Machine Learning:

from Theory to Practice

Lecture 3: Learning in Reproducing Kernel Hilbert Spaces

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Fall 2017

Outline

- Motivation
- 2 A reminder about SVM and SVR
- 3 Elements of the Reproducing Kernel Hilbert Space theory
- 4 Working in RKHS: supervised learning
- 6 References

- **Learning**: get $f_n = \mathcal{A}(\mathcal{S}_n, \mathcal{H}, \ell, \lambda, \Omega)$ with
 - \bullet \mathcal{A} :learning algorithm
 - S_n : training data
 - \bullet \mathcal{H} : class of functions
 - λ : some hyperparameter
 - ℓ : Local loss function
 - Ω : regularizing function
- **Prediction**: given x, and compute $f_n(x)$

Linear models

$$f_{lin}(x) = \beta^T x$$

Learn β by minimizing:

$$J(\beta) = \sum_{i=1}^{n} (y_i - f_{lin}(x_i))^2 + \lambda \Omega(\beta)$$

- Define
 - a representation space for data

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 - an optimization algorithm
 - a model selection method for hyperparameters

Objectives of the course

Motivation

A general framework for:

- learning (nonlinear) nonparametric functions
- dealing with non-vectorial data

Learning in Reproducing Kernel Hilbert Spaces

Linear models

$$f_{lin}(x) = \beta^T x$$

Learn β by minimizing:

$$J(\beta) = \frac{1}{2n} \sum_{i=1}^{n} L(x_i, y_i, f_{lin}(x_i)) + \lambda \Omega(\beta)$$

RKHS models

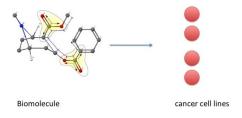
k positive definite and \mathcal{H}_k the RKHS associated, x_1, \ldots, x_n . When a representer theorem applies:

$$f_{rep}(x) = \alpha^T k_x = \sum_{i=1}^n \alpha_i k(x, x_i),$$

with $k_{x}^{T} = [k(x, x_{1}), \dots k(x, x_{n})]$ Learn α by minimizing

$$J(\alpha) = \sum_{i=1}^{n} L(x_i, y_i, f_{\alpha}(x_i)) + \lambda \Omega(f_{\alpha})$$

A supervised learning problem



- Inputs : molecule (drug candidate)
- Output : activity on a cancer line (or several cancer lines)

A regression problem from structured data.

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Outline A reminder about

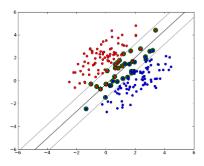
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Minimizing a convex loss for all except for A reminder about SVM and SVR some outliers

Examples

- Example 1: Support Vector Machine (reminder), maximize the margin for all except a few training data points
- Example 2: Support Vector Regression, minimize the ε-insensitive for all except a few training data points

```
Input set: \mathcal{X}
Output set: \{-1, +1\}
\mathcal{S} = \{(x_1, y_1), \dots, (x_n, y_n)\}
```



Maximizing the soft margin:

Solving the problem in the primal space

$$\min_{\substack{w,b,\xi\\ w,b,\xi}} \frac{1}{2}||w||^2 + C\sum_{i=1}^n \xi_i$$
 under the constraints $y_i(w^Tx_i + b) \ge 1 - \xi_i \ i = 1, \dots, n$.
$$\xi_i \ge 0 \ i = 1, \dots, n$$
.

 ξ_i : slack variable for each training data

Primal problem:

minimize
$$\frac{1}{2} \|w\|^2$$
 under the constraint
$$1 - y_i(w^T x_i + b) \le 0, i = 1, \dots, n.$$

Lagrangian

$$(w, b,) = \frac{1}{2}||w||^2 + \sum_{i} \alpha_i (1 - y_i(w^T x_i + b))$$
$$\forall i, \alpha_i \ge 0$$

Solve $\min_{w} \max(w,)$. The solution due to convexity is the saddle point. We can invert min and max.

