

Analytical Methods for Weakly Nonlinear Oscillators and the Two-Timing Approach: The Duffing Equation

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Abstract

- The simple harmonic oscillator, a mass attached to a spring, is governed by the second order linear differential equation, $\ddot{x} + b\dot{x} + kx = 0$ where x is vertical position, m is mass, b the damping coefficient, and k the spring constant
- Its general solution without damping is found easily, such that $x(t) = A \cos t + B \sin t$
- The **Duffing equation** is governed by the *nonlinear* differential equation, $\ddot{x} + x + \epsilon x^3 = 0$. A loose approximation of its solution can be found using perturbation theory. While it works, the solution contains a **secular** term, and grows exponentially in time
- To soothe this, the method of **two-timing** is introduced, defining 'slow' and 'fast' time, and the secular term is removed
- From here, the efficacy of ϵ can be determined

The Duffing Equation

Nonlinear oscillators are subset of oscillatory differential equations. The Duffing equation is defined by $\ddot{x} + x + \epsilon x^3 = 0$. The equation is termed *weakly nonlinear* as $\epsilon \ll 1$. The solution to the Duffing equation must be started with perturbation theory, assuming $x(t)$ is analytic. This equation also has a limit cycle about the origin, a circular orbit in which trajectories get 'caught'. Below is the phase plane for the Duffing equation. [1]

