

lecture 10

- *Poor Man's matrix class*
 - *defining class operators for $+$, $-$, $*$, $/$*
- *Inheritance -intro*
- *Strassen's matrix multiply algorithm*

poor man's matrix class

- *constructor*
- *destructor*
- *copy constructor*
- *class methods for accessing private elements*
- *operator overloading for class members*

poor man's matrix class

- *constructor*
- *destructor*
- *copy constructor*
- *class methods for accessing private elements*
- *operator overloading for class members*

```
// simple matrix class
class Matrix
{
public:
    Matrix(int, int);           // constructor
    ~Matrix();                 // destructor
    Matrix(const Matrix &other); // copy constructor

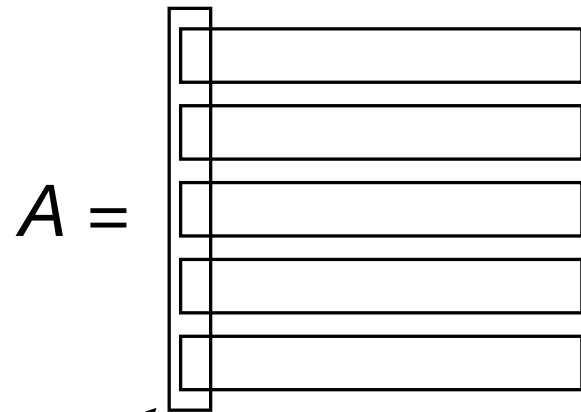
    // accessor methods – class functions that can access private foo
    int getRows() const { return rows_; }
    int getCols() const { return cols_; }
    double get_ij(int i, int j) const { return matrix_[i][j]; }
    void set_ij(int i, int j, double value) { matrix_[i][j] = value; }
    void print() const;

    // alternate reference notation ... A[i][j]
    // element access operators
    std::vector<double> &operator[](int i) { return matrix_[i]; }
    const std::vector<double> &operator[](int i) const { return matrix_[i]; }

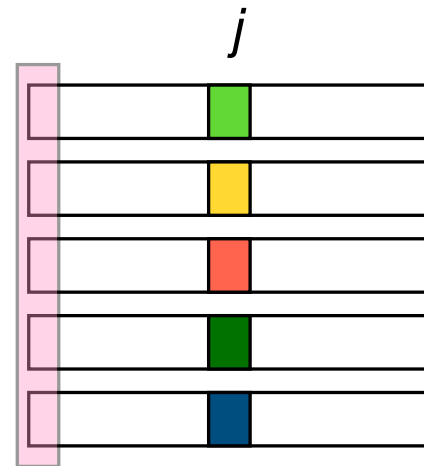
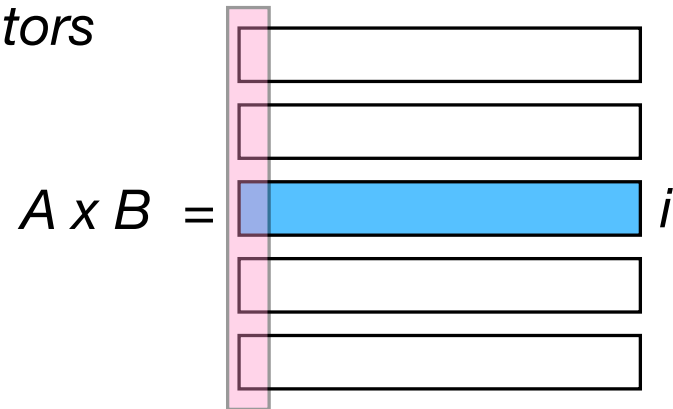
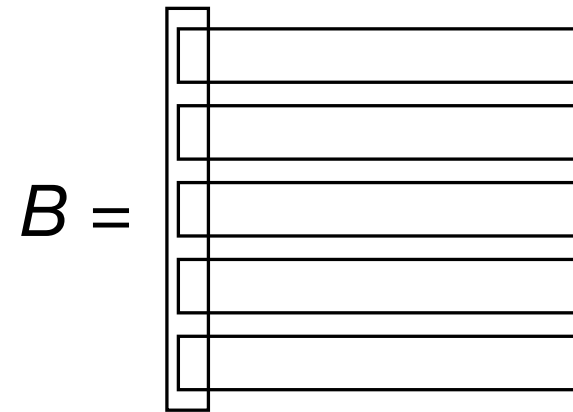
    Matrix operator*(const Matrix &other) const; // matrix multiply
    Matrix operator+(const Matrix &other) const; // matrix addition
    Matrix operator*(double scalar) const;      // scale matrix
    Matrix operator-(const Matrix &other) const; // matrix subtraction is redundant

private:
    std::vector<std::vector<double>> matrix_;
    int rows_;
    int cols_;
};
```