Karush-Kuhn-Tucker conditions (KKT)

A reminder about SVM and SVR

Let α^* be the solution of the dual problem:

$$\forall i, [y_i f_{w^*, b^*}(x_i) - 1 + \xi_i^*] \le 0 \tag{1}$$

$$\forall i, \alpha_i^* \ge 0 \tag{2}$$

$$\forall i, \alpha_i^* [y_i f_{w^*, b^*}(x_i) - 1 + \xi_i^*] = 0 \tag{3}$$

$$\forall i, \mu_i^* \ge 0 \tag{4}$$

$$\forall i, \mu_i^* \xi_i^* = 0 \tag{5}$$

$$\forall i, \alpha_i^* + \mu_i^* = C \tag{6}$$

$$\forall i, \xi_i^* \ge 0 \tag{7}$$

$$w^* = \sum_{i} \alpha_i^* y_i x_i$$
 (8)

$$\sum_{i} \alpha_i^* y_i = 0$$
 (9)

$$\sum_{i} \alpha_i^* y_i = 0 \tag{9}$$

(10)

Let α^* be the solution of the dual problem:

- if $\alpha_i^* = 0$, then $\mu_i^* = C > 0$ and then, $\xi_i^* = 0$: x_i is well classified
- if $0<\alpha_i^*< C$ then $\mu_i^*>0$ and then, $\xi_i^*=0$: x_i is such that : $y_if(x_i)=1$
- if $\alpha_i^* = C$, then $\mu_i^* = 0$, $\xi_i^* = 1 y_i f_{w^*,b^*}(x_i)$

NB : b^* is computed by taking a i such that $0 < \alpha_i^* < C$

Solving the pb in the dual

$$\max_{\alpha}$$

$$\sum_{i} \alpha_{i} - \frac{1}{2} \sum_{i,j} \alpha_{i} \alpha_{j} y_{i} y_{j} x_{i}^{\mathsf{T}} x_{j}$$

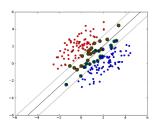
under the constraints

$$0\leq \alpha_i\leq C\ i=1,\ldots,n.$$

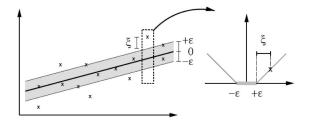
$$\sum_{i} \alpha_{i} y_{i} = 0 \ i = 1, \ldots, n.$$

$$f(x) = \sum_{i=1}^{n} \alpha_i y_i x^T x_i + b$$
$$h_{SVM}(x) = \text{sign}(f(x))$$

The x_i such that $\alpha_i > 0$ are the so-called *support vectors*.



- Extend the idea of maximal soft margin to regression: training data should be in the tube while the tube should be flat
- Impose an ϵ -tube : ϵ -sensitive loss , no penalty occurs if $||y_i f(x_i)|| \le \epsilon$. $\ell_{\epsilon}(x, y, f(x)) = |y f(x)|_{\epsilon} = \max(0, |y f(x)| \epsilon)$



SVR in the primal space

```
Given C and \epsilon
\min_{w,b,\xi} \frac{1}{2} \|w\|^2 + C \sum_i (\xi_i + \xi_i^*)
s.c.
\forall i = 1, \dots, y_i - f(x_i) \le \epsilon + \xi_i
\forall i = 1, \dots, f(x_i) - y_i \le \epsilon + \xi_i^*
\forall i = 1, \xi_i \ge 0, \xi_i^* \ge 0
with f(x) = w^T \phi(x) + b
```

$$\min_{\alpha,\alpha^*} \sum_{i,j} (\alpha_i - \alpha_i^*) (\alpha_j - \alpha_j^*) x_i^T x_j + \epsilon \sum_i (\alpha_i + \alpha_i^*) - \sum_i y_i (\alpha_i - \alpha_i^*)$$
s.c. $\sum_i (\alpha_i - \alpha_i^*) = 0$ and $0 \le \alpha_i \le C$ and $0 \le \alpha_i^* \le C$

$$w = \sum_{i=1}^n (\alpha_i - \alpha_i^*) x_i$$

Solution

$$f(x) = \sum_{i=1}^{n} (\alpha_i - \alpha_i^*) x_i^T x + b$$

Observe what is common to the two approaches

- A convex loss
- Notions of tube and geometric margin
- Insensitivity to some low errors: NB: could be useful for other algorithms as well
- Minimizing a term of complexity $||w||^2$ NB: minimize the Structural Risk and NOT the empirical risk
- Dual solution opens the door to the kernel trick

