Appendix A: Software demonstration for Killing vectors

In this demonstration, we will illustrate the utility of the programs with the following names: MaxKT, BundleLift, rnk1TracConn, getRnk1, and liftrnk1.

First, we will read in the file which contains the programs we have written and load in other necessary packages.

```
> read "TractorPrograms.txt";
  with(DifferentialGeometry):
  with(Tensor):
```

Now, we will initialize a 2-dimensional manifold.

Next, we will define a simple metric.

M > g := evalDG(u^p * (du &t du + dv &t dv));

$$g := u^p du \otimes du + u^p dv \otimes dv$$
 (2)

We need to know the required size of the fibers of the tractor bundle. We find this to be 3:

$$M > MaxKT(2, 1);$$
 3 (3)

Now we initialize the required environments.

Now that the vector bundle has been initialized, it is convenient to redefine the metric on this bundle:

N > G := BundleLift(g, N);

$$G := u^p du \otimes du + u^p dv \otimes dv$$
(6)

We will also need the Christoffel symbols:

N > Gamma := Christoffel(G);

$$\Gamma := \nabla_{\partial_{u}} \partial_{u} = \frac{p}{2 u} \partial_{u}, \nabla_{\partial_{u}} \partial_{v} = \frac{p}{2 u} \partial_{v}, \nabla_{\partial_{v}} \partial_{u} = \frac{p}{2 u} \partial_{v}, \nabla_{\partial_{v}} \partial_{v} = -\frac{p}{2 u} \partial_{u}$$
 (7)

Now we can compute the tractor connection:

N > C := rnk1TracConn(Gamma, N);

$$C := \nabla_{\partial_{u}} E1 = -\frac{p}{2 u} E1, \nabla_{\partial_{u}} E2 = -\frac{p}{2 u} E2 + \frac{p}{2 u^{2}} E3, \nabla_{\partial_{u}} E3 = -E2 - \frac{p}{u} E3$$

$$, \nabla_{\partial_{v}} E1 = \frac{p}{2 u} E2 - \frac{p}{2 u^{2}} E3, \nabla_{\partial_{v}} E2 = -\frac{p}{2 u} E1, \nabla_{\partial_{v}} E3 = E1$$
(8)

We can also represent this connection as a matrix of 1-forms:

N > convert(C, DGMatrix);

$$-\frac{p}{2 u} du - \frac{p}{2 u} dv \qquad dv$$

$$\frac{p}{2 u} dv - \frac{p}{2 u} du - du$$

$$-\frac{p}{2 u^2} dv \frac{p}{2 u^2} du - \frac{p}{u} du$$
(9)

We now compute the Curvature tensor for the tractor connection.

N > K := CurvatureTensor(C);

$$K := \frac{p(2+p)}{2u^3} E3 \otimes \Theta1 \otimes du \otimes dv - \frac{p(2+p)}{2u^3} E3 \otimes \Theta1 \otimes dv \otimes du$$
 (10)

It is interesting to note that p=0 and p=-2 are the only values of p for which the curvature tensor vanishes identically.

We can represent this tensor as a collection of (1,1) tensors by contracting the curvature tensor with the coordinate vectors of the base manifold. In our 2-dimensional case, there is only one such (1,1) tensor, but there may be others in higher dimensions.

N > k1 := ContractIndices(K, evalDG(D_u &t D_v), [[3,1],[4,2]]);
$$k1 := \frac{p(2+p)}{2u^3} E3 \otimes \Theta1$$
 (11)

We can think of this as a matrix

N > K1 := convert(k1, DGMatrix);

$$K1 := \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \frac{1}{2} \frac{p(2+p)}{u^3} & 0 & 0 \end{bmatrix}$$
 (12)

and subsequently find the basis for the 0th order reduced tractor bundle:

N > IT0 := LieAlgebras:-InvariantTensors([K1], [seq(E||i,i=1..3)]);
$$IT0 \coloneqq [E2, E3] \tag{13}$$

This calculation is assuming that p is not 0 or 2: caution is advised when examining metrics with unknown constants as exponents. Assuming that p is not 0 or 2, there are a maximum of 2 Killing vectors of the metric g, since there are 2 invariants.

We will now try to get a tighter upper bound using the 1st order reduced tractor bundle. We begin by differentiating the curvature tensor.

N > dK1 := CovariantDerivative(k1, C);

$$dK1 := \frac{p(2+p)}{2u^3} E1 \otimes \Theta1 \otimes dv - \frac{p(2+p)}{2u^3} E2 \otimes \Theta1 \otimes du - \frac{p(2+p)(6+p)}{4u^4} E3 \qquad (14)$$

$$\otimes \Theta1 \otimes du + \frac{p^2(2+p)}{4u^4} E3 \otimes \Theta2 \otimes dv - \frac{p(2+p)}{2u^3} E3 \otimes \Theta3 \otimes dv$$

We now generate a set of (1,1) tensors by contraction:

N > D1K1 := ContractIndices(dK1, D_u, [[3,1]]);

$$D1K1 := -\frac{p(2+p)}{2u^3} E2 \otimes \Theta1 - \frac{p(2+p)(6+p)}{4u^4} E3 \otimes \Theta1$$
(15)

N > D2K1 := ContractIndices(dK1, D_v, [[3,1]]);

$$D2K1 := \frac{p(2+p)}{2u^3} E1 \otimes \Theta1 + \frac{p^2(2+p)}{4u^4} E3 \otimes \Theta2 - \frac{p(2+p)}{2u^3} E3 \otimes \Theta3$$
 (16)

Now we will convert them to matrices.

