Computational Fluid Dynamics Problem Set #4

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1 Functions Used

```
# Introduction
    # In the vorticity-streamfunction formulation, the steady, incompressible flow
    # in the cavity is governed by the vorticity-transport equation
     # u(/x) + v(/y) = (1/Re)((2/x2)+(2/y2)), (1) 
    # and a Poisson equation for the streamfunction
    \# 2/x2 + 2/y2 = . (2)
    # The boundary condition for (2) is = 0 on all boundaries.
    # Using the ADI Poisson solver you developed in Problem Set #2 and your
    # ADI algorithm for the scalar transport equation developed in Problem Set
    # 3,
    # develop an iterative algorithm to solve the coupled equations (1) and (2).
    # 1. Use Thom's method to obtain Dirichlet boundary conditions for the vorticity
    # transport equation,
    # 2. use central difference approximations to evaluate the
    # definitions of the streamfunction, u = /y, v = /x, to obtain updated
    # values of the velocities u(x, y) and v(x, y) for use in this equation. Obtain
    # solutions for Re = 0 and Re = 100 on a 101 \times 101 grid. If possible plot the
    # streamlines and the iso-vorticity lines. Note that it may be necessary to use
    # different acceleration parameters for each equation.
    # Obtain what you regard to be grid-independent solutions for higher Reynolds
     # numbers
```

```
# Grid:
                   # Set-up a, b, c, for the Thomas algorithm
                  a = np.zeros(N)
                  b = np.zeros(N)
                  c = np.zeros(N)
                  d = np.zeros(N)
for i in range(1, N-1):
                                     for j in range(0, N):
# a b c for Thomas
                                                        if v[i,j] > 0.:
                                                                           a[j] = alpha + v[i,j]*delta
                                                                           b[j] = -(2.*alpha + v[i,j]*delta + sigma)
                                                                           c[j] = alpha
                                                        elif v[i,j] < 0.:
                                                                           a[j] = alpha
                                                                          b[j] = -2.*alpha + v[i,j]*delta - sigma
                                                                           c[j] = alpha - v[i,j]*delta
                                                        else: # v[i,j] == 0
                                                                          a[j] = alpha
                                                                          b[j] = -2.*alpha - sigma
                                                                          c[j] = alpha
# d for dirchlet BC
                                     for j in range(0, N):
                                                        if u[i,j] > 0.:
                                                                           d[j] = (-alpha - u[i,j]*delta)*phi[i-1,j] + (2.*alpha + (2.*alph
   \rightarrowu[i,j]*delta -sigma)*phi[i,j] + -alpha*phi[i+1,j]
                                                        elif u[i,j] < 0.:
                                                                           d[j] = (-alpha)*phi[i-1,j] + (2.*alpha - u[i,j]*delta_{\sqcup})
    \rightarrow-sigma)*phi[i,j] + (-alpha + u[i,j]*delta)*phi[i+1,j]
                                                        else: \# u[i, j] == 0
                                                                           d[j] = (-alpha)*phi[i-1,j] + (2.*alpha - sigma)*phi[i,j] + (2.*alpha - sigma)*phi[i,j] + (2.*alpha - sigma)*phi[i,j] + (3.*alpha - sigma)*phi[i,j] + (3.*a
    \rightarrow-alpha*phi[i+1,j]
# BC's for Thomas
                                     left = [1., 0., phi[i, 0]]
```

```
right = [1., 0., phi[i, N-1]]
# Solve i's column:
                       phi[i, :] = thomas(N, delta, a, b, c, d, left, right)
for j in range(1, N-1):
                       for i in range(0, N):
# a b c for Thomas
                                   if u[i,j] > 0.:
                                               a[i] = alpha + u[i,j]*delta
                                               b[i] = -(2.*alpha + u[i,j]*delta + sigma)
                                               c[i] = alpha
                                   elif u[i,j] < 0.:
                                               a[i] = alpha
                                               b[i] = -2.*alpha + u[i,j]*delta - sigma
                                               c[i] = alpha - u[i,j]*delta
                                   else: # u[i, j] == 0
                                               a[i] = alpha
                                               b[i] = -2.*alpha - sigma
                                               c[i] = alpha
# d coefficient for dirchlet BC
                       for i in range(0, N):
                                   if v[i,j] > 0.:
                                               d[i] = (-alpha - v[i,j]*delta)*phi[i,j-1] + (2.*alpha + (2.*alph
   →v[i,j]*delta -sigma)*phi[i,j] + -alpha*phi[i,j+1]
                                   elif v[i,j] < 0.:
                                               d[i] = (-alpha)*phi[i,j-1] + (2.*alpha - v[i,j]*delta_{l}
   \rightarrow-sigma)*phi[i,j] + (-alpha + v[i,j]*delta)*phi[i,j+1]
                                   else: # v[i,j] == 0
                                               d[i] = (-alpha)*phi[i,j-1] + (2.*alpha - sigma)*phi[i,j] + 
  \rightarrow-alpha*phi[i,j+1]
# BC's for Thomas
                       left = [1., 0., phi[0, j]]
                       right = [1., 0., phi[N-1, j]]
```

```
# Solve j's row:
    phi[:, j] = thomas(N, delta, a, b, c, d, left, right)
# Compare the new solution to the previous iteration's solution
return(phi)
```

```
def poisson_solver(1, I, f, u, sigma):
        import numpy as np
        from thomas_algorithm import thomas
        N = I + 1 \# Number of gridpoints
        delta = 1/I # Length of the subinterval
    # Horizontal solves:
        for j in range(1, N-1):
            a = np.full((N), 1.) # Lower diagonal
           b = np.full(N, -2. -sigma) # Main diagonal
            c = np.full((N), 1.) # Upper diagonal
            d = delta**2 * f[:, j] - u[:, (j + 1)] + (2. - sigma) * u[:, j] - u[:, (j_u)]
     →- 1)]
            left = [1., 0., u[0, j]]
            right = [1., 0., u[N-1, j]]
            u[:, j] = thomas(N, delta, a, b, c, d, left, right)
    # Vertical Solves
        for i in range(1, N-1):
            a = np.full((N), 1.) # Lower diagonal
            b = np.full(N, -2. -sigma) # Main diagonal
            c = np.full((N), 1.) # Upper diagonal
            d = delta**2. * f[i, :] - (u[(i+1), :] - (2.-sigma) * u[i, :] + u[(i-1), u]
     →:]) # Interior
            left = [1., 0., u[i, 0]]
            right = [1., 0., u[i, N-1]]
            u[i, :] = thomas(N, delta, a, b, c, d, left, right)
        u = u - u[N//2, N//2] # recenter
        #u = u - u[N//2, N//2]
```