In the dual formulation, we notice: Each time the training data appear in the objective dual function, they appear as dot product:

- SVM : $\sum_{i} \alpha_{i} \frac{1}{2} \sum_{i,j} \alpha_{i} \alpha_{j} y_{i} y_{j} x_{i}^{T} x_{j}$
- SVR :

$$\sum_{i,j} (\alpha_i - \alpha_i^*) (\alpha_j - \alpha_j^*) x_i^T x_j + \epsilon \sum_i (\alpha_i + \alpha_i^*) - \sum_i y_i (\alpha_i - \alpha_i^*)$$

Idea (credit: Isabelle Guyon):

- We just need to compute scalar product during the learning phase as well as the prediction phase
- Whatever the space / set (called \mathcal{X}) I am working in, if I had a function $k: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ such that k computes inner products.

Definition of Positive Definite Symmetric kernel, PDS kernels

Let \mathcal{X} be a non-empty set. Let $k: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ be a symmetric function. k is a positive definite kernel *if and only if* for any finite set $\{x_1, \ldots, x_m\}$ de \mathcal{X} and the column vector c of \mathbb{R}^m ,

$$c^T K c = \sum_{i,i} c_i c_j k(x_i, x_j) \geq 0$$

Be careful: each matrix needs to be semi-definite positive while we call the kernel Positive definite (improperly)

Theorem (Moore-Aronzajn, 1950)

Let $k: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ be a PDS kernel then there exists a Hilbert space \mathcal{H} , called *feature space* and a *feature map*: $\phi: \mathcal{X} \to \mathcal{H}$ such that: $k(x,x') = <\phi(x), \phi(x')>_{\mathcal{H}}$, where $<\cdot,\cdot>_{\mathcal{H}}$ is the dot product associated with \mathcal{H} .

We will come back in a few slides to the constructive proof of this theorem and the Reproducing Kernel Hilbert Space Theory.

• There always exists at least one feature map and one feature space : if we take, $\phi(x) = k(\cdot, x)$ and $\mathcal H$ as the RKHS

$$\mathcal{X} = \mathbb{R}^p$$

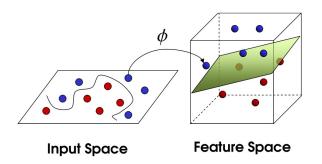
- Linear kernels: k(x, x')
- Gaussian kernels: $k(x, x') = \exp(-\gamma ||x x'||^2)$ (no finite dimensional feature map)
- Polynomial kernels: $k(x, x') = (x^T x' + c)^d$ (there exists a finite dimensional feature map)
- Sigmoidal kernels: $k(x, x') = \tanh(ax^Tx' + b)$

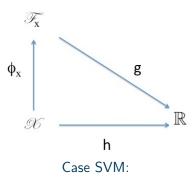
Back to the kernelization of SVM and SVR

In the dual formulation, we replace $x_i^T x_j$ by $k(x_i, x_j)$ where k is a Positive Definite Symmetric kernel

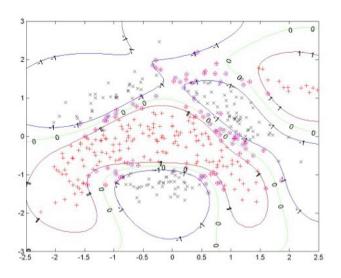
• SVM :
$$\sum_{i} \alpha_{i} - \frac{1}{2} \sum_{i,j} \alpha_{i} \alpha_{j} y_{i} y_{j} k(x_{i}, x_{j})$$

$$\sum_{i,j} (\alpha_i - \alpha_i^*)(\alpha_j - \alpha_j^*) k(x_i, x_j) + \epsilon \sum_i (\alpha_i + \alpha_i^*) - \sum_i y_i (\alpha_i - \alpha_i^*)$$