N > Md1k1 := convert(D1K1, DGMatrix);

$$Md1k1 := \begin{bmatrix} 0 & 0 & 0 & 0 \\ -\frac{1}{2} & \frac{p(2+p)}{u^3} & 0 & 0 \\ -\frac{1}{4} & \frac{p(2+p)(6+p)}{u^4} & 0 & 0 \end{bmatrix}$$
 (17)

N > Md2k1 := convert(D2K1, DGMatrix);

$$Md2k1 := \begin{bmatrix} \frac{1}{2} & \frac{p(2+p)}{u^3} & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & \frac{1}{4} & \frac{p^2(2+p)}{u^4} & -\frac{1}{2} & \frac{p(2+p)}{u^3} \end{bmatrix}$$
 (18)

And now we can compute a basis for the 1st order reduced tractor connection.

N > IT1 := LieAlgebras:-InvariantTensors([K1,Md1k1,Md2k1], [seq (E||i,i=1..3)]);
$$IT1 := \left[E2 + \frac{p}{2u}E3\right] \tag{19}$$

Thus, we get a maximum of 1 Killing vector. Let's be sure that our calculation doesn't depend on p not being 6, since p=6 appears, from looking at the matrices above, to be an exceptional value.

N > LieAlgebras:-InvariantTensors(eval([K1,Md1k1,Md2k1], p=6), [seq(E||i,i=1..3)]);
$$\left[E2 + \frac{3}{u} E3 \right]$$
 (20)

Now let's see if we can get the Killing vector explicitly. First, we form a linear combination of the 1st order reduced tractor basis elements with function coefficients.

N > s1 := DGzip([seq(q||i(u,v), i=1..nops(IT1))],IT1, "plus");

$$s1 := q1(u,v) E2 + \frac{q1(u,v) p}{2 u} E3$$
(21)

Next, we take the covariant derivative.

N > s2 := CovariantDerivative(s1, C);

$$s2 := -\left(-\left(\frac{\partial}{\partial u} q1(u, v)\right) + \frac{q1(u, v) p}{u}\right) E2 \otimes du + \frac{\partial}{\partial v} q1(u, v) E2 \otimes dv$$

$$+ \frac{p\left(\left(\frac{\partial}{\partial u} q1(u, v)\right) u - q1(u, v) p\right)}{2 u^2} E3 \otimes du + \frac{\left(\frac{\partial}{\partial v} q1(u, v)\right) p}{2 u} E3 \otimes dv$$

$$(22)$$

Let's look at the equations we need to solve.

N > s3 := DGinformation(s2, "CoefficientSet"); $s3 := \left\{ \frac{1}{2} \frac{p\left(\left(\frac{\partial}{\partial u} q1(u, v)\right) u - q1(u, v) p\right)}{u^2}, \frac{1}{2} \frac{\left(\frac{\partial}{\partial v} q1(u, v)\right) p}{u}, \frac{\partial}{\partial u} q1(u, v)\right\} \right\}$ (23)

$$-\frac{q1(u, v) p}{u}, \frac{\partial}{\partial v} q1(u, v)$$

How many equations are there?

$$N > nops(s3);$$

$$4$$
(24)

This is an easier system to solve than the Killing equations themselves, which has 3 equations and 2 unknown functions.

Let's get the solution:

N > s4 := pdsolve(s3, q||1(u,v));

$$s4 := \{q1(u,v) = C1u^p\}$$
(25)

Here is then what the parallel sections should look like:

N > s5 := DETools:-dsubs(s4, s1);

$$s5 := _C1 u^p E2 + \frac{_C1 u^p p}{2 u} E3$$
(26)

We may as well evaluate this at _C1=1.

N > s6 := eval(s5,_C1=1);

$$s6 := u^p E2 + \frac{u^p p}{2 u} E3$$
(27)

We check that it's a parallel section:

N > CovariantDerivative(s6, C);

$$0 E1 \otimes du$$
 (28)

Now we drop this parallel section down:

$$N > T := getRnk1(s6, N);$$

$$T := u^p dv$$
(29)

Let's check that this is a Killing tensor of rank 1.

N > CheckKillingTensor(G, T);

$$0 du \otimes du$$
 (30)

If the contravariant vector is desired, we can simply raise indices:

N > X := RaiseLowerIndices(InverseMetric(G), T, [1]);
$$X \coloneqq \partial_{y}$$
 (31)

Now let's check that we can lift the Killing tensors of the metric to parallel sections. We begin by calculating the Killing tensors conventionally.

N > kt1 := KillingTensors(G, 1);

$$kt1 := [u^p dv]$$
 (32)

As there is only one, we will lift this individually rather than lift the list. Note that the Christoffel symbols of G are needed.

N > liftkt1 := liftrnk1(kt1[1], Gamma, N);

$$liftkt1 := u^p E2 + \frac{u^{p-1} p}{2} E3$$
(33)

Let's check that this is a parallel section.

N > CovariantDerivative(liftkt1, C);

$$0 E1 \otimes du$$
 (34)

But are there more parallel sections?

N > Covariantly Constant Tensors (C, [seq(E||i,i=1..3)]);
$$\left[\frac{2 u^{p}}{p} E2 + u^{p-1} E3\right]$$
 (35)

Since there is only 1, which corresponds with our known parallel section, the parallel sections and the Killing vectors are in one-to-one correspondence.