return(u)

```
# Create solver that uses both vorticity transoport and streamfunction solvers
   def solver(I, Re, tol, sigma_Vort, sigma_Stream):
      import numpy as np
      import copy
    1 = 1. # domain length
      N = I + 1 \# number of grids
      delta = 1 / I # change between grids
      alpha = 1./Re # relationshiop found for alpha by derivations
    # Initialize arrays for vorticity and streamfunction
      omega = np.zeros((N, N)) # vorticity
      psi = np.zeros((N, N)) # stream function
    # Initialize the arrays of velocities
      u = np.zeros((N, N))
      v = np.zeros((N, N))
    # convergence criterion and iteration counter
      iteration = 0 # iteration counter
      e_Vort = 1. # convergence criterion for vorticity
      e_Stream = 1. # convergence criterion for streamfunction
    while (e_Vort > tol) or (e_Stream > tol):
    # Store past voricity matrix to compare to
          prev_omega = copy.copy(omega)
    # Compute the velocity field from the streamfunction
          for i in range(1, N-1):
             for j in range(1, N-1):
                u[i, j] = (psi[i, j+1] - psi[i, j-1]) / (2.* delta)
                v[i, j] = (psi[i-1, j] - psi[i+1, j]) / (2.* delta)
```

```
# BC's for vorticity
       omega[:, 0] = (2./ delta**2) * (psi[:, 0] - psi[:, 1]) # Lower BC
       omega[:, N-1] = (2./ delta**2) * (psi[:, N-1] - psi[:, N-2] - delta) #__
 → Upper BC
       omega[0, :] = (2./ delta**2) * (psi[0, :] - psi[1, :]) # Left BC
       omega[N-1, :] = (2./ delta**2) * (psi[N-1, :] - psi[N-2, :]) # Right BC
# Use transport function to calculate vortivity
       omega = transport(1, I, alpha, u, v, omega, sigma_Vort)
# Convergence Check For Vorticity
       diff_omega = omega - prev_omega # difference between current and pastu
→ iteration of vorticity
       enumer_omega = abs(max(diff_omega.min(), diff_omega.max(), key=abs))
       edenom_omega = abs(max(omega.min(), omega.max(), key=abs))
       e_Vort = enumer_omega / edenom_omega # new convergence error for_
 \rightarrowvorticity
# store past iteration of streamfunction
       prev_psi = copy.copy(psi)
# Use poisson solver for streamfunction
       psi = poisson_solver(1, I, -omega, psi, sigma_Stream)
# Convergence check for the streamfunction:
       diff_psi = psi - prev_psi
       enumer_psi = abs(max(diff_psi.min(), diff_psi.max(), key=abs))
       edenom_psi = abs(max(psi.min(), psi.max(), key=abs))
       e_Stream = enumer_psi / edenom_psi
# Add to iteration
       iteration = iteration + 1
```