- $f(x) = \sum_{i=1}^{n} \alpha_i y_i < \phi(x), \phi(x_i) >_{\mathcal{F}} = \sum_{i=1}^{n} \alpha_i y_i k(x, x_i),$
- Linear function: $g(z) = (\sum_i \alpha_i y_i \phi(x_i))^T z$
- $f(x) = g \circ \phi(x)$
- SVM : h(x) = sign(f(x) + b)



closure property	feature space representation
a) $K_1(x,y) + K_2(x,y)$	$\Phi(x) = (\Phi_1(x), \Phi_2(x))^T$
b) $\alpha K_1(x,y)$ for $\alpha > 0$	$\Phi(x) = \sqrt{\alpha}\Phi_1(x)$
c) $K_1(x,y)K_2(x,y)$	$\Phi(x)_{ij} = \Phi_1(x)_i \Phi_2(x)_j$ (tensor product)
d) $f(x)f(y)$ for any f	$\Phi(x) = f(x)$
e) $x^T A y$ for $A \succeq 0$ (i.e. psd)	$\Phi(x) = L^T x$ for $A = LL^T$ (Cholesky)

From those properties, we conclude that a polynomial of kernels is still a kernel. the pointwise limit of kernels is also a kernel.

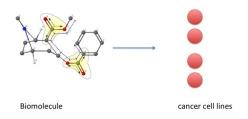
Much more interesting: kernels for complex objects

Kernels for

- Complex (unstructured) objects: texts, images, documents, signal, biological objects (gene, mRNA,protein, ...), functions, histograms
- **Structured objects**: sequences, trees, graphs, any composite objects

This made the success of kernels in computational biology, information retrieval (categorization for instance), but also in unexpected areas such as software metrics

Example: predict the property of a molecule



- Inputs : molecule (drug candidate)
- Output : activity on a cancer line (or several cancer lines)

A regression problem from structured data.

For a given length L, let us first enumerate all the paths of length $\ell \leq L$ in the training dataset (data are molecule = labeled graphs). Let m be the size of this (huge) set. For a graph, define $\phi(G) = (\phi_1(G), \ldots, \phi_m(G))^T$ where $\phi_m(T)$ is 1 if the m^{th} path appears in the labeled graph G, and 0 otherwise.

Definition 1:

$$k_L(G, G') = \langle \phi(G), \phi(G') \rangle$$

Tanimoto kernel

$$k_L^t(G, G') = \frac{k_m(G, G')}{k_m(G, G) + k_m(G', G') - k_m(G, G')}$$

idea: k_m^t calculates the ratio between the number of elements of the intersection of the two sets of paths (G and G' are seen as bags of paths) and the number of elements of the union of the two sets.

Reference: Ralaivola et al. 2005, Su et al. 2011

Definition:

Suppose that $x \in \mathcal{X}$ is a **composite structure** and x_1, \ldots, x_D are its "parts" according a relation R such that $(R(x, x_1, x_2, \ldots, x_D))$ is true, with $x_d \in \mathcal{X}_d$ for each $1 \leq d \leq D$, D being a positive integer. k_d be a PDS kernel on a set $\mathcal{X} \times \mathcal{X}$, for all (x,x'), we define:

$$k_{conv}(x, x') = \sum_{(x_1, \dots, x_d) \in R^{-1}(x), (x'_1, \dots, x'_d) \in R^{-1}(x')} \prod_{d=1}^{B} k_d(x_d, x'_d)$$

 $R^{-1}(x) = \text{all decompositions } (x_1, \ldots, x_D) \text{ such that } (R(x, x_1, x_2, \ldots, x_D). \ k_{conv} \text{ is a PDS kernel as well. Intuitive kernel, used as a building principle for a lot of other kernels. Next, we will see two examples.}$

Let x_1, \ldots, x_n , n objects associated with a non oriented graph of size n and adjacency matrix W. Define the graph Laplacian : L = D - W, D is the diagonal matrix of degrees

$$K = \exp(-\lambda L)$$

We will see applications of this kernel in the unsupervised course.