matrix foo revisited



vector of vectors



poor man's matrix class

- *constructor*
- *class methods for accessing private elements*

```
Matrix m(3, 4); // creates a 3x4 matrix
```

```
Matrix::Matrix(int rows, int cols)
    : matrix_(rows, std::vector<double>(cols)), rows_(rows), cols_(cols)
{ // matrix constructor
}
```

```
private:
    std::vector<std::vector<double>> matrix_;
    int rows_;
    int cols_;
};
```

```
Matrix::~Matrix()
```

```
{  
    // deallocate the memory used by the vector of vectors  
    matrix_.clear();  
    std::cout << "Matrix destructed" << std::endl;  
}
```

`std::vector<std::vector<double>>().swap(matrix);`
Creates a temporary, empty `std::vector<std::vector<double>>`.
Swaps it with your existing `matrix`.

```
Matrix::Matrix(int rows, int cols)
```

```
    : matrix_(rows, std::vector<double>(cols)), rows_(rows), cols_(cols)  
{ // matrix constructor  
}
```

```
Matrix::Matrix(const Matrix &other)
```

```
    : rows_(other.rows_), cols_(other.cols_), matrix_(other.matrix_)  
{ // copy constructor  
}
```

poor man's matrix class

- *class methods for accessing private elements*

```
private:
    std::vector<std::vector<double>> matrix_;
    int rows_;
    int cols_;
};
```

```
// accessor methods – class functions that can access private foo
int getRows() const { return rows_; }
int getCols() const { return cols_; }
double get_ij(int i, int j) const { return matrix_[i][j]; }
void set_ij(int i, int j, double value) { matrix_[i][j] = value; }
void print() const;
// alternate reference notation ... A[i][j]
// element access operators
std::vector<double> &operator[](int i) { return matrix_[i]; }
const std::vector<double> &operator[](int i) const { return matrix_[i]; }
```

The first `operator[]` returns a reference to the vector of double values at row `i`, which can then be indexed with `j` to retrieve the matrix element at position `(i, j)`.

poor man's matrix class

- *class methods for accessing private elements*

```
// accessor methods - class functions that can access private foo
int getRows() const { return rows_; }
int getCols() const { return cols_; }
double get_ij(int i, int j) const { return matrix_[i][j]; }
void set_ij(int i, int j, double value) { matrix_[i][j] = value; }
void print() const;
// alternate reference notation ... A[i][j]
// element access operators
std::vector<double> &operator[](int i) { return matrix_[i]; }
const std::vector<double> &operator[](int i) const { return matrix_[i]; }
```

```
void Matrix::print() const
{
    for (int i = 0; i < rows_; i++)
    {
        for (int j = 0; j < cols_; j++)
        {
            std::cout << matrix_[i][j] << " ";
        }
        std::cout << std::endl;
    }
}
```


poor man's matrix class

- *operator overloading for class members*

```
Matrix operator*(const Matrix &other) const; // matrix multiply
```

``operator*``: This is the name of the operator being overloaded. In this case, it is the multiplication operator ``*``.

``const Matrix &other``: This is the argument to the operator overload. It is a constant reference to another ``Matrix`` object that will be multiplied with the current object. The ``const`` qualifier ensures that the argument cannot be modified within the function.

``const``: This keyword specifies that the function does not modify the state of the ``Matrix`` object it is called on. It is part of the function signature and allows the function to be called on ``const`` objects of the ``Matrix`` class.

``Matrix``: This is the return type of the function. In this case, the ``operator*`` overload returns a new ``Matrix`` object that represents the result of the matrix multiplication operation.

```
Matrix operator*(const Matrix &other) const; // matrix multiply
```

poor man's matrix class

- *operator overloading for class members*

```
Matrix Matrix::operator*(const Matrix &other) const
{
    if (cols_ != other.rows_)
    {
        throw std::invalid_argument("Matrices are not compatible for multiplication");
    }
    Matrix result(rows_, other.cols_);
    for (int i = 0; i < rows_; i++)
    {
        for (int j = 0; j < other.cols_; j++)
        {
            double sum = 0;
            for (int k = 0; k < cols_; k++)
            {
                sum += matrix_[i][k] * other.matrix_[k][j];
            }
            result.set_ij(i, j, sum);
        }
    }
    return result;
}
```

A calls the `operator*` method.