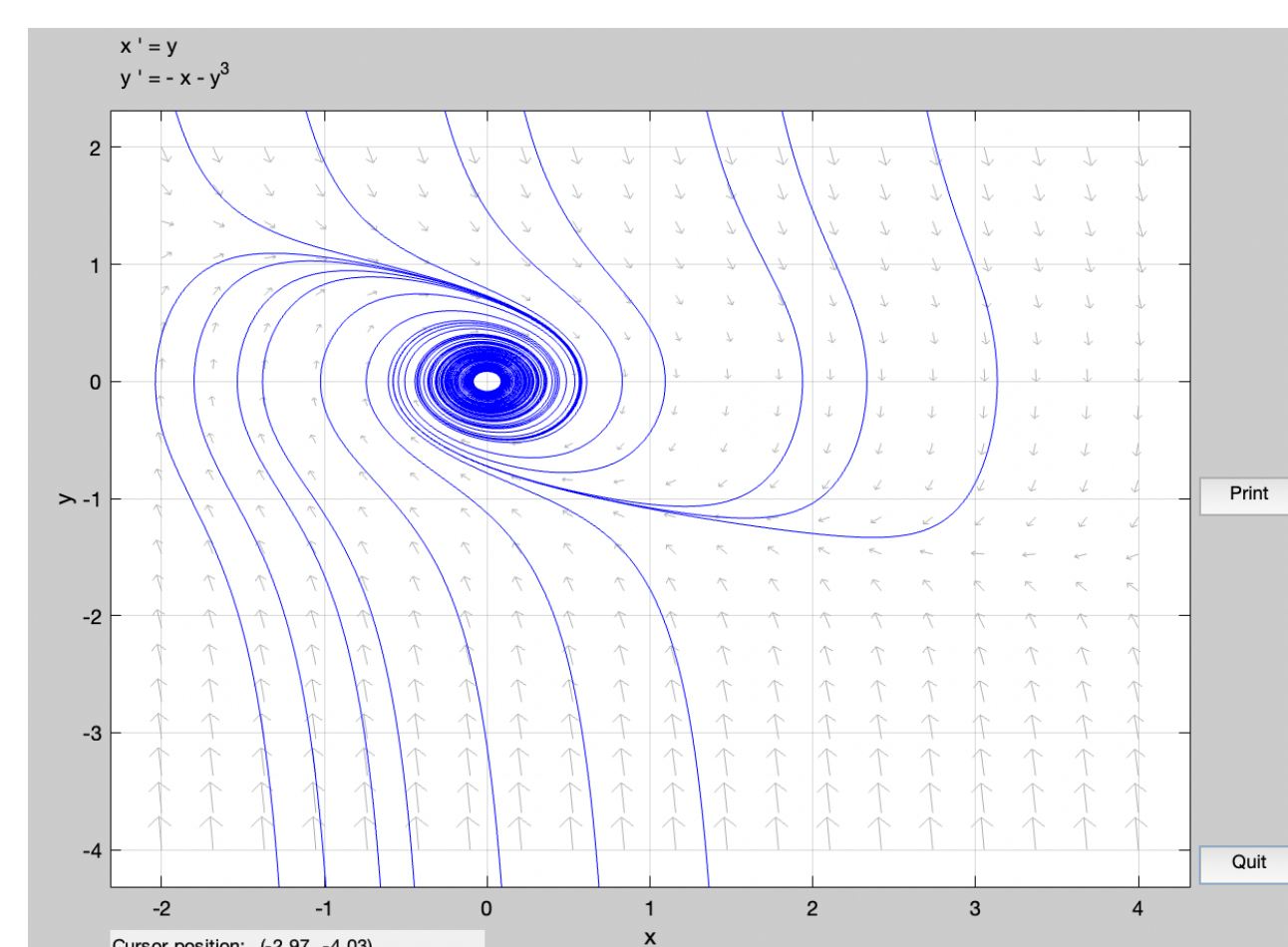


Figure 1: Phase plane for the Duffing equation

Breakdown of Motion

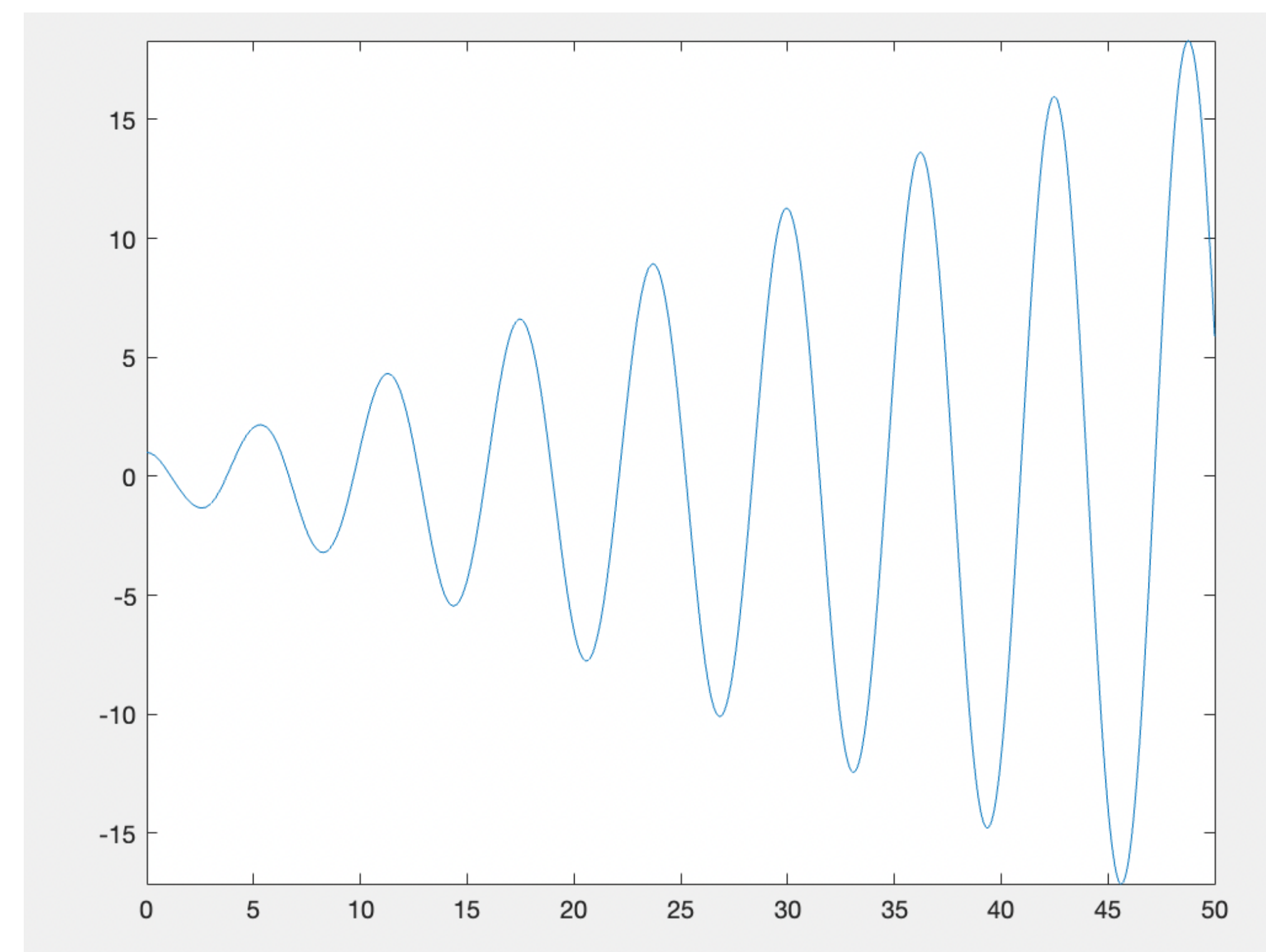


Figure 2: The failure of perturbation theory for the Duffing equation

Applying a Typical Perturbation Method

We attempt to find a solution using perturbation theory. Let x have a power series expansion in powers of ϵ and functions of t , such that:

$$x(t) = x_0(t) + \epsilon x_1(t) + \epsilon^2 x_2(t) + O(\epsilon^3) \quad (1)$$

Substitution into the Duffing equation up to powers of linear ϵ gives:

$$\ddot{x}_0 + x_0 = 0 \implies x_0(t) = \cos(t) \quad (2)$$

$$x_1(t) = \frac{1}{32}(\cos(3t) - \cos(t)) - \frac{3}{8}t \sin(t) \quad (3)$$

Finding $x_0(t)$ and $x_1(t)$ allows us to substitute them back into the perturbation approximation [2]. This gives a first order approximation of the solution to the Duffing equation:

$$x(t) = \cos(t) + \epsilon(x_1(t) = \frac{1}{32}(\cos(3t) - \cos(t)) - \frac{3}{8}t \sin(t)) \quad (4)$$

