17:26. Page 51 of 1-148.

```
by inversion \overline{\Vdash}
2601
2602
                 3. CASE v_1 \in (\lambda x. e) \cup (\text{mon } b \ v)
2603
                                     and (\operatorname{\mathsf{dyn}} b_0 \ v_0)^{\ell_0} \rhd_{\overline{\mathsf{N}}} (\operatorname{\mathsf{mon}} b_0 \ v_0)^{\ell_0}
2604
                       3.1. QED
2605
2606
                                                                                                                                           by inversion \overline{\mathbb{F}}
2607
2608
                                                                                                                                                 \cdot; \ell_1 \Vdash v_0
2609
                                                                                                                                         \overline{\cdot; \ell_0 \Vdash \mathsf{mon}\ b_0\ v_0}
2610
2611
                 4. CASE v_1 = \langle v_2, v_3 \rangle
2612
                                     and b_0 = (\ell_0 \blacktriangleleft (\tau_2 \times \tau_3)^{\ell_1} \blacktriangleleft \ell_1)
2613
                                     and (\mathsf{dyn}\ b_0\ ((\langle v_0, v_1 \rangle))^{\ell_0})^{\ell_0} \rhd_{\overline{\mathsf{N}}} ((\mathsf{dyn}\ b_3\ ((v_2)))^{\ell_1}, \mathsf{dyn}\ b_4\ ((v_3))^{\ell_1}))^{\ell_0}
2614
                       4.1. b_3 = (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1)
2615
2616
                                 and b_4 = (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1)
2617
                            by definition \triangleright_{\overline{N}}
2618
                       4.2. QED
2619
2620
2621
                                                                                                         by inversion \overline{\Vdash}
                                                                                                                                                                         by inversion  □
                                                                                                   \frac{\vdots}{\cdot;\ell_1 \ \mathbb{F} ((v_2))^{\ell_1}} \qquad \frac{\vdots}{\cdot;\ell_1 \ \mathbb{F} ((v_3))^{\ell_1}} \\ \frac{\vdots}{\cdot;\ell_0 \ \mathbb{F} \ \mathsf{dyn} \ b_3 \ ((v_2))^{\ell_1}} \qquad \frac{\vdots}{\cdot;\ell_0 \ \mathbb{F} \ \mathsf{dyn} \ b_4 \ ((v_3))^{\ell_1}}
2622
                                                                                                               \cdot; \ell_0 \Vdash \langle \operatorname{dyn} b_3 ((v_2))^{\ell_1}, \operatorname{dyn} b_4 ((v_3))^{\ell_1} \rangle
2626
                 5. Case v_1 \in i
2627
                                     and (\operatorname{dyn} b_0 \ v_0)^{\ell_0} \rhd_{\overline{\mathbb{N}}} (v_1)^{\ell_0}
2628
2629
2630
                6. Case (\mathsf{dyn}\,b_0\,v_0)^{\ell_0} \rhd_{\overline{\mathbf{N}}} (\mathsf{BndryErr}\,(b_0,v_0))^{\ell_0}
2632
                      6.1. QED
2633
                                                                                                                                                                                                                                                                                                        2634
2635
2636
                       Lemma 5.33 (N-stat preservation). If \cdot \vdash_{\mathsf{N}} stat b_0 \ v_0 : \mathcal{U} \ and \ : \ell_0 \ \overline{\vdash} \ \text{stat} \ b_0 \ v_0 \ and \ (\text{stat} \ b_0 \ v_0)^{\ell_0} \blacktriangleright_{\overline{\mathsf{N}}} (e_1)^{\ell_0} \ then
2637
2638
                 \cdot; \ell_0 \overline{\Vdash} e_1.
2639
2640
2641
                       PROOF. By case analysis of \triangleright_{\overline{N}}.
2642
                 1. b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)
2643
2644
                       and \cdot; \ell_1 \Vdash v_0
2645
                       and v_0 = ((v_1))^{\ell_1}
2646
                      by inversion \overline{\Vdash}
2647
                 2. Case v_1 \in (\lambda(x : \tau). e) \cup (\text{mon } b \ v)
2648
                                     and (stat b_0 v_0)^{\ell_0} \blacktriangleright_{\overline{N}} (\text{mon } b_0 v_0)^{\ell_0}
2649
2650
                       2.1. QED
2651
```

```
by inversion \overline{\mathbb{F}}
2654
2655
                                                                                                           \cdot; \ell_1 \Vdash v_0
2656
                                                                                                     \overline{\cdot;\ell_0 \Vdash \text{mon } b_0 \ v_0}
2657
2658
            3. CASE v_1 = \langle v_2, v_3 \rangle
2659
                           and \tau_0 = (\tau_2 \times \tau_3)^{\ell_1}
2660
                           \text{ and } (\mathsf{stat}\ b_0\ v_0)^{\ell_0} \blacktriangleright_{\overline{\mathsf{N}}} (\langle \mathsf{stat}\ (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1)\ v_2, \mathsf{stat}\ (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1)\ v_3 \rangle)^{\ell_0}
2661
                3.1. QED
                                                                          by inversion \overline{\Vdash}
                                                                                                                                   by inversion \overline{\Vdash}
2665
                                                               2666
2667
2668
                                                                          \cdot; \ell_0 \Vdash \langle \operatorname{stat} (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_2, \operatorname{stat} (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rangle
2669
2670
            4. Case v_1 \in i
2671
                           and (stat b_0 \ v_0)^{\ell_0} \blacktriangleright_{\overline{N}} (v_1)^{\ell_0}
2672
                 qedstep
2673
2674
2675
                 LEMMA 5.34. If (x_0:\tau?_0), \Gamma_0 \vdash_N e_1:\tau? and (x_0:\ell_0), L_0; \ell_1 \Vdash e_1 and \cdot \vdash_N v_0:\tau?_0 and \cdot; \ell_0 \Vdash v_0 then \Gamma_0 \vdash_N e_1[x_0 \leftarrow e_1]
2677
            v_0]: \tau? and L_0 \Vdash e_1[x_0 \leftarrow v_0].
2678
2679
                 PROOF. By induction on the structure of e_0.
2680
            1. e_0 = x_2
2681
                 1.1. SCASE x_0 = x_2
2682
                     1.1.1. QED
2683
2684
                 1.2. SCASE x_0 \neq x_2
2685
                     1.2.1. QED
2686
                         e_1[x_0 \leftarrow v_0] = e_1
2687
            2. Case e_0 \in i
                2.1. QED
                     e_1[x_0 \leftarrow v_0] = e_1
2691
            3. CASE e_0 = \lambda x_2 . e_2
2692
                           ore_0 = \lambda(x_2 : \tau_2). e_2
2693
2694
                3.1. SCASE x_0 = x_2
2695
                    3.1.1. QED
2696
                         e_1[x_0 \leftarrow v_0] = e_1
2697
                 3.2. SCASE x_0 \neq x_2
2698
2699
                     3.2.1. QED
2700
                         by the induction hypothesis
2701
            4. Case e_0 = \langle e_1, e_2 \rangle
2702
                 4.1. QED
```

```
by the induction hypothesis
2706
        5. CASE e_0 = app\{\tau?\} e_1 e_2
2707
           5.1. QED
2708
              by the induction hypothesis
2709
2710
        6. CASE e_0 = unop\{\tau?\} e_1
2711
           6.1. QED
2712
              by the induction hypothesis
2713
        7. CASE e_0 = binop\{\tau?\} e_1 e_2
2714
           7.1. QED
2715
2716
              by the induction hypothesis
2717
        8. CASE e_0 = \text{dyn } b_1 e_1
2718
           8.1. QED
2719
2720
              by the induction hypothesis
2721
        9. CASE e_0 = \operatorname{stat} b_1 e_1
2722
           9.1. QED
2723
              by the induction hypothesis
2724
        10. CASE e_0 = (e_1)^{\ell_1}
2725
2726
           10.1. \ell_0 = \ell_1
              by inversion \overline{\Vdash}
           10.2. QED
2729
2730
              by the induction hypothesis
2731
2732
```

Lemma 5.35 (boundary preservation). If $e_0:\tau$? wf and $e_0 \to_N^* E_0[\mathsf{dyn}\ b_0\ v_1]$ then either has-boundary (e_0,b_0) or has-boundary $(e_0, flip(b_0))$.

PROOF. By case analysis of \triangleright_N and \triangleright_N , evaluation does not create new labels and only creates a new boundary by flipping an existing boundary.

LEMMA 5.36. If $e_0: \tau$? wf and $e_0 \to_N^* E[\text{mon}(\ell_0 \blacktriangleleft (\tau_0 \Rightarrow \tau_1)^{\ell_1} \blacktriangleleft \ell_2) \upsilon_0]$ then $tag\text{-match}(\lfloor \tau_0 \Rightarrow \tau_1 \rfloor, \upsilon_0)$

Proof. Surface expressions do not contain monitors, and the only ways to create one via \blacktriangleright_N and \triangleright_N require tag-match as a precondition.

2759

2760 2761

2762

2776 2777

2778

2781

2783 2784

2785

2786

2787 2788

2789

2800

2801 2802

2803 2804

2805

2807

6 Transient THEOREMS, LEMMAS, AND PROOFS

6.1 Transient Theorems

THEOREM 6.1 (INCOMPLETE MONITORING). There exists $e_0:\tau$? $\overline{\mathbf{wf}}$ such that $e_0:\emptyset:\emptyset\longrightarrow_{\overline{\mathbb{T}}}^* e_1:\mathcal{H}_1:\mathcal{B}_1$ and for all O_1 such that $O_1 \Vdash_{\overline{\mathbb{T}}} \mathcal{H}_1$, we have $O_1:\cdot:\ell \not\Vdash_{\overline{\mathbb{T}}} e_1$.

2763
2764 PROOF. Let
2765 $e_f = \text{stat} (\ell_0 \blacktriangleleft (\text{Int} \Rightarrow \text{Int}) \blacktriangleleft \ell_1) (\text{dyn} (\ell_1 \blacktriangleleft (\text{Int} \Rightarrow \text{Int}) \blacktriangleleft \ell_2) (\lambda x_0. (\text{sum}\{x_0\} \, 1))^{\ell_2})^{\ell_1}$ 2766 $e_0 = (\text{app}\{\mathcal{U}\} e_0 (\lambda x_0. (\text{sum}\{x_0\} \, 1)))^{\ell_0}$ 2767 $v_f = (\text{pp}_0)^{\ell_2 \ell_1 \ell_0}$ 2768 $e_1 = (\text{app}\{\mathcal{U}\} v_f (\lambda x_1. \, 0))^{\ell_0}$ By the reduction rules:

$$e_0; \emptyset; \emptyset \longrightarrow_{\overline{1}}^* e_1; \mathcal{H}_0; \mathcal{B}_0$$
2773 where $\mathcal{H}_0 = \{ p_0 \mapsto \lambda x_0. (\text{sum}\{x_0\} 1) \}$
2774 and $\mathcal{B}_0 = \{ p_0 \mapsto \{(\ell_0 \blacktriangleleft (\text{Int} \Rightarrow \text{Int}) \blacktriangleleft \ell_1), (\ell_1 \blacktriangleleft (\text{Int} \Rightarrow \text{Int}) \blacktriangleleft \ell_2) \} \}$
2775 In the result $\overline{\mathbb{L}}$ foils because p_0 has multiple sources.

In the result, \vdash_{T} fails because v_f has multiple owners.

Theorem 6.2 (unsound blame). There exists $e_0: \tau$? $\overline{\mathbf{wf}}$ such that $e_0; \emptyset; \emptyset \longrightarrow_{\overline{1}}^* \text{BndryErr}((\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1), v_1); \mathcal{H}_1; \mathcal{B}_1$ and senders $(\overline{b}_1) \nsubseteq owners(v_1)$.

PROOF. Consider the following example e_0 where the let-expressions are sugar for untyped function applications:

$$e_0 = (\operatorname{let} f_0 = (\lambda x_0. \langle x_0, x_0 \rangle) \operatorname{in}$$

$$\operatorname{let} f_1 = (\operatorname{stat} (\ell_0 \blacktriangleleft (\operatorname{Int} \Rightarrow \operatorname{Int}) \blacktriangleleft \ell_1) (\operatorname{dyn} (\ell_1 \blacktriangleleft (\operatorname{Int} \Rightarrow \operatorname{Int}) \blacktriangleleft \ell_0) (f_0)^{\ell_0})^{\ell_1}) \operatorname{in}$$

$$\operatorname{stat} (\ell_0 \blacktriangleleft \operatorname{Int} \blacktriangleleft \ell_2) (\operatorname{app} \{\operatorname{Int}\} (\operatorname{dyn} (\ell_2 \blacktriangleleft (\operatorname{Int} \Rightarrow \operatorname{Int}) \blacktriangleleft \ell_0) (f_0)^{\ell_0}) 5)^{\ell_2})^{\ell_0}$$

By the reduction rules:

 e_0 ; \emptyset ; \emptyset $\longrightarrow_{\overline{1}}^* (\operatorname{stat} (\ell_0 \blacktriangleleft \operatorname{Int} \blacktriangleleft \ell_2) (\operatorname{app} \{\operatorname{Int}\} ((p_0))^{\ell_0 \ell_2} 5)^{\ell_2})^{\ell_0}$; \mathcal{H}_0 ; \mathcal{B}_0 $\longrightarrow_{\overline{1}}^* (\operatorname{stat} (\ell_0 \blacktriangleleft \operatorname{Int} \blacktriangleleft \ell_2) (\operatorname{check Int} ((p_1))^{\ell_0 \ell_2} p_0)^{\ell_2})^{\ell_0}$; \mathcal{H}_1 ; \mathcal{B}_1 $\longrightarrow_{\overline{1}}^* \operatorname{BndryErr} (\mathcal{B}_0(p_1) \cup \mathcal{B}_0(p_0), ((p_1))^{\ell_0 \ell_2})$; \mathcal{H}_1 ; \mathcal{B}_0 2796 where $\mathcal{H}_1 = \{p_0 \mapsto \lambda x_0, \langle x_0, x_0 \rangle, p_1 \mapsto \langle 5, 5 \rangle \}$ 2797 and $\mathcal{B}_1 = \{p_0 \mapsto (\ell_1 \blacktriangleleft (\operatorname{Int} \Rightarrow \operatorname{Int}) \blacktriangleleft \ell_0), (\ell_0 \blacktriangleleft (\operatorname{Int} \Rightarrow \operatorname{Int}) \blacktriangleleft \ell_1), (\ell_2 \blacktriangleleft (\operatorname{Int} \Rightarrow \operatorname{Int}) \blacktriangleleft \ell_0), p_1 \mapsto \emptyset \}$

Thus $senders(\mathcal{B}_0(p_1) \cup \mathcal{B}_0(p_0)) = \{\ell_0, \ell_1\} \nsubseteq \{\ell_0, \ell_2\} = owners(((p_1))^{\ell_0 \ell_2}).$

Theorem 6.3 (Incomplete blame). There exists $e_0:\tau?$ $\overline{\mathbf{wf}}$ such that $e_0;\emptyset;\emptyset\longrightarrow_{\overline{1}}^*$ BndryErr $((\ell_0\blacktriangleleft\tau_1\blacktriangleleft\ell_1),\upsilon_1);\mathcal{H}_1;\mathcal{B}_1$ and senders $(\overline{b}_1)\not\supseteq owners(\upsilon_1)$.

Proof. Consider the following example e_0 where the let-expressions are sugar for untyped function applications:

2019-10-03 17:26. Page 54 of 1-148.

```
(let f_0 = \operatorname{stat} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (\operatorname{dyn} (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) (\lambda x_0, x_0)) in
2809
2810
                               let f_1 = \operatorname{stat} (\ell_0 \blacktriangleleft (\tau_0 \Rightarrow \tau_1) \blacktriangleleft \ell_3) (\operatorname{dyn} (\ell_3 \blacktriangleleft (\tau_0 \Rightarrow \tau_1) \blacktriangleleft \ell_4) (\lambda x_1, x_1)) in
2811
                               \operatorname{stat}(\ell_0 \triangleleft (\operatorname{Int} \times \operatorname{Int}) \triangleleft \ell_5)
2812
2813
                                             (\mathsf{app}\{\mathsf{Int}\times\mathsf{Int}\}(\mathsf{dyn}(\ell_5\blacktriangleleft\tau_1\blacktriangleleft\ell_0)(\mathsf{app}\{\mathcal{U}\}\ f_1\ f_0)^{\ell_0})\ 42)^{\ell_5})^{\ell_0};\emptyset:\emptyset
2814
                            \longrightarrow_{\mp}^{*} (\operatorname{stat} (\ell_0 \blacktriangleleft (\operatorname{Int} \times \operatorname{Int}) \blacktriangleleft \ell_5)
2815
                                                             (\mathsf{app}\{\mathsf{Int}\times\mathsf{Int}\}\,(\mathsf{dyn}\,(\ell_5\blacktriangleleft\tau_1\blacktriangleleft\ell_0)\,(\mathsf{app}\{\mathcal{U}\}\,(\!(\mathsf{p}_1)\!)^{\ell_4\ell_3\ell_0}\,(\!(\mathsf{p}_0)\!)^{\ell_2\ell_1\ell_0}\!)^{\ell_0})\,42)^{\ell_5}\overset{\ell_0}{,};\mathcal{H}_0;\mathcal{B}_0
2816
2817
                            \longrightarrow_{\underline{\phantom{}}}^* (\operatorname{stat} (\ell_0 \blacktriangleleft (\operatorname{Int} \times \operatorname{Int}) \blacktriangleleft \ell_5) (\operatorname{app} \{\operatorname{Int} \times \operatorname{Int}\} ((p_0))^{\overline{\ell_0}} 42)^{\ell_5})^{\ell_0}; \mathcal{H}_1; \mathcal{B}_1
2818
                             \longrightarrow_{\overline{\mathbf{1}}}^{*} (\operatorname{stat} (\ell_{0} \blacktriangleleft (\operatorname{Int} \times \operatorname{Int}) \blacktriangleleft \ell_{5}) (\operatorname{check} (\operatorname{Int} \times \operatorname{Int}) ((42))^{\overline{\ell_{1}}} p_{0})^{\ell_{5}})^{\ell_{0}} : \mathcal{H}_{2}; \mathcal{B}_{2}
2821
                             \longrightarrow_{=}^{*} \operatorname{BndryErr}(\mathcal{B}_{2}(p_{0}), ((42))^{\overline{\ell}_{1}}); \mathcal{H}_{2}; \mathcal{B}_{2}
2822
2823
                                    where \tau_0 = (Int \Rightarrow Int)
2824
                                    and \tau_1 = (Int \Rightarrow Int \times Int)
2825
2826
                                    and \bar{\ell}_0 = \ell_2 \ell_1 \ell_0 \ell_3 \ell_4 \ell_3 \ell_0 \ell_5
                                    and \bar{\ell}_1 = \ell_5 \bar{\ell}_0 (rev(\bar{\ell}_0))
2828
2829
                                    and \mathcal{H}_2 = \{ (p_0 \mapsto \lambda x_0, x_0), (p_1 \mapsto \lambda x_1, x_1) \}
2830
                                    and \mathcal{B}_2 = \{ (p_0 \mapsto \{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1), (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2), (\ell_5 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \}),
2831
                                                                          (p_1 \mapsto \{(\ell_0 \triangleleft (\tau_0 \Rightarrow \tau_1) \triangleleft \ell_3), (\ell_3 \triangleleft (\tau_0 \Rightarrow \tau_1) \triangleleft \ell_4)\})\}
2832
```

Hence, senders $(\mathcal{B}_2(p_0)) = \{\ell_0, \ell_1, \ell_2\} \not\supseteq \{\ell_0, \ell_1, \ell_2, \ell_3, \ell_4, \ell_5\} = owners ((42))^{\overline{\ell_1}}$. The crucial labels ℓ_3 and ℓ_4 are nowhere to be found.

Theorem 6.4 (all-path sound blame). If $e_0:\tau$? $\overline{\mathbf{wf}}$:

```
\bullet \ e_0 \longrightarrow_{\overline{\tau}}^* E_0[\mathsf{dyn}\,(\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2)\, v_1]; \mathcal{H}_0; \mathcal{B}_0; \mathcal{O}_0 \, \bowtie_{\overline{\tau}} \, \mathsf{BndryErr}\,((\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2), v_1); \mathcal{H}_1; \mathcal{B}_1; \mathcal{O}_1 \,\, \mathit{then} \,\, \mathsf{deg}_1) + \mathsf{deg}_2 + \mathsf{deg}_3 + \mathsf{deg}_4 + \mathsf{deg}_4 + \mathsf{deg}_5 + \mathsf{deg}_5 + \mathsf{deg}_6 + \mathsf{deg}_
          (1) has-boundary (e_0, (\ell_1 \triangleleft \tau_1 \triangleleft \ell_2))
          (2) v_1 = ((v))^{\ell_n \dots \ell_2}
  • e_0 \longrightarrow_{\overline{\mathbf{T}}}^* E_0[\mathsf{app}\{\tau?\}\ v_0\ v_1]; \mathcal{H}_0; \mathcal{B}_0; O_0 \Vdash_{\overline{\mathbf{T}}} \mathsf{BndryErr}(\overline{b}_1, v_1); \mathcal{H}_1; \mathcal{B}_1; O_1\ \mathit{then}
          (1) \forall b_1 \in \overline{b_1}, either has-boundary (e_0, b_1) or has-boundary (e_0, flip(b_1))
```

- (2) $v_1 = ((p_1))^{\overline{\ell}_0}, \exists \overline{\ell}_1 . \overline{\ell}_1 \simeq \overline{b}_1 \text{ and } \overline{\ell}_0 \cup O_1(p_1) \subseteq \overline{\ell}_1.$
- $\bullet \ e_0 \longrightarrow_{\overline{\tau}}^* E_0[\mathsf{check}(\tau_0, v_0, \mathsf{p}_1)]; \mathcal{H}_0; \mathcal{B}_0; O_0 \, \bowtie_{\overline{\tau}} \mathsf{BndryErr}(\overline{b}_1, v_0); \mathcal{H}_0; \mathcal{B}_0; O_0 \ then$
- (1) $\forall b_1 \in \overline{b_1}$, either has-boundary (e_0, b_1) or has-boundary $(e_0, flip(b_1))$
- (2) $v_0 = ((v_1))^{\overline{\ell_0}}, \exists \overline{\ell_1} \cdot \overline{\ell_1} \simeq \overline{b_1}, \text{ and } \overline{\ell_0} \cup O_1(v_1) \cup O_1(p_1) \subseteq \text{ senders } (\overline{b_1}).$

PROOF SKETCH. The proof relies on a straight-forward subject reduction argument showing that the evaluation trace of any well-formed term e_0 satisfies two invariants:

- for all dyn $(\ell_1 \triangleleft \tau_1 \triangleleft \ell_2)$ v_1 that occur in all configurations $e; \mathcal{H}; \mathcal{B}; O$ in the trace, has-boundary $(e_0, (\ell_1 \triangleleft \tau_1 \triangleleft \ell_2))$ and $v_1 = ((v))^{\ell_1 \dots \ell_2}$;
- for all configurations $e; \mathcal{H}; \mathcal{B}; O$ in the trace, (i) if $e \neq \mathsf{BndryErr}(\overline{b}, v)$ then for all p in the domain of $O, O(p) \subseteq \ell^*$ where $\ell^* \simeq \mathcal{B}(p_0)$ and (ii) $\forall b_1 \in \mathcal{B}(p_0)$, either has-boundary (e_0, b_1) or has-boundary $(e_0, flip(b_1))$.

2019-10-03 17:26. Page 55 of 1-148.

2834

2835 2836

2837 2838

2839 2840

2841

2842

2843

2844

2846

2848

2849 2850

2851 2852

2853

2854 2855

2856

2857

2858

2860

```
We employ the first invariant to establish the first case of the theorem and the second for the others.
2861
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                2862
                                            Theorem 6.5 (all-path incomplete blame). There exists e_0 such that \cdot; \ell_{\bullet} \Vdash e_0,
2863
2864
                                                     • e_0 \longrightarrow_{\overline{\tau}}^* E_0[\operatorname{check}(\tau_0, v_0, \mathsf{p}_1)]; \mathcal{H}_0; \mathcal{B}_0; O_0 \bowtie_{\overline{\tau}} \operatorname{BndryErr}(\overline{b}_1, v_0); \mathcal{H}_0; \mathcal{B}_0; O_0 \operatorname{and} \mathcal{B}_0; O_0 \bowtie_{\overline{\tau}} \mathcal
2865
                                                        (1) \forall b_1 \in \overline{b_1}, either has-boundary (e_0, b_1) or has-boundary (e_0, flip(b_1))
2866
                                                        (2) v_0 = ((v_1))^{\ell^*}, v \neq p, \ell_1...\ell_n \simeq \overline{b_1} \text{ and } \ell_1...\ell_n \not\supseteq O_1(p_1) \cup \ell^*.
2867
2868
                                           PROOF. Consider the following example e<sub>0</sub> where the let-expressions are sugar for untyped function applications:
                                       e_0 = (\text{let } f_0 = \text{stat} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (\text{dyn} (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) (\lambda x_0. x_0)) \text{ in}
                                                                                  let f_1 = \operatorname{stat} (\ell_0 \blacktriangleleft (\tau_0 \Rightarrow \tau_1) \blacktriangleleft \ell_3) (\operatorname{dyn} (\ell_3 \blacktriangleleft (\tau_0 \Rightarrow \tau_1) \blacktriangleleft \ell_4) (\lambda x_1, x_1)) in
                                                                                  \operatorname{stat}(\ell_0 \triangleleft (\operatorname{Int} \times \operatorname{Int}) \triangleleft \ell_5)
                                                                               (\mathsf{app}\{\mathsf{Int}\times\mathsf{Int}\}\,(\mathsf{dyn}\,(\ell_{5}\blacktriangleleft\tau_{1}\blacktriangleleft\ell_{0})\,(\mathsf{app}\{\mathcal{U}\}\,f_{1}\,f_{0})^{\ell_{0}})\,42)^{\ell_{5}})^{\ell_{0}}
2874
2875
                                 With a straight-forward application of the reduction rules we obtain:
2876
                                       e_0: \emptyset: \emptyset: \emptyset
2877
                                       \rightarrow_{\mathsf{T}}^* \operatorname{stat} (\ell_0 \blacktriangleleft (\operatorname{Int} \times \operatorname{Int}) \blacktriangleleft \ell_5)
                                                                                   (\mathsf{app}\{\mathsf{Int}\times\mathsf{Int}\}\,(\mathsf{dyn}\,(\ell_{5}\blacktriangleleft\tau_{1}\blacktriangleleft\ell_{0})\,(\mathsf{app}\{\mathcal{U}\}\,(\!(p_{1})\!)^{\ell_{4}\ell_{3}\ell_{0}}\,(\!(p_{0})\!)^{\ell_{2}\ell_{1}\ell_{0}})^{\ell_{0}})\,42)^{\ell_{5}})^{\ell_{0}};\mathcal{H}_{0};\mathcal{B}_{0};\mathcal{O}_{0})
2880
                                      \rightarrow_{\mathbf{T}}^{*} (\operatorname{stat} (\ell_{0} \blacktriangleleft \operatorname{Int} \times \operatorname{Int} \blacktriangleleft \ell_{5}) (\operatorname{app} {\operatorname{Int} \times \operatorname{Int}} \} ((p_{0}))^{\overline{\ell_{0}}} 42)^{\ell_{5}})^{\ell_{0}}; \mathcal{H}_{1}; \mathcal{B}_{1}; \mathcal{O}_{1}
2881
2882
                                      \rightarrow_{\mathsf{T}}^* \left(\mathsf{stat}\left(\ell_0 \blacktriangleleft \mathsf{Int} \times \mathsf{Int} \blacktriangleleft \ell_5\right) \left(\mathsf{check} \, \mathsf{Int} \times \mathsf{Int} \, (\!(42)\!)^{\overline{\ell_1}} \, \mathsf{p_0}\right)^{\ell_5}\right)^{\ell_6}; \mathcal{H}_2; \mathcal{B}_2; \mathcal{O}_2
2883
                                       \triangleright_{\mathbf{T}} BndryErr (\mathcal{B}_2(\mathsf{p}_0), ((42))^{\overline{\ell}_1}); \mathcal{H}_2; \mathcal{B}_2; \mathcal{O}_2
                                       where \tau_0 = (Int \Rightarrow Int) and \tau_1 = (Int \Rightarrow Int \times Int)
                                       and \bar{\ell}_0 = \ell_2 \ell_1 \ell_0 \ell_3 \ell_4 \ell_3 \ell_0 \ell_5 and \bar{\ell}_1 = \ell_5 \bar{\ell}_0 (rev(\bar{\ell}_0))
2887
                                       and \mathcal{H}_2 = \{ (p_0 \mapsto \lambda x_0, x_0), (p_1 \mapsto \lambda x_1, x_1) \}
2888
                                       and \mathcal{B}_2 = \{ (p_0 \mapsto \{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1), (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2), (\ell_5 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \}),
2889
2890
                                                                                         (p_1 \mapsto \{(\ell_0 \blacktriangleleft (\tau_0 \Rightarrow \tau_1) \blacktriangleleft \ell_3), (\ell_3 \blacktriangleleft (\tau_0 \Rightarrow \tau_1) \blacktriangleleft \ell_4)\})\}
                                 Thus \{\ell_0, \ell_1, \ell_2, \ell_5\} \simeq \mathcal{B}_2(p_0) and \{\ell_0, \ell_1, \ell_2, \ell_5\} \not\supseteq O_2(p_0) \cup \{\ell_0, \ell_1, \ell_2, \ell_3, \ell_4, \ell_5\} independently of the details of O_2.
2892
2893
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                2894
2895
                                             Theorem 6.6 (type soundness). If e_0:\tau? wf then one of the following holds:
                                                     • e_0; \emptyset; \emptyset \to_T^* v_0; \mathcal{H}_0; \mathcal{B}_0 \text{ and } \exists \mathcal{T}_0 : \mathcal{T}_0; \cdot \vdash_T v_0 : \lfloor \tau? \rfloor
                                                     • e_0; \emptyset; \emptyset diverges
                                                     • e_0; \emptyset; \emptyset \to_T^* E_0[\mathsf{dyn}\ b_1\ E[e_1]]; \mathcal{H}_0; \mathcal{B}_0\ and\ e_1; \mathcal{H}_0; \mathcal{B}_0\ \triangleright_T \mathsf{TagErr} •; \mathcal{H}_1; \mathcal{B}_1
2900
                                                     • e_0; \emptyset; \emptyset \to_{\mathsf{T}}^* \mathsf{DivErr}; \mathcal{H}_0; \mathcal{B}_0
2901
                                                     • e_0; \emptyset; \emptyset \rightarrow_{\mathsf{T}}^* \mathsf{BndryErr}(\overline{b}_1, v_1); \mathcal{H}_0; \mathcal{B}_0
2902
2903
                                            Proof Sketch. By progress and preservation lemmas; preservation constructs a heap typing (\mathcal{T}) at each step. \Box
2905
```

7 Amnesic THEOREMS, LEMMAS, AND PROOFS

7.1 Amnesic Theorems

 Theorem 7.1. If $e_0:\tau$? $\overline{\mathbf{wf}}$ then $forget(e_0):\tau$? \mathbf{wf} and $e_0\longrightarrow_{\overline{\Delta}} e_1$ iff $forget(e_0)\to_{\overline{A}} forget(e_1)$

PROOF. By the definition of $\longrightarrow_{\overline{\Lambda}}$

Theorem 7.2 (type soundness). If $e_0:\tau_0$ wf then one of the following holds:

- $e_0 \rightarrow_A^* v_0 \ and \cdot \vdash_A v_0 : \tau_0$
- e₀ diverges
- $e_0 \rightarrow_A^* E_0[\mathsf{dyn}\ b_1\ E[e_1]]\ and\ e_1 \blacktriangleright_A \mathsf{TagErr} \bullet$
- $e_0 \rightarrow_A^* \text{DivErr}$ $e_0 \rightarrow_A^* \text{BndryErr}(\overline{b}_1, v_1)$

PROOF. By progress and preservation lemmas (lemma 7.11 and lemma 7.12).

Theorem 7.3 (Dynamic soundness). If $e_0: \mathcal{U}$ wf then one of the following holds:

- $e_0 \rightarrow_A^* v_0 \ and \cdot \vdash_A v_0 : \mathcal{U}$
- e₀ diverges
- $e_0 \rightarrow_A^* E_0[e_1]$ and $e_1 \blacktriangleright_A \mathsf{TagErr} \bullet$
- $e_0 \xrightarrow{A}^* \text{DivErr}$ $e_0 \xrightarrow{A}^* \text{BndryErr}(\overline{b}_1, v_1)$

PROOF. By progress and preservation lemmas (lemma 7.11 & lemma 7.12).

Proof. Let

$$e_f = \operatorname{stat} (\ell_0 \blacktriangleleft (\operatorname{Int} \Rightarrow \operatorname{Int}) \blacktriangleleft \ell_1) (\operatorname{dyn} (\ell_1 \blacktriangleleft (\operatorname{Int} \Rightarrow \operatorname{Int}) \blacktriangleleft \ell_2) (\lambda x_0. (\operatorname{sum} {\operatorname{Int}}) x_0 1))^{\ell_2})^{\ell_1}$$

$$e_0 = (\operatorname{app}\{\mathcal{U}\} e_0 (\lambda x_0. (\operatorname{sum}\{\operatorname{Int}\} x_0 1)))^{\ell_0}$$

$$v_f = (\operatorname{trace}_{\mathbf{v}} \{ (\ell_0 \blacktriangleleft (\operatorname{Int} \Rightarrow \operatorname{Int}) \blacktriangleleft \ell_1), (\ell_1 \blacktriangleleft (\operatorname{Int} \Rightarrow \operatorname{Int}) \blacktriangleleft \ell_2) \} ((\lambda x_0. (\operatorname{sum} \{\operatorname{Int}\} x_0 1)))^{\ell_2 \ell_1})^{\ell_0}$$

$$e_1 = (\operatorname{app}\{\mathcal{U}\} v_0 (\lambda x_1.0))^{\ell_0}$$

With a straight-forward application of the reduction rules we obtain:

$$(e_f)^{\ell_0} \longrightarrow_{\overline{A}}^* (\operatorname{stat} (\ell_0 \blacktriangleleft (\operatorname{Int} \Rightarrow \operatorname{Int}) \blacktriangleleft \ell_1) (\operatorname{mon} (\ell_1 \blacktriangleleft (\operatorname{Int} \Rightarrow \operatorname{Int}) \blacktriangleleft \ell_2) (\lambda x_0. (\operatorname{sum} \{\operatorname{Int}\} x_0 1))^{\ell_2})^{\ell_1})^{\ell_0}$$

$$\longrightarrow_{\overline{A}}^* (\operatorname{trace}_{\mathbf{v}} \{ (\ell_0 \blacktriangleleft (\operatorname{Int} \Rightarrow \operatorname{Int}) \blacktriangleleft \ell_1), (\ell_1 \blacktriangleleft (\operatorname{Int} \Rightarrow \operatorname{Int}) \blacktriangleleft \ell_2) \} ((\lambda x_0. (\operatorname{sum} \{\operatorname{Int}\} x_0 1)))^{\ell_2 \ell_1})^{\ell_0}$$

