

# Benjamin Shih

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http://benshih.github.io

United States Citizen  
https://github.com/benshih

## Education

University of California, San Diego  
Ph.D. Mechanical and Aerospace Engineering

San Diego, CA  
August 2015 - present

Carnegie Mellon University  
M.S. Electrical and Computer Engineering  
B.S. Electrical and Computer Engineering

Pittsburgh, PA  
August 2013 - December 2013  
August 2009 - May 2013

## Skills

**Software:** MATLAB, Eagle, SolidWorks, LaTeX, Git, Cadence, ProTools

**Electronics:** soldering, oscilloscope, function generator, multimeter, circuit simulation, PCB board design, microcontroller programming

**Coding:** C++, Python, Java, C, HTML

**Languages:** English (proficient), Mandarin Chinese (speaking), Spanish (basic)

## Experiences

### Bioinspired Robotics and Design Lab, UCSD

*Graduate Research Assistant*

San Diego, California  
September 2015 - present

- Soft robotics, proprioceptive sensing, pneumatic actuation.
- Advised by: Prof. Michael Tolley

### Momentum Machines

*Embedded Software Engineering Intern*

San Francisco, California  
May 2015 - August 2015

- Food technology startup using robotics and automation to produce gourmet food.
- Requirements gathering and electronics interfacing of dozens of sensors and actuators. Used an ARM-based microcontroller.
- Lead engineer for PCB fabrication of 6 unique boards with a design firm.
- Statecharts (finite state machine) software architecture for embedded control. Used a web-based graphical user interface to facilitate rapid prototyping and fast system bringup.
- Prototyped and tested various subsystem mechanisms for mechanical engineering team.
- Advised by: Jeff Jensen, Ali Rathore.

### Reconfigurable Robotics Lab, EPFL

*Research Assistant, École Polytechnique Fédérale de Lausanne*

Lausanne, Switzerland  
May 2014 - April 2015

- Built untethered, locomotive robot using soft pneumatic actuators (SPAs).
- Experimented with actuator frames to improve actuation consistency.
- Automated SPA testing using computer vision.
- Advised by: Prof. Jamie Paik, Dr. Juan Manuel Florez.

## Honors

Semifinalist, Hackaday Prize 2015

August 2015

UCSD Departmental Fellowship

February 2015

Winner, Intel Internet of Things Hackathon, Berlin (1500 EUR)

April 2015

Finalist (top 25 out of 101 projects), HackZurich Hackathon

October 2014

Scholarship of Excellence in Research at EPFL (20k CHF)

February 2014

Small Undergraduate Research Grant, Carnegie Mellon University (500 USD)

November 2011

NanoJapan NSF International Research Experience for Undergraduates Program

February 2011

Intel Science Talent Search, Semifinalist (1000 USD)

January 2009

## Conference Publications

J. M. Florez, **B. Shih**, Y. Bai, J. Paik. "Soft Pneumatic Actuators for Legged Locomotion". IEEE International Conference on Robotics and Biomimetics (ROBIO 2014), Bali, Indonesia. December 2014. Acceptance rate: 58.6% (374 of 638).