Important Result

The first order approximation produces a **secular term**, note the 't' in the analytical solution. When plotting the solution, we can immediately see the issue. The graph of $x(t)$ grows exponentially in time, going against the motion prescribed by the differential equation. To soothe this, we must employ other methods

Two-Timing

To remove the secular term, we begin by introducing a second time scale, scaled by a parameter α , and reapply perturbation theory

$$\tau = \alpha t \quad (5)$$

$$\alpha = \alpha_0 + \epsilon \alpha_1 + \epsilon^2 \alpha_2 + O(\epsilon^3) \quad (6)$$

$$\implies \alpha^2 \ddot{x}(\tau) + x(\tau) + \epsilon x^3(\tau) \quad (7)$$

$$x_0(\tau) = \cos(\tau) \quad (8)$$

$$x_1(\tau) = \frac{1}{32}(\cos(3\tau) - \cos(\tau)) + (\alpha_1 - \frac{3}{8})\tau \sin(\tau) \quad (9)$$

$$\implies x(t) \approx \cos((1 + \frac{3}{8}\epsilon)t) + \frac{1}{32}\epsilon(\cos((3 + \frac{9}{8}\epsilon)t) - \cos((1 + \frac{3}{8}\epsilon)t)) + O(\epsilon^2) \quad (10)$$

