

# Benjamin Shih

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benshih.github.io

## Education

University of California, San Diego  
Ph.D. Mechanical and Aerospace Engineering

San Diego, CA  
August 2015 - present

Carnegie Mellon University  
M.S. Electrical and Computer Engineering  
B.S. Electrical and Computer Engineering

Pittsburgh, PA  
August 2013 - December 2013  
August 2009 - May 2013

## Skills

**Software:** MATLAB, Eagle, SolidWorks, LaTeX, Git, Cadence, ProTools

**Electronics:** PCB design, microcontrollers, circuit simulation, oscilloscope, function generator, multimeter

**Coding:** C++, Python, Java, C, HTML

**Languages:** English (proficient), Mandarin Chinese (speaking), Spanish (basic)

## Experiences

### Bioinspired Robotics and Design Lab, UC San Diego

San Diego, California

*Graduate Research Assistant*

September 2015 - present

- Soft robotics and sensing, pneumatic actuation, computer vision, human-robot interaction, virtual reality.
- Advised by: Prof. Michael Tolley

### OpenWorm

*Community Manager*

October 2015 - present

- Volunteer coordinator for open source neuroscience project creating virtual simulation of *C. elegans*.
- Organized online series of OpenWorm Journal Clubs. Five archived YouTube videos with ~1300 views.
- Advised by: Dr. Stephen Larson

### Momentum Machines

San Francisco, California

*Embedded Software Engineering Intern*

May 2015 - August 2015

- Food technology startup using robotics and automation to produce gourmet food.
- Lead engineer for PCB fabrication of 6 unique boards with a design firm.
- Statecharts (finite state machine) software architecture for embedded control. Used a web-based graphical user interface to facilitate rapid prototyping and fast system bringup.
- Advised by: Jeff Jensen, Ali Rathore.

### Reconfigurable Robotics Lab, EPFL

Lausanne, Switzerland

*Research Assistant, École Polytechnique Fédérale de Lausanne*

May 2014 - April 2015

- Built untethered, locomotive robot using soft pneumatic actuators (SPAs).
- Experimented with actuator frames to improve actuation consistency.
- Advised by: Prof. Jamie Paik, Dr. Juan Manuel Florez.

## Honors

UC San Diego Irwin Jacobs School of Engineering Fellowship (154k USD)

February 2015

Winner, Intel Internet of Things Hackathon, Berlin (1.5k EUR)

April 2015

Finalist (top 25 out of 101 projects), HackZurich Hackathon

October 2014

Scholarship of Excellence in Research at EPFL (20k CHF)

February 2014

## Publications

A. Minori, **B. Shih**, C. Christianson, M. T. Tolley. "3D Printed Shape Memory Polymer Composite for Fabric Actuation". Robot Makers Workshop at Robotics: Science and Systems (RSS), Michigan, USA. June 2016.

P. Tandon, S. Lam, **B. Shih**, T. Mehta, A. Mitev, Z. Ong. "Quantum Robotics: Primer on Current Science and Future Perspectives". Working paper, ResearchGate. May 2016.

J. M. Florez, **B. Shih**, Y. Bai, J. Paik. "Soft Pneumatic Actuators for Legged Locomotion". IEEE International Conference on Robotics and Biomimetics (ROBIO 2014), Bali, Indonesia. December 2014. Acceptance rate: 58.6% (374 of 638).