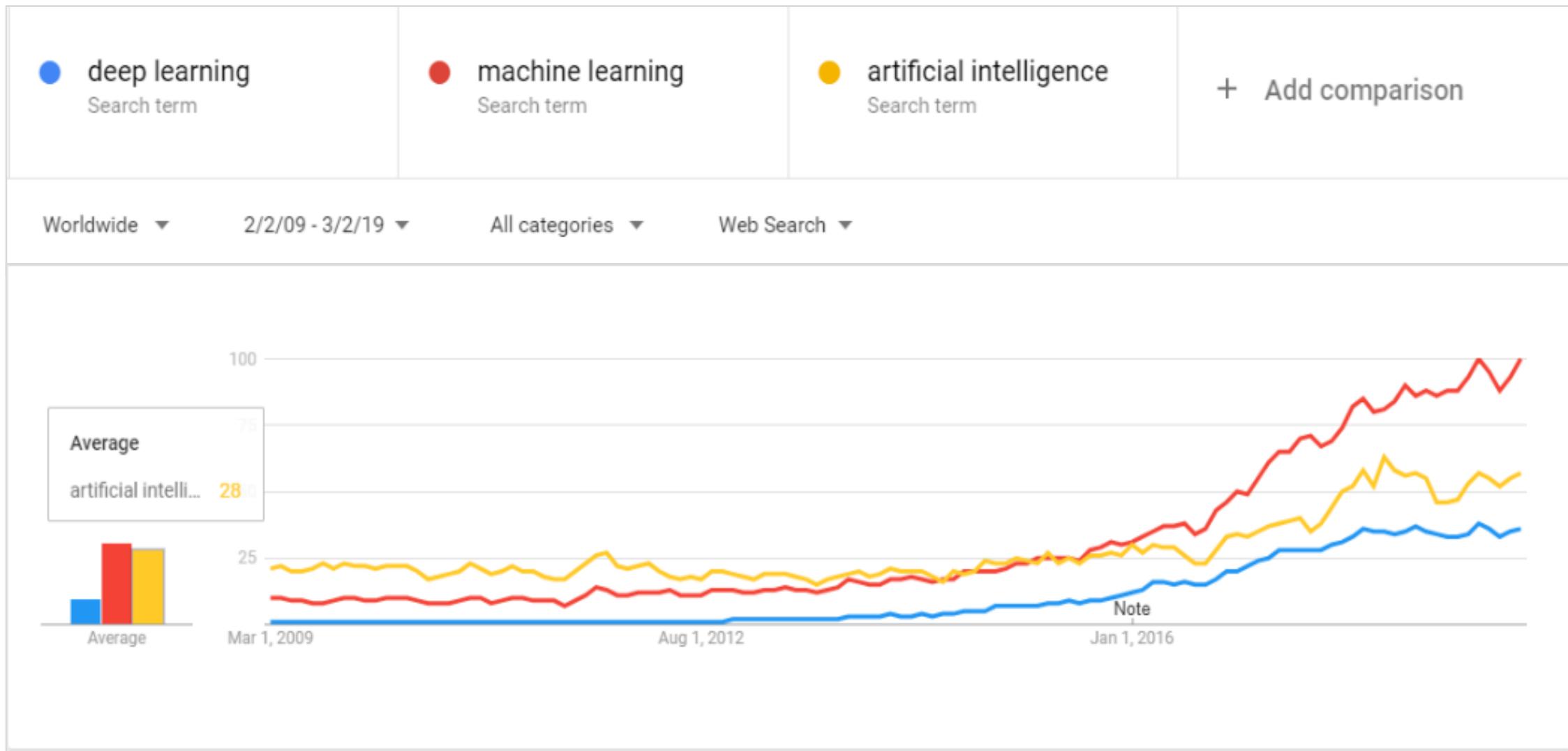


# Introduction to Deep Learning

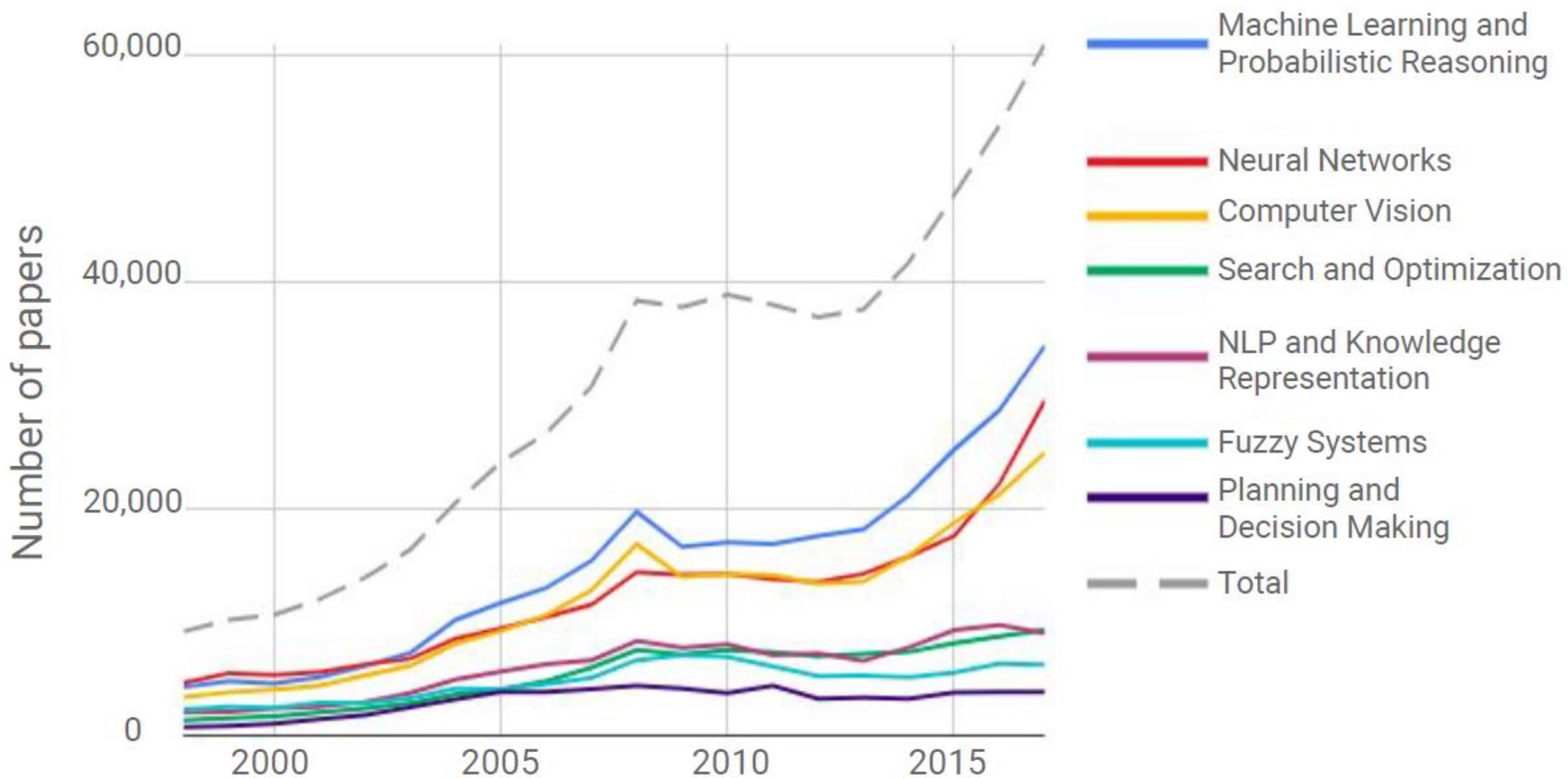
Prof. Kuan-Ting Lai

2019/7/2

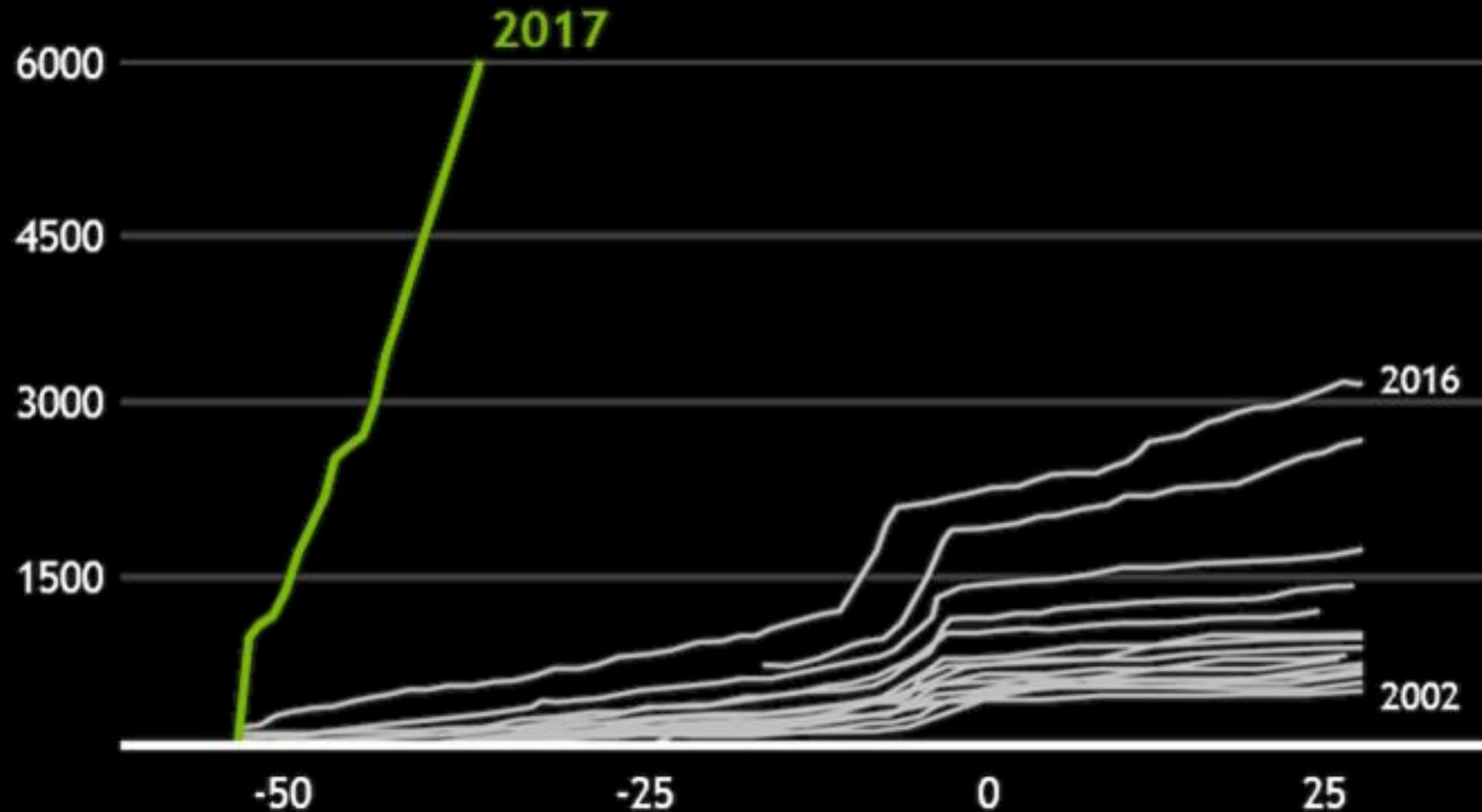
# Deep Learning – a new Buzzword



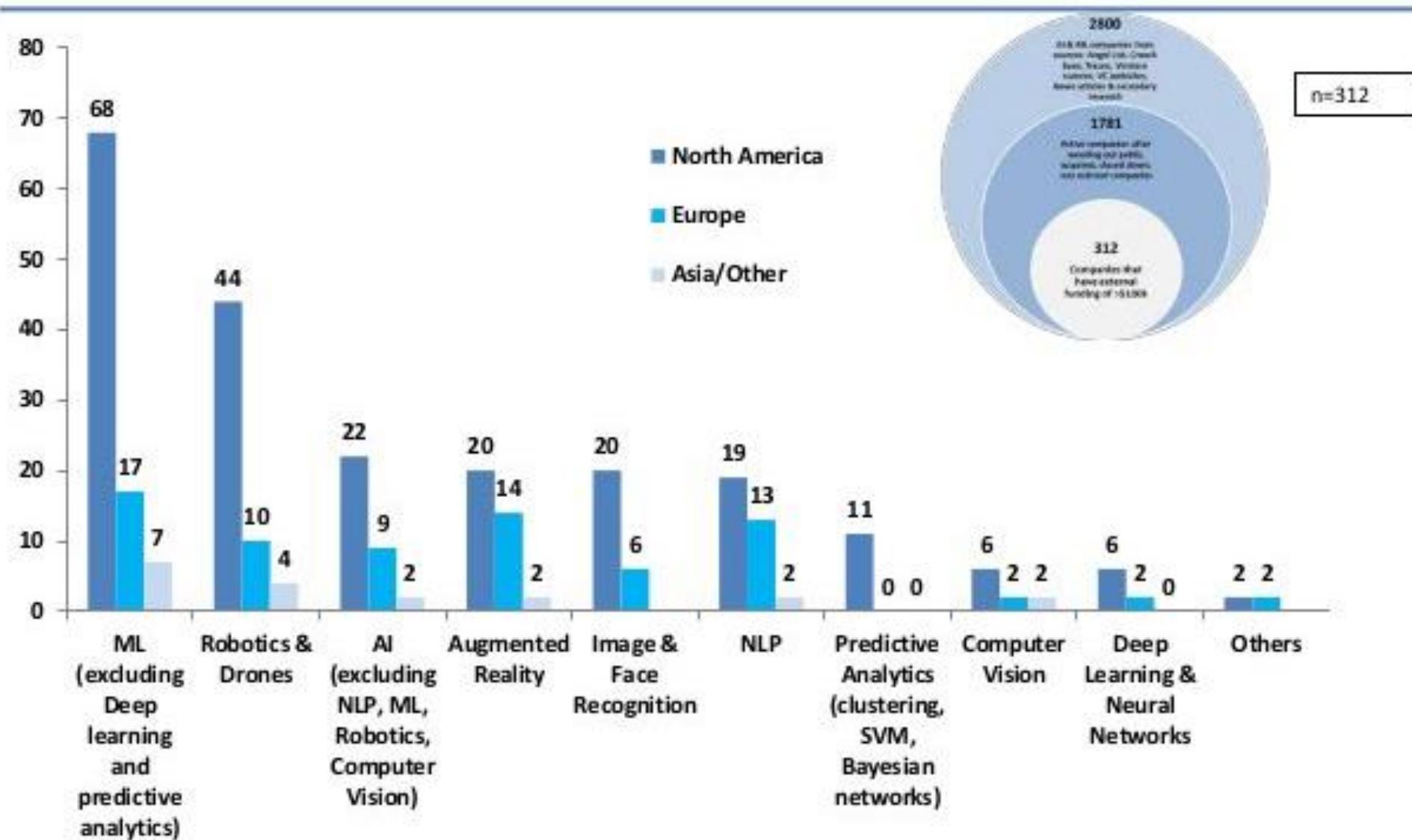
# AI Papers



# Registration of NIPS

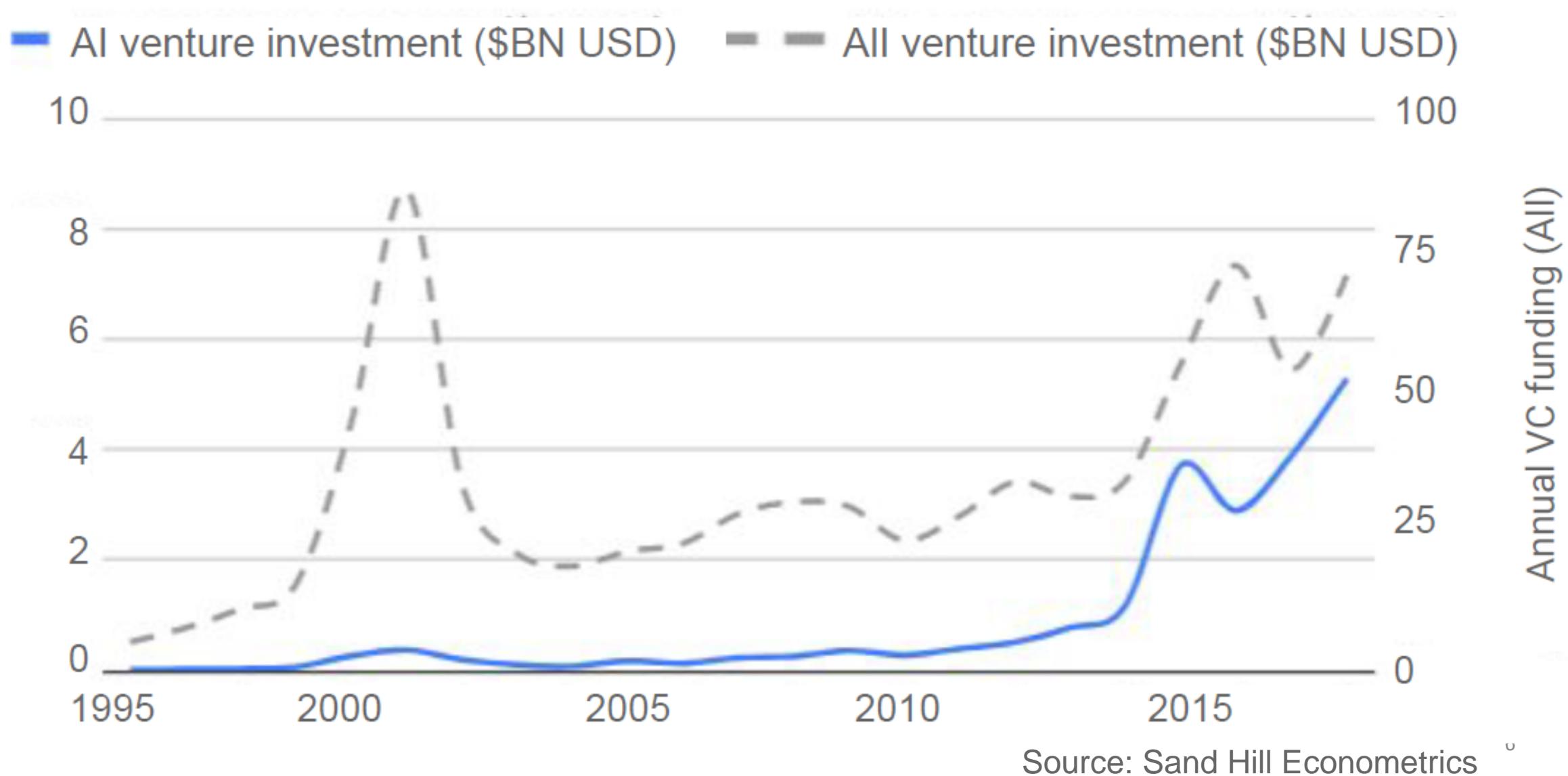


# Major Fields for AI / ML Venture Investment by Geography

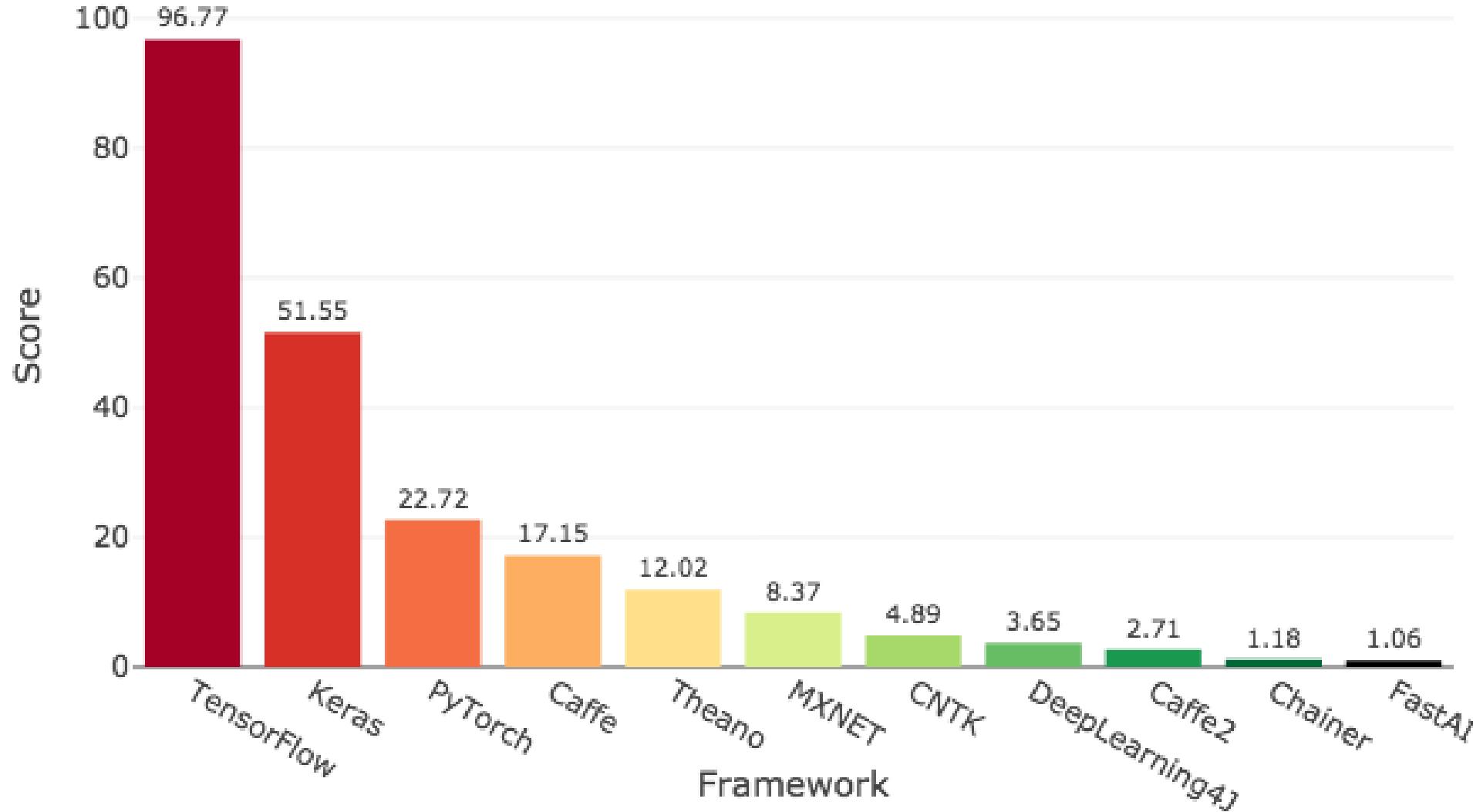


North America is leading the way but Europe has significant presence in AI & AR areas