2 Case 1: Re = 100

2.1 Convergence

2.1.1 Convergence Code

2.1.2 Convergence Results

For Re = 100, and I = 101 grid divisions. The solution has converged in 1048 iterations

The convergence criterion of e_omega = 1.3782732995474474e-07 for vorticity,

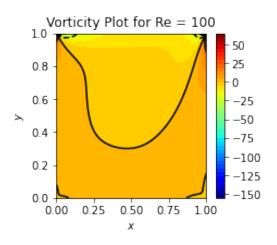
2.2 Plots

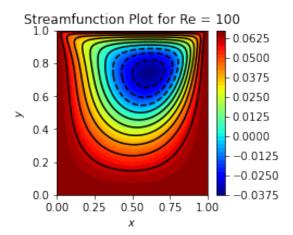
2.2.1 Code for Plots

```
import matplotlib.pyplot as plt
    import scipy.constants
    N = T+1
    1 = 1.
    delta = 1 / I
    x = np.linspace(0, 1, N)
    y = np.linspace(0, 1, N)
    X, Y = np.meshgrid(x, y)
    fsy=6
    fig = plt.figure(figsize = (1.25*fsy, fsy)) # Set the figure size to square
    left = 0.1 # the left side of the subplots of the figure
    right = 0.9 # the right side of the subplots of the figure
    bottom = 0.15 # the bottom of the subplots of the figure
    top = 0.5 # the top of the subplots of the figure
    wspace = 0.5 # the amount of width reserved for space between subplots,
    # expressed as a fraction of the average axis width
    hspace = .25 # the amount of height reserved for space between subplots,
    # expressed as a fraction of the average axis height
    plt.subplots_adjust(left, bottom, right, top, wspace, hspace)
    # plot vorticity
    plt.subplot(1,2,1)
    plt.contourf(Y, X, omega, 50, cmap = 'jet')
    plt.colorbar()
    plt.contour(Y, X, omega, 10, colors = 'k')
    plt.title('Vorticity Plot for Re = 100')
    plt.xlabel("$x$")
    plt.ylabel("$y$")
    # plot streamfunction
    plt.subplot(1,2,2)
    plt.contourf(Y, X, psi, 50, cmap = 'jet')
    plt.colorbar()
    plt.contour(Y, X, psi, 10, colors = 'k')
    plt.title('Streamfunction Plot for Re = 100')
    plt.xlabel("$x$")
    plt.ylabel("$y$")
```

plt.show()

2.2.2 Results for Plots





3 Case 2: Re = 0

An important note prior to beginning is the Re = 0 would lead to an undefined solution due to a division by zero. Therefore, Re = 0.1 will be used instead to approximate the case for Re = 0.