Results

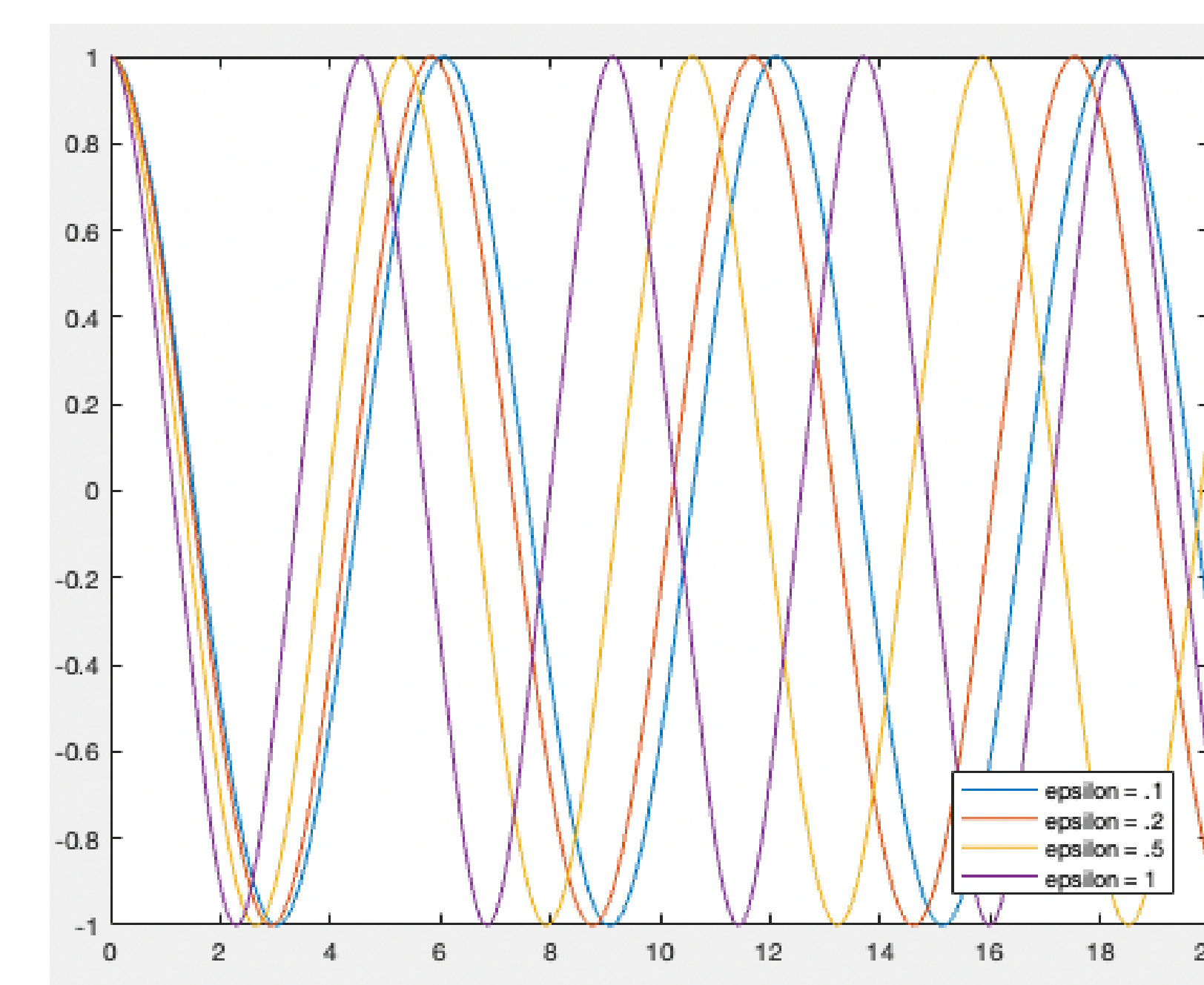


Figure 3: Various analytical solutions to the Duffing equation

Conclusion

The first order two-timed solution is represented by (10). By scaling time in two different dimensions, we are able to derive a solution that is more synonymous with the motion of the oscillator. Although, we must still be conscious of ϵ , as the motion breaks down if the parameter is tended too high.

Additional Information

From here, my research will continue by looking at examples of other oscillators and the underpinnings of perturbation theory. The next step is to time oscillators three-fold, adding an additional parameter to ensure the solution is even more exact.

References

- [1] S. Strogatz.
Nonlinear Dynamics and Chaos.
Westview Press, 2nd edition, 2015.
- [2] H. A Salas.
An elementary solution to a duffing equation.
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Acknowledgements

I'd like to thank Dr. Kyle Zhao and Dr. Lisa Fauci for their mentorship and insights throughout my studies. Their contributions to applied mathematics are forever appreciated.

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