$$= v_f$$

$$e_0 \longrightarrow_{\overline{A}}^* e_1$$

Theorem 7.5 (sound and complete blame). If $\cdot; \ell_{\bullet} \Vdash e_0$ and $e_0 \longrightarrow_{\overline{\Delta}}^* \mathsf{BndryErr} ((\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1), \upsilon_1)$ then 2019-10-03 17:26. Page 57 of 1-148.

```
• either has-boundary ((\ell_0 \triangleleft \tau_1 \triangleleft \ell_1), e_0) or has-boundary ((\ell_1 \triangleleft \tau_1 \triangleleft \ell_0), e_0), and
2966
                          • senders(\overline{b}_1) = owners(v_1)
2967
                      Theorem 7.6 (blame correctness). If (e_0)^{\ell_0}: \tau? \overline{\mathbf{wf}} then one of the following holds:
                         • e_0 \longrightarrow_{\overline{A}}^* v_0 \text{ and } \cdot; \ell_0 \ \overline{\Vdash}_A \ v_0
• e_0 \text{ diverges}
                         • e_0 \longrightarrow_{\overline{A}}^* \operatorname{TagErr} \bullet

• e_0 \longrightarrow_{\overline{A}}^* \operatorname{DivErr}

• e_0 \longrightarrow_{\overline{A}}^* E_0[\operatorname{dyn}(\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2) \ \upsilon_1] \longrightarrow_{\overline{A}} \operatorname{BndryErr}(\overline{b}_1, \upsilon_1) \ and \ furthermore:
                           (1) \forall b_1 \in \overline{b_1}, either has-boundary (e_0, b_1) or has-boundary (e_0, flip(b_1))
                           (2) one of the following holds:
                                 (a) v_1 \notin (\text{trace}_{\mathbf{v}} \overline{b}(v))^{\overline{\ell}}) \text{ and } \cdot; \ell_2 \overline{\Vdash}_{\mathsf{A}} v_1
2979
                                (b) v_1 = (\operatorname{trace}_{v} \overline{b}_2 ((v_2))^{\overline{\ell}_2 \ell_2}) and \overline{b}_2 \simeq \ell_2 \overline{\ell}_2 \ell_2 and : \operatorname{last}(\ell_3) \overline{\Vdash}_{A} v_2
                      Proof.
               1. Suffices assume e_0 \longrightarrow_{\overline{A}}^* E_0[\mathsf{dyn}\,(\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2)\,v_1] \longrightarrow_{\overline{A}} \mathsf{BndryErr}\,(\overline{b}_1,v_1)
\mathsf{PROVE}\,\,(1)\,\,\forall\,b_1 \in \overline{b}_1,\,\mathsf{either}\,\,\mathit{has-boundary}\,(e_0,b_1)\,\,\mathsf{or}\,\,\mathit{has-boundary}\,(e_0,flip\,(b_1))
2983
2984
2985
                                                             (2) one of the following holds:
                                                                 (a) v_1 \notin (\operatorname{trace}_{\mathbf{v}} \overline{b} ((v))^{\overline{\ell}}) \text{ and } \cdot; \ell_2 \overline{\Vdash}_{\mathsf{A}} v_1
                                                                 (b) v_1 = (\text{trace}_{\mathbf{v}} \overline{b_2} ((v_2))^{\overline{\ell_2} \ell_2}) and \overline{b_2} \simeq \ell_2 \overline{\ell_2} \ell_2 and \cdot; last(\ell_3) \Vdash_{\mathsf{A}} v_2
                     by lemma 7.26 and lemma 7.27
                2. (\ell_1 \blacktriangleleft \ell_2 \blacktriangleleft \overline{\Vdash}_A)\tau_1 and \ell_2 \overline{\Vdash}_A v_1
2991
                     by lemma 7.27
2992
                3. \forall b_1 \in \overline{b}_1 either b_1 \in e_0 or flip(b_1) \in e_0
2993
2994
                     by lemma 7.41
                4. either \overline{b}_1 = (\ell_1 \blacktriangleleft \ell_2 \blacktriangleleft)
                      or v_1 = (\text{trace}_{\mathbf{v}} \overline{b_0} v_0) and \overline{b_1} = (\ell_1 \blacktriangleleft \ell_2 \blacktriangleleft) \overline{b_0}
2997
                     by the definition of \longrightarrow_{\overline{\Lambda}}
                                                                                                                                                                                                                                                                                  Corollary 7.7 (minimal blame info). If e_0:\tau? wf and e_0 \to_A^* BndryErr (\overline{b}_1,v_1) then \overline{b}_1 \neq \cdot
3003
                      Proof. by Theorem 7.6
3004
3005
3006
                      COROLLARY 7.8 (BLAME/OWNERSHIP MATCH). If L_0; \ell_0 \Vdash_A e_0 then for all subterms (trace, \bar{b}_1 e_1) there exists \bar{\ell}_1 such
3007
                that e_1 = ((e_2))^{\overline{\ell}_1} and \overline{b}_1 \simeq \overline{\ell}_1
3008
3009
                      Proof. by definition of \overline{\mathbb{H}}_A
3010
3011
                                                                                                                                                                                                                                                                                  3012
                      Theorem 7.9. If e_0: \tau_0 wf and e_0 \rightarrow_A^* v_1 then mon-depth (v_1) \le 2
3013
                      Proof. 1. Suffices if dyn b_0 \ v_2 \rhd_{A} v_3 then mon\text{-}depth(v_3) \leq 2
                                                                                                                                                                                                                         2019-10-03 17:26. Page 58 of 1-148.
```

```
because the only way to increase the mon-depth of a value is by crossing a boundary
3017
3018
3019
                 by lemma 7.10 and the definition of \triangleright_{A}
3020
3021
3022
                  Theorem 7.10. If e_0: \mathcal{U} wf and e_0 \to_A^* v_1 then mon-depth (v_1) \le 1
3023
3024
                 Proof. 1. Suffices if stat b_0 v_2 \triangleright_A v_3 then mon\text{-}depth(v_3) \leq 1
                 because the only way to increase the mon-depth of a value is by crossing a boundary
3028
                 by definition of \triangleright_{\Lambda}
3029
3030
3031
3032
             7.2 Amnesic Lemmas
3033
                 Lemma 7.11 (\vdash_A progress). If \cdot \vdash_A e_0 : \tau? then one of the following holds:
3034
3035
                     • e_0 \in v
3036
                    • e_0 \in Err
3037
                    • \exists e_1 \text{ such that } e_0 \rightarrow_A e_1
3038
3039
                 PROOF. By case analysis of e_0.
             By lemma 7.15 it suffices to consider the following cases.
3041
             1. Case e_0 \in v
3042
3043
                 1.1. QED
3044
            2. CASE e_0 = E_0[Err]
3045
                 2.1. QED
3046
            3. CASE e_0 = E_0[app\{\tau_1\} v_0 v_1]
3048
                 3.1. v_0 \in (\lambda(x : \tau). e) \cup (\text{mon } b \ v)
3049
                     by lemma 7.16 and inversion ⊢A
3050
                 3.2. SCASE v_0 = \lambda(x_2 : \tau_2). e_2
3051
                     3.2.1. QED
                          e_0 \rhd_{\mathsf{A}} E_0[e_2[x_2 \leftarrow v_1]]
3054
                 3.3. SCASE v_0 = \text{mon} (\ell_0 \blacktriangleleft (\tau_1 \Rightarrow \tau_2) \blacktriangleleft \ell_1) v_2
3055
                     3.3.1. QED
3056
                          e_0 \rhd_{\mathsf{A}} E_0[\mathsf{dyn}\,(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)\,(\mathsf{app}\{\mathcal{U}\}\,v_2\,(\mathsf{stat}\,(\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0)\,v_1))]
3057
3058
             4. CASE e_0 = E_0[app\{\tau_1\} v_0 v_1]
3059
                 4.1. SCASE v_0 = \text{trace}_{v}^{?} \overline{b}_0 (\lambda(x_2 : \tau_2). e_2)
3060
                     4.1.1. QED
3061
                          e_0 \blacktriangleright_A E_0[\operatorname{trace} \overline{b}_0 (e_2[x_2 \leftarrow v_1])]
3062
3063
                 4.2. SCASE v_0 = \operatorname{trace}_{\mathbf{v}}^? \overline{b}_0 \left( \operatorname{mon} \left( \ell_0 \blacktriangleleft (\tau_1 \Rightarrow \tau_2) \blacktriangleleft \ell_1 \right) v_2 \right)
3064
                          e_0 \blacktriangleright_A E_0[\operatorname{trace} \bar{b}_0 \left(\operatorname{stat} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \left(\operatorname{app}\left\{\operatorname{forget}(\tau_2)\right\} v_2 \left(\operatorname{dyn} \left(\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0\right) v_1\right)\right)\right)]
                 4.3. SCASE v_0 \notin (\operatorname{trace}_{v}^? \overline{b}(\lambda(x:\tau).e)) \cup (\operatorname{trace}_{v}^? \overline{b}(\operatorname{mon} b v))
3068
             2019-10-03 17:26. Page 59 of 1-148.
```

```
4.3.1. QED
3069
3070
                         e_0 \triangleright_{A} E_0[\mathsf{TagErr} \bullet]
3071
            5. Case e_0 = E_0[unop\{\tau?\} v_0]
3072
3073
3074
                     by lemma 7.16 and lemma 7.18
3075
            6. CASE e_0 = E_0[binop\{\tau?\} v_0 v_1]
3076
                6.1. QED
3077
                     by lemma 7.16 and lemma 7.18
            7. CASE e_0 = E_0[\mathsf{dyn} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \upsilon_0]
                7.1. QED
3081
                     by lemma 7.16 and lemma 7.20
3082
            8. Case e_0 = E_0[\operatorname{stat}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \upsilon_0]
3083
3084
3085
                     by lemma 7.16 and lemma 7.21
            9. CASE e_0 = E_0[\operatorname{trace} \overline{b}_0 v_0]
3087
                 9.1. QED
3088
                    e_0 \triangleright_{A} E_0[add\text{-}trace(\overline{b}_0, v_0)]
3089
3090
                                                                                                                                                                                                                      Lemma 7.12 (FA type preservation). If \cdot FA e_0:\tau? and e_0 \rightarrow_A e_1 then \cdot FA e_1:\tau?.
3095
                 PROOF. By lemma 7.13 and lemma 7.14.
3096
3097
                                                                                                                                                                                                                      3098
                 Lemma 7.13 (\triangleright_{A} preservation). If \cdot \vdash_{A} e_0 : \tau_0 and e_0 \triangleright_{A} e_1 then \cdot \vdash_{A} e_1 : \tau_0.
3100
3101
                 Proof. By case analysis of \triangleright_{A}.
3102
             1. Case \delta_A(unop, v_0) is defined
3103
3104
                           and unop\{\tau?\}\ v_0 \rhd_A \delta_A(unop, v_0)
3105
                 1.1. QED
                    by lemma 7.19
3107
            2. \ \text{Case fst} \{\tau_0\} \left( \mathsf{mon} \left( \ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1 \right) \upsilon_0 \right) \rhd_{\!\!\!\!\!A} \ \mathsf{dyn} \left( \ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1 \right) \left( \mathsf{fst} \{\mathcal{U}\} \upsilon_0 \right) \\
3108
3109
                 2.1. QED
3110
3111
3112
                                                                                                          \cdot v_0: \mathcal{U}
3113
                                                                                                 \frac{v_0 \cdot v_1}{\cdot \vdash_{\mathsf{A}} \mathsf{fst}\{\mathcal{U}\} v_0 : \mathcal{U}}
3114
3115
3116
                                                                                  \cdot \vdash_{\mathsf{A}} \mathsf{dyn} \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) \left(\mathsf{fst}\{\mathcal{U}\} v_0\right) : \tau_0
3117
            3118
                 3.1. QED
3119
```

```
3122
                                                                                                                            by inversion \vdash_A
3123
                                                                                                                                     \cdot v_0 : \mathcal{U}
3124
3125
                                                                                                                        \cdot \vdash_{\mathsf{A}} \mathsf{snd}\{\mathcal{U}\} \, v_0 : \mathcal{U}
3126
                                                                                                    \cdot \vdash_{\mathsf{A}} \mathsf{dyn} \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) \left(\mathsf{snd}\{\mathcal{U}\}\ v_0\right) : \tau_0
3127
               4. Case binop\{\tau?\}\ v_0\ v_1 \rhd_A \delta_A(binop, v_0, v_1)
3128
3129
                    4.1. QED
3130
                         by lemma 7.19
               5. Case app\{\tau_0\} (\lambda(x_1:\tau_1). e_1) \ v_2 \rhd_A e_1[x_1 \leftarrow v_2]
3132
3133
                    5.1. QED
3134
                         by lemma 7.25
3135
               6. CASE app\{\tau_0\} (mon (\ell_0 \blacktriangleleft (\tau_1 \Rightarrow \tau_2) \blacktriangleleft \ell_1) v_0) v_1
3136
                                  3137
3138
                    6.1. QED
3139
3140
3141
                                                                                      by inversion \vdash_A
                                                                                                                                                       \cdot \vdash_{\mathsf{A}} v_1 : \tau_1
3142
                                                                                                                                    \cdot \vdash_{\mathsf{A}} stat (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \ v_1 : \mathcal{U}
3143
                                                                                           \cdot \vdash_{\mathsf{A}} \upsilon_0 : \mathcal{U}
3144
                                                                                                \cdot \vdash_{\mathsf{A}} \mathsf{app}\{\mathcal{U}\} \, v_0 \; (\mathsf{stat} \; (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \, v_1) : \mathcal{U}
3145
3146
                                                                             \cdot \vdash_{\mathsf{A}} \mathsf{dyn} \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) \left(\mathsf{app} \{\mathcal{U}\} \ v_0 \ (\mathsf{stat} \ (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \ v_1)\right) : \tau_0
3147
               7. case dyn b_0 v_0 \triangleright_{A} v_1
3148
                    7.1. QED
3149
3150
                         by lemma 7.22
3151
3152
3153
3154
3155
                    Lemma 7.14 (\blacktriangleright_A preservation). If \cdot \vdash_A e_0 : \mathcal{U} and e_0 \blacktriangleright_A e_1 then \cdot \vdash_A e_1 : \mathcal{U}.
3156
3157
3158
3159
                    PROOF. By case analysis of \triangleright_{\Lambda}.
3160
               1. case unop\{\tau?\}\ v_0 \blacktriangleright_A \mathsf{TagErr} \bullet
3161
                    1.1. QED
3162
                         \cdot \vdash_{\mathsf{A}} \mathsf{TagErr} \bullet : \mathcal{U}
3163
3164
               2. Case unop\{\tau?\} v_0 \blacktriangleright_A \delta_A(unop, v_0)
3165
                    2.1. QED
3166
                         by lemma 7.19
3167
               3. CASE \operatorname{fst}\{\mathcal{U}\}(\operatorname{trace}_{\mathsf{v}}^? \overline{b_0} (\operatorname{mon}(\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) v_1)) \blacktriangleright_{\mathsf{A}} \operatorname{trace} \overline{b_0} (\operatorname{stat} b_7 (\operatorname{fst}\{fst(\tau_0)\} v_1))
3168
                                  where b_7 = (\ell_1 \blacktriangleleft fst(\tau_0) \blacktriangleleft \ell_2)
3169
3170
                    3.1. QED
3171
3172
               2019-10-03 17:26. Page 61 of 1-148.
```

```
3173
3174
                                                                                                                                                                 by inversion \vdash_A
3175
                                                                                                                                                                       \cdot \vdash_{\mathsf{A}} v_1 : \tau_0
3176
3177
                                                                                                                                                 \cdot \vdash_{\mathsf{A}} \mathsf{fst}\{\mathit{fst}(\tau_0)\} v_1 : \mathit{fst}(\tau_0)
3178
                                                                                                                                           \cdot \vdash_{\mathsf{A}} \mathsf{stat}\ b_7\ (\mathsf{fst}\{\mathit{fst}(	au_0)\}\ v_1) : \mathcal{U}
3179
3180
                                                                                                                              \cdot \vdash_{\mathsf{A}} \operatorname{trace} \overline{b_0} \left( \operatorname{stat} b_7 \left( \operatorname{fst} \left\{ fst(\tau_0) \right\} v_1 \right) \right) : \mathcal{U}
3181
                   4. \ \operatorname{CASE} \ \operatorname{snd}\{\mathcal{U}\} \left(\operatorname{trace}_{\mathbf{v}}^{?} \overline{b}_{0} \left(\operatorname{mon} \left(\ell_{1} \blacktriangleleft \tau_{0} \blacktriangleleft \ell_{2}\right) \upsilon_{1}\right)\right) \blacktriangleright_{\mathbf{A}} \ \operatorname{trace} \overline{b}_{0} \left(\operatorname{stat} b_{7} \left(\operatorname{snd}\left\{\operatorname{snd}\left(\tau_{0}\right)\right\} \upsilon_{1}\right)\right) + \left(\operatorname{snd}\left\{\operatorname{snd}\left(\tau_{0}\right)\right\} \upsilon_{1}\right)\right)
3182
                                            where b_7 = (\ell_1 \blacktriangleleft snd(\tau_0) \blacktriangleleft \ell_2)
3183
3184
                           4.1. QED
3185
3186
                                                                                                                                                                 by inversion ⊦<sub>A</sub>
3187
                                                                                                                                                                      \cdot \vdash_{\mathsf{A}} v_1 : \tau_0
3188
3189
                                                                                                                                            \cdot \vdash_{\mathsf{A}} \mathsf{snd} \{ \mathit{snd}(\tau_0) \} \ v_1 : \mathit{snd}(\tau_0) 
3190
                                                                                                                                        3191
3192
                                                                                                                             \cdot \vdash_{\mathsf{A}} \mathsf{trace}\,\overline{b}_0\,(\mathsf{stat}\,b_7\,(\mathsf{snd}\{\mathit{snd}(\tau_0)\}\,v_1)):\mathcal{U}
3193
                    5. Case binop\{\tau?\} v_0 v_1 \blacktriangleright_A TagErr \bullet
3194
3195
                           5.1. QED
3196
                                  \cdot \vdash_{\mathsf{A}} \mathsf{TagErr} \bullet : \mathcal{U}
3197
                    6. Case binop\{\tau?\} v_0 v_1 \blacktriangleright_A \delta_A(binop, v_0, v_1)
3198
                          6.1. QED
3199
                                 by lemma 7.19
3200
3201
                    7. CASE app{\mathcal{U}} (trace, \bar{b}_0(\lambda x_1.e_1)) v_2
3202

ightharpoonup_{A} \operatorname{trace} \overline{b}_{0} \left( e_{1}[x_{1} \leftarrow v_{2}] \right)
3203
                          7.1. QED
3204
3205
                                 by lemma 7.25
3206
                    8. CASE app\{\mathcal{U}\} (trace, \bar{b}_0 (mon (\ell_0 \blacktriangleleft (\tau_1 \Rightarrow \tau_0) \blacktriangleleft \ell_1) v_0)) <math>v_1
3207
                                            \blacktriangleright_{\mathsf{A}} \mathsf{trace}\, \overline{b}_0\, (\mathsf{stat}\, (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\, (\mathsf{app}\{\tau_0\}\, v_0\, (\mathsf{dyn}\, (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0)\, v_1)))
3208
                           8.1. QED
3209
3210
3211
                                                                                                                                                                                                 by inversion \vdash_A

\frac{\text{by inversion } \vdash_{\mathsf{A}}}{\cdot \vdash_{\mathsf{A}} v_0 : \tau_1 \Rightarrow \tau_0} \qquad \frac{\cdot}{\cdot \vdash_{\mathsf{A}} v_1 : \mathcal{U}} \\
\cdot \vdash_{\mathsf{A}} \mathsf{dyn} \left(\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0\right) v_1 : \tau_1

3212
3213
3214
3215
                                                                                                                            \cdot \vdash_{\mathsf{A}} \mathsf{app}\{\tau_0\} \, v_0 \, (\mathsf{dyn} \, (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \, v_1) : \tau_0
3216
3217
                                                                                       \cdot \vdash_{\mathsf{A}} \mathsf{trace}\, \overline{b}_0\, (\mathsf{stat}\, (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\, (\mathsf{app}\{\tau_0\}\, v_0\, (\mathsf{dyn}\, (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0)\, v_1))): \, \mathcal{U}
3218
                    9. CASE stat b_0 v_0 \triangleright_{\Lambda} v_1
3219
                           9.1. QED
3220
                                 by lemma 7.23
3221
                    10. Case trace \overline{b}_0 \, v_0 \blacktriangleright_{\!\!\! A} add\text{-trace}(\overline{b}_0, v_0)
3223
```

```
10.1. QED
3225
3226
               by lemma 7.24
3227
3228
3229
            Lemma 7.15 (unique decomposition). If \cdot \vdash_A e_0 : \tau? then either:
3230
3231
              • e_0 \in v
3232
              • e_0 = E_0[\mathsf{app}\{\tau?\} v_0 v_1]
3233
              • e_0 = E_0[unop\{\tau?\} v_0]
3234
3235
              • e_0 = E_0[binop\{\tau?\} v_0 v_1]
3236
              • e_0 = E_0[\mathsf{dyn}\ b_1\ v_1]
3237
              • e_0 = E_0[\text{stat } b_1 \ v_1]
3238
              • e_0 = E_0[\operatorname{trace} \overline{b_1} v_1]
3239
3240
              • e_0 = E_0[Err]
3241
3242
            Proof. By induction on the structure of e_0.
3243
         1. CASE e_0 = x_0
3244
            1.1. Contradiction:
3245
3246
               \cdot \vdash_{\mathsf{A}} e_0 : \tau?
3247
        2. Case e_0 = v_0
            2.1. QED
3249
        3. Case e_0 = \langle e_1, e_2 \rangle
3250
            3.1. SCASE e_1 \notin v
3251
3252
               3.1.1. QED
3253
                  by the induction hypothesis
3254
            3.2. Scase e_1 \in v and e_2 \notin v
3255
3256
               3.2.1. QED
3257
                  by the induction hypothesis
3258
            3.3. SCASE e_1 \in v and e_2 \in v
3259
               3.3.1. QED
3260
                  e_0 \in v
3262
        4. CASE e_0 = app\{\tau?\} e_1 e_2
3263
            4.1. QED
3264
              by the induction hypothesis
3265
3266
        5. CASE e_0 = unop\{\tau?\} e_1
3267
            5.1. QED
3268
               by the induction hypothesis
3269
        6. CASE e_0 = binop\{\tau?\} e_1 e_2
3270
3271
3272
               by the induction hypothesis
3273
        7. CASE e_0 = \text{dyn } b_1 e_1
3274
            7.1. QED
3275
3276
        2019-10-03 17:26. Page 63 of 1-148.
```

```
3277
               by the induction hypothesis
3278
        8. Case e_0 = \operatorname{stat} b_1 e_1
3279
            8.1. QED
3280
               by the induction hypothesis
3281
         9. CASE e_0 = \operatorname{trace} \overline{b}_1 e_1
3282
3283
            9.1. QED
3284
               by the induction hypothesis
3285
         10. Case e_0 \in Err
            10.1. QED
3288
                                                                                                                                                             3289
3290
            Lemma 7.16. If \cdot \vdash_A E_0[e_0] : \tau? then one of the following holds:
3291
3292
              \bullet · \vdash_{\mathsf{A}} e_0 : \mathcal{U}
3293
              • \exists \tau_0 ... \vdash_{\mathsf{A}} e_0 : \tau_0
3294
3295
            PROOF. By induction on the structure of E_0 and case analysis of \vdash_A.
3296
         1. case E_0 = []
3297
            1.1. QED
3298
3299
        2. Case E_0 = \langle E_1, e_2 \rangle
3300
            2.1. \cdot \vdash_{\mathsf{A}} E_1[e_0] : \tau?
3301
               by inversion \vdash_A
3302
            2.2. QED
3303
3304
               by the induction hypothesis
3305
        3. Case E_0 = \langle v_1, E_2 \rangle
3306
            3.1. QED
3307
3308
               by the induction hypothesis
3309
         4. CASE E_0 = app\{\tau?\} E_1 e_2
3310
            4.1. QED
3311
               by the induction hypothesis
3312
3313
        5. Case E_0 = app\{\tau?\} v_1 E_2
3314
            5.1. QED
3315
               by the induction hypothesis
3316
        6. CASE E_0 = unop\{\tau?\} E_1
3317
3318
3319
               by the induction hypothesis
3320
        7. Case E_0 = binop\{\tau?\} E_1 e_2
3321
            7.1. QED
3322
3323
               by the induction hypothesis
3324
         8. CASE E_0 = binop\{\tau?\} v_1 E_2
3325
            8.1. QED
3326
               by the induction hypothesis
3327
```

```
9. CASE E_0 = \text{dyn } b_1 E_1
3329
3330
             9.1. QED
3331
                by the induction hypothesis
3332
         10. Case E_0 = \text{stat } b_1 E_1
3333
3334
             10.1. QED
3335
                by the induction hypothesis
3336
         11. CASE E_0 = \operatorname{trace} \overline{b}_1 E_1
3337
             11.1. QED
3338
3339
                by the induction hypothesis
3340
3341
3342
             LEMMA 7.17 (⊢A REPLACEMENT).
3343
3344
               \bullet \ \ \textit{If} \ \cdot \vdash_{\mathsf{A}} E_0[e_0] : \tau? \ \textit{and the derivation contains a proof of} \ \cdot \vdash_{\mathsf{A}} e_0 : \tau_0 \ \textit{and} \ \cdot \vdash_{\mathsf{A}} e_1 : \tau_0 \ \textit{then} \ \cdot \vdash_{\mathsf{A}} E_0[e_1] : \tau?.
3345
               • If \cdot \vdash_A E_0[e_0] : \tau? and the derivation contains a proof of \cdot \vdash_A e_0 : \mathcal{U} and \cdot \vdash_A e_1 : \mathcal{U} then \cdot \vdash_A E_0[e_1] : \tau?.
3346
3347
             PROOF. By induction on E_0.
3348
         1. CASE E_0 = []
3349
3350
             1.1. QED
3351
         2. Case E_0 = \langle E_1, e_2 \rangle
3352
             2.1. QED
3353
                by the induction hypothesis
3354
         3. Case E_0 = \langle v_1, E_2 \rangle
3355
3356
             3.1. QED
3357
                by the induction hypothesis
3358
         4. Case E_0 = app\{\tau?\} E_1 e_2
3359
3360
             4.1. QED
3361
                by the induction hypothesis
3362
         5. CASE E_0 = app\{\tau?\} v_1 E_2
3363
             5.1. QED
3364
               by the induction hypothesis
3366
         6. Case E_0 = unop\{\tau?\} E_1
3367
             6.1. QED
3368
                by the induction hypothesis
3369
3370
         7. CASE E_0 = binop\{\tau?\} E_1 e_2
3371
             7.1. QED
3372
                by the induction hypothesis
3373
         8. CASE E_0 = binop\{\tau?\} v_1 E_2
3374
3375
3376
                by the induction hypothesis
3377
         9. CASE E_0 = \text{dyn } b_1 E_1
3378
            9.1. QED
3379
3380
         2019-10-03 17:26. Page 65 of 1-148.
```

```
3381
                        by the induction hypothesis
3382
               10. CASE E_0 = \text{stat } b_1 E_1
3383
                    10.1. QED
3384
                        by the induction hypothesis
3385
               11. CASE E_0 = \operatorname{trace} \overline{b}_1 E_1
3386
3387
                    11.1. QED
3388
                        by the induction hypothesis
3389
                                                                                                                                                                                                                                                                3392
                    LEMMA 7.18.
3393
                       • If \cdot \vdash_A unop\{\tau_1\} v_0 : \tau_0 \text{ then } unop\{\tau_1\} v_0 \rhd_A e_1.
3394
3395
                       • if \cdot \vdash_A binop\{\tau_1\} \ v_0 \ v_1 : \tau_0 \ then \ binop\{\tau_1\} \ v_0 \ v_1 \mathrel{\triangleright_A} \ e_1.
3396
                       • If \cdot \vdash_A unop\{\mathcal{U}\} v_0 : \mathcal{U} \text{ then } unop\{\mathcal{U}\} v_0 \blacktriangleright_{\!\!\!\! \Delta} e_1.
3397
                        • if \cdot \vdash_A binop\{\mathcal{U}\} \ v_0 \ v_1 : \mathcal{U} \ then \ binop\{\mathcal{U}\} \ v_0 \ v_1 \blacktriangleright_A e_1.
3398
3399
                    Proof. By case analysis of \delta_A, \vdash_A, and \blacktriangleright_A.
3400
              1. CASE \cdot \vdash_A \text{fst}\{\tau_0\} v_0
3401
3402
                    1.1. v_0 \in \langle v, v \rangle \cup \text{mon} (\ell \blacktriangleleft \tau \times \tau \blacktriangleleft \ell) v
3403
                        by \vdash_A canonical forms
3404
                    1.2. SCASE v_0 = \langle v_1, v_2 \rangle
3405
                        1.2.1. QED
3406
3407
                             fst\{\tau_0\} v_0 \rhd_A v_1
3408
                    1.3. SCASE v_0 = \text{mon} (\ell_0 \blacktriangleleft \tau_1 \times \tau_2 \blacktriangleleft \ell_1) v_1
3409
                         1.3.1. QED
3410
                              \mathsf{fst}\{\tau_0\}\,v_0\,\rhd_{\!\!\mathsf{A}}\,\mathsf{dyn}\,(\ell_0\,\blacktriangleleft\,\tau_0\,\blacktriangleleft\,\ell_1)\,(\mathsf{fst}\{\mathcal{U}\}\,v_0)
3411
3412
              2. CASE \cdot \vdash_A \operatorname{snd}\{\tau_0\} v_0
3413
                    2.1. QED
3414
                        similar to the fst case
3415
              3. CASE \cdot \vdash_{\mathsf{A}} \mathsf{fst}\{\mathcal{U}\} v_0
3416
3417
                   3.1. SCASE v_0 = \langle v_1, v_2 \rangle
3418
                        3.1.1. QED
3419
                             fst\{\mathcal{U}\} v_0 \blacktriangleright_{A} v_1
3420
                    3.2. SCASE v_0 = \operatorname{trace}_{\mathbf{v}}^? \overline{b_0} \left( \operatorname{mon} \left( \ell_1 \blacktriangleleft \tau_1 \times \tau_2 \blacktriangleleft \ell_2 \right) v_1 \right)
3421
3422
                        3.2.1. QED
3423
                             \mathsf{fst}\{\mathcal{U}\}\,v_0 \blacktriangleright_{\mathsf{A}} \mathsf{trace}\,\overline{b}_0\,(\mathsf{stat}\,(\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2)\,(\mathsf{fst}\{\tau_1\}\,v_1))
3424
                    3.3. SCASE v_0 \notin \langle v, v \rangle \cup (\text{mon}(\ell \blacktriangleleft \tau \times \tau \blacktriangleleft \ell) v)
3425
                        3.3.1. QED
3426
3427
                             fst\{\mathcal{U}\} v_0 \blacktriangleright_A TagErr \bullet
3428
              4. CASE \cdot \vdash_{\mathsf{A}} \mathsf{snd}\{\mathcal{U}\} v_0
3429
                    4.1. QED
3430
3431
                         similar to the fst case
```

```
5. CASE \cdot \vdash_A binop\{\tau_1\} v_0 v_1 : \tau_0
3433
3434
                    5.1. v_0 \in i and v_1 \in i
3435
                         by \vdash_A canonical forms
3436
                    5.2. QED
3437
3438
                          \mathit{binop}\{\tau_1\}\ v_0\ v_1\ \triangleright_{\!\!A}\ \delta_A(\mathit{binop},v_0,v_1)
3439
               6. CASE \cdot \vdash_A binop\{\mathcal{U}\} v_0 v_1 : \mathcal{U}
3440
                    6.1. SCASE v_0 \in i and v_1 \in i
3441
                         6.1.1. QED
3442
                               binop\{\mathcal{U}\}\ v_0\ v_1\ \blacktriangleright_A\ \delta_A(binop,v_0,v_1)
3444
                    6.2. SCASE v_0 \notin i or v_1 \notin i
3445
                         6.2.1. QED
3446
                               binop\{\mathcal{U}\} v_0 v_1 \blacktriangleright_A TagErr \bullet
3447
3448
3449
3450
                     Lemma 7.19.
3451
                        • If \cdot \vdash_A unop\{\tau_1\} \ v_0 : \tau_0 \ and \ unop\{\tau_1\} \ v_0 \ \rhd_A \ e_1 \ then \cdot \vdash_A \ e_1 : \tau_0.
3452
                        • If \cdot \vdash_A binop\{\tau_1\} \ v_0 \ v_1 : \tau_0 \ and \ binop\{\tau_1\} \ v_0 \ v_1 \ \triangleright_{\!\scriptscriptstyle A} \ e_2 \ then \cdot \vdash_A \ e_2 : \tau_0.
3453
                        • If \cdot \vdash_{\mathsf{A}} unop\{\mathcal{U}\} \ v_0 : \mathcal{U} \ and \ unop\{\mathcal{U}\} \ v_0 \blacktriangleright_{\mathsf{A}} e_1 \ then \cdot \vdash_{\mathsf{A}} e_1 : \mathcal{U}.
3454
3455
                        • If \cdot \vdash_A binop\{\mathcal{U}\} \ v_0 \ v_1 : \mathcal{U} \ and \ binop\{\mathcal{U}\} \ v_0 \ v_1 \blacktriangleright_A \ e_2 \ then \cdot \vdash_A \ e_2 : \mathcal{U}.
3456
                     PROOF. By case analysis of \delta_A and \vdash_A.
3457
3458
               1. Case \cdot \vdash_{\mathsf{A}} \mathsf{fst}\{\tau_0\} \, \upsilon_0 : \tau_0
3459
                    1.1. Scase fst\{\tau_0\}\langle v_1, v_2\rangle \rhd_{\Delta} v_1
3460
                         1.1.1. QED
3461
3462
                               by inversion ⊢A
                    1.2. SCASE fst\{\tau_0\} (mon (\ell_0 \blacktriangleleft \tau_1 \times \tau_2 \blacktriangleleft \ell_1) \ v_1)
3464
                                            \rhd_{\mathsf{A}} \operatorname{\mathsf{dyn}} \left(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1\right) \left(\operatorname{\mathsf{fst}} \{\mathcal{U}\} \, v_1\right)
3465
                         1.2.1. QED
3466
3467
3468
                                                                                                   by inversion ⊢A
                                                                                                       \cdot \vdash_{\mathsf{A}} v_1 : \mathcal{U}
3470
3471
                                                                                                \cdot \vdash_{\mathsf{A}} \mathsf{fst}\{\mathcal{U}\}\,v_1:\mathcal{U}
                                                                                                                                                                          by inversion ⊢A
3472
                                                                             \cdot \vdash_{\mathsf{A}} \mathsf{dyn} \left(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1\right) \left(\mathsf{fst}\{\mathcal{U}\} v_1\right) : \tau_1
                                                                                                                                                                                   \tau_1 \leqslant : \tau_0
3473
3474
                                                                                                     \cdot \vdash_{\mathsf{A}} \mathsf{dyn} \left(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1\right) \left(\mathsf{fst}\{\mathcal{U}\} v_1\right) : \tau_0
3475
               2. CASE \cdot \vdash_A \operatorname{snd}\{\tau_0\} v_0 : \tau_0
3476
                    2.1. QED
3477
                          similar to fst
3478
3479
               3. CASE \cdot \vdash_A sum\{\tau_1\} v_0 v_1 : \tau_0
3480
                    3.1. \operatorname{sum}\{\tau_1\} v_0 v_1 \rhd_{\mathsf{A}} \delta_A(\operatorname{sum}, v_0, v_1)
3481
                    3.2. \tau<sup>0</sup> ∈ Int ∪ Nat
3482
3483
                         by inversion ⊢A
3484
```

2019-10-03 17:26. Page 67 of 1-148.

```
3485
                  3.3. Scase \tau_0 = \text{Int}
3486
                       3.3.1. \cdot \vdash_A v_0 : Int \ and \cdot \vdash_A v_1 : Int
3487
                            by inversion ⊢<sub>A</sub>
3488
                      3.3.2. v_0 \in i \text{ and } v_1 \in i
3489
3490
                            by \vdash_A canonical forms
3491
                       3.3.3. QED
3492
                            \cdot \vdash_{\mathsf{A}} \delta_A(\mathit{binop}, v_0, v_1) : \mathsf{Int}
3493
                  3.4. SCASE \tau_0 = \text{Nat}
3494
                      3.4.1. \cdot \vdash_{\mathsf{A}} v_0 : \mathsf{Nat} \ \mathsf{and} \cdot \vdash_{\mathsf{A}} v_1 : \mathsf{Nat}
3496
                            by inversion ⊦<sub>A</sub>
3497
                       3.4.2. v_0 \in n and v_1 \in n
3498
                            by ⊢A canonical forms
3499
3500
                       3.4.3. QED
3501
                            \cdot \vdash_{\mathsf{A}} \delta_A(\mathit{binop}, v_0, v_1) : \mathsf{Nat}
3502
              4. CASE \cdot \vdash_A \text{quotient}\{\tau_1\} v_0 v_1 : \tau_0
3503
                  4.1. quotient\{\tau_1\} v_0 v_1 \triangleright_A \delta_A(quotient, v_0, v_1)
3504
                  4.2. \tau<sup>0</sup> ∈ Int ∪ Nat
3505
3506
                       by inversion ⊢A
3507
                  4.3. scase \tau_0 = \text{Int}
                       4.3.1. \cdot \vdash_A v_0 : Int \ and \cdot \vdash_A v_1 : Int
3510
                            by inversion ⊢<sub>A</sub>
3511
                       4.3.2. v_0 \in i \text{ and } v_1 \in i
3512
                            by \vdash_A canonical forms
3513
                       4.3.3. QED
3514
3515
                            \delta_A(binop, v_0, v_1) \in i \cup \mathsf{DivErr}
3516
                  4.4. scase \tau_0 = Nat
3517
                       4.4.1. \cdot \vdash_{\mathsf{A}} v_0 : \mathsf{Nat} \ \mathsf{and} \cdot \vdash_{\mathsf{A}} v_1 : \mathsf{Nat}
3518
                            by inversion ⊢<sub>A</sub>
3519
                       4.4.2. v_0 \in n and v_1 \in n
                            by ⊢A canonical forms
                      4.4.3. QED
3523
                            \delta_A(binop, v_0, v_1) \in n \cup \mathsf{DivErr}
3524
              5. CASE \cdot \vdash_{\mathsf{A}} \mathsf{fst}\{\mathcal{U}\} v_0 : \mathcal{U}
3525
3526
                  5.1. SCASE v_0 = \operatorname{trace}_{\mathbf{v}}^? \overline{b_0} \langle v_1, v_2 \rangle
3527
                                        and fst\{\mathcal{U}\}\ v_0 \blacktriangleright_{\mathsf{A}} add\text{-}trace(\bar{b}_0, v_1)
3528
                       5.1.1. \cdot \vdash_{\mathsf{A}} v_1 : \mathcal{U}
3529
3530
                            by inversion ⊢<sub>A</sub>
3531
                      5.1.2. QED
3532
                            by lemma 7.24
3533
                  5.2. Scase v_0 = \operatorname{trace}_{\mathbf{v}}^? \overline{b_0} \left( \operatorname{mon} \left( \ell_1 \blacktriangleleft \tau_1 \times \tau_2 \blacktriangleleft \ell_2 \right) v_1 \right)
3534
                                        and \mathsf{fst}\{\mathcal{U}\}\,v_0 \blacktriangleright_\mathsf{A} \mathsf{trace}\, \overline{b}_0\, (\mathsf{stat}\, (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2)\, (\mathsf{fst}\{\tau_1\}\,v_1))
```

```
3537
                           5.2.1. QED
3538
3539
                                                                                                                                by inversion ⊦A
3540
                                                                                                                                    \cdot \vdash_{\mathsf{A}} v_1 : \mathcal{U}
3541
3542
                                                                                                                             \cdot \vdash_{\mathsf{A}} \mathsf{fst}\{\tau_1\} \, v_1 : \mathcal{U}
3543
                                                                                                         \cdot \vdash_{\mathsf{A}} \operatorname{stat} (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2) \left( \operatorname{fst} \{\tau_1\} \ v_1 \right) : \mathcal{U}
3544
3545
                                                                                               \cdot \vdash_{\mathsf{A}} \mathsf{trace}\,\overline{b}_0\,(\mathsf{stat}\,(\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2)\,(\mathsf{fst}\{\tau_1\}\,v_1)):\mathcal{U}
3546
                     5.3. SCASE v_0 \notin (\operatorname{trace}_{\mathbf{v}}^? \overline{b} \langle v, v \rangle) \cup (\operatorname{trace}_{\mathbf{v}}^? \overline{b} (\operatorname{mon} b v))
3547
                                               and \operatorname{fst}\{\mathcal{U}\}v_0 \blacktriangleright_{\!\scriptscriptstyle A} \operatorname{TagErr} \bullet
3548
3549
                           5.3.1. QED
3550
                                \cdot \vdash_{\mathsf{A}} \mathsf{TagErr} \bullet : \mathcal{U}
3551
                6. CASE \cdot \vdash_{\mathsf{A}} \mathsf{snd}\{\mathcal{U}\} \, v_0 : \mathcal{U}
3552
3553
                     6.1. QED
3554
                           similar to fst
3555
                7. CASE \cdot \vdash_{\mathsf{A}} \mathsf{sum}\{\mathcal{U}\} v_0 v_1 : \mathcal{U}
3556
                     7.1. \operatorname{sum}\{\mathcal{U}\}\ v_0\ v_1 \blacktriangleright_{\mathsf{A}} \delta_A(\mathit{binop}, v_0, v_1)
3557
3558
                     7.2. \delta_A(binop, v_0, v_1) \in i
3559
                          by definition \delta_A
                     7.3. QED
3561
                           \cdot \vdash_{\mathsf{A}} \delta_A(\mathit{binop}, v_0, v_1) : \mathcal{U}
3562
                8. CASE \cdot \vdash_{\mathsf{A}} \mathsf{quotient}\{\mathcal{U}\} v_0 v_1 : \mathcal{U}
3563
3564
                     8.1. quotient\{\mathcal{U}\}\ v_0\ v_1 \blacktriangleright_{\mathsf{A}} \delta_A(\mathit{binop}, v_0, v_1)
3565
                     8.2. \delta_A(binop, v_0, v_1) \in i \cup DivErr
3566
                           by definition \delta_A
3567
3568
                     8.3. QED
3569
                           \cdot \vdash_{\mathsf{A}} \delta_A(\mathit{binop}, v_0, v_1) : \mathcal{U}
3570
3571
3572
                     Lemma 7.20. If \cdot \vdash_A \operatorname{dyn} b_0 v_0 : \tau_0 and b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) then \exists e_1 \text{ such that dyn } b_0 v_0 \rhd_A e_1.
3573
3574
                     PROOF. By case analysis of tag-match([\tau_0], v_0).
3575
                1. CASE tag-match(\lfloor \tau_0 \rfloor, \operatorname{trace}_{v}^{?} \overline{b}_2(\lambda x_1. e_1))
3576
                     1.1. QED
3577
3578
                           \mathsf{dyn}\ b_0\ v_0 \,\rhd_{\!\!\mathsf{A}}\ \mathsf{mon}\ b_0\ v_0
3579
                2. Case tag-match(\lfloor \tau_0 \rfloor, \lambda(x_1 : \tau_1). e_1)
3580
                     2.1. Contradiction:
3581
3582
                           \cdot \vdash_{\mathsf{A}} \mathsf{dyn} \ b_0 \ v_0 : \tau_0
3583
               3. CASE tag-match(\lfloor \tau_0 \rfloor, \operatorname{trace}_{v}^{?} \overline{b}_2 \pmod{b_1 \ v_1})
3584
3585
                           \mathsf{dyn}\ b_0\ v_0 \,\rhd_{\!\!\mathsf{A}}\ \mathsf{mon}\ b_0\ v_0
3586
                4. CASE tag-match(\lfloor (\tau_1 \times \tau_2) \rfloor, \operatorname{trace}_{v}^{?} \overline{b}_2 \langle v_1, v_2 \rangle)
3587
3588
                2019-10-03 17:26. Page 69 of 1-148.
```

```
4.1. QED
3589
3590
                         \mathsf{dyn}\,b_0\,v_0\,\rhd_{\!\!\mathsf{A}}\,\mathsf{mon}\,b_0\,v_0
3591
              5. CASE tag-match([Int], trace_{v}^{?} \overline{b}_{1} v_{1})
3592
                   5.1. QED
3593
3594
                        \operatorname{\mathsf{dyn}} b_0 \ v_0 \, \triangleright_{\!\!\mathsf{A}} v_1
3595
              6. CASE tag-match([Nat], trace_{v}^{?} \overline{b}_{1} v_{1})
3596
                   6.1. QED
3597
                        dyn b_0 v_0 \rhd_{A} v_1
3598
              7. CASE \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)
3600
                   7.1. QED
3601
                        \mathsf{dyn}\,b_0\,\,v_0\,\rhd_{\!\!\mathsf{A}}\,\mathsf{BndryErr}\,(b_0,v_0)
3602
3603
                                                                                                                                                                                                                                                           3604
                   LEMMA 7.21. If \cdot \vdash_A stat b_0 \ v_0 : \mathcal{U} and b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) then \exists \ e_1 \ such \ that \ stat \ b_0 \ v_0 \blacktriangleright_A \ e_1.
3605
3606
                   PROOF. By case analysis on v_0.
3607
               1. Case v_0 \in \operatorname{trace}_{\mathbf{v}}^? \overline{b}_2(\lambda x. e)
3608
                   1.1. Contradiction:
3609
3610
                        \cdot \vdash_{\mathsf{A}} \mathsf{stat}\ b_0\ v_0: \mathcal{U}
3611
              2. Case v_0 \in \lambda(x:\tau). e
3612
                   2.1. QED
3613
3614
                        stat b_0 v_0 \triangleright_A \text{mon } b_0 v_0
3615
              3. Case v_0 = \text{mon } b_1 v_1
3616
                   3.1. SCASE v_1 = \operatorname{trace}_{v}^{?} \overline{b}_2 v_2
3617
                                          and v_2 \in (\lambda x. e) \cup \langle v, v \rangle
3618
3619
                       3.1.1. QED
3620
                             stat b_0 v_0 \blacktriangleright_A \operatorname{trace} b_0 b_1 \overline{b}_2 v_0
3621
                   3.2. SCASE v_1 = \operatorname{trace}_{v}^{?} \overline{b}_{2} \pmod{b_3 v_2}
3622
                                          and v_2 \in (\lambda(x:\tau), v) \cup \langle v, v \rangle
3623
                       stat b_0 \ v_0 \blacktriangleright_{\mathsf{A}} \operatorname{trace} b_0 b_1 \overline{b}_2 \, (\mathsf{mon} \ b_3 \ v_2)
              4. Case v_0 = \langle v_1, v_2 \rangle
                   4.1. \tau_0 = \tau_1 \times \tau_2
                       by inversion ⊦<sub>A</sub>
3628
3629
3630
                        stat b_0 \ v_0 \blacktriangleright_{A} \ \mathsf{mon} \ b_0 \ v_0
3631
              5. Case v_0 \in i
3632
                   5.1. QED
3633
3634
                        stat b_0 v_0 \blacktriangleright_{\mathsf{A}} v_0
3635
                                                                                                                                                                                                                                                           3636
                   \text{Lemma 7.22. } \textit{If } \cdot \vdash_{\mathsf{A}} \mathsf{dyn} \ b_0 \ \upsilon_0 : \tau_0 \ \textit{and} \ b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ \textit{and} \ \mathsf{dyn} \ b_0 \ \upsilon_0 \, \rhd_{\!\!\!\!A} \ e_1 \ \textit{then} \cdot \vdash_{\mathsf{A}} e_1 : \tau_0.
                   PROOF. By case analysis of \triangleright_{A}.
                                                                                                                                                                                                      2019-10-03 17:26. Page 70 of 1-148.
```

```
1. Case dyn b_0 \ v_0 \rhd_{\!\!\!A} \ {\sf mon} \ b_0 \ v_0
3641
3642
                     1.1. QED
3643
3644
                                                                                                                                 by inversion \vdash_A
3645
                                                                                                                                      \cdot \vdash_{\mathsf{A}} v_0 : \mathcal{U}
3646
3647
                                                                                                                               \cdot \vdash_{\mathsf{A}} \mathsf{mon}\ b_0\ v_0 : \tau_0
3648
                2. CASE dyn b_0 trace v_0^? \overline{b}_1 i_0 \triangleright_A i_0
3649
                     2.1. QED
                          by case analysis of tag-match(|\tau_0|, i_0)
               3. Case dyn b_0 v_0 \rhd_{\!\!\mathsf{A}} \mathsf{BndryErr}(b_0,v_0)
3653
                     3.1. QED
3654
                          \cdot \vdash_{\mathsf{A}} \mathsf{BndryErr}\,(b_0, v_0) : \tau_0
3655
3656
3657
3658
                      \text{Lemma 7.23. } \textit{If } \cdot \vdash_{\mathsf{A}} \textit{stat } b_0 \ \upsilon_0 : \mathcal{U} \textit{ and } b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \textit{ and } \textit{stat } b_0 \ \upsilon_0 \blacktriangleright_{\mathsf{A}} e_1 \textit{ then } \cdot \vdash_{\mathsf{A}} e_1.
3659
3660
                     PROOF. By case analysis of \triangleright_{A}.
3661
                1. Case v_0 \in (\lambda(x:\tau).e) \cup (\langle v, v \rangle)
3662
                                   and stat b_0 \ v_0 \blacktriangleright_A \ \mathsf{mon} \ b_0 \ v_0
3663
                     1.1. QED
3665
3666
                                                                                                                                 by inversion \vdash_A
3667
                                                                                                                              \frac{\cdot \vdash_{\mathsf{A}} \upsilon_0 : \tau_0}{\cdot \vdash_{\mathsf{A}} \mathsf{mon} \ b_0 \ \upsilon_0 : \mathcal{U}}
3668
3669
3670
                2. Case v_0 \in (\lambda x. e) \cup (\langle v, v \rangle)
                                   and stat b_0 \; (\mathsf{mon} \; b_1 \; (\mathsf{trace}^?_\mathsf{v} \, \overline{b}_2 \, v_0)) \, \blacktriangleright_\mathsf{A} \; \mathsf{trace} \, b_0 b_1 \overline{b}_2 \, v_0
3672
3673
                     2.1. QED
3674
3675
                                                                                                                                \frac{\text{by inversion} \vdash_A}{\cdot \vdash_A \upsilon_0 : \mathcal{U}}
3676
                                                                                                                         \overline{\cdot}_{\mathsf{FA}} \mathsf{trace}\, b_0 b_1 \overline{b}_2 \, v_0 : \mathcal{U}
3678
3679
                3. Case v_0 \in (\lambda(x:\tau).e) \cup (\langle v,v \rangle)
3680
                                  and stat b_0 \pmod{b_1 \pmod{v_0}} b_1 \pmod{b_3 v_0} \triangleright_A \operatorname{trace} b_0 b_1 \overline{b_2} \pmod{b_3 v_0}
3681
3682
                                   and b_3 = (\ell_4 \blacktriangleleft \tau_3 \blacktriangleleft \ell_5)
3683
                     3.1. QED
3684
3685
                                                                                                                                by inversion ⊦<sub>A</sub>
3686
3687
3688
                                                                                                                              \cdot \vdash_{\mathsf{A}} \mathsf{mon}\ b_3\ v_0 : \mathcal{U}
3689
3690
                                                                                                              \cdot \vdash_{\mathsf{A}} \mathsf{trace}\, b_0 b_1 \overline{b}_2 \, (\mathsf{mon}\, b_3 \, v_0) : \mathcal{U}
3692
```

2019-10-03 17:26. Page 71 of 1-148.

```
3693
            4. CASE stat b_0 i_0 \triangleright_A i_0
3694
                4.1. QED
3695
                    \cdot \vdash_{\mathsf{A}} i_0 : \mathcal{U}
3696
                                                                                                                                                                                                                       3698
                Lemma 7.24. If \cdot \vdash_{\mathsf{A}} \operatorname{trace} \overline{b}_0 \, v_0 : \mathcal{U} \, \operatorname{then} \cdot \vdash_{\mathsf{A}} \operatorname{add-trace} (\overline{b}_0, v_0) : \mathcal{U}.
3699
3700
                PROOF. By case analysis of add-trace.
3701
            1. CASE add-trace(\cdot, v_0) = v_0
3704
            2. \ \operatorname{case} \ \operatorname{add-trace} (\overline{b}_0, (\!(\operatorname{trace_v} \overline{b}_1 \, v_1)\!)^{\overline{\ell}_2}) = \operatorname{trace_v} \overline{b}_0 \overline{b}_1 \, (\!(v_1)\!)^{\overline{\ell}_2}
3705
                2.1. QED
3706
3707
                    by \cdot \vdash_{\mathsf{A}} v_1 : \mathcal{U}
3708
            3. CASE add-trace(\overline{b}_0, v_1) = \text{trace}_{\overline{v}} \overline{b}_0 v_1
3709
3710
                    by \cdot \vdash_A v_1 : \mathcal{U}
3711
3712
                                                                                                                                                                                                                       3713
3714
                LEMMA 7.25.
3715
                   • If (x_0:\tau_0), \Gamma_0 \vdash_A e_1:\tau? and \cdot \vdash_A v_0:\tau_0 then \Gamma_0 \vdash_A e_1[x_0 \leftarrow v_0]:\tau?
3717
                    • If (x_0:\mathcal{U}), \Gamma_0 \vdash_A e_1 : \tau? and \cdot \vdash_A v_0 : \mathcal{U} then \Gamma_0 \vdash_A e_1[x_0 \leftarrow v_0] : \tau?
3718
3719
                 PROOF. By induction on e_1.
3720
            1. CASE e_1 = x_2
3721
                1.1. SCASE x_0 = x_2
3722
                    1.1.1. QED
3723
3724
                         e_1[x_0 \leftarrow v_0] = v_0
3725
                1.2. SCASE x_0 \neq x_2
3726
                    1.2.1. QED
3727
                         e_1[x_0\!\leftarrow\!v_0]=e_1
            2. Case e_1 = i_0
3730
                2.1. QED
3731
                    e_1[x_0 \leftarrow v_0] = e_1
3732
            3. Case e_1 = \lambda x_2 . e_2
3733
3734
                3.1. SCASE x_0 = x_2
3735
                    3.1.1. QED
3736
                         by the induction hypothesis
3737
                3.2. SCASE x_0 \neq x_2
3738
3739
                    3.2.1. QED
3740
                         e_1[x_0\!\leftarrow\!v_0]=e_1
3741
            4. Case e_1 = \lambda(x_2 : \tau_2). e_2
3742
                4.1. SCASE x_0 = x_2
```

```
4.1.1. QED
3745
3746
                   by the induction hypothesis
3747
             4.2. SCASE x_0 \neq x_2
3748
                4.2.1. QED
3749
3750
                   e_1[x_0 \leftarrow v_0] = e_1
3751
         5. Case e_1 = \langle e_2, e_3 \rangle
3752
             5.1. QED
3753
                by the induction hypothesis
3754
3755
         6. CASE e_1 = app\{\tau?\} e_2 e_3
3756
            6.1. QED
3757
                by the induction hypothesis
3758
         7. CASE e_1 = unop\{\tau?\} e_2
3759
            7.1. QED
3760
3761
                by the induction hypothesis
3762
         8. CASE e_1 = binop\{\tau?\} e_2 e_3
3763
            8.1. QED
3764
                by the induction hypothesis
3765
3766
         9. CASE e_1 = \text{dyn } b_2 e_2
3767
             9.1. QED
3768
                by the induction hypothesis
3769
3770
         10. CASE e_1 = \text{stat } b_2 e_2
3771
             10.1. QED
3772
                by the induction hypothesis
3773
         11. CASE e_1 = \operatorname{trace}_{\mathbf{v}} \mathbf{\bar{b}}_2 v_2
3774
3775
             11.1. OED
3776
                by the induction hypothesis
3777
         12. CASE e_1 = \operatorname{trace} \overline{b_2} e_2
3778
             12.1. QED
3779
                by the induction hypothesis
3780
3781
3782
3783
             LEMMA 7.26 (\overline{\Vdash}_A-PROGRESS). If \cdot \vdash_A e_0 : \tau? and \cdot ; \ell_{\bullet} \ \overline{\vdash}_A e_0 then one of the following holds:
3784
               • e_0 \in (v)^{\overline{\ell}}
3785
3786
               • e_0 \in E[\mathsf{Err}]^\ell
3787
               • \exists e_1 \text{ such that } e_0 \rightarrow_A e_1
3788
3789
             PROOF. By case analysis of e_0.
3790
         By lemma 7.30, it suffices to consider the following cases.
3791
3792
         1. CASE e_0 \in (v)^{\overline{\ell}}
3793
             1.1. QED
3794
```