3.1 Convergence

3.1.1 Convergence Code

3.1.2 Convergence Results

For Re = 0, and I = 101 grid divisions. The solution has converged in 672 iterations

The convergence criterion of $e_{omega} = 8.353445290779422e-08$ for vorticity, and $e_{omega} = 9.883159456997435e-06$ for streamfunction was achieved

3.2 Plots

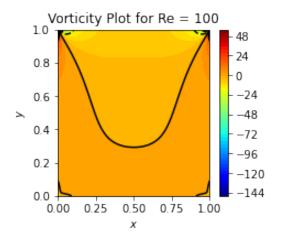
3.2.1 Code for Plots

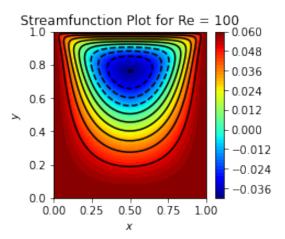
```
import matplotlib.pyplot as plt
     import scipy.constants
     N = I+1
     1 = 1.
     delta = 1 / I
     x = np.linspace(0, 1, N)
     y = np.linspace(0, 1, N)
     X, Y = np.meshgrid(x, y)
     fsv=6
     fig = plt.figure(figsize = (1.25*fsy, fsy)) # Set the figure size to square
     left = 0.1 # the left side of the subplots of the figure
     right = 0.9 # the right side of the subplots of the figure
     bottom = 0.15 # the bottom of the subplots of the figure
     top = 0.5 # the top of the subplots of the figure
     wspace = 0.5 # the amount of width reserved for space between subplots,
     # expressed as a fraction of the average axis width
     hspace = .25 # the amount of height reserved for space between subplots,
     # expressed as a fraction of the average axis height
     plt.subplots_adjust(left, bottom, right, top, wspace, hspace)
     # plot vorticity
     plt.subplot(1,2,1)
     plt.contourf(Y, X, omega, 50, cmap = 'jet')
```

```
plt.colorbar()
plt.contour(Y, X, omega, 10, colors = 'k')
plt.title('Vorticity Plot for Re = 100')
plt.xlabel("$x$")
plt.ylabel("$y$")

# plot streamfunction
plt.subplot(1,2,2)
plt.contourf(Y, X, psi, 50, cmap = 'jet')
plt.colorbar()
plt.contour(Y, X, psi, 10, colors = 'k')
plt.title('Streamfunction Plot for Re = 100')
plt.xlabel("$x$")
plt.ylabel("$y$")
```

3.2.2 Results for Plots





4 Case 3: Grid Independence for Higher Reynolds Numbers

Grid independence of higher Reynolds numbers was found by first looking at how vorticity and streamfunction changes with respect to a varying Reynolds number. Keeping grid size constant, Reynolds number was change from 10 to 180 with a step of 10 each time.

