

$$1. a) \langle \psi | \hat{p}_+ | \phi \rangle$$

$$= \langle \psi | +z \rangle \langle +z | \phi \rangle$$

$$= \langle +z | \phi \rangle \langle \psi | +z \rangle \quad \text{can write in any order}$$

$$= \langle \phi | +z \rangle^* \langle +z | \psi \rangle^*$$

$$= \langle \phi | \hat{p}_+ | \psi \rangle^*$$

Thus \hat{p}_+ is Hermitian

$$b) \hat{p}_+ |\lambda\rangle = \lambda |\lambda\rangle$$

$$\hat{p}_+^2 |\lambda\rangle = \hat{p}_+ \hat{p}_+ |\lambda\rangle = \lambda^2 |\lambda\rangle$$

but now since $\hat{p}_+ = \hat{p}_+^2$, we have
 $\lambda |\lambda\rangle = \lambda^2 |\lambda\rangle$, which is true only for
 $\lambda = 1, 0$.

c) Recall unitary operators have the property
 $\hat{U} \hat{U}^\dagger = \hat{U}^\dagger \hat{U} = \mathbb{1}$.

An orthonormal basis satisfies

$$\langle a_m | a_n \rangle = \delta_{mn}$$

I'll insert $\hat{U}^\dagger \hat{U}$ between my $|a\rangle$ states
 since it's an identity

$$\delta_{mn} = \langle a_m | a_n \rangle$$

$$= \langle a_m | \hat{U}^\dagger \hat{U} | a_n \rangle$$

$$= \langle b_m | b_n \rangle$$

$$\text{where } |b_n\rangle = \hat{U} |a_n\rangle$$

So the $|b_n\rangle = \hat{U} |a_n\rangle$ are also
 orthonormal.

We also need to show that the $|b_n\rangle$
 are complete, i.e. a basis

$$\mathbb{I} = \sum_n |a_n\rangle \langle a_n|$$

$$= \sum_n \hat{U} |a_n\rangle \langle a_n| \hat{U}^\dagger$$

multiply both sides
from the right by \hat{U}^\dagger and from the
left by \hat{U} . Since $\hat{U}\hat{U}^\dagger = \mathbb{I}$ the
LHS is not changed

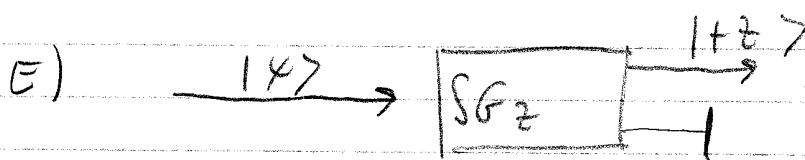
$$= \sum_n |b_n\rangle \langle b_n|$$

So the $|b_n\rangle = \hat{U}|a_n\rangle$ are also complete.

$$\begin{aligned} \text{D)} \quad & \langle \lambda | \hat{U}^\dagger \hat{U} | \lambda \rangle = \langle \lambda | \lambda^* \lambda | \lambda \rangle \quad *1 \\ & \frac{\langle \lambda | \lambda \rangle}{\lambda^* \lambda} = \frac{\lambda^* \lambda \langle \lambda | \lambda \rangle}{\lambda^* \lambda} \quad *2 \\ & \Rightarrow \lambda = e^{i\theta} \end{aligned}$$

My $E_0 * 1$ is true since λ is the eigenvalue of \hat{U} and $\langle \lambda | \hat{U}^\dagger = (\langle \lambda | \lambda \rangle)^\dagger = \langle \lambda | \lambda^*$

My $E_0 * 2$ is true because $\hat{U}^\dagger \hat{U}$ is an identity.



