My Project

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Contents

1	Nam	nespace	Index																1
	1.1	Names	space List									 	 	 	 			 	1
2	Hier	archica	l Index																3
	2.1	Class I	Hierarchy									 	 	 	 			 	3
3	Clas	s Index																	5
	3.1	Class I	List									 	 	 	 			 	5
4	File	Index																	7
	4.1	File Lis	st									 	 	 	 			 	7
5	Nam	nespace	Documer	ntati	on														9
	5.1	AutoTe	st Names	pace	Refe	erenc	e .					 	 	 	 			 	9
		5.1.1	Typedef I	Docu	ımen	tatio	n					 	 	 	 			 	9
			5.1.1.1	Tes	stList							 	 	 	 			 	9
		5.1.2	Function	Doc	umei	ntatio	n .					 	 	 	 			 	9
			5.1.2.1	ado	dTest							 	 	 	 			 	9
			5.1.2.2	fino	dObje	ect						 	 	 	 			 	10
			5.1.2.3	run	ı							 	 	 	 			 	10
			5.1.2.4	tes	tList							 	 	 	 			 	10
6	Clas	s Docu	mentation	1															11
	6.1	Coords	s Class Re	eferei	nce							 	 	 	 			 	11
		6.1.1	Detailed	Des	criptic	on						 	 	 	 			 	11
		6.1.2	Construc	ctor 8	≩ Des	struct	tor D	ocu	men	tatio	n.	 	 	 	 			 	11
			6.1.2.1	Со	ords							 	 	 	 			 	11
			6.1.2.2	Со	ords							 	 	 	 			 	12
		6.1.3	Member	Fund	ction	Docı	ume	ntati	on			 	 	 	 			 	12
			6.1.3.1	De	gToD	ec						 	 	 	 			 	12
			6.1.3.2	get	tDecL	_atitu	ıde .					 	 	 	 			 	12
			6.1.3.3	get	tDecL	_ongi	itude	. .				 	 	 	 			 	12
			6.1.3.4	get	tLatitu	udeD)					 	 	 	 			 	12

iv CONTENTS

		6.1.3.5	getLatitudeM	12
		6.1.3.6	getLatitudeS	12
		6.1.3.7	getLongitudeD	12
		6.1.3.8	getLongitudeM	12
		6.1.3.9	getLongitudeS	13
		6.1.3.10	setDecLatitude	13
		6.1.3.11	setDecLongitude	13
		6.1.3.12	setLatitudeD	13
		6.1.3.13	setLatitudeM	13
		6.1.3.14	setLatitudeS	13
		6.1.3.15	setLongitudeD	13
		6.1.3.16	setLongitudeM	13
		6.1.3.17	setLongitudeS	13
6.2	Radar	Class Refe	erence	13
	6.2.1	Detailed I	Description	14
	6.2.2	Construc	tor & Destructor Documentation	14
		6.2.2.1	Radar	14
	6.2.3	Member I	Function Documentation	14
		6.2.3.1	getDistance	14
	6.2.4	Member I	Data Documentation	14
		6.2.4.1	directDistance	14
		6.2.4.2	otherPoz	15
		6.2.4.3	sac	15
		6.2.4.4	selfPoz	15
6.3	Test<	T > Class	Template Reference	15
	6.3.1	Construc	tor & Destructor Documentation	15
		6.3.1.1	Test	15
	6.3.2	Member I	Data Documentation	15
		6.3.2.1	child	15
6.4	TestCo	ord Class	Reference	16
	6.4.1	Construc	tor & Destructor Documentation	16
		6.4.1.1	TestCoord	16
6.5	TestRa	adar Class	Reference	16
	6.5.1	Construc	tor & Destructor Documentation	17
		6.5.1.1	TestRadar	17
File	Docum	entation		19
7.1			eference	19
	7.1.1		efinition Documentation	20
		7.1.1.1	DECLARE TEST	20
				_0