2. CASE $e_0 \in E[\mathsf{Err}]^\ell$

2019-10-03 17:26. Page 73 of 1-148.

```
2.1. QED
3797
3798
               3. CASE e_0 = E[app\{\tau_0\} ((v_0))^{\overline{\ell}_0} v_1]^{\ell_1}
3799
                    3.1. v_0 \in (\lambda(x:\tau).e) \cup (\text{mon } b \ v)
3800
                         by ⊢A inversion and canonical forms
3801
3802
                    3.2. SCASE v_0 = \lambda(x_2 : \tau_2). e_2
3803
                         3.2.1. QED
3804
                              e_0 \rhd_{\mathsf{A}} E[((e_2[x_2 \leftarrow (v_1)^{\ell_1 rev(\overline{\ell_0})}]))^{\overline{\ell_0}}]^{\ell_1}]
3805
                    3.3. SCASE v_0 = \text{mon} (\ell_2 \blacktriangleleft (\tau_2 \Rightarrow \tau_3) \blacktriangleleft \ell_3) (v_2)^{\ell_4}
                         3.3.1. LET b_3 = (\ell_2 \blacktriangleleft \tau_3 \blacktriangleleft \ell_3)
                                                and b_4 = (\ell_3 \blacktriangleleft \tau_2 \blacktriangleleft \ell_2)
                         3.3.2. QED
3810
                              e_0 \rhd_{A} E[((\text{dyn } b_3 (\text{app}\{\mathcal{U}\} v_2 (\text{stat } b_4 ((v_1))^{\ell_1 \ell_1 rev(\overline{\ell_0})}))^{\ell_4}))]^{\ell_1}]^{\ell_1}]
3811
3812
               4. CASE e_0 = E[app\{\mathcal{U}\} ((v_0))^{\overline{\ell}_0} v_1]^{\ell_1}
3813
                    4.1. SCASE v_0 = \operatorname{trace}_{V}^{?} \overline{b}_2 ((\lambda x_2, e_2))^{\overline{\ell}_3}
3814
                         4.1.1. Let v_2 = add\text{-}trace(rev(\overline{b}_2), ((v_1))^{\ell_1 rev(\overline{\ell}_0)rev(\overline{\ell}_3)})
3815
3816
3817
                              e_0 \blacktriangleright_{\mathsf{A}} E[(\mathsf{trace}\,\overline{b}_2\,(\!(e_2[x_2 \leftarrow v_1])\!)^{\overline{\ell}_3})^{\overline{\ell}_0}]^{\ell_1}]
3818
                    4.2. \text{ SCASE } v_0 = \operatorname{trace}_{\mathbf{v}}^2 \overline{b}_2 \, (\!\!(\mathsf{mon} \, (\ell_3 \blacktriangleleft (\tau_2 \Rightarrow \tau_3)^{\ell_4} \blacktriangleleft \ell_4) \, (v_2)^{\ell_5})\!\!)^{\overline{\ell}_6}
3819
                         4.2.1. LET b_7 = (\ell_3 \blacktriangleleft \tau_3 \blacktriangleleft \ell_4)
                                                and b_8 = (\ell_4 \blacktriangleleft \tau_2 \blacktriangleleft \ell_3)
3823
                                                and \tau_4 = forget(\tau_3)
3824
                         4.2.2. QED
3825
                              e_0 \blacktriangleright_A E[(\operatorname{trace} \overline{b_2} (\operatorname{stat} b_7 (\operatorname{app} \{ \tau_4 \} v_2 (\operatorname{dyn} b_8 ((v_2))^{last(\overline{\ell_6})}))^{\ell_3})]^{\ell_1})]^{\ell_1}]
3826
3827
                    4.3. SCASE v_0 \notin (\lambda x. e) \cup (\text{mon } b \ v)
3828
                         4.3.1. QED
3829
3830
                              e_0 \blacktriangleright_{\mathsf{A}} E[\mathsf{TagErr} \bullet]^{\ell_0}
3831
               5. CASE e_0 = E[unop\{\tau?\} ((v_0))^{\overline{\ell}_0}]^{\ell_1}
3832
                    5.1. QED
3833
                         by lemma 7.16 and lemma 7.33
3835
               6. Case e_0 = E[binop\{\tau?\} ((v_0))^{\overline{\ell}_0} ((v_1))^{\overline{\ell}_1}]^{\ell_2}
3836
                    6.1. QED
3837
                         by lemma 7.16 and lemma 7.33
3838
               7. CASE e_0 = E[\operatorname{dyn} b_0 ((v_1))^{\overline{\ell}_1}]^{\ell_2}
3839
3840
                    7.1. QED
3841
                         by lemma 7.16 and lemma 7.35
3842
               8. CASE e_0 = E[\text{stat } b_0 ((v_1))^{\ell_1}]^{\ell_2}
3843
                    8.1. QED
3844
3845
                         by lemma 7.16 and lemma 7.36
               9. CASE e_0 = E[\operatorname{trace} \overline{b_0} v_0]^{\ell_2}
3847
```

```
9.1. QED
3849
3850
                        e_0 \triangleright_{A} E[add-trace(\overline{b}_0, v_0)]^{\ell_2}
3851
3852
3853
3854
                    Lemma 7.27 (\mathbb{F}_A-preservation). If \cdot \vdash_A e_0 : \tau? and \cdot ; \ell_{\bullet} \ \mathbb{F}_A \ e_0 and e_0 \to_A e_1 \ then \cdot ; \ell_{\bullet} \ \mathbb{F}_A \ e_1
3855
3856
3857
3858
                    PROOF. By lemma 7.28 and lemma 7.29.
3860
3861
3862
                    Lemma 7.28. If \cdot \vdash_A e_0 : \tau_0 \text{ and } \cdot ; \ell_0 \ \overline{\vdash}_A e_0 \text{ and } e_0 \rhd_A e_1 \text{ then } \cdot ; \ell_0 \ \overline{\vdash}_A e_1
3863
3864
3865
3866
                    PROOF. By case analysis of \triangleright_{\Lambda}.
3867
               1. CASE \delta_A(unop, v_0) is defined
3868
                                 and (unop\{\tau_1\} v_0)^{\ell_0} \rhd_{\mathsf{A}} (\delta_A(unop, v_0))^{\ell_0}
3869
                    1.1. QED
3870
3871
                        by lemma 7.34
               2. CASE \delta_A(binop, v_0, v_1) is defined
3873
                                and (binop\{\tau_1\} v_0 v_1)^{\ell_0} \rhd_{\mathsf{A}} (\delta_A(binop, v_0, v_1))^{\ell_0}
                    2.1. QED
3875
3876
                        by lemma 7.34
              3877
3878
                    3.1. \overline{\ell}_0 = \ell_1 \cdots \ell_1
3879
3880
                        by inversion \overline{\mathbb{F}}_{A}
3881
                   3.2. \cdot; \ell_0 \Vdash_{\mathsf{A}} ((v_1))^{\ell_1 rev(\overline{\ell}_0)}
3882
                        by 3.1 and inversion \overline{\mathbb{H}}_A
3883
                    3.3. QED
3884
                        by lemma 7.40
                                                                                                   \frac{\overline{\cdot; \ell_1 \Vdash_{A} e_0[x_0 \leftarrow ((v_1))^{\ell_1 rev(\overline{\ell_0})}]}}{\cdot; \ell_1 \Vdash_{A} (e_0[x_0 \leftarrow ((v_1))^{\ell_1 rev(\overline{\ell_0})}])^{\overline{\ell_0}\ell_1}}
3888
3889
3890
              4. Case (\operatorname{app}\{\tau_0\} (\!(\operatorname{mon}(\ell_0 \blacktriangleleft (\tau_1 \Rightarrow \tau_2)^{\ell_1} \blacktriangleleft \ell_1) (v_0)^{\ell_2})\!)^{\overline{\ell}_3} v_1)^{\ell_4}
3891
3892
                                \rhd_{\mathsf{A}} \left( \mathsf{dyn} \left( \ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1 \right) \left( \mathsf{app} \{ \mathcal{U} \} \, v_0 \left( \mathsf{stat} \left( \ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0 \right) \left( \! \left( v_1 \right) \! \right)^{\! \ell_4 rev(\overline{\ell_3})} \right) \right)^{\! \ell_2} \overline{\ell_3} \ell_4
3893
3894
                    4.1. \ell_1 = \ell_2
3895
                             and \overline{\ell}_3 = \ell_4 \cdots \ell_4
3896
3897
                        by inversion \overline{\mathbb{F}}_{A}
                    4.2. QED
3900
              2019-10-03 17:26. Page 75 of 1-148.
```

```
by inversion \overline{\mathbb{F}}_{A}
3902
3903
                                                                                                                                                                                                                                                                                                                                    \cdot; \ell_0 \ \overline{\Vdash}_A \ v_1
3904
                                                                                                                                                                                                                                                                                                            \frac{1}{\cdot;\ell_0 \Vdash_{\mathsf{A}} (\!(v_1)\!)^{\ell_4 \mathit{rev}(\overline{\ell}_3)}}
3905
                                                                                                                                                               by inversion \overline{\mathbb{H}}_A
3906
                                                                                                                                                                           \cdot; \ell_1 \ \overline{\Vdash}_{\mathsf{A}} \ v_0 \qquad \qquad \cdot; \ell_1 \ \overline{\Vdash}_{\mathsf{A}} \ \mathsf{stat} \ (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \ (\!(v_1)\!)^{\ell_4 \mathit{rev}(\overline{\ell}_3)}
3907
                                                                                                                                                                                  \cdot ; \ell_1 \ \overline{\Vdash}_{\mathsf{A}} \ \overline{\mathsf{app}} \{ \mathcal{U} \} \ v_0 \ (\mathsf{stat} \ (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \ (\!(v_1)\!)^{\ell_4 \mathit{rev}(\overline{\ell_3})})
3908
                                                                                                                                                                             \cdot ; \ell_1 \ \overline{\Vdash}_{\mathsf{A}} \ (\mathsf{app} \{ \mathcal{U} \} \ v_0 \ (\mathsf{stat} \ (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \ (\!(v_1)\!)^{\ell_4 \mathit{rev}(\overline{\ell_3})}))^{\ell_2}
                                                                                                                                         \overrightarrow{\cdot}; \ell_0 \ \overline{\vdash}_{\mathsf{A}} \ \mathsf{dyn} \ (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ (\mathsf{app}\{\overline{\mathcal{U}}\} \ v_0 \ (\mathsf{stat} \ (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \ (\!(v_1)\!)^{\ell_4 \mathit{rev}(\overline{\ell_3})}))^{\ell_2} 
3912
3913
                                                                                                                             \cdot ; \ell_0 \ \overline{\Vdash}_{\mathsf{A}} \ (\mathsf{dyn} \ (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ (\mathsf{app} \{\mathcal{U}\} \ v_0 \ (\mathsf{stat} \ (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \ (\!(v_1)\!)^{\ell_4 \mathit{rev}(\overline{\ell_3})}))^{\ell_2} \ \overline{\ell_3 \ell_4}
3914
3915
                                5. CASE (\operatorname{dyn}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) ((v_0))^{\overline{\ell}_2})^{\ell_3} \rhd_{\Delta} e_2
3916
3917
                                             by lemma 7.37
3918
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              3919
3920
3921
3922
                                             LEMMA 7.29. If \cdot \vdash_A e_0 : \mathcal{U} \text{ and } \cdot ; \ell_0 \ \overline{\vdash}_A e_0 \text{ and } e_0 \blacktriangleright_A e_1 \text{ then } \cdot ; \ell_0 \ \overline{\vdash}_A e_1
3927
3928
                                             PROOF. By case analysis of \triangleright_{A}.
3929
                                  1. CASE v_0 \notin \text{mon}(\ell \blacktriangleleft \tau \times \tau \blacktriangleleft \ell) v
3930
3931
                                                                        and \delta_A(unop, v_0) is not defined
3932
                                                                         and (unop\{\mathcal{U}\} v_0)^{\ell_0} \blacktriangleright_{\mathsf{A}} (\mathsf{TagErr} \bullet)^{\ell_0}
3933
3934
                                  2. CASE \delta_A(unop, v_0) is defined
3935
                                                                        and (unop\{\mathcal{U}\} v_0)^{\ell_0} \blacktriangleright_{\mathsf{A}} (\delta_A(unop, v_0))^{\ell_0}
 3936
                                             2.1. QED
                                                      by lemma 7.34
                               3. CASE (fst{$\mathcal{U}$} (\text{trace}_{\mathbf{v}}^{?} \overline{b}_{0} (\text{mon} (\ell_{1} \left(\tau_{0} \times \tau_{1})^{\ell_{2}} \left(\ell_{2}) (\varbnu_{1})^{\ell_{3}})^{\overline{\ell_{4}}} \) \\
\text{(trace } \overline{b}_{0} (\text{stat} (\ell_{1} \left(\tau_{0} \left(\ell_{2}) (\text{fst} \{\tau_{0}\} \varbnu_{1})^{\ell_{3}})^{\overline{\ell_{4}}} \) \\
\text{(fst} \(\frac{\overline{\ell_{5}}}{\overline{\ell_{5}}} \) (\text{fst} \(\text{(\text{$\ell_{1}$} \left(\text{$\ell_{2}$}) (\text{fst} \{\tau_{0}\} \varbnu_{1})^{\ell_{3}}} \) \\
\text{(fst} \(\frac{\overline{\ell_{5}}}{\overline{\ell_{5}}} \) (\text{fst} \(\text{(\text{$\ell_{1}$} \varphi_{1})^{\ell_{3}}} \) \\
\text{(fst} \(\frac{\overline{\ell_{5}}}{\overline{\ell_{5}}} \) (\text{fst} \(\text{(\text{$\ell_{5}$} \varha_{1})^{\ell_{3}}} \) \\
\text{(fst} \(\text{(\text{$\ell_{5}$} \varha_{1})^{\ell_{3}}} \) (\text{fst} \(\text{(\text{$\ell_{5}$} \varha_{1})^{\ell_{3}}} \) \\
\text{(fst} \(\text{(\text{$\ell_{5}$} \varha_{1})^{\ell_{3}}} \) (\text{fst} \(\text{(\text{$\ell_{5}$} \varha_{1})^{\ell_{3}}} \) (\text{fst} \(\text{(\text{$\ell_{5}$} \varha_{1})^{\ell_{3}}} \) \\
\text{(fst} \(\text{(\text{$\ell_{5}$} \varha_{1})^{\ell_{3}}} \varha_{1} \varha_{2} \varha_{1})^{\ell_{3}}} \) (\text{(\text{$\ell_{5}$} \varha_{1})^{\ell_{3}}} \) \\
\text{(fst} \(\text{(\text{$\ell_{5}$} \varha_{1})^{\ell_{3}} \varha_{2} \varha_{2} \varha_{1})^{\ell_{3}}} \) (\text{(\text{$\ell_{5}$} \varha_{1})^{\ell_{3}}} \varha_{2} \
3940
3941
3942
3943
                                             3.1. \overline{\ell}_5 = \ell_6 \cdots \ell_6
3944
                                                                 and \bar{b}_0 \simeq \bar{\ell}_4
3945
                                                                 and last(\overline{\ell}_4) = \ell_1
3946
3947
                                                                 and \ell_2 = \ell_3
3948
                                                       by inversion \overline{\mathbb{H}}_{A}
3949
                                             3.2. QED
```

```
by inversion \overline{\mathbb{F}}_{A}
3954
3955
                                                                                                                                                                                            \cdot; \ell_2 \overline{\Vdash}_{\mathsf{A}} v_1
3956
                                                                                                                                                                                 \cdot; \ell_2 \overline{\Vdash}_{\mathsf{A}} \operatorname{fst}\{\tau_0\} v_1
3957
3958
                                                                                                                                                                             \overline{\cdot;\ell_2\; \overline{\Vdash}_{\mathsf{A}}\; (\mathsf{fst}\{\tau_0\}\, v_1)^{\ell_3}}
3959
                                                                                                                                        \frac{}{\cdot; last(\overline{\ell}_4) \, \overline{\Vdash}_{\mathsf{A}} \, \operatorname{stat} \, (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) \, (\operatorname{fst}\{\tau_0\} \, \upsilon_1)^{\ell_3}}
3960
3961
                                                                                                                               \overline{ \cdot ; \ell_6 \Vdash_{\mathsf{A}} \mathsf{trace} \, \overline{b_0} \, (\!\! (\mathsf{stat} \, (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) \, (\mathsf{fst} \{\tau_0\} \, v_1)^{\ell_3}) \!\! )^{\overline{\ell_4}} } 
                                                                                                                        \cdot; \ell_6 \Vdash_{\mathsf{A}} (\mathsf{trace}\,\overline{b}_0\,(\!(\mathsf{stat}\,(\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2)\,(\mathsf{fst}\{\tau_0\}\,v_1)^{\ell_3})^{\overline{\ell}_4})^{\overline{\ell}_5\ell_6}
 3964
3965
                      4. CASE (\operatorname{snd}\{\mathcal{U}\} (\operatorname{trace}_{\mathbf{v}}^{?} \overline{b_0} (\operatorname{mon} (\ell_1 \blacktriangleleft (\tau_0 \times \tau_1)^{\ell_2} \blacktriangleleft \ell_2) (v_1)^{\ell_3}))^{\overline{\ell_4}}))^{\overline{\ell_5}})^{\ell_6} \blacktriangleright_{\mathbf{A}}
3966
3967
                                                  (\operatorname{trace} \overline{b_0} \left( \operatorname{stat} \left( \ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2 \right) \left( \operatorname{snd} \left\{ \tau_1 \right\} \upsilon_1 \right)^{\ell_3} \right)^{\overline{\ell_4}} \overline{\ell_5 \ell_6}
3968
3969
                               4.1. QED
3970
                                      similar to fst
3971
                       5. CASE \delta_A(binop, v_0, v_1) is not defined
3972
                                                  and (binop\{\mathcal{U}\} v_0 v_1)^{\ell_0} \blacktriangleright_{\Delta} (TagErr \bullet)^{\ell_0}
3973
3974
                               5.1. QED
3975
                       6. CASE \delta_A(binop, v_0, v_1) is defined
3976
                                                  and (binop\{\mathcal{U}\}\ v_0\ v_1)^{\ell_0} \blacktriangleright_{\mathsf{A}}\ (\delta_A(binop,v_0,v_1))^{\ell_0}
3977
3978
                               6.1. QED
3979
                                      by lemma 7.34
3980
                       7. Case (app{\mathcal{U}} ((trace^?_v \overline{b}_0 ((\lambda x_0. e_0))^{\overline{\ell}_1}))^{\overline{\ell}_2} v_1) \blacktriangleright_A
3981
3982
                                                 (\operatorname{trace} \overline{b_0} ((e_0[x_0 \leftarrow add - \operatorname{trace} (\operatorname{rev}(\overline{b_0}), ((v_1))^{\ell_3 \operatorname{rev}(\overline{\ell_2}) \operatorname{rev}(\overline{\ell_1})})])^{\overline{\ell_1}})^{\overline{\ell_2}\ell_3})
3983
3984
                               7.1. \overline{\ell}_2 = \ell_3 \cdots \ell_3
3985
                                            and \overline{b}_0 \simeq \overline{\ell}_1
3986
                                            and \cdot; last(\overline{\ell}_1) \Vdash_A \lambda x_0. e_0
3987
                              7.2. :: last(\overline{\ell}_1) \ \overline{\Vdash}_A \ add-trace(rev(\overline{b}_0), ((v_1))^{\ell_3 rev(\overline{\ell}_2) rev(\overline{\ell}_1)})
                               7.3. QED
3991
                                                                                                                                                                                         by lemma 7.40
3992
                                                                                                             \frac{}{\cdot; last(\overline{\ell}_1) \Vdash_{\mathsf{A}} e_0[x_0 \leftarrow add\text{-}trace(rev(\overline{b}_0), ((v_1))^{\ell_3 rev(\overline{\ell}_2)rev(\overline{\ell}_1)})]}
3993
3994
                                                                                                   \frac{}{\cdot ; \ell_3 \Vdash_{\mathsf{A}} \mathsf{trace} \, \overline{b}_0 \, (\!(e_0[x_0 \leftarrow \mathit{add-trace} \, (\mathit{rev}(\overline{b}_0), (\!(v_1)\!)^{\ell_3 \mathit{rev}(\overline{\ell}_2) \mathit{rev}(\overline{\ell}_1)})]))^{\overline{\ell}_1}}
3995
3996
                                                                                            \cdot; \ell_3 \ \overline{\Vdash}_{\mathsf{A}} \ (\mathsf{trace} \ \overline{b_0} \ (\!(e_0[x_0 \leftarrow add\text{-}trace (rev(\overline{b_0}), (\!(v_1)\!)^{\ell_3 rev(\overline{\ell_2})} rev(\overline{\ell_1}))]) \!)^{\overline{\ell_1} \ \overline{\ell_2} \ell_3}
3997
3998
                       8. Case (\operatorname{app}{\mathcal{U}}) (\operatorname{trace}_{\mathbf{v}}^{?} \overline{b_0} (\operatorname{mon} (\ell_1 \blacktriangleleft (\tau_0 \Rightarrow \tau_1)^{\ell_2} \blacktriangleleft \ell_2) (v_0)^{\ell_3}))^{\overline{\ell_4}}))^{\overline{\ell_4}})^{\overline{\ell_5}} v_1) \blacktriangleright_{\mathbf{A}}
3999
4000
                                                  (\operatorname{trace} \overline{b_0} \left( \operatorname{stat} \left( \ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2 \right) \left( \operatorname{app} \left\{ \tau_1 \right\} v_0 \left( \operatorname{dyn} \left( \ell_2 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1 \right) \left( v_2 \right)^{last(\overline{\ell_4})} \right) \right)^{\ell_3} \right)^{u_3} \right)
4001
4002
4003
```

by inversion $\overline{\mathbb{F}}_{A}$

```
8.1. \overline{\ell}_5 = \ell_6 \cdots \ell_6
4005
4006
                                     and \overline{b}_0 \simeq \overline{\ell}_4
4007
                                     and \ell_1 = last(\overline{\ell}_4)
4008
                                     and \ell_2 = \ell_3
4009
                                by inversion \overline{\mathbb{H}}_A
4010
4011
                          8.2. QED
4012
4013

\frac{\neg \text{inversion } \overline{\Vdash}_{A}}{\neg \cdot ; \ell_{2} \ \overline{\Vdash}_{A} \ v_{0}} \qquad \frac{\neg \cdot ; \ell_{1} \ \overline{\Vdash}_{A} \ v_{2}}{\neg \cdot ; \ell_{2} \ \overline{\Vdash}_{A} \ \text{dyn} \left(\ell_{2} \blacktriangleleft \tau_{0} \blacktriangleleft \ell_{1}\right) \left(v_{2}\right)^{last(\overline{\ell}_{4})}}

                                                                                                by inversion \overline{\mathbb{H}}_A
4016
4017
                                                                                                          \cdot; \ell_2 \Vdash_{\mathsf{A}} \mathsf{app}\{\tau_1\} v_0 \left(\mathsf{dyn} \left(\ell_2 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) (v_2)^{last(\overline{\ell}_4)}\right)
4018
4019
                                                                           \cdot ; last(\overline{\ell}_4) \ \overline{\Vdash}_{A} \ stat(\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2) \ (app\{\tau_1\} \ v_0 \ (dyn \ (\ell_2 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ (v_2)^{last(\overline{\ell}_4)}))^{\ell_3}
4020
4021
                                                                 \cdot ; \ell_6 \ \overline{\Vdash}_{\mathsf{A}} \ \mathsf{trace} \ \overline{b_0} \ (\!\!(\mathsf{stat} \ (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2) \ (\mathsf{app} \{\tau_1\} \ v_0 \ (\mathsf{dyn} \ (\ell_2 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ (v_2)^{\mathit{last}} \overline{(\overline{\ell_4})}))^{\ell_3})\!\!)^{\ell_3})
4022
4023
                                                            \overline{ \vdots_{\mathsf{A}} } \text{ (trace } \overline{b_0} \text{ ((stat } (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2) \text{ (app} \{\tau_1\} \ v_0 \text{ (dyn } (\ell_2 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ (v_2)^{last(\overline{\ell_4})}))^{\ell_3} )) ) 
4024
4025
                  9. Case (stat (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) ((v_0))^{\ell_3}^{\ell_0} \blacktriangleright_{\mathsf{A}} e_2
4026
4027
                          9.1. QED
                                by lemma 7.38
4029
                    10. CASE \left(\operatorname{trace} \overline{b}_0 \, v_0\right)^{\ell_1}
4030
                                             \blacktriangleright_{\mathsf{A}} \left( add\text{-}trace(\overline{b}_0, v_0) \right)^{\ell_1}
4031
4032
                          10.1. QED
4033
                               by lemma 7.39
4034
4035
4036
4037
                          LEMMA 7.30. If \cdot \vdash_A e_0 : \tau? and \cdot ; \ell_0 \Vdash_A e_0 then either:
4038
                               • e_0 \in ((v))^{\overline{\ell}}
4039
                               • e_0 = E_0[\mathsf{app}\{\tau?\}(v_0)^{\overline{\ell}_0}(v_1)^{\ell_1}]^{\ell_2}
                               • e_0 = E_0[unop\{\tau?\} ((v_0))^{\overline{\ell}_0}] \ell_1
                              • e_0 = E_0[binop\{\tau?\} ((v_0))^{\overline{\ell}_0} ((v_1))^{\overline{\ell}_1}]^{\ell_2}
                              • e_0 = E_0[\text{dyn } b_1 \ ((v_1))^{\overline{\ell_0}}]^{\ell_1}
4044
                               • e_0 = E_0[\operatorname{stat} b_1 ((v_1))^{\overline{\ell}_0}]^{\ell_1}
4045
4046
                               • e_0 = E_0[\text{stat } b_1 ((v_1))^{\overline{\ell}_0}]^{\ell_1}
4047
                               • e_0 = E_0[\operatorname{trace} \overline{b}_1 ((v_1))^{\overline{\ell}_0}]^{\ell_1}
4048
                               • e_0 = E_0[\operatorname{Err}]^{\ell_0}
4049
4050
                           PROOF. By induction on the structure of e_0.
4051
4052
                    1. CASE e_0 = x_0
4053
                          1.1. Contradiction:
4054
```

 $\cdot; \ell_0 \ \overline{\Vdash}_{\mathsf{A}} \ e_0$

4055

2019-10-03 17:26. Page 78 of 1-148.

```
2. Case e_0 \in ((v))^{\overline{\ell}}
4057
4058
               2.1. QED
4059
          3. Case e_0 = \langle e_1, e_2 \rangle
4060
               3.1. \cdot \vdash_A e_1 : \tau? and \cdot \vdash_A e_2 : \tau?
4061
4062
                  by inversion ⊦<sub>A</sub>
4063
               3.2. \cdot; \ell_0 \ \overline{\Vdash}_A \ e_1 \ \text{and} \ \cdot; \ell_0 \ \overline{\Vdash}_A \ e_2
4064
                  by inversion \overline{\mathbb{F}}_{A}
4065
              3.3. SCASE e_1 \notin (v)^{\overline{\ell}}
4066
                  3.3.1. QED
4068
                      by the induction hypothesis
4069
               3.4. SCASE e_1 \in (v)^{\overline{\ell}} and e_2 \notin (v)^{\overline{\ell}}
4070
                  3.4.1. QED
4071
                      by the induction hypothesis
4072
4073
               3.5. SCASE e_1 \in (v)^{\overline{\ell}} and e_2 \in (v)^{\overline{\ell}}
4074
                  3.5.1. QED
4075
                      e_0 \in v
4076
4077
           4. CASE e_0 = app\{\tau?\} e_1 e_2
4078
               4.1. QED
4079
                  by the induction hypothesis
           5. CASE e_0 = unop\{\tau?\} e_1
4081
4082
               5.1. QED
4083
                  by the induction hypothesis
4084
           6. CASE e_0 = binop\{\tau?\} e_1 e_2
4085
               6.1. QED
4086
4087
                  by the induction hypothesis
4088
          7. CASE e_0 = \text{dyn} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (e_1)^{\ell_1}
4089
              7.1. \cdot; \ell_1 \ \overline{\Vdash}_A \ e_1
4090
                  by inversion \overline{\mathbb{F}}_{A}
4091
4092
               7.2. QED
                  by the induction hypothesis
4094
          8. CASE e_0 = \text{stat } b_1 e_1
4095
               8.1. QED
4096
                  by the induction hypothesis
4097
4098
          9. CASE e_0 = \operatorname{trace} \overline{b}_1 ((e_1))^{\overline{\ell}_2}
4099
              9.1. QED
4100
                  by the induction hypothesis
4101
4102
4103
               LEMMA 7.31. If \cdot; \ell_0 \Vdash_A E_0[e_0] then \exists \ell_1 \text{ such that } \cdot; \ell_1 \Vdash_A e_0
4104
4105
               PROOF. By induction on the structure of E_0.
4106
4107
           1. E_0 = []
```

2019-10-03 17:26. Page 79 of 1-148.

2019-10-03 17:26. Page 80 of 1-148.

```
4109
                                      1.1. QED
4110
                            2. E_0 = \langle E_1, e_2 \rangle
4111
                                      2.1. QED
4112
                                                by the induction hypothesis
4113
4114
                            3. E_0 = \langle e_1, E_2 \rangle
4115
                                      3.1. QED
4116
                                                by the induction hypothesis
4117
                            4. E_0 = unop\{\tau?\} E_1
4118
4119
                                       4.1. QED
4120
                                                by the induction hypothesis
4121
                             5. E_0 = binop\{\tau?\} E_1 e_2
4122
                                       5.1. QED
4123
                                                by the induction hypothesis
4124
4125
                             6. E_0 = binop\{\tau?\} e_1 E_2
4126
                                      6.1. QED
4127
                                                by the induction hypothesis
4128
                            7. E_0 = \text{dyn} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) (E_1)^{\ell_3}
4129
4130
                                      7.1. \cdot; \ell_2 \overline{\Vdash}_A E_1[e_0]
4131
                                       7.2. QED
4132
                                                by the induction hypothesis
4133
4134
                             8. E_0 = \text{stat} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) (E_1)^{\ell_3}
4135
                                      8.1. QED
4136
                                                by the induction hypothesis
4137
                             9. E_0 = (E_1)^{\ell_0}
4138
4139
                                      9.1. QED
4140
                                                by the induction hypothesis
4141
                             10. E_0 = \operatorname{trace} \bar{b_1} ((E_1))^{\bar{\ell}_1}
4142
                                       10.1. QED
4143
4144
                                                by the induction hypothesis
4145
4146
4147
                                        \text{Lemma 7.32 } (\overline{\Vdash}_{\!\!\!A} \text{ replacement}). \  \, \textit{If} : ; \ell_0 \ \overline{\Vdash}_{\!\!\!A} \ \textit{E}_0[e_0] \ \textit{and the derivation contains a proof of} : ; \ell_1 \ \overline{\Vdash}_{\!\!\!A} \ e_0 \ \textit{and} : ; \ell_1 \ \overline{\Vdash}_{\!\!\!A} \ e_1 \ \textit{and} : ; \ell_2 \ \overline{\Vdash}_{\!\!\!A} \ e_2 \ \textit{and} : ; \ell_3 \ \overline{\Vdash}_{\!\!\!A} \ e_3 \ \textit{and} : ; \ell_4 \ \overline{\Vdash}_{\!\!\!A} \ e_4 \ \textit{and} : ; \ell_5 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 \ \textit{and} : ; \ell_6 \ \overline{\Vdash}_{\!\!\!A} \ e_5 
4148
                             then L_0; \ell_0 \Vdash_A E_0[e_1]
4149
4150
                                       PROOF. By induction on the structure of E_0.
4151
                             1. E_0 = []
4152
                                      1.1. QED
4153
4154
                            2. E_0 = \langle E_1, e_2 \rangle
4155
                                      2.1. QED
4156
                                                 by the induction hypothesis
4157
                            3. E_0 = \langle e_1, E_2 \rangle
4158
4159
                                      3.1. QED
4160
```

```
by the induction hypothesis
4161
4162
              4. E_0 = unop\{\tau?\} E_1
4163
                  4.1. QED
4164
                       by the induction hypothesis
4165
4166
              5. E_0 = binop\{\tau?\} E_1 e_2
4167
                  5.1. QED
4168
                       by the induction hypothesis
4169
              6. E_0 = binop\{\tau?\} e_1 E_2
4170
4171
                  6.1. QED
4172
                       by the induction hypothesis
4173
              7. E_0 = \text{dyn} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) (E_1)^{\ell_3}
4174
                  7.1. \cdot; \ell_2 \overline{\Vdash}_A E_1[e_0]
4175
                  7.2. QED
4176
4177
                       by the induction hypothesis
4178
              8. E_0 = \text{stat} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) (E_1)^{\ell_3}
4179
                  8.1. QED
4180
                       by the induction hypothesis
4181
4182
              9. E_0 = (E_1)^{\ell_0}
4183
                  9.1. QED
4184
                       by the induction hypothesis
4185
              10. E_0 = \operatorname{trace} \bar{b}_1 ((E_1))^{\bar{\ell}_1}
4186
4187
                  10.1. QED
4188
                       by the induction hypothesis
4189
4190
4191
4192
                  Lemma 7.33 (\delta_A label progress).
4193
4194
                      • If \cdot \vdash_{\mathsf{A}} unop\{\tau_1\} \ v_0 : \tau_0 \ and \ \cdot; \ell_0 \ \overline{\vdash}_{\mathsf{A}} \ unop\{\tau_1\} \ v_0 \ and \ (unop\{\tau_1\} \ v_0)^{\ell_0} \ \triangleright_{\!_{\mathsf{A}}} (e_1)^{\ell_0}.
4195
                      • if \cdot \vdash_{\mathsf{A}} binop\{\tau_1\} \ v_0 \ v_1 : \tau_0 \ and \ :; \ell_0 \ \overline{\vdash_{\mathsf{A}}} \ binop\{\tau_1\} \ v_0 \ v_1 \ and \ (binop\{\tau_1\} \ v_0 \ v_1)^{\ell_0} \rhd_{\mathsf{A}} \ (e_2)^{\ell_0}.
4196
                      • If \cdot \vdash_{\mathsf{A}} unop\{\mathcal{U}\} \ v_0 : \mathcal{U} \ and \ \cdot ; \ell_0 \ \overline{\vdash}_{\mathsf{A}} \ unop\{\mathcal{U}\} \ v_0 \ then \ (unop\{\mathcal{U}\} \ v_0)^{\ell_0} \blacktriangleright_{\mathsf{A}} (e_1)^{\ell_0}.
4197
                      • if \cdot \vdash_{\mathsf{A}} binop\{\mathcal{U}\} \ v_0 \ v_1 : \mathcal{U} \ and \ \cdot; \ell_0 \ \overline{\vdash}_{\mathsf{A}} \ binop\{\mathcal{U}\} \ v_0 \ v_1 \ then \ (binop\{\mathcal{U}\} \ v_0 \ v_1)^{\ell_0} \blacktriangleright_{\mathsf{A}} (e_2)^{\ell_0}.
4198
4199
4200
                   PROOF. By case analysis of \delta_A, \vdash_A, \overline{\vdash}_A, and \blacktriangleright_{\vartriangle}.
4201
              1. CASE \cdot \vdash_A unop\{\tau_1\} v_0 : \tau_0
4202
                  1.1. v_0 \in ((\!(\langle v, v \rangle)\!)^{\overline{\ell}}) \cup ((\!(\operatorname{mon}(\ell \blacktriangleleft (\tau \times \tau)^{\ell} \blacktriangleleft \ell) v)\!)^{\overline{\ell}})
4203
4204
                       by ⊢A inversion and canonical forms
4205
                  1.2. SCASE v_0 = (\langle v_1, v_2 \rangle)^{\overline{\ell}_0}
```

1.3.1. QED
2019-10-03 17:26. Page 81 of 1–148.

 $(unop\{\tau_1\}\ v_0)^{\ell_0} \rhd_{\Lambda} (\delta_A(unop,v_0))^{\ell_0}$

1.3. scase $v_0 = (\!(\operatorname{mon}\,(\ell_1 \blacktriangleleft (\tau_1 \times \tau_2)^{\ell_2} \blacktriangleleft \ell_2) \, v_1)\!)^{\overline{\ell}_3}$

1.2.1. QED

4206

4207

4208

4209 4210

```
(\operatorname{fst}\{\tau_0\}\,v_0)^{\ell_0} \,\rhd_{\mathsf{A}} \, (\!(\operatorname{\mathsf{dyn}}\,(\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2)\,(\operatorname{\mathsf{fst}}\{\mathcal{U}\}\,v_1))\!)^{\overline{\ell}_3\ell_1}
4213
4214
                                  (and similarly for snd)
4215
                2. CASE \cdot \vdash_A binop\{\tau_1\} \upsilon_0 \upsilon_1 : \tau_0
4216
                      2.1. v_0 \in ((i))^{\overline{\ell}} and v_1 \in ((i))^{\overline{\ell}}
4217
                            by ⊢A inversion and canonical forms
4218
4219
4220
                            (\mathit{binop}\{\tau_1\}\ v_0\ v_1)^{\ell_0}\ \rhd_{\!_{\mathbf{A}}}\ (\delta_A(\mathit{binop},v_0,v_1))^{\ell_0}
4221
                3. CASE \cdot \vdash_A unop\{\mathcal{U}\} v_0 : \mathcal{U}
                      3.1. SCASE v_0 \in \operatorname{trace}_{v}^{?} \overline{b} ((\operatorname{mon} b(v)^{\ell}))^{\overline{\ell}}
4224
                                  by definition 
ightharpoonup_A
4226
                      3.2. SCASE v_0 \in \operatorname{trace}_{v}^{?} \overline{b} ((\langle v, v \rangle))^{\overline{\ell}}
4227
4228
                            3.2.1. QED
4229
                                 (unop\{\mathcal{U}\}\ v_0)^{\ell_0} \blacktriangleright_A (\delta_A(unop, v_0))^{\ell_0}
4230
                      3.3. SCASE rem-trace(v_0) \notin \langle v, v \rangle \cup (\text{mon } b(v)^{\ell})
4231
4232
4233
                                 (unop\{\mathcal{U}\} v_0)^{\ell_0} \blacktriangleright_{A} (TagErr \bullet)^{\ell_0}
4234
                 4. CASE \cdot \vdash_{\mathsf{A}} binop\{\mathcal{U}\} v_0 v_1 : \mathcal{U}
4235
                            by definition \triangleright_{\Delta}
                                                                                                                                                                                                                                                                                                 4239
4240
4241
4242
                       Lemma 7.34 (\delta_A label preservation).
4243
4244
                          • If \cdot; \ell_0 \Vdash_A unop\{\tau?\} v_0 and (unop\{\tau?\} v_0)^{\ell_0} (\triangleright_A \cup \blacktriangleright_A) (e_1)^{\ell_0} then \cdot; \ell_0 \Vdash_A e_1.
4245
                          • If \cdot; \ell_0 \Vdash_A binop\{\tau?\} v_0 v_1 and (binop\{\tau?\} v_0 v_1)^{\ell_0} (\triangleright_A \cup \blacktriangleright_A) (e_1)^{\ell_0} then \cdot; \ell_0 \Vdash_A e_1.
4246
4247
                      Proof. By case analysis of (\triangleright_A \cup \blacktriangleright_A).
                1. (\operatorname{fst}\{\tau_0\} ((\langle v_1, v_2 \rangle))^{\overline{\ell}_1})^{\ell_0} \triangleright_{A} (((v_1))^{\overline{\ell}_1})^{\ell_0}
4251
                      1.1. \cdot; \ell_0 \Vdash_{\mathsf{A}} v_0
4252
4253
                                and \overline{\ell}_1 = \ell_0 \cdots \ell_0
4254
                           by inversion \mathbb{F}_{A}
4255
4256
                2. (\operatorname{fst}\{\tau_0\} ((\operatorname{mon} (\ell_1 \blacktriangleleft (\tau_1 \times \tau_2)^{\ell_2} \blacktriangleleft \ell_2) (\upsilon_1)^{\ell_2}))^{\overline{\ell}_3})^{\ell_0} \triangleright_{A} (\operatorname{dyn} (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) (\operatorname{fst}\{\mathcal{U}\} \upsilon_0)^{\ell_2})^{\overline{\ell}_3 \ell_0}
4257
4258
                      2.1. \overline{\ell}_3 = \ell_0 \cdots \ell_0
4259
                                and \ell_0 = \ell_1
4260
4261
                           by inversion \overline{\mathbb{F}}_{A}
                      2.2. QED
```

```
by inversion \overline{\mathbb{H}}_{A}
4266
4267
                                                                                                                                                                                             \cdot; \ell_0 \ \overline{\Vdash}_{\mathsf{A}} \ v_0
4268
                                                                                                                                                                                   \overline{\cdot;\ell_0\; \overline{\Vdash}_{\!\mathsf{A}}\; \mathsf{fst}\{\mathcal{U}\}\, v_0}
4269
4270
                                                                                                                                                 \overline{\cdot; \ell_0 \Vdash_{\mathsf{A}} \mathsf{dyn} (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) (\mathsf{fst} \{\mathcal{U}\} v_0)^{\ell_2}}
4271
                                                                                                                                           \frac{}{\cdot ; \ell_0 \Vdash_{\mathsf{A}} (\mathsf{dyn} \, (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) \, (\mathsf{fst} \{\mathcal{U}\} \, v_0)^{\ell_2})^{\overline{\ell}_3 \ell_0}}
4272
4273
                      3. (\operatorname{fst}\{\mathcal{U}\}((\operatorname{trace}_{\mathbf{V}}^{2}\overline{b}_{0}((\langle v_{1}, v_{2}\rangle))^{\overline{\ell}_{1}}))^{\overline{\ell}_{2}})^{b_{\Delta}} (add\operatorname{-trace}(\overline{b}_{0}, ((v_{1}))^{\overline{\ell}_{1}}))^{\overline{\ell}_{2}\ell_{0}})^{b_{\Delta}})^{b_{\Delta}}
4274
4275
                               3.1. \overline{\ell}_2 = \ell_0 \cdots \ell_0
4276
                                             and \overline{b}_0 \simeq \overline{\ell}_1
4277
                                             and : last(\overline{\ell}_1) \overline{\mathbb{H}}_A v_1
4278
4279
                                      by inversion \overline{\mathbb{H}}_{A}
4280
                               3.2. QED
4281
                                      by lemma 7.39
4282
                      4. (\operatorname{fst}\{\mathcal{U}\} ((\operatorname{trace}_{\mathbf{v}}^{?} \overline{b_0} ((\operatorname{mon} (\ell_1 \blacktriangleleft (\tau_1 \times \tau_2)^{\ell_2} \blacktriangleleft \ell_2) (v_1)^{\ell_3}))^{\overline{\ell_4}}))^{\overline{\ell_5}})^{\ell_6} 
4283
4284
                               (\operatorname{trace} \overline{b_0} \, (\!\! (\operatorname{stat} \, (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2) \, (\operatorname{fst} \{ \mathit{forget}(\tau_1) \} \, v_1)^{\ell_3})^{\overline{\ell_4}} )^{\overline{\ell_5} \ell_0}
4285
4286
                               4.1. \overline{\ell}_5 = \ell_0 \cdots \ell_0
4287
                                             and \overline{b}_0 \simeq \overline{\ell}_4
4289
                                             and last(\overline{\ell}_4) = \ell_1
4290
                                             and \cdot; \ell_2 \overline{\Vdash}_A v_1
4291
                                      by inversion \overline{\mathbb{H}}_{A}
4292
4293
                               4.2. QED
4294
4295
                                                                                                                                                                                    by inversion \mathbb{F}_{A}
4296
                                                                                                                                                                                            \cdot; \ell_0 \Vdash_{\mathsf{A}} v_1
4297
4298
                                                                                                                                                                      \overline{\cdot; \ell_0 \Vdash_{\mathsf{A}} \mathsf{fst}\{forget(\tau_1)\} v_1}
4299
                                                                                                                                     \overline{\cdot ; \ell_0 \Vdash_{\mathsf{A}} \mathsf{stat} \left( \ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2 \right) \left( \mathsf{fst} \{ \mathit{forget} \left( \tau_1 \right) \} \, v_1 \right)^{\ell_3}}
4300
4301
                                                                                                                   \overline{\cdot ; \ell_0 \Vdash_{\mathsf{A}} \mathsf{trace} \, \overline{b}_0 \, (\!\! \! \! (\mathsf{stat} \, (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2) \, (\mathsf{fst} \{ \mathit{forget} \, (\tau_1) \} \, \upsilon_1)^{\ell_3})^{\overline{\ell}_4}}
4302
4303
                                                                                                            \overline{\vdots}_{\mathsf{A}} (\operatorname{trace} \overline{b_0} ( \operatorname{stat} (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_2) (\operatorname{fst} \{ \operatorname{forget}(\tau_1) \} v_1)^{\ell_3} )^{\overline{\ell_4}} \overline{\ell_5 \ell_0} 
4304
                      5. (\operatorname{snd}\{\tau?\} v_0)^{\ell_0} (\rhd_{\mathsf{A}} \cup \blacktriangleright_{\mathsf{A}}) (\!(e_2)\!)^{\ell_0}
4305
4306
4307
                                       similar to fst cases
4308
                      6. (\operatorname{sum}\{\tau?\} v_0 v_1)^{\ell_0} (\triangleright_{\mathsf{A}} \cup \blacktriangleright_{\mathsf{A}}) (i_2)^{\ell_0}
4309
4310
4311
                      7. (\operatorname{quotient}\{\tau?\} v_0 v_1)^{\ell_0} (\triangleright_{\mathsf{A}} \cup \blacktriangleright_{\mathsf{A}}) (\operatorname{DivErr})^{\ell_0}
4312
4313
                      8. (quotient\{\tau?\} ((i_1))^{\ell_1} ((i_2))^{\ell_2} (\triangleright_{\Delta} \cup \blacktriangleright_{\Delta}) (\lfloor i_1/i_2 \rfloor)^{\ell_0}
4314
4315
4316
```

2019-10-03 17:26. Page 83 of 1-148.

```
8.1. QED
4317
4318
                                                                                                                                                                                                                                                                 4319
4320
                     \text{Lemma 7.35. } \textit{If } \cdot \vdash_{\mathsf{A}} \mathsf{dyn} \ b_0 \ v_0 : \tau_0 \ \textit{and} \cdot ; \ell_0 \ \overline{\vdash}_{\mathsf{A}} \ \mathsf{dyn} \ b_0 \ v_0 \ \textit{then} \ (\mathsf{dyn} \ b_0 \ v_0)^{\ell_0} \, \rhd_{\!_{\mathsf{A}}} \ (e_1)^{\ell_0}. 
4321
4322
                    PROOF. By inversion of \vdash_A and case analysis of tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0).
4323
               1. b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)
4324
                     and \ell_0; \ell_1 \Vdash \tau_0
4325
                    and \cdot; \ell_1 \overline{\Vdash}_A v_0
                    and v_0 = ((v_1))^{\ell_1}
                    by inversion \overline{\mathbb{H}}_A
4329
               2. CASE tag-match (|\tau_0|, v_1)
4330
                                and rem-trace(v_1) \in ((\lambda x. e))^{\overline{\ell}} \cup ((\langle v, v \rangle))^{\overline{\ell}} \cup ((mon b v))^{\overline{\ell}}
4331
4332
4333
                        (\operatorname{dyn} b_0 \ v_0)^{\ell_0} \rhd_{\Delta} (\operatorname{mon} b_0 \ v_0)^{\ell_0}
4334
4335
              3. CASE v_1 \in i and tag\text{-}match([Int], v_1)
4336
4337
                        (\mathsf{dyn}\ b_0\ v_0)^{\ell_0} \rhd_{\!\!\mathsf{A}} (v_1)^{\ell_0}
4338
               4. CASE v_1 \in n and tag-match(\lfloor Nat \rfloor, v_1)
4339
4341
                        (\mathsf{dyn}\ b_0\ v_0)^{\ell_0} \rhd_{\!\!\mathsf{A}} (v_1)^{\ell_0}
4342
               5. CASE \neg tag-match(\lfloor \tau_0 \rfloor, \upsilon_1)
4343
4344
                        (\mathsf{dyn}\ b_0\ v_0)^{\ell_0} \rhd_{\mathsf{A}} (\mathsf{BndryErr}\ (b_0,v_0))^{\ell_0}
4345
4346
                                                                                                                                                                                                                                                                 4347
4348
                    Lemma 7.36. If \cdot \vdash_A stat b_0 \ v_0 : \mathcal{U} and \cdot ; \ell_0 \ \overline{\vdash}_A stat b_0 \ v_0 then (stat b_0 \ v_0)^{\ell_0} \blacktriangleright_A (e_1)^{\ell_0}.
4349
4350
                    PROOF. By case analysis on v_0.
4351
               1. b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)
4352
                     and \ell_0; \ell_1 \Vdash \tau_0
4354
                    and \cdot; \ell_1 \stackrel{}{\Vdash}_A v_0
4355
                    and v_0 = (v_1)^{\overline{\ell}_2}
4356
                    by inversion \overline{\mathbb{F}}_{A}
4357
4358
               2. Case v_1 \in \lambda x. e
4359
                    2.1. Contradiction:
4360
                         \cdot \vdash_{\mathsf{A}} \mathsf{stat} \ b_0 \ v_0 : \mathcal{U}
4361
              3. Case v_1 \in \lambda(x:\tau). e
4362
4363
                        (\operatorname{stat} b_0 \ v_0)^{\ell_0} \blacktriangleright_{\mathsf{A}} (\operatorname{mon} b_0 \ v_0)^{\ell_0}
4364
4365
               4. Case v_1 \in \langle v, v \rangle
4366
                    4.1. QED
4368
```

```
(\operatorname{stat} b_0 \ v_0)^{\ell_0} \blacktriangleright_{\mathsf{A}} (\operatorname{mon} b_0 \ v_0)^{\ell_0}
4369
                 5. Case v_1 = \operatorname{mon} b_1 \left( \operatorname{trace}_{\mathbf{v}}^? \overline{b}_2 \left( \! \left( v_2 \right) \! \right)^{\overline{\ell}_3} \right) \! \right)^{\overline{\ell}_4}
4370
4371
                      5.1. SCASE v_2 \in (\lambda x. e) \cup (\langle v, v \rangle)
4372
4373
4374
                                  (\mathsf{stat}\ b_0\ v_0)^{\ell_0} \blacktriangleright_{\mathsf{A}} (\mathsf{trace}\ b_0b_1\overline{b}_2\,(\!(v_2)\!)^{\overline{\ell}_3\overline{\ell}_4\overline{\ell}_2})^{\ell_0}
4375
                      5.2. Scase v_2 \in (\lambda(x:\tau).e)
4376
                           5.2.1. Contradiction:
4377
4378
                                  \cdot \vdash_{\mathsf{A}} v_0 : \tau_0
                      5.3. SCASE v_2 = (\text{mon } b_5 ((v_3))^{\overline{\ell}_6})
4380
                            5.3.1. SSCASE v_3 \in (\lambda(x : e).) \cup \langle v, v \rangle
4381
                                  (\mathsf{stat}\ b_0\ v_0)^{\ell_0} \blacktriangleright_\mathsf{A} (\mathsf{trace}\ b_0b_1\overline{b}_2\,(\!(v_2)\!)^{\overline{\ell}_3\overline{\ell}_4\overline{\ell}_2}\!)^{\ell_0}
4382
4383
                            5.3.2. SSCASE v_3 \notin (\lambda(x:e).) \cup \langle v, v \rangle
4384
                                  5.3.2.1. Contradiction:
4385
                                       \cdot \vdash_{\mathsf{A}} v_1 : \tau_0
4386
4387
                      5.4. SCASE otherwise
4388
                            5.4.1. Contradiction:
4389
                                  \cdot \vdash_{\mathsf{A}} v_1 : \tau_0
4390
                 6. CASE v_1 = \operatorname{trace}_{v}^{?} \overline{b_0} ((i_1))^{\overline{\ell_1}}
4391
                      6.1. QED
4393
                            (\operatorname{stat} b_0 \ v_0)^{\ell_0} \blacktriangleright_{\!\!\!\! A} (i_1)^{\ell_0}
4394
4395
4396
                      LEMMA 7.37. If \cdot \vdash_A \operatorname{dyn} b_0 v_0 : \tau_0 \text{ and } \cdot ; \ell_0 \ \overline{\vdash}_A \operatorname{dyn} b_0 v_0 \text{ and } (\operatorname{dyn} b_0 v_0)^{\ell_0} \rhd_A (e_1)^{\ell_0} \text{ then } \cdot ; \ell_0 \ \overline{\vdash}_A e_1.
4397
4398
                       PROOF. By case analysis of \triangleright_{A}.
4399
4400
                 1. b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)
4401
                       and \ell_0; \ell_1 \Vdash \tau_0
4402
                      and \cdot; \ell_1 \overline{\Vdash}_A v_0
4403
                      by inversion \overline{\mathbb{H}}_A
4404
                2. Case (\operatorname{dyn} b_0 \ v_0)^{\ell_0} \rhd_{\!\!\mathsf{A}} (\operatorname{mon} b_0 \ v_0)^{\ell_0}
4405
4406
                      2.1. QED
4407
4408
                                                                                                                                       by inversion \overline{\mathbb{H}}_A
4409
                                                                                                                                            \cdot; \ell_1 \ \overline{\Vdash}_{\mathsf{A}} \ v_0
4410
4411
                                                                                                                                     \overline{\cdot; \ell_0 \Vdash_{\mathsf{A}} \mathsf{mon} \, b_0 \, v_0}
4412
                3. CASE (\text{dyn } b_0 \ v_0)^{\ell_0} \rhd_{\mathbf{A}} (i_1)^{\ell_0}
4413
4414
4415
                4. Case (\mathsf{dyn}\ b_0\ v_0)^{\ell_0} \rhd_{\mathsf{A}} (\mathsf{BndryErr}\ (b_0,v_0))^{\ell_0}
4416
                      4.1. QED
4417
4418
```

```
Lemma 7.38 (A-stat preservation). If \cdot \vdash_A stat b_0 \ v_0 : \mathcal{U} \ and \ \cdot ; \ell_0 \ \overline{\vdash_A} \ stat \ b_0 \ v_0 \ and \ (stat \ b_0 \ v_0)^{\ell_0} \blacktriangleright_A \ (e_1)^{\ell_0} \ then
4421
4422
                  \cdot; \ell_0 \stackrel{\overline{\Vdash}}{\Vdash}_A e_1.
4423
4424
                        PROOF. By case analysis of \triangleright_{\Lambda}.
4425
                  1. b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)
4426
                        and \cdot; \ell_1 \Vdash_A v_0
4427
                        by inversion \overline{\mathbb{H}}_A
4428
                 2. CASE (stat b_0 \ v_0)^{\ell_0} \blacktriangleright_{\mathbf{A}} (\mathsf{mon} \ b_0 \ v_0)^{\ell_0}
4429
                        2.1. QED
4431
4432
                                                                                                                                              by inversion \overline{\mathbb{H}}_A
4433
4434
                                                                                                                                                     \cdot; \ell_1 \overline{\Vdash}_A v_0
4435
                                                                                                                                            \overline{\cdot; \ell_0 \Vdash_{\mathsf{A}} \mathsf{mon} \, b_0 \, v_0}
4436
                 3. Case (stat b_0 ((mon b_1 ((trace {}^?_{\mathbf{v}}\overline{b_2}\,v_2))^{\overline{\ell_4}})^{\overline{\ell_5}})^{\ell_0} \blacktriangleright_{\mathbf{A}} (trace b_0b_1\overline{b_2}\,((v_2))^{\overline{\ell_4}\overline{\ell_5}\ell_0})^{\ell_0}
4437
4438
4439
                        3.1. \overline{b}_2 \simeq \overline{\ell}_4
4440
                             by inversion \overline{\mathbb{F}}_{A}
4441
                        3.2. QED
4442
4443
                                                                                                                                             by inversion \overline{\mathbb{H}}_{A}
4445
                                                                                                                          \frac{\overline{\cdot; last(\overline{\ell}_4) \, \mathbb{F}_{\!\mathsf{A}} \, v_2}}{\cdot; \ell_0 \, \mathbb{F}_{\!\mathsf{A}} \, \mathrm{trace} \, b_0 b_1 \overline{b}_2 \, (\!(v_2)\!)^{\overline{\ell}_4 \overline{\ell}_5 \ell_0}}
4446
4447
                                                                                                                       \frac{}{\cdot ; \ell_0 \Vdash_{\mathsf{A}} (\mathsf{trace}\, b_0 b_1 \overline{b}_2 (\!(v_2)\!)^{\overline{\ell}_4 \overline{\ell}_5 \ell_0})^{\ell_0}}
4448
4449
                 4. CASE (stat b_0 \ v_0)^{\ell_0} \blacktriangleright_{\!\!\! A} (i_1)^{\ell_0}
4450
4451
                        qedstep
4452
4453
                                                                                                                                                                                                                                                                                                                   4454
                        LEMMA 7.39. If \cdot \vdash_A \operatorname{trace} \overline{b_0} v_0 : \mathcal{U} \ and \ :_{\ell_0} \ \overline{\vdash}_A \ \operatorname{trace} \overline{b_0} v_0 \ then \ :_{\ell_0} \ \overline{\vdash}_A \ add-trace(\overline{b_0}, v_0).
4455
                        PROOF. By case analysis of add-trace.
4458
                  1. CASE add-trace(\cdot, v_0) = v_0
4459
4460
                 2. CASE add-trace (\overline{b}_0, ((\operatorname{trace}_{\mathbf{v}} \overline{b}_1 \ v_1))^{\overline{\ell}_2}) = \operatorname{trace}_{\mathbf{v}} \overline{b}_0 \overline{b}_1 ((v_1))^{\overline{\ell}_2}
4461
4462
                        2.1. OED
4463
                             2.1.1. \overline{b}_0 \simeq \overline{\ell}_2
4464
                                   by inversion \overline{\mathbb{H}}_{A}
4465
                              2.1.2. QED
4466
                 3. Case add-trace(\overline{b}_0, v_1) = \operatorname{trace}_{v} \overline{b}_0 v_1
4467
4468
                                       and v_0 \notin \operatorname{trace}_{\mathbf{v}} \overline{b} v
4469
                        3.1. v_1 = ((v_2))^{\overline{\ell}_2}
4470
                                  and \overline{b}_0 \simeq \overline{\ell}_2
4471
```

```
by inversion \cdot; \ell_0 \Vdash_{\mathsf{A}} \operatorname{trace} \overline{b_0} v_1
4473
4474
             3.2. QED
4475
4476
4477
             LEMMA 7.40. If (x_0:\tau_0), \Gamma_0 \vdash_A e_1:\tau? and (x_0:\ell_0), L_0; \ell_1 \stackrel{}{\Vdash}_A e_1 and \cdot \vdash_A v_0:\tau?' and \cdot ; \ell_0 \stackrel{}{\Vdash}_A v_0 then \Gamma_0 \vdash_A e_1[x_0 \leftarrow v_0]
4478
          v_0]: \tau? and L_0 \overline{\Vdash}_A e_1[x_0 \leftarrow v_0].
4479
4480
             PROOF. By induction on the structure of e_0.
4481
          1. e_0 = x_2
4482
4483
             1.1. Scase x_0 = x_2
4484
                1.1.1. QED
4485
             1.2. Scase x_0 \neq x_2
4486
                1.2.1. QED
4487
                    e_1[x_0 \leftarrow v_0] = e_1
4488
4489
          2. Case e_0 \in i
4490
             2.1. QED
4491
                e_1[x_0\!\leftarrow\!v_0]=e_1
4492
         3. CASE e_0 = \lambda x_2 . e_2
4493
4494
                     or e_0 = \lambda(x_2 : \tau_2). e_2
4495
             3.1. SCASE x_0 = x_2
4496
                3.1.1. QED
4497
4498
                    e_1[x_0 \leftarrow v_0] = e_1
4499
             3.2. Scase x_0 \neq x_2
4500
                3.2.1. QED
4501
                    by the induction hypothesis
4502
4503
         4. Case e_0 = \langle e_1, e_2 \rangle
4504
             4.1. QED
4505
                by the induction hypothesis
4506
         5. Case e_0 = app\{\tau?\} e_1 e_2
4507
4508
             5.1. QED
                by the induction hypothesis
4510
         6. CASE e_0 = unop\{\tau?\} e_1
4511
             6.1. QED
4512
                by the induction hypothesis
4513
4514
         7. CASE e_0 = binop\{\tau?\} e_1 e_2
4515
             7.1. QED
4516
                by the induction hypothesis
4517
4518
         8. CASE e_0 = \text{dyn } b_1 e_1
4519
             8.1. QED
4520
                by the induction hypothesis
4521
          9. Case e_0 = \text{stat } b_1 e_1
4522
4523
             9.1. QED
4524
         2019-10-03 17:26. Page 87 of 1-148.
```

```
by the induction hypothesis
4525
4526
            10. CASE e_0 = (e_1)^{\ell_1}
4527
                10.1. \ell_0 = \ell_1
4528
                    by inversion \overline{\mathbb{H}}_{A}
4529
4530
                10.2. QED
4531
                    by the induction hypothesis
4532
            11. CASE e_0 = \operatorname{trace} \bar{b}_1 ((e_1))^{\bar{\ell}_1}
4533
                11.1. \cdot; last(\overline{\ell}_1) \ \overline{\Vdash}_A \ e_1
4534
                    by inversion \overline{\mathbb{H}}_A
4536
                11.2. QED
4537
                    by the induction hypothesis
4538
            12. CASE e_0 = \operatorname{trace}_{\mathbf{v}} \overline{b}_1 \left( \left( e_1 \right) \right)^{\overline{\ell}_1}
4539
4540
4541
                    by the induction hypothesis
4542
4543
```

Lemma 7.41 (boundary preservation). If $e_0:\tau$? $\overline{\mathbf{wf}}$ and $e_0 \to_A^* E_0[\mathsf{dyn}\ b_1\ v_1]$ then either has-boundary (e_0,b_1) or has-boundary $(e_0,flip\ (b_1))$.