This "projects" out the $|+z\rangle$ component of $|\psi\rangle$. The probability that $|\psi\rangle$ yields $|+z\rangle$ is $|\langle +z | \psi \rangle|^2 = c c^*$ if we write $|\psi\rangle = c |+z\rangle + b |-z\rangle$.

projection operator expectation also yields $\langle \psi | P_{+z} | \psi \rangle = \langle \psi | c | +z \rangle = c \langle \psi | +z \rangle = c c^*$. So our expectation value is the probability to observe $|\psi\rangle$ in the $|+z\rangle$ state.

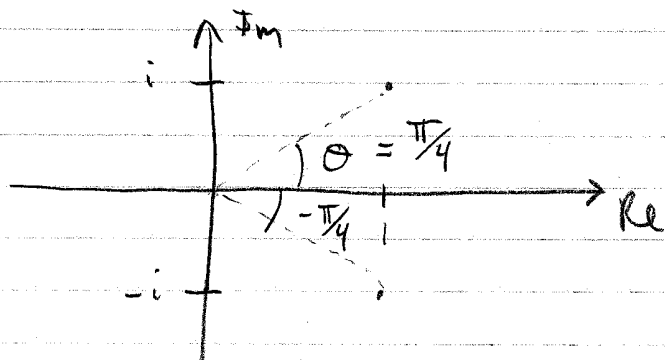
$$2. | \pm x \rangle = \begin{pmatrix} \langle +y | \pm x \rangle \\ \langle -y | \pm x \rangle \end{pmatrix}$$

$$= \begin{pmatrix} \langle -z | \frac{1}{\sqrt{2}} + \langle +z | \frac{1}{\sqrt{2}} \rangle \left(\frac{1}{\sqrt{2}} | +z \rangle + \frac{1}{\sqrt{2}} | -z \rangle \right) \\ \langle -z | \frac{1}{\sqrt{2}} - \langle +z | \frac{1}{\sqrt{2}} \rangle \left(\frac{1}{\sqrt{2}} | +z \rangle + \frac{1}{\sqrt{2}} | -z \rangle \right) \end{pmatrix}$$

$$= \begin{pmatrix} \frac{1}{2} + \frac{1}{2}i \\ \frac{1}{2} - \frac{1}{2}i \end{pmatrix}$$

$$= \frac{1}{2} \begin{pmatrix} 1+i \\ 1-i \end{pmatrix}$$

$$\begin{cases} |1-i| = \sqrt{(1-i)(1+i)} = \sqrt{1+1} = \sqrt{2} \\ |1+i| = \sqrt{(1+i)(1-i)} = \sqrt{2} \end{cases}$$



$$\text{So } 1-i = \sqrt{2} e^{-i\pi/4} \quad \text{and} \quad 1+i = \sqrt{2} e^{i\pi/4}$$

$$|+x\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} e^{-i\pi/4} \\ e^{i\pi/4} \end{pmatrix} = \frac{e^{-i\pi/4}}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}$$

$$|-x\rangle = \frac{1}{\sqrt{2}} e^{-i\pi/4} \begin{pmatrix} i \\ 1 \end{pmatrix}$$

$$3a) \hat{J}_x \xrightarrow{S_z \text{ basis}} \begin{pmatrix} \langle +z | \hat{J}_x | +z \rangle & \langle +z | \hat{J}_x | -z \rangle \\ \langle -z | \hat{J}_x | +z \rangle & \langle -z | \hat{J}_x | -z \rangle \end{pmatrix}$$

One could use the $| \pm z \rangle$ states in the $| \pm x \rangle$ basis to work this out directly or (It's really the same calculations in a different order) do the following

$$= S^\dagger \begin{pmatrix} \langle +x | \hat{J}_x | +x \rangle & \langle +x | \hat{J}_x | -x \rangle \\ \langle -x | \hat{J}_x | +x \rangle & \langle -x | \hat{J}_x | -x \rangle \end{pmatrix} S$$

$$\text{The } S = \begin{pmatrix} \langle +x | +z \rangle & \langle +x | -z \rangle \\ \langle -x | +z \rangle & \langle -x | -z \rangle \end{pmatrix}$$

This would take a ket from z to x , so, as used above it takes \hat{J}_x from the x representation to the z rep.