7

CONTENTS

		7.1.1.2	TEST_MAIN	١	 	 	 	 	 	 20
7.2	coords	cpp File F	Reference .		 	 	 	 	 	 21
	7.2.1	Detailed	Description		 	 	 	 	 	 21
	7.2.2	Function	Documentation	on	 	 	 	 	 	 21
		7.2.2.1	sgn		 	 	 	 	 	 21
7.3	coords	s.h File Re	ference		 	 	 	 	 	 21
7.4	main.c	pp File Re	ference		 	 	 	 	 	 22
	7.4.1	Function	Documentation	on	 	 	 	 	 	 23
		7.4.1.1	main		 	 	 	 	 	 23
7.5	radar.c	pp File Re	eference		 	 	 	 	 	 24
7.6	radar.h	r File Refe	rence		 	 	 	 	 	 24
7.7	test_co	oord.cpp F	ile Reference		 	 	 	 	 	 25
	7.7.1	Function	Documentation	on	 	 	 	 	 	 26
		7.7.1.1	cutNumber		 	 	 	 	 	 26
	7.7.2	Variable	Documentatio	n	 	 	 	 	 	 26
		7.7.2.1	cutDecLat		 	 	 	 	 	 26
		7.7.2.2	cutDecLong		 	 	 	 	 	 26
		7.7.2.3	mich_p37.		 	 	 	 	 	 26
		7.7.2.4	mie_mor .		 	 	 	 	 	 26
		7.7.2.5	mssr_bucen		 	 	 	 	 	 26
		7.7.2.6	mssr_veljav		 	 	 	 	 	 26
		7.7.2.7	po_mor5 .		 	 	 	 	 	 26
7.8	test_co	oord.h File	Reference .		 	 	 	 	 	 26
7.9	test_ra	dar.cpp Fi	le Reference		 	 	 	 	 	 27
	7.9.1	Variable	Documentatio	n	 	 	 	 	 	 27
		7.9.1.1	michp37		 	 	 	 	 	 27
		7.9.1.2	miemor		 	 	 	 	 	 28
		7.9.1.3	mssrbuce	n	 	 	 	 	 	 28
		7.9.1.4	mssrveljav	<i>/</i>	 	 	 	 	 	 28
		7.9.1.5	pomor5		 	 	 	 	 	 28
		7.9.1.6	r1		 	 	 	 	 	 28
7.10	test_ra	dar.h File	Reference .		 	 	 	 	 	 28
Index										29

Namespace Index

1.1	Namespace List	
Here	is a list of all namespaces with brief descriptions:	
Δ	The state of the s	

2 Namespace Index

Hierarchical Index

2.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

Coords	 	 . 11
QObject		
TestCoord	 	 16
TestRadar	 	 16
Radar	 	 . 13
Test< T >	 	 . 15

Hierarchical Index

Class Index

3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

Coords														
	Trieda Coords	 	 	 	 					 				. 1
Radar														
	Trieda Radar	 	 	 	 					 				. 10
$Test{$	>	 	 	 	 					 				. 18
TestCoor	rd	 	 	 	 					 				. 16
TestRada	ar	 	 	 	 					 				. 16

6 Class Index

File Index

4.1 File List

Here is a list of all files with brief descriptions:

AutoTest.	h .																																										19
coords.cp	op																																										
	Tent	o s	ub	or	ok	osa	ah	uj	e l	koı	าร	tru	kt	or	а	m	et	od	y t	rie	edy	y (Co	ord	ds	р	rec	dst	av	ujı	uce	e s	ur	ac	Ini	се	ra	ıda	aro	νe	eh	С	
	syste	emı	J																																								21
coords.h																																											21
main.cpp																																											22
radar.cpp																																											24
radar.h																																											24
test_coor	d.cp	р																																									25
test_coor	d.h																																										26
test_rada	ır.cpp																																										27
test rada	ır.h																																										28

8 File Index

Namespace Documentation

5.1 AutoTest Namespace Reference

Typedefs

typedef QList< QObject * > TestList

Functions

- TestList & testList ()
- bool findObject (QObject *object)
- void addTest (QObject *object)
- int run (int argc, char *argv[])