PROOF. By case analysis of \triangleright_A and \blacktriangleright_A , evaluation does not create new labels and only creates a new boundary by flipping an existing boundary.

 $\text{Lemma 7.42. If } e_0 : \tau ? \ \overline{\mathbf{wf}} \ \textit{and} \ e_0 \rightarrow_{\mathsf{A}}^* E[\mathsf{mon} \ (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_2) \ \upsilon_0] \ \textit{and} \ \textit{tag-match} \ (\lfloor \tau_1 \times \tau_2 \rfloor, \upsilon_0) \ \textit{then} \ \tau_0 \in (\tau \times \tau)^\ell$

Proof. Surface expressions do not contain monitors, and \triangleright_A and \triangleright_A only create monitors with compatible types and values.

8 N/A SIMULATION

```
v \lesssim v
```

$$\frac{v_0 \lesssim v_2 \qquad v_1 \lesssim v_3}{i_0 \lesssim \mathsf{trace}_{\mathsf{v}} \overline{b_0} \, i_0} \qquad \frac{v_0 \lesssim v_2 \qquad v_1 \lesssim v_3}{\langle v_0, v_1 \rangle \lesssim \langle v_2, v_3 \rangle} \qquad \frac{v_0 \lesssim \mathsf{mon}^? \, \mathsf{fst} \, (b_0) \, v_2 \qquad v_1 \lesssim \mathsf{mon}^? \, \mathsf{snd} \, (b_0) \, v_3}{\langle v_0, v_1 \rangle \lesssim \mathsf{mon} \, b_0 \, \langle v_2, v_3 \rangle}$$

$$\frac{v_0 \lesssim \textit{add-trace}(\mathsf{fst}(\overline{b_0}), (\mathsf{mon}^? \, \mathsf{fst}(b_1) \, v_2))}{v_0 \lesssim \textit{add-trace}(\mathsf{fst}(\overline{b_0}), v_2) \qquad v_1 \lesssim \textit{add-trace}(\mathsf{snd}(\overline{b_0}), v_3)} \\ \frac{v_0 \lesssim \textit{add-trace}(\mathsf{fst}(\overline{b_0}), (\mathsf{mon}^? \, \mathsf{fst}(b_1) \, v_2))}{\langle v_0, v_1 \rangle \lesssim \mathsf{trace}_{\mathsf{v}} \, \overline{b_0} \, \langle v_2, v_3 \rangle} \\ \frac{v_0 \lesssim \textit{add-trace}(\mathsf{fst}(\overline{b_0}), (\mathsf{mon}^? \, \mathsf{fst}(b_1) \, v_2))}{\langle v_0, v_1 \rangle \lesssim \mathsf{trace}_{\mathsf{v}} \, \overline{b_0} \, (\mathsf{mon} \, b_1 \, \langle v_2, v_3 \rangle)}$$

$$\frac{v_0 \lesssim \mathsf{mon}^? \, \mathsf{fst} \, (b_0) \, (\mathit{add-trace} \, (\mathsf{fst} \, (\overline{b}_1), v_2)) \qquad v_1 \lesssim \mathsf{mon}^? \, \mathsf{snd} \, (b_1) \, (\mathit{add-trace} \, (\mathsf{snd} \, (\overline{b}_1), v_3))}{\langle v_0, v_1 \rangle \lesssim \mathsf{mon} \, b_0 \, (\mathsf{trace}_{\mathsf{V}} \, \overline{b}_1 \, \langle v_2, v_3 \rangle)}$$

$$\frac{v_0 \lesssim \mathsf{mon}^? \, \mathsf{fst} \, (b_0) \, (\mathsf{mon}^? \, \mathsf{fst} \, (b_1) \, v_2) \qquad v_1 \lesssim \mathsf{mon}^? \, \mathsf{snd} \, (b_0) \, (\mathsf{mon}^? \, \mathsf{snd} \, (b_1) \, v_3)}{\langle v_0, v_1 \rangle \lesssim \mathsf{mon} \, b_0 \, (\mathsf{mon} \, b_1 \, \langle v_2, v_3 \rangle)}$$

$$v_0 \lesssim \mathsf{mon}^? \, \mathsf{fst} \, (b_0) \, (\mathit{add-trace} \, (\mathsf{fst} \, (\overline{b_1}), (\mathsf{mon} \, \mathsf{fst} \, (b_2) \, v_2))))$$

$$v_1 \lesssim \mathsf{mon}^? \, \mathsf{snd} \, (b_0) \, (\mathit{add-trace} \, (\mathsf{snd} \, (\overline{b_1}), (\mathsf{mon} \, \mathsf{snd} \, (b_2) \, v_3))))$$

$$\langle v_0, v_1 \rangle \lesssim \mathsf{mon} \, b_0 \, (\mathsf{trace}_v \, \overline{b_1} \, (\mathsf{mon} \, b_2 \, \langle v_2, v_3 \rangle))$$

$$\frac{v_0 \lesssim \mathsf{mon}^{+?} \operatorname{fst}(\overline{b_0}) \left(\mathsf{mon}^? \operatorname{fst}(b_1) \left(\mathsf{mon}^? \operatorname{fst}(b_2) v_2\right)\right)}{\langle v_0, v_1 \rangle \lesssim \mathsf{mon}^{+} \overline{b_0} \left(\mathsf{mon} \ b_1 \left(\mathsf{mon} \ b_2 \left\langle v_2, v_3 \right\rangle\right)\right)} \\ \frac{\langle v_0, v_1 \rangle \lesssim \mathsf{mon}^{+} \overline{b_0} \left(\mathsf{mon} \ b_1 \left(\mathsf{mon} \ b_2 \left\langle v_2, v_3 \right\rangle\right)\right)}{\langle v_1, v_2 \rangle \langle v_2, v_3 \rangle \langle v_3$$

$$\begin{array}{ll} v_0 \lesssim \mathsf{mon}^{+?} \, \mathsf{fst} \, (\overline{b}_0) \, (\mathsf{mon}^? \, \mathsf{fst} \, (b_1) \, (\mathit{add-trace} \, (\mathsf{fst} \, (\overline{b}_2), (\mathsf{mon}^? \, \mathsf{fst} \, (b_3) \, v_2)))) \\ \\ \underline{v_1 \lesssim \mathsf{mon}^{+?} \, \mathsf{snd} \, (\overline{b}_0) \, (\mathsf{mon}^? \, \mathsf{snd} \, (b_1) \, (\mathit{add-trace} \, (\mathsf{snd} \, (\overline{b}_2), (\mathsf{mon}^? \, \mathsf{snd} \, (b_3) \, v_3)))) } \\ \\ \underline{v_0, v_1 \rangle \lesssim \mathsf{mon}^{+} \, \overline{b}_0 \, (\mathsf{mon} \, b_1 \, (\mathsf{trace}_{\mathsf{v}} \, \overline{b}_2 \, (\mathsf{mon} \, b_3 \, \langle v_2, v_3 \rangle)))} \\ \\ \underline{\lambda x_0. \, e_0 \lesssim \lambda x_0. \, e_1} \\ \\ \\ \underline{\lambda x_0. \, e_0 \lesssim \lambda x_0. \, e_1} \\ \end{array}$$

$$\frac{v_1 \in \lambda x. \ e \cup \mathsf{mon} \ b \ (\lambda(x : \tau). \ e)}{b_0 \leqslant : b_2 \qquad b_1 \leqslant : b_3 \qquad v_0 \lesssim v_1} \\ \frac{b_0 \leqslant : b_2 \qquad b_1 \leqslant : b_3 \qquad v_0 \lesssim v_1}{\mathsf{mon} \ b_0 \ (\mathsf{mon} \ b_1 \ v_0) \lesssim \mathsf{trace}_{\mathsf{v}} \ b_2 b_3 \cdot v_1}$$

$$\begin{array}{lll} & v_1 \in \lambda x. \ e \cup \operatorname{mon} b \ (\lambda(x \colon \tau). \ e) \\ & \underbrace{b_0 \leqslant : b_2 \quad b_1 \leqslant : b_3 \quad v_0 \lesssim \operatorname{trace_v} \overline{b}_4 \ v_1}_{\operatorname{mon} b_0 \ (\operatorname{mon} b_1 \ v_0) \lesssim \operatorname{trace_v} b_2 b_3 \overline{b}_4 \ v_1} & \underbrace{b_0 \leqslant : b_1 \quad v_0 \lesssim v_1}_{\operatorname{mon} b_0 \ v_0 \lesssim \operatorname{mon} b_1 \ v_1} \end{array}$$

```
4629
4630
4631
                             \frac{e_0 \lesssim e_2 \qquad e_1 \lesssim e_3}{\langle e_0, e_1 \rangle \lesssim \langle e_2, e_3 \rangle} \qquad \frac{e_0 \lesssim e_2 \qquad e_1 \lesssim e_3}{\operatorname{app}\{\tau?_0\} e_0 \ e_1 \lesssim \operatorname{app}\{\tau?_0\} e_2 \ e_3} \qquad \frac{e_0 \lesssim e_1}{unop\{\tau?\} e_0 \lesssim unop\{\tau?\} e_1}
4632
4633
4634
                                                \frac{e_0 \lesssim e_2 \qquad e_1 \lesssim e_3}{binop\{\tau?\} \ e_0 \ e_1 \lesssim binop\{\tau?\} \ e_2 \ e_3} \qquad \qquad \frac{b_0 \leqslant :b_1 \qquad e_0 \lesssim e_1}{\mathsf{dyn} \ b_0 \ e_0 \lesssim \mathsf{dyn} \ b_1 \ e_1} \qquad \qquad \frac{b_0 \leqslant :b_1 \qquad e_0 \lesssim e_1}{\mathsf{stat} \ b_0 \ e_0 \lesssim \mathsf{stat} \ b_1 \ e_1}
4635
4636
4637
4638
                                          b_0 \leqslant b_2 \qquad b_1 \leqslant b_3
4639
                      \frac{e_0 \lesssim \operatorname{trace} \overline{b_4} \, e_1}{\operatorname{stat} \, b_0 \, (\operatorname{dyn} \, b_1 \, e_0) \lesssim \operatorname{trace} \, b_2 b_3 \overline{b_4} \, e_1} \qquad \overline{\operatorname{TagErr} \, \circ \, \lesssim \operatorname{TagErr} \, \circ} \qquad \overline{\operatorname{TagErr} \, \circ \, \lesssim \operatorname{TagErr} \, \circ}
4640
4641
                                                                                                                                                                                                                                                                                                                      DivErr \lesssim DivErr
4642
4643
4644
                                                                                                                                                                 BndryErr (b_0, v_0) \lesssim e_1
4645
4646
                       E \lesssim E
4647
                                  \frac{E_0 \lesssim E_2 \quad e_1 \lesssim e_3}{\langle E_0, e_1 \rangle \lesssim \langle E_2, e_3 \rangle} \qquad \frac{v_0 \lesssim v_2 \quad E_1 \lesssim E_3}{\langle v_0, E_1 \rangle \lesssim \langle v_2, E_3 \rangle} \qquad \frac{E_0 \lesssim E_2 \quad e_1 \lesssim e_3}{\operatorname{app}\{\tau?_0\} E_0 \ e_1 \lesssim \operatorname{app}\{\tau?_0\} E_2 \ e_3}
4648
4649
4650
4651
                               \frac{v_0 \lesssim v_2 \qquad E_1 \lesssim E_3}{\operatorname{app}\{\tau?_0\} \ v_0 \ E_1 \lesssim \operatorname{app}\{\tau?_0\} \ v_2 \ E_3} \qquad \frac{E_0 \lesssim E_1}{\operatorname{unop}\{\tau?\} \ E_0 \lesssim \operatorname{unop}\{\tau?\} \ E_1} \qquad \frac{E_0 \lesssim E_2 \qquad e_1 \lesssim e_3}{\operatorname{binop}\{\tau?\} \ E_0 \ e_1 \lesssim \operatorname{binop}\{\tau?\} \ E_2 \ e_3}
4652
4653
4654
4655
                                             \frac{\upsilon_0 \lesssim \upsilon_2 \qquad E_1 \lesssim E_3}{\textit{binop}\{\tau?\}\ \upsilon_0\ E_1 \lesssim \textit{binop}\{\tau?\}\ \upsilon_2\ E_3} \qquad \qquad \frac{b_0 \leqslant :b_1 \qquad E_0 \lesssim E_1}{\textit{dyn}\ b_0\ E_0 \lesssim \textit{dyn}\ b_1\ E_1} \qquad \qquad \frac{b_0 \leqslant :b_1 \qquad E_0 \lesssim E_1}{\textit{stat}\ b_0\ E_0 \lesssim \textit{stat}\ b_1\ E_1}
4656
4657
4658
4659
                                                                                                                                  b_0 \leqslant b_2 b_1 \leqslant b_3 E_0 \lesssim \operatorname{trace} \overline{b}_4 E_1
4660
                                                                                                                                            stat b_0 (dyn b_1 E_0) \lesssim trace b_2 b_3 \overline{b}_4 E_1
4661
4662
```

4732

2019-10-03 17:26. Page 91 of 1-148.

```
Corollary 8.1. If e_0:\tau? wf and e_0 \to_{\Lambda}^* BndryErr (\overline{b}_2, v_2) then e_0 \to_{\Lambda}^* BndryErr (b_1, v_1)
4682
                PROOF. By lemma 8.6 and the fact that e \lesssim \text{BndryErr}(\overline{b_2}, v_2) implies e \in \text{BndryErr}(b, v)
4683
                                                                                                                                                                                                             4685
                Example 8.2. There exists e_0:\tau? wf such that e_0 \to_A^* BndryErr (\overline{b}_2, v_2) and e_0 \to_N^* BndryErr (b_1, v_1) and b_1 \notin \overline{b}_2
4687
4688
                PROOF. Choose any e_0 where Natural detects an error that Amnesic misses, and then Amnesic detects an error at a
            boundary between two different components, e.g.:
              e_0 = \operatorname{sum} \left( \operatorname{fst} \{ \operatorname{Nat} \} \left( \operatorname{dyn} \left( \ell_0 \blacktriangleleft \left( \operatorname{Nat} \times \operatorname{Nat} \right)^{\ell_1} \blacktriangleleft \ell_1 \right) \langle 0, -1 \rangle \right) \right)
                              (\operatorname{dyn}(\ell_0 \blacktriangleleft (\operatorname{Nat})^{\ell_1} \blacktriangleleft \ell_1) (\operatorname{stat}(\ell_1 \blacktriangleleft (\operatorname{Nat})^{\ell_2} \blacktriangleleft \ell_2) (\operatorname{dyn}(\ell_2 \blacktriangleleft (\operatorname{Nat})^{\ell_3} \blacktriangleleft \ell_3) - 1)))
4692
4693
                                                                                                                                                                                                             4694
4695
                Theorem 8.3. If e_0:\tau? wf and e_0\to_N^* e_1\to_N BndryErr (b_1,v_1) then \exists e_2 such that e_0\to_A^* e_2 and one of the following
4696
4697
4698
                   • e_1 \lesssim e_2, or
4699
                   • e_1 = E_1[\mathsf{app}\{\tau_2\}\ v_0\ (\mathsf{dyn}\ b_1\ v_1)] and e_2 = E_2[\mathsf{app}\{\tau_2\}\ (\mathsf{trace}_{\mathsf{v}}\ \overline{b_2}\ v_2)\ v_3] and E_1 \lesssim E_2 and flip(b_1) \in \overline{b_2}
4700
4701
                PROOF. by lemma 8.6 and lemma 8.26.
4702
                                                                                                                                                                                                             4703
                Example 8.4. There exists e_0:\tau? wf such that e_0 \to_N^* \text{BndryErr}(b_1, v_1) and e_0 \to_A^* v_1
4705
4706
                PROOF. e_0 = \text{dyn} (\ell_0 \blacktriangleleft \text{Nat} \times \text{Nat} \blacktriangleleft \ell_1) \langle -1, -2 \rangle
4707
4708
                                                                                                                                                                                                             4709
4710
                Lemma 8.5 (\lesssim surface reflexivity). If e_0:\tau? wf then e_0\lesssim e_0
4711
4712
                PROOF. By induction on e_0.
4713
            1. CASE e_0 = x_0
4714
                1.1. QED
4715
                    x_0 \lesssim x_0
4716
4717
            2. CASE e_0 = i_0
4718
                2.1. QED
4719
                    i_0 \lesssim i_0
4720
            3. CASE e_0 = \lambda x_1 . e_1
4721
4722
                3.1. e_1 \lesssim e_1
4723
                   by the induction hypothesis
4724
                3.2. QED
4725
                   \lambda x_1. e_1 \lesssim \lambda x_1. e_1
4726
4727
            4. CASE e_0 = \langle e_1, e_2 \rangle
4728
                4.1. QED
4729
                    by the induction hypothesis
4730
            5. CASE e_0 = app\{\tau?\} e_1 e_2
4731
```