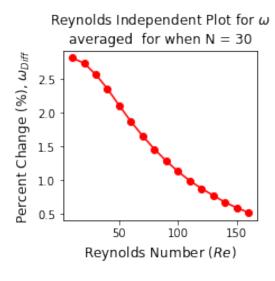
4.1 Varying Reynolds Number

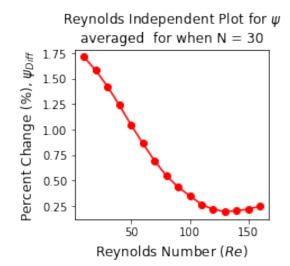
4.1.1 Code

```
# Grid indpendence for high reynolds numbers, solve by increasing reynolds
    # number increasing and investigationg how it changes.
     # Use 30 grid intervals to test changing reynolds number
     # Essentially find Reynolds number independence to find grid independence
    # Grid independence will be determined by looking at the change in the average
    # phi, both cases of alpha will be observed
    import numpy as np
    import matplotlib.pyplot as plt
    # Changing Reynolds Number
    k = np.arange(10, 180, 10)
    test_5 = []
    for Re in k:
                  # (N, Re, tolerance, sigma, sigma)
        test5 = solver(30, Re, 1e-5, 0.3, 1.49)
        test_5.append(test5)
```

```
# Plots
# Convergence Plot (Change in Vorticity vs. Reynolds)
fsy=6
fig = plt.figure(figsize = (1.25*fsy, fsy)) # Set the figure size to square
left = 0.1 # the left side of the subplots of the figure
right = 0.9 # the right side of the subplots of the figure
bottom = 0.15 # the bottom of the subplots of the figure
top = 0.5 # the top of the subplots of the figure
wspace = 0.5 # the amount of width reserved for space between subplots,
# expressed as a fraction of the average axis width
hspace = .25 # the amount of height reserved for space between subplots,
# expressed as a fraction of the average axis height
plt.subplots_adjust(left, bottom, right, top, wspace, hspace)
plt.subplot(1,2,1)
plt.plot(k[0:-1], omega_diff1, color = 'r', marker = 'o')
plt.xlabel('Reynolds Number $(Re)$', fontsize =12)
plt.ylabel('Percent Change (%), $\omega_{Diff}$ ', fontsize =12)
plt.title('Reynolds Independent Plot for $\omega$ \naveraged for when N = 30')
# Convergence Plot (Change in Streamfunction vs. Reynolds)
plt.subplot(1,2,2)
plt.plot(k[0:-1], psi_diff1, color = 'r', marker = 'o')
plt.xlabel('Reynolds Number $(Re)$', fontsize =12)
plt.ylabel('Percent Change (%), $\psi_{Diff}$$ ', fontsize =12)
plt.title('Reynolds Independent Plot for $\psi$ \naveraged for when N = 30')
plt.show()
# now check convergence based on change in omega For vorticity
for l in range(0, len(omega_diff1)):
   if abs(omega_diff1[1]) < 1.0:</pre>
       break
Num\_reynol = k[1]
print(' For a Reynolds independent solution with less than 1.0% change in
⇔vorticity, requrires, '
     'a Reynolds Number =', Num_reynol, 'for a reynolds independent solution.')
# now check convergence based on change in omega For streamfunction
for l in range(0, len(psi_diff1)):
```

4.1.2 Plots and Results





For a Reynolds independent solution with less than 1.0% change in vorticity, requrires, a Reynolds Number = 110 for a reynolds independent solution.

For a Reynolds independent solution with less than 1.0% change in streamfunction, requrires, a Reynolds Number = 60 for a reynolds independent solution.

Since the Reynolds number independence was difference for vorticity and the streamfunciton, Re = 110 was chosen to look at for grid independence since it is the higher Reynolds to chose.