# Source: Sand Hill Econometrics



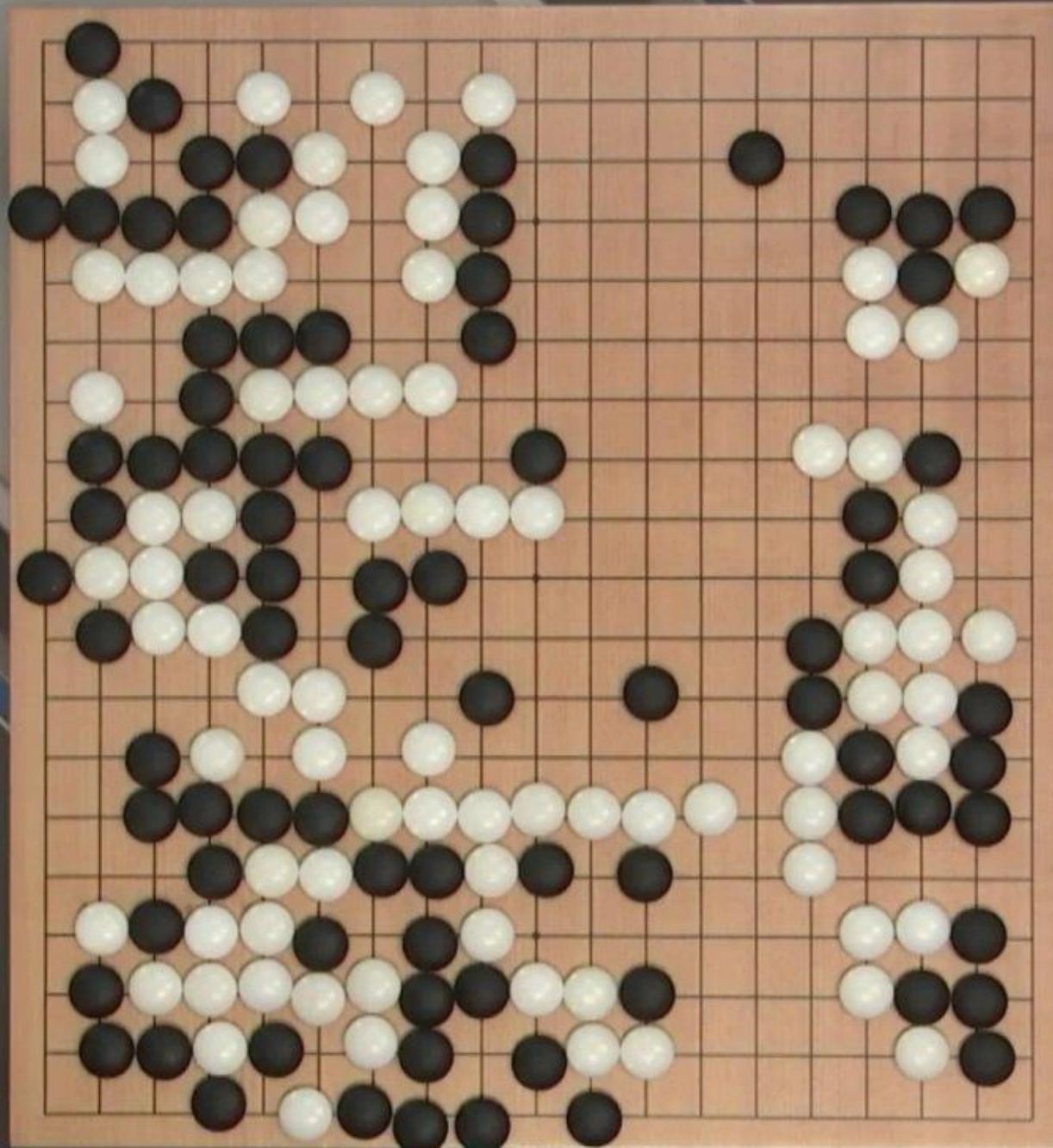
## Deep Learning Framework Power Scores 2018





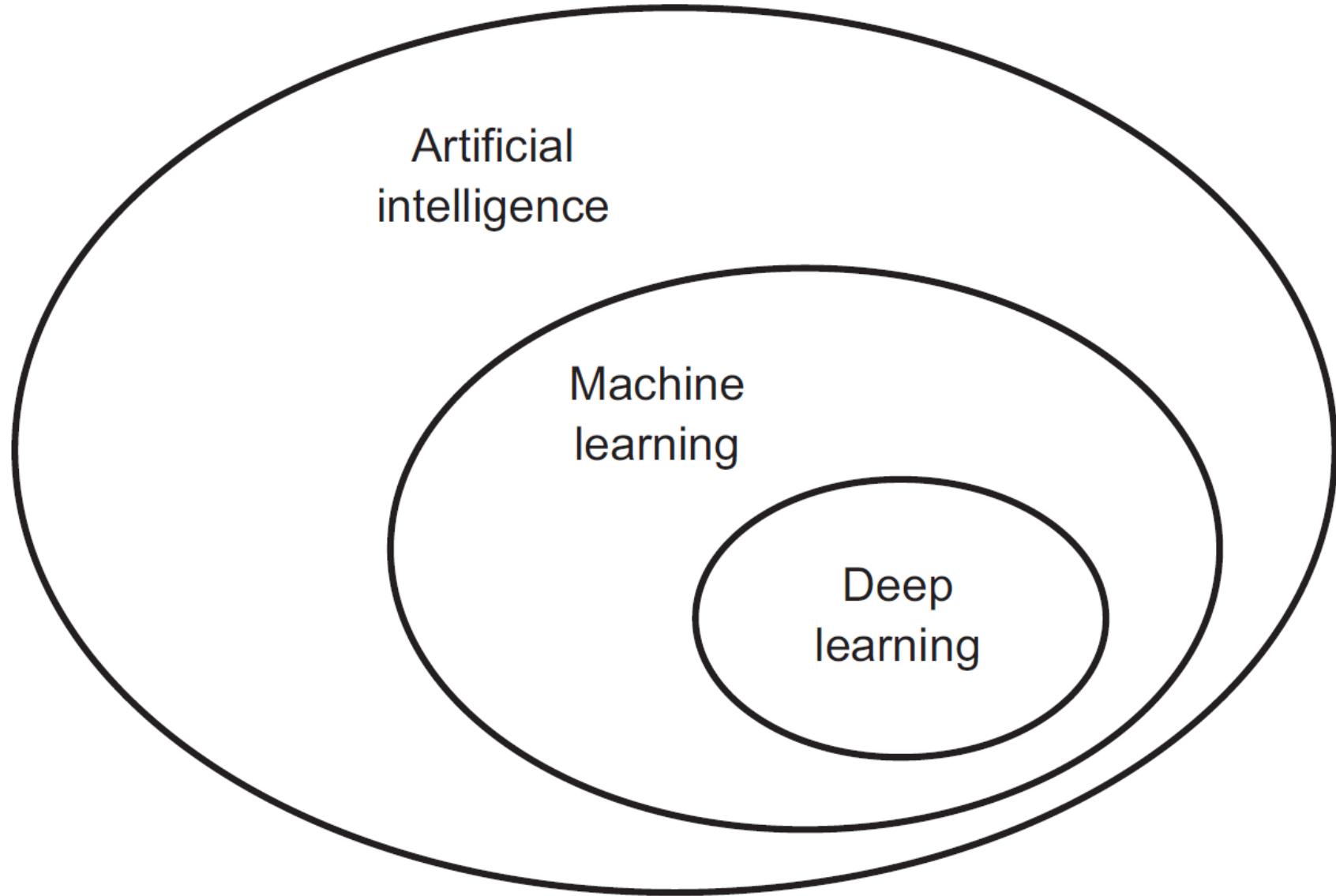
ALPHAGO  
00:10:29

  
AlphaGo  
Google DeepMind

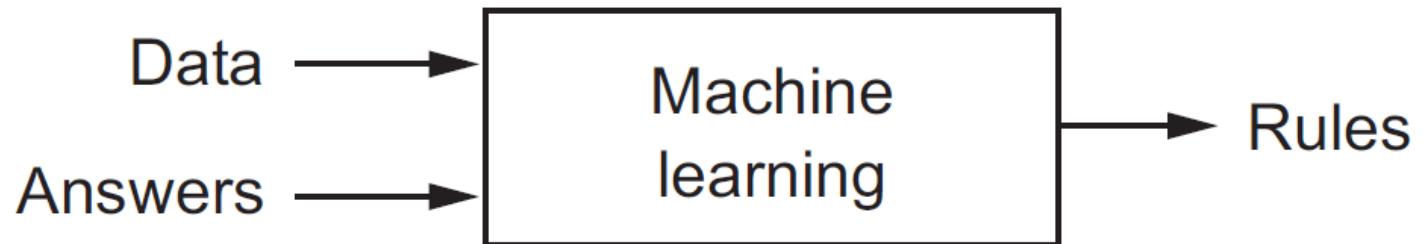
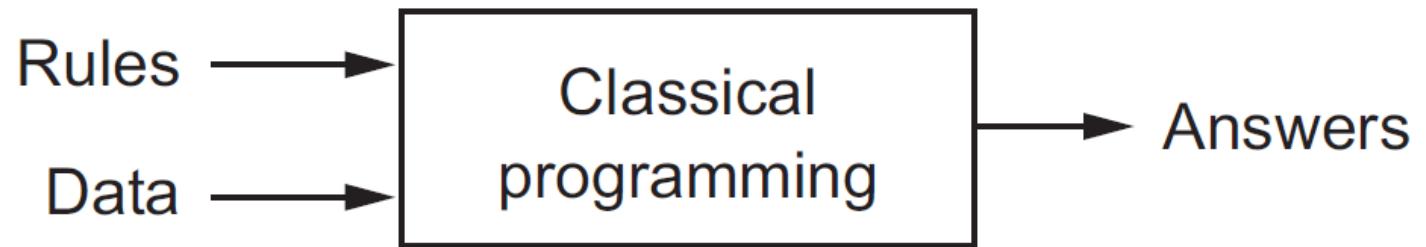


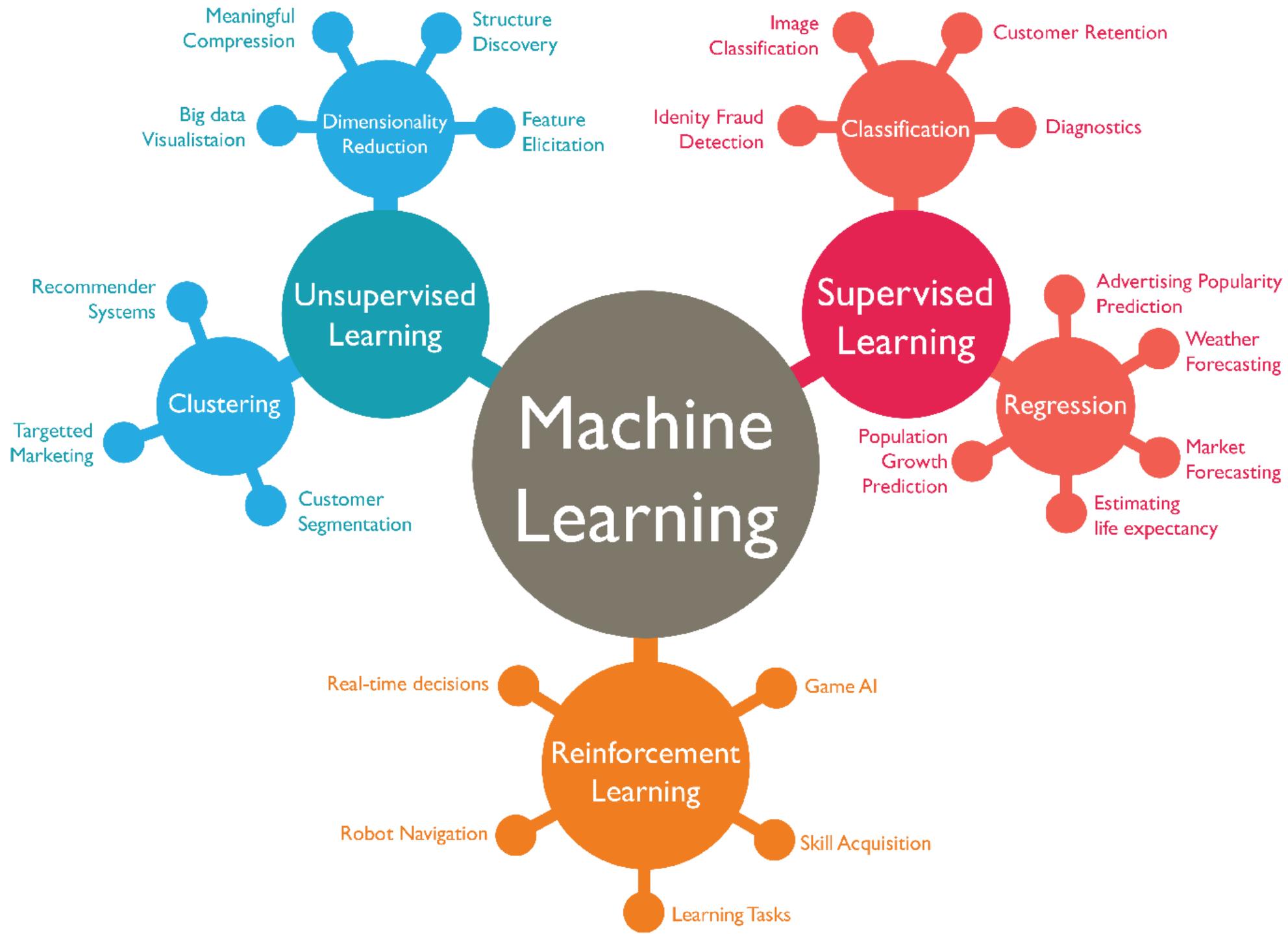
LEE SEDOL  
00:01:00

So, what is  
Deep Learning?

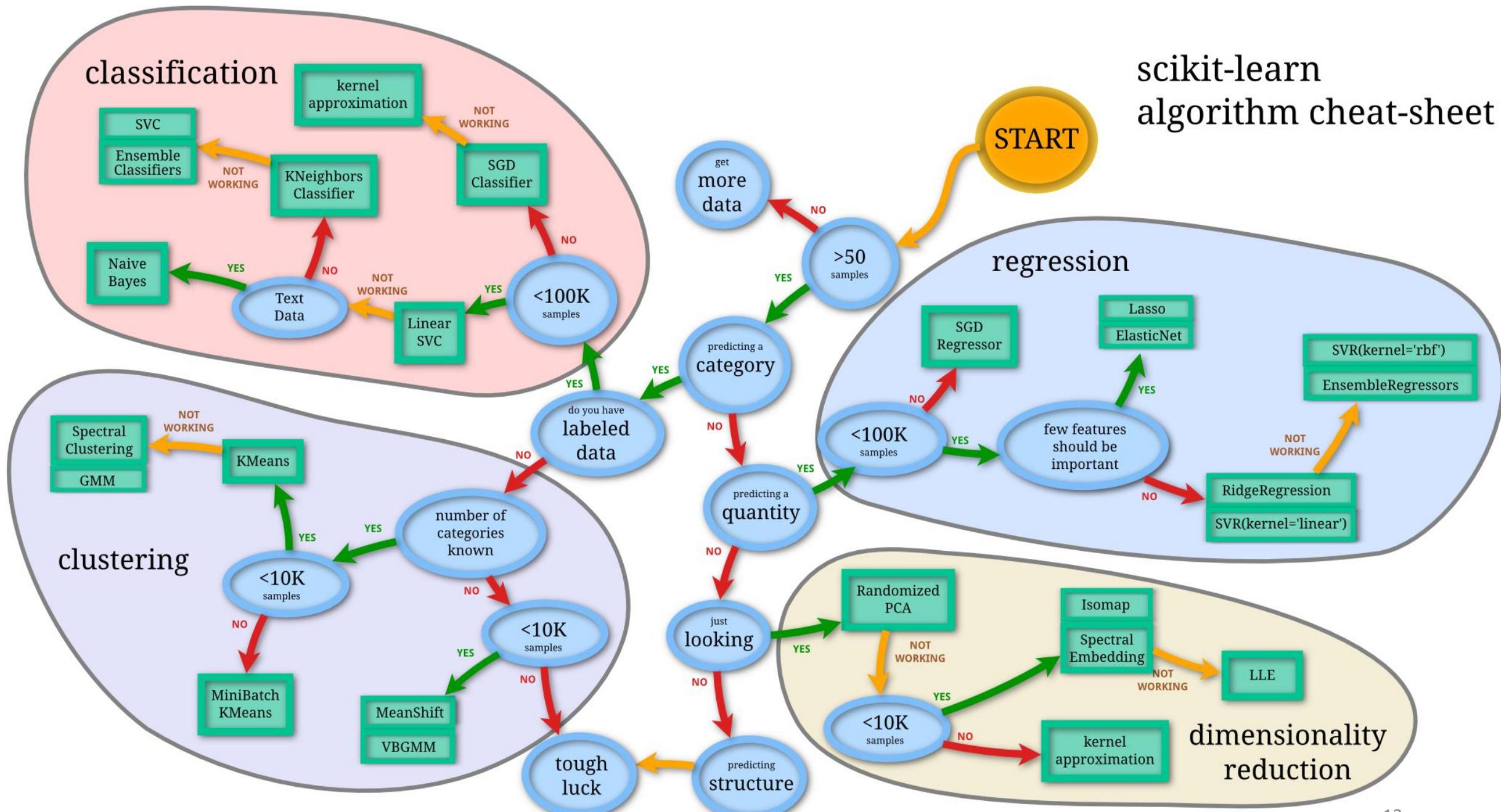


# Machine Learning





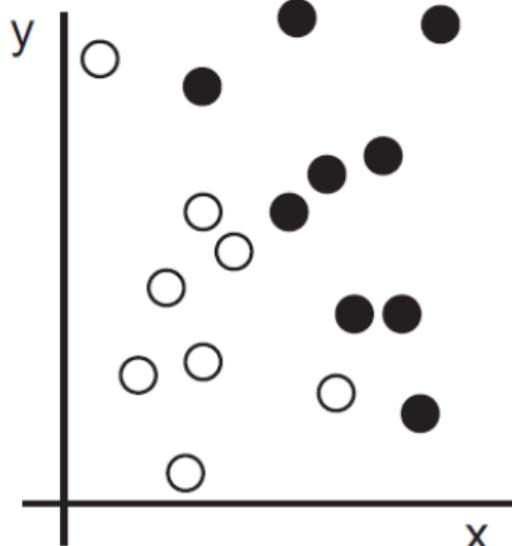
# scikit-learn algorithm cheat-sheet



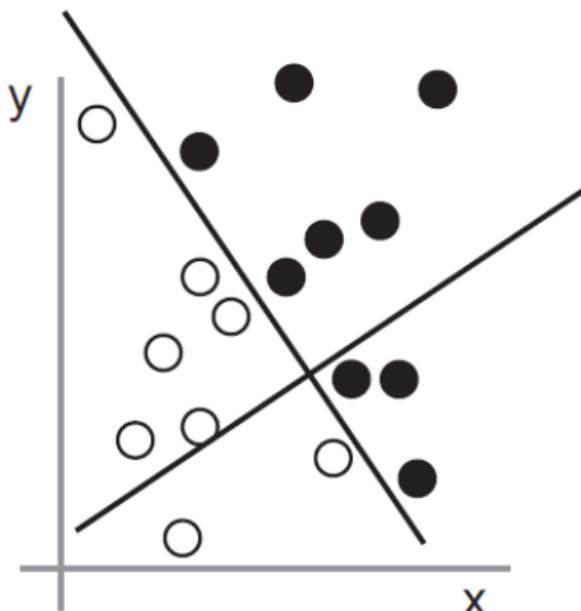
# Learning Representation

- Objective: Classify white & black
- Input:  $(x, y)$
- Output: Black or White

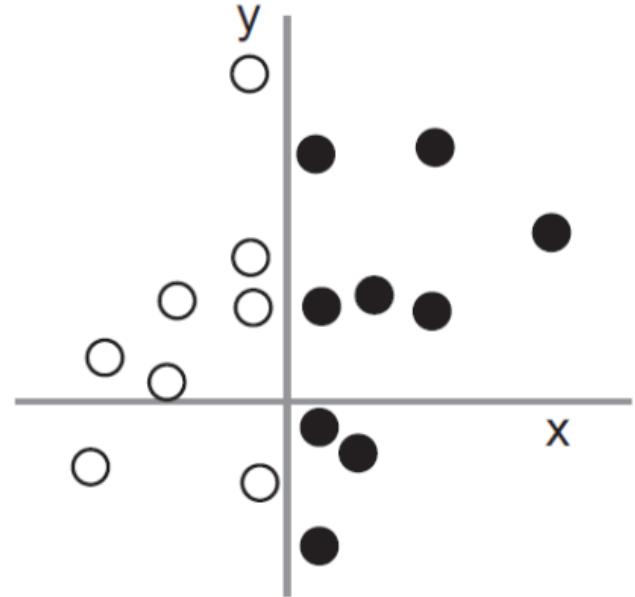
1: Raw data



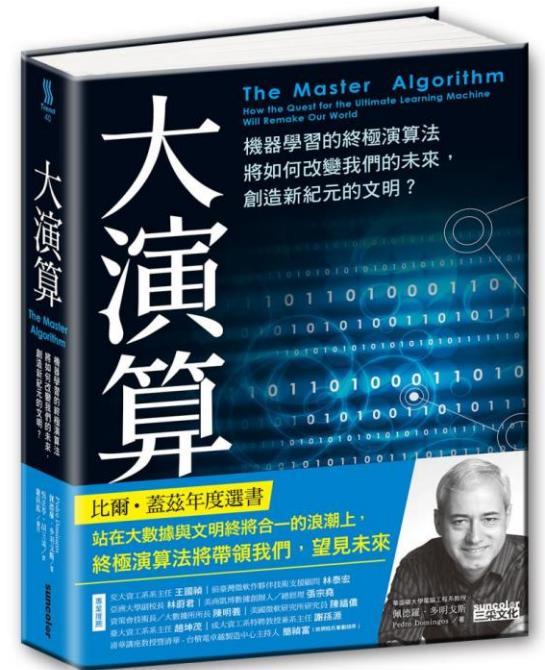
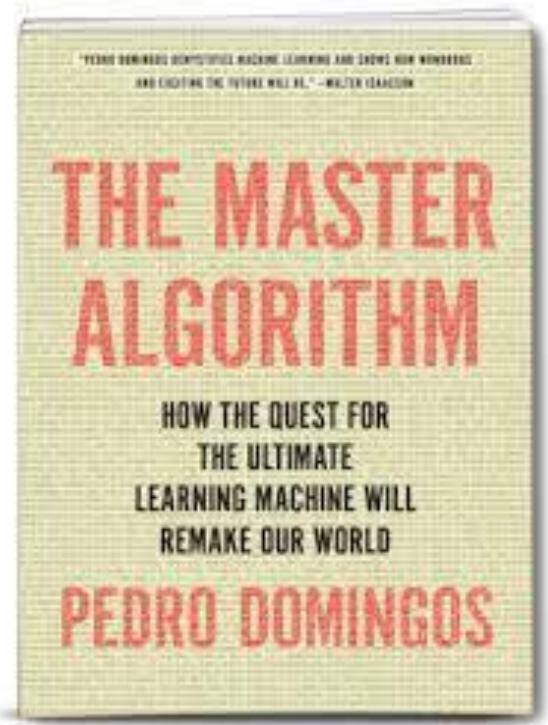
2: Coordinate change