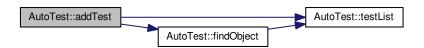
5.1.1 Typedef Documentation

 $\textbf{5.1.1.1} \quad \textbf{typedef QList}{<} \textbf{QObject}{*}{>} \textbf{AutoTest}{::} \textbf{TestList}$

5.1.2 Function Documentation

5.1.2.1 void AutoTest::addTest (QObject * object) [inline]

Here is the call graph for this function:



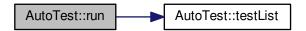
5.1.2.2 bool AutoTest::findObject(QObject*object) [inline]

Here is the call graph for this function:



5.1.2.3 int AutoTest::run (int argc, char * argv[]) [inline]

Here is the call graph for this function:



5.1.2.4 TestList& AutoTest::testList() [inline]

Class Documentation

6.1 Coords Class Reference

Trieda Coords.

```
#include <coords.h>
```

Public Member Functions

- · Coords ()
- Coords (double, double, double, double, double, double)
- void setLatitudeD (double)
- void setLatitudeM (double)
- void setLatitudeS (double)
- void setLongitudeD (double)
- void setLongitudeM (double)
- void setLongitudeS (double)
- void setDecLatitude (double decLatitude)
- void setDecLongitude (double decLongitude)
- double getLatitudeD (void)
- double getLatitudeM (void)
- double getLatitudeS (void)
- double getLongitudeD (void)
- double getLongitudeM (void)
- double getLongitudeS (void)
- double getDecLatitude ()
- double getDecLongitude ()
- void DegToDec (void)

6.1.1 Detailed Description

Trieda Coords.

Trieda Coords predstavuje suradnice radaroveho systemu a ich prevod do roznych typov.

6.1.2 Constructor & Destructor Documentation

6.1.2.1 Coords::Coords ()

Impicitny konstruktor

12 Class Documentation

6.1.2.2 Coords::Coords (double latitudeD, double latitudeM, double latitudeS, double longitudeD, double longitudeM, double longitudeS)

Konstruktor triedy Coords obsahujuci vstupne suradnice.

Konstruktor ma ako vstupne argumenty sestticu cisel predstavujucich stupne minuty a sekundy zemepisnej sirky a dlzky.

Parameters

arraySize	size of dynamically allocated array

Returns

nothing

- < Informacia o stupni zemepisnej sirky
- < Informacia o minute zemepisnej sirky
- < Informacia o sekunde zemepisnej sirky
- < Informacia o stupni zemepisnej dlzky
- < Informacia o stupni zemepisnej dlzky
- < Informacia o stupni zemepisnej dlzky
- < Prevod zemepisnej sirky do dekadickych stupnov
- < Prevod zemepisnej dlzky do dekadickych stupnov

Here is the call graph for this function:



- 6.1.3 Member Function Documentation
- 6.1.3.1 void Coords::DegToDec (void)
- 6.1.3.2 double Coords::getDecLatitude ()
- 6.1.3.3 double Coords::getDecLongitude ()
- 6.1.3.4 double Coords::getLatitudeD (void)
- 6.1.3.5 double Coords::getLatitudeM (void)
- 6.1.3.6 double Coords::getLatitudeS (void)
- 6.1.3.7 double Coords::getLongitudeD (void)
- 6.1.3.8 double Coords::getLongitudeM (void)

6.2 Radar Class Reference 13

```
6.1.3.9 double Coords::getLongitudeS ( void )
6.1.3.10 void Coords::setDecLatitude ( double decLatitude )
6.1.3.11 void Coords::setDecLongitude ( double decLongitude )
6.1.3.12 void Coords::setLatitudeD ( double latitudeD )
6.1.3.13 void Coords::setLatitudeM ( double latitudeM )
6.1.3.14 void Coords::setLatitudeS ( double latitudeS )
6.1.3.15 void Coords::setLongitudeD ( double longitudeD )
6.1.3.16 void Coords::setLongitudeM ( double longitudeM )
6.1.3.17 void Coords::setLongitudeS ( double longitudeS )
```

The documentation for this class was generated from the following files:

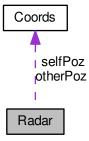
- · coords.h
- · coords.cpp

6.2 Radar Class Reference

Trieda Radar.