Reference: Kondor and Lafferty, 2003

Combine the advantages of graphical models and discriminative methods

Let $x \in \mathbb{R}^p$ be the input vector of a classifier.

- Learn a generative model $p_{\theta}(x)$ from unlabeled data x_1, \dots, x_n
- Define the Fisher vector as : $u_{\theta}(x) = \nabla_{\theta} \log p_{\theta}(x)$
- Estimate the Fisher Information matrix of p_{θ} : $F_{\theta} = \mathbb{E}_{\mathbf{x} \sim p_{\theta}}[u_{\theta}(\mathbf{x})u_{\theta}(\mathbf{x})^{T}]$
- **Definition**: $k_{Fisher}(x, x') = u_{\theta}(x)^T F_{\theta} u_{\theta}(x)$

Applications

Classification of secondary structure of proteins, topic modeling in documents, image classification and object recognition, audio signal classification ... Ref: Haussler, 1998. Perronnin et al. 2013.

- Use closure properties to build new kernels from existing ones
- Kernels can be defined for various objects:
 - Structured objects: (sets), graphs, trees, sequences, . . .
 - Unstructured data with underlying structure: texts, images, documents, signal, biological objects (gene, mRNA,protein, ...)

Kernel learning:

- Hyperparameter learning: see Chapelle et al. 2002
- Multiple Kernel Learning: given k_1, \ldots, k_m , learn a convex combination $\sum_i \beta_i k_i$ of kernels (SimpleMKL Rakotomamonjy et al. 2008, unifying view in Kloft et al. 2010)

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Definition (Reproducing Kernel Hilbert space - RKHS)

Let \mathcal{H} be a Hilbert space of \mathbb{R} -valued functions on non-empty set \mathcal{X} . A function $k: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ is a **reproducing kernel** of \mathcal{H} , and \mathcal{H} is a reproducing kernel Hilbert space if:

- $\forall x \in \mathcal{X}, k(\cdot, x) \in \mathcal{H},$
- $\forall x \in \mathcal{X}, \forall f \in \mathcal{H}, \langle f(\cdot), k(\cdot, x) \rangle_{\mathcal{H}} = f(x)$ (reproducing property).

In particular, for any $x,y \in \mathcal{X}$,

$$k(x,y) = \langle k(\cdot,x), k(\cdot,y) \rangle_{\mathcal{H}}$$

Theorem (Reproducing Kernel Hilbert space induced by a kernel (Aronszajn, 1950)

Let $k: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ be a positive definite symmetric kernel. Then, there exists a Hilbert space \mathcal{H} and a function $\phi: \mathcal{X} \to \mathcal{H}$ such that:

$$\forall (x, x') \in \mathcal{X} \times \mathcal{X}, k(x, x') = \langle \phi(x), \phi(x') \rangle_{\mathcal{H}}$$

Note that \mathcal{H} is not unique but there exists a unique Hilbert Space that has the following "reproducing property":

$$\forall f \in \mathcal{H}, \forall x \in \mathcal{X}, f(x) = \langle f(\cdot), k(\cdot, x) \rangle$$

Let us define $\mathcal{H}_0 = \mathrm{span}\{\sum_{i \in I} \alpha_i k(\cdot, x_i), x_i \in \mathcal{X}, |I| < \infty\}$. \mathcal{H}_0 is the set of finite linear combinations of functions $x \to k(\cdot, x_i)$. Introduce the operation $<, \cdot, \cdot>_{\mathcal{H}_0}$:

$$\forall f, g, \in \mathcal{H}_0^2, f(\cdot) = \sum_{i \in I} \alpha_i k(\cdot, x_i)$$
$$g(\cdot) = \sum_{j \in J} \beta_j k(\cdot, z_j)$$

by

$$< f, g>_{\mathcal{H}_0} = \sum_{i \in I, j \in J} \alpha_i \beta_j k(x_i, z_j)$$