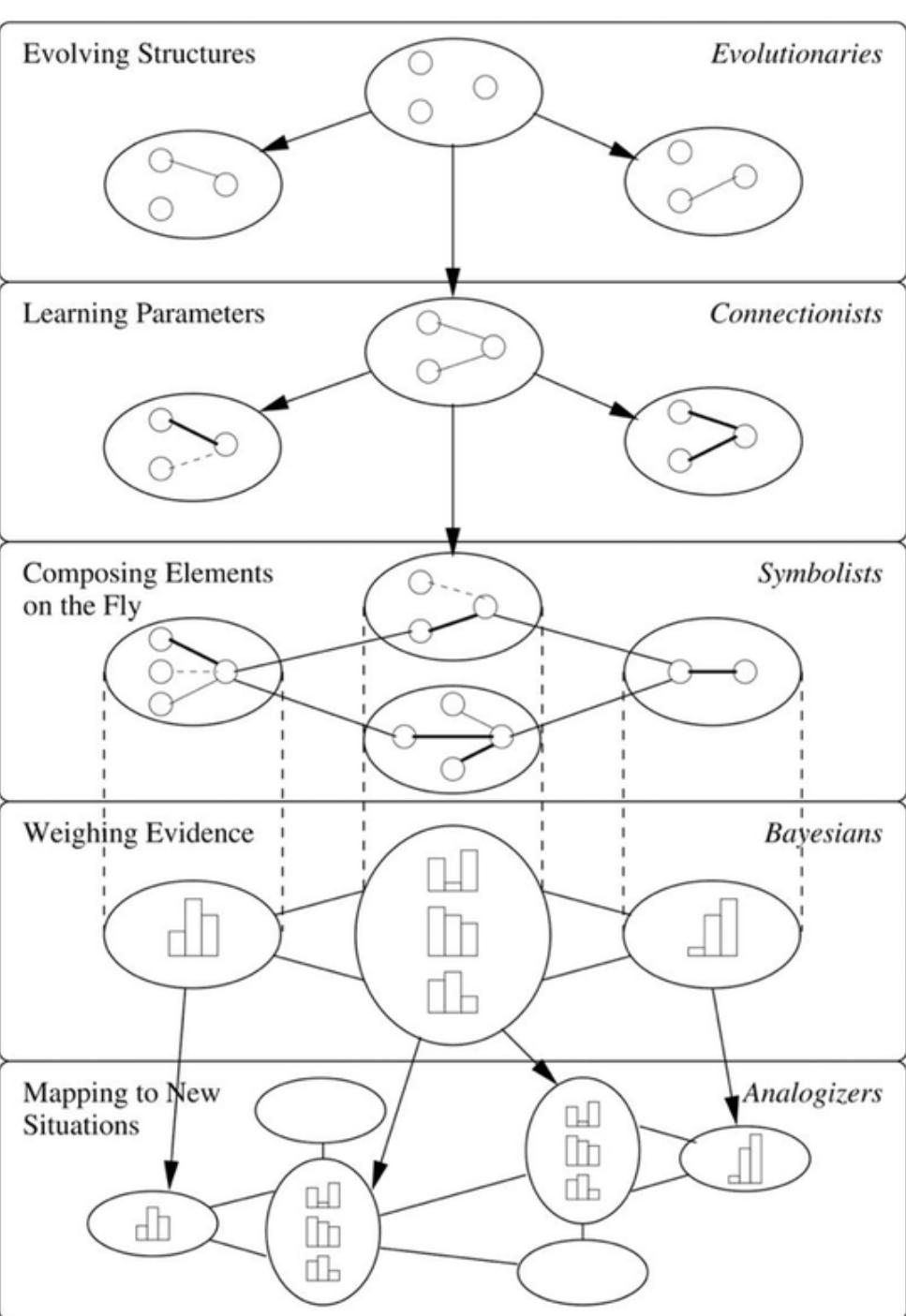


3: Better representation



# The Master Algorithm – Pedro Domingos





# Five Tribes of Machine Learning

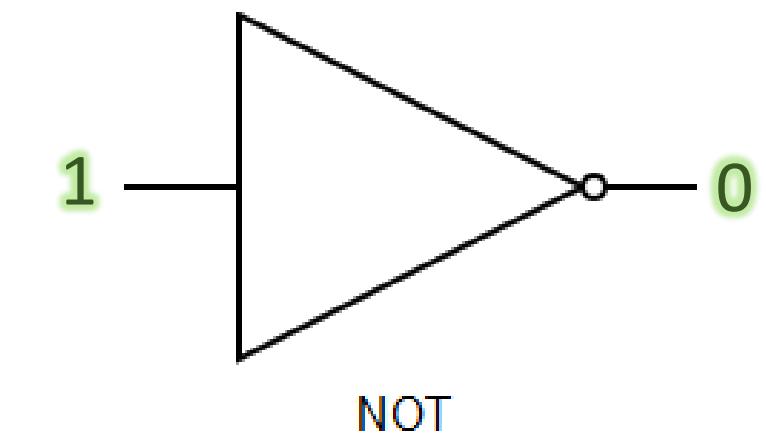
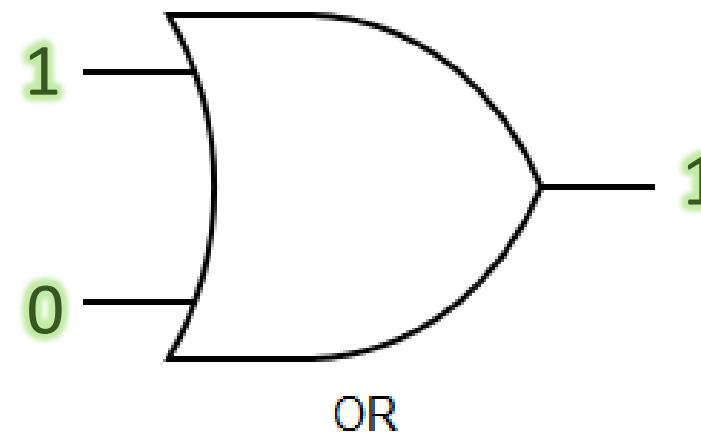
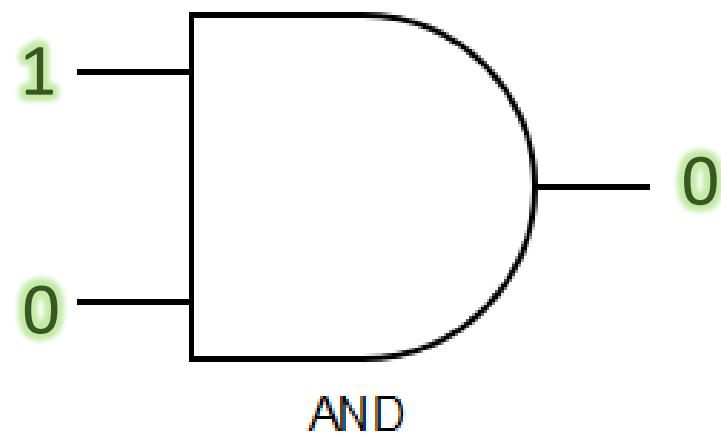
---

- **Evolutionaries** (基因演化法)
- **Connectionists** (類神經網路)
- **Symbolists** (歸納法)
- **Bayesians** (貝氏機率)
- **Analogizers** (類比近似)

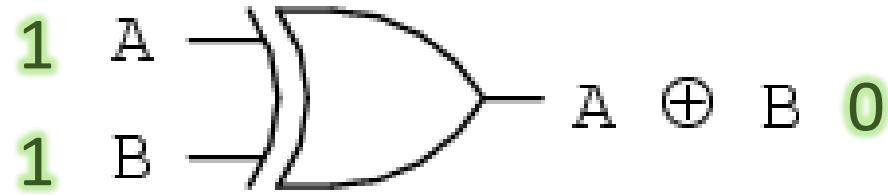
# Five Tribes of Machine Learning

- Symbolists: Decision Trees, Random Forest
- Bayesians: Naïve Bayesians
- Analogizers: SVM, k-NN
- Evolutionaries: Gene algorithms
- Connectionists: Deep Learning

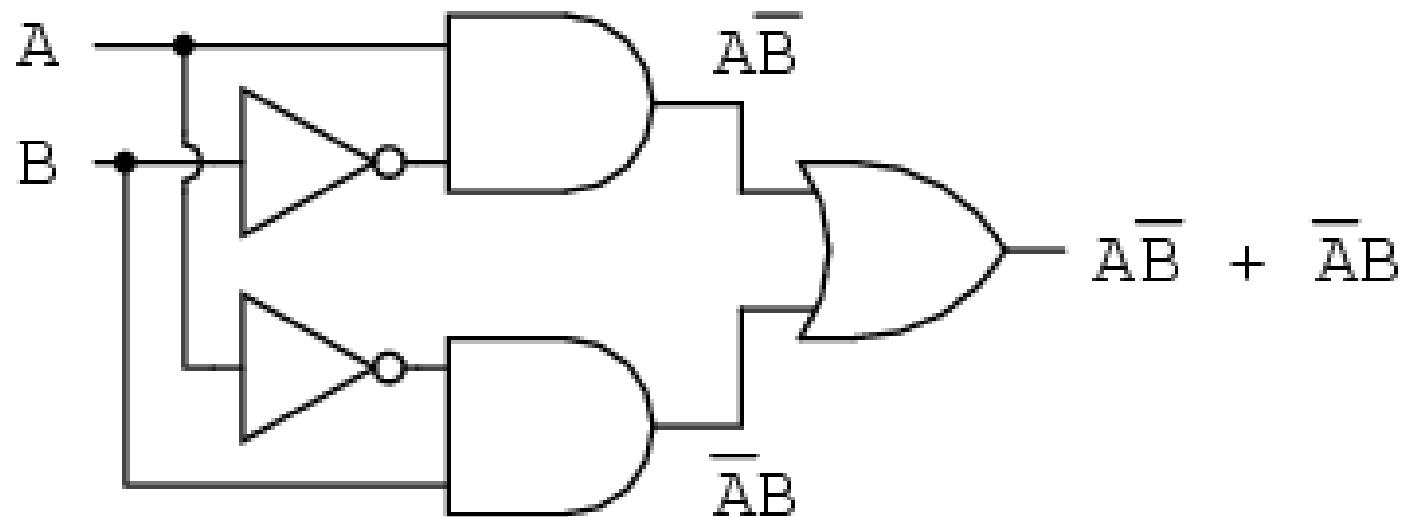
# All Algorithms can be Reduced to 3 Operations



XOR



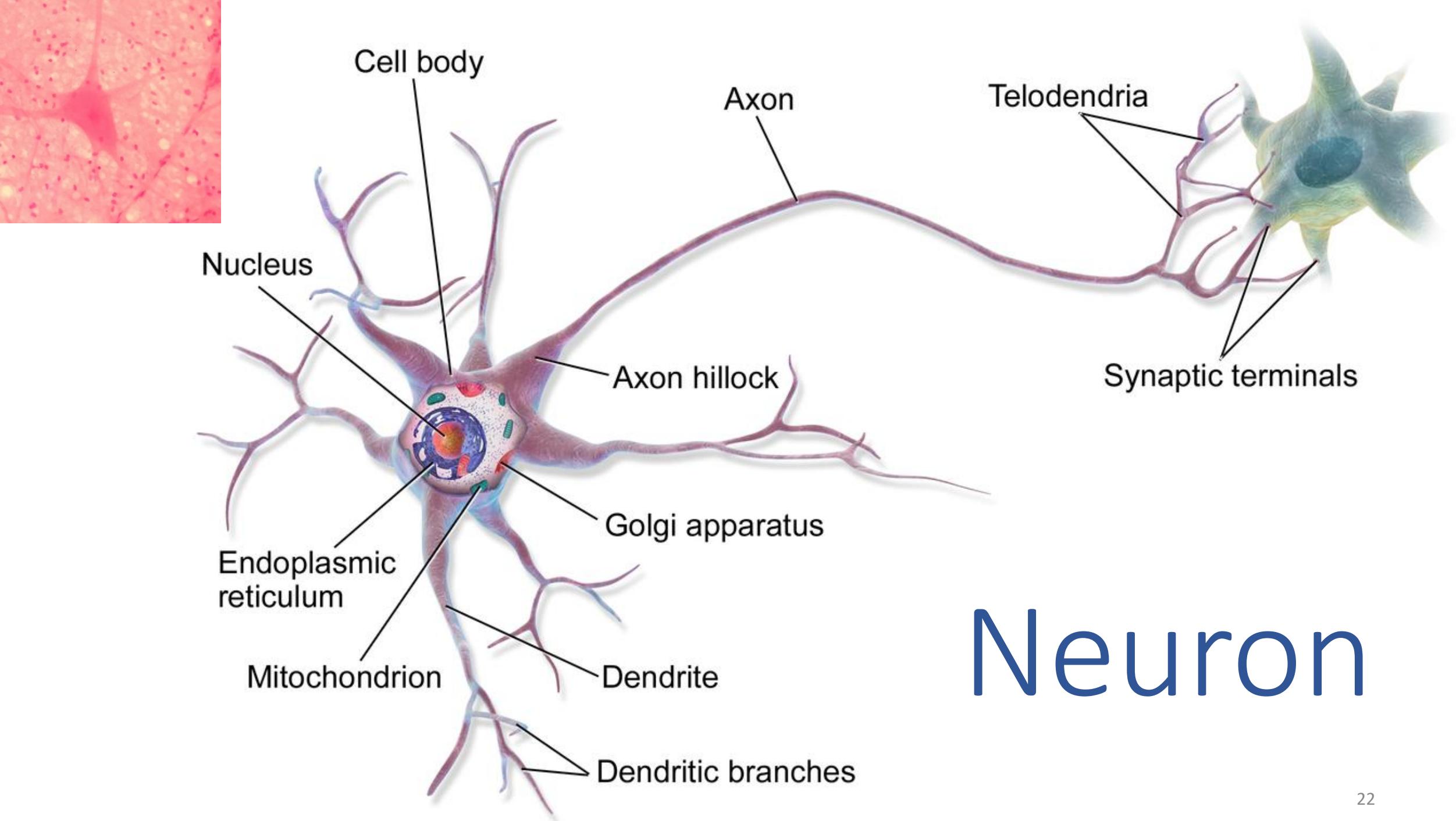
*... is equivalent to ...*



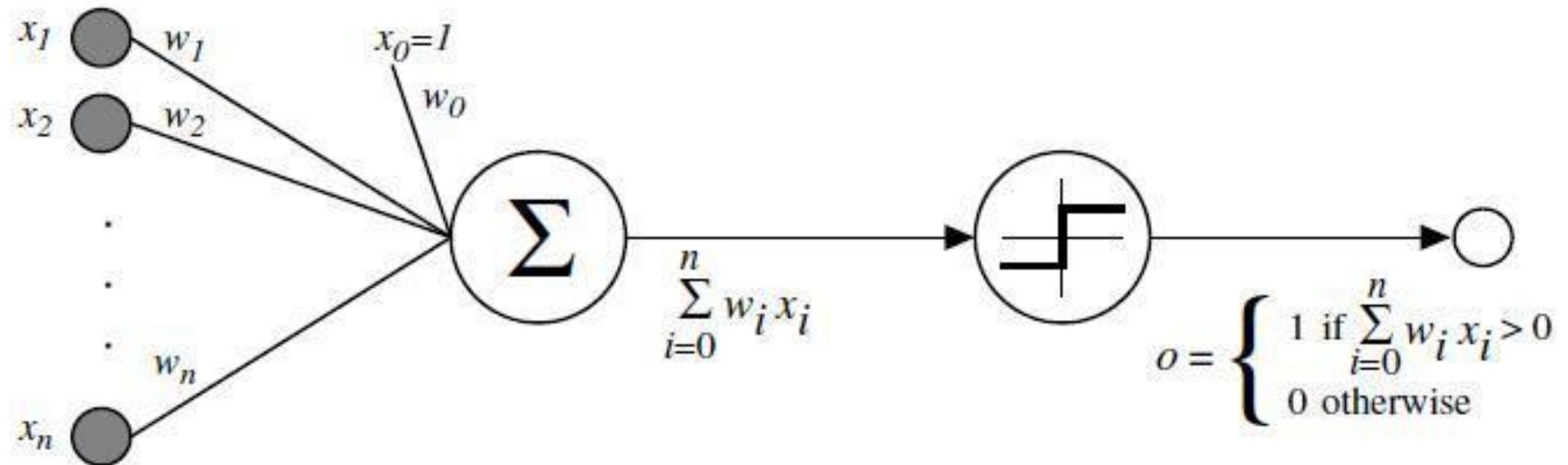
$$A \oplus B = \overline{\overline{AB}} + \overline{AB}$$

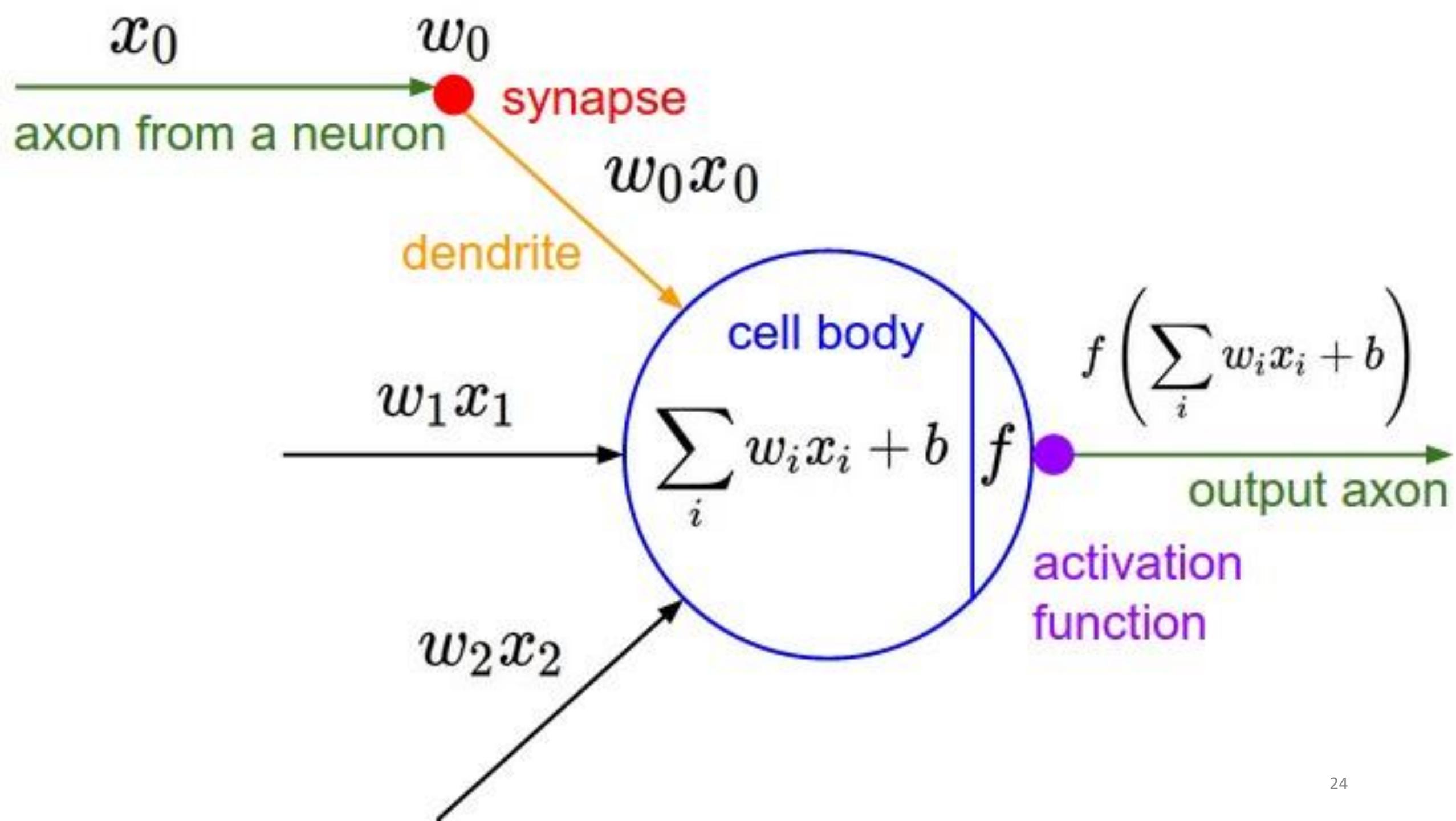
OK, machine learning  
is cool. But what is  
Deep Learning?