#include <radar.h>

Collaboration diagram for Radar:



Public Member Functions

- · Radar (Coords, Coords)
- double getDistance (void)

Public Attributes

• const double sac =48.0

14 Class Documentation

- double directDistance
- · Coords selfPoz
- · Coords otherPoz

6.2.1 Detailed Description

Trieda Radar.

Trieda predstavuje model radaru.

6.2.2 Constructor & Destructor Documentation

6.2.2.1 Radar::Radar (Coords selfPoz, Coords otherPoz)

Konstruktor triedy Radar obsahujuci vlastnu a vzdialenu suradnicu.

Konstruktor ma ako vstupne argumenty dva parametre typu Coords.

Parameters

arraySize	size of dynamically allocated array

Returns

nothing

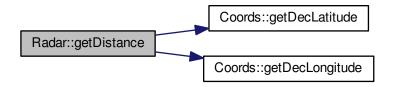
6.2.3 Member Function Documentation

6.2.3.1 double Radar::getDistance (void)

Funkcia getDistance triedy Radar pocitajuca vzdialenost.

Funkcia pocita vzdialenost pomocou kniznice GeographicLib vytvorenu pre geograficke vypocty.

Here is the call graph for this function:



6.2.4 Member Data Documentation

6.2.4.1 double Radar::directDistance

Vzdialenost od inej wgs suradnice

6.2.4.2 Coords Radar::otherPoz

Pozicia od ktorej sa pocita vzdialenost

6.2.4.3 const double Radar::sac =48.0

SAC identifikator

6.2.4.4 Coords Radar::selfPoz

Vlastna pozicia radaru

The documentation for this class was generated from the following files:

- radar.h
- · radar.cpp

6.3 Test < T > Class Template Reference

#include <AutoTest.h>

Public Member Functions

Test (const QString &name)

Public Attributes

QSharedPointer< T > child

6.3.1 Constructor & Destructor Documentation

6.3.1.1 template < class T > Test < T >::Test (const QString & name) [inline]

Here is the call graph for this function:



6.3.2 Member Data Documentation

6.3.2.1 template < class T > QSharedPointer<T> Test< T>::child

The documentation for this class was generated from the following file:

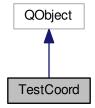
AutoTest.h

16 Class Documentation

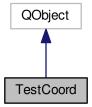
6.4 TestCoord Class Reference

#include <test_coord.h>

Inheritance diagram for TestCoord:



Collaboration diagram for TestCoord:



Public Member Functions

• TestCoord ()

6.4.1 Constructor & Destructor Documentation

6.4.1.1 TestCoord::TestCoord ()

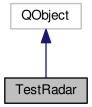
The documentation for this class was generated from the following files:

- test_coord.h
- test_coord.cpp

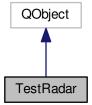
6.5 TestRadar Class Reference

#include <test_radar.h>

Inheritance diagram for TestRadar:



Collaboration diagram for TestRadar:



Public Member Functions

- TestRadar ()
- 6.5.1 Constructor & Destructor Documentation
- 6.5.1.1 TestRadar::TestRadar ()

The documentation for this class was generated from the following files:

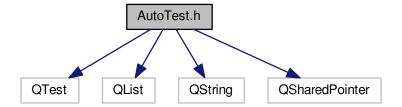
- test_radar.h
- test_radar.cpp

18 **Class Documentation**

File Documentation

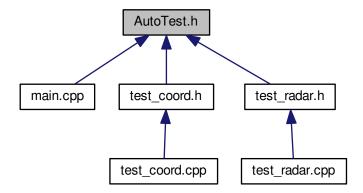
7.1 AutoTest.h File Reference

```
#include <QTest>
#include <QList>
#include <QString>
#include <QSharedPointer>
Include dependency graph for AutoTest.h:
```