We notice that:

$$\langle f, g \rangle = \sum_{j \in J} \beta_j f(z_j) = \sum_{i \in I} \alpha_i g(x_i)$$

meaning that this product between f and g does not depend on the expansions of f or g. This last equation also shows that this product is bilinear. It is also trivially symmetric. $<\cdot,\cdot>_{\mathcal{H}_0}$ is a dot product on functions of \mathcal{H}_0

We define a norm from this dot product:

$$||f||_{\mathcal{H}_0}^2 = \langle f, f \rangle_{\mathcal{H}_0} = \sum_{i \in I, j \in I} \alpha_i \alpha_j k(x_i, x_j)$$

where K is the Gram matrix associated to k.

Remark: we have a Cauchy-Schwartz inequality for PDS kernels (that we will use).

Proposition: Cauchy-Schwartz inequality

Let k be a PDS kernel then $\forall (x, z) \in \mathcal{X}^2$, we have:

$$k(x,z)^2 \le k(x,x)k(z,z)$$

Proof:

consider the matrix:
$$K = \begin{pmatrix} k(x,x) & k(x,z) \\ k(z,x) & k(z,z) \end{pmatrix}$$

then, $\det(K) = k(x,x)k(z,z) - k(x,z)^2$. We know that K is semi-definite positive so $\det(K) \ge 0$.

We need to prove that we have the reproducing property:

$$\langle f, k(\cdot, x) \rangle_{\mathcal{H}_0} = \langle \sum_{i} \alpha_i k(\cdot, x_i), k(\cdot, x_i) \rangle$$

 $= \sum_{i} \alpha_i k(x, x_i)$
 $= f(x)$

Now \mathcal{H}_0 is named a pre-Hilbert space and we need to complete it with the limits of Cauchy sequences to get a **Hilbert space**.

Let $(f_n)_n$, a Cauchy sequence of functions of \mathcal{H}_0 .

$$\forall \epsilon > 0, \exists N \in \mathbb{N}, \forall p, q > N, ||f_p - f_q||^2 < \epsilon$$

Let us consider $\mathcal{H}=\mathcal{H}_0\cup\{\text{Iim\,of Cauchy sequences from}\mathcal{H}_0\}.$

Let us call $f = \lim_{n \to \infty} f_n$.

To ensure the reproducing property for these new functions, we need to have the pointwise convergence of $(f_n(x))_n$ for $x \in \mathcal{X}$.

Proof of pointwise convergence of $(f_n(x))_n$ for $x \in \mathcal{X}$ $\forall x \in \mathcal{X}, \forall (p,q) \in \mathbb{N}^2$,

$$|fp(x) - f_q(x)| = |\langle f_p, k(\cdot, x) - \langle f_q, k(\cdot, x) \rangle|$$

$$= |\langle f_p - f_q, k(\cdot, x) \rangle|$$

$$\leq \sqrt{\langle f_p - f_q, f_p - f_q \rangle} \sqrt{k(x, x)}$$

$$\leq ||fp - f_q|| \sqrt{k(x, x)}$$

Then it comes that $(f_n(x))_n$ is a Cauchy Sequence in $\mathbb R$ and thus has a limit. now $f(x) = \lim_{n \to \infty} f_n(x)$.

We want to compute $< \lim f_n, k(\cdot, x) >$. Let us first compute:

 $\lim_{n\to\infty} \langle f_n, k(\cdot, x) \rangle = \lim f_n(x) = f(x).$

We now define the dot product between a limit of Cauchy Sequence and the function $k(\cdot,x)$ from \mathcal{H}_0 as: $< lim f_n, k(\cdot,x) > := \lim f_n(x) = f(x)$. The dot product can be also defined between two limits of Cauchy sequences and also benefit from the reproducing property.

Unicity theorem

Elements of the Reproducing Kernel Hilbert Space theory

Theorem

Let $k: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ be a positive definite symmetric kernel and \mathcal{H}_k be a Hilbert space built from k and \mathcal{X} , then \mathcal{H}_k is unique.