# Neural Networks

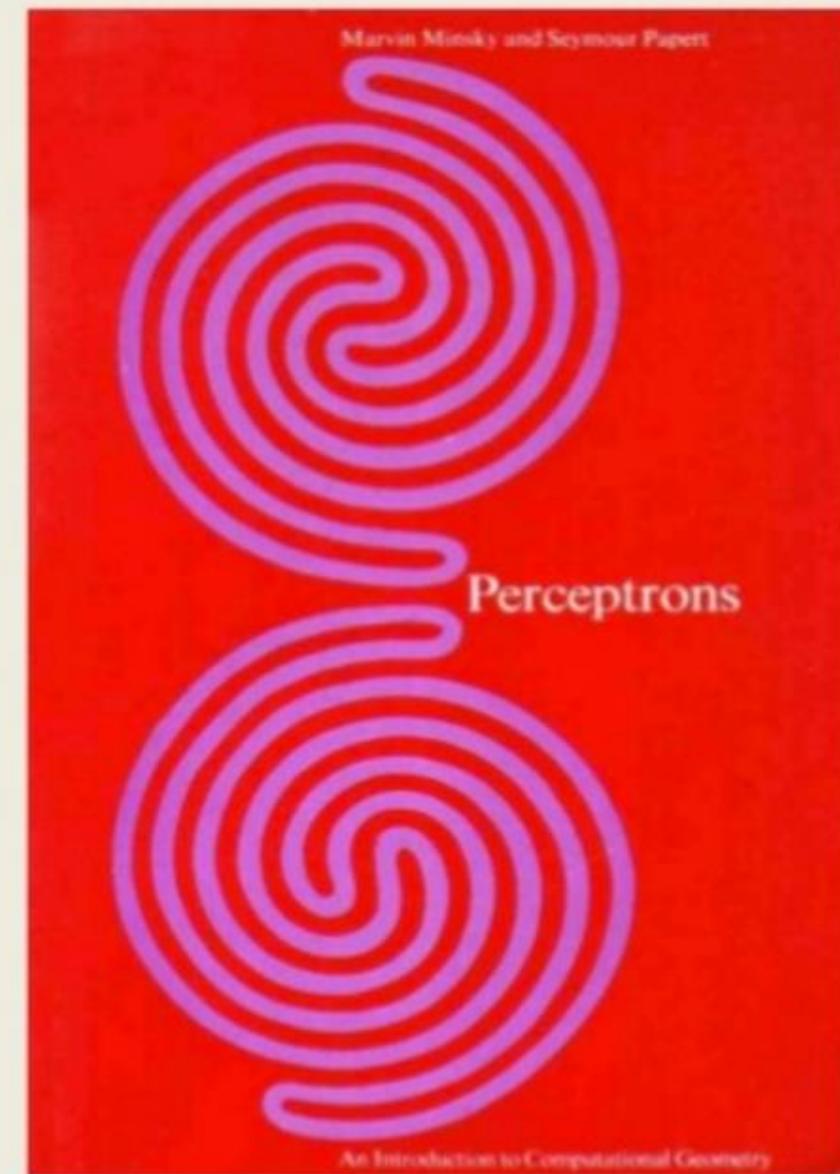


# Frank Rosenblatt's Perceptron (1957)

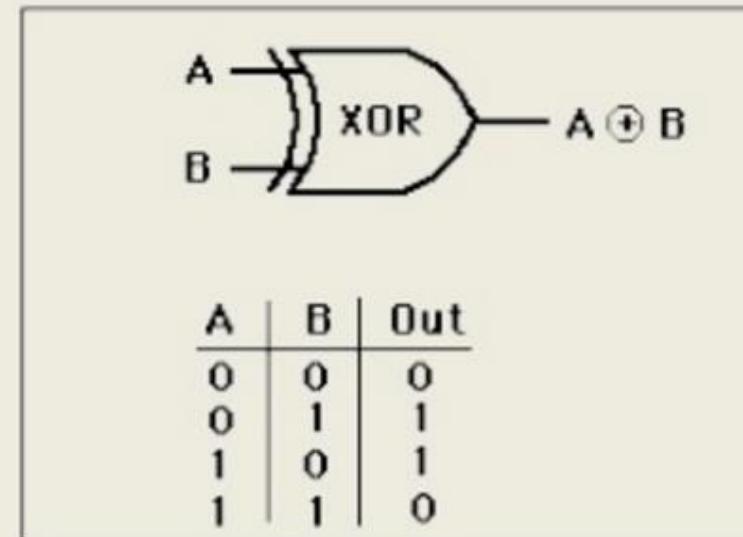




# 1969: Perceptrons can't do XOR!



<http://www.i-programmer.info/images/stories/BabBag/AI/book.jpg>



<http://hyperphysics.phy-astr.gsu.edu/hbase/electronic/ietron/xor.gif>



Minsky & Papert

<https://constructingkids.files.wordpress.com/2013/05/minsky-papert-71-csolomon-x640.jpg>



AI Winter  
1969 - 1990

# Deep Learning



Geoffrey Hinton  
(Toronto, Google)



Yann LeCun  
(New York, Facebook)



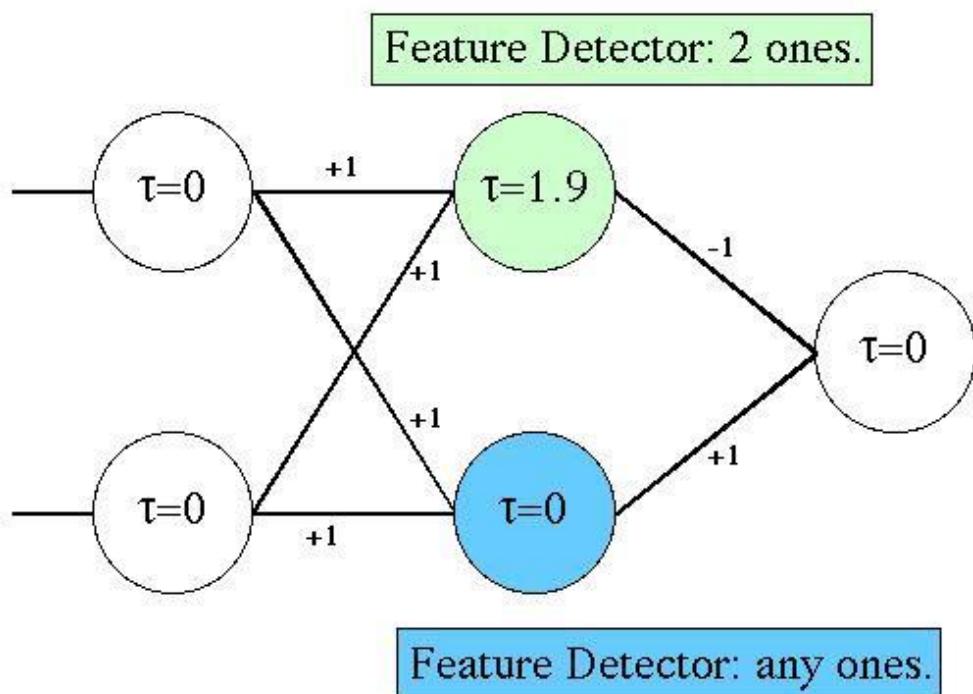
Yoshua Bengio  
(Montreal)  
27



# Learning XOR (1986)

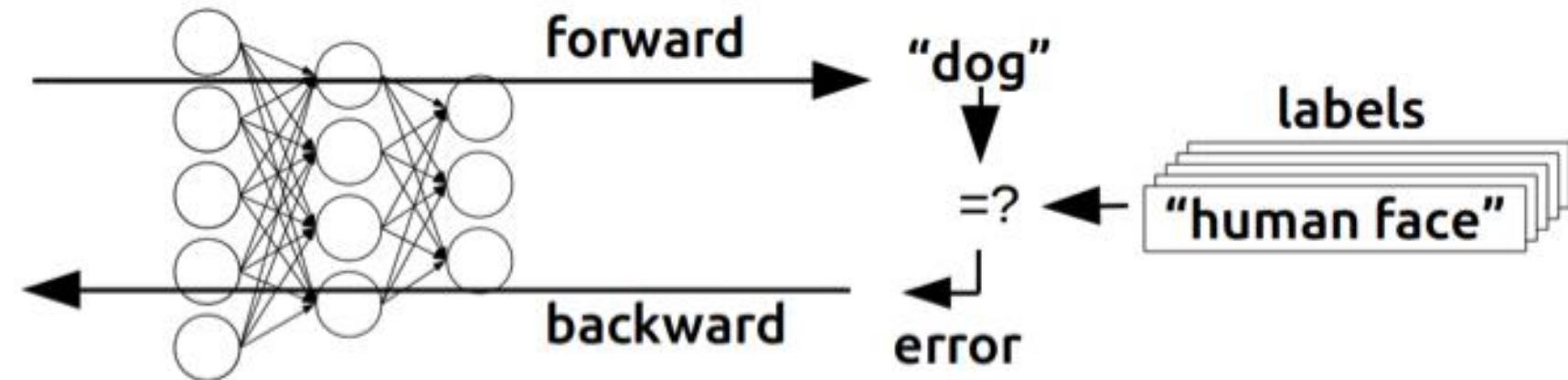
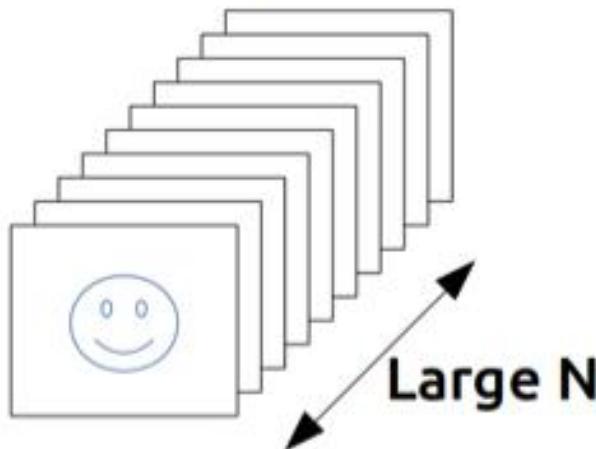
Geoffrey Hinton

## XOR Network

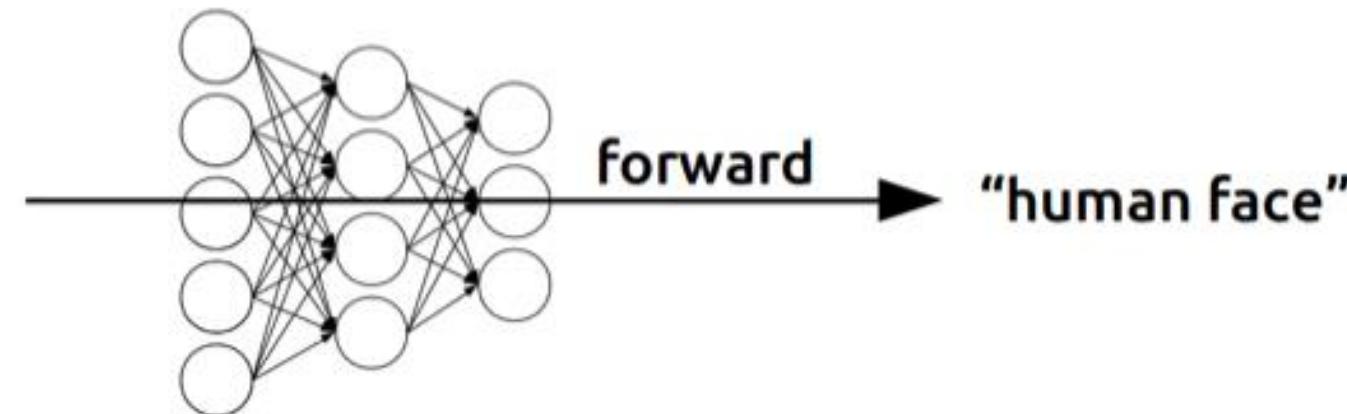
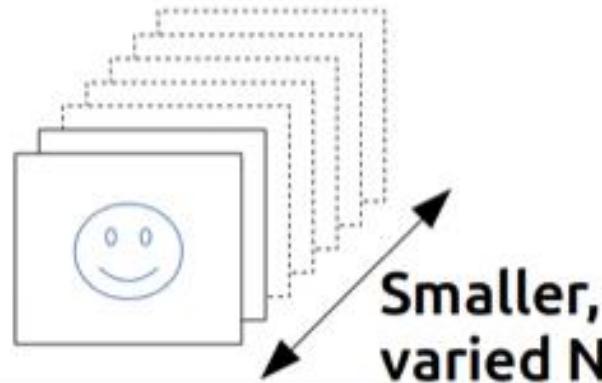


# Backpropagation

## Training



## Inference



# Chain Rule

$$\frac{dy}{dx} = \frac{dy}{du} \frac{du}{dx}$$

$$\frac{d^2y}{dx^2} = \frac{d^2y}{du^2} \left( \frac{du}{dx} \right)^2 + \frac{dy}{du} \frac{d^2u}{dx^2}$$

$$\frac{d^3y}{dx^3} = \frac{d^3y}{du^3} \left( \frac{du}{dx} \right)^3 + 3 \frac{d^2y}{du^2} \frac{du}{dx} \frac{d^2u}{dx^2} + \frac{dy}{du} \frac{d^3u}{dx^3}$$

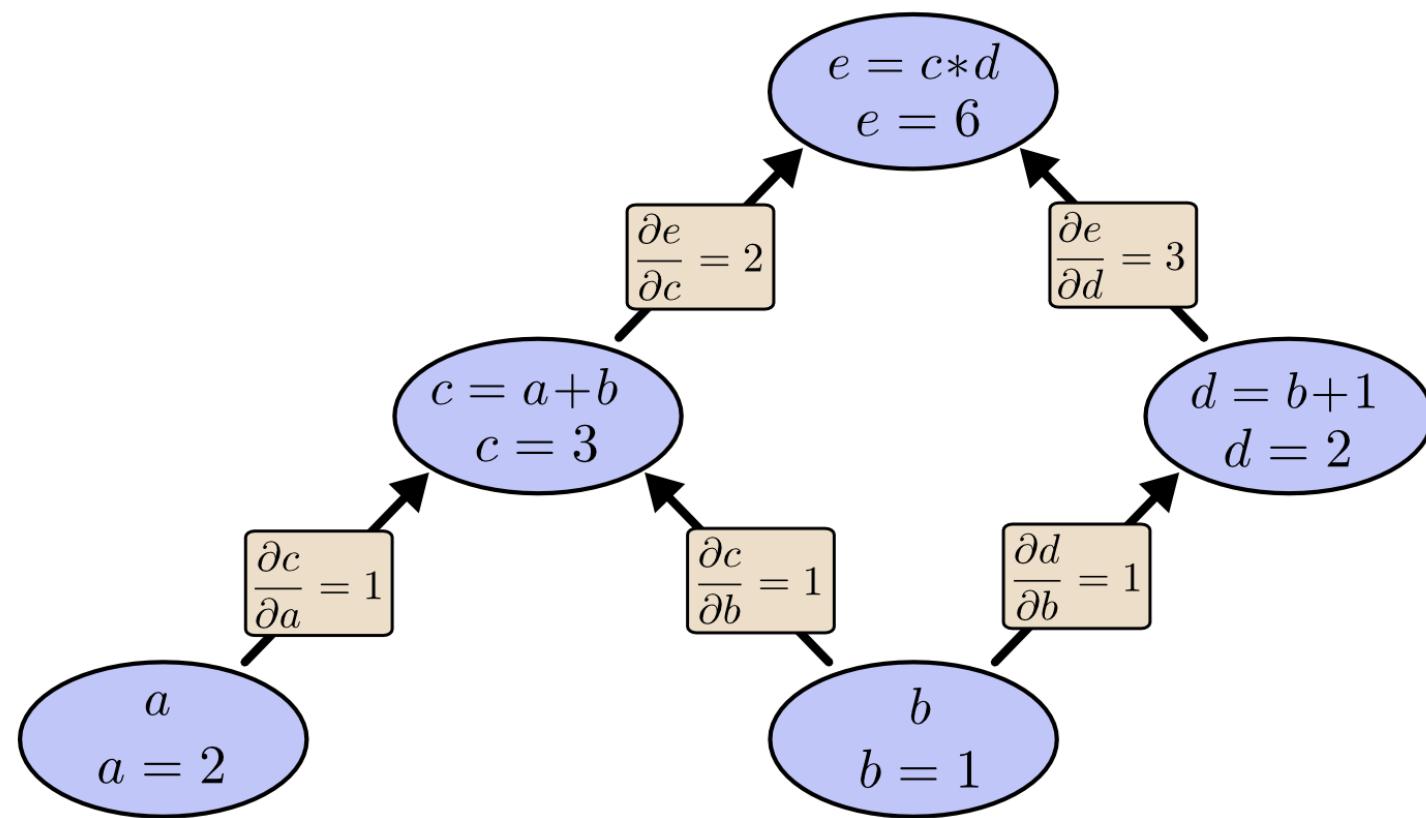
$$\frac{d^4y}{dx^4} = \frac{d^4y}{du^4} \left( \frac{du}{dx} \right)^4 + 6 \frac{d^3y}{du^3} \left( \frac{du}{dx} \right)^2 \frac{d^2u}{dx^2} + \frac{d^2y}{du^2} \left( 4 \frac{du}{dx} \frac{d^3u}{dx^3} + 3 \left( \frac{d^2u}{dx^2} \right)^2 \right) + \frac{dy}{du} \frac{d^4u}{dx^4}.$$