`other` becomes B.

A new `Matrix C` is created inside the method and returned — A and B are not modified.

```

// example of simple matrix class with operator overloading
// Initialize matrices
Matrix A(2, 2); // constructor invoked ...
A.set_ij(0, 0, 1.0);
A.set_ij(0, 1, 2.0);
A.set_ij(1, 0, 3.0);
A.set_ij(1, 1, 4.0);

Matrix F(A); // copy A using the copy constructor

// check the alternate access notation
double v = A[0][1];
std::cout << "w = A[0][1] = " << v << std::endl;

Matrix B(2, 2);
B.set_ij(0, 0, 5.0);
B.set_ij(0, 1, 6.0);
B.set_ij(1, 0, 7.0);
B.set_ij(1, 1, 8.0);

// Matrix multiplication
Matrix C = A * B;
std::cout << "Matrix C = A * B:" << std::endl;
C.print();

// Matrix addition
Matrix D = A + B;
std::cout << "Matrix D = A + B:" << std::endl;
D.print();

// Scalar multiplication
Matrix E = 2.0 * A;
std::cout << "Matrix E = 2. * A:" << std::endl;
E.print();

```

```

w = A[0][1] = 2
Matrix C = A * B:
19 22
43 50
Matrix D = A + B:
6 8
10 12
Matrix E = 2 * A:
2 4
6 8
Matrix destructed
Matrix destructed
Matrix destructed
Matrix destructed
Matrix destructed
Matrix destructed

```

inheritance

- *allows a class to acquire the members of another class*

```
//inheritance ...  
class square : public rectangle{};  
// rectangle is the base class of square  
// square is derived from rectangle  
//square does not define any new member  
//functions or variables,  
//but it can use all of the member functions  
//and variables of rectangle
```

```
int main()  
{  
    rectangle r1;  
    r1.x = 3;  
    r1.y = 4;  
    std::cout << "area: " << r1.area() << std::endl;  
  
    square s1;  
    s1.x = 4; s1.y=5;  
    std::cout << "area s1: " << s1.area() << std::endl;  
}
```

```
rectangle constructed  
area: 12  
rectangle constructed  
area s1: 20  
rectangle destructed  
rectangle destructed
```

inheritance

- allows a class to acquire the members of another class

```
1  #ifndef AUTOMOBILE_HPP
2  #define AUTOMOBILE_HPP
3
4  #include <string>
5  #include <iostream>
6
7  class Automobile {
8  protected:
9      std::string brand;
10     int year;
11
12 public:
13     Automobile(const std::string& brand, int year)
14         : brand(brand), year(year) {}
15
16     void showDetails() const {
17         std::cout << "Brand: " << brand << ", Year: " << year << std::endl;
18     }
19 };
20
21 #endif // AUTOMOBILE_HPP
```

```
1  #ifndef CAR_HPP
2  #define CAR_HPP
3
4  #include "automobile.hpp"
5
6  class Car : public Automobile {
7  private:
8      int num_doors;
9
10 public:
11     Car(const std::string& brand, int year, int doors)
12         : Automobile(brand, year), num_doors(doors) {}
13
14     void showCar() const {
15         showDetails();
16         std::cout << "Type: Car, Doors: " << num_doors << std::endl;
17     }
18 };
```

```
1  #ifndef TRUCK_HPP
2  #define TRUCK_HPP
3
4  #include "automobile.hpp"
5
6  class Truck : public Automobile {
7  private:
8      double payload_capacity;
9
10 public:
11     Truck(const std::string& brand, int year, double capacity)
12         : Automobile(brand, year), payload_capacity(capacity) {}
13
14     void showTruck() const {
15         showDetails();
16         std::cout << "Type: Truck, Payload Capacity: " << payload_capacity << " tons" << std::endl;
17     }
18 };
```

```
1  #include "car.hpp"
2  #include "truck.hpp"
3
4  int main() {
5      Car myCar("Toyota", 2022, 4);
6      Truck myTruck("Ford", 2020, 2.5);
7
8      myCar.showCar();
9      std::cout << std::endl;
10     myTruck.showTruck();
11
12     return 0;
13 }
```

```
[bash-3.2$ vi automobile.hpp
[bash-3.2$ vi car.hpp
[bash-3.2$ vi truck.hpp
[bash-3.2$ vi inherit1.cpp
[bash-3.2$ g++ -std=c++17 -o xinherit1 -I./ inherit1.cpp
[bash-3.2$ ./xinherit1
Brand: Toyota, Year: 2022
Type: Car, Doors: 4

Brand: Ford, Year: 2020
Type: Truck, Payload Capacity: 2.5 tons
[bash-3.2$
```