2019-10-03 17:26. Page 92 of 1-148.

```
4733
              5.1. QED
4734
                  by the induction hypothesis
4735
          6. CASE e_0 = unop\{\tau?\} e_1
4736
              6.1. QED
4737
4738
                  by the induction hypothesis
4739
          7. CASE e_0 = binop\{\tau?\} e_1 e_2
4740
              7.1. QED
4741
                  by the induction hypothesis
4742
          8. CASE e_0 = \operatorname{dyn} b_0 e_1
4743
4744
              8.1. b_0 \leqslant b_0
4745
                 by reflexivity ≤:
4746
              8.2. QED
4747
                  by the induction hypothesis
4748
4749
          9. CASE e_0 = \text{stat } b_0 e_1
4750
              9.1. QED
4751
                  by the induction hypothesis
4752
4753
                                                                                                                                                                                           4754
4755
               LEMMA 8.6 (SIMULATION).
                • if e_0 \lesssim e_2 and e_0 \to_N e_1 then \exists \, e_3, e_4 such that e_1 \to_N^* e_3 and e_2 \to_A^* e_4 and e_3 \lesssim e_4
• if e_0 \lesssim e_2 and e_2 \to_A e_3 then \exists \, e_1, e_4 such that e_3 \to_A^* e_4 and e_0 \to_N^* e_1 and e_1 \lesssim e_4
4757
4758
4759
               PROOF. By lemma 8.8 and lemma 8.9.
4760
4761
                                                                                                                                                                                           4762
4763
               Definition 8.7 (reduced WF expressions). Expressions e_1 and e_2 are reduced WF expressions if e_0:\tau? wf and e_0 \to_N^* e_1
4764
          and e_0 \rightarrow_A^* e_2
4765
4766
              Lemma 8.8 (H-step simulation). If e_0 and e_2 are reduced WF expressions and e_0 \lesssim e_2 and e_0 \rightarrow_N e_1 then \exists \, e_3, e_4
4767
          such that e_1 \to_{\mathsf{N}}^* e_3 and e_2 \to_{\mathsf{A}}^* e_4 and e_3 \lesssim e_4
4768
              Proof. By case analysis of e_0 \rightarrow_{\mathsf{N}} e_1
           1. CASE e_0 = E_0[\mathsf{BndryErr}\,(b_0,v_0)] and e_0 \to_{\mathsf{N}} \mathsf{BndryErr}\,(b_0,v_0)
4771
              1.1. QED
4772
                  trivial, BndryErr (b_0, v_0) \lesssim e_2
4773
4774
          2. CASE e_0 = E_0[\mathsf{Err}_0] and \mathsf{Err}_0 \notin \mathsf{BndryErr}(\overline{b}, v) and e_0 \to_{\mathsf{N}} \mathsf{Err}_0
4775
              2.1. e_2 = E_2[\mathsf{Err}_1] and E_0 \lesssim E_2 and \mathsf{Err}_0 \lesssim \mathsf{Err}_1
4776
                  by lemma 8.10
4777
4778
              2.2. e_2 \rightarrow_A \mathsf{Err}_1
4779
                  by definition \rightarrow_A
4780
4781
                  Err_0 \lesssim Err_1
          3. CASE e_0 = E_0[\operatorname{dyn} b_0 \ v_0] and \operatorname{dyn} b_0 \ v_0 \ \triangleright_{\!\!\! N} \ e_3
4783
```

```
3.1. e_2 = E_2[\mathsf{dyn}\ b_2\ v_2] and E_0 \lesssim E_2 and \mathsf{dyn}\ b_0\ v_0 \lesssim \mathsf{dyn}\ b_2\ v_2
4785
4786
                      by lemma 8.10
4787
                  3.2. dyn b_0 \ v_0 \to_{\mathsf{N}}^* e_3 and dyn b_2 \ v_2 \to_{\mathsf{A}}^* e_4 and e_3 \lesssim e_4
4788
                      by lemma 8.12
4789
4790
                  3.3. QED
4791
                  by lemma 8.31
4792
             4. CASE e_0 = E_0[\text{stat } b_0 \ v_0] and stat b_0 \ v_0 \blacktriangleright_N \ e_3
4793
                  4.1. e_2 = E_2[\text{stat } b_2 \ v_2] and E_0 \lesssim E_2 and stat b_0 \ v_0 \lesssim \text{stat } b_2 \ v_2
4794
4796
                 4.2. stat b_0 v_0 \rightarrow_{\mathsf{N}}^* e_3 and stat b_2 v_2 \rightarrow_{\mathsf{A}}^* e_4 and e_3 \lesssim e_4
4797
                      by lemma 8.14
4798
                  4.3. QED
4799
4800
                     by lemma 8.31
4801
             5. CASE e_0 = E_0[unop\{\tau?\} v_0] and unop\{\tau?\} v_0 \triangleright_N \delta_N(unop, v_0)
4802
                  5.1. e_2 = E_2[unop\{\tau?\} v_2] and E_0 \lesssim E_2 and unop\{\tau?\} v_0 \lesssim unop\{\tau?\} v_2
4803
                      by lemma 8.10
4804
                  5.2. \vdash_{\mathsf{N}} unop\{\tau?\} v_0 : \tau_0 \text{ and } \vdash_{\mathsf{A}} unop\{\tau?\} v_2 : \tau_0
4805
4806
                     by type soundness
                  5.3. unop\{\tau?\}\ v_2 \rightarrow_{\mathsf{A}}^* v_3 \text{ and } \delta_N(unop, v_0) \lesssim v_3
                      by lemma 8.22
4809
4810
                  5.4. QED
4811
                      by lemma 8.31
4812
             6. CASE e_0 = E_0[unop\{\tau?\} v_0] and unop\{\tau?\} v_0 \triangleright_{N} e_1
4813
                  6.1. QED
4814
4815
                      by lemma 8.23
4816
             7. CASE e_0 = E_0[\operatorname{app}\{\tau_0\} (\operatorname{mon} (\ell_0 \blacktriangleleft (\tau_1 \Rightarrow \tau_2) \blacktriangleleft \ell_1) v_0) v_1]
4817
                             and \operatorname{app}\{\tau_0\} (\operatorname{mon} (\ell_0 \blacktriangleleft (\tau_1 \Rightarrow \tau_2) \blacktriangleleft \ell_1) \ v_0) \ v_1 \rhd_{\mathsf{N}} \operatorname{dyn} (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) (\operatorname{app}\{\mathcal{U}\} \ v_0 \ (\operatorname{stat} (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) \ v_1)) 
4818
                  7.1. e_2 = E_2[\mathsf{app}\{\tau_0\} \ v_3 \ v_4]
4819
                      by lemma 8.10
                  7.2. SCASE v_3 = \text{mon} (\ell_0 \blacktriangleleft (\tau_3 \Rightarrow \tau_4) \blacktriangleleft \ell_1) v_5
4822
                      4823
                          by definition \triangleright_{\!\!\!A}
4824
                      7.2.2. QED
4825
4826
                          by lemma 8.31
4827
                  7.3. SCASE v_3 = \text{trace}_{v_1} \overline{b_0} v_5
4828
                      7.3.1. Contradiction:
4829
4830
                           \cdot \vdash_{\mathsf{A}} \mathsf{app} \{ \tau_0 \} \ v_3 \ v_4 : \tau_0
4831
             8. CASE e_0 = E_0[\operatorname{app}\{\mathcal{U}\} (\operatorname{mon} (\ell_0 \blacktriangleleft (\tau_0 \Rightarrow \tau_1) \blacktriangleleft \ell_1) v_0) v_1]
4832
                             \text{and app}\{\mathcal{U}\}\left(\text{mon}\left(\ell_0 \blacktriangleleft (\tau_0 \Rightarrow \tau_1) \blacktriangleleft \ell_1\right) v_0\right) v_1 \blacktriangleright_{\mathsf{N}} \text{stat}\left(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1\right) \left(\text{app}\{\tau_1\} \ v_0 \ (\text{stat} \ (\ell_1 \blacktriangleleft \tau_0 \blacktriangleleft \ell_0) \ v_1\right)\right)
4833
                  8.1. e_2 = E_2[\mathsf{app}\{\mathcal{U}\} v_3 v_4]
4834
4835
                      by lemma 8.10
4836
             2019-10-03 17:26. Page 93 of 1-148.
```

```
8.2. SCASE v_3 = \text{mon} (\ell_0 \blacktriangleleft (\tau_3 \Rightarrow \tau_4) \blacktriangleleft \ell_1) v_3 \text{ and } v_0 \lesssim v_3
4837
4838
                   8.2.1. QED
4839
                      by definition \triangleright_{A} and \lesssim
4840
               8.3. SCASE v_3 = \operatorname{trace}_{\mathbf{v}} \overline{b}_2 v_5
4841
4842
                  8.3.1. QED
4843
                      by lemma 8.26
4844
           9. CASE e_0 = E_0[\mathsf{app}\{\tau_0\} (\lambda(x_0:\tau_1).e_0) \ v_1] and e_0 \rhd_{\mathsf{N}} E_0[e_0[x_0 \leftarrow v_1]]
4845
               9.1. e_2 = E_2[\mathsf{app}\{\tau_0\} \ v_2 \ v_3]
                  by lemma 8.10
4848
               9.2. v_2 = \lambda(x_0 : \tau_1). e_4 and e_0 \lesssim e_4
4849
                  by inversion ≤
4850
               9.3. QED
4851
4852
                  by lemma 8.30
4853
           10. CASE e_0 = E_0[\mathsf{app}\{\mathcal{U}\}(\lambda x_0. e_0) \ v_1] and e_0 \blacktriangleright_{\mathsf{N}} E_0[e_0[x_0 \leftarrow v_1]]
4854
               10.1. e_2 = E_2[\mathsf{app}\{\tau_0\} \ v_2 \ v_3]
4855
                  by lemma 8.10
4856
               10.2. v_2 = \lambda x_0. e_4 and e_0 \lesssim e_4
4857
4858
                  by inversion ≤
               10.3. QED
                  by lemma 8.30
4862
           11. CASE e_0 = E_0[binop\{\tau?\} v_0 v_1] and e_0 \to_N E_0[e_1]
4863
               11.1. e_2 = E_2[binop\{\tau?\}\ v_2\ v_3]
4864
                  by lemma 8.10
4865
               11.2. QED
4866
4867
                  by lemma 8.29
4868
4869
4870
               Lemma 8.9 (A-step simulation). If e_0 and e_2 are reduced WF expressions and e_0 \lesssim e_2 and e_2 \rightarrow_A e_3 then \exists \, e_1, e_4
4871
           such that e_3 \to_A^* e_4 and e_0 \to_N^* e_1 and e_1 \lesssim e_4
4872
               Proof. By case analysis of e_2 \rightarrow_A e_3
4874
           1. CASE e_0 contains a boundary error; e_0 = E_0[\mathsf{BndryErr}\,(b_0,v_0)]
4875
               1.1. e_0 \rightarrow_{\mathsf{N}} \mathsf{BndryErr}(b_0, v_0)
4876
                  by definition \rightarrow_N
4877
4878
               1.2. QED
4879
                   BndryErr (b_0, v_0) \lesssim e_3
4880
           2. CASE e_2 = E_2[\mathsf{Err}_2] and e_2 \to_{\mathsf{A}} \mathsf{Err}_2
4881
               2.1. e_0 = E_0[\mathsf{Err}_0] and E_0 \lesssim E_2 and \mathsf{Err}_0 \lesssim \mathsf{Err}_2
4882
4883
                  by lemma 8.11
4884
               2.2. QED
4885
                   e_0 \rightarrow_{\mathsf{N}} \mathsf{Err}_0 \lesssim \mathsf{Err}_2
           3. Case e_2 = E_2[\mathsf{dyn}\ b_2\ v_2] and \mathsf{dyn}\ b_2\ v_2 \rhd_{\!\!\mathsf{A}}\ e_3
4887
```

```
3.1. e_0 = E_0[\text{dyn } b_0 \ v_0] and \text{dyn } b_0 \ v_0 \lesssim \text{dyn } b_2 \ v_2
4889
4890
                     by lemma 8.11
4891
                 3.2. dyn b_0 v_0 
ightharpoonup^*_{\mathsf{N}} e_1 and dyn b_2 v_2 
ightharpoonup^*_{\mathsf{A}} e_4 and e_1 \lesssim e_4
4892
                     by lemma 8.12
4893
4894
                 3.3. QED
4895
                     by lemma 8.31
4896
             4. CASE e_2 = E_2[\text{stat } b_2 \ v_2] and stat b_2 \ v_2 \blacktriangleright_{\!\scriptscriptstyle A} e_3
4897
                 4.1. e_0 = E_0[\text{stat } b_0 \ v_0] and stat b_0 \ v_0 \lesssim \text{stat } b_2 \ v_2
4898
                     by lemma 8.11
4900
                 4.2. stat b_0 v_0 \rightarrow_{\mathsf{N}}^* e_1 and stat b_2 v_2 \rightarrow_{\mathsf{A}}^* e_4 and e_1 \lesssim e_4
4901
                     by lemma 8.14
4902
                 4.3. QED
4903
4904
                     by lemma 8.31
4905
             5. CASE e_2 = E_2[unop\{\tau?\} v_2] and unop\{\tau?\} v_2 \triangleright_A e_3
4906
                 5.1. e_0 = E_0[unop\{\tau?\} v_0] and E_0 \lesssim E_2 and v_0 \lesssim v_2
4907
                     by lemma 8.11
4908
                 5.2. \vdash_{\mathsf{N}} unop\{\tau?\} v_0 : \tau_0 \text{ and } \vdash_{\mathsf{A}} unop\{\tau?\} v_2 : \tau_0
4909
4910
                     by type soundness
4911
                 5.3. unop\{\tau?\}\ v_2 \rightarrow_{\mathsf{A}}^* v_4 \text{ and } \delta_N(unop, v_0) \lesssim v_4
4912
                     by lemma 8.22
4913
4914
                 5.4. QED
4915
                     by lemma 8.31
4916
             6. CASE e_2 = E_2[unop\{\tau?\} v_2] and unop\{\tau?\} v_2 \blacktriangleright_A e_3
4917
                 6.1. QED
4918
4919
                     by lemma 8.23
4920
             7. CASE e_2 = E_2[\operatorname{app}\{\tau_2\} (\operatorname{mon} (\ell_0 \blacktriangleleft (\tau_3 \Rightarrow \tau_4) \blacktriangleleft \ell_1) v_2) v_3]
4921
                             and e_2 \rightarrow_A E_2[\mathsf{dyn}(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1)(\mathsf{app}\{\mathcal{U}\} v_2 (\mathsf{stat}(\ell_1 \blacktriangleleft \tau_3 \blacktriangleleft \ell_0) v_3))]
4922
                 7.1. \tau_4 \leqslant : \tau_2
4923
4924
                     by inversion ⊢A
                 7.2. e_0 = E_0[\mathsf{app}\{\tau_2\} \, v_0 \, v_1]
4926
                     by lemma 8.11
4927
                 7.3. v_0 = \text{mon} (\ell_0 \blacktriangleleft (\tau_0 \Rightarrow \tau_1) \blacktriangleleft \ell_1) v_4
4928
                     by inversion \le \
4929
4930
                 7.4. QED
4931
                     \mathsf{app}\{\tau_2\}\,v_0\,\,v_1\,\rhd_{\mathsf{N}}\,\mathsf{dyn}\,(\ell_0\,\blacktriangleleft\,\tau_4\,\blacktriangleleft\,\ell_1)\,(\mathsf{app}\{\mathcal{U}\}\,v_4\,(\mathsf{stat}\,(\ell_1\,\blacktriangleleft\,\tau_3\,\blacktriangleleft\,\ell_0)\,v_1))
4932
             8. CASE e_2 = E_2[\mathsf{app}\{\mathcal{U}\} (\mathsf{trace}_{\mathsf{v}} b_0 \bar{b}_1 v_2) v_3]
4933
                 8.1. e_0 = E_0[\mathsf{app}\{\mathcal{U}\} v_0 \ v_1]
4934
4935
                     by lemma 8.11
4936
                 8.2. QED
4937
                     by lemma 8.26
4938
4939
             9. CASE e_2 = E_2[app\{\tau_0\} (\lambda(x_1:\tau_1).e_2) v_3]
4940
             2019-10-03 17:26. Page 95 of 1-148.
```

```
9.1. e_0 = E_0[\mathsf{app}\{\tau_0\} \ v_0 \ v_1]
4941
4942
                by lemma 8.11
4943
             9.2. v_0 = \lambda x_0. e_1 and e_1 \lesssim e_2
4944
                by inversion \lesssim
4945
4946
             9.3. QED
4947
                by lemma 8.30
4948
          10. CASE e_2 = E_2[binop\{\tau?\} \ v_2 \ v_3] and e_2 \rightarrow_A E_2[e_4]
4949
             10.1. e_0 = E_0[binop\{\tau?\} v_0 v_1]
                by lemma 8.11
4952
             10.2. QED
4953
                by lemma 8.29
4954
4955
                                                                                                                                                                            4956
             Lemma 8.10 (H context-matching). If E_0[e_0] \lesssim e_1 and e_0 \notin v then \exists E_2, e_2 such that e_1 = E_2[e_2] and E_0 \lesssim E_2 and
4957
4958
          e_0 \lesssim e_2
4959
             PROOF. By induction on the structure of E_0
4960
          1. CASE E_0 = []
4961
4962
             trivial, E_2 = [] and e_2 = e_1
          2. Case E_0 = \langle E_3, e_4 \rangle
4964
             2.1. E[e_0] = \langle E_3[e_0], e_4 \rangle \lesssim e_1
                by assumption
4966
4967
             2.2. e_1 = \langle e_5, e_6 \rangle and E_3[e_0] \lesssim e_5 and e_4 \lesssim e_6
4968
                by inversion \lesssim
4969
             2.3. e_4 = E_7[e_8] and E_3 \lesssim E_7 and e_0 \lesssim e_8
4970
4971
                by the induction hypothesis
4972
             2.4. QED
4973
                 E_1 = \langle E_7, e_6 \rangle and e_2 = e_8
4974
          3. Case E_0 = \langle v_3, E_4 \rangle
4975
             3.1. e_1 = \langle e_5, e_6 \rangle and v_3 \lesssim e_5 and E_4[e_0] \lesssim e_6
4976
                by inversion \le \
             3.2. QED
4979
                by the induction hypothesis
4980
          4. CASE E_0 = app\{\tau_{0}\} E_3 e_4
4981
4982
             4.1. e_1 = \operatorname{app}\{\tau?_0\} e_5 e_6 \text{ and } E_3[e_0] \lesssim e_5 \text{ and } e_4 \lesssim e_6
4983
                by inversion ≤
4984
             4.2. QED
4985
                by the induction hypothesis
4986
4987
          5. CASE E_0 = app\{\tau?_0\} v_3 E_4
4988
             5.1. e_1 = \operatorname{app}\{\tau_{0}^{2}\} e_5 e_6 and v_3 \leq e_5 and E_4[e_0] \leq e_6
4989
                by inversion \le \
             5.2. QED
```

```
by the induction hypothesis
4993
4994
         6. CASE E_0 = unop\{\tau?\} E_3
4995
             6.1. e_1 = unop\{\tau?\} e_4 and E_3[e_0] \lesssim e_4
4996
                by inversion \lesssim
4997
4998
             6.2. QED
4999
                by the induction hypothesis
5000
         7. CASE E_0 = binop\{\tau?\} E_3 e_4
5001
             7.1. e_1 = binop\{\tau?\} e_5 e_6 and E_3[e_0] \lesssim e_5 and e_4 \lesssim e_6
5002
                by inversion \lesssim
5004
             7.2. QED
5005
                by the induction hypothesis
5006
         8. CASE E_0 = binop\{\tau?\} v_3 E_4
5007
             8.1. e_1 = binop\{\tau?\} \ v_5 \ e_6 \ \text{and} \ v_3 \lesssim v_5 \ \text{and} \ E_4[e_0] \lesssim e_6
5008
5009
                by inversion \lesssim
5010
             8.2. QED
5011
                by the induction hypothesis
5012
         9. CASE E_0 = \text{dyn } b_0 E_3
5013
5014
             9.1. e_1 = \text{dyn } b_1 \ e_4 \text{ and } E_3[e_0] \lesssim e_4
5015
                by inversion \lesssim
5016
             9.2. QED
5017
5018
                by the induction hypothesis
5019
          10. CASE E_0 = \text{stat } b_0 E_3
5020
             10.1. e_1 = \text{stat } b_1 \ e_4 \text{ and } E_3[e_0] \lesssim e_4
5021
                by inversion \lesssim
5022
             10.2. QED
5024
                by the induction hypothesis
5025
5026
5027
             Lemma 8.11 (A context-matching). If e_0 \lesssim E_2[e_2] and e_2 \notin v and e_0 does not contain a subterm BndryErr (b,v)
5028
         then \exists E_1, e_1 such that e_0 = E_1[e_1] and E_1 \lesssim E_2 and e_1 \lesssim e_2
5030
             PROOF. By induction on the structure of E_2
5031
         1. CASE E_2 = []
5032
            trivial, E_1 = [] and e_1 = e_0
5033
5034
         2. Case E_2 = \langle E_3, e_3 \rangle
5035
             2.1. e_0 = \langle e_4, e_5 \rangle \lesssim \langle E_3[e_2], e_3 \rangle
5036
                by inversion \lesssim
5037
5038
             2.2. QED
5039
                by the induction hypothesis
5040
         3. Case E_2 = \langle v_3, E_3 \rangle
5041
             3.1. e_0 = \langle e_4, e_5 \rangle \lesssim \langle v_3, E_3[e_2] \rangle
5042
                by inversion ≤
5043
5044
         2019-10-03 17:26. Page 97 of 1-148.
```

```
5045
             3.2. QED
5046
                 by the induction hypothesis
5047
          4. CASE E_2 = app\{\tau?_0\} E_3 e_3
5048
             4.1. e_0 = \operatorname{app}\{\tau_{0}^{2}\} e_4 e_5 \lesssim \operatorname{app}\{\tau_{0}^{2}\} E_3[e_2] e_3
5049
5050
                 by inversion \lesssim
5051
             4.2. QED
5052
                by the induction hypothesis
          5. CASE E_2 = app\{\tau?_0\} v_3 E_3
             5.1. e_0 = \operatorname{app}\{\tau_{0}^{2}\} e_4 e_5 \lesssim \operatorname{app}\{\tau_{0}^{2}\} v_3 E_3[e_2]
                by inversion \lesssim
5057
             5.2. QED
5058
                 by the induction hypothesis
5059
          6. Case E_2 = unop\{\tau?\} E_3
5060
5061
             6.1. e_0 = unop\{\tau?\} e_4 \lesssim unop\{\tau?\} E_3[e_2]
5062
                 by inversion ≤
5063
             6.2. QED
5064
                by the induction hypothesis
5065
5066
          7. CASE E_2 = binop\{\tau?\} E_3 e_3
5067
             7.1. e_0 = binop\{\tau?\} e_4 e_5 \lesssim binop\{\tau?\} E_3[e_2] e_3
                by inversion \lesssim
5070
             7.2. QED
5071
                 by the induction hypothesis
5072
          8. CASE E_2 = binop\{\tau?\} v_3 E_3
5073
             8.1. e_0 = binop\{\tau?\} e_4 e_5 \lesssim binop\{\tau?\} v_3 E_3[e_2]
5074
5075
                 by inversion ≤
5076
             8.2. QED
5077
                by the induction hypothesis
5078
          9. CASE E_2 = \text{dyn } b_0 E_3
5079
             9.1. e_0 = \text{dyn } b_0 \ e_4 \lesssim \text{dyn } b_2 \ E_3[e_2]
                 by inversion \lesssim
             9.2. QED
                 by the induction hypothesis
5084
          10. CASE E_2 = \text{stat } b_0 E_3
5085
5086
             10.1. e_0 = \operatorname{stat} b_0 \ e_4 \lesssim \operatorname{stat} b_1 \ E_3[e_2]
5087
                by inversion \lesssim
5088
             10.2. QED
5089
                by the induction hypothesis
5090
5091
          11. CASE E_2 = \operatorname{trace} b_0 b_1 \overline{b}_2 E_3
5092
             11.1. e_0 = \text{stat } b_3 \text{ dyn } b_4 e_4 \text{ and } e_4 \lesssim E_3[e_0]
5093
                 by inversion \lesssim
5094
             11.2. QED
```

```
5097
                      by the induction hypothesis
5098
                                                                                                                                                                                                                                   5099
5100
                 LEMMA 8.12. If (dyn \ b_0 \ v_0) and (dyn \ b_1 \ v_1) are reduced WF expressions and dyn \ b_0 \ v_0 \lesssim dyn \ b_1 \ v_1 then dyn \ b_0 \ v_0 \rightarrow^*_N
5101
            e_2 and dyn b_1 v_1 \rightarrow_A^* e_3 then e_2 \lesssim e_3
5102
5103
                 PROOF. By case analysis of v_0 \lesssim v_1.
5104
             1. Case v_0 = i_0 \lesssim i_0 = v_1
5105
                 1.1. SCASE tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
5106
5107
                      1.1.1. dyn b_0 \ v_0 \rhd_{N} v_0
5108
                          by definition \triangleright_{N}
5109
                      1.1.2. tag-match(\lfloor \tau_1 \rfloor, \upsilon_1)
5110
                          by lemma 8.17
5111
                      1.1.3. QED
5112
5113
                           dyn b_1 v_1 \triangleright_A v_1
5114
                 1.2. SCASE \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)
5115
                      1.2.1. QED
5116
                           \mathsf{dyn}\,b_0\,\,v_0\, \rhd_{\mathsf{N}} \, \mathsf{BndryErr}\,(b_0,v_0) \lesssim \mathsf{dyn}\,b_1\,\,v_1
5117
5118
             2. CASE v_0 = i_0 \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_2 i_0 = v_1
5119
                 2.1. SCASE tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
5120
                      2.1.1. dyn b_0 v_0 \triangleright_{\mathsf{N}} v_0
5121
5122
                          by definition \triangleright_{N}
5123
                      2.1.2. tag-match(\lfloor \tau_1 \rfloor, \upsilon_1)
5124
                          by lemma 8.17
5125
                      2.1.3. QED
5126
5127
                           dyn b_1 v_1 \triangleright_{A} v_1
5128
                 2.2. Scase \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)
5129
                      2.2.1. QED
5130
                           \mathsf{dyn}\,b_0\,v_0\,\rhd_{\mathsf{N}}\,\mathsf{BndryErr}\,(b_0,v_0)\lesssim \mathsf{dyn}\,b_1\,v_1
5131
            3. CASE v_0 = \langle v_2, v_3 \rangle \lesssim \langle v_4, v_5 \rangle = v_1
5132
5133
                 3.1. SCASE tag-match (|\tau_0|, v_0)
5134
                      3.1.1. let b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) and b_1 = (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)
5135
                      3.1.2. v_2 \lesssim v_4 and v_3 \lesssim v_5
5136
                          by inversion \le \
5137
5138
                     3.1.3. \tau_0 = \tau_2 \times \tau_3 \leqslant : \tau_4 \times \tau_5 = \tau_1
5139
                          by 3.1 and inversion ≤:
5140
                      3.1.4. \operatorname{dyn}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_0 \rhd_{\mathsf{N}} \langle \operatorname{dyn}(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_2, \operatorname{dyn}(\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rangle
5141
5142
                          by definition \triangleright_{N}
5143
                      3.1.5. tag-match(\lfloor \tau_1 \rfloor, \upsilon_1)
5144
                          by lemma 8.17
5145
                      3.1.6. dyn b_1 v_1 \triangleright_{A} \text{mon } b_1 v_1
5146
                          by definition \triangleright_{A}
5147
5148
             2019-10-03 17:26. Page 99 of 1-148.
```

```
3.1.7. \operatorname{dyn}\left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) v_2 \to_{\mathsf{N}}^* e_6 \lesssim \operatorname{mon}\left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) v_4
5149
5150
                                                 and dyn (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rightarrow_N^* e_7 \lesssim \text{mon} \ (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) \ v_5
5151
                                      by lemma 8.13
5152
                                3.1.8. QED
5153
                                       either e_6 or e_7 \in BndryErr(b, v) or:
5154
5155
                                                                                                   e_6 \lesssim \operatorname{mon}^?(\ell_0 \triangleleft \tau_4 \triangleleft \ell_1) v_4 \qquad e_7 \lesssim \operatorname{mon}^?(\ell_0 \triangleleft \tau_5 \triangleleft \ell_1) v_5
5156
                                                                                                                                \langle e_6, e_7 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) \langle v_4, v_5 \rangle
5157
                         3.2. SCASE \neg tag-match(|\tau_0|, v_0)
                                3.2.1. QED
5160
                                       \mathsf{dyn}\ b_0\ v_0\ \triangleright_{\mathsf{N}}\ \mathsf{BndryErr}\ (b_0,v_0)\lesssim \mathsf{dyn}\ b_1\ v_1
5161
                   4. CASE v_0 = \langle v_2, v_3 \rangle \lesssim \text{mon} (\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) \langle v_4, v_5 \rangle = v_1
5162
                         4.1. SCASE tag-match (|\tau_0|, v_0)
5163
5164
                                 4.1.1. let b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)
5165
                                                and b_1 = (\ell_0 \triangleleft \tau_1 \triangleleft \ell_1)
5166
                                4.1.2. v_2 \lesssim \text{mon}^? (\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3) v_4 \text{ and } v_3 \lesssim \text{mon}^? (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) v_5
5167
                                      by inversion ≤
5168
5169
                                4.1.3. \tau_0 = \tau_2 \times \tau_3 \leqslant : \tau_4 \times \tau_5 = \tau_1
5170
                                      by 4.1 and inversion ≤:
5171
                                4.1.4. \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) v_0 \rhd_{\mathsf{N}} \left\langle \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) v_2, \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1\right) v_3 \right\rangle
5172
                                       by definition ⊳<sub>N</sub>
5174
                                4.1.5. tag-match(\lfloor \tau_1 \rfloor, \upsilon_1)
5175
                                      by lemma 8.17
5176
                                4.1.6. dyn b_1 v_1 \rhd_{\mathsf{A}} \mathsf{mon} b_1 v_1
5177
5178
                                      by definition \triangleright_{\!\scriptscriptstyle \Delta}
5179
                                4.1.7. \ \operatorname{dyn} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) v_2 \to_{\mathsf{N}}^* e_6 \lesssim \operatorname{mon}^? \left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\operatorname{mon}^? \left(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3\right) v_4\right)
5180
                                                and \operatorname{dyn}(\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \to_{\mathsf{N}}^* \ e_7 \lesssim \operatorname{mon}^?(\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) \ (\operatorname{mon}^?(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) \ v_5)
5181
                                      by lemma 8.13
5182
5183
                                4.1.8. QED
5184
                                       either e_6 or e_7 \in BndryErr(b, v) or:
                                             e_6 \lesssim \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\mathsf{mon}^? \left(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3\right) \upsilon_4\right) \qquad e_7 \lesssim \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1\right) \left(\mathsf{mon}^? \left(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3\right) \upsilon_5\right)
5186
                                                                                                 \langle e_6, e_7 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) (\text{mon} (\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) \langle v_4, v_5 \rangle)
5187
5188
                         4.2. SCASE \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)
5189
                                4.2.1. QED
5190
                                       \mathsf{dyn}\ b_0\ v_0 \, \rhd_{\!\mathsf{N}} \, \mathsf{BndryErr}\,(b_0,v_0) \lesssim \mathsf{dyn}\ b_1\ v_1
5191
                   5. CASE v_0 = \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_2 \langle v_4, v_5 \rangle = v_1
5192
5193
                         5.1. SCASE tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
5194
                                5.1.1. let b_0 = (\ell_0 \triangleleft \tau_0 \triangleleft \ell_1)
5195
                                                and b_1 = (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)
5196
                                5.1.2. v_2 \lesssim add-trace (\overline{b}_2, v_4) and v_3 \lesssim add-trace (\overline{b}_2, v_5)
5197
                                      by inversion \lesssim
```

```
5201
                                5.1.3. \tau_0 = \tau_2 \times \tau_3 \leqslant : \tau_4 \times \tau_5 = \tau_1
5202
                                      by 5.1 and inversion ≤:
5203
                                5.1.4. \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) v_0 \rhd_{\mathsf{N}} \left\langle \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) v_2, \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1\right) v_3 \right\rangle
5204
                                       by definition \triangleright_{N}
5205
5206
                                5.1.5. tag-match(\lfloor \tau_1 \rfloor, \upsilon_1)
5207
                                      by lemma 8.17
5208
                                5.1.6. dyn b_1 v_1 \rhd_{\mathsf{A}} \mathsf{mon} b_1 v_1
5209
                                      by definition \triangleright_{A}
5210
                                5.1.7. dyn (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) v_2 \rightarrow_N^* e_6 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) (add-trace(\overline{b}_2, v_4))
5212
                                                 and dyn (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) v_3 \rightarrow_{\mathsf{N}}^* e_7 \lesssim \mathsf{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (add-trace(\overline{b}_2, v_5))
5213
                                      by lemma 8.13
5214
                                5.1.8. QED
5215
5216
                                       either e_6 or e_7 \in BndryErr(b, v) or:
5217
                                                        e_6 \lesssim \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\mathit{add-trace}(\overline{b}_2, v_4)\right) \qquad e_7 \lesssim \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1\right) \left(\mathit{add-trace}(\overline{b}_2, v_5)\right)
5218
                                                                                                                  \langle e_6, e_7 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) (\text{trace}_{\mathbf{v}} \, \overline{b}_2 \, \langle v_4, v_5 \rangle)
5219
5220
                          5.2. SCASE \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)
5221
                                5.2.1. QED
5222
                                       \operatorname{\mathsf{dyn}} b_0 \ v_0 \, \rhd_{\! \mathsf{N}} \, \operatorname{\mathsf{BndryErr}} (b_0, v_0) \lesssim \operatorname{\mathsf{dyn}} b_1 \ v_1
5223
                   6. CASE v_0 = \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_2 \left( \operatorname{mon} \left( \ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3 \right) \langle v_4, v_5 \rangle \right) = v_1
5224
5225
                          6.1. SCASE tag-match (|\tau_0|, v_0)
5226
                                6.1.1. let b_0 = (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)
5227
                                                and b_1 = (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)
5228
                                6.1.2. v_2 \lesssim add-trace (\overline{b}_2, (\text{mon}^?(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3) \ v_4)) and v_3 \lesssim add-trace (\overline{b}_2, (\text{mon}^?(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) \ v_5))
5229
5230
                                      by inversion ≤
                                6.1.3. \tau_0 = \tau_2 \times \tau_3 \leqslant : \tau_4 \times \tau_5 = \tau_1
5232
                                      by 6.1 and inversion ≤:
5233
                                6.1.4. \operatorname{dyn}\left(\ell_{0} \blacktriangleleft \tau_{0} \blacktriangleleft \ell_{1}\right) \upsilon_{0} \rhd_{N} \left\langle \operatorname{dyn}\left(\ell_{0} \blacktriangleleft \tau_{2} \blacktriangleleft \ell_{1}\right) \upsilon_{2}, \operatorname{dyn}\left(\ell_{0} \blacktriangleleft \tau_{3} \blacktriangleleft \ell_{1}\right) \upsilon_{3} \right\rangle
5234
5235
                                       by definition \triangleright
5236
                                6.1.5. tag-match(\lfloor \tau_1 \rfloor, \upsilon_1)
                                       by lemma 8.17
                                6.1.6. dyn b_1 v_1 \rhd_{A} \text{mon } b_1 v_1
5239
                                      by definition \triangleright_{A}
5240
5241
                                6.1.7. \ \mathsf{dyn} \ (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_2 \to_{\mathsf{N}}^* e_6 \lesssim \mathsf{mon}^? \ (\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) \ (\mathit{add-trace} (\overline{b}_2, (\mathsf{mon}^? (\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3) \ v_4)))
5242
                                                and dyn (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) v_3 \rightarrow_N^* e_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (add-trace(\bar{b_2}, (\text{mon}^?(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) v_5)))
5243
                                      by lemma 8.13
5244
5245
                                6.1.8. QED
5246
                                       either e_6 or e_7 \in BndryErr(b, v) or:
5247
                                                                                            e_6 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) (add\text{-}trace(\overline{b}_2, (\text{mon}^? (\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3) \ v_4)))
5248
                                                                                            e_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (add\text{-trace}(\overline{b}_2, (\text{mon}^? (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) v_5)))
5249
5250
                                                                                   \langle e_6, e_7 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) (\text{trace}_{\mathbf{v}} \overline{b}_2 (\text{mon} (\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) \langle v_4, v_5 \rangle))
5252
```

```
5253
                  6.2. SCASE \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)
5254
                       6.2.1. QED
5255
                             \mathsf{dyn}\ b_0\ v_0 \, \rhd_{\! {\textstyle \,\,{\sf N}}} \, \mathsf{BndryErr}\, (b_0,v_0) \lesssim \mathsf{dyn}\ b_1\ v_1
5256
              7. CASE v_0 = \langle v_2, v_3 \rangle \lesssim \text{mon } b_2 \text{ (trace}_{\mathbf{v}} \overline{b}_3 \langle v_4, v_5 \rangle) = v_1
5257
5258
                   7.1. Contradiction:
5259
                        \cdot \vdash_{\mathsf{A}} v_1 : \mathcal{U}
5260
              8. Case v_0 = \langle v_2, v_3 \rangle \lesssim \text{mon } b_2 \text{ (mon } b_3 \langle v_4, v_5 \rangle) = v_1
5261
                   8.1. Contradiction:
5262
                       by lemma 7.10
5264
              9. CASE v_0 = \langle v_2, v_3 \rangle \lesssim \text{mon } b_2 \left( \text{trace}_{\mathbf{v}} \, \overline{b_3} \left( \text{mon } b_4 \, \langle v_4, v_5 \rangle \right) \right) = v_1
5265
                   9.1. Contradiction:
5266
                       by lemma 7.10
5267
              10. CASE v_0 = \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \overline{b}_2 \pmod{b_3 \pmod{b_4 \langle v_4, v_5 \rangle}} = v_1
5268
5269
                   10.1. Contradiction:
5270
                       by lemma 7.10
5271
              11. CASE v_0 = \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \bar{b}_2 \pmod{b_3} (\text{trace}_{\mathbf{v}} \bar{b}_4 \pmod{b_5} \langle v_4, v_5 \rangle)) = v_1
5272
                   11.1. Contradiction:
5273
5274
                       by lemma 7.10
5275
              12. CASE v_0 = \lambda x_2. e_2 \lesssim \lambda x_2. e_3 = v_1
5276
                   12.1. SCASE tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
5277
5278
                        12.1.1. QED
5279
                             \mathsf{dyn}\;b_0\;v_0\mathrel{\rhd_{\!\!\mathsf{N}}}\;\mathsf{mon}\;b_0\;v_0\;\mathsf{and}\;\mathsf{dyn}\;b_1\;v_1\mathrel{\rhd_{\!\!\mathsf{A}}}\;\mathsf{mon}\;b_1\;v_1
5280
                   12.2. SCASE \neg tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
5281
5282
5283
                             \mathsf{dyn}\ b_0\ v_0\ {
hd}_\mathsf{N}\ \mathsf{BndryErr}\ (b_0,v_0) \lesssim \mathsf{dyn}\ b_1\ v_1
5284
              13. Case v_0 = \lambda(x_2 : \tau_2). e_2 \lesssim \lambda(x_2 : \tau_2). e_3 = v_1
5285
                   13.1. Contradiction:
5286
                        \cdot \vdash_{\mathsf{N}} \upsilon_0 : \mathcal{U}
5287
5288
              14. CASE v_0 = \text{mon } b_2 \pmod{b_3 v_2} \lesssim \text{trace}_{v_0} b_4 b_5 (\lambda x_0. e_3) = v_1
                   14.1. SCASE tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
                        14.1.1. dyn b_0 v_0 \triangleright_{\mathsf{N}} \mathsf{mon} b_0 v_0
5291
                            by definition \triangleright_{N}
5292
                        14.1.2. tag-match(\lfloor \tau_1 \rfloor, \upsilon_1)
5293
5294
                            by lemma 8.17
5295
                        14.1.3. dyn b_1 v_1 \rhd_{\mathsf{A}} \mathsf{mon} \ b_1 v_1
5296
                            by definition \triangleright_{A}
5297
5298
                        14.1.4. QED
5299
5300
                                                                                        \operatorname{mon} b_2 (\operatorname{mon} b_3 v_2) \lesssim \operatorname{trace}_{v} b_4 b_5 (\lambda x_0. e_3)
5301
                                                                     \operatorname{\mathsf{mon}} b_0 \left( \operatorname{\mathsf{mon}} b_2 \left( \operatorname{\mathsf{mon}} b_3 v_2 \right) \right) \lesssim \operatorname{\mathsf{mon}} b_1 \left( \operatorname{\mathsf{trace}}_{\mathsf{v}} b_4 b_5 \left( \lambda x_0. \, e_3 \right) \right)
5302
```

```
14.2. SCASE \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)
5305
5306
                         14.2.1. QED
5307
                              \mathsf{dyn}\,b_0\,v_0\,\rhd_{\mathsf{N}}\,\mathsf{BndryErr}\,(b_0,v_0)\lesssim \mathsf{dyn}\,b_1\,v_1
5308
               15. CASE v_0 = \text{mon } b_2 \text{ (mon } b_3 v_2) \lesssim (\text{trace}_v b_4 b_5 \overline{b}_6 (\lambda x_3. e_3)) = v_1
5309
5310
                    15.1. tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
5311
                          15.1.1. dyn b_0 v_0 \triangleright_{N} \text{mon } b_0 v_0
5312
                              by definition \triangleright_{N}
5313
                         15.1.2. tag-match(\lfloor \tau_1 \rfloor, \upsilon_1)
5314
5315
                              by lemma 8.17
5316
                         15.1.3. dyn b_1 v_1 \rhd_{A} \text{mon } b_1 v_1
5317
                              by definition \triangleright_{A}
5318
                         15.1.4. QED
5319
5320
                                                                                        mon b_2 (mon b_3 v_2) \lesssim (trace, b_4b_5\overline{b}_6 (\lambda x_3. e_3))
5321
5322
                                                                       \operatorname{\mathsf{mon}} b_0 \left( \operatorname{\mathsf{mon}} b_2 \left( \operatorname{\mathsf{mon}} b_3 v_2 \right) \right) \lesssim \operatorname{\mathsf{mon}} b_1 \left( \operatorname{\mathsf{trace}}_{\mathsf{v}} b_4 b_5 \overline{b}_6 \left( \lambda x_3. e_3 \right) \right)
5323
                    15.2. \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)
5324
5325
                         15.2.1. QED
5326
                              \operatorname{\mathsf{dyn}} b_0 \ v_0 \, \rhd_{\!_{\mathbf N}} \, \operatorname{\mathsf{BndryErr}} (b_0, v_0) \lesssim \operatorname{\mathsf{dyn}} b_1 \ v_1
5327
               16. CASE v_0 = \text{mon } b_2 \ v_2 \lesssim \text{mon } b_3 \ v_3 = v_1
5328
                    16.1. SCASE tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
5329
5330
                         16.1.1. dyn b_0 \ v_0 \rhd_{\mathsf{N}} \ \mathsf{mon} \ b_0 \ v_0
5331
                              by definition \triangleright_{N}
5332
                         16.1.2. tag-match(|\tau_1|, v_1)
5333
                              by lemma 8.17
5334
                         16.1.3. dyn b_1 v_1 \triangleright_{A} \text{mon } b_1 v_1
5336
                              by definition \triangleright_{\!\!\!A}
5337
                         16.1.4. QED
5338
5339
                                                                                                                \operatorname{\mathsf{mon}} b_2 \ v_2 \lesssim \operatorname{\mathsf{mon}} b_3 \ v_3
5340
                                                                                             \operatorname{\mathsf{mon}} b_0 \ (\operatorname{\mathsf{mon}} b_2 \ v_2) \lesssim \operatorname{\mathsf{mon}} b_1 \ (\operatorname{\mathsf{mon}} b_3 \ v_3)
5342
                    16.2. SCASE \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)
5343
5344
5345
                              \mathsf{dyn}\,b_0\,v_0\,\rhd_{\mathsf{N}}\,\mathsf{BndryErr}\,(b_0,v_0)\lesssim \mathsf{dyn}\,b_1\,v_1
5346
5347
5348
                    \text{LEMMA 8.13. } \textit{If} \; \cdot \vdash_{\mathsf{N}} v_0 : \mathcal{U} \; \textit{and} \; \cdot \vdash_{\mathsf{A}} v_1 : \mathcal{U} \; \textit{and} \; v_0 \lesssim v_1 \; \textit{and} \; b_0 \leqslant : b_1 \; \textit{then} \; \text{dyn} \; b_0 \; v_0 \; \mathop{\longrightarrow}^*_{\mathsf{N}} \; e_2 \; \textit{and} \; e_2 \lesssim \mathsf{mon}^? \; b_1 \; v_1.
5349
                    PROOF. By induction on v_0 via case analysis of v_0 \lesssim v_1.
5350
5351
               1. CASE i_0 \lesssim i_0
5352
                    1.1. SCASE tag-match (\lfloor \tau_0 \rfloor, v_0)
5353
                         1.1.1. dyn b_0 \ v_0 \rhd_{N} \ v_0
5354
                              by definition \triangleright_{N}
5355
5356
               2019-10-03 17:26. Page 103 of 1-148.
```

```
1.1.2. QED
5357
5358
                                        mon^{?} b_1 v_1 = v_1
5359
                           1.2. SCASE \neg tag\text{-}match(|\tau_0|, v_0)
5360
                                  1.2.1. QED
5361
5362
                                        \operatorname{dyn} b_0 v_0 \rhd_{\mathsf{N}} \operatorname{BndryErr}(b_0, v_0) \lesssim \operatorname{mon}^? b_1 v_1
5363
                    2. CASE i_0 \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_2 i_0
5364
                           2.1. SCASE tag-match (|\tau_0|, v_0)
5365
                                 2.1.1. dyn b_0 \ v_0 \rhd_{N} \ v_0
                                        by definition \triangleright_{N}
5368
                                 2.1.2. QED
5369
                                        mon? b_1 v_1 = v_1
5370
                           2.2. SCASE \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)
5371
5372
                                 2.2.1. QED
5373
                                        \operatorname{dyn} b_0 v_0 \rhd_{\mathsf{N}} \operatorname{BndryErr}(b_0, v_0) \lesssim \operatorname{mon}^? b_1 v_1
5374
                    3. Case \langle v_2, v_3 \rangle \lesssim \langle v_4, v_5 \rangle
5375
                           3.1. SCASE tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
5376
                                 3.1.1. let b_0 = (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1) and b_1 = (\ell_0 \blacktriangleleft \tau_4 \times \tau_5 \blacktriangleleft \ell_1)
5377
5378
                                 3.1.2. \operatorname{dyn} b_0 \ v_0 \ \triangleright_{\mathbb{N}} \langle \operatorname{dyn} (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_2, \operatorname{dyn} (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rangle
5379
                                        by definition \triangleright_{N}
                                 3.1.3. v_2 \lesssim v_4 and v_3 \lesssim v_5
                                        by inversion \lesssim
                                 3.1.4. \operatorname{dyn}\left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) v_2 \to_N^* e_6 \lesssim \operatorname{mon}^2\left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) v_4
5383
5384
                                                  and dyn (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) v_3 \rightarrow_N^* e_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) v_5
5385
                                        by the induction hypothesis
5386
5387
                                3.1.5. QED
5388
                                        either e_6 or e_7 \in BndryErr(b, v), or:
5389
                                                                                                       \underline{e_6} \lesssim \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \upsilon_4 \qquad \underline{e_7} \lesssim \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1\right) \upsilon_5
5390
                                                                                                                                                \langle e_6, e_7 \rangle \lesssim \text{mon } b_1 \langle v_4, v_5 \rangle
5391
5392
                           3.2. SCASE tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
                                        \operatorname{dyn} b_0 v_0 \rhd_{\mathsf{N}} \operatorname{BndryErr}(b_0, v_0) \lesssim \operatorname{mon}^? b_1 v_1
5395
                    4. Case \langle v_2, v_3 \rangle \lesssim \text{mon} (\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) \langle v_4, v_5 \rangle
5396
5397
                           4.1. SCASE tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
5398
                                  4.1.1. let b_0 = (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1) and b_1 = (\ell_0 \blacktriangleleft \tau_4 \times \tau_5 \blacktriangleleft \ell_1)
5399
                                 4.1.2. \operatorname{\mathsf{dyn}} b_0 \ v_0 \ \triangleright_{\mathsf{N}} \ \langle \operatorname{\mathsf{dyn}} (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_2, \operatorname{\mathsf{dyn}} (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rangle
5400
5401
                                        by definition ⊳<sub>N</sub>
5402
                                 4.1.3. v_2 \lesssim \text{mon}^2 (\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3) v_4 \text{ and } v_3 \lesssim \text{mon}^2 (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) v_5
5403
                                        by inversion ≤
5404
                                4.1.4. \operatorname{dyn}\left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) v_2 \to_{\mathsf{N}}^* e_6 \lesssim \operatorname{mon}^?\left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\operatorname{mon}^?\left(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3\right) v_4\right) and \operatorname{dyn}\left(\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1\right) v_3 \to_{\mathsf{N}}^* e_7 \lesssim \operatorname{mon}^?\left(\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1\right) \left(\operatorname{mon}^?\left(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3\right) v_5\right)
5405
```

```
5409
                                   by the induction hypothesis
5410
                             4.1.5. QED
5411
                                    either e_6 or e_7 \in BndryErr(b, v), or:
5412
                                          e_6 \lesssim \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\mathsf{mon}^? \left(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3\right) v_4\right) \qquad e_7 \lesssim \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1\right) \left(\mathsf{mon}^? \left(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3\right) v_5\right)
5413
5414
                                                                                                      \langle e_6, e_7 \rangle \lesssim \text{mon } b_1 \text{ (mon } (\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) \langle v_4, v_5 \rangle)
5415
                       4.2. SCASE tag-match (|\tau_0|, v_0)
5416
                             4.2.1. QED
5417
                                    \mathsf{dyn}\ b_0\ v_0 \mathrel{\triangleright_{\mathsf{N}}} \mathsf{BndryErr}\ (b_0,v_0) \lesssim \mathsf{mon}^?\ b_1\ v_1
5418
5419
                  5. CASE \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_2 \langle v_4, v_5 \rangle
5420
                       5.1. SCASE tag-match (|\tau_0|, v_0)
5421
                             5.1.1. let b_0 = (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1) and b_1 = (\ell_0 \blacktriangleleft \tau_4 \times \tau_5 \blacktriangleleft \ell_1)
5422
                             5.1.2. dyn b_0 \ v_0 \rhd_{\mathsf{N}} \langle \mathsf{dyn} \left( \ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1 \right) v_2, \mathsf{dyn} \left( \ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1 \right) v_3 \rangle
5423
5424
                                    by definition \triangleright_{N}
5425
                             5.1.3. v_2 \lesssim add-trace (\bar{b}_2, v_4) and v_3 \lesssim add-trace (\bar{b}_2, v_5)
5426
                                   by inversion ≤
5427
                            5.1.4. \mathsf{dyn}\,(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1)\; v_2 \to_\mathsf{N}^* e_6 \lesssim \mathsf{mon}^?\,(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1)\,(\mathit{add-trace}\,(\overline{b}_2, v_4))
5428
5429
                                            and dyn (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) v_3 \rightarrow^*_{N} e_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (add-trace(\overline{b}_2, v_5))
5430
                                   by the induction hypothesis
5431
                             5.1.5. QED
5432
                                    either e_6 or e_7 \in BndryErr(b, v), or:
5433
5434
                                                   e_6 \lesssim \text{mon}^?(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) (add\text{-}trace(\overline{b}_2, v_4)) \qquad e_7 \lesssim \text{mon}^?(\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (add\text{-}trace(\overline{b}_2, v_5))
5435
                                                                                                                    \langle e_6, e_7 \rangle \lesssim \text{mon } b_1 \text{ (trace, } \overline{b}_2 \langle v_4, v_5 \rangle)
5436
5437
                       5.2. SCASE tag-match (|\tau_0|, v_0)
5438
5439
                                    \operatorname{dyn} b_0 v_0 \rhd_{\mathsf{N}} \operatorname{BndryErr}(b_0, v_0) \lesssim \operatorname{mon}^? b_1 v_1
5440
                 6. CASE \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_2 \langle v_4, v_5 \rangle
5441
                       6.1. SCASE tag-match (|\tau_0|, v_0)
5442
5443
                             6.1.1. let b_0 = (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1) and b_1 = (\ell_0 \blacktriangleleft \tau_4 \times \tau_5 \blacktriangleleft \ell_1)
5444
                             6.1.2. \operatorname{dyn} b_0 \ v_0 \ \triangleright_{\mathsf{N}} \ \langle \operatorname{dyn} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \ v_2, \operatorname{dyn} \left(\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1\right) \ v_3 \rangle
5445
                                   by definition \triangleright_{N}
5446
                             6.1.3. v_2 \lesssim add-trace (\overline{b}_2, v_4) and v_3 \lesssim add-trace (\overline{b}_2, v_5)
5447
5448
                                   by inversion \le \
5449
                            \text{6.1.4. dyn} \ (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_2 \to_{\mathsf{N}}^* \ e_6 \lesssim \mathsf{mon}^? \ (\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) \ (\mathit{add-trace} \ (\overline{b}_2, v_4))
5450
                                            and dyn (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) v_3 \rightarrow_N^* e_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (add-trace(\overline{b}_2, v_5))
5451
5452
                                   by the induction hypothesis
5453
                             6.1.5. QED
5454
                                    either e_6 or e_7 \in BndryErr(b, v), or:
5455
                                                   e_6 \lesssim \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\mathit{add-trace}(\overline{b}_2, v_4)\right) \qquad e_7 \lesssim \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1\right) \left(\mathit{add-trace}(\overline{b}_2, v_5)\right)
5456
                                                                                                                   \langle e_6, e_7 \rangle \leq \text{mon } b_1 \text{ (trace, } \overline{b}_2 \langle v_4, v_5 \rangle)
5457
5458
                       6.2. SCASE tag-match (|\tau_0|, v_0)
5459
5460
                 2019-10-03 17:26. Page 105 of 1-148.
```

```
6.2.1. QED
5461
5462
                                        \operatorname{dyn} b_0 v_0 \rhd_{\mathsf{N}} \operatorname{BndryErr}(b_0, v_0) \lesssim \operatorname{mon}^? b_1 v_1
5463
                   7. CASE \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_2 \left( \operatorname{mon} \left( \ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_1 \right) \langle v_4, v_5 \rangle \right)
5464
                          7.1. SCASE tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
5465
5466
                                  7.1.1. let b_0 = (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1) and b_1 = (\ell_0 \blacktriangleleft \tau_4 \times \tau_5 \blacktriangleleft \ell_1)
5467
                                 7.1.2. dyn b_0 \ v_0 \ \triangleright_{\mathbb{N}} \ \langle \mathsf{dyn} \ (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_2, \mathsf{dyn} \ (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rangle
5468
                                        by definition ⊳<sub>N</sub>
5469
                                 7.1.3. v_2 \lesssim add-trace (\overline{b}_2, (\text{mon}^?(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_7) \ v_4)) and v_3 \lesssim add-trace (\overline{b}_2, (\text{mon}^?(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_7) \ v_5))
                                        by inversion \lesssim
5472
                                7.1.4. \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \ v_2 \to_{\mathsf{N}}^* \ e_6 \lesssim \mathsf{mon}^2\left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\mathit{add-trace}\left(\overline{b}_2, \left(\mathsf{mon}^2\left(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_7\right) \ v_4\right)\right)\right)
5473
                                                  \text{ and dyn } (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \overset{\cdot \cdot \cdot}{\upsilon_3} \rightarrow_{\mathsf{N}}^* e_7 \lesssim \mathsf{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) \, (\mathit{add-trace} (\overline{b}_2, (\mathsf{mon}^? \, (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_7) \, \upsilon_5)))
5474
                                       by the induction hypothesis
5475
5476
                                 7.1.5. QED
5477
                                        either e_6 or e_7 \in BndryErr(b, v), or:
5478
                                                                                               e_6 \lesssim \mathsf{mon}^?(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) \left( \mathit{add-trace}(\overline{b}_2, (\mathsf{mon}^?(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_7) \ v_4)) \right)
5479
                                                                                               e_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (add\text{-trace}(\overline{b}_2, (\text{mon}^? (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_7) v_5)))
5480
5481
                                                                                                   \langle e_6, e_7 \rangle \lesssim \text{mon } b_1 \text{ (trace}_{\mathbf{v}} \overline{b}_2 \text{ (mon } (\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) \langle v_4, v_5 \rangle))
5482
                          7.2. SCASE tag-match (\lfloor \tau_0 \rfloor, v_0)
5483
5484
                                        \operatorname{dyn} b_0 v_0 \rhd_{\mathsf{N}} \operatorname{BndryErr}(b_0, v_0) \lesssim \operatorname{mon}^? b_1 v_1
5485
5486
                    8. CASE \langle v_2, v_3 \rangle \lesssim \text{mon } b_2 \left( \text{trace}_{\mathbf{v}} \, \overline{b}_3 \, \langle v_4, v_5 \rangle \right)
5487
                          8.1. Contradiction:
5488
                                  \cdot \vdash_{\mathsf{A}} v_1 : \mathcal{U}
5489
5490
                    9. CASE \langle v_2, v_3 \rangle \lesssim \text{mon } b_2 \pmod{b_3} \langle v_4, v_5 \rangle
5491
                          9.1. v_2 \lesssim \text{mon}^? b_2 \text{ (mon}^? b_3 v_4)
5492
                                      and v_3 \leq \text{mon}^2 b_2 \text{ (mon}^2 b_3 v_5)
5493
                                 by inversion ≤
5494
                          9.2. \operatorname{dyn}\left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) \, v_0 \, \blacktriangleright_{\mathsf{N}} \, \left\langle \operatorname{dyn}\left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \, v_2, \operatorname{dyn}\left(\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1\right) \, v_3 \right\rangle
5495
                                 by definition \triangleright_N
                          9.3. \operatorname{dyn}\left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) v_2 \to_{\mathsf{N}}^* v_6 \lesssim \operatorname{mon}^?\left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\operatorname{mon}^? b_2 \left(\operatorname{mon}^? b_3 \ v_4\right)\right)
                                      and dyn (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) v_3 \rightarrow^*_{\mathsf{N}} v_7 \lesssim \mathsf{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\mathsf{mon}^? b_2 (\mathsf{mon}^? b_3 v_5))
                                 by the induction hypothesis
5500
5501
                          9.4. QED
5502
5503
                                            v_6 \lesssim \text{mon}^2(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) (\text{mon}^2 b_2 (\text{mon}^2 b_3 v_4))
                                                                                                                                                                                     v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^? b_2 (\text{mon}^? b_3 v_5))
5504
                                                                                                         \langle v_6, v_7 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) (\text{mon } b_2 (\text{mon } b_3 \langle v_4, v_5 \rangle))
5505
5506
                    10. CASE \langle v_2, v_3 \rangle \lesssim \text{mon } b_2 \text{ (trace}_{\mathbf{v}} \overline{b}_3 \text{ (mon } b_4 \langle v_4, v_5 \rangle))
5507
                           10.1. v_2 \lesssim \text{mon}^2 b_2 (\text{trace}_{v} \bar{b}_3 (\text{mon}^2 b_4 v_4))
5508
                                          and v_3 \lesssim \text{mon}^2 b_2 \text{ (trace}_{v} \overline{b}_3 \text{ (mon}^2 b_4 v_5))
5509
                                 by inversion ≤
5510
```

```
5513
                            10.2. \operatorname{dyn}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_0 \blacktriangleright_{N} \langle \operatorname{dyn}(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) v_2, \operatorname{dyn}(\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) v_3 \rangle
5514
                                  by definition \triangleright_{N}
5515
                            10.3. \operatorname{dyn}\left(\ell_{0} \blacktriangleleft \tau_{2} \blacktriangleleft \ell_{1}\right) v_{2} \rightarrow_{N}^{*} v_{6} \lesssim \operatorname{mon}^{?}\left(\ell_{0} \blacktriangleleft \tau_{4} \blacktriangleleft \ell_{1}\right) \left(\operatorname{mon}^{?} b_{2} \left(\operatorname{trace}_{v} \overline{b}_{3} \left(\operatorname{mon}^{?} b_{4} \ v_{4}\right)\right)\right)
5516
                                            and dyn (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rightarrow_N^* v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^? b_2 (\text{trace}_v \overline{b}_3 (\text{mon}^? b_4 \ v_5)))
5517
5518
                                  by the induction hypothesis
5519
                            10.4. QED
5520
5521
                                                                                                          v_6 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) (\text{mon}^? b_2 (\text{trace}_v \overline{b}_3 (\text{mon}^? b_4 v_4)))
5522
                                                                                                         v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^? b_2 (\text{trace}_{v} \overline{b}_3 (\text{mon}^? b_4 v_5)))
5523
5524
                                                                                              \langle v_6, v_7 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) (\text{mon } b_2 (\text{trace}_{\mathbf{v}} \overline{b}_3 (\text{mon } b_4 \langle v_4, v_5 \rangle)))
5525
                     11. CASE \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \overline{b}_2 \pmod{b_3 \pmod{b_4 \langle v_4, v_5 \rangle}}
5526
                            11.1. v_2 \leq \text{mon}^{+?} \overline{b_2} (\text{mon}^? b_3 (\text{mon}^? b_4 v_4))
5527
                                            and v_3 \lesssim \text{mon}^{+?} \overline{b}_2 \text{ (mon}^? b_3 \text{ (mon}^? b_4 v_5))
5528
5529
                                  by inversion \le \cdots
5530
                            11.2. \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) v_0 \blacktriangleright_{\mathsf{N}} \left\langle \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) v_2, \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1\right) v_3 \right\rangle
5531
5532
                            11.3. \operatorname{dyn}\left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) v_2 \rightarrow_{\mathsf{N}}^* v_6 \lesssim \operatorname{mon}^{?}\left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\operatorname{mon}^{+?} \overline{b}_2 \left(\operatorname{mon}^? b_3 \left(\operatorname{mon}^? b_4 v_4\right)\right)\right)
5533
5534
                                           and dyn (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) v_3 \rightarrow_N^* v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^+? \overline{b_2} (\text{mon}^? b_3 (\text{mon}^? b_4 v_5)))
5535
                                  by the induction hypothesis
5536
                            11.4. QED
5537
5538
                                                                                                        v_6 \leq \text{mon}^? (\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) (\text{mon}^{+?} \bar{b}_2 (\text{mon}^? b_3 (\text{mon}^? b_4 v_4)))
5539
5540
                                                                                                        v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^{+?} \overline{b}_2 (\text{mon}^? b_3 (\text{mon}^? b_4 v_5)))
5541
                                                                                              \langle v_6, v_7 \rangle \lesssim \operatorname{mon} \left( \ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1 \right) \left( \operatorname{mon}^+ \overline{b}_2 \left( \operatorname{mon} b_3 \left( \operatorname{mon} b_4 \left\langle v_4, v_5 \right\rangle \right) \right) \right)
5542
5543
                     12. CASE \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \bar{b}_2 \pmod{b_3} \left( \text{trace}_v \bar{b}_4 \pmod{b_5} \langle v_4, v_5 \rangle \right) 
5544
                            12.1. v_2 \lesssim \text{mon}^+ \overline{b}_2 \text{ (mon } b_3 \text{ (trace}_{\mathbf{v}} \overline{b}_4 \text{ (mon } b_5 v_4)))
5545
                                            and v_3 \lesssim \text{mon}^+ \bar{b}_2 \text{ (mon } b_3 \text{ (trace}_{v} \bar{b}_4 \text{ (mon } b_5 v_5)))
5546
                                  by inversion ≤
5547
5548
                            12.2. \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) v_0 \blacktriangleright_{\mathsf{N}} \left\langle \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) v_2, \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1\right) v_3 \right\rangle
                                  by definition \triangleright_{N}
5550
                            12.3. \ \operatorname{dyn} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \ v_2 \to_{\mathsf{N}}^* \ v_6 \lesssim \operatorname{mon}^2 \left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\operatorname{mon}^+ \overline{b}_2 \left(\operatorname{mon} b_3 \left(\operatorname{trace}_{\mathsf{V}} \overline{b}_4 \left(\operatorname{mon} b_5 \ v_4\right)\right)\right)\right)
5551
                                            and dyn (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rightarrow_N^* v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^+ \overline{b}_2 (\text{mon } b_3 (\text{trace}_v \overline{b}_4 (\text{mon } b_5 v_5))))
5552
5553
                                  by the induction hypothesis
5554
                            12.4. QED
5555
5556
                                                                                             v_6 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) (\text{mon}^+ \overline{b}_2 (\text{mon } b_3 (\text{trace}_v \overline{b}_4 (\text{mon } b_5 v_4))))
5557
                                                                                             v_7 \lesssim \text{mon}^2(\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) \left( \text{mon}^+ \overline{b}_2 \left( \text{mon } b_3 \left( \text{trace}_{\mathbf{v}} \overline{b}_4 \left( \text{mon } b_5 v_5 \right) \right) \right) \right)
5558
5559
                                                                               \langle v_6, v_7 \rangle \lesssim \text{mon} \left( \ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1 \right) \left( \text{mon}^+ \overline{b_2} \left( \text{mon } b_3 \left( \text{trace}_v \overline{b_4} \left( \text{mon } b_5 \left\langle v_4, v_5 \right\rangle \right) \right) \right) \right)
5560
                     13. Case \lambda x_2. e_2 \lesssim \lambda x_2. e_3
5561
                            13.1. SCASE tag-match (\lfloor \tau_0 \rfloor, \upsilon_0)
5562
5563
5564
                     2019-10-03 17:26. Page 107 of 1-148.
```

```
13.1.1. QED
5565
5566
                                \mathsf{dyn}\ b_0\ v_0\ {
hd}_\mathsf{N}\ \mathsf{mon}\ b_0\ v_0\lesssim \mathsf{mon}\ b_1\ v_1
5567
                     13.2. SCASE \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)
5568
                           13.2.1. QED
5569
5570
                                \mathsf{dyn}\ b_0\ v_0\ {
hd}_\mathsf{N}\ \mathsf{BndryErr}\ (b_0,v_0) \lesssim \mathsf{dyn}\ b_1\ v_1
5571
                14. CASE \lambda(x_2:\tau_2). e_2 \lesssim \lambda(x_2:\tau_2). e_3
5572
                     14.1. Contradiction:
5573
                          \cdot \vdash_{\mathsf{N}} v_0 : \mathcal{U}
5574
                15. CASE mon b_2 (mon b_3 v_2) \lesssim trace<sub>v</sub> b_4b_5 (\lambda x_0. e_3)
5576
                     15.1. Scase tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
5577
                           15.1.1. dyn b_0 v_0 \triangleright_{\mathsf{N}} \mathsf{mon} b_0 v_0
5578
                                by definition \triangleright_{N}
5579
5580
                          15.1.2. QED
5581
5582
                                                                                                   \operatorname{\mathsf{mon}} b_2 \left(\operatorname{\mathsf{mon}} b_3 \ v_2\right) \lesssim \operatorname{\mathsf{trace}}_{\mathsf{v}} b_4 b_5 \left(\lambda x_0. \ e_3\right)
5583
                                                                              \operatorname{\mathsf{mon}} b_0 \left( \operatorname{\mathsf{mon}} b_2 \left( \operatorname{\mathsf{mon}} b_3 v_2 \right) \right) \lesssim \operatorname{\mathsf{mon}} b_1 \left( \operatorname{\mathsf{trace}}_{\mathsf{v}} b_4 b_5 \left( \lambda x_0. \, e_3 \right) \right)
5584
5585
                     15.2. SCASE \neg tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
5586
5587
                                \mathsf{dyn}\ b_0\ v_0\ {
hd}_\mathsf{N}\ \mathsf{BndryErr}\ (b_0,v_0) \lesssim \mathsf{dyn}\ b_1\ v_1
                16. CASE mon b_2 (mon b_3 v_2) \lesssim (trace<sub>v</sub> b_4b_5\overline{b}_6 (\lambda x_3.e_3))
5589
5590
                     16.1. tag-match(\lfloor \tau_0 \rfloor, v_0)
5591
                           16.1.1. dyn b_0 v_0 \triangleright_{\mathsf{N}} \mathsf{mon} b_0 v_0
5592
                                by definition \triangleright_{N}
5593
                           16.1.2. QED
5594
5595
                                                                                              mon b_2 (mon b_3 v_2) \lesssim (trace<sub>v</sub> b_4b_5\overline{b}_6 (\lambda x_3. e_3))
5596
5597
                                                                           \operatorname{\mathsf{mon}} b_0 \left( \operatorname{\mathsf{mon}} b_2 \left( \operatorname{\mathsf{mon}} b_3 v_2 \right) \right) \lesssim \operatorname{\mathsf{mon}} b_1 \left( \operatorname{\mathsf{trace}}_{\mathsf{v}} b_4 b_5 \overline{b_6} \left( \lambda x_3. e_3 \right) \right)
5598
                     16.2. \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)
5599
                           16.2.1. QED
                                \mathsf{dyn}\ b_0\ v_0\ {
hd}_{\mathsf{N}}\ \mathsf{BndryErr}\ (b_0,v_0) \lesssim \mathsf{dyn}\ b_1\ v_1
                17. CASE v_0 = \text{mon } b_2 \ v_2 \lesssim \text{mon } b_3 \ v_3 = v_1
5603
                     17.1. SCASE tag-match(\lfloor \tau_0 \rfloor, \upsilon_0)
5604
5605
                           17.1.1. dyn b_0 v_0 \triangleright_{\mathsf{N}} \mathsf{mon} b_0 v_0
5606
                                by definition \triangleright_{N}
5607
                          17.1.2. QED
5608
5609
                                                                                                                       \operatorname{\mathsf{mon}} b_2 \ v_2 \lesssim \operatorname{\mathsf{mon}} b_3 \ v_3
5610
5611
                                                                                                   \operatorname{\mathsf{mon}} b_0 \ (\operatorname{\mathsf{mon}} b_2 \ v_2) \lesssim \operatorname{\mathsf{mon}} b_1 \ (\operatorname{\mathsf{mon}} b_3 \ v_3)
5612
                     17.2. SCASE \neg tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0)
5613
                          17.2.1. QED
5614
```

```
\operatorname{\mathsf{dyn}} b_0 \ v_0 \, \rhd_{\! \mathsf{N}} \, \operatorname{\mathsf{BndryErr}} (b_0, v_0) \lesssim \operatorname{\mathsf{dyn}} b_1 \ v_1
5618
                                                                                                                                                                                                                                                                                                                                        5619
5620
                          LEMMA 8.14. If stat b_0 \ v_0 and stat b_1 \ v_1 are reduced WF expressions and stat b_0 \ v_0 \lesssim stat b_1 \ v_1 and stat b_0 \ v_0 \blacktriangleright_N e_2
5621
                   and stat b_1 \ v_1 \blacktriangleright_A e_3 \ then \ e_2 \lesssim e_3
5622
5623
                         PROOF. By case analysis of v_0 \lesssim v_1.
5624
                   1. CASE i_0 \lesssim i_0
5625
                         1.1. stat b_0 \ v_0 \blacktriangleright_{\mathsf{N}} v_0 and stat b_1 \ v_1 \blacktriangleright_{\mathsf{A}} v_1
5626
                               by definition \triangleright_{N}, \triangleright_{A}
5628
                         1.2. QED
5629
                  2. CASE i_0 \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_2 i_0
5630
                         2.1. Contradiction:
5631
5632
                               \cdot \vdash_{\mathsf{A}} v_1 : \tau_1
5633
                  3. Case \langle v_2, v_3 \rangle \lesssim \langle v_4, v_5 \rangle
5634
                         3.1. let b_0 = (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1) and b_1 = (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1)
5635
                         3.2. v_2 \lesssim v_4 and v_3 \lesssim v_5
5636
                               by inversion ≤
5637
5638
                         3.3. stat b_0 \ v_0 \blacktriangleright_{\mathbb{N}} \langle \operatorname{stat} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) v_2, \operatorname{stat} \left(\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1\right) v_3 \rangle
5639
                                     and stat b_1 \ v_1 \blacktriangleright_A \ \mathsf{mon} \ b_1 \ v_1
                               by definition 
ightharpoonup_N and 
ightharpoonup_A
5641
                         3.4. stat (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_2 \to_N^* \ v_6 \lesssim \mathsf{mon}^? \ (\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) \ v_4
5642
                                     and stat (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) v_3 \rightarrow_N^* v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) v_5
5643
5644
                               by lemma 8.15
5645
                         3.5. QED
5646
                                                                                                 \frac{v_6 \lesssim \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) v_4 \qquad v_7 \lesssim \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1\right) v_5}{\langle v_6, v_7 \rangle \lesssim \mathsf{mon} \ b_1 \ \langle v_4, v_5 \rangle}
5648
5649
5650
                   4. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} (\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) \langle v_4, v_5 \rangle
5651
                         4.1. let b_0 = (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1) and b_1 = (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1)
5652
5653
                         4.2. v_2 \lesssim \text{mon}^2 (\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3) v_4
5654
                                     and v_3 \lesssim \text{mon}^2 (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) v_5
5655
                               by inversion \le \cdot
5656
                         4.3. stat b_0 \ v_0 \blacktriangleright_{\mathbb{N}} \langle \operatorname{stat} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) v_2, \operatorname{stat} \left(\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1\right) v_3 \rangle
5657
5658
                                     and stat b_1 \ v_1 \to_{\mathsf{A}}^* \mathsf{trace}_{\mathsf{v}} \ b_1(\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) \ \langle v_4, v_5 \rangle
5659
                               by definition \triangleright_{N} and \triangleright_{A}
5660
                         4.4. stat (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) v_2 \rightarrow_N^* v_6 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) (\text{mon}^? (\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3) v_4)
5661
                                     and stat (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) v_3 \rightarrow_N^* v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^? (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) v_5)
5662
5663
                               by lemma 8.15
5664
                         4.5. v_6 \lesssim add-trace ((\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1)(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3), v_4)
5665
                                     and v_7 \leq add-trace ((\ell_0 \triangleleft \tau_5 \triangleleft \ell_1)(\ell_2 \triangleleft \tau_7 \triangleleft \ell_3), v_5)
5666
                               by lemma 8.16
5668
                   2019-10-03 17:26. Page 109 of 1-148.
```

```
4.6. QED
5669
5670
5671
                                                             v_6 \lesssim add-trace ((\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1)(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3), v_4)
                                                                                                                                                                                                                v_7 \lesssim add-trace ((\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1)(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3), v_5)
5672
                                                                                                                                           \langle v_6, v_7 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} b_1(\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) \langle v_4, v_5 \rangle
 5673
5674
                       5. CASE \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{v_1} \overline{b_2} \langle v_4, v_5 \rangle
5675
                              5.1. Contradiction:
5676
                                       \cdot \vdash_{\mathsf{A}} v_1 : \tau_1
5677
                      6. CASE \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_2 \pmod{b_3} \langle v_4, v_5 \rangle
5678
                              6.1. Contradiction:
                                      \cdot \vdash_{\mathsf{A}} v_1 : \tau_1
                      7. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} \left( \ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3 \right) \left( \text{trace}_{\mathbf{v}} \, \overline{b}_4 \, \langle v_4, v_5 \rangle \right)
5682
                              7.1. let b_0 = (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1) and b_1 = (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1)
5683
                              7.2. v_2 \leq \text{mon}^2(\ell_2 \triangleleft \tau_6 \triangleleft \ell_3) (add\text{-trace}(\overline{b}_4, v_4))
5684
5685
                                            and v_3 \lesssim \text{mon}^2(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) (add-trace (\overline{b}_4, v_5))
                                     by inversion \le \
 5687
                              7.3. stat b_0 \ v_0 \blacktriangleright_{\mathbb{N}} \langle \operatorname{stat} (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_2, \operatorname{stat} (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rangle
5688
5689
                                            and stat b_1 \ v_1 \rightarrow_A^* \operatorname{trace}_{\mathsf{v}} b_1(\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) \overline{b}_4 \langle v_4, v_5 \rangle
5690
                                     by definition \triangleright_N and \triangleright_A
                              7.4. \operatorname{stat}\left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) v_2 \xrightarrow{N}^* v_6 \lesssim \operatorname{mon}^?\left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\operatorname{mon}^?\left(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3\right) \left(\operatorname{add-trace}\left(\overline{b}_4, v_4\right)\right)\right)
                                            and stat (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rightarrow_N^* v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) \ (\text{mon}^? (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) \ (add\text{-trace} (\overline{b}_4, v_5)))
5694
                                     by lemma 8.15
5695
                              7.5. v_6 \lesssim add-trace ((\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1)(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3), (add-trace (\overline{b}_4, v_4)))
5696
                                            and v_7 \lesssim add-trace ((\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1)(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3), (add-trace (\bar{b}_4, v_5)))
5697
                                     by lemma 8.16
5698
5699
                              7.6. QED
5700
5701
                                                      v_6 \lesssim add-trace ((\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1)(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3)\overline{b}_4, v_4)
                                                                                                                                                                                                                v_7 \lesssim add-trace((\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1)(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3)\bar{b}_4, v_5)
5702
                                                                                                                                        \langle v_6, v_7 \rangle \leq \operatorname{trace}_{v} b_1(\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) \overline{b}_4 \langle v_4, v_5 \rangle
5703
                       8. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} \left( \ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3 \right) \left( \text{mon} \left( \ell_4 \blacktriangleleft \tau_8 \times \tau_9 \blacktriangleleft \ell_5 \right) \left\langle v_4, v_5 \right\rangle \right)
5704
                              8.1. let b_0 = (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1) and b_1 = (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1)
                              8.2. v_2 \lesssim \text{mon}^2 (\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3) (\text{mon}^2 (\ell_4 \blacktriangleleft \tau_8 \blacktriangleleft \ell_5) v_4)
                                            and v_3 \lesssim \text{mon}^2(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) (\text{mon}^2(\ell_4 \blacktriangleleft \tau_9 \blacktriangleleft \ell_5) v_5)
5708
5709
                                     by inversion \le \
5710
                              8.3. stat b_0 \ v_0 \blacktriangleright_{\mathbb{N}} \langle \operatorname{stat} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \ v_2, \operatorname{stat} \left(\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1\right) \ v_3 \rangle
5711
                                            \text{and stat } b_1 \ v_1 \to_{\mathsf{A}}^* \operatorname{trace}_{\mathsf{V}} b_1(\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) (\operatorname{\mathsf{mon}} \left(\ell_4 \blacktriangleleft \tau_8 \times \tau_9 \blacktriangleleft \ell_5\right) \langle v_4, v_5 \rangle)
5712
                                     by definition \triangleright_N and \triangleright_A
5713
                              8.4. \ \operatorname{stat} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \ v_2 \to_{\mathsf{N}}^* \ v_6 \lesssim \operatorname{\mathsf{mon}}^? \left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\operatorname{\mathsf{mon}}^? \left(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3\right) \left(\operatorname{\mathsf{mon}}^? \left(\ell_4 \blacktriangleleft \tau_8 \blacktriangleleft \ell_5\right) \ v_4\right)\right)
5714
5715
                                            and stat (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) v_3 \rightarrow_N^* v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^? (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) (\text{mon}^? (\ell_4 \blacktriangleleft \tau_9 \blacktriangleleft \ell_5) v_5))
5716
                                     by lemma 8.15
5717
```

```
8.5. v_6 \lesssim add-trace ((\ell_0 \triangleleft \tau_4 \triangleleft \ell_1)(\ell_2 \triangleleft \tau_6 \triangleleft \ell_3), (\text{mon}^? (\ell_4 \triangleleft \tau_8 \triangleleft \ell_5) v_4))
5721
5722
                                        and v_7 \lesssim add-trace ((\ell_0 \triangleleft \tau_5 \triangleleft \ell_1)(\ell_2 \triangleleft \tau_7 \triangleleft \ell_3), (\text{mon}^2 (\ell_4 \triangleleft \tau_9 \triangleleft \ell_5) v_5))
5723
                                  by lemma 8.16
5724
                           8.6. QED
5725
5726
                                                                                                 v_6 \lesssim add-trace ((\ell_0 \triangleleft \tau_4 \triangleleft \ell_1)(\ell_2 \triangleleft \tau_6 \triangleleft \ell_3), (\text{mon}^? (\ell_4 \triangleleft \tau_8 \triangleleft \ell_5) v_4))
5727
5728
                                                                                                v_7 \lesssim add\text{-trace}((\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1)(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3), (\text{mon}^? (\ell_4 \blacktriangleleft \tau_9 \blacktriangleleft \ell_5) v_5))
5729
                                                                                             \langle v_6, v_7 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} b_1(\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) (\operatorname{mon} (\ell_4 \blacktriangleleft \tau_8 \times \tau_9 \blacktriangleleft \ell_5) \langle v_4, v_5 \rangle)
5730
                    9. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} (\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) (\text{trace}_v \bar{b}_4 (\text{mon} (\ell_5 \blacktriangleleft \tau_8 \times \tau_9 \blacktriangleleft \ell_6) \langle v_4, v_5 \rangle))
5731
5732
                           9.1. let b_0 = (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1) and b_1 = (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1)
5733
                           9.2. v_2 \lesssim \text{mon}^2(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3) \left( \text{trace}_{\nu}^2 \overline{b}_4 \left( \text{mon}^2(\ell_5 \blacktriangleleft \tau_8 \blacktriangleleft \ell_6) v_4 \right) \right)
5734
                                        and v_3 \lesssim \text{mon}^? (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) (\text{trace}_{\nu}^? \overline{b}_4 (\text{mon}^? (\ell_5 \blacktriangleleft \tau_9 \blacktriangleleft \ell_6) v_5))
5735
5736
                                  by inversion ≤
5737
                           9.3. stat b_0 \ v_0 \blacktriangleright_{\mathsf{N}} \langle \mathsf{stat} \ (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_2, \mathsf{stat} \ (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rangle
5738
                                        and stat b_1 \ v_1 \to_{\mathsf{A}}^* \operatorname{trace}_{\mathsf{V}} b_1(\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) \overline{b}_4 \left( \operatorname{mon} \left( \ell_5 \blacktriangleleft \tau_8 \times \tau_9 \blacktriangleleft \ell_6 \right) \left\langle v_4, v_5 \right\rangle \right)
5739
                                  by definition \triangleright_{\mathsf{N}} and \triangleright_{\mathsf{A}}
5740
                           9.4. \ \operatorname{stat} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \ v_2 \to_{\mathsf{N}}^* \ v_6 \lesssim \operatorname{mon}^? \left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\operatorname{mon}^? \left(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3\right) \left(\operatorname{trace}_{\mathsf{V}}^? \overline{b_4} \left(\operatorname{mon}^? \left(\ell_5 \blacktriangleleft \tau_8 \blacktriangleleft \ell_6\right) v_4\right)\right)\right)
5741
5742
                                        \text{and stat} \ (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \to_{\mathsf{N}}^* v_7 \lesssim \mathsf{mon}^? \ (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) \ (\mathsf{mon}^? \ (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) \ (\mathsf{trace}_{\mathsf{v}}^? \ \overline{b}_4 \ (\mathsf{mon}^? \ (\ell_5 \blacktriangleleft \tau_9 \blacktriangleleft \ell_6) \ v_5)))
5743
                                  by lemma 8.15
5744
                           9.5. v_6 \lesssim add-trace ((\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1)(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3), (\operatorname{trace}_v^? \overline{b}_4 (\operatorname{mon}^? (\ell_5 \blacktriangleleft \tau_8 \blacktriangleleft \ell_6) v_4)))
5745
5746
                                        and v_7 \leq add-trace ((\ell_0 \triangleleft \tau_5 \triangleleft \ell_1)(\ell_2 \triangleleft \tau_7 \triangleleft \ell_3), (\text{trace}_{v}^2 \overline{b_4} (\text{mon}^2 (\ell_5 \triangleleft \tau_9 \triangleleft \ell_6) v_5)))
5747
                                  by lemma 8.16
5748
                           9.6. QED
5749
5750
                                                                                                      v_6 \leq add-trace (b_1(\ell_2 \triangleleft \tau_6 \times \tau_7 \triangleleft \ell_3)\overline{b}_4, (\text{mon}^?(\ell_5 \triangleleft \tau_8 \triangleleft \ell_6) v_4))
5751
                                                                                                     v_7 \lesssim add-trace (b_1(\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3)\overline{b}_4, (\text{mon}^2(\ell_5 \blacktriangleleft \tau_9 \blacktriangleleft \ell_6) v_5))
5752
5753
                                                                                          \langle v_6, v_7 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} b_1(\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) \overline{b_4} \left( \operatorname{mon} \left( \ell_5 \blacktriangleleft \tau_8 \times \tau_9 \blacktriangleleft \ell_6 \right) \langle v_4, v_5 \rangle \right)
5754
                     10. CASE \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \overline{b}_2 \pmod{b_3 \pmod{b_4 \langle v_4, v_5 \rangle}}
5755
5756
                           10.1. Contradiction:
5757
                                  by lemma 7.9
                     11. CASE \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \overline{b}_2 \pmod{b_3} \left( \text{trace}_{v_3} \overline{b}_4 \pmod{b_5} \langle v_4, v_5 \rangle \right) 
5759
                           11.1. Contradiction:
5760
5761
                                  by lemma 7.9
5762
                     12. CASE \lambda x_2. e_2 \lesssim \lambda x_2. e_3
5763
                           12.1. Contradiction:
5764
                                   \cdot \vdash_{\mathsf{N}} v_0 : \tau_0
5765
5766
                     13. CASE \lambda(x_2:\tau_2). e_2 \leq \lambda(x_2:\tau_2). e_3
5767
5768
                                   stat b_0 v_0 \blacktriangleright_N \mod b_0 v_0 and stat b_1 v_1 \blacktriangleright_N \mod b_1 v_1
5769
                     14. CASE mon b_2 (mon b_3 v_2) \lesssim trace, \overline{b}_4 v_3
5770
5771
5772
                    2019-10-03 17:26. Page 111 of 1-148.
```