4.2 Grid Independence for Re = 110

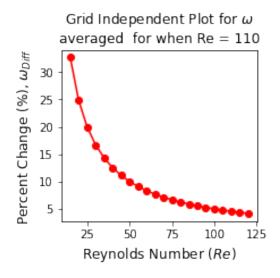
4.2.1 Code

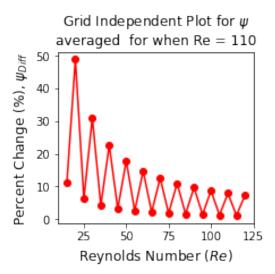
```
# Plot of grid independence from results where Re is independent at
     # Re = 110
     # Understand and interpret data to check reynolds number
     # Take average of vorticity and streamline for whole contour plot in
     # this case
     omega_diff1 = np.zeros(len(k)-1) # vorticity
     psi_diff1 = np.zeros(len(k)-1) # streamfunction
     for r in range(0,len(k)-1):
        omega1, omega_avg1, psi1, psi_avg1, I, e_Vort, e_Stream, iteration, dx, l = __
      →test_5[r]
        omega2, omega_avg2, psi2, psi_avg2, I, e_Vort, e_Stream, iteration, dx, l = ___
      \rightarrowtest_5[r+1]
        omega_diff1[r] = ((abs(omega_avg1 - omega_avg2)) / abs(omega_avg1 )) * 100
        psi_diff1[r] = ((abs(psi_avg1 - psi_avg2)) / psi_avg1 ) * 100
     # Plots
     # Convergence Plot (Change in Vorticity vs. Grid Number)
     fsy=6
     fig = plt.figure(figsize = (1.25*fsy, fsy)) # Set the figure size to square
     left = 0.1 # the left side of the subplots of the figure
```

```
right = 0.9 # the right side of the subplots of the figure
bottom = 0.15 # the bottom of the subplots of the figure
top = 0.5 # the top of the subplots of the figure
wspace = 0.5 # the amount of width reserved for space between subplots,
# expressed as a fraction of the average axis width
hspace = .25 # the amount of height reserved for space between subplots,
# expressed as a fraction of the average axis height
plt.subplots_adjust(left, bottom, right, top, wspace, hspace)
plt.subplot(1,2,1)
plt.plot(k[0:-1], omega_diff1, color = 'r', marker = 'o')
plt.xlabel('Reynolds Number $(Re)$', fontsize =12)
plt.ylabel('Percent Change (%), $\omega_{Diff}$ ', fontsize =12)
plt.title('Grid Independent Plot for $\omega$ \naveraged for when Re = 110')
# Convergence Plot (Change in Streamfunction vs. Number)
plt.subplot(1,2,2)
plt.plot(k[0:-1], psi_diff1, color = 'r', marker = 'o')
plt.xlabel('Reynolds Number $(Re)$', fontsize =12)
plt.ylabel('Percent Change (%), $\psi_{Diff}$ ', fontsize =12)
plt.title('Grid Independent Plot for $\psi$ \naveraged for when Re = 110')
plt.show()
# now check convergence based on change in omega For vorticity
for l in range(0, len(omega_diff1)):
   if abs(omega_diff1[1]) < 5.0:
       break
Num_grid_points = k[1]
print('For a grid independent solution with less than 5.0% percent change in ⊔
 →streamfunction requires, '
      'Number of grid points =', Num_grid_points,'\n for a grid independent
→solution. ' )
# now check convergence based on change in omega For streamfunction
for l in range(0, len(psi_diff1)):
   if abs(psi_diff1[1]) < 5.0:</pre>
       break
Num_grid_points = k[1]
print('For a grid independent solution with less than 5.0% percent change in ⊔
 →streamfunction requires, '
```

```
'Number of grid points =', Num_grid_points,'\n for a grid independent⊔ ⇔solution. ')
```

4.2.2 Results





For a grid independent solution with less than 5.0% percent change in streamfunction requires, Number of grid points = 100 for a grid independent solution.

For a grid independent solution with less than 5.0% percent change in streamfunction requires, Number of grid points = 35 for a grid independent solution.

Looking at the results and choosing the higher number of grid points as the grid independence solution. The observation can be made that grid independence occurs for a 100 grid points. Next we will look at the solution for 100 grids.

```
print("The convergence criterion of e_omega = ", e_Vort, " for vorticity, and \cup e_psi = ", e_Stream, " for streamfunction was achieved ")
```

For Re = 0, and I = 101 grid divisions. The solution has converged in 1287 iterations