We can work this out from the $| \pm x \rangle$ states in the z basis

$| +x \rangle = \frac{1}{\sqrt{2}} (| +z \rangle + | -z \rangle)$
 $| -x \rangle = \frac{1}{\sqrt{2}} (| +z \rangle - | -z \rangle)$

$$S = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

So now we have

$$\hat{J}_x \rightarrow \frac{\hbar}{4} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

$$= \frac{\hbar}{4} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$$

$$= \frac{\hbar}{4} \begin{pmatrix} 0 & 2 \\ 2 & 0 \end{pmatrix} = \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

(5)

We can check this result
with $|+\rangle \xrightarrow{S_z \text{ basis}} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$$\langle +x | J_x | +x \rangle$$

$$\xrightarrow{S_z \text{ basis}} \frac{\hbar}{4} \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$= \frac{\hbar}{4} \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$= \frac{\hbar}{2} \quad \checkmark$$

$$b) \langle S_x \rangle = \langle \psi | J_x | \psi \rangle$$

$$= \frac{\hbar}{3\sqrt{2}} \begin{pmatrix} 1 & \sqrt{2} \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ \sqrt{2} \end{pmatrix}$$

$$= \frac{\hbar}{6} \begin{pmatrix} 1 & \sqrt{2} \end{pmatrix} \begin{pmatrix} \sqrt{2} \\ 1 \end{pmatrix}$$

$$= \frac{\hbar}{6} (2\sqrt{2})$$

$$= \frac{\sqrt{2}}{3} \hbar$$

It should be between $\pm \frac{\hbar}{2}$ and
 $\frac{\sqrt{2}}{3} \hbar = 0.47 \hbar \quad \checkmark$

(6)

4. A) We need to find the angular momentum of the beam. I'll use the $|R\rangle$ + $|L\rangle$ from Eq 2.114

$$P_L = |\langle L | \psi \rangle|^2 = \left| \frac{1}{\sqrt{2}} (\langle x | + i \langle y |) \left(\sqrt{\frac{2}{3}} |x\rangle + \frac{i}{\sqrt{3}} |y\rangle \right) \right|^2$$

$$= \left| \left(\frac{1}{\sqrt{3}} - \frac{1}{\sqrt{6}} \right) \right|^2$$

$$= \left| \frac{1}{\sqrt{6}} (\sqrt{2} - 1) \right|^2$$

$$= \frac{1}{6} (-2 - 2\sqrt{2} + 1)$$

$$= \frac{1}{2} - \frac{1}{3} \sqrt{2}$$

$$P_R = |\langle R | \psi \rangle|^2 = \left| \frac{1}{\sqrt{2}} (\langle x | - i \langle y |) \left(\sqrt{\frac{2}{3}} |x\rangle + \frac{i}{\sqrt{3}} |y\rangle \right) \right|^2$$

I could work this out as I did above, but since the probabilities of right + left sum to 1, I can just do

$$\begin{aligned} P_R &= |\langle R | \psi \rangle|^2 = 1 - |\langle L | \psi \rangle|^2 \\ &= 1 - \left(\frac{1}{2} - \frac{1}{3} \sqrt{2} \right) \\ &= \frac{1}{2} + \frac{1}{3} \sqrt{2} \end{aligned}$$

So the angular momentum transfer rate to the plate is

$$\begin{aligned} \frac{dL}{dt} &= N (\hbar P_R - \hbar P_L) \\ &= N \hbar \frac{2\sqrt{2}}{3} \end{aligned}$$