20 File Documentation

This graph shows which files directly or indirectly include this file:



Classes

class Test< T >

Namespaces

AutoTest

Macros

- #define DECLARE_TEST(className) static Test<className> t(#className);
- #define TEST_MAIN

Typedefs

typedef QList< QObject * > AutoTest::TestList

Functions

- TestList & AutoTest::testList ()
- bool AutoTest::findObject (QObject *object)
- void AutoTest::addTest (QObject *object)
- int AutoTest::run (int argc, char *argv[])

7.1.1 Macro Definition Documentation

- $7.1.1.1 \quad \text{\#define DECLARE_TEST(} \quad \textit{className} \text{) static Test} < \text{className} > \text{t(\#className)};$
- 7.1.1.2 #define TEST_MAIN

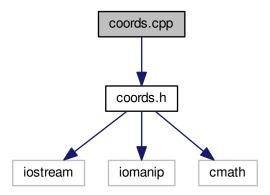
Value:

```
int main(int argc, char *argv[]) \
    { \
        return AutoTest::run(argc, argv); \
    }
```

7.2 coords.cpp File Reference

Tento subor obsahuje konstruktor a metody triedy Coords predstavujuce suradnice radaroveho systemu.

```
#include "coords.h"
Include dependency graph for coords.cpp:
```



Functions

template<typename T > T sgn (T n)

7.2.1 Detailed Description

Tento subor obsahuje konstruktor a metody triedy Coords predstavujuce suradnice radaroveho systemu. Mozny obsahlejsi popis na vice radek.

7.2.2 Function Documentation

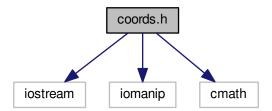
7.2.2.1 template < typename T > T sgn (T n)

7.3 coords.h File Reference

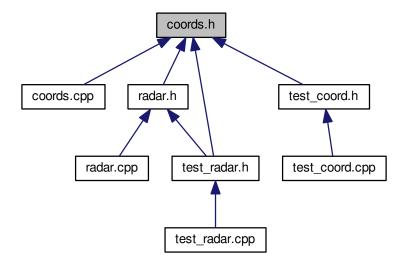
```
#include <iostream>
#include <iomanip>
#include <cmath>
```

22 File Documentation

Include dependency graph for coords.h:



This graph shows which files directly or indirectly include this file:



Classes

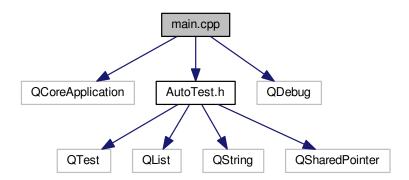
• class Coords

Trieda Coords.

7.4 main.cpp File Reference

#include <QCoreApplication>
#include "AutoTest.h"
#include <QDebug>

Include dependency graph for main.cpp:



Functions

• int main (int argc, char *argv[])

7.4.1 Function Documentation

7.4.1.1 int main (int argc, char * argv[])

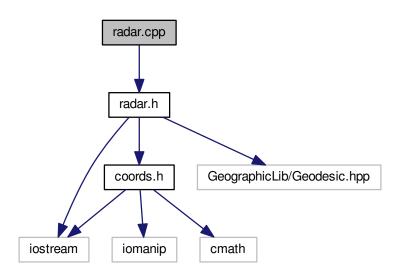
Here is the call graph for this function:



24 File Documentation

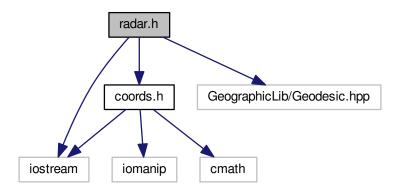
7.5 radar.cpp File Reference

#include "radar.h"
Include dependency graph for radar.cpp:

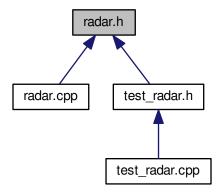


7.6 radar.h File Reference

#include "coords.h"
#include <iostream>
#include <GeographicLib/Geodesic.hpp>
Include dependency graph for radar.h:



This graph shows which files directly or indirectly include this file:



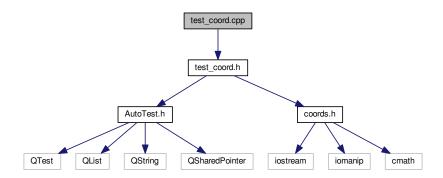
Classes

• class Radar

Trieda Radar.