Feature Space and feature map

Elements of the Reproducing Kernel Hilbert Space theory

Any Hilbert space $\mathcal H$ such that there exists $\phi: \mathcal X \to \mathcal H$ with: $\forall (x,x') \in \mathcal X \times \mathcal X, k(x,x') = <\phi(x), \phi(x')>_{\mathcal H}$ is called a feature space associated with k and ϕ is called a feature map.

Theorem

Let $k: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ be a positive definite symmetric kernel and \mathcal{H}_k , its corresponding RKHS, then, for any strictly increasing function $\Omega: \mathbb{R} \to \mathbb{R}$ and any loss function L: $\mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$, any minimizer of :

$$J(f) = L(f(x_1), \dots, f(x_n)) + \lambda \Omega(\|f\|_{\mathcal{H}})$$
(11)

admits an expansion of the form:

$$f^*(\cdot) = \sum_{i=1}^n \alpha_i k(x_i, \cdot).$$

Let us define: $\mathcal{H}_1 = \text{span } \{k(x_i, \cdot), i = 1, \dots, n\}$ Any $f \in \mathcal{H}$ writes as: $f = f_1 + f^{\perp}$, with $f_1 \in \mathcal{H}_1$ and $f^{\perp} \in \mathcal{H}_1^{\perp}$ where $\mathcal{H}=$ direct sum of \mathcal{H}_1 and \mathcal{H}_1^+ .

By the reproducing property, we get:

$$f(x_i) = \langle f_1(\cdot) + f_1^{\perp}(\cdot), k(x_i, \cdot) \rangle = \langle f_1(\cdot), k(x_i, \cdot) \rangle = f_1(x_i)$$

Hence, $L(f(x_1), \dots, f(x_n)) = L(f_1(x_1), \dots, f_1(x_n))$

By orthogonality,
$$||f||^2 = ||f_1||^2 + ||f_1^{\perp}||^2$$

Hence, by property of Ω , $\Omega(\|f\|) = \Omega(\sqrt{\|f_1\|^2 + \|f_1^\perp\|^2}) \geq \Omega(\|f_1\|)$ and $J(f_1) < J(f)$

There is equality if and only if $\left\|f_1^\perp\right\|=0$. Therefore if f^* is the minimum than it is equal to f_1^* .

Theorem

Let $k: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ be a positive definite symmetric kernel and \mathcal{H}_k , its corresponding RKHS. Let us assume we are given $(x_1,\ldots,x_n)\in\mathcal{X}^n$ and a set of real functions $\{\psi_p,p=1\ldots M\}$ such that the $n\times M$ matrix $(\psi_p(x_i))_{ip}$ is of rank M. Then, for $\tilde{f}=f+h$ where $f\in\mathcal{H}_k$ and $h\in \text{span}(\psi_p)$, for any strictly increasing function $\Omega:\mathbb{R}\to\mathbb{R}$ and any loss function L:

 $\mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$, any minimizer of :

$$J(\tilde{f}) = L(\tilde{f}(x_1), \dots, \tilde{f}(x_n)) + \lambda \Omega(\|f\|_{\mathcal{H}})$$
 (12)

admits an expansion of the form:

$$f^*(\cdot) = \sum_{i=1}^n \alpha_i k(x_i, \cdot) + \sum_{p=1}^M \beta_p \psi_p(\cdot).$$

with unique coefficients β_p , $p = 1, \dots, M$.