Since $\tau = dL/dt$, we have

$$\boxed{\tau = N \hbar \frac{2\sqrt{2}}{3}}$$

b) For a Disk we have $I_D = \frac{1}{2} m r^2$. Here $m = 1 \text{ kg}$ and $r = 1 \text{ m}$

$$L_D = I \omega$$

$$L_{\text{of}} - L_{\text{oi}} = \int_0^t N \hbar \frac{2\sqrt{2}}{3} dt$$

$$I_D \omega = N \hbar \frac{2\sqrt{2}}{3} t$$

$$t = \frac{I_D \omega}{N \hbar \frac{2\sqrt{2}}{3}}$$

$$= \frac{(\frac{1}{2} \text{ kg m}^2) (1 \text{ rad/s})}{(10,180/\text{s}) (1.05 \times 10^{-34} \text{ J s}) \frac{2\sqrt{2}}{3}}$$

$$\approx 5 \times 10^{29} \text{ s}$$

This is a really long time (!) to reach just 1 rad/s (!) So Dr D's plan is not practical, though in principle the spin angular momentum of light can rotate a macroscopic object.

It's harder with e^- , though the angular momentum would become "a part of the disk." Some issues:

- When e^- are absorbed, depending on the process, they may still be e^- , keeping their angular momentum as spin rather than L of the disk.
- The disk would become charged.

C. Probability of transmission is

$$\begin{aligned}
 |\langle y | \psi \rangle|^2 &= |\langle y | (\frac{\sqrt{2}}{2} |x\rangle + \frac{i}{\sqrt{3}} |y\rangle) |^2 \\
 &= |\frac{i}{\sqrt{3}}|^2 \\
 &= \frac{i}{\sqrt{3}} \cdot \frac{i}{\sqrt{3}} \\
 &= \frac{1}{3}
 \end{aligned}$$

D. The photons will come out of the polarizer in the $|y\rangle$ state

$$|\langle L | y \rangle|^2 = |\frac{i}{\sqrt{2}}|^2 = \frac{1}{2}$$

So the beam will be a 50/50 mix of $+\hbar$ and $-\hbar$ so no angular momentum will be gained by the disk over a large number of photons.

The intensity is also less since the $|\langle x | \psi \rangle|^2$ fraction of the beam is removed by the polarizer.

5. Let's start with the $|R\rangle/|L\rangle$ basis. That will be easy since our state is already in that basis

$$\langle S_z \rangle = (a^*, b^*) \begin{pmatrix} \hbar & 0 \\ 0 & -\hbar \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix}$$

$$= (a^*, b^*) \begin{pmatrix} \hbar a \\ -\hbar b \end{pmatrix}$$

$$= \hbar (a a^* - b b^*)$$

Now to do it in the $|X\rangle/|Y\rangle$ basis we first need to transform our state to this basis.

The S matrix to go from R/L to X/Y is also worked out in Example 2.8:

$$S = \begin{pmatrix} \langle R|X \rangle & \langle R|Y \rangle \\ \langle L|X \rangle & \langle L|Y \rangle \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -i \\ 1 & i \end{pmatrix},$$

Though it's not hard to work out these inner products yourself.

$$\langle S_z \rangle = \underbrace{\langle Y|}_{\substack{\uparrow \\ \text{RL basis}}} S S^\dagger \underbrace{\hat{J}_z}_{\substack{\uparrow \\ \text{RL basis}}} S S^\dagger \underbrace{|\psi\rangle}_{\substack{\uparrow \\ \text{RL basis}}}$$

When we write it in this way, it makes it clear that the answer is invariant, but proceeding to matrix notation we get

$$|\psi\rangle \xrightarrow{\text{XY basis}} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ i & -i \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} a+b \\ i(a-b) \end{pmatrix}$$

$$J_z \rightarrow \frac{1}{2} \begin{pmatrix} 1 & 1 \\ i & -i \end{pmatrix} \begin{pmatrix} \hbar & 0 \\ 0 & -\hbar \end{pmatrix} \begin{pmatrix} 1 & -i \\ 1 & i \end{pmatrix}$$

$$= \frac{\hbar}{2} \begin{pmatrix} 1 & 1 \\ i & -i \end{pmatrix} \begin{pmatrix} 1 & -i \\ -1 & -i \end{pmatrix}$$