inheritance

- *allows a class to acquire the members of another class*
- *virtual functions + polymorphism: lets us call the correct method on derived classes via a base class pointer or reference*

Concept	Description
virtual	Declares a method meant to be overridden by derived classes. Enables polymorphism.
override	Ensures a derived method is actually overriding a virtual base method.

```

1  #ifndef AUTOMOBILE_HPP
2  #define AUTOMOBILE_HPP
3
4  #include <string>
5  #include <iostream>
6
7  class Automobile {
8  protected:
9      std::string brand;
10     int year;
11
12 public:
13     Automobile(const std::string& brand, int year)
14         : brand(brand), year(year) {}
15
16     // Virtual function to allow overriding
17     virtual void showInfo() const {
18         std::cout << "Automobile - Brand: " << brand << ", Year: " << year << std::endl;
19     }
20
21     // Always good practice: a virtual destructor for base classes
22     virtual ~Automobile() = default;
23 };
24
25 #endif // AUTOMOBILE_HPP

```

```

1  #ifndef CAR_HPP
2  #define CAR_HPP
3
4  #include "automobile.hpp"
5
6  class Car : public Automobile {
7  private:
8      int num_doors;
9
10 public:
11     Car(const std::string& brand, int year, int doors)
12         : Automobile(brand, year), num_doors(doors) {}
13
14     void showInfo() const override {
15         std::cout << "Car - Brand: " << brand << ", Year: " << year
16         << ", Doors: " << num_doors << std::endl;
17     }
18 };
19 #endif // CAR_HPP

```

```

1  #ifndef TRUCK_HPP
2  #define TRUCK_HPP
3
4  #include "automobile.hpp"
5
6  class Truck : public Automobile {
7  private:
8      double payload_capacity;
9
10 public:
11     Truck(const std::string& brand, int year, double capacity)
12         : Automobile(brand, year), payload_capacity(capacity) {}
13
14     void showInfo() const override {
15         std::cout << "Truck - Brand: " << brand << ", Year: " << year
16         << ", Payload: " << payload_capacity << " tons" << std::endl;
17     }
18 };
19 #endif // TRUCK_HPP

```

```

1  #include "car.hpp"
2  #include "truck.hpp"
3  #include <vector>
4
5  int main() {
6      // Create instances
7      Car car("Honda", 2023, 4);
8      Truck truck("Volvo", 2019, 7.5);
9
10     // Store as pointers to base class
11     std::vector<Automobile*> garage;
12     garage.push_back(&car);
13     garage.push_back(&truck);
14
15     // Call polymorphic function
16     for (const auto* vehicle : garage) {
17         vehicle->showInfo(); // Dynamically calls Car/Truck version
18     }
19
20     return 0;
21 }

```

The function `showInfo()` is **virtual** in the base class, and **overridden** in derived classes.

Even though we use `Automobile*` in the loop, the **correct derived class version** is invoked.

This is **runtime polymorphism** via **dynamic dispatch**.

```

bash-3.2$ g++ -std=c++17 -o xinherit1 -I./ inherit1.cpp
bash-3.2$ ./xinherit1
Car - Brand: Honda, Year: 2023, Doors: 4
Truck - Brand: Volvo, Year: 2019, Payload: 7.5 tons
bash-3.2$