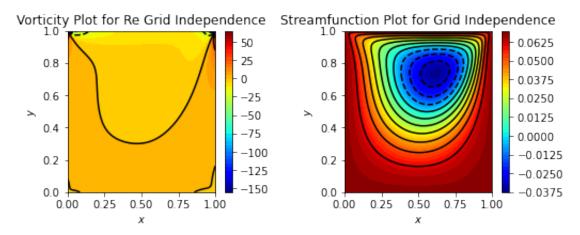
The sequences criterion of a error = $\frac{1}{2}$ 65556709210154290 07, for vertical

The convergence criterion of $e_omega = 1.6555679831015428e-07$ for vorticity, and $e_psi = 9.978726872391717e-06$ for streamfunction was achieved

```
import matplotlib.pyplot as plt
     import scipy.constants
     N = I+1
     1 = 1.
     delta = 1 / I
     x = np.linspace(0, 1, N)
     y = np.linspace(0, 1, N)
     X, Y = np.meshgrid(x, y)
     fsy=6
     fig = plt.figure(figsize = (1.25*fsy, fsy)) # Set the figure size to square
     left = 0.1 # the left side of the subplots of the figure
     right = 0.9 # the right side of the subplots of the figure
     bottom = 0.15 # the bottom of the subplots of the figure
     top = 0.5 # the top of the subplots of the figure
     wspace = 0.5 # the amount of width reserved for space between subplots,
     # expressed as a fraction of the average axis width
     hspace = .25 # the amount of height reserved for space between subplots,
     # expressed as a fraction of the average axis height
     plt.subplots_adjust(left, bottom, right, top, wspace, hspace)
     # plot vorticity
     plt.subplot(1,2,1)
     plt.contourf(Y, X, omega, 50, cmap = 'jet')
     plt.colorbar()
     plt.contour(Y, X, omega, 10, colors = 'k')
     plt.title('Vorticity Plot for Re Grid Independence')
     plt.xlabel("$x$")
     plt.ylabel("$y$")
     # plot streamfunction
     plt.subplot(1,2,2)
     plt.contourf(Y, X, psi, 50, cmap = 'jet')
     plt.colorbar()
```

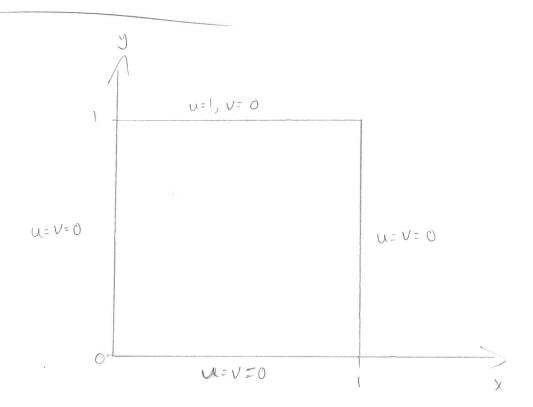
```
plt.contour(Y, X, psi, 10, colors = 'k')
plt.title('Streamfunction Plot for Grid Independence')
plt.xlabel("$x$")
plt.ylabel("$y$")
plt.show()
```

4.3 Plots of Grid Independent Solution



5 Derivations

Below are the derivations and written work done in order to have a better understanding of this problem. The functions were developed in problem set #3 and #4 however written work was still done.



All 4 boundaires are directlet

L don't need to be
updated

Vorticity transport eyn:

$$\frac{\partial x}{\partial x} + \sqrt{\frac{\partial y}{\partial y}} = \frac{1}{Re} \left(\frac{\partial^2 x}{\partial x^2} + \frac{\partial^2 x}{\partial y^2} \right)$$

Poisson egn

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial y}{\partial y^2} = -\omega$$
 where BC is $\psi = 0$ for all boundwise

use central difference approximations to evaluate $u = \frac{\partial \psi}{\partial y}$, $v = -\frac{\partial \psi}{\partial x}$ to obtain upolities u(x,y) and v(x,y) $\frac{\partial \psi}{\partial y}$, $\frac{\partial \psi}{\partial x}$