2019-10-03 17:26. Page 112 of 1-148.

```
5773
                        14.1. Contradiction:
5774
                               \cdot \vdash_{\mathsf{A}} v_1 : \tau_1
5775
                  15. Case mon b_2 v_2 \lesssim \text{mon } b_3 v_3
5776
                        15.1. stat b_0 v_0 \blacktriangleright_{\mathsf{N}} \mathsf{mon} b_0 v_0
5777
5778
                              by definition \triangleright_{N}
5779
                        15.2. stat b_1 v_1 \triangleright_A add-trace (b_1b_3get-trace (v_3), rem-trace (v_3)
5780
                              by definition \triangleright_{\scriptscriptstyle \Lambda}
5781
                        15.3. QED
                                                                                   b_0 \leqslant : b_1 \qquad b_1 \leqslant : b_3 \qquad v_2 \lesssim \mathsf{trace}_{\mathsf{v}} \, \mathit{get-trace} \, (v_3) \, \mathit{rem-trace} \, (v_3)
5784
5785
                                                                                         mon \ b_0 \ (mon \ b_1 \ v_2) \lesssim trace_v \ b_1b_3get-trace(v_3) \ rem-trace(v_3)
5786
5787
                                                                                                                                                                                                                                                                                                                       5788
                        Lemma 8.15. If v_0 and v_1 are reduced WF expressions and v_0 \lesssim v_1 and \cdot \vdash_N v_0 : \tau_0 and \cdot \vdash_A v_1 : \tau_1 and \tau_0 \leqslant : \tau_1 then
5789
5790
                  \mathsf{stat}\,(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_0 \to_\mathsf{N}^* \ v_2 \ \mathit{and} \ v_2 \lesssim \mathsf{mon}^? \, (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) \ v_3
5791
                         Proof. By induction on v_0 via case analysis of v_0 \lesssim v_1.
5792
                  1. Case i_0 \lesssim i_0
5793
5794
                       1.1. QED
5795
                              \mathsf{stat}\,(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\,v_0 \blacktriangleright_\mathsf{N} v_0 \lesssim \mathsf{mon}^?\,(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)\,v_1
                        1.2. QED
                  2. CASE i_0 \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_2 i_0
5798
5799
                        2.1. Contradiction:
5800
                              \cdot \vdash_{\mathsf{A}} v_1 : \tau_1
5801
                  3. Case \langle v_2, v_3 \rangle \lesssim \langle v_4, v_5 \rangle
5802
5803
                        3.1. v_2 \lesssim v_4 and v_3 \lesssim v_5
5804
                              by inversion \lesssim
5805
                        3.2. \operatorname{stat}\left(\ell_{0} \blacktriangleleft \tau_{0} \blacktriangleleft \ell_{1}\right) v_{0} \blacktriangleright_{\mathsf{N}} \left\langle \operatorname{stat}\left(\ell_{0} \blacktriangleleft \tau_{2} \blacktriangleleft \ell_{1}\right) v_{2}, \operatorname{stat}\left(\ell_{0} \blacktriangleleft \tau_{3} \blacktriangleleft \ell_{1}\right) v_{3} \right\rangle
5806
                              by definition 
ightharpoonup_N
5807
                       3.3. stat (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_2 \rightarrow_N^* v_6 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) \ v_4
5808
                                   and stat (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rightarrow_N^* v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) \ v_5
                              by the induction hypothesis
5811
                        3.4. QED
5812
5813
                                                                                           v_6 \lesssim \operatorname{mon}^?(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) v_4 \qquad v_7 \lesssim \operatorname{mon}^?(\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) v_5
5814
5815
                                                                                                                       \langle v_6, v_7 \rangle \leq \text{mon} (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) \langle v_4, v_5 \rangle
5816
                  4. Case \langle v_2, v_3 \rangle \lesssim \text{mon} (\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) \langle v_4, v_5 \rangle
5817
                        4.1. v_2 \lesssim \text{mon}^? (\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3) v_4
5818
5819
                                   and v_3 \lesssim \text{mon}^2 (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) v_5
5820
                              by inversion \lesssim
5821
                        4.2. \operatorname{stat}\left(\ell_{0} \blacktriangleleft \tau_{0} \blacktriangleleft \ell_{1}\right) \upsilon_{0} \blacktriangleright_{\mathsf{N}} \left\langle \operatorname{stat}\left(\ell_{0} \blacktriangleleft \tau_{2} \blacktriangleleft \ell_{1}\right) \upsilon_{2}, \operatorname{stat}\left(\ell_{0} \blacktriangleleft \tau_{3} \blacktriangleleft \ell_{1}\right) \upsilon_{3} \right\rangle
5822
                              by definition \triangleright_{N}
```

```
4.3. \ \operatorname{stat} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \, v_2 \to_{\mathsf{N}}^* \, v_6 \lesssim \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\mathsf{mon}^? \left(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3\right) \, v_4\right)
5825
5826
                                             and stat (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) v_3 \rightarrow_N^* v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^? (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) v_5)
5827
                                      by the induction hypothesis
5828
                               4.4. QED
5829
5830
                                                     v_6 \lesssim \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\mathsf{mon}^? \left(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3\right) v_4\right) \qquad v_7 \lesssim \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1\right) \left(\mathsf{mon}^? \left(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3\right) v_5\right)
5831
5832
                                                                                                             \langle v_6, v_7 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_4 \times \tau_5 \blacktriangleleft \ell_1) (\text{mon} (\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) \langle v_4, v_5 \rangle)
5833
                       5. CASE \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_2 \langle v_4, v_5 \rangle
5834
5835
                               5.1. Contradiction:
5836
                                       \cdot \vdash_{\mathsf{A}} v_1 : \tau_1
5837
                       6. CASE \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_2 \pmod{b_3} \langle v_4, v_5 \rangle
5838
                               6.1. Contradiction:
5839
5840
                                       \cdot \vdash_{\mathsf{A}} v_1 : \tau_1
5841
                       7. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} (\ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3) (\text{trace}_{\mathbf{v}} \, \overline{b}_4 \, \langle v_4, v_5 \rangle)
5842
                               7.1. v_2 \leq \text{mon}^2(\ell_2 \triangleleft \tau_6 \triangleleft \ell_3) (add\text{-trace}(\overline{b}_4, v_4))
5843
                                             and v_3 \lesssim \text{mon}^? (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) (add\text{-trace}(\overline{b}_4, v_5))
5844
5845
                                      by inversion \le \cdots
5846
                               7.2. \operatorname{stat}\left(\ell_{0} \blacktriangleleft \tau_{0} \blacktriangleleft \ell_{1}\right) \upsilon_{0} \blacktriangleright_{\mathsf{N}} \left\langle \operatorname{stat}\left(\ell_{0} \blacktriangleleft \tau_{2} \blacktriangleleft \ell_{1}\right) \upsilon_{2}, \operatorname{stat}\left(\ell_{0} \blacktriangleleft \tau_{3} \blacktriangleleft \ell_{1}\right) \upsilon_{3} \right\rangle
5847
                                      by definition 
ightharpoonup_N
5848
                              7.3. stat (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) v_2 \rightarrow_N^* v_6 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) (\text{mon}^? (\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3) (add-trace(\overline{b}_4, v_4)))
5849
                                             \text{and stat} \ (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \xrightarrow{\quad \  }^* \ v_7 \lesssim \text{mon}^? \ (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) \ (\text{mon}^? \ (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) \ (\textit{add-trace} \ (\overline{b}_4, v_5)))
5850
5851
                                      by the induction hypothesis
5852
                               7.4. QED
5853
5854
                                                                                                             v_6 \leq \text{mon}^? (\ell_0 \triangleleft \tau_4 \triangleleft \ell_1) (\text{mon}^? (\ell_2 \triangleleft \tau_6 \triangleleft \ell_3) (add-trace(\overline{b}_4, v_4)))
5855
                                                                                                             v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^? (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) (add-trace(\overline{b}_4, v_5)))
5856
5857
                                                                                            \langle v_6, v_7 \rangle \lesssim \text{mon} \left( \ell_0 \blacktriangleleft \tau_4 \times \tau_5 \blacktriangleleft \ell_1 \right) \left( \text{mon} \left( \ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3 \right) \left( \text{trace}_{\mathbf{v}} \, \overline{b}_4 \, \langle v_4, v_5 \rangle \right) \right)
5858
                       8. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} \left( \ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3 \right) \left( \text{mon} \left( \ell_4 \blacktriangleleft \tau_8 \times \tau_9 \blacktriangleleft \ell_5 \right) \langle v_4, v_5 \rangle \right)
5859
5860
                               8.1. v_2 \lesssim \text{mon}^? (\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3) (\text{mon}^? (\ell_4 \blacktriangleleft \tau_8 \blacktriangleleft \ell_5) v_4)
5861
                                             and v_3 \lesssim \text{mon}^2(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) (\text{mon}^2(\ell_4 \blacktriangleleft \tau_9 \blacktriangleleft \ell_5) v_5)
5862
                                      by inversion \le \cdots
5863
                               8.2. \operatorname{stat} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_0 \blacktriangleright_{\mathsf{N}} \langle \operatorname{stat} (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) v_2, \operatorname{stat} (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) v_3 \rangle
5864
5865
                                      by definition \triangleright_{N}
5866
                              8.3. \operatorname{stat}\left(\ell_{0} \blacktriangleleft \tau_{2} \blacktriangleleft \ell_{1}\right) v_{2} \rightarrow_{N}^{*} v_{6} \lesssim \operatorname{mon}^{?}\left(\ell_{0} \blacktriangleleft \tau_{4} \blacktriangleleft \ell_{1}\right) \left(\operatorname{mon}^{?}\left(\ell_{2} \blacktriangleleft \tau_{6} \blacktriangleleft \ell_{3}\right) \left(\operatorname{mon}^{?}\left(\ell_{4} \blacktriangleleft \tau_{8} \blacktriangleleft \ell_{5}\right) v_{4}\right)\right)
5867
                                             \text{and stat} \ (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \to_{\mathsf{N}}^* \ v_7 \lesssim \mathsf{mon}^? \ (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) \ (\mathsf{mon}^? \ (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) \ (\mathsf{mon}^? \ (\ell_4 \blacktriangleleft \tau_9 \blacktriangleleft \ell_5) \ v_5))
5868
                                      by the induction hypothesis
5869
5870
                               8.4. QED
5871
5872
5873
5874
5875
5876
```

```
5877
                                                                                                        v_6 \lesssim \text{mon}^2(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) (\text{mon}^2(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3) (\text{mon}^2(\ell_4 \blacktriangleleft \tau_8 \blacktriangleleft \ell_5) v_4))
5878
5879
                                                                                                        v_7 \lesssim \text{mon}^2(\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^2(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) (\text{mon}^2(\ell_4 \blacktriangleleft \tau_9 \blacktriangleleft \ell_5) v_5))
5880
                                                                        \langle v_6, v_7 \rangle \lesssim \text{mon} \left( \ell_0 \blacktriangleleft \tau_4 \times \tau_5 \blacktriangleleft \ell_1 \right) \left( \text{mon} \left( \ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3 \right) \left( \text{mon} \left( \ell_4 \blacktriangleleft \tau_8 \times \tau_9 \blacktriangleleft \ell_5 \right) \left\langle v_4, v_5 \right\rangle \right) \right)
 5881
5882
                       9. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} \left( \ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3 \right) \left( \text{trace}_{\mathbf{v}} \, \overline{b}_4 \left( \text{mon} \left( \ell_5 \blacktriangleleft \tau_8 \times \tau_9 \blacktriangleleft \ell_6 \right) \left\langle v_4, v_5 \right\rangle \right) \right)
5883
                               9.1. v_2 \lesssim \text{mon}^2(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3) (\text{trace}^2 \overline{b_4} (\text{mon}^2(\ell_5 \blacktriangleleft \tau_8 \blacktriangleleft \ell_6) v_4))
5884
                                             and v_3 \lesssim \text{mon}^2(\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) \text{ (trace}_v^2 \overline{b_4} \text{ (mon}^2(\ell_5 \blacktriangleleft \tau_9 \blacktriangleleft \ell_6) v_5))
5885
                                      by inversion \le \
                               9.2. stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_0 \blacktriangleright_{\mathsf{N}} \langle \operatorname{stat} (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_2, \operatorname{stat} (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rangle
                                       by definition \triangleright_{N}
                              9.3. \ \operatorname{stat} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \ v_2 \to_{\mathsf{N}}^* \ v_6 \lesssim \operatorname{mon}^? \left(\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1\right) \left(\operatorname{mon}^? \left(\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3\right) \left(\operatorname{trace}_{\mathsf{V}}^? \overline{b_4} \left(\operatorname{mon}^? \left(\ell_5 \blacktriangleleft \tau_8 \blacktriangleleft \ell_6\right) v_4\right)\right)\right)
5890
                                             and stat (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rightarrow_N^* v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) \ (\text{mon}^? (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) \ (\text{trace}_v^? \ \overline{b_4} \ (\text{mon}^? (\ell_5 \blacktriangleleft \tau_9 \blacktriangleleft \ell_6) \ v_5)))
5891
5892
                                      by the induction hypothesis
5893
                               9.4. QED
 5894
5895
                                                                                      v_6 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) (\text{mon}^? (\ell_2 \blacktriangleleft \tau_6 \blacktriangleleft \ell_3) (\text{trace}_v^? \overline{b_4} (\text{mon}^? (\ell_5 \blacktriangleleft \tau_8 \blacktriangleleft \ell_6) v_4)))
5896
                                                                                      v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^? (\ell_2 \blacktriangleleft \tau_7 \blacktriangleleft \ell_3) (\text{trace}_v^? \overline{b_4} (\text{mon}^? (\ell_5 \blacktriangleleft \tau_9 \blacktriangleleft \ell_6) v_5)))
5897
5898
                                                             \langle v_6, v_7 \rangle \lesssim \operatorname{mon} \left( \ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1 \right) \left( \operatorname{mon} \left( \ell_2 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_3 \right) \left( \operatorname{trace}_{\mathbf{v}} \overline{b}_4 \left( \operatorname{mon} \left( \ell_5 \blacktriangleleft \tau_8 \times \tau_9 \blacktriangleleft \ell_6 \right) \left\langle v_4, v_5 \right\rangle \right) \right) \right)
5899
                       10. CASE \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \overline{b_2} \pmod{b_3} \pmod{b_4} \langle v_4, v_5 \rangle
                               10.1. v_2 \lesssim \text{mon}^{+?} \overline{b}_2 \text{ (mon}^? b_3 \text{ (mon}^? b_4 v_4))
5901
                                                 and v_3 \leq \text{mon}^{+?} \overline{b}_2 \text{ (mon}^? b_3 \text{ (mon}^? b_4 v_5))
5902
5903
                                       by inversion \le \
5904
                               10.2. stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_0 \blacktriangleright_{\mathsf{N}} \langle \operatorname{stat} (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_2, \operatorname{stat} (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rangle
5905
                                       by definition ▶
5906
                               10.3. \ \operatorname{stat} \ (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ \upsilon_2 \to_{\mathsf{N}}^* \ \upsilon_6 \lesssim \mathsf{mon}^? \ (\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) \ (\mathsf{mon}^{+?} \ \overline{b}_2 \ (\mathsf{mon}^? \ b_3 \ (\mathsf{mon}^? \ b_4 \ \upsilon_4)))
5908
                                                and stat (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) v_3 \rightarrow_N^* v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^+? \overline{b}_2 (\text{mon}^? b_3 (\text{mon}^? b_4 v_5)))
5909
                                      by the induction hypothesis
5910
                               10.4. QED
5911
5912
                                                                                                                    v_6 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) (\text{mon}^{+?} \overline{b}_2 (\text{mon}^? b_3 (\text{mon}^? b_4 v_4)))
5914
                                                                                                                    v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^{+?} \overline{b}_2 (\text{mon}^? b_3 (\text{mon}^? b_4 v_5)))
5915
                                                                                                         \langle v_6, v_7 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) (\text{mon}^+ \overline{b}_2 (\text{mon } b_3 (\text{mon } b_4 \langle v_4, v_5 \rangle)))
5916
                       11. CASE \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \bar{b}_2 \pmod{b_3} \left( \text{trace}_v \bar{b}_4 \pmod{b_5} \langle v_4, v_5 \rangle \right) \right)
5917
5918
                               11.1. v_2 \lesssim \text{mon}^+ \overline{b}_2 \text{ (mon } b_3 \text{ (trace}_{\mathbf{v}} \overline{b}_4 \text{ (mon } b_5 v_4)))
5919
                                                 and v_3 \lesssim \text{mon}^+ \bar{b}_2 \text{ (mon } b_3 \text{ (trace}_{V} \bar{b}_4 \text{ (mon } b_5 v_5)))
5920
                                       by inversion ≤
5921
5922
                               11.2. stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_0 \blacktriangleright_{\mathsf{N}} \langle \mathsf{stat} \ (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \ v_2, \mathsf{stat} \ (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) \ v_3 \rangle
5923
                                       by definition 
ightharpoonup_N
5924
                               11.3. \operatorname{stat}\left(\ell_{0} \blacktriangleleft \tau_{2} \blacktriangleleft \ell_{1}\right) v_{2} \rightarrow_{N}^{*} v_{6} \lesssim \operatorname{mon}^{?}\left(\ell_{0} \blacktriangleleft \tau_{4} \blacktriangleleft \ell_{1}\right) \left(\operatorname{mon}^{+} \overline{b}_{2} \left(\operatorname{mon} b_{3} \left(\operatorname{trace}_{V} \overline{b}_{4} \left(\operatorname{mon} b_{5} v_{4}\right)\right)\right)\right)
5925
                                                and stat (\ell_0 \blacktriangleleft \tau_3 \blacktriangleleft \ell_1) v_3 \rightarrow_N^* v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^+ \bar{b}_2 (\text{mon } b_3 (\text{trace}_v \bar{b}_4 (\text{mon } b_5 v_5))))
```

```
5929
                                                by the induction hypothesis
5930
                                       11.4. QED
5931
5932
                                                                                                                                   v_6 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_4 \blacktriangleleft \ell_1) (\text{mon}^+ \bar{b}_2 (\text{mon } b_3 (\text{trace}_v \bar{b}_4 (\text{mon } b_5 v_4))))
5933
                                                                                                                                  v_7 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_5 \blacktriangleleft \ell_1) (\text{mon}^+ \overline{b}_2 (\text{mon } b_3 (\text{trace}_{\mathbf{v}} \overline{b}_4 (\text{mon } b_5 v_5))))
5934
5935
                                                                                                                \langle v_6, v_7 \rangle \lesssim \text{mon} \left( \ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1 \right) \left( \text{mon}^+ \overline{b_2} \left( \text{mon } b_3 \left( \text{trace}_v \overline{b_4} \left( \text{mon } b_5 \left\langle v_4, v_5 \right\rangle \right) \right) \right) \right)
5936
                              12. CASE \lambda x_2. e_2 \lesssim \lambda x_2. e_3
5937
                                       12.1. Contradiction:
5938
                                                  \cdot \vdash_{\mathsf{N}} v_0 : \tau_0
5940
                              13. CASE \lambda(x_2:\tau_2). e_2 \lesssim \lambda(x_2:\tau_2). e_3
5941
                                      13.1. QED
5942
                                                 \mathsf{stat}\; (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\; v_0 \; \blacktriangleright_{\mathsf{N}} \; \mathsf{mon}\; (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\; v_0 \lesssim \mathsf{mon}\; (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)\; v_1
5943
                              14. CASE mon b_2 (mon b_3 v_2) \lesssim trace, \bar{b}_4 v_3
5944
5945
                                       14.1. Contradiction:
5946
                                                  \cdot \vdash_{\mathsf{A}} v_1 : \tau_1
5947
                              15. Case mon b_2 v_2 \lesssim \text{mon } b_3 v_3
5948
5949
                                       15.1. QED
5950
                                                \mathsf{stat}\,(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\,v_0 \,\blacktriangleright_{\mathsf{N}} \,\mathsf{mon}\,(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\,v_0 \lesssim \mathsf{mon}\,(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)\,v_1
5951
5953
                                        LEMMA 8.16. If \cdot \vdash_{\mathsf{N}} v_0 : \mathcal{U} \text{ and } \cdot \vdash_{\mathsf{A}} \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) : \mathcal{U} \text{ and } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_1) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \lesssim \mathsf{mon}^? b_0 \; (\mathsf{mon}^? b_1 \; v_2) \; \text{then } v_0 \simeq \mathsf{mon}^? b_0 \; (\mathsf{mon
5954
                              add-trace (b_0b_1, v_1).
5955
5956
                                        PROOF. By induction on v_0 via case analysis of v_0 \le \text{mon}^2 b_0 \pmod{b_1 v_1}.
5957
                              1. Case i_0 \lesssim i_0
5958
5959
                                       1.1. QED
5960
                                                  i_0 \lesssim \operatorname{trace}_{\mathsf{v}} b_0 b_1 i_0
5961
                             2. CASE i_0 \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_2 i_0
5962
                                       2.1. QED
5963
                                                 i_0 \leq \operatorname{trace}_{v} b_0 b_1 \overline{b}_2 i_0
                            3. Case \langle v_2, v_3 \rangle \lesssim \text{mon } b_0 \text{ (mon } b_1 \langle v_4, v_5 \rangle)
5966
                                       3.1. v_2 \lesssim \text{mon}^2 b_0 \text{ (mon}^2 b_1 v_4)
5967
                                                         and v_3 \lesssim \text{mon}^2 b_0 \text{ (mon}^2 b_1 v_5)
5968
                                               by inversion \lesssim
5969
5970
                                       3.2. v_2 \lesssim add-trace (b_0b_1, v_4)
5971
                                                         and v_3 \leq add-trace (b_0b_1, v_5)
5972
                                                by the induction hypothesis
5973
                                       3.3. QED
5974
5975
5976
                                                                                                                                                             v_2 \lesssim add-trace(b_0b_1, v_4)
                                                                                                                                                                                                                                                                                    v_3 \lesssim add-trace (b_0b_1, v_5)
5977
                                                                                                                                                                                                               \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} b_0 b_1 \langle v_4, v_5 \rangle
                             4. CASE \langle v_2, v_3 \rangle \lesssim \text{mon } b_0 \text{ (mon } b_1 \text{ (trace}_{\mathbf{v}} \overline{b}_2 \langle v_4, v_5 \rangle))
5980
                             2019-10-03 17:26. Page 115 of 1-148.
```

```
4.1. v_2 \lesssim \text{mon}^2 b_0 \text{ (mon}^2 b_1 \text{ (add-trace}(\overline{b_2}, v_4)))
5981
5982
                         and v_3 \lesssim \mathsf{mon}^? b_0 \ (\mathsf{mon}^? b_1 \ (\mathit{add-trace} \ (\overline{b}_2, v_5)))
5983
                     by inversion \le \
5984
                 4.2. v_2 \lesssim add-trace (b_0b_1, (add-trace (\overline{b}_2, v_4)))
                         and v_3 \lesssim add-trace (b_0b_1, (add-trace (\overline{b}_2, v_5)))
5987
                     by the induction hypothesis
                 4.3. QED
                                        \upsilon_2 \lesssim \textit{add-trace}\left(b_0b_1, (\textit{add-trace}(\overline{b}_2, \upsilon_4))\right) \qquad \upsilon_3 \lesssim \textit{add-trace}\left(b_0b_1, (\textit{add-trace}(\overline{b}_2, \upsilon_5))\right)
                                                                                          \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} b_0 b_1 \overline{b}_2 \langle v_4, v_5 \rangle
             5. CASE \langle v_2, v_3 \rangle \lesssim \text{mon } b_0 \text{ (mon } b_1 \text{ (mon } b_2 \langle v_4, v_5 \rangle))
5994
                 5.1. v_2 \lesssim \text{mon}^? b_0 \text{ (mon}^? b_1 \text{ (mon}^? b_2 v_4))
5995
                         and v_3 \leq \text{mon}^2 b_0 \text{ (mon}^2 b_1 \text{ (mon}^2 b_2 v_5))
5996
5997
                     by inversion ≤
                 5.2. v_2 \lesssim add-trace (b_0b_1, (\text{mon}^? b_2 v_4))
5999
                         and v_3 \lesssim add-trace (b_0b_1, (\text{mon}^? b_2 v_5))
6000
6001
                     by the induction hypothesis
6002
                 5.3. QED
6003
                                                   v_2 \lesssim add-trace (b_0b_1, (\mathsf{mon}^? b_2 v_4)) v_3 \lesssim add-trace (b_0b_1, (\mathsf{mon}^? b_2 v_5))
                                                                                   \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{v_0} b_0 b_1 \pmod{b_2 \langle v_4, v_5 \rangle}
6006
6007
             6. CASE \langle v_2, v_3 \rangle \lesssim \text{mon } b_0 \text{ (mon } b_1 \text{ (trace}_{\mathbf{v}} \overline{b_2} \text{ (mon } b_3 \langle v_4, v_5 \rangle)))
6008
                 6.1. v_2 \lesssim \text{mon}^? b_0 \text{ (mon}^? b_1 \text{ (add-trace}(\overline{b}_2, (\text{mon}^? b_3 v_4))))
6009
                         and v_3 \lesssim \text{mon}^2 b_0 \text{ (mon}^2 b_1 \text{ (add-trace}(\overline{b}_2, (\text{mon}^2 b_3 v_5))))
6010
6011
                     by inversion \le \
6012
                 6.2. v_2 \lesssim add-trace(b_0b_1, (add-trace(\overline{b_2}, (\text{mon}^? b_3 v_4))))
6013
                         and v_3 \lesssim add-trace (b_0b_1, (add-trace (\overline{b}_2, (\text{mon}^? b_3 v_5))))
6014
                     by the induction hypothesis
6015
6016
                 6.3. QED
6018
                                               v_2 \lesssim add-trace(b_0b_1\overline{b}_2, (\mathsf{mon}^?b_3\ v_4)) v_3 \lesssim add-trace(b_0b_1\overline{b}_2, (\mathsf{mon}^?b_3\ v_5))
6019
                                                                                  \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} b_0 b_1 \overline{b}_2 \pmod{b_3} \langle v_4, v_5 \rangle
6020
6021
             7. Case mon b_2 (mon b_3 v_2) \lesssim mon b_0 (mon b_1 \lambda x_3. e_3)
6022
                 7.1. v_2 \lesssim \lambda x_3 . e_3
6023
                     by inversion \le \
6024
                 7.2. QED
6025
6026
6027
                                                                                                           v_2 \lesssim \lambda x_3. e_3
6028
                                                                           \operatorname{mon} b_2 (\operatorname{mon} b_3 v_2) \lesssim (add\operatorname{-trace}(b_0 b_1, \lambda x_3, e_3))
             8. Case mon b_2 (mon b_3 v_2) \lesssim mon b_0 (mon b_n (trace, \overline{b}_6 \lambda x_3. e_3))
```

```
8.1. v_2 \lesssim (\text{trace}_{\mathbf{v}} \, \overline{b}_6 \, \lambda x_3. \, e_3)
6033
6034
                       by inversion \lesssim
6035
                  8.2. QED
6036
6037
                                                                                                                   v_2 \lesssim \lambda x_3. e_3
6038
6039
                                                                               mon b_2 (mon b_3 v_2) \lesssim (add-trace (b_0b_1\overline{b_6}, \lambda x_3. e_3))
6040
              9. CASE mon b_2 (mon b_3 v_2) \lesssim mon b_0 (mon b_1 \lambda(x_3:\tau_3). e_3)
6041
                  9.1. Contradiction:
6042
                       \cdot \vdash_{\mathsf{A}} v_1 : \mathcal{U}
6044
6045
6046
                   LEMMA 8.17. If \vdash \vdash_{N} v_0 : \mathcal{U} and \vdash_{\vdash_{A}} v_1 : \mathcal{U} and tag-match (\lfloor \tau_0 \rfloor, v_0) and v_0 \lesssim v_1 then tag-match (\lfloor \tau_0 \rfloor, v_1)
6047
                  PROOF. By induction on v_1 via case analysis of v_0 \lesssim v_1.
6048
6049
              1. Case i_0 \lesssim i_0
6050
                  1.1. \tau<sup>0</sup> ∈ Nat ∪ Int
6051
                       by inversion tag-match
6052
                  1.2. scase \tau_0 = \text{Nat}
6053
6054
                       1.2.1. i_0 \in \mathbb{N}
6055
                            by inversion tag-match
                       1.2.2. QED
6057
                            tag\text{-}match(\lfloor \mathsf{Nat} \rfloor, i_0)
6058
6059
                  1.3. scase \tau_0 = \operatorname{Int}
6060
                       1.3.1. QED
6061
                            tag-match([Int], i_0)
6062
              2. CASE i_0 \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b_0} i_0
6064
                  similar to previous case
6065
             3. Case \langle v_2, v_3 \rangle \lesssim \langle v_4, v_5 \rangle
6066
                  similar to previous case
6067
             4. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_1) \langle v_4, v_5 \rangle
                  similar to previous case
6070
              5. CASE \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b_0} \langle v_4, v_5 \rangle
6071
                  similar to previous case
6072
             6. CASE \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b_0} \left( \operatorname{mon} \left( \ell_1 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_2 \right) \langle v_4, v_5 \rangle \right)
6073
6074
                  similar to previous case
6075
             7. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} \left( \ell_0 \blacktriangleleft \tau_6 \times \tau_7 \blacktriangleleft \ell_1 \right) \left( \text{trace}_{\mathbf{v}} \, \overline{b}_2 \, \langle v_4, v_5 \rangle \right)
6076
                  similar to previous case
6077
6078
             8. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_6 \times \tau_6 \blacktriangleleft \ell_1) (\text{mon } b_2 \langle v_4, v_5 \rangle)
6079
                  similar to previous case
6080
              9. CASE \langle v_2, v_3 \rangle \lesssim \text{mon } \ell_0 \ \tau_6 \times \tau_7 \ell_1(\text{trace}_{\mathbf{v}} \ \overline{b}_2 \ (\text{mon } b_3 \ \langle v_4, v_5 \rangle))
6081
                  similar to previous case
6082
              10. CASE \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \overline{b}_0 \pmod{b_1 \pmod{b_2 \langle v_4, v_5 \rangle}}
6083
6084
              2019-10-03 17:26. Page 117 of 1-148.
```

```
similar to previous case
6085
6086
                11. CASE \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \bar{b}_0 \text{ (mon } b_1 \text{ (trace}_{\mathbf{v}} \bar{b}_2 \text{ (mon } b_3 \langle v_4, v_5 \rangle)))
6087
                     11.1. \tau_0 \in \tau \times \tau
6088
                          by inversion tag-match
6089
6090
                     11.2. QED
6091
                12. Case \lambda x_2. e_2 \lesssim \lambda x_2. e_3
6092
                     12.1. \tau_0 \in \tau \Longrightarrow \tau
                         by inversion tag-match
                     12.2. QED
                13. CASE \lambda(x_2:\tau_2). e_2 \lesssim \lambda(x_2:\tau_2). e_3
6097
                     13.1. Contradiction:
6098
                           \cdot \vdash_{\mathsf{N}} \upsilon_0 : \mathcal{U}
6099
                14. CASE mon (\ell_0 \blacktriangleleft \tau_2 \Rightarrow \tau_3 \blacktriangleleft \ell_1) (mon b_2 v_2) \lesssim \operatorname{trace}_{v_1} \overline{b}_3 \lambda x_3 \cdot e_3
6100
6101
                     14.1. \tau_0 \in \tau \Longrightarrow \tau
6102
                          by inversion tag-match
6103
                     14.2. QED
6104
                15. CASE mon (\ell_0 \blacktriangleleft \tau_2 \Rightarrow \tau_3 \blacktriangleleft \ell_1) \ v_2 \lesssim \text{mon} \ (\ell_0 \blacktriangleleft \tau_4 \Rightarrow \tau_5 \blacktriangleleft \ell_1) \ v_3
6105
6106
                     similar to previous case
6107
                                                                                                                                                                                                                                                                             LEMMA 8.18. If v_0 and \mathsf{mon}^?(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) v_1 are reduced WF expressions and \cdot \vdash_\mathsf{N} v_0 : \tau_0 and \cdot \vdash_\mathsf{A} \mathsf{mon}^?(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) v_1 : \tau_0
6110
               \tau_1 \text{ and } \tau_0 \leqslant : \tau_1 \text{ and } v_0 \lesssim \text{mon}^? \left(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1\right) v_1 \text{ then dyn } \left(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1\right) v_1 \xrightarrow{*}_{A} v_2 \text{ and } v_0 \lesssim v_2.
6111
6112
                     PROOF. By case analysis of \tau_0 and \lesssim.
6113
               1. Case \tau_0 = \text{Nat}
6114
6115
                     1.1. v_0 \in \mathbb{N}
6116
                          by inversion \vdash_N
6117
                     1.2. Scase v_0 \lesssim v_0
6118
                          1.2.1. QED
6119
                               \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1\right) v_1 \rhd_{\mathsf{A}} v_0 = \mathsf{mon}^?\left(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1\right) v_1
                     1.3. SCASE v_0 \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_0 v_0
                          1.3.1. QED
                               \mathsf{dyn}\,(\ell_0\,\blacktriangleleft\,\tau_1\,\blacktriangleleft\,\ell_1)\,v_1\,\rhd_{\!A}\,\mathsf{trace}_{\!\scriptscriptstyle \mathbf{v}}\,\overline{b}_0\,v_0=\mathsf{mon}^?\,(\ell_0\,\blacktriangleleft\,\tau_1\,\blacktriangleleft\,\ell_1)\,v_1
6124
                2. CASE \tau_0 = Int
6125
6126
                     similar to previous case
6127
               3. CASE \tau_0 = \tau_1 \times \tau_2
6128
                     3.1. v_0 \in \langle v, v \rangle
6129
6130
                          by inversion \vdash_N
6131
                     3.2. SCASE v_0 \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1) \langle v_2, v_3 \rangle
6132
6133
                               6134
                     3.3. SCASE v_0 \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1) (\text{trace}_{\mathbf{v}} \, \overline{b}_2 \, \langle v_2, v_3 \rangle)
```

```
6137
                                                     3.3.1. QED
6138
                                                                \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1\right) v_1 \rhd_{\mathsf{A}} \mathsf{mon}\left(\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1\right) v_1
6139
                                          3.4. SCASE v_0 \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1) (\text{mon } b_2 \langle v_2, v_3 \rangle)
6140
                                                     3.4.1. QED
6141
6142
                                                                \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1\right) v_1 \rhd_{\!\mathsf{A}} \mathsf{mon}\left(\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1\right) v_1
6143
                                          3.5. SCASE v_0 \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1) (\text{trace}_{\mathbf{v}} \overline{b}_2 (\text{mon } b_3 \langle v_2, v_3 \rangle))
6144
                                                     3.5.1. Contradiction:
6145
                                                                \cdot \vdash_{\mathsf{A}} v_1 : \mathcal{U}
6146
                                          3.6. SCASE v_0 \lesssim \text{mon}^+ \overline{b}_0 \pmod{b_1 \pmod{b_2 \langle v_2, v_3 \rangle}}
6148
                                                     3.6.1. Contradiction:
6149
                                                                by lemma 7.10
6150
                                          3.7. SCASE v_0 \lesssim \text{mon}^+ \overline{b_0} \pmod{b_1} (\text{trace}_{\mathbf{v}} \overline{b_2} \pmod{b_3} \langle v_2, v_3 \rangle))
6151
                                                     3.7.1. Contradiction:
6152
6153
                                                                by lemma 7.10
6154
                                4. Case \tau_0 = \tau_1 \Longrightarrow \tau_2
6155
                                          4.1. v_0 \in \lambda x. e \cup \text{mon } b \ v
6156
6157
                                                     by inversion \vdash_{N}
6158
                                          4.2. SCASE v_0 \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_3 \Rightarrow \tau_4 \blacktriangleleft \ell_1) v_1
6159
                                                     4.2.1. QED
                                                                \mathsf{dyn}\,(\ell_0\,\blacktriangleleft\,\tau_3\,\Rightarrow\,\tau_4\,\blacktriangleleft\,\ell_1)\;v_1\,\rhd_{\!\mathsf{A}}\;\mathsf{mon}\,(\ell_0\,\blacktriangleleft\,\tau_3\,\Rightarrow\,\tau_4\,\blacktriangleleft\,\ell_1)\;v_1
6161
6162
6163
                                           LEMMA 8.19. If v_0 and mon^2(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) (mon^2(\ell_2 \blacktriangleleft \tau_2 \blacktriangleleft \ell_3) v_1) are reduced WF expressions and \cdot \vdash_N v_0 : \tau_0 and
6164
6165
                                \cdot \vdash_{\mathsf{A}} \mathsf{mon}^?(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) \left(\mathsf{mon}^?(\ell_2 \blacktriangleleft \tau_2 \blacktriangleleft \ell_3) \ v_1\right) : \tau_1 \ \textit{and} \ v_0 \lesssim \mathsf{mon}^?(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) \left(\mathsf{mon}^?(\ell_2 \blacktriangleleft \tau_2 \blacktriangleleft \ell_3) \ v_1\right) \ \textit{and} \ \tau_0 \leqslant : \tau_1 \blacktriangleleft \tau_1 \blacktriangleleft \tau_2 \blacktriangleleft \tau_2 \blacktriangleleft \tau_3 + \tau_2 \blacktriangleleft \tau_3 + \tau_2 \blacktriangleleft \tau_2 \blacktriangleleft \tau_3 + \tau_3 + \tau_3 + \tau_3 + \tau_3 + \tau_4 + \tau_3 + \tau_4 + \tau
6166
                                then \mathsf{dyn}\,(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)\,(\mathsf{stat}\,(\ell_2 \blacktriangleleft \tau_2 \blacktriangleleft \ell_3)\,\upsilon_1) \to_\mathsf{A}^* \upsilon_2 \ \textit{and}\ \upsilon_0 \lesssim \upsilon_2.
6167
6168
                                          PROOF. By case analysis of \tau_0 and \lesssim.
6169
                                1. Case \tau_0 = Nat
6170
                                          1.1. v_0 \in \mathbb{N}
6171
6172
                                                     by inversion ⊢N
                                          1.2. Scase v_0 \lesssim v_0
6174
                                                     1.2.1. QED
6175
                                                                \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1\right) \left(\mathsf{stat}\left(\ell_2 \blacktriangleleft \tau_2 \blacktriangleleft \ell_3\right) \upsilon_1\right) \to_\mathsf{A}^* \upsilon_0 = \mathsf{mon}^?\left(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1\right) \left(\mathsf{mon}^?\left(\ell_2 \blacktriangleleft \tau_2 \blacktriangleleft \ell_3\right) \upsilon_1\right)
6176
                                          1.3. SCASE v_0 \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b_0} v_0
6177
6178
                                                     1.3.1. QED
6179
                                                                \mathsf{dyn}\,(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)\,(\mathsf{stat}\,(\ell_2 \blacktriangleleft \tau_2 \blacktriangleleft \ell_3)\,v_1) \to_\mathsf{A}^* v_0 = \mathsf{mon}^?\,(\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1)\,(\mathsf{mon}^?\,(\ell_2 \blacktriangleleft \tau_2 \blacktriangleleft \ell_3)\,v_1)
6180
                                2. case \tau_0 = Int
6181
6182
                                          similar to previous case
6183
                               3. Case \tau_0 = \tau_1 \times \tau_2
6184
                                          3.1. v_0 \in \langle v, v \rangle
6185
                                                     by inversion \vdash_N
6186
6187
                                          3.2. SCASE v_0 \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1) \langle v_2, v_3 \rangle
6188
                                2019-10-03 17:26. Page 119 of 1-148.
```

```
6189
                     3.2.1. QED
6190
                           \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1\right) v_1 \rhd_{\mathsf{A}} \mathsf{mon}\left(\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1\right) v_1
6191
                  3.3. SCASE v_0 \lesssim \text{mon} \left(\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1\right) \left(\text{trace}_{\mathbf{v}} \overline{b}_2 \left\langle v_2, v_3 \right\rangle\right)
6192
                      3.3.1. QED
6193
6194
                           \mathsf{dyn}\left(\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1\right) v_1 \rhd_{\!\mathsf{A}} \mathsf{mon}\left(\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1\right) v_1
6195
                  3.4. SCASE v_0 \lesssim \text{mon} \left(\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1\right) \left(\text{mon} \left(\ell_2 \blacktriangleleft \tau_5 \blacktriangleleft \ell_3\right) \langle v_2, v_3 \rangle\right)
6196
                      3.4.1. \tau_5 \in \tau \times \tau
6197
                          by inversion ⊦<sub>A</sub>
                     3.4.2. QED
                           6201
                  3.5. SCASE v_0 \lesssim \text{mon}^+ \overline{b}_0 \pmod{b_1 \pmod{b_2 \langle v_2, v_3 \rangle}}
6202
                      3.5.1. Contradiction:
6203
6204
                          by lemma 7.9
6205
                  3.6. SCASE v_0 \lesssim \text{mon}^+ \overline{b_0} \pmod{b_1} (\text{trace}_{\mathbf{v}} \overline{b_2} \pmod{b_3} \langle v_2, v_3 \rangle))
6206
                      3.6.1. Contradiction:
6207
                          by lemma 7.9
6208
6209
             4. Case \tau_0 = \tau_1 \Rightarrow \tau_2
6210
                  4.1. v_0 \in \lambda x. e \cup \text{mon } b \ v
6211
                      by inversion \vdash_N
6212
                  4.2. Scase v_0 \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_3 \Rightarrow \tau_4 \blacktriangleleft \ell_1) (\text{mon} (\ell_2 \blacktriangleleft \tau_5 \blacktriangleleft \ell_3) v_1)
6213
6214
                      4.2.1. \tau_5 \in \tau \Longrightarrow \tau
6215
                          by inversion ⊢<sub>A</sub>
6216
                      4.2.2. QED
6217
                           6218
6219
                                                                                                                                                                                                                                     6220
6221
                  LEMMA 8.20. If tag\text{-}match(\lfloor \tau_0 \rfloor, \upsilon_0) and \tau_0 \leqslant : \tau_1 then tag\text{-}match(\lfloor \tau_1 \rfloor, \upsilon_0).
6222
                  PROOF. By induction on v_0 via case analysis of tag-match(\lfloor \tau_0 \rfloor, v_0).
6223
             1. CASE tag-match(|Nat|, i_0)
                  1.1. QED
                      \tau_1 \in \text{Nat} \cup \text{Int}
             2. CASE tag-match([Int], i_0)
6228
                  2.1. QED
6229
6230
                      \tau_1 \in Int
6231
             3. CASE tag-match (\lfloor \tau_2 \Rightarrow \tau_3 \rfloor, \lambda x_0. e_0)
6232
                  3.1. QED
6233
6234
                      \tau_1 \in \tau \Longrightarrow \tau
6235
             4. CASE tag-match([\tau_3 \Rightarrow \tau_4], \lambda(x_0:\tau_2). e_0)
6236
6237
                      \tau_1 \in \tau \Longrightarrow \tau
6239
             5. CASE tag-match (\lfloor \tau_2 \times \tau_3 \rfloor, \langle v_2, v_3 \rangle)
```

```
5.1. QED
6241
6242
                           \tau_1 \in \tau \times \tau
6243
                6. CASE tag-match([\tau_4 \Rightarrow \tau_5], mon(\ell_0 \blacktriangleleft \tau_2 \Rightarrow \tau_3 \blacktriangleleft \ell_1) v_1)
6244
                     6.1. QED
6245
6246
                           \tau_1 \in \tau \Longrightarrow \tau
6247
               7. CASE tag-match([\tau_4 \times \tau_5], mon(\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1) v_1)
6248
                     7.1. QED
6249
                           \tau_1 \in \tau \times \tau
6250
               8. CASE tag-match(\lfloor \tau_0 \rfloor, trace_{v}, \bar{b_0}, v_1)
6252
                     8.1. tag-match(\lfloor \tau_0 \rfloor, v_1)
6253
                           by inversion tag-match
6254
                     8.2. tag-match(\lfloor \tau_1 \rfloor, \upsilon_1)
6255
                           by the induction hypothesis
6256
6257
                     8.3. QED
6258
                     8.4. QED
6259
                           by definition tag-match
6260
6261
6262
                      \text{Lemma 8.21. If } \textit{tag-match}(\lfloor \tau_0 \rfloor, \upsilon_0) \textit{ and } \cdot \vdash_{\mathsf{A}} \upsilon_0 : \mathcal{U} \textit{ then } \mathsf{dyn} \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) \upsilon_0 \mathrel{\triangleright_{\!\!\!A}} \mathsf{mon}^? \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) \upsilon_0. 
6263
                      PROOF. By case analysis of tag-match([\tau_0], v_0).
6265
                1. CASE tag-match([Nat], n_0)
6266
6267
                     1.1. QED
6268
                           dyn (\ell_0 \blacktriangleleft Nat \blacktriangleleft \ell_1) n_0 \triangleright_A n_0
6269
                2. Case tag-match([Int], i_0)
6270
6271
                     2.1. QED
6272
                           dyn (\ell_0 \blacktriangleleft Int \blacktriangleleft \ell_1) i_0 \rhd_{A} i_0
6273
               3. CASE tag-match (\lfloor \tau_1 \Rightarrow \tau_2 \rfloor, \lambda x_0. e_0)
6274
                     3.1. QED
6275
6276
                           \mathsf{dyn}\,(\ell_0\,\blacktriangleleft\,\tau_0\,\blacktriangleleft\,\ell_1)\,\upsilon_0\,\rhd_{\!\!A}\,\mathsf{mon}\,(\ell_0\,\blacktriangleleft\,\tau_0\,\blacktriangleleft\,\ell_1)\,\upsilon_0
               4. Case tag-match([\tau_2 \Rightarrow \tau_3], \lambda(x_0:\tau_1).e_0)
6278
                     4.1. Contradiction:
6279
                           \cdot \vdash_{A} \upsilon_{0} : \mathcal{U}
6280
                5. CASE tag-match(\lfloor \tau_1 \times \tau_2 \rfloor, \langle v_1, v_2 \rangle)
6281
6282
                     \mathsf{dyn}\,(\ell_0\,\blacktriangleleft\,\tau_0\,\blacktriangleleft\,\ell_1)\;\upsilon_0\,\rhd_{\!\!A}\;\mathsf{mon}\,(\ell_0\,\blacktriangleleft\,\tau_0\,\blacktriangleleft\,\ell_1)\;\upsilon_0
6283
               6. Case tag-match([\tau_3 \Rightarrow \tau_4], mon(\ell_0 \blacktriangleleft \tau_1 \Rightarrow \tau_2 \blacktriangleleft \ell_1) v_1)
6284
                     \mathsf{dyn}\,(\ell_0\,\blacktriangleleft\,\tau_0\,\blacktriangleleft\,\ell_1)\;\upsilon_0\,\rhd_{\!A}\;\mathsf{mon}\,(\ell_0\,\blacktriangleleft\,\tau_0\,\blacktriangleleft\,\ell_1)\;\upsilon_0
6285
               7. CASE tag-match([\tau_3 \times \tau_4], mon(\ell_0 \blacktriangleleft \tau_1 \times \tau_2 \blacktriangleleft \ell_1) v_1)
6286
6287
                     \mathsf{dyn}\,(\ell_0\,\blacktriangleleft\,\tau_0\,\blacktriangleleft\,\ell_1)\;\upsilon_0\,\rhd_{\!\mathsf{A}}\;\mathsf{mon}\,(\ell_0\,\blacktriangleleft\,\tau_0\,\blacktriangleleft\,\ell_1)\;\upsilon_0
6288
               8. CASE tag-match(\lfloor \tau_1 \rfloor, trace_{v}, \overline{b_0}, v_1)
6289
                     8.1. tag-match(\lfloor \tau_1 \rfloor, \upsilon_1)
6290
                           by inversion tag-match
6292
                2019-10-03 17:26. Page 121 of 1-148.
```

```
8.2. \operatorname{dyn}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_1 \rhd_{A} \operatorname{mon}^{?}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_1
6293
6294
                                                by the induction hypothesis
6295
6296
                                               \mathsf{dyn}\,(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\,\mathsf{trace}_{\mathsf{v}}\,\bar{b_0}\,v_1 \,\rhd_{\mathsf{A}}\,\mathsf{mon}^?\,(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\,(\mathsf{trace}_{\mathsf{v}}\,\bar{b_0}\,v_1)
6297
6298
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          6299
                                        \text{Lemma 8.22. If } v_0 \text{ and } v_1 \text{ are reduced WF expressions and unop} \{\tau?\} \ v_0 \lesssim \text{unop} \{\tau?\} \ v_1 \text{ and } \cdot \vdash_{\mathsf{N}} \text{unop} \{\tau?\} \ v_0 : \tau_0 \text{ and } v_1 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ and } v_1 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ and } v_1 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ and } v_1 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ and } v_1 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ and } v_1 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ and } v_1 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ and } v_1 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ and } v_1 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and unop} \{\tau\} \ v_0 \lesssim v_0 \text{ are reduced WF expressions and uno
6300
6301
                            \cdot \vdash_{\mathsf{A}} \mathit{unop}\{\tau?\} \ v_1 : \tau_1 \ \mathit{and} \ \tau_0 \leqslant \vdash \tau_1 \ \mathit{then} \ \mathit{unop}\{\tau?\} \ v_1 \to_{\mathsf{A}}^* v_2 \ \mathit{and} \ \delta_N(\mathit{unop}, v_0) \lesssim v_2
6302
                                       PROOF. By induction on v_1 via case analysis of \lesssim. The cases for unop = fst\{\tau_2\} and unop = snd\{\tau_2\} are analogous;
6304
                           we show only the fst cases.
6305
                             1. CASE i_0 \leq i_0
6306
                                      1.1. Contradiction:
6307
6308
                                                \cdot \vdash_{\mathsf{N}} unop\{\tau?\} v_0 : \tau_0
6309
                            2. Case i_0 \lesssim \operatorname{trace_v} \overline{b}_0 i_0
6310
                                      2.1. Contradiction:
6311
                                                \cdot \vdash_{\mathsf{N}} unop\{\tau?\} v_0 : \tau_0
6312
                           3. Case \langle v_2, v_3 \rangle \lesssim \langle v_4, v_5 \rangle
6313
6314
                                      3.1. v_2 \lesssim v_4
6315
                                               by inversion \le \
                                      3.2. \delta_N(unop, v_0) = v_2
6317
                                               by definition \delta_N
6318
6319
                                      3.3. unop\{\tau?\} v_1 \triangleright_A v_4
6320
                                               by definition \triangleright_{A}
6321
                                      3.4. QED
6322
6323
                                               by 3.1
6324
                            4. Case \langle v_2, v_3 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1) \langle v_4, v_5 \rangle
6325
                                      4.1. v_2 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) v_4
6326
                                               by inversion \lesssim and \tau_3 \leqslant : \tau_2
6327
                                      4.2. \delta_N(unop, v_0) = v_2
                                               by definition \delta_N
                                      4.3. unop\{\tau?\} v_1
6331
                                                        \rightarrow_{\mathsf{A}} \mathsf{dyn} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \left(\mathit{unop}\{\tau?\} \left< \upsilon_4, \upsilon_5 \right>\right)
6332
                                                       \rightarrow_{\mathsf{A}} \mathsf{dyn} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) v_4
6333
6334
                                               by definition \rightarrow_A
6335
                                      4.4. QED
6336
                                               by lemma 8.18
6337
                            5. CASE \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{v} \overline{b_0} \langle v_4, v_5 \rangle
6338
6339
                                      5.1. Contradiction:
6340
                                                 \cdot \vdash_{\mathsf{A}} v_1 : \tau_1
6341
                            6. CASE \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b_0} \left( \operatorname{mon} \left( \ell_1 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_2 \right) \langle v_4, v_5 \rangle \right)
6342
                                      6.1. Contradiction:
```

```
6345
                                  \cdot \vdash_{\mathsf{A}} v_1 : \tau_1
6346
                    7. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1) (\text{trace}_{\mathbf{v}} \, \overline{b}_2 \, \langle v_4, v_5 \rangle)
6347
                           7.1. v_2 \lesssim \text{mon}^2(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) (add-trace(\overline{b}_2, v_4))
6348
                                  by inversion \lesssim and \tau_3 \leqslant : \tau_2
6349
6350
                           7.2. \delta_N(unop, v_0) = v_2
6351
                                 by definition \delta_N
6352
                           7.3. unop\{\tau?\}v_1
6353
                                         \rightarrow_{\mathsf{A}} \operatorname{\mathsf{dyn}} (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) (\operatorname{\mathit{unop}} \{\tau?\} (\operatorname{\mathsf{trace}}_{\mathsf{V}} \overline{b}_2 \langle v_4, v_5 \rangle))
6354
                                        \rightarrow_{\mathsf{A}} \operatorname{\mathsf{dyn}} (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) (\mathit{add-trace}(\overline{b}_2, v_4))
6355
6356
                                  by definition \rightarrow_{\Delta}
6357
                           7.4. QED
6358
                                  by lemma 8.18
6359
                     8. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} \left( \ell_0 \blacktriangleleft \tau_3 \times \tau_4 \blacktriangleleft \ell_1 \right) \left( \text{mon} \left( \ell_2 \blacktriangleleft \tau_5 \times \tau_6 \blacktriangleleft \ell_3 \right) \langle v_4, v_5 \rangle \right)
6360
6361
                           8.1. v_2 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) (\text{mon}^? (\ell_2 \blacktriangleleft \tau_5 \blacktriangleleft \ell_3) v_4)
6362
                                  by inversion \leq and \tau_3 \leqslant : \tau_2
6363
                           8.2. \delta_N(unop, v_0) = v_2
6364
                                  by definition \delta_N
6365
6366
                           8.3. unop\{\tau?\}v_1
6367
                                         \rightarrow_{\mathsf{A}} \mathsf{dyn} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \left(\mathit{unop}\{\tau?\} \left(\mathsf{mon} \left(\ell_2 \blacktriangleleft \tau_5 \times \tau_6 \blacktriangleleft \ell_3\right) \left\langle v_4, v_5 \right\rangle\right)\right)
                                         \rightarrow_{\mathsf{A}} \mathsf{dyn} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \left(\mathsf{stat} \left(\ell_2 \blacktriangleleft \tau_5 \blacktriangleleft \ell_3\right) \left(\mathit{unop}\{\tau?\} \left\langle v_4, v_5 \right\rangle\right)\right)
6369
6370
                                         \rightarrow_{\mathsf{A}} \mathsf{dyn} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \left(\mathsf{stat} \left(\ell_2 \blacktriangleleft \tau_5 \blacktriangleleft \ell_3\right) v_4\right)
6371
                                         \rightarrow_{\mathsf{A}} \mathsf{dyn} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \left(\mathsf{stat} \left(\ell_2 \blacktriangleleft \tau_5 \blacktriangleleft \ell_3\right) v_4\right)
6372
                                  by definition \rightarrow_A
6373
                           8.4. QED
6374
6375
                                  by lemma 8.19
6376
                    9. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} \left( \ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1 \right) \left( \text{trace}_{\mathbf{v}} \, \overline{b}_2 \left( \text{mon} \left( \ell_3 \blacktriangleleft \tau_4 \times \tau_5 \blacktriangleleft \ell_4 \right) \left\langle v_4, v_5 \right\rangle \right) \right)
6377
                           9.1. v_2 \lesssim \text{mon}^? (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) (add\text{-trace}(\overline{b}_2, (\text{mon}^? (\ell_3 \blacktriangleleft \tau_4 \blacktriangleleft \ell_4) v_4)))
6378
                                  by inversion \lesssim and \tau_3 \leqslant : \tau_2
6379
6380
                           9.2. \delta_N(unop, v_0) = v_2
                                  by definition \delta_N
6382
                           9.3. unop\{\tau?\}v_1
6383
                                        \to_{\mathsf{A}} \mathsf{dyn} \, (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) \, (\mathit{unop}\{\tau?\} \, (\mathsf{trace}_{\mathsf{v}} \, \overline{b}_2 \, (\mathsf{mon} \, (\ell_3 \blacktriangleleft \tau_4 \times \tau_5 \blacktriangleleft \ell_4) \, \langle v_4, v_5 \rangle)))
6384
                                        \to_{\mathsf{A}} \mathsf{dyn}\,(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1)\,(\mathsf{trace}\,\overline{b}_2\,(\mathsf{stat}\,(\ell_3 \blacktriangleleft \tau_4 \blacktriangleleft \ell_4)\,(\mathit{unop}\{\tau?\}\,\langle \upsilon_4,\upsilon_5\rangle)))
6385
6386
                                        \to_{\mathsf{A}} \mathsf{dyn}\,(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1)\,(\mathsf{trace}\, \overline{b}_2\,(\mathsf{stat}\,(\ell_3 \blacktriangleleft \tau_4 \blacktriangleleft \ell_4)\,v_4))
6387
                                  by definition \rightarrow_{\Delta}
6388
                           9.4. QED
6389
6390
                                  by lemma 8.19
6391
                     10. CASE \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \overline{b_0} \pmod{b_1 \pmod{b_2 \langle v_4, v_5 \rangle}}
6392
                           10.1. Contradiction:
6393
                                   by lemma 7.9
6394
                     11. CASE \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \overline{b_0} \left( \text{mon } b_1 \left( \text{trace}_v \overline{b_2} \left( \text{mon } b_3 \left\langle v_4, v_5 \right\rangle \right) \right) \right)
6395
6396
                    2019-10-03 17:26. Page 123 of 1-148.
```

```
6397
                    11.1. Contradiction:
6398
                         by lemma 7.9
6399
               12. CASE \lambda x_2. e_2 \lesssim \lambda x_2. e_3
6400
                    12.1. Contradiction:
6401
6402
                         \cdot \vdash_{\mathsf{N}} unop\{\tau?\} v_0 : \tau_0
6403
               13. CASE \lambda(x_2:\tau_2). e_2 \lesssim \lambda(x_2:\tau_2). e_3
6404
                    13.1. Contradiction:
6405
                         \cdot \vdash_{\mathsf{N}} unop\{\tau?\} v_0 : \tau_0
6406
               14. CASE mon (\ell_0 \blacktriangleleft \tau_2 \Rightarrow \tau_3 \blacktriangleleft \ell_1) (mon b_2 v_2) \lesssim \operatorname{trace}_{v_1} \overline{b}_3 \lambda x_3 \cdot e_3
6407
6408
                    14.1. Contradiction:
6409
                         \cdot \vdash_{\mathsf{N}} unop\{\tau?\} v_0 : \tau_0
6410
               15. CASE mon (\ell_0 \blacktriangleleft \tau_2 \Rightarrow \tau_3 \blacktriangleleft \ell_1) v_2 \lesssim \text{mon } (\ell_0 \blacktriangleleft \tau_4 \Rightarrow \tau_5 \blacktriangleleft \ell_1) v_3
6411
                    15.1. Contradiction:
6412
6413
                         \cdot \vdash_{\mathsf{N}} unop\{\tau?\} v_0 : \tau_0
6414
                                                                                                                                                                                                                                                                6415
6416
                    LEMMA 8.23. If v_0 and v_1 are reduced WF expressions and unop\{\tau?\} v_0 \lesssim unop\{\tau?\} v_1 and \cdot \vdash_N unop\{\tau?\} v_0 : \mathcal{U} and
6417
               \cdot \vdash_{\mathsf{A}} unop\{\tau?\} v_1 : \mathcal{U} \text{ then } unop\{\tau?\} v_0 \blacktriangleright_{\mathsf{N}} e_2 \text{ and } unop\{\tau?\} v_1 \rightarrow_{\mathsf{A}}^* e_3 \text{ and } e_2 \lesssim e_3.
6418
6419
                    PROOF. By cases on v_0 \lesssim v_1. The cases for unop = fst\{\tau\} and unop = snd\{\tau\} are similar; we present only the fst
6420
               cases.
6421
6422
               1. CASE i_0 \leq i_0
6423
                    1.1. QED
6424
                         unop\{\tau?\}\ v_0 \blacktriangleright_{\mathsf{N}} \mathsf{TagErr} \bullet \mathsf{and}\ unop\{\tau?\}\ v_1 \blacktriangleright_{\mathsf{A}} \mathsf{TagErr} \bullet
6425
               2. CASE i_0 \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_0 i_0
6426
6427
                    2.1. QED
6428
                         unop\{\tau?\}\,v_0\,\blacktriangleright_{\mathsf{N}}\,\mathsf{TagErr}\bullet \mathrm{and}\,\,unop\{\tau?\}\,v_1\,\blacktriangleright_{\mathsf{A}}\,\mathsf{TagErr}\bullet
6429
              3. Case \langle v_2, v_3 \rangle \lesssim \langle v_4, v_5 \rangle
6430
                   3.1. v_2 \lesssim v_4
6431
                        by inversion ≤
6432
6433
                         unop\{\tau?\} v_0 \triangleright_{\mathsf{N}} v_2 \text{ and } unop\{\tau?\} v_1 \triangleright_{\mathsf{A}} v_4
               4. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1) \langle v_4, v_5 \rangle
6436
                    4.1. v_2 \leq \text{mon}^? (\ell_0 \triangleleft \tau_2 \triangleleft \ell_1) v_4
6437
6438
                        by inversion \le \( \)
6439
                    4.2. unop\{\tau?\} v_0 \triangleright_{N} v_2
6440
                        by definition \triangleright_{N}
6441
                    4.3. unop\{\tau?\}v_1
6442
6443
                             \rightarrow_{\mathsf{A}} \mathsf{stat} \left(\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1\right) \left(\mathit{unop}\{\tau?\} \left< \upsilon_4, \upsilon_5 \right>\right)
6444
                             \rightarrow_{\mathsf{A}} \operatorname{stat} (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) v_4
6445
                        by definition \rightarrow_A
6446
                    4.4. QED
```

```
by lemma 8.24
6449
6450
                 5. CASE \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b_0} \langle v_4, v_5 \rangle
6451
                      5.1. v_2 \lesssim add-trace (\overline{b}_0, v_4)
6452
                           by inversion \lesssim
6453
6454
                      5.2. unop\{\tau?\} v_0 \blacktriangleright_{N} v_2
6455
                           by definition \triangleright_{N}
6456
                      5.3. unop\{\tau?\} v_1 \blacktriangleright_A add-trace(\overline{b}_0, v_4)
6457
                           by definition \triangleright_A
6458
6459
                      5.4. QED
6460
                           by 5.1
6461
                6. CASE \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b_0} \left( \operatorname{mon} \left( \ell_1 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_2 \right) \langle v_4, v_5 \rangle \right)
6462
                      6.1. v_2 \lesssim add-trace (\overline{b}_0, (\text{mon}^? (\ell_1 \blacktriangleleft \tau_2 \blacktriangleleft \ell_2) v_4))
6463
                           by inversion \lesssim
6464
6465
                      6.2. unop\{\tau?\} v_0 \triangleright_{N} v_2
6466
                           by definition \triangleright_{N}
6467
                      6.3. unop\{\tau?\}v_1
6468
                                 \to_{\mathsf{A}} \mathsf{trace}\, \overline{b}_0\, (\mathsf{stat}\, (\ell_1 \blacktriangleleft \tau_2 \blacktriangleleft \ell_2)\, (\mathit{unop}\{\tau?\}\, \langle \upsilon_4, \upsilon_5\rangle))
6469
6470
                                 \rightarrow_{\Delta} \operatorname{trace} \overline{b}_0 \left( \operatorname{stat} \left( \ell_1 \blacktriangleleft \tau_2 \blacktriangleleft \ell_2 \right) \upsilon_4 \right)
6471
                                \rightarrow_{\mathsf{A}} \operatorname{trace} \overline{b}_0 \left( \mathsf{mon}^? \left( \ell_1 \blacktriangleleft \tau_2 \blacktriangleleft \ell_2 \right) v_4 \right)
6472
                                \rightarrow_{\mathsf{A}} add\text{-trace}(\overline{b}_0, (\mathsf{mon}^? (\ell_1 \blacktriangleleft \tau_2 \blacktriangleleft \ell_2) \ v_4))
6473
6474
                           by definition \rightarrow_A and lemma 8.24
6475
                      6.4. QED
6476
                7. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} \left( \ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1 \right) \left( \text{trace}_{\mathbf{v}} \, \overline{b}_2 \, \langle v_4, v_5 \rangle \right)
6477
                      7.1. Contradiction:
6478
6479
                            \cdot \vdash_{\mathsf{A}} v_1 : \mathcal{U}
6480
                8. CASE \langle v_2, v_3 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_1) (\text{mon} (\ell_2 \blacktriangleleft \tau_4 \times \tau_5 \blacktriangleleft \ell_3) \langle v_4, v_5 \rangle)
6481
                      8.1. Contradiction:
6482
                           by lemma 7.10
6483
                9. CASE \langle v_2, v_3 \rangle \lesssim \text{mon } \ell_0 \ \tau_2 \times \tau_3 \ell_1(\text{trace}_{\mathbf{v}} \ \overline{b}_2 \ (\text{mon } b_3 \ \langle v_4, v_5 \rangle))
6484
6485
                      9.1. Contradiction:
6486
                           by lemma 7.10
6487
                 10. CASE \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \bar{b}_0 \pmod{b_1 \pmod{b_2 \langle v_4, v_5 \rangle}}
6488
                      10.1. Contradiction:
6489
6490
                           by lemma 7.10
6491
                 11. CASE \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \overline{b}_0 \text{ (mon } b_1 \text{ (trace}_v \overline{b}_2 \text{ (mon } b_3 \langle v_4, v_5 \rangle)))}
6492
                      11.1. Contradiction:
6493
                           by lemma 7.10
6494
6495
                 12. CASE \lambda x_2. e_2 \lesssim \lambda x_2. e_3
6496
                      12.1. QED
6497
                            unop\{\tau?\}\ v_0 \blacktriangleright_{\mathsf{N}} \mathsf{TagErr} \bullet \mathsf{and}\ unop\{\tau?\}\ v_1 \blacktriangleright_{\mathsf{A}} \mathsf{TagErr} \bullet
6498
6499
                 13. CASE \lambda(x_2:\tau_2). e_2 \lesssim \lambda(x_2:\tau_2). e_3
6500
                2019-10-03 17:26. Page 125 of 1-148.
```

```
6501
                        13.1. Contradiction:
6502
                               \cdot \vdash_{\mathsf{N}} v_0 : \mathcal{U}
6503
                  14. CASE mon (\ell_0 \blacktriangleleft \tau_2 \Rightarrow \tau_3 \blacktriangleleft \ell_1) (mon b_2 v_2) \lesssim trace, \bar{b}_3 \lambda x_3. e_3
6504
6505
                               unop\{\tau?\}\ v_0 \blacktriangleright_{\mathsf{N}} \mathsf{TagErr} \bullet \mathsf{and}\ unop\{\tau?\}\ v_1 \blacktriangleright_{\mathsf{A}} \mathsf{TagErr} \bullet
6506
6507
                  15. CASE mon (\ell_0 \blacktriangleleft \tau_2 \Rightarrow \tau_3 \blacktriangleleft \ell_1) v_2 \lesssim \text{mon } (\ell_0 \blacktriangleleft \tau_4 \Rightarrow \tau_5 \blacktriangleleft \ell_1) v_3
6508
                        15.1. QED
6509
                               unop\{\tau?\} v_0 \triangleright_{\mathsf{N}} \mathsf{TagErr} \bullet \text{ and } unop\{\tau?\} v_1 \triangleright_{\mathsf{A}} \mathsf{TagErr} \bullet
6510
                                                                                                                                                                                                                                                                                                                        6512
6513
                        LEMMA 8.24. If v_0 and v_1 are reduced WF expressions and \cdot \vdash_N v_0 : \mathcal{U} and \cdot \vdash_A v_1 : \tau_0 and v_0 \leq \text{mon}^2 (\ell_0 \triangleleft \tau_0 \triangleleft \ell_1) v_1
6514
                  then stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_1 \rightarrow^*_{\Delta} v_2 and v_0 \lesssim v_2.
6515
                        PROOF. By case analysis of \lesssim.
6516
6517
                  1. Case i_0 \lesssim i_0
6518
                        1.1. QED
6519
                              \operatorname{stat} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_1 \blacktriangleright_{\!\!\!\! A} v_1
6520
                  2. CASE i_0 \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_2 i_0
6521
6522
6523
                              \mathsf{stat} \; (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \; \upsilon_1 \; \blacktriangleright_{\!\!\!\! A} \; \upsilon_0
6524
                 3. Case \langle v_3, v_4 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \langle v_5, v_6 \rangle
6525
6526
6527
                               stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_1 \blacktriangleright_A \mod (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_1
6528
                  4. CASE \langle v_3, v_4 \rangle \leq \text{mon} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (\text{trace}_{v} \overline{b}_2 \langle v_5, v_6 \rangle)
6529
                        4.1. Contradiction:
6530
6531
                              \cdot \vdash_{\mathsf{A}} v_1 : \tau_0
6532
                  5. Case \langle v_3, v_4 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (\text{mon } b_2 \langle v_5, v_6 \rangle)
6533
                        5.1. v_3 \leq \text{mon}^2 \left(\ell_0 \blacktriangleleft fst(\tau_0) \blacktriangleleft \ell_1\right) \left(\text{mon fst}(b_2) v_5\right)
6534
                                   and v_4 \lesssim \text{mon}^2(\ell_0 \blacktriangleleft snd(\tau_0) \blacktriangleleft \ell_1) \text{ (mon snd } (b_2) v_6)
6535
                              by inversion ≤
6536
                        5.2. stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (mon b_2 \langle v_5, v_6 \rangle) \blacktriangleright_{\mathsf{A}} \operatorname{trace}_{\mathsf{v}} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) b_2 \langle v_5, v_6 \rangle
                              by definition ▶₄
                  6. CASE \langle v_3, v_4 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (\text{trace}_{\mathbf{v}} \overline{b}_2 (\text{mon } b_3 \langle v_4, v_5 \rangle))
6540
                        6.1. Contradiction:
6541
6542
                               \cdot \vdash_{\mathsf{A}} v_1 : \tau_0
6543
                  7. CASE \langle v_3, v_4 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (\text{mon } b_2 (\text{trace}_v^? \overline{b_3} (\text{mon } b_4 \langle v_4, v_5 \rangle)))
6544
                        7.1. stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_1 \blacktriangleright_A \operatorname{trace}_{\mathsf{v}} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) b_2 \overline{b}_3 \pmod{b_4} \langle v_4, v_5 \rangle)
6545
                              by definition \triangleright_{\Delta}
6546
6547
                        7.2. QED
6548
                              by lemma 8.25
6549
                  8. CASE \langle v_3, v_4 \rangle \lesssim \text{mon} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (\text{mon } b_2 (\text{mon } b_3 (\text{trace}_v^? \overline{b_4} (\text{mon } b_5 \langle v_4, v_5 \rangle))))
6550
                        8.1. Contradiction:
```

```
by lemma 7.10
6553
6554
              9. CASE mon b_2(\lambda x_2. e_2) \lesssim \text{mon}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)(\lambda x_2. e_3)
6555
                  9.1. Contradiction:
6556
                       \cdot \vdash_{\mathsf{A}} v_1 : \tau_0
6557
              10. Case mon b_2 (\lambda(x_2:\tau_2).e_2)\lesssim \text{mon}\ (\ell_0\blacktriangleleft\tau_0\blacktriangleleft\ell_1)\ (\lambda(x_2:\tau_2).e_3)
6558
6559
                  10.1. QED
6560
                       \operatorname{stat} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_1 \blacktriangleright_{\mathsf{A}} \ \operatorname{mon} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_1
6561
              11. CASE mon b_2 (mon b_3 (\lambda x_2. e_2)) \lesssim mon (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (mon b_4 (trace \frac{?}{b_5}(\lambda x_2. e_3)))
6562
                  11.1. stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_1 \blacktriangleright_{\mathsf{N}} add\text{-}trace((\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)b_4\overline{b}_5, (\lambda x_2.e_3))
6564
                       by definition \triangleright_N
6565
                  11.2. QED
6566
                       by lemma 8.25
6567
              12. CASE mon b_2 (mon b_3 (mon b_4 (\lambda x_2.e_2))) \lesssim mon (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (mon b_5 (trace \frac{1}{2}b_6 (mon b_7 (\lambda (x_2:\tau_2).e_3))))
6568
6569
                  12.1. stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_1 \blacktriangleright_N add-trace((\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)b_4b_5\overline{b}_6, (\text{mon } b_7 (\lambda(x_2:\tau_2).\ e_3)))
6570
                       by definition \triangleright_{N}
6571
                  12.2. QED
6572
6573
                       by lemma 8.25
6574
              13. CASE mon b_2 (mon b_3 (mon b_4 (mon b_5 (\lambda x_2.e_2)))) \lesssim mon (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (mon b_5 (mon b_6 (mon b_7 v_2)))
6575
                   13.1. Contradiction:
6576
                       by lemma 7.10
6577
6578
                                                                                                                                                                                                                                              6579
6580
                   LEMMA 8.25. If v_0 and v_1 are reduced WF expressions and \cdot \vdash_N v_0 : \mathcal{U} and \cdot \vdash_A v_1 : \mathcal{U} and v_0 \lesssim \text{mon}^2 b_0 \, (\text{mon}^2 b_1 \, v_1)
6581
              then v_0 \lesssim add-trace (b_0b_1, v_1).
6582
6583
                  PROOF. By induction on v_0 via case analysis of \lesssim.
6584
6585
              1. Case i_0 \lesssim i_0
6586
                  1.1. QED
6587
                       i_0 \lesssim \operatorname{trace}_{\mathsf{v}} b_0 b_1 i_0
6588
             2. CASE i_0 \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_2 i_0
6590
                  2.1. QED
6591
                       i_0 \lesssim \operatorname{trace}_{\mathsf{v}} b_0 b_1 \overline{b}_2 i_0
6592
             3. CASE \langle v_2, v_3 \rangle \lesssim \text{mon } b_0 \text{ (mon } b_1 \langle v_4, v_5 \rangle)
6593
                  3.1. v_2 \lesssim \text{mon}^2 \text{ fst } (b_0) \text{ (mon}^2 \text{ fst } (b_1) v_4)
6594
6595
                           and v_3 \lesssim \text{mon}^2 \text{ snd } (b_0) \text{ (mon}^2 \text{ snd } (b_1) v_5)
6596
                       by inversion \lesssim
6597
                  3.2. v_2 \lesssim add-trace (fst (b_0)fst (b_1), v_4)
6598
                           and v_3 \lesssim add-trace (snd (b_0)snd (b_1), v_5)
6599
6600
                       by the induction hypothesis
6601
6602
             4. CASE \langle v_2, v_3 \rangle \lesssim \text{mon } b_0 \text{ (mon } b_1 \text{ (trace}_v^? \overline{b_2} \text{ (mon } b_3 \langle v_4, v_5 \rangle)))
6603
6604
             2019-10-03 17:26. Page 127 of 1-148.
```

```
4.1. v_2 \lesssim \text{mon}^2 \text{ fst } (b_0) \text{ (mon}^2 \text{ fst } (b_1) \text{ (add-trace (fst } (\overline{b}_2), (\text{mon } b_3 v_4))))}
6605
6606
                     and v_3 \lesssim \text{mon}^2 \text{ snd } (b_0) \text{ (mon}^2 \text{ snd } (b_1) \text{ (add-trace} (\text{snd } (\overline{b}_2), (\text{mon } b_3 v_5))))
6607
                  by inversion \le \
6608
               4.2. v_2 \lesssim add-trace (fst (b_0)fst (b_1), (add-trace (fst (\overline{b_2}), (\text{mon } b_3 \ v_4))))
6609
                     and v_3 \lesssim add-trace (snd (b_0)snd (b_1), (add-trace (snd (\overline{b_2}), (mon b_3 v_5))))
6610
6611
                  by the induction hypothesis
6612
               4.3. QED
6613
           5. CASE \langle v_2, v_3 \rangle \lesssim \text{mon } b_0 \text{ (mon } b_1 \text{ (mon } b_2 \text{ (trace}_v^? \overline{b}_3 \text{ (mon } b_4 \langle v_4, v_5 \rangle))))}
6614
               5.1. Contradiction:
6616
                  by lemma 7.10
6617
           6. CASE mon b_2 (mon b_3 (\lambda x_2. e_2)) \lesssim mon b_0 (mon b_1 (\lambda x_2. e_3))
6618
               6.1. \lambda x_2. e_2 \lesssim \lambda x_2. e_3
6619
                  by inversion ≤
6620
6621
               6.2. QED
6622
                  by definition \le \
6623
           7. Case mon b_2 (mon b_3 (mon b_4 (\lambda(x_2:\tau_2).e_2))) \lesssim mon b_0 (mon b_1 (mon b_5 (\lambda x_2.e_3)))
6624
               7.1. \lambda(x_2:\tau_2). e_2 \lesssim \lambda(x_2:\tau_2). e_3
6625
6626
                  by inversion ≤
               7.2. QED
                  by definition ≤
6630
           8. CASE mon b_2 (mon b_3 (mon b_4 (mon b_5 v_2))) \lesssim mon b_0 (mon b_1 (mon b_6 (mon b_7 v_3)))
6631
               8.1. Contradiction:
6632
                  by lemma 7.10
6633
6634
                                                                                                                                                                                                6635
6636
               LEMMA 8.26. If app\{U\} v_0 v_1 and app\{U\} (trace, b_0\overline{b_1} v_2) v_3 are reduced WF expressions and app\{U\} v_0 v_1 \lesssim
6637
           app\{\mathcal{U}\} (trace, b_0\overline{b}_1 v_2) v_3 then one of the following holds:
6638
                 • \operatorname{app}\{\mathcal{U}\}\ v_0\ v_1 \to_{\mathsf{N}}^* E_0[\operatorname{app}\{\tau?\}\ v_4\ (\operatorname{BndryErr}\ (b_3,v_5))]
6639
                     and E_0 \lesssim \operatorname{trace} b_0 \cdots b_i
                     and v_4 \lesssim add-trace (b_i \cdots b_n, v_2)
                 • app\{\mathcal{U}\} v_0 v_1 \rightarrow_{\mathsf{N}}^* E_0[app\{\tau?\} v_4 v_5]
6643
                     and E_0 \lesssim \operatorname{trace} b_0 \overline{b}_1 []
6644
6645
                     and v_4 \lesssim v_2
6646
                     and v_5 \lesssim add-trace (flip (b_0 \overline{b}_1), v_3)
6647
6648
               PROOF. By induction on the length of \bar{b}_1.
6649
           1. \overline{b}_1 = \cdot
6650
               1.1. Contradiction:
6651
6652
                  by \leq
6653
           2. \bar{b}_1 = b_1
6654
               2.1. v_0 = \text{mon } b_2 \pmod{b_3 v_4} and b_2 \leqslant b_0 and b_3 \leqslant b_1
6655
```

```
by inversion \le \
6657
6658
                   2.2. \operatorname{app}\{\mathcal{U}\}\,v_0\,\,v_1\,\blacktriangleright_{\!\!\!\!\!N}\,\operatorname{stat}\,\operatorname{cod}\,(b_2)\,(\operatorname{app}\{\tau_1\}\,(\operatorname{mon}\,b_3\,\,v_4)\,(\operatorname{dyn}\,\operatorname{dom}\,(b_2)\,v_1))
6659
                       by definition \triangleright_{N}
6660
                   2.3. Assume dyn dom (b_2)v_1 = v_5
6661
                        otherwise, end with a boundary error
6662
6663
                   2.4. app\{\tau_1\} (mon b_3 \ v_4) v_5 \rhd_N dyn cod(b_3) (app\{\mathcal{U}\}\ v_4 (stat dom(b_3)\ v_5)) and stat dom(b_3)\ v_5 \blacktriangleright_N \ v_6
6664
                        by definition \triangleright_{\mathsf{N}} and \blacktriangleright_{\mathsf{N}}
6665
                   2.5. v_6 \lesssim add-trace (flip (dom (b_0)dom (b_1)), v_3)
                       by lemma 8.27
6668
                   2.6. QED
6669
                        \operatorname{stat} \operatorname{cod}(b_2) (\operatorname{dyn} \operatorname{cod}(b_3) (\operatorname{app}\{\mathcal{U}\} v_4 v_6)) \lesssim \operatorname{trace}_{\mathbf{v}} b_0 b_1 (\operatorname{app}\{\mathcal{U}\} v_2 \operatorname{trace}_{\mathbf{v}} \operatorname{flip}(b_0 b_1) v_3)
6670
              3. \bar{b}_1 = b_1 b_2 \bar{b}_3
6671
                   3.1. v_0 = \text{mon } b_3 \pmod{b_4} v_4 and b_3 \leqslant b_1 and b_4 \leqslant b_2
6672
6673
                       by inversion ≤
6674
                   3.2. \operatorname{app}\{\mathcal{U}\}\ v_0\ v_1 \to_{\stackrel{N}{N}}^* \operatorname{stat}\operatorname{cod}(b_3) \left(\operatorname{dyn}\operatorname{dom}(b_4)\left(\operatorname{app}\{\mathcal{U}\}\ v_4\ v_6\right)\right) and v_4 \lesssim \operatorname{trace}_{\stackrel{V}{V}} \overline{b_3}\ v_2 and v_6 \lesssim \operatorname{trace}_{\stackrel{V}{V}} \operatorname{flip}(b_0b_1)\ v_3
6675
6676
                       by similar reasoning as the previous case
6677
6678
                   3.3. \operatorname{app}\{\mathcal{U}\}\ v_4\ v_6 \to_{\mathsf{N}}^* E_1[\operatorname{app}\{\mathcal{U}\}\ v_7\ v_8]
                       by the induction hypothesis, assuming no boundary errors
                   3.4. QED
6681
                        stat b_3 (dyn b_4 (E_1[app\{\mathcal{U}\}v_7v_8])) \lesssim add-trace (b_0b_1b_2\bar{b}_3, app\{\mathcal{U}\}v_2 (trace, flip(b_0b_1\bar{b}_2)v_3)
6682
6683
6684
6685
                    LEMMA 8.27. If v_0 and v_1 are reduced WF expressions and \cdot \vdash_N v_0 : \mathcal{U} and \cdot \vdash_A v_1 : \mathcal{U} and v_0 \lesssim v_1 and b_0 \leqslant b_2 and
6686
              b_1\leqslant:b_3 \text{ then stat } b_0 \text{ (dyn } b_1 \text{ } v_0) \to_{\mathsf{N}}^* e_2 \text{ and } e_2\lesssim \textit{add-trace}(b_2b_3,v_1).
6687
6688
                   PROOF. By induction on v_0 via cases on v_0 \lesssim v_1.
6689
              We assume below that every subexpression of the form dyn b v steps to a value, because otherwise e_2 is a boundary
6690
              error and the result is immediate.
6691
              1. CASE i_0 \lesssim i_0
6692
                        \mathsf{stat}\ b_0\ (\mathsf{dyn}\ b_1\ i_0) \to_{\mathsf{N}}^*\ i_0 \lesssim \mathsf{trace}_{\mathsf{V}}\ b_2b_3\ i_0
6695
              2. CASE i_0 \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_0 \operatorname{trace}_{\mathbf{v}} \overline{b}_4 i_0
6696
6697
                        \mathsf{stat}\ b_0\ (\mathsf{dyn}\ b_1\ i_0) \to_{\mathsf{N}}^*\ i_0 \lesssim \mathsf{trace}_{\mathsf{V}}\ b_2b_3\overline{b}_4\ i_0
6698
6699
              3. Case \langle v_2, v_3 \rangle \lesssim \langle v_4, v_5 \rangle
6700
                   3.1. v_2 \lesssim v_4 and v_3 \lesssim v_5
6701
                       by inversion \le \
6702
6703
                   3.2. stat b_0 (dyn b_1 \langle v_2, v_3 \rangle) \rightarrow_{\mathsf{N}} stat b_0 \langle \mathsf{dyn} \, \mathsf{fst} \, (b_1) \, v_2, \mathsf{dyn} \, \mathsf{snd} \, (b_1) \, v_3 \rangle
6704
                       by definition \rightarrow_{N}
6705
                   3.3. stat b_0 \langle \mathsf{dyn} \, \mathsf{fst} \, (b_1) \, v_2, \mathsf{dyn} \, \mathsf{snd} \, (b_1) \, v_3 \rangle \, \mathop{\to_{\mathsf{N}}^*} \, \langle v_6, v_7 \rangle
6706
                            if and only if \langle \text{stat fst } (b_0) \text{ (dyn fst } (b_1) v_2), \text{ stat snd } (b_0) \text{ (dyn snd } (b_1) v_3) \rangle \rightarrow_N^* \langle v_6, v_7 \rangle
6707
6708
              2019-10-03 17:26. Page 129 of 1-148.
```

```
by lemma 8.28
6709
6710
               3.4. v_6 \lesssim add-trace (fst (b_2)fst (b_3), v_4)
6711
                      and v_7 \lesssim add-trace (snd (b_2)snd (b_3), v_4)
6712
                   by the induction hypothesis
6713
6714
               3.5. OED
6715
                   by definition \le \
6716
            4. CASE \langle v_2, v_3 \rangle \lesssim \text{mon } b_4 \langle v_4, v_5 \rangle
6717
               4.1. v_2 \lesssim \text{mon}^2 fst (b_4) v_4 and v_3 \lesssim \text{mon}^2 snd (b_4) v_5
                   by inversion \lesssim
6720
               4.2. stat b_0 (dyn b_1 \langle v_2, v_3 \rangle) \rightarrow_N^* \langle v_6, v_7 \rangle
6721
                      and v_6 \lesssim add-trace (fst (b_2)fst (b_3), mon? fst (b_4) v_4)
6722
                       and v_7 \lesssim add-trace (snd (b_2)snd (b_3), mon<sup>?</sup> snd (b_4) v_5)
6723
                   by definition \rightarrow_{N} and lemma 8.28 and the induction hypothesis
6724
6725
               4.3. QED
6726
                   by definition \le \
6727
            5. CASE \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_4 \langle v_4, v_5 \rangle
6728
               5.1. v_2 \lesssim add-trace (fst (\overline{b}_4), v_4) and v_3 \lesssim add-trace (snd (\overline{b}_4), v_5)
6729
6730
                   by inversion \lesssim
               5.2. stat b_0 (dyn b_1 \langle v_2, v_3 \rangle) \rightarrow_N^* \langle v_6, v_7 \rangle
                      and v_6 \lesssim add-trace (fst (b_2)fst (b_3), add-trace (fst (\overline{b}_4), v_4))
6733
                      and v_7 \lesssim add-trace (snd (b_2)snd (b_3), add-trace (snd (\overline{b_4}), v_5))
6734
6735
                   by definition \rightarrow_{\mathsf{N}} and lemma 8.28 and the induction hypothesis
6736
               5.3. QED
6737
                   by definition ≤
6738
            6. CASE \langle v_2, v_3 \rangle \lesssim \operatorname{trace}_{\mathbf{v}} \overline{b}_4 \pmod{b_5} \langle v_4, v_5 \rangle
6740
               6.1. v_2 \lesssim add-trace (fst (\overline{b_4}), (mon? fst (b_5) v_4)) and v_3 \lesssim add-trace (snd (\overline{b_4}), (mon? snd (b_5) v_5))
6741
                   by inversion \lesssim
6742
               6.2. stat b_0 (dyn b_1 \langle v_2, v_3 \rangle) \rightarrow_N^* \langle v_6, v_7 \rangle
6743
                      and v_6 \leq add-trace (fst (b_2)fst (b_3), add-trace (fst (\overline{b_4}), (\text{mon}^2 \text{ fst } (b_5) v_4)))
                      and v_7 \lesssim add-trace (snd (b_2)snd (b_3), add-trace (snd (\overline{b_4}), (mon<sup>?</sup> snd (b_5) v_5)))
                   by definition \rightarrow_{\mathsf{N}} and lemma 8.28 and the induction hypothesis
               6.3. QED
6748
                   by definition \le \
6749
6750
            7. CASE \langle v_2, v_3 \rangle \lesssim \text{mon } b_4 \text{ (trace}_{\mathbf{v}} \overline{b}_5 \langle v_4, v_5 \rangle)
6751
               7.1. Contradiction:
6752
                    \cdot \vdash_{\mathsf{A}} v_1 : \mathcal{U}
6753
           8. CASE \langle v_2, v_3 \rangle \lesssim \text{mon } b_4 \text{ (mon } b_5 \langle v_4, v_5 \rangle)
6754
6755
               8.1. Contradiction:
6756
                   by lemma 7.10
6757
           9. CASE \langle v_2, v_3 \rangle \lesssim \text{mon } b_4 \text{ (trace}_{\mathbf{v}} \bar{b}_5 \text{ (mon } b_6 \langle v_4, v_5 \rangle))
6758
               9.1. Contradiction:
```

```
6761
                     by lemma 7.10
6762
             10. CASE \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \overline{b}_4 \pmod{b_5 \pmod{b_6 \langle v_4, v_5 \rangle}}
6763
6764
             11. CASE \langle v_2, v_3 \rangle \lesssim \text{mon}^+ \overline{b}_4 \, (\text{mon } b_5 \, (\text{trace}_{\mathbf{v}} \, b_6 \, (\text{mon } b_7 \, \langle v_4, v_5 \rangle)))
6765
6766
                 11.1. Contradiction:
6767
                     by lemma 7.10
6768
             12. Case \lambda x_2. e_2 \lesssim \lambda x_2. e_3
6769
                 12.1. QED
6770
                     \mathsf{stat}\ b_0\ (\mathsf{dyn}\ b_1\ v_0) \to_{\mathsf{N}}^* \ \mathsf{mon}\ b_0\ (\mathsf{mon}\ b_1\ v_0) \lesssim \mathsf{trace}_{\mathsf{v}}\ b_2b_3\ v_1
6772
             13. Case \lambda(x_2:\tau_2). e_2 \lesssim \lambda(x_2:\tau_2). e_3
6773
                 13.1. Contradiction:
6774
                      \cdot \vdash_{\mathsf{A}} v_1 : \mathcal{U}
6775
             14. CASE mon b_4 (mon b_5 v_3) \lesssim trace, b_6b_7 v_4
6776
6777
                              and v_4 \in \lambda x. e \cup \text{mon } b (\lambda(x:\tau). e)
6778
6779
                     \mathsf{stat}\ b_0\ (\mathsf{dyn}\ b_1\ v_0) \to_{\mathsf{N}}^* \ \mathsf{mon}\ b_0\ (\mathsf{mon}\ b_1\ v_0) \lesssim \mathsf{trace}_{\mathsf{v}}\ b_2b_3b_6b_7\ v_4
6780
             15. CASE mon b_4 (mon b_5 v_3) \lesssim trace, b_6b_7\overline{b}_8v_4
6781
6782
                              and v_4 \in \lambda x. e \cup \text{mon } b (\lambda(x:\tau). e)
6783
                 15.1. QED
6784
                     \mathsf{stat}\ b_0\ (\mathsf{dyn}\ b_1\ v_0) \to^*_{\mathsf{N}} \mathsf{mon}\ b_0\ (\mathsf{mon}\ b_1\ v_0) \lesssim \mathsf{trace}_{\mathsf{v}}\ b_2b_3b_6b_7\overline{b}_8\ v_4
6785
6786
             16. CASE mon b_4 v_3 \lesssim \text{mon } b_5 v_4
6787
                 16.1. v_4 \in \lambda(x:\tau). e
6788
                     by inversion \vdash_A and \lesssim and lemma 7.10
6789
                 16.2. stat b_0 (dyn b_1 v_0) \rightarrow_N^* mon b_0 (mon b_1 v_0)
6790
                     by definition \rightarrow_N
6792
                 16.3. QED
6793
                     by definition ≤
6794
6795
                                                                                                                                                                                                                            6796
                 Lemma 8.28. stat b_0 (dyn b_1 v_0, dyn b_2 v_1) \rightarrow_N^* (v_2, v_3) if and only if
6798
             \langle \mathsf{stat}\;\mathsf{fst}\,(b_0)\;(\mathsf{dyn}\;b_1\;v_0),\mathsf{stat}\;\mathsf{snd}\,(b_0)\;(\mathsf{dyn}\;b_2\;v_1)\rangle \,\to_{\mathsf{N}}^*\,\langle v_2,v_3\rangle
6799
6800
                 PROOF. By definition of \triangleright_{N} and \blacktriangleright_{N}.
6801
                                                                                                                                                                                                                            6802
6803
                 \text{Lemma 8.29. If } \textit{binop}\{\tau?\} \ v_0 \ v_1 \lesssim \textit{binop}\{\tau?\} \ v_2 \ v_3 \ \textit{then binop}\{\tau?\} \ v_0 \ v_1 \rightarrow_{\mathsf{N}} e_4 \ \textit{if and only if } \textit{binop}\{\tau?\} \ v_2 \ v_3 \rightarrow_{\mathsf{A}} e_5 = 0
6804
6805
                  Proof. The binary operations are only defined for integers and \lesssim relates integers iff they are equal.
6806
6807
             1. Case binop\{\tau?\} v_0 v_1 \blacktriangleright_N \mathsf{TagErr} \bullet
6808
                 1.1. SCASE v_0 \notin i
6809
                     1.1.1. v_2 \notin i
6810
                         by inversion \lesssim
6811
6812
             2019-10-03 17:26. Page 131 of 1-148.
```

```
1.1.2. QED
6813
6814
                       binop\{\tau?\} svalue_2 v_3 \triangleright_A TagErr \bullet
6815
               1.2. SCASE v_1 \notin i
6816
                   1.2.1. v_3 ∉ i
6817
6818
                      by inversion ≤
6819
                   1.2.2. QED
6820
                       binop\{\tau?\} v_2 v_3 \blacktriangleright_A \mathsf{TagErr} \bullet
6821
           2. CASE binop\{\tau?\} v_2 v_3 \triangleright_A TagErr \bullet
6822
               2.1. SCASE rem-trace (v_2) \notin i
6824
                  2.1.1. v_0 \notin i
6825
                      by inversion \le \
6826
                  2.1.2. QED
6827
6828
                       binop\{\tau?\} svalue_0 v_1 \triangleright_{N} TagErr \bullet
6829
               2.2. SCASE rem-trace (v_3) \notin i
6830
                  2.2.1. v_1 \notin i
6831
                      by inversion \lesssim
6832
                  2.2.2. QED
6833
6834
                       binop\{\tau?\} v_0 v_1 \blacktriangleright_{\mathsf{N}} \mathsf{TagErr} \bullet
6835
           3. CASE binop = sum and v_0 = i_0 and v_1 = i_1
6836
               3.1. binop\{\tau?\}\ v_0\ v_1 \rightarrow_{\mathsf{N}} v_0 + v_1
                  by definition \triangleright_{\!\!\mathsf{N}}, \blacktriangleright_{\!\!\mathsf{N}}, and \delta_N
6838
6839
               3.2. rem-trace (v_2) = v_0 and rem-trace (v_3) = v_1
6840
                  by inversion \le \( \)
6841
               3.3. QED
6842
6843
                   binop\{\tau?\}\ v_2\ v_3\ \rightarrow_{\mathsf{A}}\ v_0+v_1
6844
           4. CASE binop = sum and rem-trace (v_2) = i_0 and rem-trace (v_3) = i_1
6845
               4.1. binop\{\tau?\} v_2 v_3 \rightarrow_A i_0 + i_1
6846
                  by definition \triangleright_{A}, \blacktriangleright_{A}, and \delta_{A}
6847
               4.2. v_0 = i_0 and v_1 = i_1
                  by inversion \le \
               4.3. QED
6851
                   binop\{\tau?\}\ v_0\ v_1 \longrightarrow_{\mathsf{N}} v_2 + v_3
6852
           5. CASE binop = quotient and v_0 = i_0 and v_1 = i_1 and i_1 = 0
6853
6854
               5.1. binop\{\tau?\}\ v_0\ v_1 \rightarrow_{\mathsf{N}} \mathsf{TagErr} \bullet
6855
                  by definition \triangleright_{\mathsf{N}}, \blacktriangleright_{\mathsf{N}}, and \delta_N
6856
               5.2. rem-trace(v_2) = i_0 and rem-trace(v_3) = 0
6857
                  by inversion \le \
6858
6859
               5.3. QED
6860
                   binop\{\tau?\} v_2 v_3 \rightarrow_A \mathsf{TagErr} \bullet
6861
           6. CASE binop = quotient and rem-trace (v_2) = i_2 and rem-trace (v_3) = i_3 and i_3 = 0
6862
               6.1. binop\{\tau?\}\ v_2\ v_3 \rightarrow_{\mathsf{A}} \mathsf{TagErr} \bullet
6864
```

```
by definition \triangleright_A, \blacktriangleright_A, and \delta_A
6865
6866
               6.2. v_0 = i_2 and v_1 = 0
6867
                  by inversion \le \
6868
              6.3. QED
6869
6870
                   binop\{\tau?\} v_0 v_1 \rightarrow_{\mathsf{N}} \mathsf{TagErr} \bullet
6871
           7. CASE binop = quotient and v_0 = i_0 and v_1 = i_1 and i_1 \neq 0
6872
               7.1. binop\{\tau?\}\ v_0\ v_1 \rightarrow_{\mathsf{N}} \lfloor i_0/i_1 \rfloor
6873
                  by definition \triangleright_{\mathsf{N}}, \blacktriangleright_{\mathsf{N}}, and \delta_N
6874
               7.2. rem-trace(v_2) = i_0 and rem-trace(v_3) = i_1
6876
                  by inversion \lesssim
6877
              7.3. QED
6878
                   binop\{\tau?\} v_2 v_3 \rightarrow_{\mathsf{A}} \lfloor i_0/i_1 \rfloor
6879
           8. CASE binop = quotient and rem-trace (v_2) = i_2 and rem-trace (v_3) = i_3 and i_3 \neq 0
6880
6881
               8.1. binop\{\tau?\}\ v_2\ v_3 \rightarrow_A \lfloor i_2/i_3 \rfloor
6882
                  by definition \triangleright_A, \blacktriangleright_A, and \delta_A
6883
               8.2. v_0 = i_0 and v_1 = i_1
6884
                  by inversion \lesssim
6885
6886
               8.3. QED
                   binop\{\tau?\}\ v_0\ v_1 \rightarrow_{\mathsf{N}} \lfloor i_0/i_1 \rfloor
6890
               Lemma 8.30. If e_0 \lesssim e_1 and v_0 \lesssim v_1 then e_0[x_0 \leftarrow v_0] \lesssim e_1[x_0 \leftarrow v_1]
6891
6892
               PROOF. By induction on the structure of both expressions (or rather, the pair \langle e_0, e_1 \rangle) via case analysis of e_0 \lesssim e_1.
6893
6894
6896
               Lemma 8.31. If e_0 \lesssim e_1 and E_0 \lesssim E_1 then E_0[e_0] \lesssim E_1[e_1]
6897
6898
               PROOF. By induction on the structure of E_0.
6899
```