7.7 test_coord.cpp File Reference

#include "test_coord.h"
Include dependency graph for test_coord.cpp:



Functions

• double cutNumber (double number)

Variables

double cutDecLat

26 File Documentation

- · double cutDecLong
- Coords mssr_veljav (48, 15, 38.56, 17, 9, 47.83)
- Coords mssr_bucen (48, 18, 19.95, 19, 52, 14.61)
- Coords mie_mor (48, 3, 42.00, 17, 22, 35.00)
- Coords mich_p37 (48, 43, 24.98, 21, 57, 4.39)
- Coords po_mor5 (49, 1, 55.2701, 21, 18, 51.607)

7.7.1 Function Documentation

7.7.1.1 double cutNumber (double *number*)

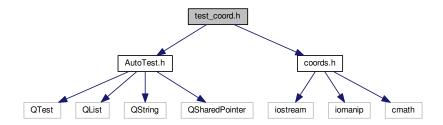
7.7.2 Variable Documentation

- 7.7.2.1 double cutDecLat
- 7.7.2.2 double cutDecLong
- 7.7.2.3 Coords mich_p37(48, 43, 24.98, 21, 57, 4.39)
- 7.7.2.4 Coords mie_mor(48, 3, 42.00, 17, 22, 35.00)
- 7.7.2.5 Coords mssr_bucen(48, 18, 19.95, 19, 52, 14.61)
- 7.7.2.6 Coords mssr_veljav(48, 15, 38.56, 17, 9, 47.83)
- 7.7.2.7 Coords po_mor5(49, 1, 55.2701, 21, 18, 51.607)

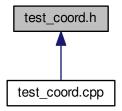
7.8 test coord.h File Reference

```
#include "AutoTest.h"
#include "coords.h"
```

Include dependency graph for test_coord.h:



This graph shows which files directly or indirectly include this file:

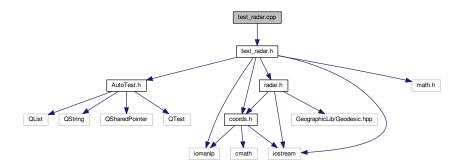


Classes

· class TestCoord

7.9 test_radar.cpp File Reference

#include "test_radar.h"
Include dependency graph for test_radar.cpp:



Variables

- Coords mssr_veljav (48, 15, 38.56, 17, 9, 47.83)
- Coords mssr__bucen (48, 18, 19.95, 19, 52, 14.61)
- Coords mie__mor (48, 3, 42.00, 17, 22, 35.00)
- Coords mich__p37 (48, 43, 24.98, 21, 57, 4.39)
- Coords po__mor5 (49, 1, 55.2701, 21, 18, 51.607)
- Radar r1 (mssr_veljav, mssr_bucen)

7.9.1 Variable Documentation

7.9.1.1 Coords mich_p37(48, 43, 24.98, 21, 57, 4.39)

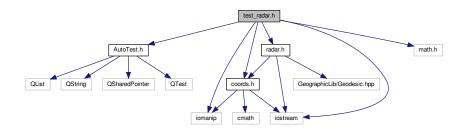
28 File Documentation

- 7.9.1.2 Coords mie_mor(48, 3, 42.00, 17, 22, 35.00)
- 7.9.1.3 Coords mssr_bucen(48, 18, 19.95, 19, 52, 14.61)
- 7.9.1.4 Coords mssr_veljav(48, 15, 38.56, 17, 9, 47.83)
- 7.9.1.5 Coords po__mor5(49, 1, 55.2701, 21, 18, 51.607)
- 7.9.1.6 Radar r1(mssr_veljav, mssr_bucen)