# Computation Graph

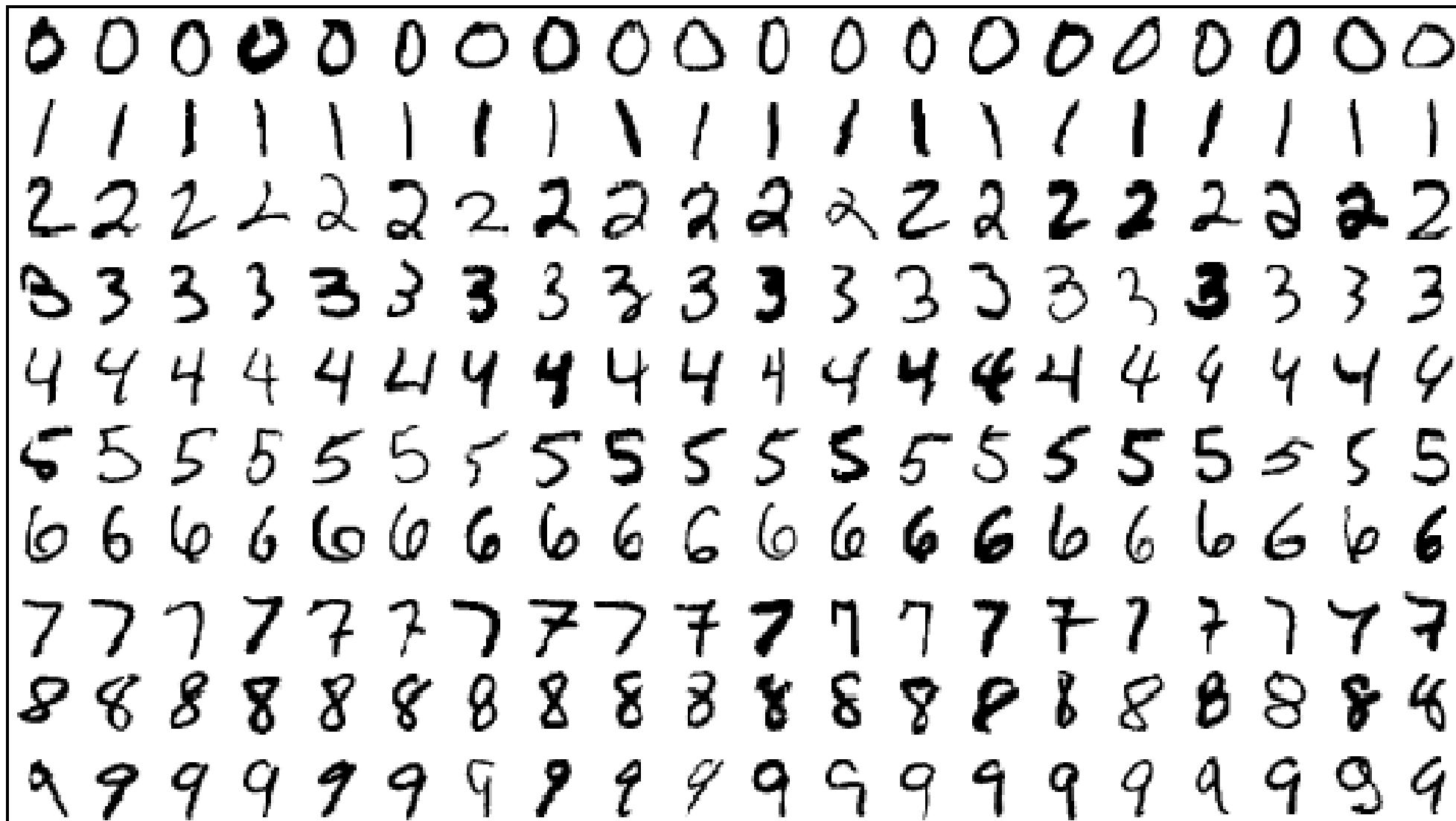
$$c = a + b$$

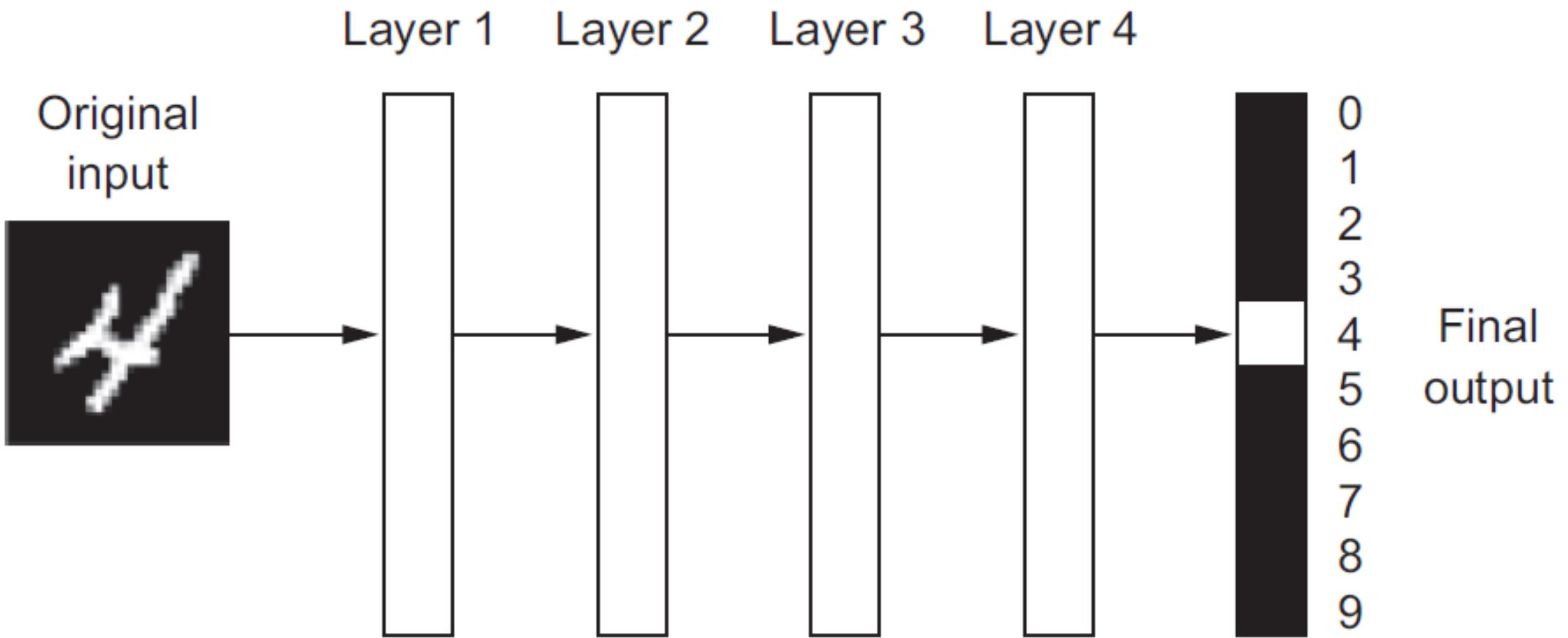
$$d = b + 1$$

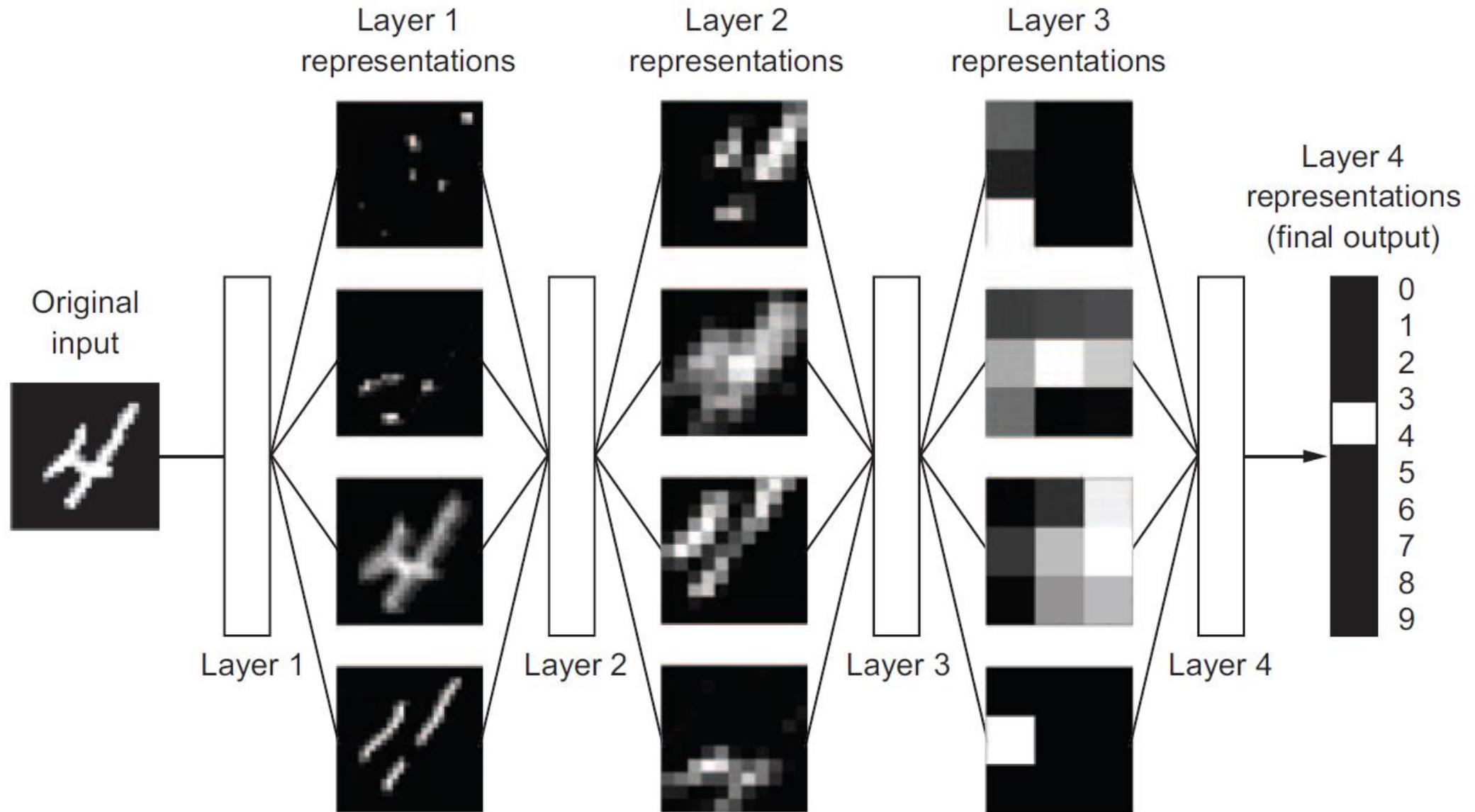
$$e = c * d$$

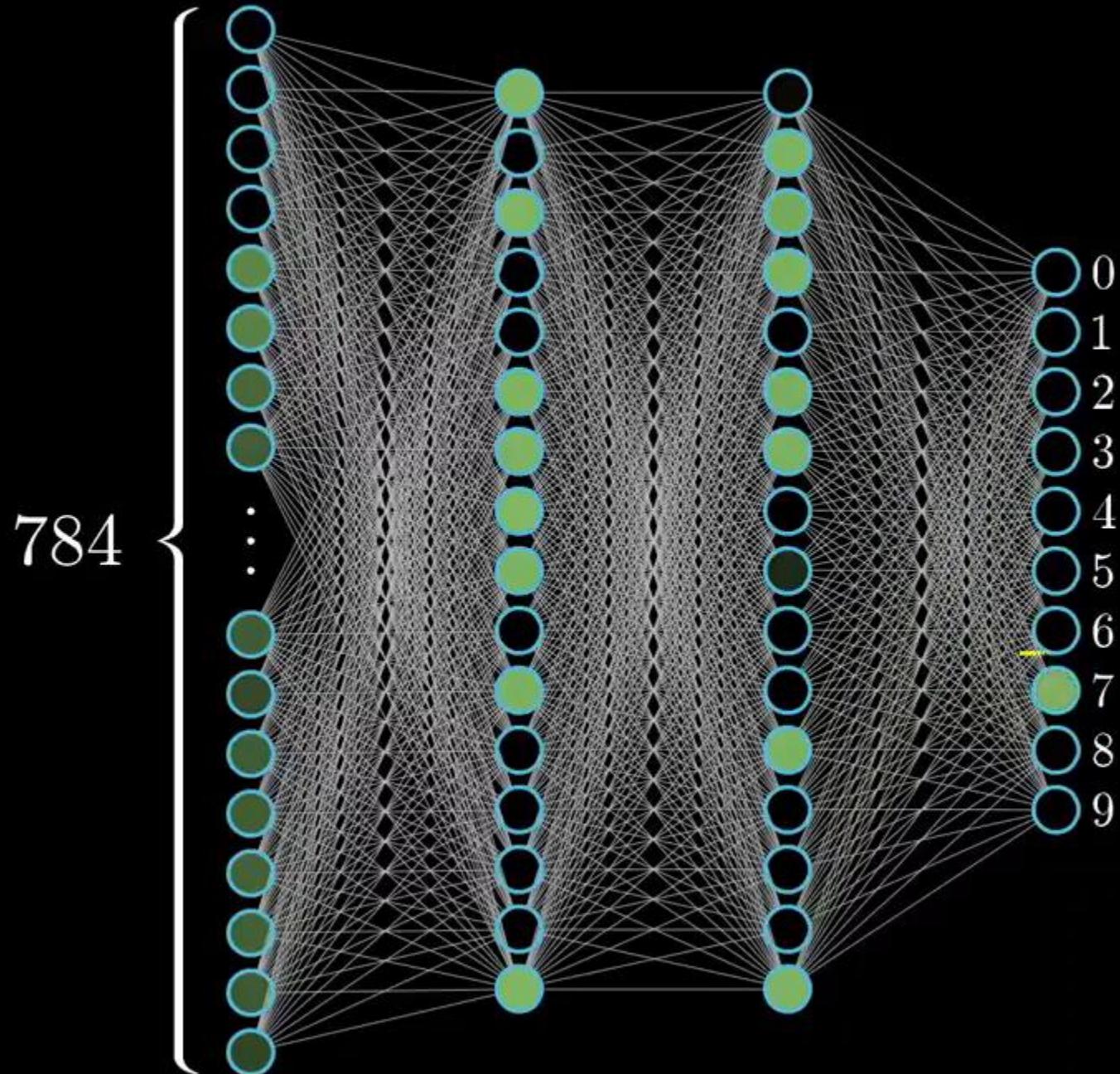


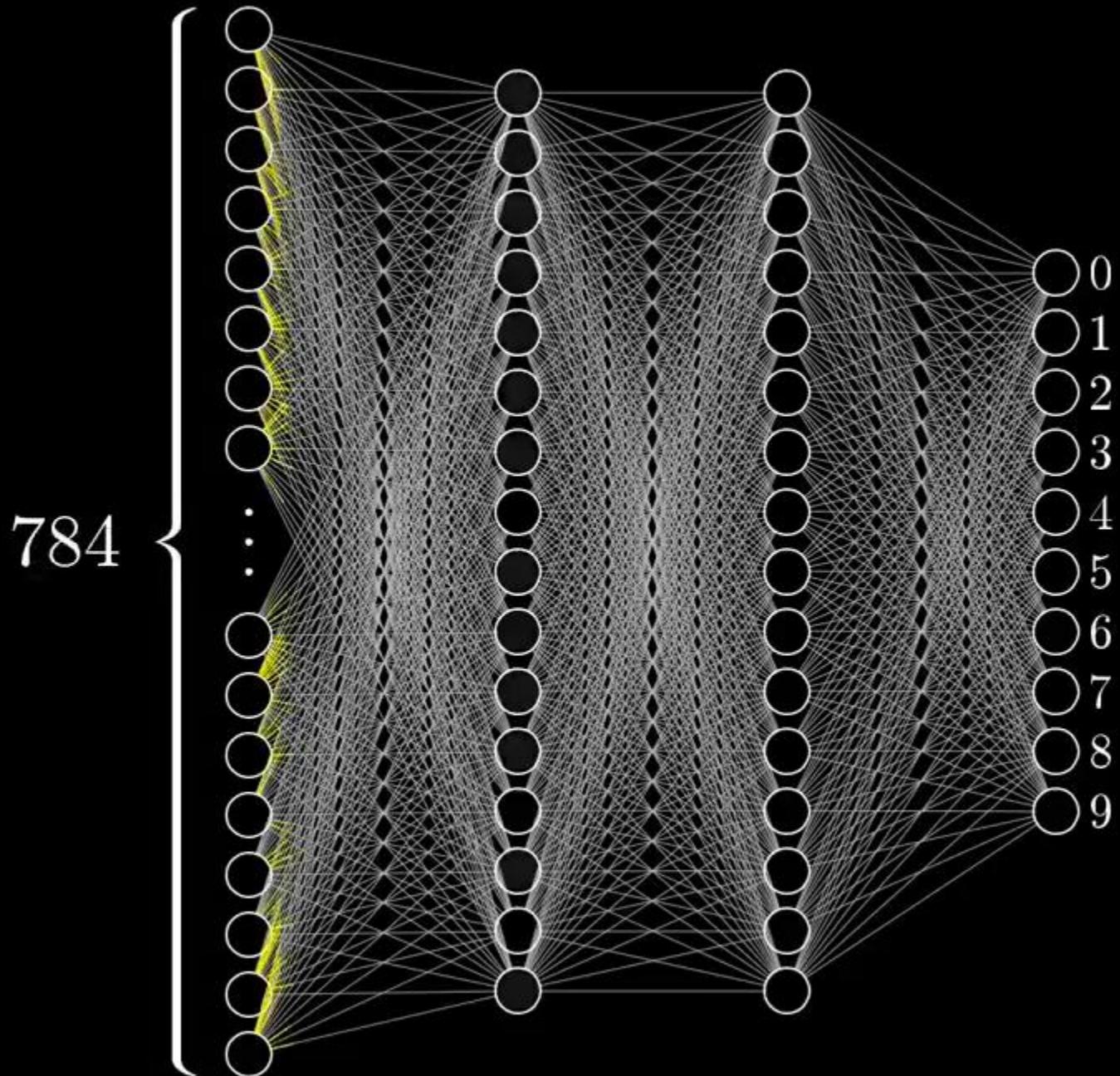
# MNIST database of Handwritten Digits



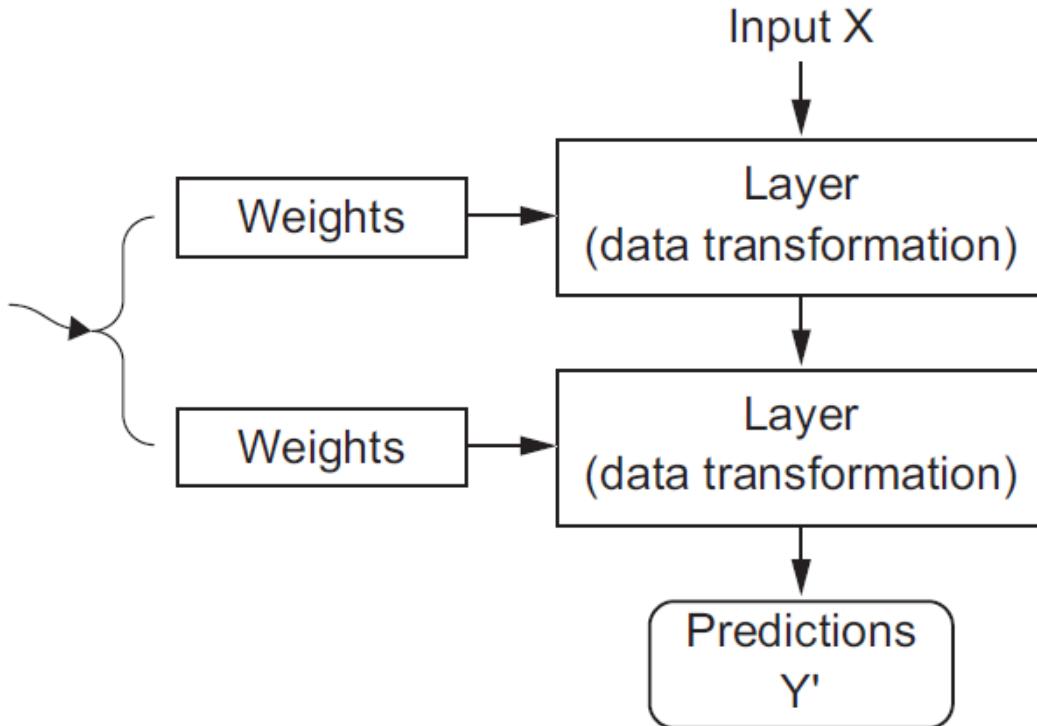


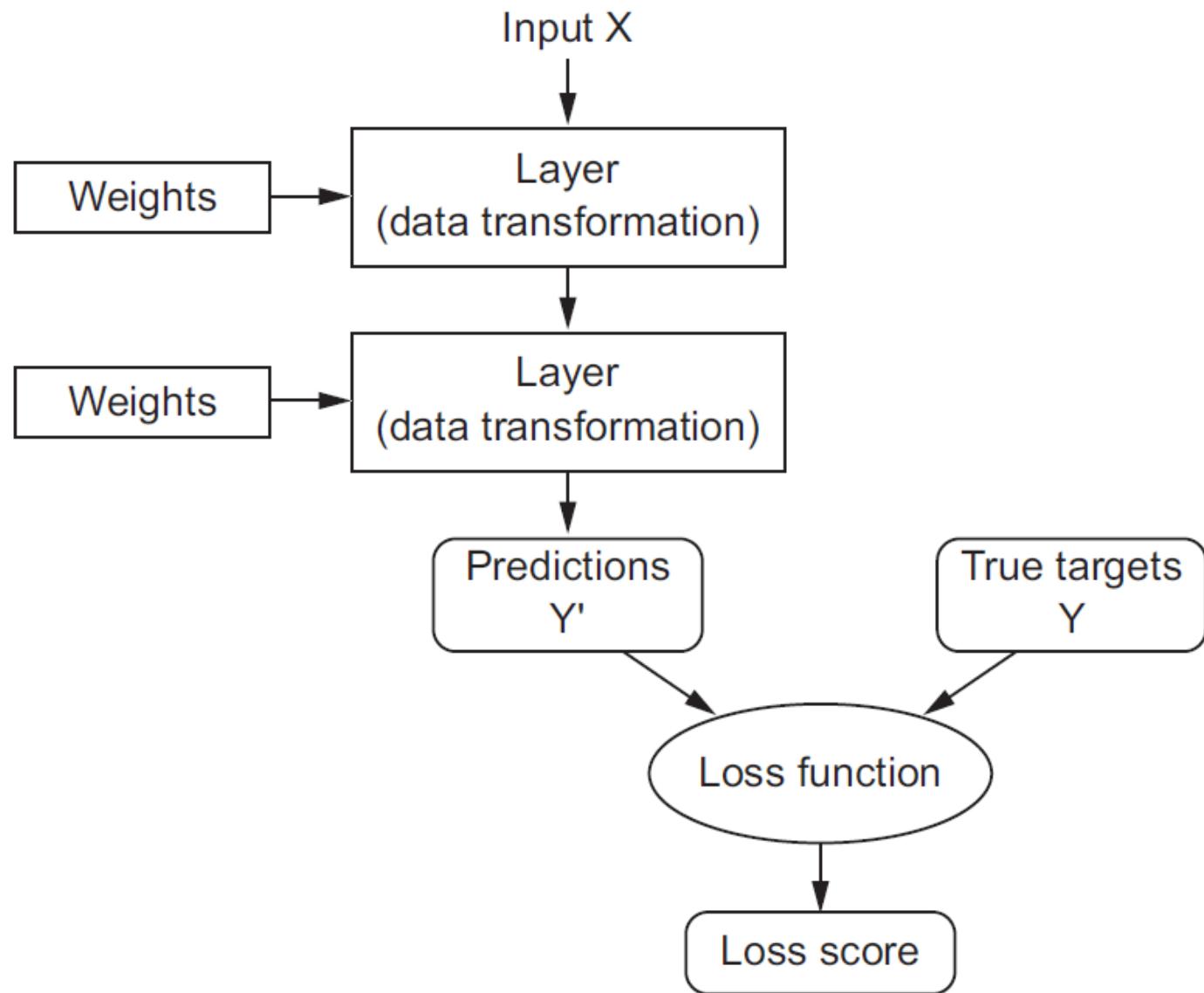


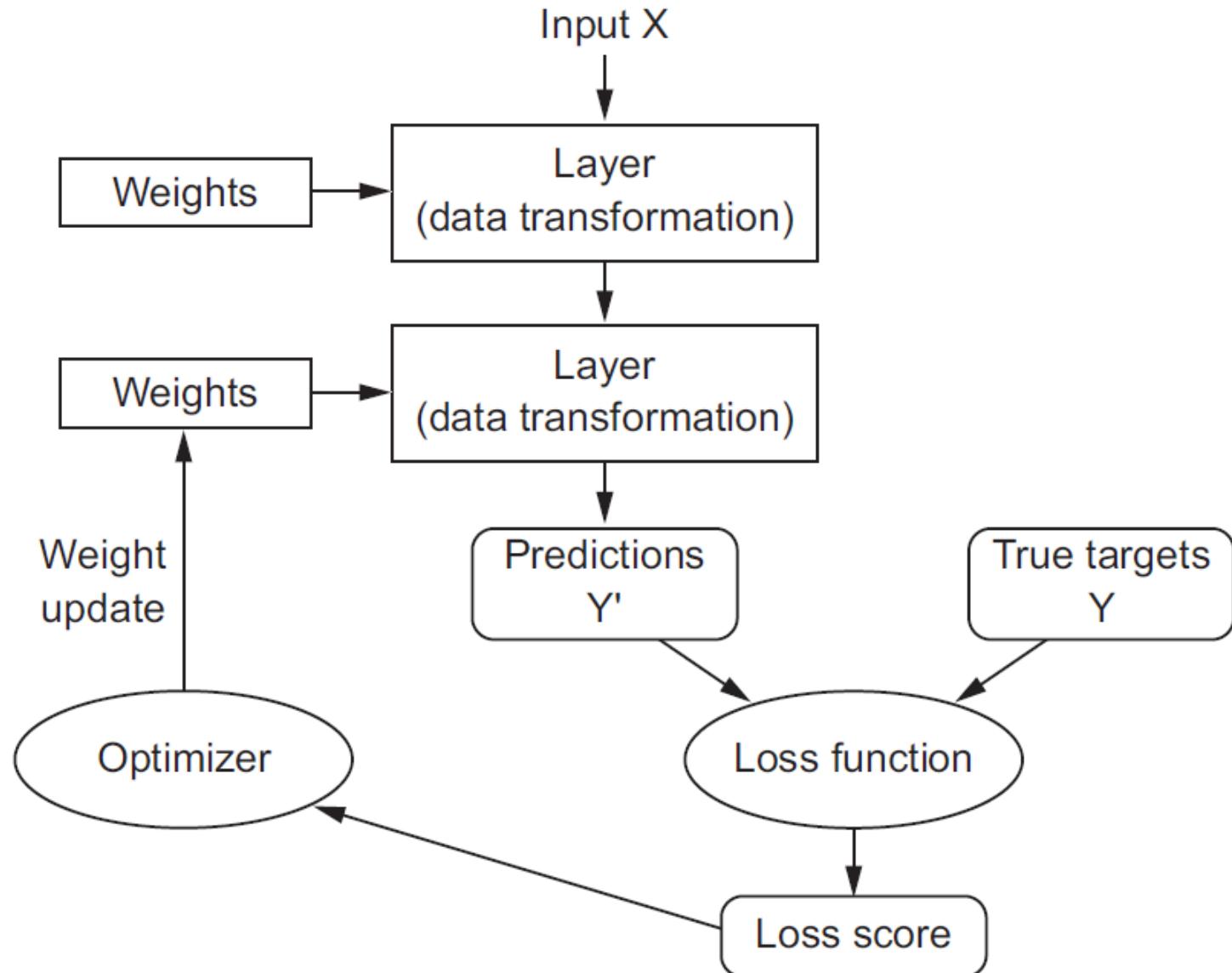




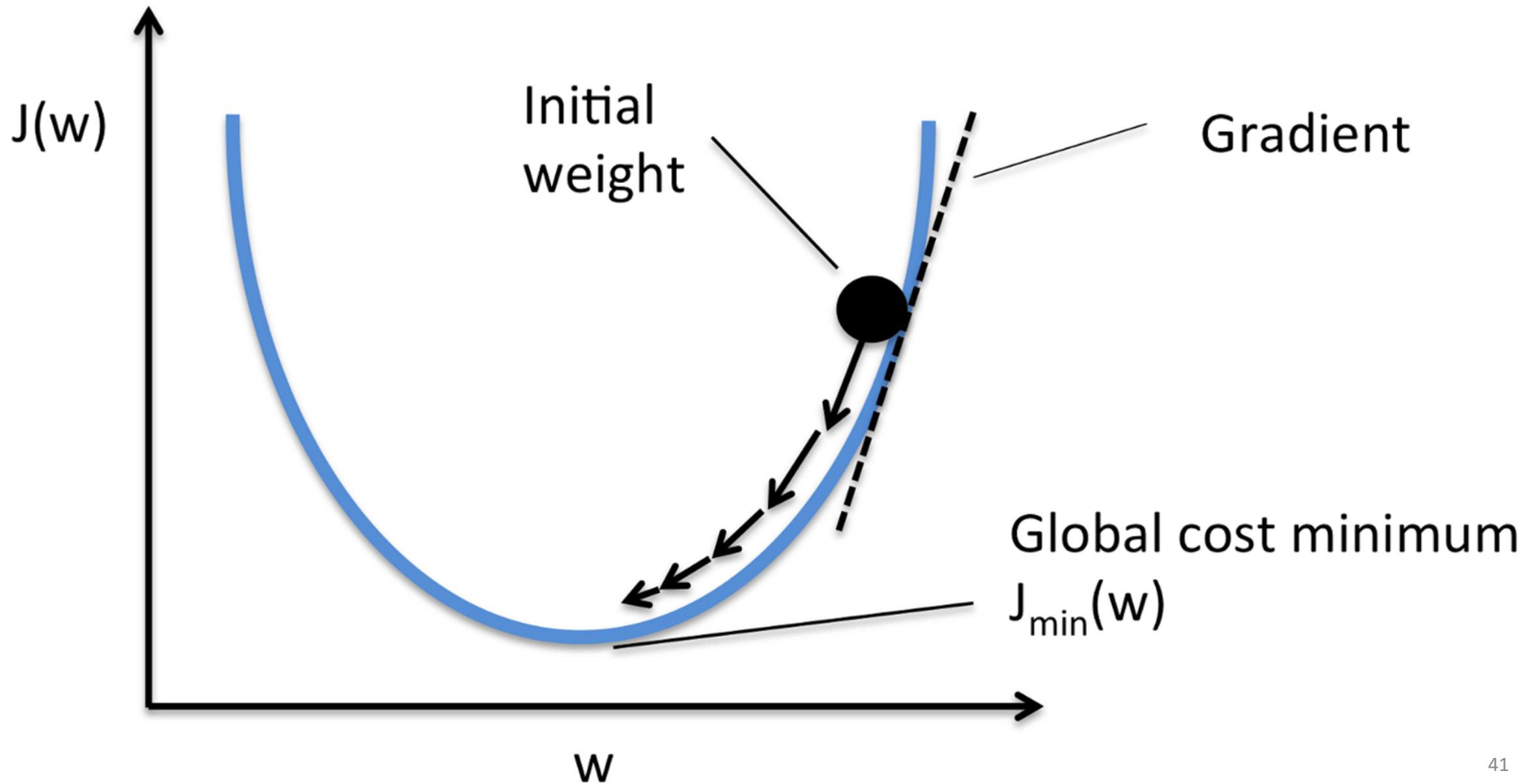
**Goal: finding the right values for these weights**