```

inheritance

- *objects can be upcast to their base class*
- *assign derived object to reference of base class*
- *assign derived object to a pointer of the base class*

```
//inheritance ...  
class square : public rectangle{};  
// rectangle is the base class of square  
// square is derived from rectangle  
//square does not define any new member  
//functions or variables,  
//but it can use all of the member functions  
//and variables of rectangle
```

```
//allows accessing only the public members of rectangle  
rectangle& r6 = s1; //reference upcast  
rectangle* r7 = &s1; //pointer upcast
```


inheritance

- *an upcast object can be downcast to their base class safely always*
- *explicit casting*

```
// multiple inheritance
class people {};
class employee {};
class professor : public people, public employee {};
```

```
//allows accessing only the public members of rectangle
rectangle& r6 = s1; //reference upcast
rectangle* r7 = &s1; //pointer upcast
```


```
//downcast by explicit cast
square& sq1 = static_cast<square&>(r6);
square* sq2 = static_cast<square*>(r7);
```

inheritance -upcast

- *an upcast object can be downcast to their base class safely always*
- *explicit casting*

Upcasting

Definition: Converting a derived class pointer or reference to a base class type.

 **Always safe** — no cast operator required.

cpp

 Copy

 Edit

```
class Vehicle {  
public:  
    virtual void drive() {}  
};
```

```
class Car : public Vehicle {  
public:  
    void drive() override {}  
};
```

```
Car myCar;
```

```
Vehicle* vPtr = &myCar; //  Upcasting — safe and implicit
```




inheritance -downcast

- *use with care*

Downcasting

Definition: Converting a base class pointer/reference to a derived class type.

 **Potentially unsafe** — must ensure the base class actually points to the correct derived type.

cpp

 Copy

 Edit

```
Vehicle* vPtr = new Car();
```

```
Car* cPtr = dynamic_cast<Car*>(vPtr); //  Safe if vPtr really points to a Car
```

- Use `dynamic_cast` (requires at least one **virtual** function in the base class).
- Returns `nullptr` if the cast is invalid (for pointers).
- If using references, `dynamic_cast<Car&>(vRef)` throws `std::bad_cast` on failure.

inheritance

- *multiple inheritance*

```
// multiple inheritance
class people {};
class employee {};
class professor : public people, public employee {};
```

matrix multiply revisited divide and conquer ala Strassen

- 2 x 2 multiplication can be achieve with 7 multiplies - not 8
- tradeoffs
 - increase in storage
 - number of additions goes from 4 to 18

$$\begin{array}{|c|c|} \hline C(1,1) & C(1,2) \\ \hline C(2,1) & C(2,2) \\ \hline \end{array} = \begin{array}{|c|c|} \hline A(1,1) & A(1,2) \\ \hline A(2,1) & A(2,2) \\ \hline \end{array} \begin{array}{|c|c|} \hline B(1,1) & B(1,2) \\ \hline B(2,1) & B(2,2) \\ \hline \end{array}$$

$$C = A B$$

$$P1 = (A(1,1)+A(2,2))*(B(1,1)+B(2,2))$$

$$P2 = (A(2,1)+A(2,2))*B(1,1)$$

$$P3 = A(1,1)*(B(1,2)-B(2,2))$$

$$P4 = A(2,2)*(B(2,1)-B(1,1))$$

$$P5 = (A(1,1)+A(1,2))*B(2,2)$$

$$P6 = (A(2,1)-A(1,1))*(B(1,1)+B(1,2))$$

$$P7 = (A(1,2)-A(2,2))*(B(2,1)+B(2,2))$$

$$C(1,1) = P1 + P4 - P5 + P7 \quad C(1,2) = P3 + P5$$

$$C(2,1) = P2 + P4$$

$$C(2,2) = P1 + P3 - P2 + P6$$

matrix multiply revisited divide and conquer ala Strassen

- *2 x 2 multiplication can be achieved with 7 multiplies - not 8*
- *tradeoffs*
 - *increase in storage*
 - *number of additions goes from 4 to 18*
- *complexity*
 - *$O(4.7 n^{2.81})$ vs $O(2 n^3)$*
 - *$n=1000$: $2n^3=2e9$; $4.7n^{2.81} \sim 1.27e9$*

- *$n \times n$ multiplication, n even*
- *partition matrices into $(n/2) \times (n/2)$ blocks*
 - *multiplies $\sim 2(n/2)^3$*
 - *adds $\sim (n/2)^2$*
- *complexity*
 - *$7 \times 2(n/2)^3 + 18 \times (n/2)^2 = (7/4)n^3 + (9/2)n^2$*
 - *for $n > 18$, Strassen has less complex operation count*

End Lecture 10