$$= \frac{\hbar}{2} \begin{pmatrix} 0 & -2i \\ 2i & 0 \end{pmatrix}$$

$$= \hbar \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \leftarrow \text{worked out in 2.8 too}$$

$$\langle S_z \rangle = \frac{\hbar}{2} \begin{pmatrix} a^\dagger + b^\dagger & -i(a^\dagger - b^\dagger) \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} a+b \\ i(a-b) \end{pmatrix}$$

$$= \frac{\hbar}{2} \begin{pmatrix} a^\dagger + b^\dagger & -i(a^\dagger - b^\dagger) \end{pmatrix} \begin{pmatrix} a-b \\ i(a+b) \end{pmatrix}$$

$$= \frac{\hbar}{2} \left((a^\dagger + b^\dagger)(a-b) + (a+b)(a^\dagger - b^\dagger) \right)$$

$$= \frac{\hbar}{2} \left(a^\dagger a - \cancel{a^\dagger b} + \cancel{a b^\dagger} - b b^\dagger + a a^\dagger - \cancel{a b^\dagger} + \cancel{a^\dagger b} - b b^\dagger \right)$$

$$= \hbar (a a^\dagger - b b^\dagger)$$

Matches what we got on the R/L basis

$$\begin{aligned}
 6, a) [\hat{A}, \hat{B} + \hat{C}] &= \hat{A}(\hat{B} + \hat{C}) - (\hat{B} + \hat{C})\hat{A} \\
 &= \hat{A}\hat{B} + \hat{A}\hat{C} - \hat{B}\hat{A} - \hat{C}\hat{A} \\
 &= (\hat{A}\hat{B} - \hat{B}\hat{A}) + (\hat{A}\hat{C} - \hat{C}\hat{A}) \\
 &= [\hat{A}, \hat{B}] + [\hat{A}, \hat{C}]
 \end{aligned}$$

b) $[\hat{A}, \hat{B}\hat{C}] = \hat{A}\hat{B}\hat{C} - \hat{B}\hat{C}\hat{A}$
 we need to RHS terms with \hat{C} at the back and 2 with \hat{B} at the front. If we add $0 = \hat{B}\hat{A}\hat{C} - \hat{B}\hat{A}\hat{C}$ we can pair up terms ① and ④ as well as terms ② and ③ as follows

$$\begin{aligned}
 &= (\hat{A}\hat{B} - \hat{B}\hat{A})\hat{C} + \hat{B}(\hat{A}\hat{C} - \hat{C}\hat{A}) \\
 &= [\hat{A}, \hat{B}]\hat{C} + \hat{B}[\hat{A}, \hat{C}]
 \end{aligned}$$

c) You could do a proof just like (b), but you could use (b) as follows

$$\begin{aligned}
 [\hat{A}\hat{B}, \hat{C}] &= -[\hat{C}, \hat{A}\hat{B}] \quad \text{Now apply rule (b)} \\
 &= -(\hat{A}[\hat{C}, \hat{B}] + [\hat{C}, \hat{A}]\hat{B}) \\
 &= \hat{A}[\hat{B}, \hat{C}] + [\hat{A}, \hat{C}]\hat{B}
 \end{aligned}$$

$$\begin{aligned}
 d) -i\hat{C}^\dagger &= [\hat{A}, \hat{B}]^\dagger \\
 &= (\hat{A}\hat{B} - \hat{B}\hat{A})^\dagger \\
 &= \hat{B}^\dagger\hat{A}^\dagger - \hat{A}^\dagger\hat{B}^\dagger \quad \text{Hermitian} \\
 &= \hat{B}\hat{A} - \hat{A}\hat{B} \\
 &= -[\hat{A}, \hat{B}] \\
 &= -i\hat{C}
 \end{aligned}$$

So $\hat{C} = \hat{C}^\dagger$ ✓