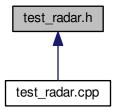
7.10 test_radar.h File Reference

```
#include "AutoTest.h"
#include "coords.h"
#include "radar.h"
#include <math.h>
#include <iomanip>
#include <iostream>
```

Include dependency graph for test_radar.h:



This graph shows which files directly or indirectly include this file:



Classes

class TestRadar

Index

addTest	findObject
AutoTest, 9	AutoTest, 9
AutoTest, 9	
addTest, 9	getDecLatitude
findObject, 9	Coords, 12
run, 10	getDecLongitude
TestList, 9	Coords, 12
testList, 10	getDistance
AutoTest.h, 19	Radar, 14
DECLARE_TEST, 20	getLatitudeD
TEST MAIN, 20	Coords, 12
	getLatitudeM
child	Coords, 12
Test, 15	getLatitudeS
Coords, 11	Coords, 12
Coords, 11	getLongitudeD
DegToDec, 12	Coords, 12
getDecLatitude, 12	getLongitudeM
getDecLongitude, 12	Coords, 12
getLatitudeD, 12	getLongitudeS
getLatitudeM, 12	Coords, 12
getLatitudeWi, 12	
getLongitudeD, 12	main
getLongitudeD, 12	main.cpp, 23
getLongitudeN, 12	main.cpp, 22
setDecLatitude, 13	main, 23
setDecLatitude, 13	michp37
setLatitudeD, 13	test_radar.cpp, 27
setLatitudeD, 13	mich_p37
setLatitudeW, 13	test_coord.cpp, 26
	miemor
setLongitudeD, 13 setLongitudeM, 13	test_radar.cpp, 27
setLongitudeN, 13	mie_mor
_	test_coord.cpp, 26
coords.cpp, 21	mssrbucen
sgn, 21	test_radar.cpp, 28
coords.h, 21	mssrveljav
cutDecLat	test_radar.cpp, 28
test_coord.cpp, 26	mssr_bucen
cutDecLong	test_coord.cpp, 26
test_coord.cpp, 26	mssr_veljav
cutNumber	test_coord.cpp, 26
test_coord.cpp, 26	
DECLARE TEST	otherPoz
DECLARE_TEST	Radar, 14
AutoTest.h, 20	
DegToDec	pomor5
Coords, 12	test_radar.cpp, 28
directDistance	po_mor5
Radar, 14	test_coord.cpp, 26

30 INDEX

r1	r1, 28
test_radar.cpp, 28	test_radar.h, 28
Radar, 13	TestCoord, 16
directDistance, 14	TestCoord, 16
getDistance, 14	TestCoord, 16
otherPoz, 14	TestList
Radar, 14	AutoTest, 9
sac, 15	testList
selfPoz, 15	AutoTest, 10
radar.cpp, 24	TestRadar, 16
radar.h, 24	TestRadar, 17
run	TestRadar, 17
AutoTest, 10	
sac	
Radar, 15	
selfPoz	
Radar, 15	
setDecLatitude	
Coords, 13	
setDecLongitude	
Coords, 13	
setLatitudeD	
Coords, 13	
setLatitudeM	
Coords, 13	
setLatitudeS	
Coords, 13	
setLongitudeD	
Coords, 13	
setLongitudeM	
Coords, 13	
setLongitudeS	
Coords, 13	
sgn	
coords.cpp, 21	
TEST_MAIN	
AutoTest.h, 20	
Test	
child, 15	
Test, 15	
Test< T >, 15	
test_coord.cpp, 25	
cutDecLat, 26	
cutDecLong, 26	
cutNumber, 26	
mich_p37, <mark>26</mark>	
mie_mor, 26	
mssr_bucen, 26	
mssr_veljav, <mark>26</mark>	
po_mor5, <mark>26</mark>	
test_coord.h, 26	
test_radar.cpp, 27	
michp37, 27	
miemor, 27	
mssrbucen, 28	
mssrveljav, 28	
pomor5, 28	