Elements of the Reproducing Kernel Hilbert Space theory

- it converts a minimization problem in infinite dimensional space into a finite dimensional space
- You can obtain the representer theorem by two ways: using the reproducing properties, or using convex programming and dualization
- Importance of norm $\ell_2||f||_{\mathcal{H}}$: the choice of the kernel directly influences the regularization through $\alpha^T K \alpha$
- Idea: choose the kernel not uniquely for its reprensentation power but for the regularization to which it gives access

- **①** Define a PDS kernel: $k(\cdot, \cdot)$ that captures background knowledge
- **2** Define a RKHS, \mathcal{H} from k with an appropriate norm $||\cdot||_{\mathcal{H}}$
- Define a loss functional with two terms: a local loss function ℓ and a penalty function Ω
- Prove/use a representer theorem to get the form of the minimizer of this functional: $\sum_i \alpha_i k(\cdot, x_i)$
- Solve the optimization problem with this minimizer

- Motivation
- 2 A reminder about SVM and SVR
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$$L(f(x_1), ..., f(x_n)) = \sum_i (y_i - f(x_i))^2$$
 and $\Omega(||f||) = ||f||^2$

$$L(\alpha) = \frac{1}{2} ||Y - K\alpha||^2 + \lambda ||f||^2$$

$$= \frac{1}{2} ||Y - K\alpha||^2 + \lambda \alpha^T K\alpha,$$

where $K_{ij} = k(x_i, x_j)$.

First order conditions:

$$\frac{\partial L}{\partial \alpha} = -(Y - K\alpha)^T K + \lambda \alpha^T K$$

$$= -K(Y - K\alpha) + \lambda K\alpha$$

$$= -KY + K^2 \alpha + \lambda K\alpha$$

We have : $\frac{\partial L}{\partial \alpha} = 0 \iff K(K\alpha + \lambda I\alpha) = Ky$.

$$K((K + \lambda I)\alpha - Y) = 0$$

$$\iff ((K + \lambda I)\alpha - Y) \in \text{Ker } K$$

NB: $(K + \lambda I)$ is invertible if λ is positive

Therefore, (2)
$$\iff \alpha - (K + \lambda I)^{-1}Y \in \text{Ker } K$$

Then, $\alpha = (K + \lambda I)^{-1} Y$ is a solution.

As well as any $\alpha' = \alpha + \epsilon$ with $K\epsilon = 0$.

Now, if we compare f_{α} and $f_{\alpha'}$:

$$||f_{\alpha'} - f_{\alpha}||^{2} = (\alpha' - \alpha)^{T} K(\alpha' - \alpha)$$
$$= \epsilon^{T} K \epsilon$$
$$= 0$$

so the solution writes as:

$$\alpha = (K + \lambda I)^{-1} Y$$

Note that in practise we prefer not to inverse a $n \times n$ matrix and use a stochastic gradient descent algorithm to find the minimum.

- SVM without bias b
- $L(f(x_1),\ldots,f(x_n))=\max(0,1-y_if(x_i))$ (hinge loss) and $\Omega(\|f\|)=\|f\|^2$
- $\min_{\alpha} \sum_{i=1}^{n} \max(0, 1 y_i \sum_{i} \alpha_j k(x_i, x_j)) + \lambda \alpha^T K \alpha$
 - NB: If you want to introduce b, you need the refer to the semi-parametric representer theorem.

Example: predict the property of a molecule



• Inputs : molecule (drug candidate)

• Output : activity on a cancer line (or several cancer lines)

A regression problem from structured data.

- $S_n = \{(x_1, y_1), \dots, (x_n, y_n)\}$
- Each x_i is a labeled graph, each y_i is a scalar
- Assume we have defined a kernel over labeled graphs
- Different loss functions for different methods
 - **1** $\arg\min_{f \in \mathcal{F}} \frac{1}{2} \sum_{i=1}^{n} ||y_i f(x_i)||^2 + \lambda ||f||_{\mathcal{H}}^2 : KRR$ **2** $\arg\min_{f \in \mathcal{F}} \frac{1}{2} \sum_{i=1}^{n} \max(0, |y_i f(x_i)|_{\epsilon} + \lambda ||f||_{\mathcal{H}}^2 : SVR$

See exercise in Datalab 1.

Outline

- Motivation
- 2 A reminder about SVM and SVR
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References

- A tutorial review of RKHS, Hoffman, Scholpkoft, Smola, 2005 (first part).
- Foundations of Machine Learning, Mohri, MIT Press, 2012.