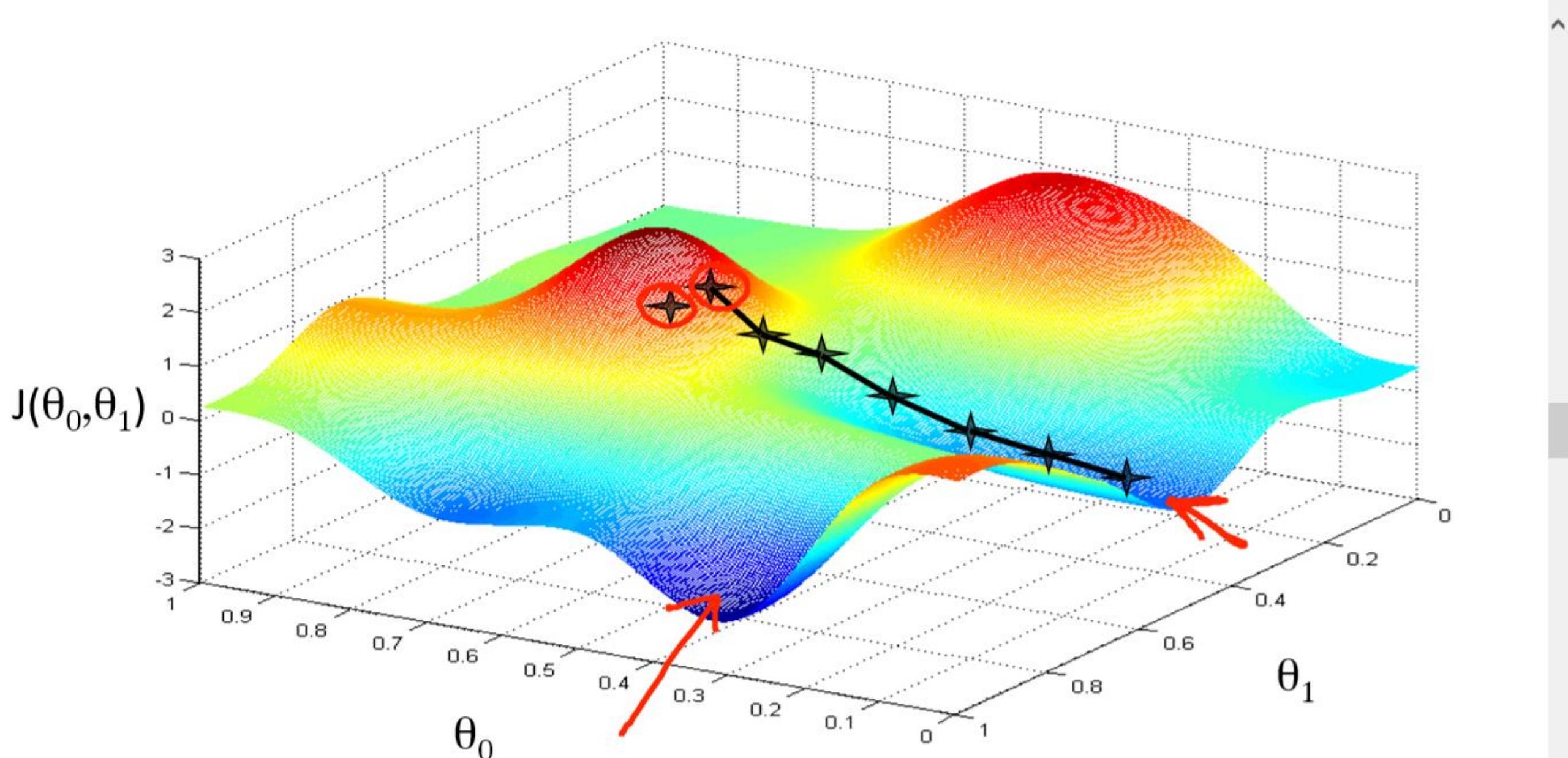






# Gradient Descent





<https://hackernoon.com/gradient-descent-aynk-7cbe95a778da>

# Cost Function

- Mean-Squared Error

$$J(\theta) = \frac{1}{N} \sum_{i=1}^N (f_\theta(x_i) - y_i)^2$$

# Gradient Descent of MSE

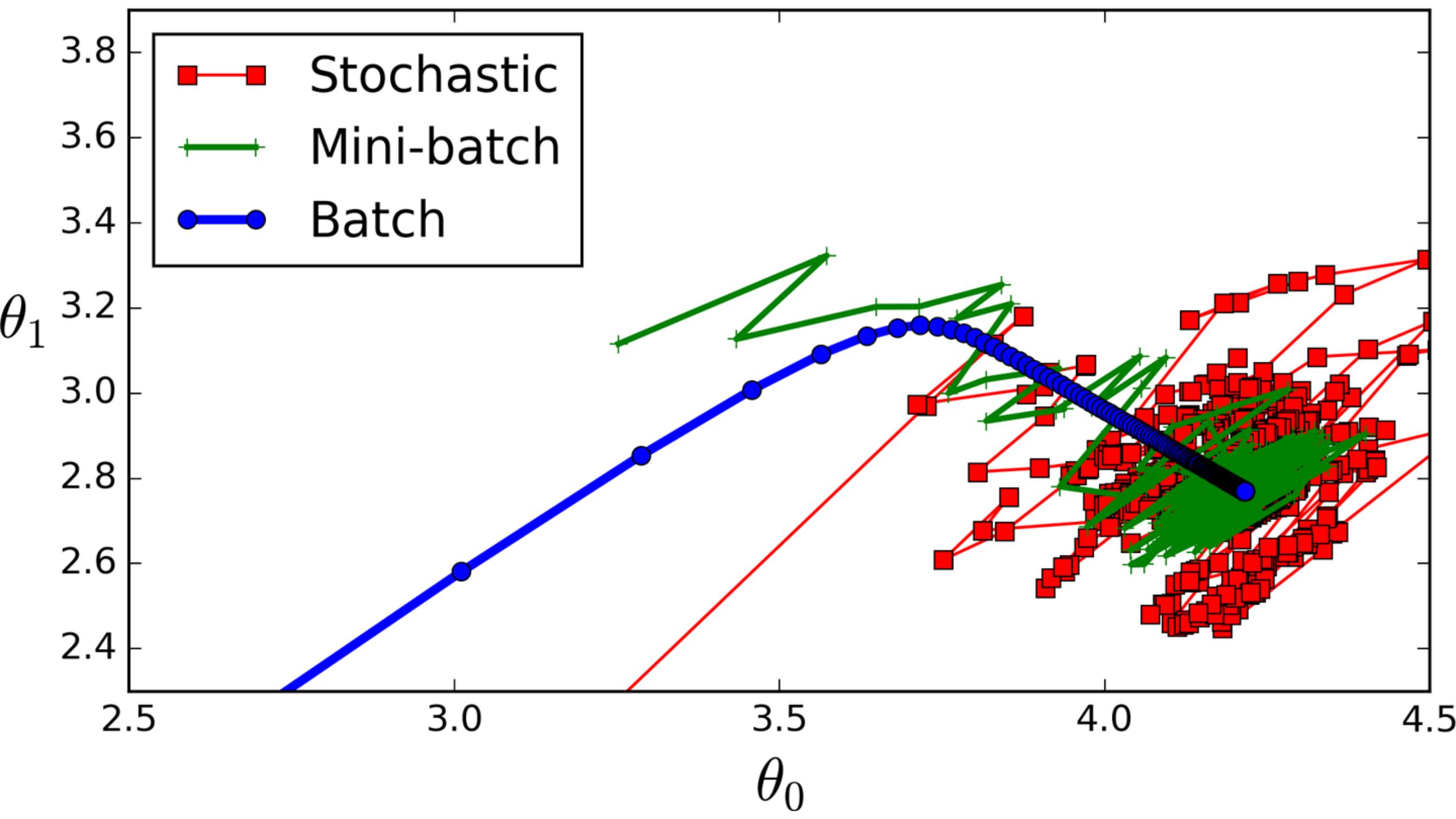
- Gradient of MSE

$$\frac{\partial J(\theta)}{\partial \theta} = \frac{2}{N} \sum_{i=1}^N (f_\theta(x_i) - y_i) f'_\theta(x_i)$$

- Update

$$\theta_j \leftarrow \theta_j - \alpha \frac{\partial J(\theta)}{\partial \theta_j}$$

- Repeat until Convergence

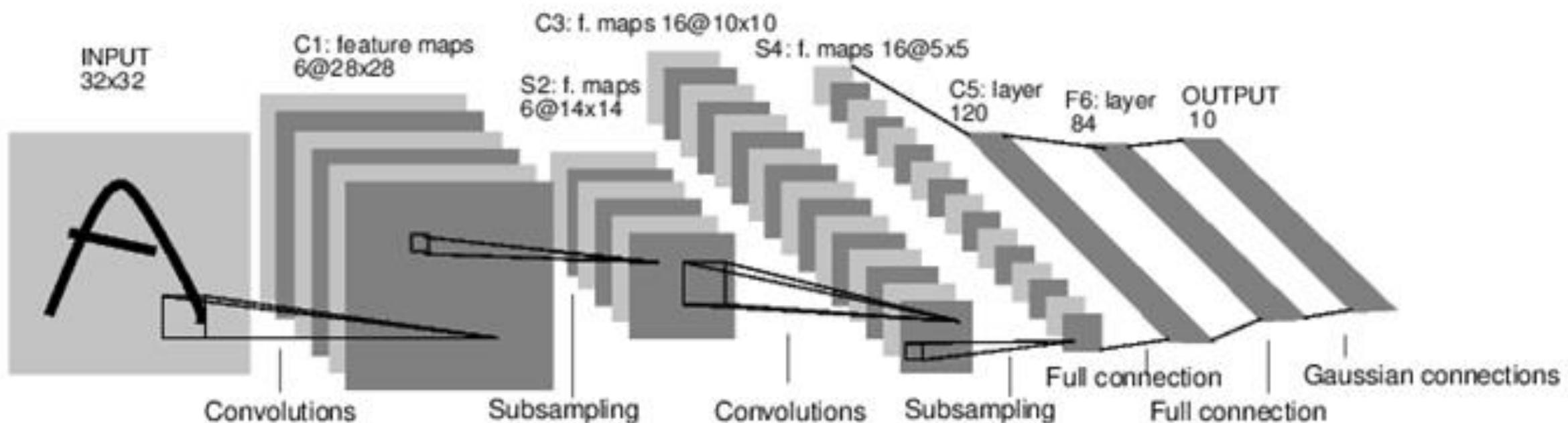


## Cost function

$$C(\underbrace{w_1, w_2, \dots, w_{13,002}}_{\text{Weights and biases}})$$

# Convolutional Neural Network (LeNet-5)

- <https://medium.com/@sh.tsang/paper-brief-review-of-lenet-1-lenet-4-lenet-5-boosted-lenet-4-image-classification-1f5f809dbf17>



A Full Convolutional Neural Network (LeNet)

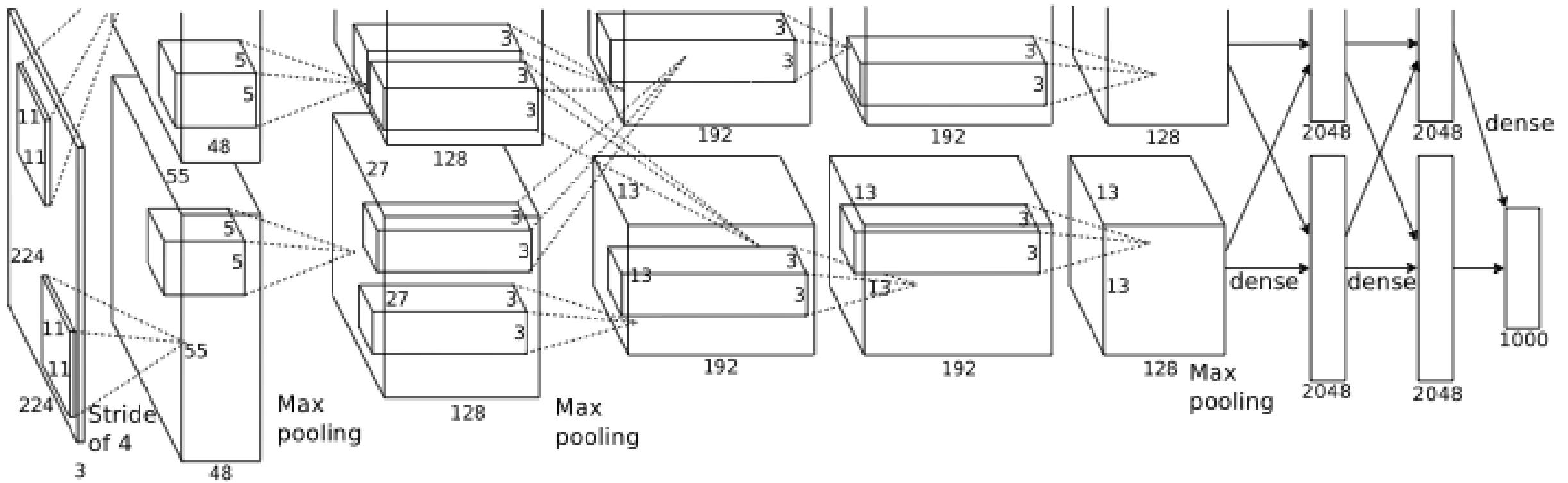


# ImageNet Large Scale Visual Object Recognition Challenge (ILSVRC)

- 1000 categories
- For ILSVRC 2017
  - Training **images** for each category ranges from 732 to 1300
  - 50,000 validation **images** and 100,000 test **images**.
- Total number of images in ILSVRC 2017 is around 1,150,000