 $\frac{1}{\Delta x} \left(\frac{\omega_{i1,i} - \omega_{i,i}}{\omega_{i,j}}, \frac{\omega_{i,j}^* < 0}{\omega_{i,j}^*} \right)$

multiply by Av2 to keep coefficients Oci)

$$\Delta x^{2} T_{x} = \int \frac{1}{Re} \left[\omega_{i+1,j}(-\delta) \omega_{i,j} + \omega_{i+1,j} \right] - \omega_{i,j}^{*} \Delta x \left[\omega_{i,j} - \omega_{i+1,j} \right] , \quad \omega_{i,j}^{*} = 0$$

$$\left[\frac{1}{Re} \left[\omega_{i+1,j} - (c-\delta) \omega_{i,j} + \omega_{i+1,j} \right] - \omega_{i,j}^{*} \Delta x \left[\omega_{i,j} - \omega_{i+1,j} \right] , \quad \omega_{i,j}^{*} = 0$$

group like terms

ai ui-1 + biui + Ciui+1 = di

for $w_{i,j}^{\dagger}$ 70 $\alpha = \frac{1}{Re} + w_{i,j}^{\dagger} \Delta x$ | for $w_{i,j}^{\dagger} \neq 0$

C = TRE

a= I Re

B= -2 + AX Win C= Re-AXW

for with = 0 a = Re

5= -2 - 0

C = I

BC=[Pqr]

leA Tight constant y-lines

Right B= [1 0 Wys]

from PS *3 & is used so for PS *44 \alpha = \frac{1}{Re} = \frac{1}{a}

$$u \frac{\partial \omega}{\partial y} + v \frac{\partial \omega}{\partial y} = \frac{1}{Re} \left(\frac{\partial^2 \omega}{\partial x^2} + \frac{\partial^2 \omega}{\partial y^2} \right)$$

$$T_{x} = \frac{1}{Re} \frac{\partial^{2} \omega}{\partial x^{2}} - u \frac{\partial \omega}{\partial x} = v \frac{\partial \omega}{\partial y} - \frac{1}{Re} \frac{\partial^{2} \omega}{\partial y^{2}}$$

solve for RHS

remember Tx is multiplied by Dx

$$\Delta x^{2}T_{x} = \frac{\omega_{i,j}^{*}}{\Delta y} \left[? \right] \Delta x^{2} - \frac{\Delta x^{2}}{Rc} \left[\frac{\omega_{i+1,j} - 2\omega_{i,j}}{\Delta y^{2}} + \frac{\omega_{i+1,j}}{\Delta y^{2}} \right] - \frac{\sigma_{i}}{\sigma_{i}} \omega_{i,j} \Delta x^{2}$$

$$\Delta_{x} = \Delta = 1$$

Some egn's as before for a,b, c, d when solveng



Left
$$BC = [1, 0, \omega_{i,0}]$$

Fight $BC = [1, 0, \omega_{i,N-1}]$

Look at BEs for streamfunction

(i) lover BC
$$\frac{1}{12} - \omega_{i,0} = \frac{1}{12} + \frac{1}{12}$$

$$-\omega_{\ell,o} = \frac{(2) \left[\psi_{\ell,1} - \psi_{\ell,o} \right]}{\Delta y^2}$$

$$\omega_{i,0} = \frac{2}{\Delta x^2} \left[\psi_{i,0} - \psi_{i,1} \right]$$

@ upper BC

$$\omega_{i,N} = \frac{7}{\Delta x^2} \left[\psi_{i,N} - \psi_{i,N-1} - \Delta x \right]$$

left BC Wn = 2 [40; - 40;]



Constant y-lines

(slide 191) uitis - (2+0)uis + uitis = 125is - D[uist - (2- \(\frac{1}{2}\) uist + uist), i=2,... I

$$A = 1$$

$$B = -2 - 0$$

$$C = 1$$

Costant x-lines / ristil left = [1,0, win]

$$A = 1$$
 $B = -2-0$
 $C = 1$
 C