9 A/T SIMULATION

This simulation uses the Transient notion of reduction from the paper and a modified Amnesic notion of reduction that inserts check expressions that are guaranteed (by type soundness) to be no-ops.

```
e \sim e; \mathcal{H}; \mathcal{B}
6969
6970
6971
                                           v_0 \sim v_1; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                     v_0 \sim \mathcal{H}_0(\mathsf{p}_0); \mathcal{H}_0; \mathcal{B}_0
                                                                                                       \frac{v_0 \sim \mathcal{H}_0(\mathsf{p}_0); \mathcal{H}_0; \mathcal{B}_0}{v_0 \sim \mathsf{p}_0; \mathcal{H}_0; \mathcal{B}_0} \qquad \frac{}{i_0 \sim i_0; \mathcal{H}_0; \mathcal{B}_0} \qquad \frac{}{\mathsf{trace}_{\mathsf{v}} \, \bar{b}_0 \, i_0 \sim i_0; \mathcal{H}_0; \mathcal{B}_0}
6972
                                trace \overline{b}_0 v_0 \sim v_1; \mathcal{H}_0; \mathcal{B}_0
6973
6974
6975
                                        v_0 \sim v_2; \mathcal{H}_0; \mathcal{B}_0 \qquad v_1 \sim v_3; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                                                                          v_0 \sim v_2; \mathcal{H}_0; \mathcal{B}_0 \qquad v_1 \sim v_3; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                              \frac{}{\mathsf{trace}_{\mathsf{v}}^{?} \bar{b_0} \left(\mathsf{mon} \ b_0 \left(\mathsf{trace}_{\mathsf{v}}^{?} \bar{b_1} \left\langle v_0, v_1 \right\rangle \right)\right) \sim \left\langle v_2, v_3 \right\rangle; \mathcal{H}_0; \mathcal{B}_0}
6976
                                         \operatorname{trace}_{v}^{?} \overline{b_0} \langle v_0, v_1 \rangle \sim \langle v_2, v_3 \rangle; \mathcal{H}_0; \mathcal{B}_0
6977
6978
                                                                  v_0 \sim v_2; \mathcal{H}_0; \mathcal{B}_0 \qquad v_1 \sim v_3; \mathcal{H}_0; \mathcal{B}_0
                                          \frac{v_0 \sim v_2; \mathcal{H}_0; \mathcal{B}_0}{\text{mon } b_0 \left( \text{trace}_{\mathbf{v}}^? \overline{b_0} \left( \text{mon } b_1 \left\langle v_0, v_1 \right\rangle \right) \right) \sim \left\langle v_2, v_3 \right\rangle; \mathcal{H}_0; \mathcal{B}_0}{\text{trace}_{\mathbf{v}}^? \overline{b_0} \left( \lambda x_0, e_0 \right) \sim \lambda x_0, e_1; \mathcal{H}_0; \mathcal{B}_0}
6980
6981
6982
                                           \frac{e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0}{\text{mon } b_0 \left( \text{trace}_{V}^? \overline{b_0} \left( \lambda x_0. \, e_0 \right) \right) \sim \lambda x_0. \, e_1; \mathcal{H}_0; \mathcal{B}_0}{\text{trace}_{V}^? \overline{b_0} \left( \lambda (x_0 \colon \tau_0). \, e_0 \right) \sim \lambda (x_0 \colon \tau_0). \, e_1; \mathcal{H}_0; \mathcal{B}_0}
                                                                                 e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                                                                                                                 e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0
6983
6984
6985
6986
                                                                                                                                                           e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0
6987
                                                                                                        \overline{\operatorname{trace}_{\lambda}^{?} \overline{b_0} (\operatorname{mon} b_0 (\lambda(x_0 : \tau_0), e_0))} \sim \lambda(x_0 : \tau_0), e_1 : \mathcal{H}_0 : \mathcal{B}_0
6988
6989
6990
                                                                                                                       e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0
                                                     mon b_0 (trace \sqrt[p]{b_0} (mon b_1 (\lambda(x_0:\tau_0).e_0))) \sim \lambda(x_0:\tau_0).e_1; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                                                                                                                         x_0 \sim x_0; \mathcal{H}_0; \mathcal{B}_0
                                                             e_0 \sim e_2; \mathcal{H}_0; \mathcal{B}_0 e_1 \sim e_3; \mathcal{H}_0; \mathcal{B}_0
6994
                                                                                                                                                                                               e_0 \sim e_2; \mathcal{H}_0; \mathcal{B}_0 \qquad e_1 \sim e_3; \mathcal{H}_0; \mathcal{B}_0
6995
                                                                                                                                                                                               app\{\tau?\} e_0 e_1 \sim app\{\tau?\} e_2 e_3; \mathcal{H}_0; \mathcal{B}_0
                                                                           \langle e_0, e_1 \rangle \sim \langle e_2, e_3 \rangle; \mathcal{H}_0; \mathcal{B}_0
6996
6997
                                              e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                  e_0 \sim e_2; \mathcal{H}_0; \mathcal{B}_0 \qquad e_1 \sim e_3; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                                                                                                                                                                   e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0
6998
6999
                     unop\{\tau?\} e_0 \sim unop\{\tau?\} e_1; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                         binop\{\tau?\} e_0 e_1 \sim binop\{\tau?\} e_2 e_3; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                                                                                                                                                \operatorname{dyn} b_0 e_0 \sim \operatorname{dyn} b_0 e_1; \mathcal{H}_0; \mathcal{B}_0
7000
7001
                                                                              e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                                                                                                      e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0
7002
7003
                                                             stat b_0 e_0 \sim \text{stat } b_0 e_1; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                                                                 \operatorname{dyn}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) e_0 \sim \operatorname{check} \tau_0 e_1 p_0; \mathcal{H}_0; \mathcal{B}_0
7004
7005
                                                               e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                                                                                                 \tau_1 \leqslant : \tau_0 \qquad e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0
7006
7007
                         \operatorname{stat}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) e_0 \sim \operatorname{check} \mathcal{U} e_1 p_0; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                                                  dyn (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (stat (\ell_2 \blacktriangleleft \tau_1 \blacktriangleleft \ell_3) e_0) \sim check \tau_0 e_1 p_0; \mathcal{H}_0; \mathcal{B}_0
7008
7009
                                                       e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0
7010
                          check \tau? e_0 \bullet \sim \text{check } \tau? e_1 p_0; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                                \mathsf{TagErr} \circ \sim \mathsf{TagErr} \circ; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                                                                                                                               TagErr • ~ TagErr •; \mathcal{H}_0; \mathcal{B}_0
7011
7012
```