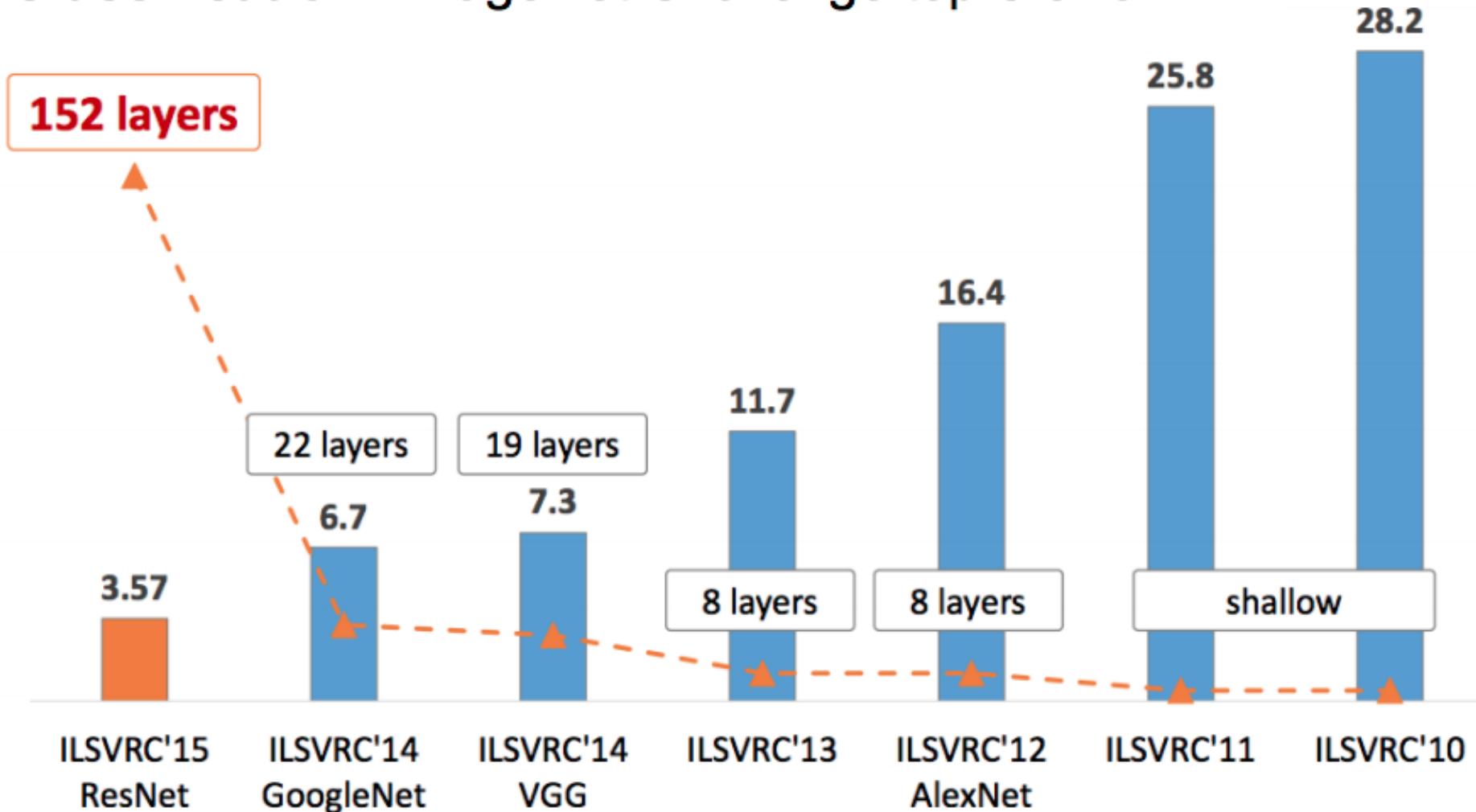
# Convolutional Neural Network

- Alex Krizhevsky, Geoffrey Hinton et al., 2012



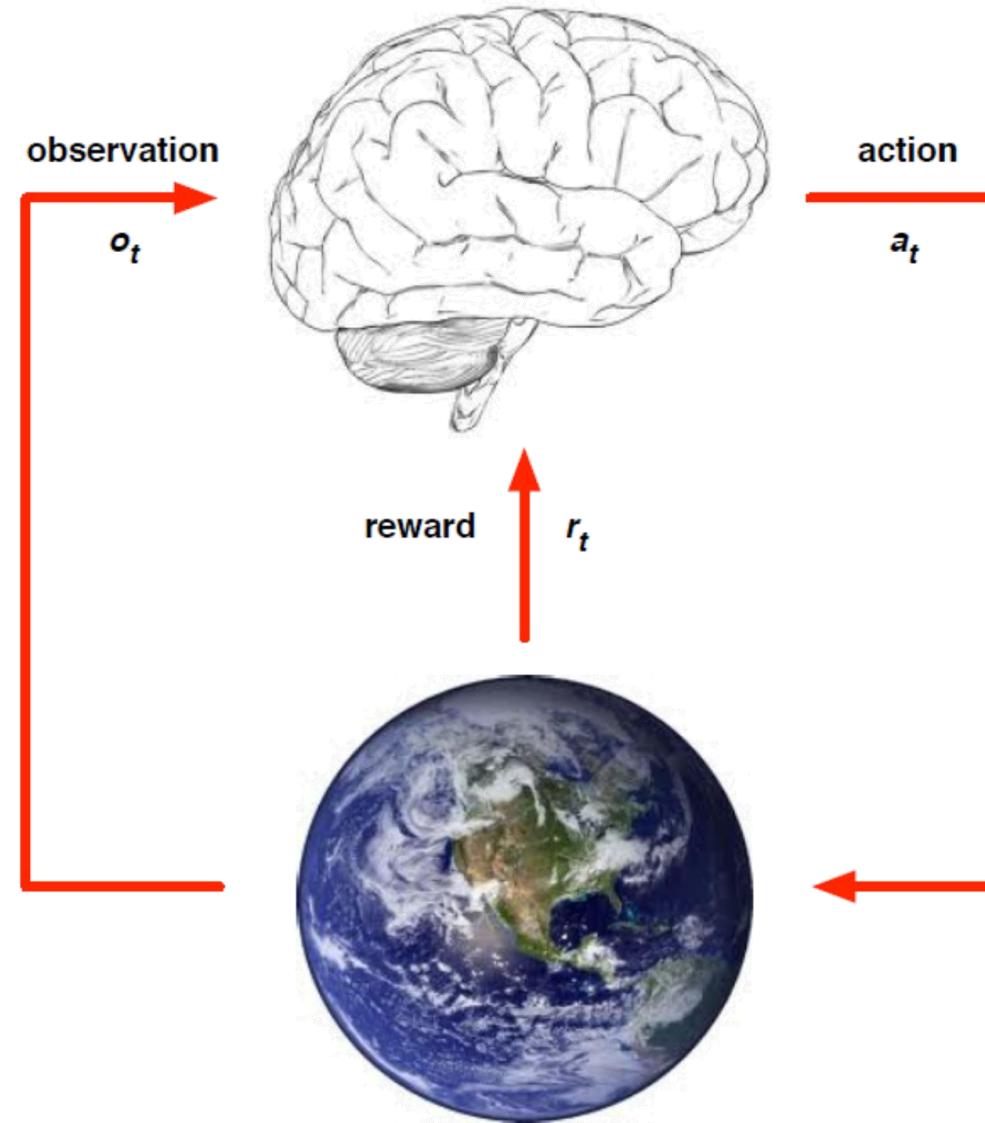
# Previous Winners of ILSVRC

**Classification: ImageNet Challenge top-5 error**



# Deep Reinforcement Learning

# Reinforcement Learning



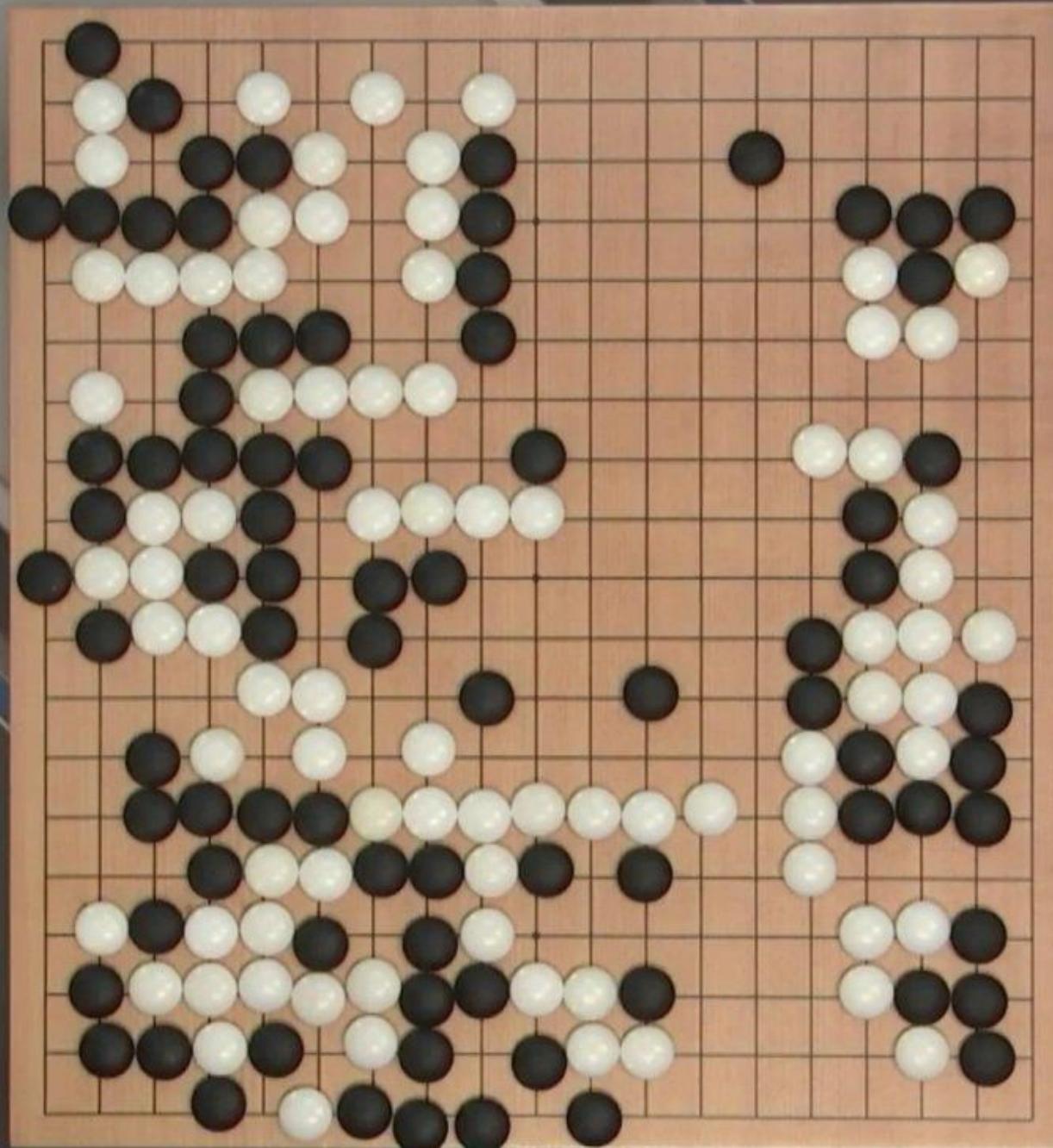


Google DeepMind



ALPHAGO  
00:10:29

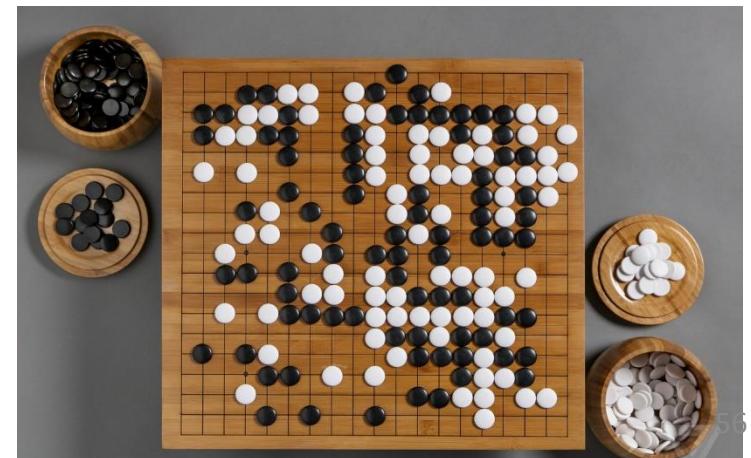
  
AlphaGo  
Google DeepMind



LEE SEDOL  
00:01:00

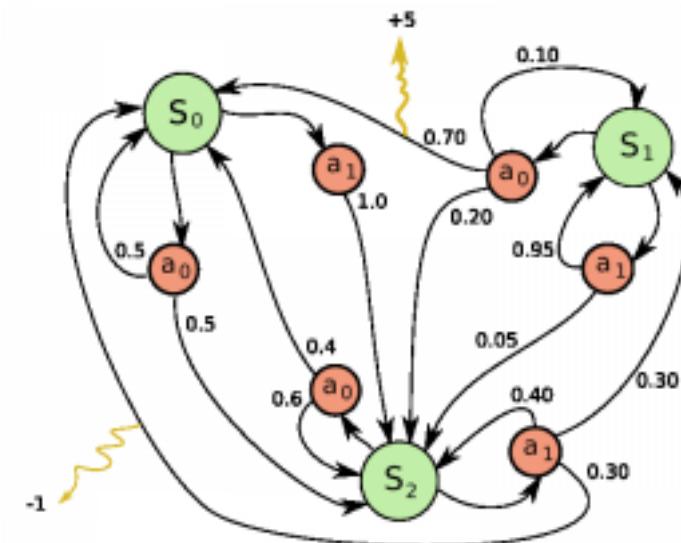
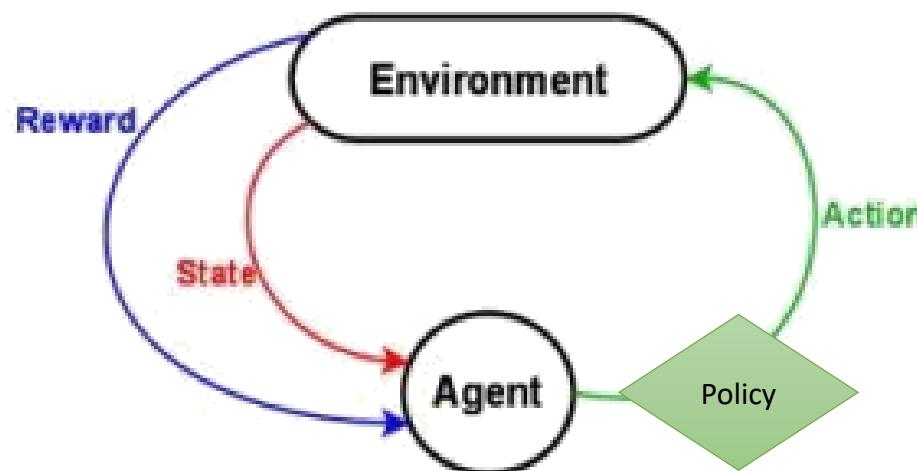
# The Complexity of Go vs Chess

<b>Game</b>	<b>Board size</b>	<b>State space</b>	<b>Game tree size</b>
Go	19 x 19	$10^{172}$	$10^{360}$
Chess	8 x 8	$10^{50}$	$10^{123}$
Checkers	8 x 8	$10^{18}$	$10^{54}$



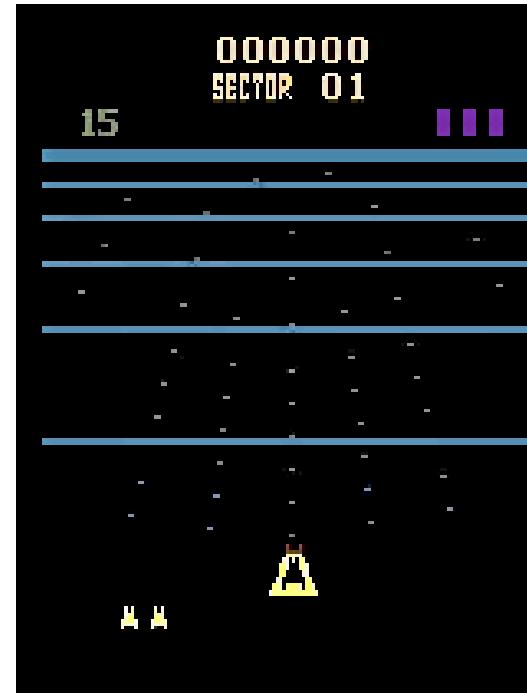
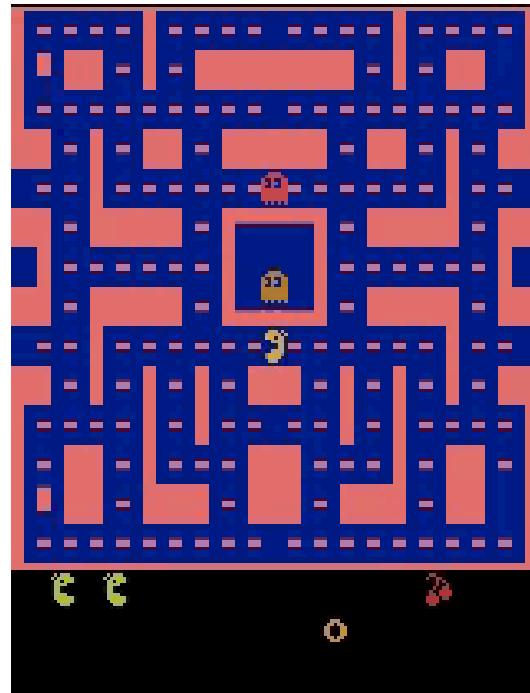
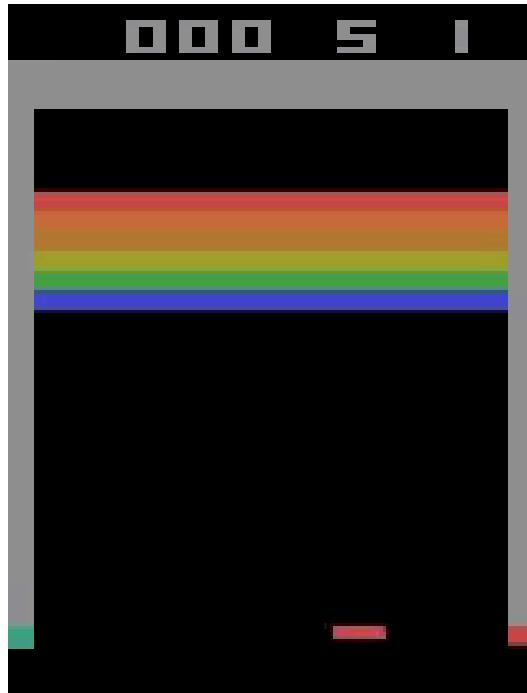
# Reinforcement Learning

- An agent learns how to do actions  $a_t$  to achieve maximum reward  $R$
- Policy  $\pi(a_t|s_t)$ : agent's behavior function
- Value function  $V$ : evaluate quality of each action/state
- Model: agent's representation of the environment

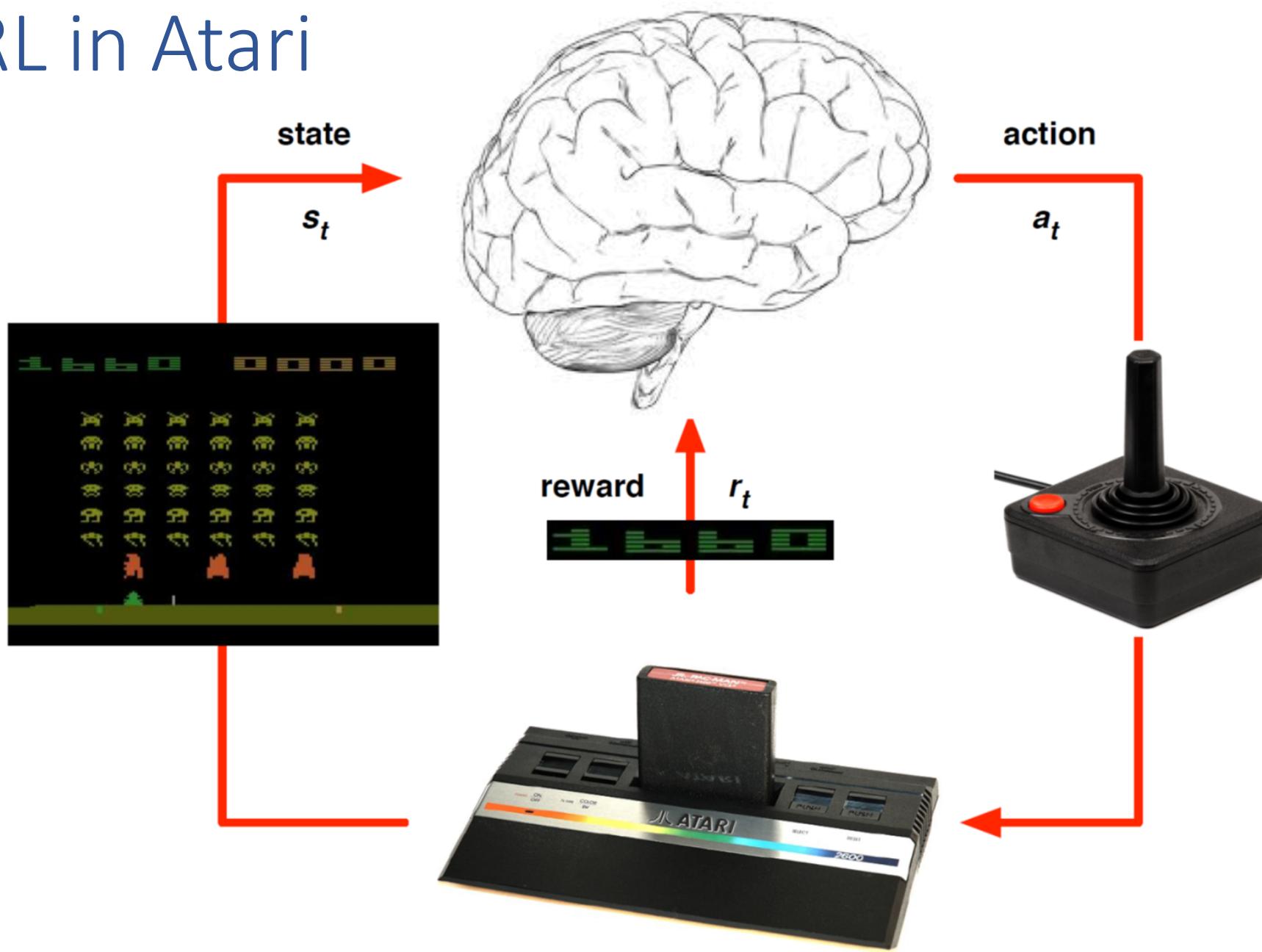


# Learn to Play Atari Games

- Mnih et al., “Human Level Control through Deep Reinforcement Learning,” *Nature*, 2015

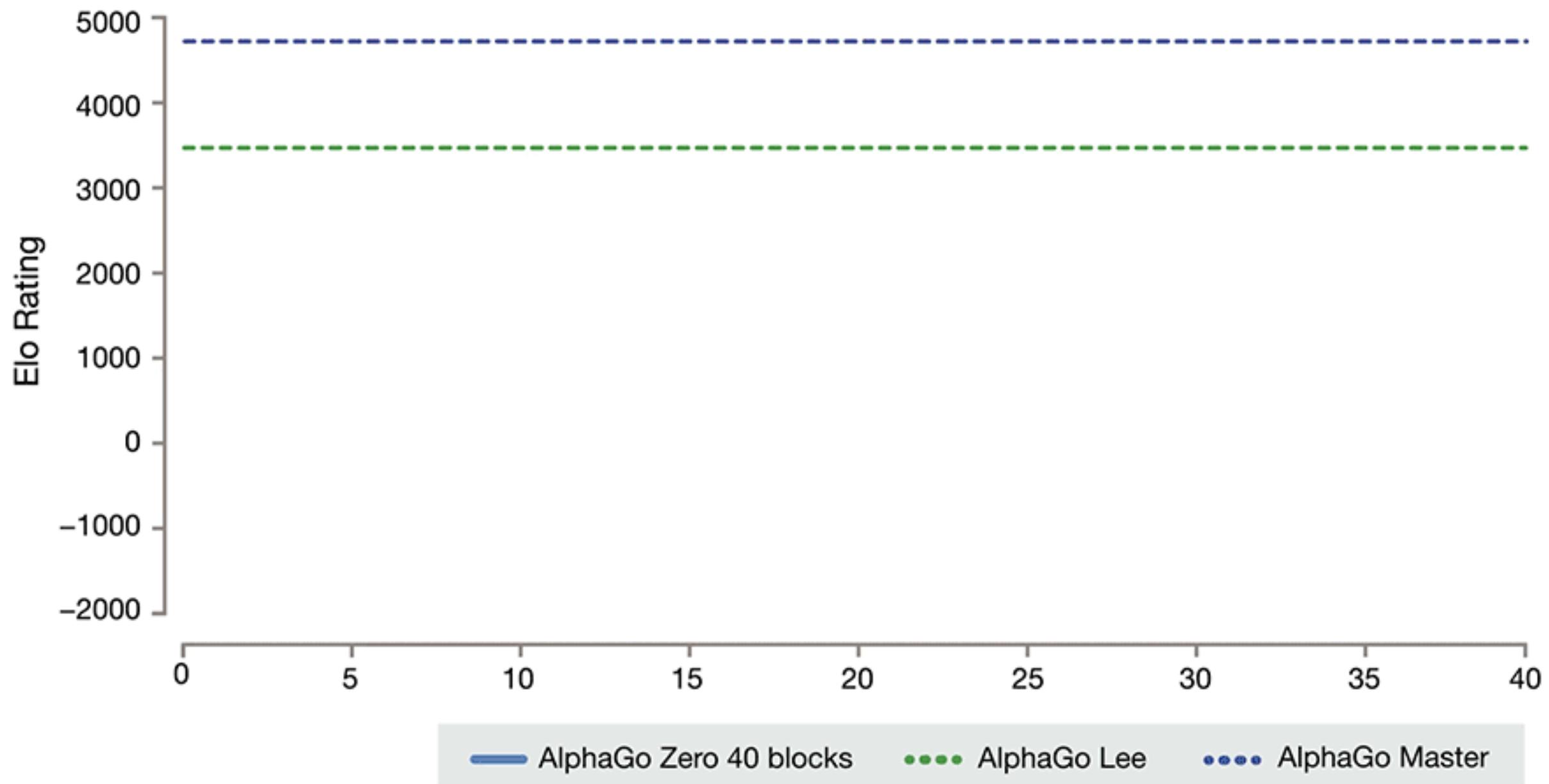


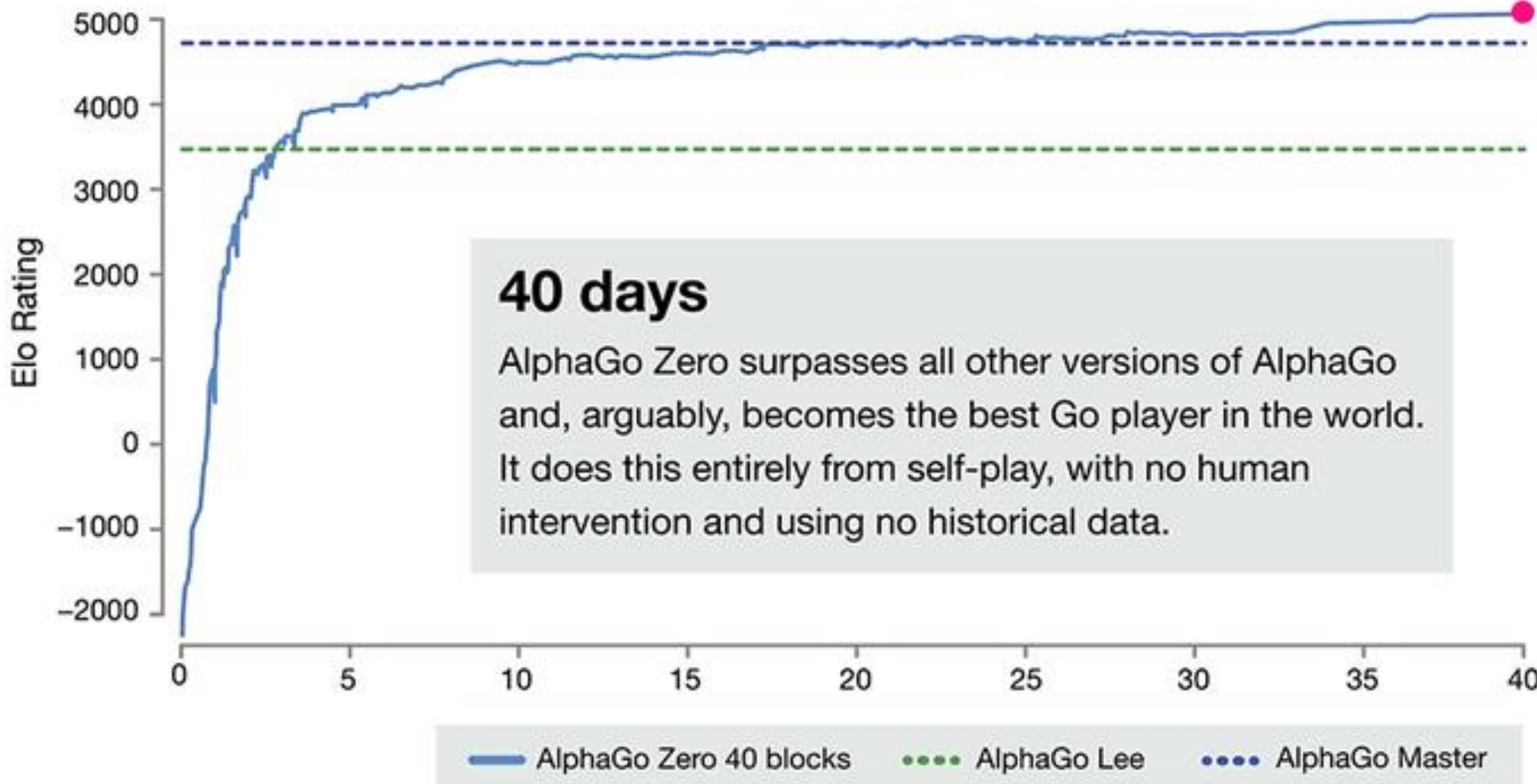
# DRL in Atari



# AlphaGo Zero

Starting from scratch





# Virtual-to-real Learning

- Inspired by DeepMind (Mnih et al., *Nature*, 2015)
  - “Human Level Control through Deep Reinforcement Learning”
- Applied to computer vision applications
  - **Image segmentation:** Armeni et al. (2016), Qiu et al., (2017)
  - **Indoor navigation:** Brodeur et al. (2017), Gupta et al. (2017), Savva et al. (2017), Wu et al. (2018)
  - **Autonomous vehicles:** Martinez et al. (2017), Muller et al. (2018), Pan et al. (2017), Shah et al. (2018)

UnrealCV



CAD<sup>2</sup>Real



## Semantic Segmentation



# VIVID

## Autonomous Navigation



## Depth Prediction



## Action Recognition



# Simulate Real-life Events



UMPQUA  
COMMUNITY  
COLLEGE

WELCOME BACK  
STAFF



65



# Searching for the Shooter



# DeepDrive



*Deepdrive is a simulator that allows anyone with a PC to push the state-of-the-art in self-driving.*

# Limits of Deep Learning

# No Idea of Real World



**school bus** 1.0 **garbage truck** 0.99 **punching bag** 1.0 **snowplow** 0.92



**motor scooter** 0.99 **parachute** 1.0 **bobsled** 1.0 **parachute** 0.54



**fire truck** 0.99 **school bus** 0.98 **fireboat** 0.98 **bobsled** 0.79

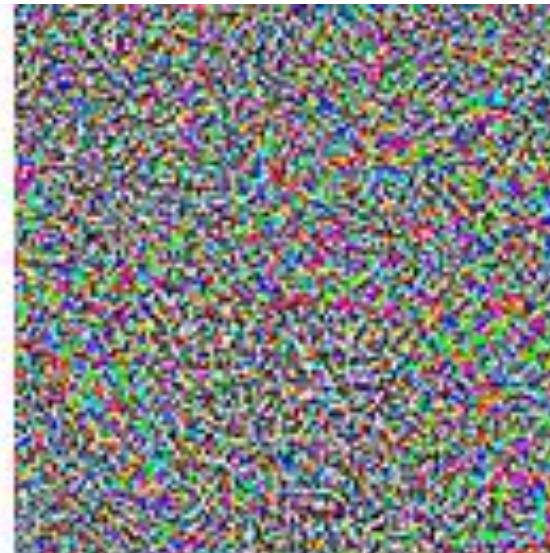
# Adversarial Attack



"panda"

57.7% confidence

$+ \epsilon$



=



"gibbon"

99.3% confidence



# Number of Connections in the Brain

**Neurons (for adults):**

$10^{11}$ , or 100 billion, 100000000000

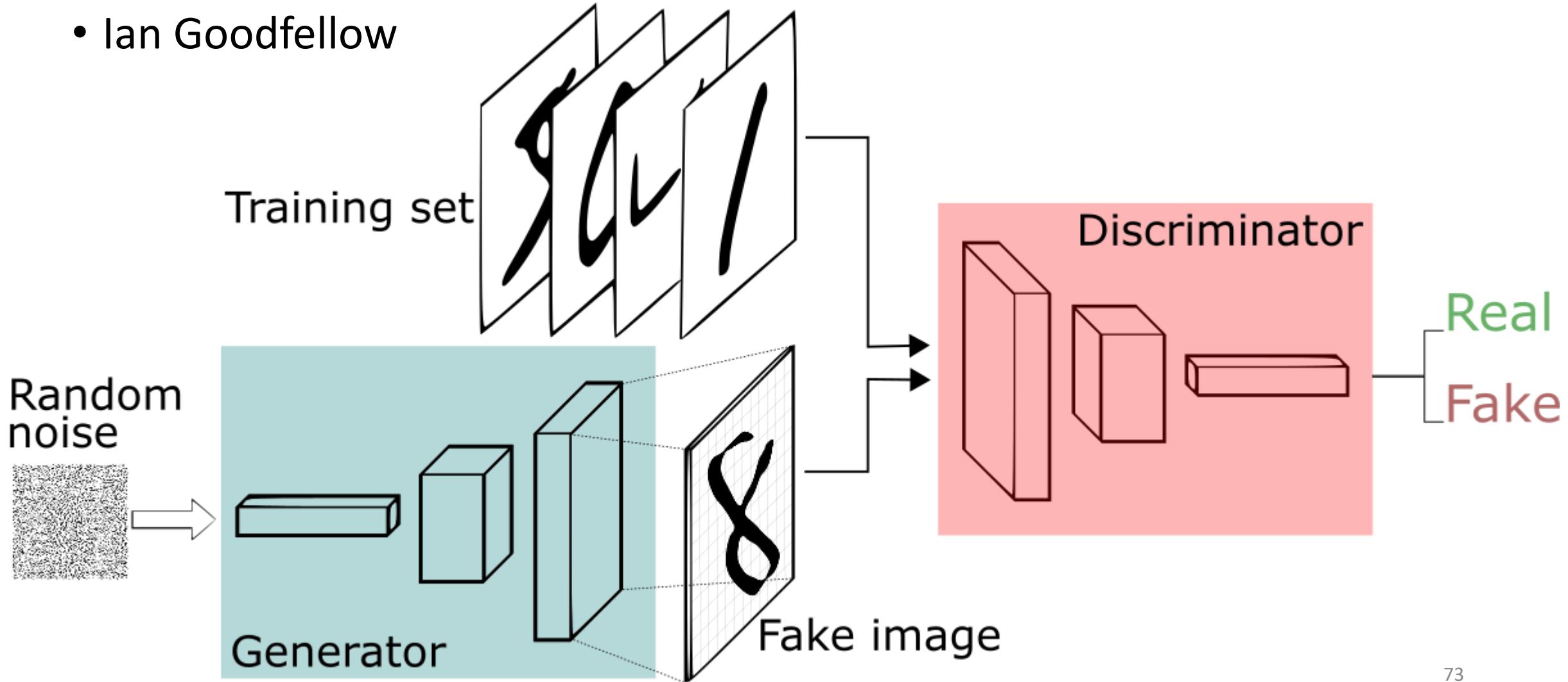
**Synapses (based on 1000 per neuron):**

$10^{14}$ , or 100 trillion, 100000000000000

# Generative Adversarial Networks (GAN)

# Generative Adversarial Networks (GAN)

- Ian Goodfellow



# Painting like Van Gogh



# Super Resolution

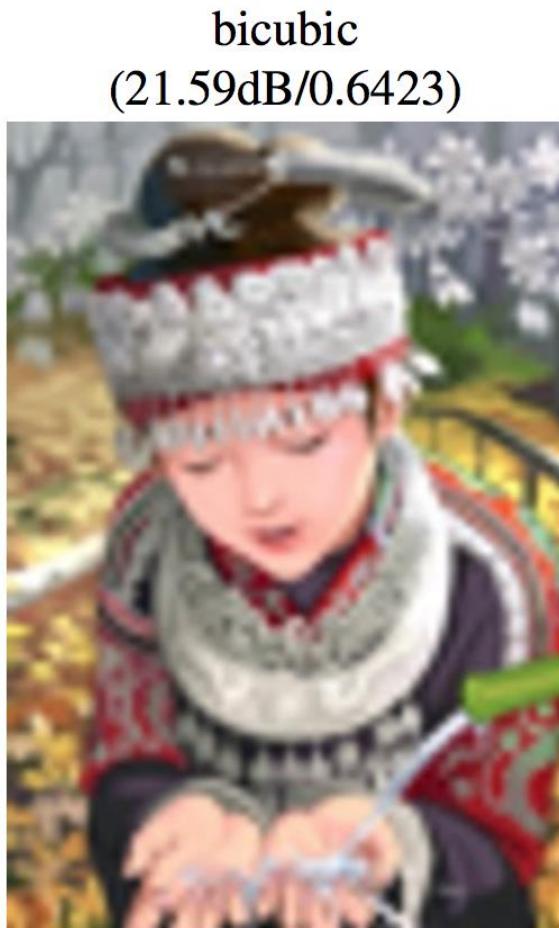
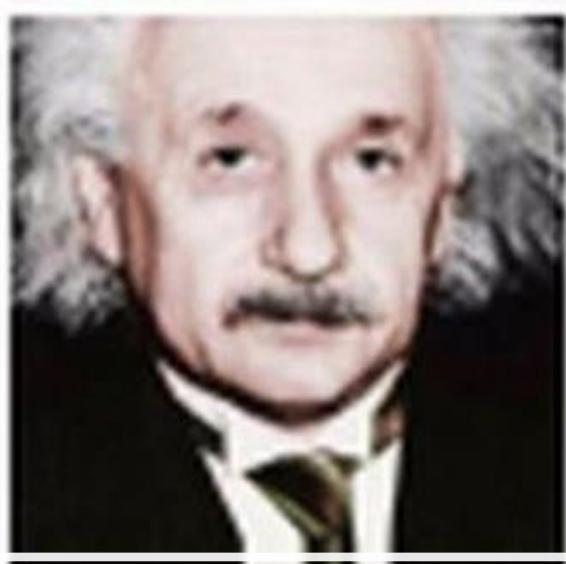


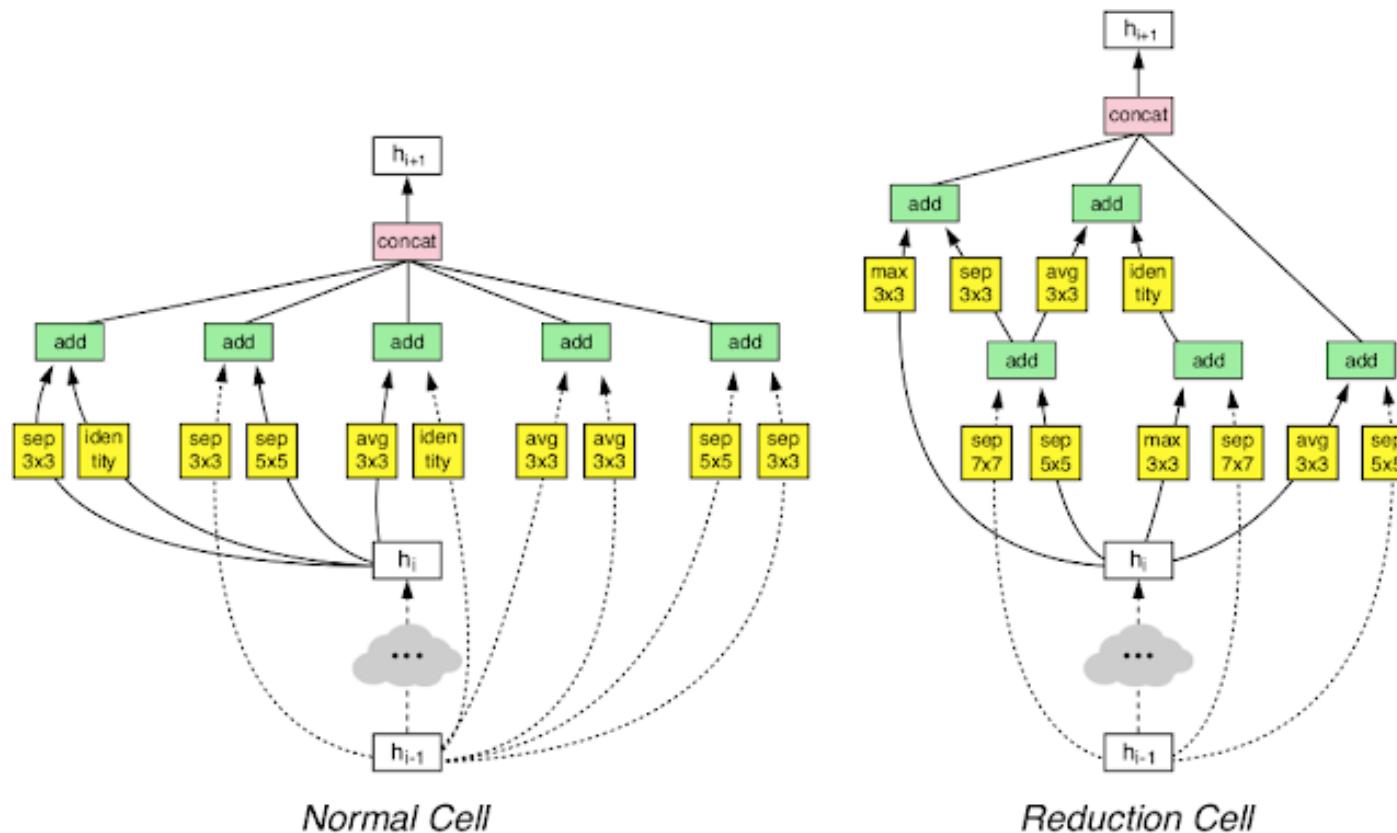
Figure 2: From left to right: bicubic interpolation, deep residual network optimized for MSE, deep residual generative adversarial network optimized for a loss more sensitive to human perception, original HR image. Corresponding PSNR and SSIM are shown in brackets. [4× upscaling]



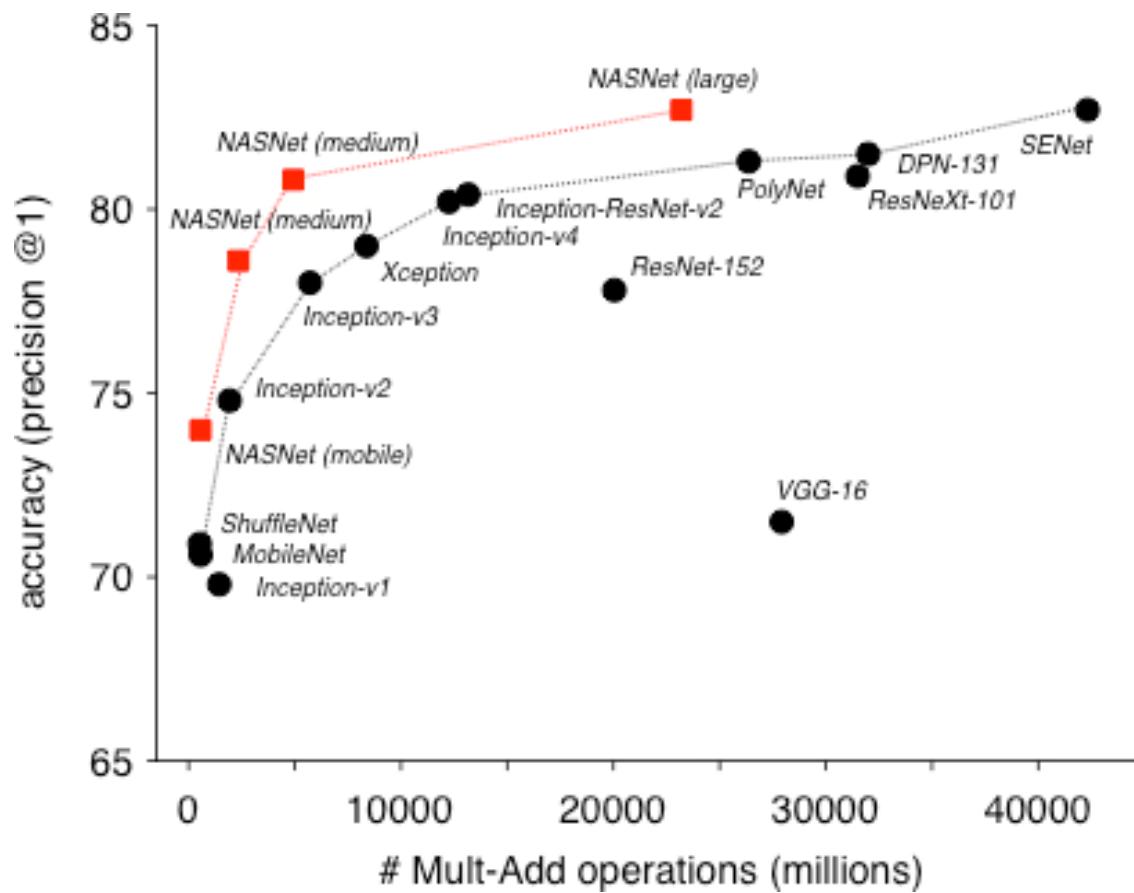
DeepFake: Is this you?

# Google's AutoML

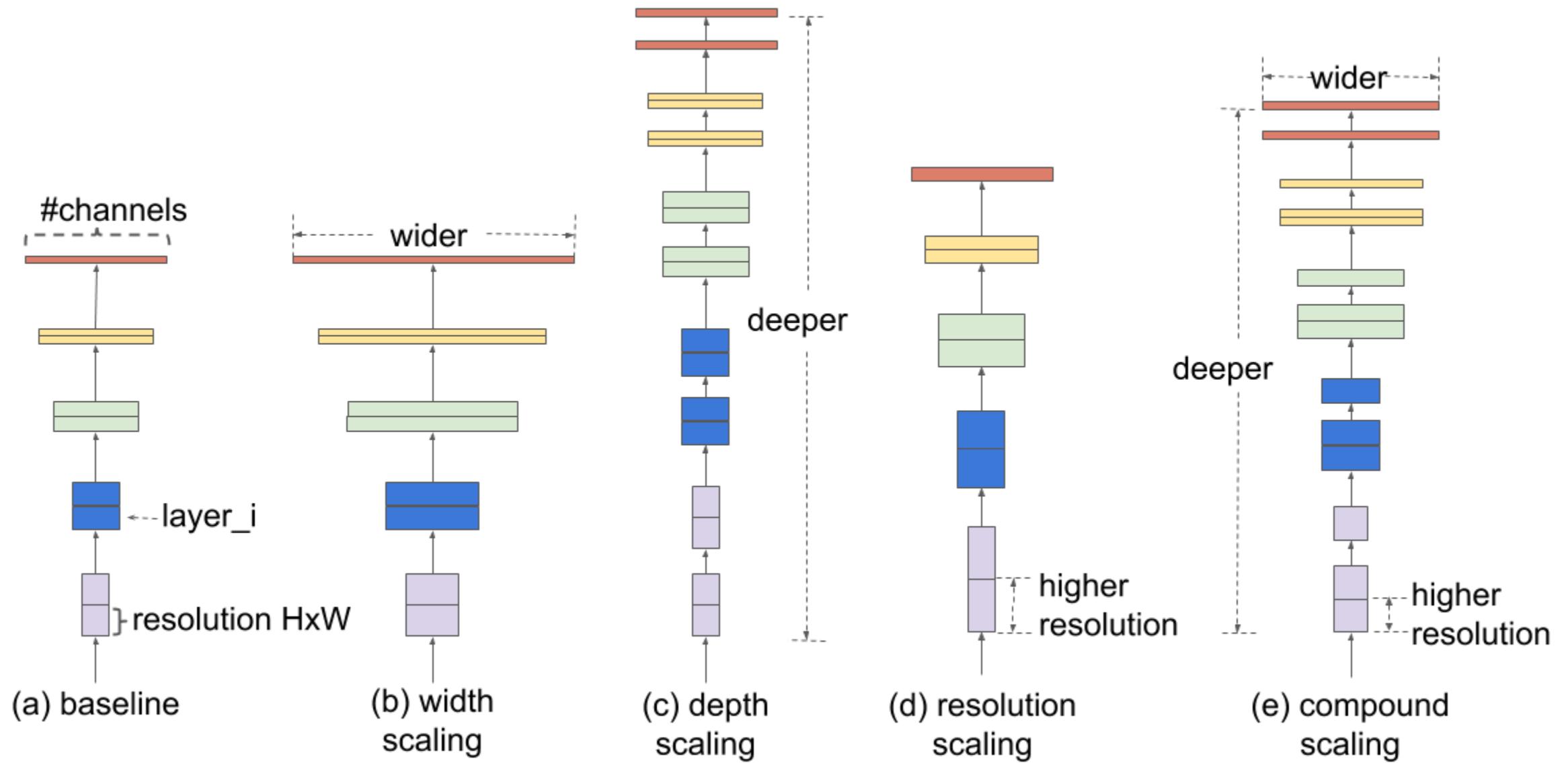
- Learning neural network cells automatically

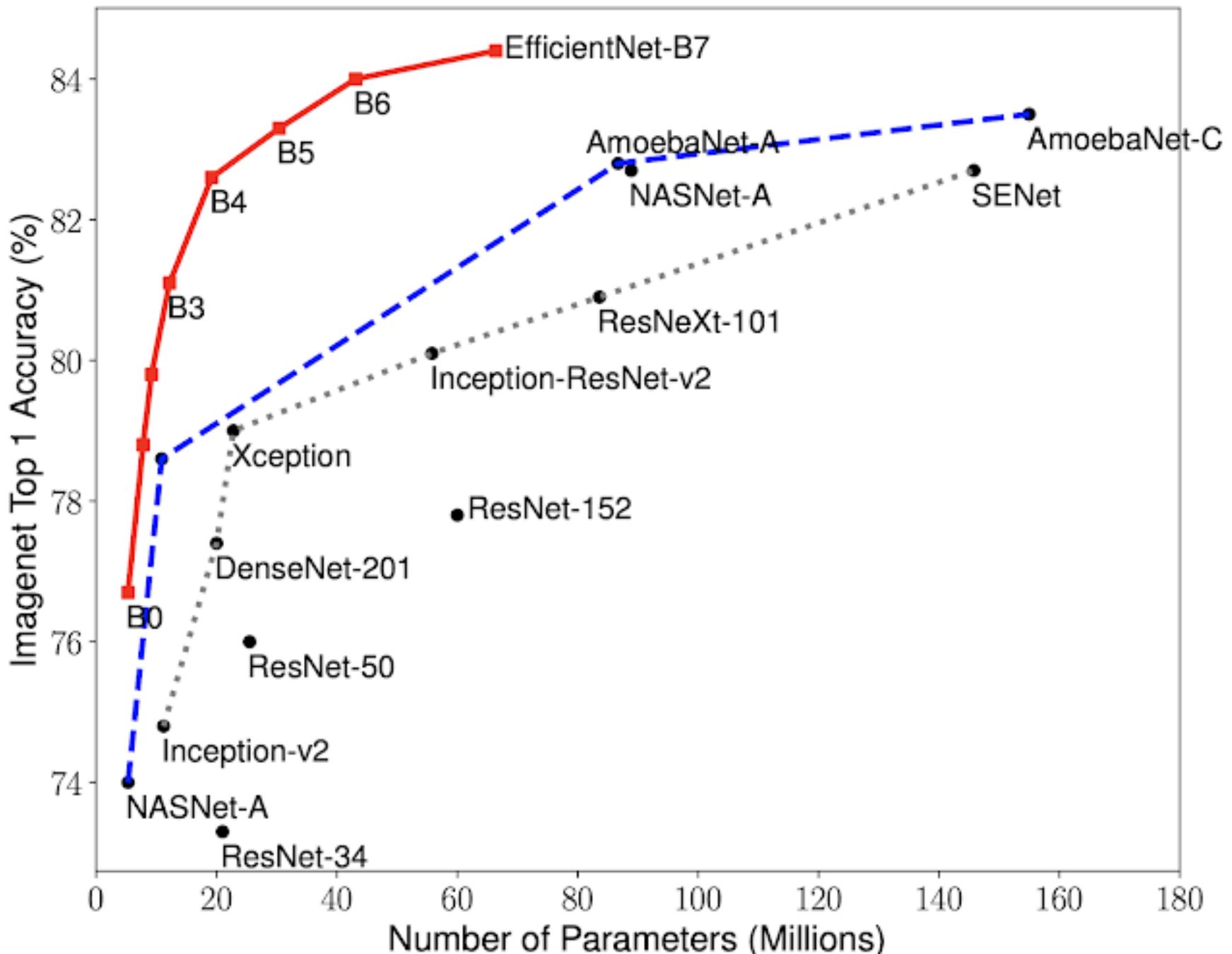


# AutoML on ImageNet



# EfficientNet (May, 2019)





# References

- Francois Chollet, “Deep Learning with Python.” Chapter 1
- What is backpropagation really doing? ( 3Blue1Brown)  
<https://www.youtube.com/watch?v=llg3gGewQ5U>
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