 $v_0 \sim v_1; \mathcal{H}_0; \mathcal{B}_0$

BndryErr $(b_0, v_0) \sim \text{BndryErr}(b_0, v_1); \mathcal{H}_0; \mathcal{B}_0$

 $DivErr \sim DivErr; \mathcal{H}_0; \mathcal{B}_0$

7013

7014

$E \sim E; \mathcal{H}; \mathcal{B}$

```
COROLLARY 9.1. eval<sub>A</sub>(\uparrow s_0) \in Err if and only if eval<sub>T</sub>(\uparrow s_0) \in Err
7074
             PROOF. By lemma 9.2
7075
7076
7077
7078
             Lemma 9.2. If eval_A(\uparrow s_0) = r_0 and eval_T(\uparrow s_0) = r_1; \mathcal{H}_0; \mathcal{B}_0 then one of the following holds:
7079
               • r_0 = r_1 = \Omega
7080
               • r_0 \neq \Omega and r_1 \neq \Omega and r_0 \sim r_1; \mathcal{H}_0; \mathcal{B}_0
7081
7082
             PROOF. By lemma 9.3 and lemma 9.4.
7084
7085
7086
             Lemma 9.3. \uparrow s_0 \sim \uparrow s_0; \emptyset; \emptyset for all \uparrow s_0
7087
             PROOF. By induction on the structure of s_0.
7088
7089
         1. CASE s_0 = x_0
7090
             1.1. QED
7091
                x_0 \sim x_0; \mathcal{H}_0; \mathcal{B}_0
7092
7093
         2. Case s_0 = i_0
7094
             2.1. QED
7095
                i_0 \sim i_0; \mathcal{H}_0; \mathcal{B}_0
         3. Case s_0 = \lambda x_0 . s_0
7097
7098
            3.1. QED
7099
                by the induction hypothesis
and the definition of \sim
7100
         4. CASE s_0 = \lambda(x_0 : \tau_0). s_1
7101
7102
                by the induction hypothesis
and the definition of \sim
7103
7104
         5. Case s_0 = \langle s_1, s_2 \rangle
7105
             5.1. QED
7106
                by the induction hypothesis
7107
7108
         6. CASE s_0 = app\{\tau_0\} s_1 s_2
7109
            6.1. QED
7110
                by the induction hypothesis
7111
         7. CASE s_0 = unop\{\tau?\} s_1
7112
            7.1. QED
7113
7114
                by the induction hypothesis
7115
         8. CASE s_0 = binop\{\tau?\} s_1 s_2
7116
            8.1. QED
7117
7118
                by the induction hypothesis
7119
         9. CASE s_0 = \text{dyn } \tau_0 \ s_1
7120
            9.1. QED
7121
                by the induction hypothesis
7122
7123
         10. CASE s_0 = \text{stat } \tau_0 \ s_1
7124
         2019-10-03 17:26. Page 137 of 1-148.
```

```
7125
              10.1. QED
7126
                 by the induction hypothesis
7127
7128
                                                                                                                                                                                   7129
              Lemma 9.4. If e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0 then:
7130
7131
                \bullet \ \ \textit{if} \ \ e_0 \rightarrow_A e_2 \ \textit{then} \ e_2 \rightarrow_A^* e_3 \ \textit{and} \ e_1; \\ \mathcal{H}_0; \\ \mathcal{B}_0 \rightarrow_T^* e_4; \\ \mathcal{H}_1; \\ \mathcal{B}_1 \ \textit{and} \ e_3 \sim e_4; \\ \mathcal{H}_1; \\ \mathcal{B}_1
7132
                • if e_1; \mathcal{H}_0; \mathcal{B}_0 \to_T e_3; \mathcal{H}_1; \mathcal{B}_1 then e_0 \to_A^* e_2 and e_2 \sim e_3; \mathcal{H}_1; \mathcal{B}_1
7133
7134
              PROOF. By lemma 9.5 and lemma 9.6 and lemma 9.7 and lemma 9.8 and lemma 9.9.
7135
7136
                                                                                                                                                                                   7137
              LEMMA 9.5. If E_0[e_0] \sim e_1; \mathcal{H}_0; \mathcal{B}_0 then e_1 = E_1[e_2] and E_0 \sim E_1; \mathcal{H}_0; \mathcal{B}_0 and e_0 \sim e_2; \mathcal{H}_0; \mathcal{B}_0
7138
7139
              PROOF. By induction on the structure of E_0.
7140
7141
          1. CASE E_0 = []
7142
              1.1. QED
7143
                 E_1 = []
7144
          2. Case E_0 = \langle E_2, e_2 \rangle
7145
7146
7147
                 by the induction hypothesis
7148
          3. Case E_0 = \langle v_0, E_2 \rangle
7149
              3.1. QED
7150
7151
                 by the induction hypothesis
7152
          4. CASE E_0 = app\{\tau?\} E_2 e_2
7153
7154
                 by the induction hypothesis
7155
7156
          5. CASE E_0 = app\{\tau?\} v_0 E_2
7157
              5.1. QED
7158
                 by the induction hypothesis
7159
          6. CASE E_0 = unop\{\tau?\} E_2
7160
7161
             6.1. QED
7162
                 by the induction hypothesis
7163
          7. CASE E_0 = binop\{\tau^2\} E_2 e_2
7164
7165
7166
                 by the induction hypothesis
7167
          8. Case E_0 = binop\{\tau?\} E_2 e_2
7168
              8.1. QED
7169
                 by the induction hypothesis
7170
7171
          9. CASE E_0 = \text{dyn } b_0 E_2 \text{ and } E_2 \neq \text{check } \tau ? E_3 \bullet
7172
              9.1. Scase E_1 = \text{dyn } b_0 E_3
7173
                 9.1.1. QED
7174
                    by the induction hypothesis
```

```
9.2. SCASE E_1 = \text{check } \tau_0 E_3 p_0
7177
7178
               9.2.1. QED
7179
                  by the induction hypothesis
7180
         10. CASE E_0 = \text{dyn } b_0 \text{ (stat } b_1 E_2)
7181
7182
               10.0.1. QED
7183
                  by the induction hypothesis
7184
         11. CASE E_0 = \text{stat } b_0 E_2
7185
            11.1. SCASE E_1 = \text{stat } b_0 E_3
7186
7187
               11.1.1. QED
7188
                  by the induction hypothesis
7189
            11.2. scase E_1 = \operatorname{check} \mathcal{U} E_3 p_0
7190
               11.2.1. QED
7191
                  by the induction hypothesis
7192
7193
         12. CASE E_0 = \operatorname{check} \tau ? E_2 \bullet
7194
            12.1. QED
7195
               by the induction hypothesis
7196
7197
7198
            Lemma 9.6. If e_0 \sim E_1[e_1]; \mathcal{H}_0; \mathcal{B}_0 then e_0 = E_0[e_2] and E_0 \sim E_1; \mathcal{H}_0; \mathcal{B}_0 and e_2 \sim e_1; \mathcal{H}_0; \mathcal{B}_0
7199
            PROOF. By induction on the structure of E_1 and E_0; the latter is because E_0 may be a suffix context (trace \bar{b} E).
7201
         1. CASE E_1 = []
7202
7203
            1.1. SCASE E_0 = []
7204
               1.1.1. QED
7205
            1.2. SCASE E_0 = \operatorname{trace} \overline{b_0} E_2
7206
               1.2.1. QED
7208
                  by the induction hypothesis
7209
         2. Case E_1 = \langle E_2, e_3 \rangle
7210
            2.1. QED
7211
7212
               by the induction hypothesis
7213
         3. Case E_1 = \langle v_0, E_2 \rangle
7214
            3.1. QED
7215
               by the induction hypothesis
7216
         4. Case E_1 = app\{\tau?\} E_2 e_3
7217
7218
            4.1. QED
7219
               by the induction hypothesis
7220
         5. Case E_1 = app\{\tau?\} v_0 E_2
7221
7222
            5.1. QED
7223
               by the induction hypothesis
7224
         6. CASE E_1 = unop\{\tau?\} E_2
7225
            6.1. QED
7226
7227
               by the induction hypothesis
7228
         2019-10-03 17:26. Page 139 of 1-148.
```

```
7. CASE E_1 = binop\{\tau?\} E_2 e_3
7229
7230
              7.1. QED
7231
                 by the induction hypothesis
7232
          8. Case E_1 = binop\{\tau?\} v_0 E_2
7233
7234
              8.1. QED
7235
                 by the induction hypothesis
7236
          9. CASE E_1 = \text{dyn } b_0 E_2
7237
              9.1. QED
7238
                 by the induction hypothesis
7240
          10. CASE E_1 = \text{stat } b_0 E_2
7241
              10.1. QED
7242
                 by the induction hypothesis
7243
          11. CASE E_1 = \operatorname{check} \tau_0 E_2 p_0
7244
7245
              11.1. scase E_0 = \text{dyn } b_0 E_3 \text{ and } E_3 \notin \text{stat } b E
7246
                 by the induction hypothesis
7247
              11.2. scase E_0 = \text{dyn } b_0 \text{ (stat } b_1 E_3)
7248
                 by the induction hypothesis
7249
7250
              11.3. scase E_0 = \operatorname{check} \tau_0 E_3 \bullet
7251
                 by the induction hypothesis
7252
          12. CASE E_1 = \operatorname{check} \mathcal{U} E_2 p_0
7253
7254
              12.1. SCASE E_0 = \text{stat } b_0 E_3
                 by the induction hypothesis
7256
              12.2. SCASE E_0 = \operatorname{check} \mathcal{U} E_3 \bullet
7257
                 by the induction hypothesis
7258
7259
                                                                                                                                                                                      7260
7261
              LEMMA 9.7. If E_0 \sim E_1; \mathcal{H}_0; \mathcal{B}_0 and e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0 then E_0[e_0] \sim E_1[e_1]; \mathcal{H}_0; \mathcal{B}_0
7262
              PROOF. By case analysis of E_0 \sim E_1; \mathcal{H}_0; \mathcal{B}_0 and induction on the structure of E_0 and E_1.
7263
          1. CASE trace \overline{b}_0 E_2 \sim E_1; \mathcal{H}_0; \mathcal{B}_0
7264
7266
                 by the induction hypothesis
7267
          2. Case [] ~ []; \mathcal{H}_0; \mathcal{B}_0
7268
              2.1. QED
7269
7270
                 by e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0
7271
          3. CASE \langle E_2, e_2 \rangle \sim \langle E_3, e_3 \rangle; \mathcal{H}_0; \mathcal{B}_0
7272
              3.1. QED
7273
7274
                 by the induction hypothesis
7275
          4. CASE \langle v_0, E_2 \rangle \sim \langle v_1, E_3 \rangle; \mathcal{H}_0; \mathcal{B}_0
7276
7277
                 by the induction hypothesis
7278
7279
          5. Case app\{\tau?\} E_2 e_2 \sim \text{app}\{\tau?\} E_3 e_3; \mathcal{H}_0; \mathcal{B}_0
```

```
7281
                                  5.1. QED
7282
                                          by the induction hypothesis
7283
                         6. CASE app\{\tau?\} v_0 E_2 \sim \text{app}\{\tau?\} v_1 E_3; \mathcal{H}_0; \mathcal{B}_0
7284
                                  6.1. QED
7285
7286
                                          by the induction hypothesis
7287
                         7. CASE unop\{\tau?\} E_2 \sim unop\{\tau?\} E_3; \mathcal{H}_0; \mathcal{B}_0
7288
7289
                                          by the induction hypothesis
                         8. CASE binop\{\tau?\} E_2 e_2 \sim binop\{\tau?\} E_3 e_3; \mathcal{H}_0; \mathcal{B}_0
7291
7292
7293
                                          by the induction hypothesis
7294
                         9. Case binop\{\tau?\} v_0 E_2 \sim binop\{\tau?\} v_1 E_3; \mathcal{H}_0; \mathcal{B}_0
7295
7296
7297
                                          by the induction hypothesis
7298
                         10. CASE dyn b_0 E_2 \sim \text{dyn } b_0 E_3; \mathcal{H}_0; \mathcal{B}_0
7299
                                  10.1. QED
7300
7301
                                          by the induction hypothesis
7302
                          11. CASE stat b_0 E_2 \sim \text{stat } b_0 E_3; \mathcal{H}_0; \mathcal{B}_0
7303
                                  11.1. OED
7304
                                          by the induction hypothesis
7305
7306
                          12. CASE dyn b_0 E_2 \sim \text{check } \tau_0 E_3 p_0; \mathcal{H}_0; \mathcal{B}_0
7307
                                  12.1. QED
7308
                                          by the induction hypothesis
7309
                          13. CASE stat b_0 E_2 \sim \operatorname{check} \mathcal{U} E_3 p_0; \mathcal{H}_0; \mathcal{B}_0
7310
7311
                                  13.1. QED
7312
                                          by the induction hypothesis
7313
                          14. CASE dyn b_0 (stat b_1 E_2) ~ check \tau_0 E_3 p_0; \mathcal{H}_0; \mathcal{B}_0
7314
                                  14.1. QED
7315
7316
                                          by the induction hypothesis
7317
                         15. CASE check \tau? E_2 \bullet \sim \operatorname{check} \tau? E_3 p_0; \mathcal{H}_0; \mathcal{B}_0
7318
                                  15.1. QED
7319
                                          by the induction hypothesis
7320
7321
7322
7323
                                  \text{Lemma 9.8. If } e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0 \text{ and } e_0 \ (\rhd_{\!\!\!A} \cup \blacktriangleright_{\!\!\!A}) \ e_2 \text{ then } e_2 \xrightarrow{*}_A^* e_3 \text{ and } e_1; \mathcal{H}_0; \mathcal{B}_0 \xrightarrow{*}_T^* e_4; \mathcal{H}_1; \mathcal{B}_1 \text{ and } e_3 \sim e_4; \mathcal{H}_1; \mathcal{B}_1 \text{ and } e_3 \leftarrow e_4; \mathcal{H}_1; \mathcal{B}_2 \text{ and } e_3 \leftarrow e_4; \mathcal{H}_1; \mathcal{H}_2; \mathcal{H}_1; \mathcal{H}_2; \mathcal{H}_1; \mathcal{H}_2; \mathcal{H}_1; \mathcal{H}_2; \mathcal{H}_1; \mathcal{H}_2; \mathcal{H}_1; \mathcal{H}_2; \mathcal{H}_1; \mathcal{
7324
                                   PROOF. By case analysis of (\triangleright_A \cup \blacktriangleright_A) and inversion on the \sim relation. In short, the shape of the Amnesic expression
7325
7326
                          e_0 determines (and matches) the shape of the Transient expression.
7327
                          Expressions on the Transient side may be pre-values. This proof assumes that all pre-values have already been allocated
7328
                          to the heap by stutter steps (lemma 9.10).
7329
                          1. Case unop\{\tau?\}\langle v_0, v_1\rangle \rhd_A \delta(unop, \langle v_0, v_1\rangle)
7330
7331
                                  1.1. QED
7332
                         2019-10-03 17:26. Page 141 of 1-148.
```

```
7333
                               by lemma 9.14
7334
                  2. Case binop\{\tau?\} v_0 v_1 \triangleright_{\Lambda} \delta(binop, v_0, v_1)
7335
                         2.1. QED
7336
                               by lemma 9.15
7337
7338
                  3. Case \operatorname{fst}\{\tau_0\} (\operatorname{mon} (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) \ v_0) \rhd_{\!\!\!\!A} \operatorname{dyn} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (\operatorname{fst}\{\mathcal{U}\} \ v_0)
7339
                         3.1. CASE v_0 = \langle v_1, v_2 \rangle
7340
                               3.1.1. \, \operatorname{dyn} \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) \left(\operatorname{fst}\{\mathcal{U}\} \, v_0\right) \to_{\operatorname{A}} \, \operatorname{dyn} \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) \, \delta(\operatorname{fst}\{\mathcal{U}\}, v_0)
7341
                               3.1.2. e_1 = unop\{\tau?\} v_2 and e_1; \mathcal{H}_0; \mathcal{B}_0 \rightarrow_{\tau}^* check \tau_0 \delta(fst\{\tau_0\}, v_2) v_2; \mathcal{H}_0; \mathcal{B}_0
7342
                              3.1.3. QED
7344
                                     by definition ~
7345
                         3.2. CASE v_0 = \text{mon} (\ell_2 \blacktriangleleft \tau_2 \blacktriangleleft \ell_3) \langle v_1, v_2 \rangle
7346
                               3.2.1. \operatorname{dyn}\left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) \left(\operatorname{fst}\{\mathcal{U}\}\ v_0\right) \to_{\operatorname{A}} \operatorname{dyn}\left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) \left(\operatorname{stat}\left(\ell_2 \blacktriangleleft \operatorname{fst}(\tau_2) \blacktriangleleft \ell_3\right) \delta(\operatorname{fst}\{\operatorname{fst}(\tau_2)v_0\})\right)
7347
                               3.2.2. e_1 = unop\{\tau?\}\ v_2 and e_1; \mathcal{H}_0; \mathcal{B}_0 \rightarrow_{\mathsf{T}}^* \operatorname{check} \tau_0\ \delta(\operatorname{fst}\{\tau_0\}, v_2)\ v_2; \mathcal{H}_0; \mathcal{B}_0
7348
7349
                              3.2.3. QED
7350
                                     by definition ~
7351
                  4. Case \operatorname{snd}\{\tau_0\} (\operatorname{mon} b_0 \ v_0) \rhd_{\mathsf{A}} \ldots
7352
7353
                         4.1. QED
7354
                                similar to fst case
7355
                  5. Case app\{\tau_0\} (\lambda(x_0:\tau_0).e_2) v_1 \triangleright_A check \tau_0 e_2[x_0 \leftarrow v_0] \bullet
7356
                         5.1. QED
7357
7358
                               by lemma 9.17
7359
                   6. \text{ CASE app}\{\tau_0\} \left( \mathsf{mon} \left( \ell_0 \blacktriangleleft (\tau_1 \Rightarrow \tau_2) \blacktriangleleft \ell_1 \right) v_0 \right) v_1 \rhd_{\mathsf{A}} \mathsf{dyn} \left( \ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1 \right) \left( \mathsf{app}\{\mathcal{U}\} \, v_0 \, \left( \mathsf{stat} \left( \ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0 \right) \, v_1 \right) \right) \right) \left( \mathsf{app}\{\tau_0\} \, \mathsf{mon} \left( \ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1 \right) \, \mathsf{not} \right) = 0
7360
                         6.1. \ \operatorname{dyn} \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) \left(\operatorname{app}\{\mathcal{U}\} \ v_0 \ (\operatorname{stat} \left(\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0\right) \ v_1\right)\right) \to_{\operatorname{A}} \ \operatorname{dyn} \left(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1\right) \left(\operatorname{app}\{\mathcal{U}\} \ v_0 \ v_2\right)
7361
7362
7363
                               by lemma 9.12/lemma 9.13 for stat and the definition of \sim for the whole
7364
                  7. Case \operatorname{dyn}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_0 \rhd_{\!\!\!A} \ \operatorname{mon}(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_0
7365
7366
                               by lemma 9.16 and lemma 9.13
7367
                  8. CASE dyn (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) (trace \bar{b}_0 i_0) \triangleright_A i_0
7368
                               by lemma 9.16
7371
                  9. CASE dyn (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_0 \rhd_A \operatorname{BndryErr}(\overline{b}_0, v_0)
7372
7373
7374
                               by lemma 9.16
7375
                   10. Case check \tau_0 \ v_0 \bullet \rhd_{\!\! A} \ v_0
7376
                         10.1. QED
7377
7378
                               by inversion ~
7379
                   11. case check \tau_0 v_0 \bullet \rhd_A \mathsf{BndryErr}(\bar{b}_0, v_0)
7380
                         11.1. Contradiction:
7381
                               by Theorem 7.2
7382
                   12. CASE trace \bar{b}_0 v_0 \rhd_{\mathsf{A}} add-trace (\bar{b}_0, v_0)
7383
```

```
7385
                    12.1. QED
7386
                         by lemma 9.12
7387
               13. CASE unop\{\tau?\} v_0 \blacktriangleright_A TagErr \bullet
7388
                    13.1. QED
7389
7390
                         by lemma 9.14
7391
               14. CASE unop\{\tau?\} v_0 \blacktriangleright_{\Delta} \operatorname{check} \mathcal{U} \delta(unop, v_0) \bullet
7392
                    14.1. QED
7393
                         by lemma 9.14
7394
               15. Case binop\{\tau?\} v_0 v_1 \blacktriangleright_A \mathsf{TagErr} \bullet
7395
7396
                    15.1. QED
7397
                         by lemma 9.15
7398
               16. CASE binop\{\tau?\} v_0 v_1 \blacktriangleright_A \delta(binop, v_0, v_1)
7399
7400
7401
                         by lemma 9.15
7402
               17. CASE \operatorname{fst}\{\mathcal{U}\} (\operatorname{trace}_{\mathbf{v}}^{?} \bar{b_0} (\operatorname{mon} (\ell_0 \blacktriangleleft (\tau_0 \times \tau_1) \blacktriangleleft \ell_1) v_0)) \blacktriangleright_{\mathbf{A}} \operatorname{trace} \bar{b_0} (\operatorname{stat} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \operatorname{fst}\{\tau_0\} v_0)
7403
                    17.1. trace \bar{b}_0 (stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) fst\{\tau_0\} v_0) \rightarrow_A trace \bar{b}_0 (stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \delta(fst\{fst(\tau_0)\}, v_0))
7404
                    17.2. e_1 = \operatorname{fst}\{\mathcal{U}\}\ v_1 \text{ and } e_1; \mathcal{H}_0; \mathcal{B}_0 \geqslant_{\mathsf{T}} \operatorname{check} \mathcal{U}\ \delta(\operatorname{fst}\{\mathcal{U}\}, v_1)\ v_1; \mathcal{H}_0; \mathcal{B}_0
7405
7406
                    17.3. QED
7407
                         by definition ~
7408
               18. CASE \operatorname{snd}\{\mathcal{U}\}\ldots\blacktriangleright_{\!\!\!\!A}\ldots
7409
7410
                    18.1. QED
7411
                          similar to previous case
7412
               19. CASE app\{\mathcal{U}\} (trace v \in \overline{b_0} (\lambda x_0. e_0)) v_0 \triangleright_A trace \overline{b_0} check \mathcal{U}(e_0[x_0 \leftarrow v_0]) \bullet
7413
                    19.1. QED
7414
7415
                         by lemma 9.17
7416
               20. CASE app\{\mathcal{U}\} (trace v_0 \bar{b}_0 (mon (\ell_0 \blacktriangleleft (\tau_1 \Rightarrow \tau_2) \blacktriangleleft \ell_1) v_0)) <math>v_1 \blacktriangleright_A
7417
                                   trace \overline{b}_0 (stat (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) (app\{\tau_2\} v_0 (dyn (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) v_1)))
7418
                    20.1. Case trace \overline{b}_0 (stat (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) (app\{\tau_2\} v_0 (dyn (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) v_1))) <math>\rightarrow_A
7419
                                            trace \bar{b}_0 (stat (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) (app\{\tau_2\} v_0 v_2))
7420
7421
                         20.1.1. QED
7422
                              by lemma 9.16
7423
                    20.2. CASE trace \bar{b}_0 (stat (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) (app\{\tau_2\} v_0 (dyn (\ell_1 \blacktriangleleft \tau_1 \blacktriangleleft \ell_0) v_1))) \rightarrow_{\Lambda}
7424
                                            trace \bar{b}_0 (stat (\ell_0 \blacktriangleleft \tau_2 \blacktriangleleft \ell_1) (app\{\tau_2\} v_0 BndryErr (\bar{b}_0, v_1)))
7425
7426
                         20.2.1. QED
7427
                              by lemma 9.16
7428
               21. Case stat b_0 \ v_0 \blacktriangleright_{\mathsf{A}} \mathsf{mon} \ b_0 \ v_0
7429
7430
                    21.1. QED
7431
                         by lemma 9.16 and lemma 9.13
7432
               22. CASE stat b_0 (mon b_1 (trace, \overline{b_0} v_0)) \blacktriangleright_{\mathsf{A}} trace (b_0b_1\overline{b_0}) v_0
7433
                    22.1. QED
7434
7435
                         by lemma 9.16
7436
               2019-10-03 17:26. Page 143 of 1-148.
```

```
23. CASE stat b_0 i_0 \triangleright_A i_0
7437
7438
                                             23.1. QED
7439
                                                         by lemma 9.16
7440
                                  24. CASE check \mathcal{U} v_0 p_0 \blacktriangleright_{\!\scriptscriptstyle A} v_0
7441
7442
                                             24.1. QED
7443
                                                        by inversion ~
7444
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     7445
                                             \text{Lemma 9.9. If } e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0 \text{ and } e_1; \mathcal{H}_0; \mathcal{B}_0 \Vdash_{\text{T}} e_3; \mathcal{H}_1; \mathcal{B}_1 \text{ then } e_0 \rightarrow_{\text{A}}^* e_2 \text{ and } e_2 \sim e_3; \mathcal{H}_1; \mathcal{B}_1 \mapsto_{\text{T}} e_3; \mathcal{H}_1; \mathcal{B}_1 \mapsto_{\text{T}} e_3; \mathcal{H}_1; \mathcal{B}_2 \mapsto_{\text{T}} e_3; \mathcal{H}_1; \mathcal{H}_
7448
                                             PROOF. By case analysis of \triangleright_{\mathsf{T}}.
7449
                                  Any Amnesic expression can have the form (trace \bar{b}v); the proof assumes these have been reduced by stutter steps
7450
7451
7452
                                  1. Case w_0; \mathcal{H}_0; \mathcal{B}_0 \triangleright_T p_0; p_0 \mapsto w_0, \mathcal{H}_0; p_0 \mapsto \emptyset, \mathcal{B}_0
7453
                                             1.1. QED
7454
                                                         by inversion ~ and lemma 9.18
7455
                                  2. CASE unop\{\tau?\} p_0; \mathcal{H}_0; \mathcal{B}_0 \bowtie_{\mathsf{T}} \operatorname{check} \tau? \delta(unop, v_0) p_0; \mathcal{H}_0; \mathcal{B}_0
7456
                                             2.1. SCASE e_0 \in unop\{\tau?\} \operatorname{trace}_{v}^{?} \overline{b} \langle v, v \rangle
7457
7458
                                                         2.1.1. QED
7459
                                                                    by lemma 9.14
                                             2.2. SCASE e_0 = unop\{\tau?\} \mod (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) (\operatorname{trace}_{\nu}^2 \overline{b_0} \langle v_2, v_3 \rangle)
7461
7462
                                                       2.2.1. \ \textit{e}_0 \rightarrow_{\mathsf{A}}^* \mathsf{dyn} \ (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ \delta(\textit{unop}, \mathsf{trace}_v^? \ \overline{b_0} \ \langle \upsilon_2, \upsilon_3 \rangle)
7463
7464
7465
                                             2.3. SCASE e_0 = unop\{\tau?\} \mod (\ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1) \left( \operatorname{trace}_{\mathbf{v}}^2 \overline{b_0} \left( \operatorname{mon} \left( \ell_2 \blacktriangleleft \tau_2 \times \tau_3 \blacktriangleleft \ell_3 \right) \langle v_2, v_3 \rangle \right) \right)
7466
7467
7468
                                                       2.3.1. e_0 \rightarrow_{\mathsf{A}}^* \mathsf{dyn} \ (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ (\mathsf{stat} \ (\ell_2 \blacktriangleleft \tau_1 \blacktriangleleft \ell_3) \ \delta(\mathit{unop}, \mathsf{trace}_v^? \ \overline{b_0} \ \langle v_2, v_3 \rangle))
7469
7470
                                             2.4. SCASE e_0 = unop\{\tau?\} \operatorname{trace}_{\mathsf{v}}^? \overline{b}_0 \left( \operatorname{mon} \left( \ell_0 \blacktriangleleft \tau_1 \blacktriangleleft \ell_1 \right) \langle \upsilon_2, \upsilon_3 \rangle \right)
7471
7472
7473
                                                       2.4.1. e_0 \rightarrow_{\mathsf{A}}^* \operatorname{stat} (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ \delta(\operatorname{unop}, \operatorname{trace}_{\mathsf{v}}^? \overline{b_0} \ \langle v_2, v_3 \rangle)
7474
7475
                                  3. Case unop\{\tau?\}\ v_0; \mathcal{H}_0; \mathcal{B}_0 \triangleright_T \mathsf{TagErr} \bullet; \mathcal{H}_0; \mathcal{B}_0
7476
7477
                                             3.1. QED
7478
                                                         by inversion ~
7479
                                  4. CASE binop\{\tau?\} i_0 i_1; \mathcal{H}_0; \mathcal{B}_0 \bowtie_{\mathsf{T}} \delta(binop, v_0, v_1); \mathcal{H}_0; \mathcal{B}_0
7480
                                             4.1. QED
7481
7482
                                                        by lemma 9.15
7483
                                  5. CASE binop\{\tau?\} i_0 i_1; \mathcal{H}_0; \mathcal{B}_0 \triangleright_T TagErr \bullet; \mathcal{H}_0; \mathcal{B}_0
7484
7485
                                                        by lemma 9.15
7486
                                  6. Case \operatorname{app}\{\tau?\}\operatorname{p}_0v_0;\mathcal{H}_0;\mathcal{B}_0 \bowtie_{\operatorname{T}} \operatorname{check}\tau?\operatorname{e}_2[x_0\leftarrow v_0]\operatorname{p}_0;\mathcal{H}_0;\mathcal{B}_0[v_0\cup\operatorname{rev}(\mathcal{B}_0(\operatorname{p}_0))]
7487
                                                                                                                                                                                                                                                                                                                                                                                                                                                                      2019-10-03 17:26. Page 144 of 1-148.
```

```
7489
                    6.1. QED
7490
                         by lemma 9.17
7491
               7. CASE app\{\tau?\} p<sub>0</sub> v_0; \mathcal{H}_0; \mathcal{B}_0 \bowtie_{\mathsf{T}} \mathsf{BndryErr}(\bar{b}_0, v_0); \mathcal{H}_0; \mathcal{B}_0
7492
                    7.1. QED
7493
7494
                         by lemma 9.16
7495
              8. CASE app\{\tau_0\} p<sub>0</sub> v_0; \mathcal{H}_0; \mathcal{B}_0 \bowtie_T \operatorname{check} \tau_0 e_2[x_0 \leftarrow v_0] p<sub>0</sub>; \mathcal{H}_0; \mathcal{B}_0[v_0 \cup \operatorname{rev}(\mathcal{B}_0(p_0))]
7496
7497
                         by lemma 9.17
7498
              9. Case app\{\mathcal{U}\} p<sub>0</sub> v_0; \mathcal{H}_0; \mathcal{B}_0 \bowtie_{\mathsf{T}} e_2[x_0 \leftarrow v_0]; \mathcal{H}_0; \mathcal{B}_0
7499
7500
7501
                         similar to previous case
7502
               10. CASE app\{\mathcal{U}\} v_0 v_1; \mathcal{H}_0; \mathcal{B}_0 \bowtie_T \mathsf{TagErr} \bullet; \mathcal{H}_0; \mathcal{B}_0
7503
7504
7505
                         by lemma 9.16
7506
               11. Case dyn(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) \ v_0; \mathcal{H}_0; \mathcal{B}_0 \Vdash_\mathsf{T} v_0; \mathcal{H}_0; \mathcal{B}_0[v_0 \cup \{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\}]
7507
7508
7509
                         by lemma 9.16
7510
               12. CASE dyn (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_0; \mathcal{H}_0; \mathcal{B}_0 \bowtie_{\mathsf{T}} \mathsf{BndryErr}(\bar{b}_0, v_0); \mathcal{H}_0; \mathcal{B}_0
7511
7512
                         by lemma 9.16
7513
7514
               13. CASE stat (\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1) v_0; \mathcal{H}_0; \mathcal{B}_0 \bowtie_{\mathsf{T}} v_0; \mathcal{H}_0; \mathcal{B}_0[v_0 \cup \{(\ell_0 \blacktriangleleft \tau_0 \blacktriangleleft \ell_1)\}]
7515
7516
                         by inversion ~ and lemma 9.12 and lemma 9.13
7517
               14. CASE check \mathcal{U} v_0 p_0; \mathcal{H}_0; \mathcal{B}_0 \triangleright_T v_0; \mathcal{H}_0; \mathcal{B}_0
7518
7519
                    14.1. QED
7520
                         by inversion ~
7521
               15. CASE check \tau_0 \ v_0 \ \mathsf{p}_0; \mathcal{H}_0; \mathcal{B}_0 \ \triangleright_\mathsf{T} \ v_0; \mathcal{H}_0; \mathcal{B}_0[v_0 \cup \mathcal{B}_0(\mathsf{p}_0)]
7522
                    15.1. QED
7523
7524
                         by lemma 9.16
7525
               16. CASE check \tau_0 v_0 p_0; \mathcal{H}_0; \mathcal{B}_0 \triangleright_{\mathsf{T}} \mathsf{BndryErr}(\overline{b_0}, v_0); \mathcal{H}_0; \mathcal{B}_0
7526
                    16.1. QED
7527
                         by lemma 9.16
7528
7529
7530
7531
                    Lemma~9.10.~\textit{If}~\upsilon_0 \sim \textit{e}_0; \mathcal{H}_0; \mathcal{B}_0~\textit{then}~\textit{e}_0; \mathcal{H}_0; \mathcal{B}_0 \rightarrow_T^* \upsilon_1; \mathcal{H}_1; \mathcal{B}_1~\textit{and}~\upsilon_0 \sim \upsilon_1; \mathcal{H}_1; \mathcal{B}_1
7532
                    Proof. 1. case e_0 \in v
7533
7534
                    1.1. QED
7535
               2. Case e_0 \in w
7536
                    2.1. e_0; \mathcal{H}_0; \mathcal{B}_0 \rightarrow_T^* p_0; p_0 \mapsto e_0, \mathcal{H}_0; p_0 \mapsto \emptyset, \mathcal{B}_0
7537
7538
                         by v_0 \sim e_0; \mathcal{H}_0; \mathcal{B}_0 and lemma 9.18
7539
7540
               2019-10-03 17:26. Page 145 of 1-148.
```

```
7541
                                                                                                                                                                                                                                           7542
                  Lemma 9.11. If e_0 \sim v_0; \mathcal{H}_0; \mathcal{B}_0 then e_0 \rightarrow_A^* v_1 and v_1 \sim v_0; \mathcal{H}_0; \mathcal{B}_0
7543
7544
                  Proof. 1. Case e_0 \in v
7545
7546
                  1.1. QED
7547
             2. CASE e_0 = \operatorname{trace} \overline{b_0} v_1
7548
                  2.1. e_0 \rightarrow_A^* add\text{-trace}(\overline{b}_0, v_1)
7549
7550
                      by lemma 9.12
7552
                                                                                                                                                                                                                                           7553
7554
                  Lemma 9.12. If v_0 \sim v_1; \mathcal{H}_0; \mathcal{B}_0 and \Gamma_0 \vdash_A v_0 : \mathcal{U} then add-trace (\overline{b}_0, v_0) \sim v_1; \mathcal{H}_0; \mathcal{B}_0
7555
7556
                  PROOF. By case analysis of v_0 \sim v_1; \mathcal{H}_0; \mathcal{B}_0
7557
              1. CASE add-trace (\overline{b}_0, v_0) = v_0
7558
                  1.1. QED
7559
             2. CASE add-trace(\overline{b}_0, v_0) = \text{trace}_{\overline{v}} \overline{b}_1 v_2
7560
7561
                  2.1. SCASE v_0 = \operatorname{trace}_{v}^{?} \overline{b}_2 i_0
7562
                      2.1.1. QED
7563
                  2.2. SCASE v_0 = \operatorname{trace}_{v}^{?} \overline{b}_{2} \langle v_2, v_3 \rangle
7565
                      2.2.1. QED
7566
                  2.3. SCASE v_0 = \operatorname{trace}_{\mathbf{v}}^? \overline{b}_2 \pmod{b_0 \langle v_2, v_3 \rangle}
7567
7568
                  2.4. SCASE v_0 = \operatorname{trace}_{\mathbf{v}}^? \overline{b}_2 \pmod{b_0} \left( \operatorname{trace}_{\mathbf{v}}^? \overline{b}_3 \pmod{b_1} \langle v_2, v_3 \rangle \right) \right)
7569
7570
                      2.4.1. Contradiction:
7571
                           by lemma 7.10
7572
                  2.5. SCASE v_0 = \operatorname{trace}_{v}^{?} \overline{b}_2 (\lambda x_0. e_0)
7573
7574
                  2.6. SCASE v_0 = \operatorname{trace}_{V}^{?} \overline{b}_2 \pmod{b_0 (\lambda x_0. e_0)}
7575
7576
                      2.6.1. Contradiction:
                           by \Gamma_0 \ \overline{\Vdash}_A \ v_0 : \mathcal{U}
7578
                  2.7. SCASE v_0 = \text{trace}_{v}^{?} \bar{b}_2 (\lambda(x_0 : \tau_0). e_0)
7579
                      2.7.1. Contradiction:
7580
7581
                           by \Gamma_0 \Vdash_{\mathsf{A}} v_0 : \mathcal{U}
7582
                  2.8. scase v_0 = \operatorname{trace}_{\mathbf{v}}^? \overline{b}_2 \, (\operatorname{mon} b_0 \, (\lambda(x_0 \colon \tau_0). \, e_0))
7583
7584
                  2.9. SCASE v_0 = \operatorname{trace}_{\mathbf{v}}^? \overline{b_2} (\operatorname{mon} b_0 (\operatorname{trace}_{\mathbf{v}}^? \overline{b_3} (\operatorname{mon} b_1 (\lambda(x_0 : \tau_0). e_0))))
7585
7586
                      2.9.1. Contradiction:
7587
                           by lemma 7.10
7588
                                                                                                                                                                                                                                           Lemma 9.13. If v_0 \sim v_1; \mathcal{H}_0; \mathcal{B}_0 and v_0 \in (\lambda(x:\tau).e) \cup \langle v, v \rangle then mon b_0 \ v_0 \sim v_1; \mathcal{H}_0; \mathcal{B}_0
                                                                                                                                                                                        2019-10-03 17:26. Page 146 of 1-148.
```

```
PROOF. Immediate from the definition of \sim.
7593
7594
                                                                                                                                                                                                     7595
7596
               LEMMA 9.14. If unop\{\tau?\} v_0 \sim unop\{\tau?\} v_1; \mathcal{H}_0; \mathcal{B}_0 \text{ and } v_0 \notin mon b v \text{ then } \delta(unop, v_0) \text{ is defined iff } \delta(unop, v_1) \text{ is}
7597
           defined. Furthermore, if both are defined, then \delta(unop, v_0) \sim \delta(unop, v_1); \mathcal{H}_0; \mathcal{B}_0
7598
7599
               PROOF. 1. v_0 \in \text{trace}_{\mathbf{v}}^? \overline{b} \langle v, v \rangle \text{ iff } v_1 \in \langle v, v \rangle
7600
               by definition ~
7601
7602
           2. QED
7603
               by definition \delta
7604
7605
                                                                                                                                                                                                     7606
               LEMMA 9.15. If binop\{\tau^?\} v_0 v_1 \sim binop\{\tau^?\} v_2 v_3; \mathcal{H}_0; \mathcal{B}_0 then \delta(binop, v_0, v_1) is defined iff \delta(binop, v_2, v_3) is defined.
7607
7608
           Furthermore, if both are defined, then \delta(binop, v_0, v_1) \sim \delta(binop, v_2, v_3); \mathcal{H}_0; \mathcal{B}_0
7609
7610
               Proof. 1. v_0 \in i iff v_2 \in i
7611
                and v_1 \in i iff v_3 \in i
7612
               by definition ~
7613
           2. QED
7614
7615
               by definition \delta
7616
                                                                                                                                                                                                     7617
7618
               LEMMA 9.16. If v_0 \sim v_1; \mathcal{H}_0; \mathcal{B}_0 then tag-match (\lfloor \tau_0 \rfloor, v_0) iff tag-match (\lfloor \tau_1 \rfloor, v_1)
7619
7620
               PROOF. By case analysis of v_0 \sim v_1;; and tag-match
7621
           1. CASE trace, \bar{b}_0 i_0 \sim i_0; \mathcal{H}_0; \mathcal{B}_0
7622
               1.1. QED
7623
7624
                   by the definition of tag-match
7625
           2. CASE trace v_0^? \overline{b}_0 \langle v_2, v_3 \rangle \sim p_0; \mathcal{H}_0; \mathcal{B}_0
7626
                         and \mathcal{H}_0(p_0) = \langle v_4, v_5 \rangle
7627
               2.1. QED
7628
                  by tag-match
7630
           3. CASE trace, \overline{b}_0 (mon b_0 \langle v_2, v_3 \rangle) \sim p_0; \mathcal{H}_0; \mathcal{B}_0
7631
                         and \mathcal{H}_0(p_0) = \langle v_4, v_5 \rangle
7632
               3.1. QED
7633
7634
                   by tag-match
7635
           4. CASE mon b_0 (trace \sqrt[7]{b_0} (mon b_1 \langle v_2, v_3 \rangle)) \sim p_0; \mathcal{H}_0; \mathcal{B}_0
7636
                         and \mathcal{H}_0(p_0) = \langle v_4, v_5 \rangle
7637
               4.1. QED
7638
7639
                   by tag-match
7640
           5. CASE trace v_0^2 \overline{b}_0(\lambda x_0, e_0) \sim p_0; \mathcal{H}_0; \mathcal{B}_0
7641
                         and \mathcal{H}_0(p_0) = \lambda x_0. e_1
7642
7643
               5.1. QED
7644
           2019-10-03 17:26. Page 147 of 1-148.
```

2019-10-03 17:26. Page 148 of 1-148.

```
by tag-match
7645
7646
           6. CASE trace \overline{b_0} (mon b_0 (\lambda x_0. e_0)) \sim p_0; \mathcal{H}_0; \mathcal{B}_0
7647
                         and \mathcal{H}_0(p_0) = \lambda x_0 \cdot e_1
7648
               6.1. QED
7649
7650
                   by tag-match
7651
           7. CASE trace v = \overline{b_0} (\lambda(x_0 : \tau_0). e_0) \sim p_0; \mathcal{H}_0; \mathcal{B}_0
7652
                         and \mathcal{H}_0(p_0) = \lambda(x_0 : \tau_0). e_1
7653
               7.1. QED
7654
                   by tag-match
7656
           8. Case trace v_0^2 \overline{b_0} \pmod{b_0} (\lambda(x_0:\tau_0).e_0) \sim p_0; \mathcal{H}_0; \mathcal{B}_0
7657
                         and \mathcal{H}_0(p_0) = \lambda(x_0 : \tau_0). e_1
7658
               8.1. QED
7659
7660
                   by tag-match
7661
                                                                                                                                                                                                        7662
7663
               Lemma 9.17. If e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0 and v_0 \sim v_1; \mathcal{H}_0; \mathcal{B}_0 then e_0[x_0 \leftarrow v_0] \sim e_1[x_0 \leftarrow v_1]; \mathcal{H}_0; \mathcal{B}_0
7664
7665
               Proof. By case analysis of e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0 and induction on the structure of e_0 and e_1
7666
                                                                                                                                                                                                        Lemma 9.18. If e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0 and \mathcal{H}_1 adds bindings to \mathcal{H}_0 and \mathcal{B}_1 adds bindings and blame information to \mathcal{B}_0 then
7669
7670
           e_0 \sim e_1; \mathcal{H}_1; \mathcal{B}_1
7671
               PROOF. By induction on the derivation of e_0 \sim e_1; \mathcal{H}_0; \mathcal{B}_0
7672
7673
                                                                                                                                                                                                        7674
7676
7677
7678
7679
7682
7683
7684
7685
7686
7687
7688
7689
7690
7691
7692
7693
7694
```