

1. Lee 1-5 [SECOND edition] = Lee 1-7 [FIRST edition 1-7]. So either way you will have done it (since hw 1 originally read 1. Lee 1-5, 2. Lee 1-7).

ONLY DO THE CASE WHEN $n = 2$.

Let N denote the north pole $(0, \dots, 0, 1) \in S^n \subset \mathbb{R}^{n+1}$ and let S denote the south pole $(0, \dots, 0, -1)$. Define the **stereographic projection** $\sigma : S^n \setminus \{N\} \rightarrow \mathbb{R}^n$ by

$$\sigma(x^1, \dots, x^{n+1}) = \frac{(x^1, \dots, x^n)}{1 - x^{n+1}}$$

Let $\tilde{\sigma}(x) = -\sigma(-x)$ for $x \in S^n \setminus \{S\}$.

(a) For any $x \in S^n \setminus \{N\}$, show that $\sigma(x) = u$, where $(u, 0)$ is the point where the line through N and x intersects the linear subspace where $x^{n+1} = 0$ (Fig. 1.13 in LEE SECOND and FIRST). Similarly, show that $\tilde{\sigma}(x)$ is the point where the line through S and x intersects the same subspace. (For this reason, $\tilde{\sigma}$ is called **stereographic projection from the south pole**.)

Solution: The following is restricted to the case $n = 2$. Consider the line through the points $(0, 0, 1), (x, y, z) \in S^2$ which can be parametrized by $\{(tx, ty, (1-t) + tz) \mid t \in \mathbb{R}\}$. When this intersects the equatorial plane, $(1-t) + tz = 0$ so $t = \frac{1}{1-z}$. Therefore, the intersection point is at, $(\frac{x}{1-z}, \frac{y}{1-z}, 0)$ which equals $\sigma(x, y, z)$ with \mathbb{R}^2 identified as the equatorial plane. The case for the south pole is identical.

Consider the line through the points $(0, 0, -1), (x, y, z) \in S^2$ which can be parametrized by $\{(tx, ty, -(1-t) + tz) \mid t \in \mathbb{R}\}$. When this intersects the equatorial plane, $-(1-t) + tz = 0$ so $t = \frac{1}{1+z}$. Therefore, the intersection point is at, $(\frac{x}{1+z}, \frac{y}{1+z}, 0)$ which equals $\tilde{\sigma}(x, y, z)$ with \mathbb{R}^2 identified as the equatorial plane.

(b) Show that σ is bijective, and

$$\sigma^{-1}(u^1, \dots, u^n) = \frac{(2u^1, \dots, 2u^n, |u|^2 - 1)}{|u|^2 + 1}$$

Solution:

It suffices to show that the compositions $\sigma \circ \sigma^{-1} = \text{id}_{\mathbb{R}^2}$ and $\sigma^{-1} \circ \sigma = \text{id}_{S^2}$. This follows directly by computation, take $(x, y, z) \in S^2$ and $(u, v) \in \mathbb{R}^2$,

$$\begin{aligned} \sigma^{-1} \circ \sigma(x, y, z) &= \sigma^{-1} \left(\frac{(x, y)}{1-z} \right) = \frac{\left(\frac{2x}{1-z}, \frac{2y}{1-z}, \left(\frac{x}{1-z} \right)^2 + \left(\frac{y}{1-z} \right)^2 - 1 \right)}{\left(\frac{x}{1-z} \right)^2 + \left(\frac{y}{1-z} \right)^2 + 1} \\ &= \frac{(2x(1-z), 2y(1-z), x^2 + y^2 - (1-z)^2)}{x^2 + y^2 + (1-z)^2} \\ &= \frac{(2x(1-z), 2y(1-z), -2z^2 + 2z)}{2(1-z) + (x^2 + y^2 + z^2 - 1)} = (x, y, z) = \text{id}_{S^2}(x, y, z) \\ \sigma \circ \sigma^{-1}(u, v) &= \sigma \left(\frac{(2u, 2v, u^2 + v^2 - 1)}{u^2 + v^2 + 1} \right) = \frac{(2u, 2v)}{(u^2 + v^2 + 1) \left(1 - \frac{u^2 + v^2 - 1}{u^2 + v^2 + 1} \right)} \\ &= \frac{(2u, 2v)(u^2 + v^2 + 1)}{2(u^2 + v^2 + 1)} = (u, v) = \text{id}_{\mathbb{R}^2}(u, v) \end{aligned}$$

(c) Compute the transition map $\tilde{\sigma} \circ \sigma^{-1}$ and verify that the atlas consisting of the two charts $(S^n \setminus \{N\}, \sigma)$ and $(S^n \setminus \{S\}, \tilde{\sigma})$ defines a smooth structure on S^n . (The coordinates defined by σ or $\tilde{\sigma}$ are called stereographic coordinates.)

Solution: Take $(x, y) \in \mathbb{R}^2$,

$$\begin{aligned}\tilde{\sigma} \circ \sigma^{-1}(x, y) &= -\sigma(-\sigma^{-1}(x, y)) = -\frac{(-2x, -2y)}{(x^2 + y^2 + 1) \left(1 - \frac{x^2 + y^2 - 1}{x^2 + y^2 + 1}\right)} \\ &= \frac{2(x, y)}{x^2 + y^2 + 1 - (x^2 + y^2 - 1)} = (x, y)\end{aligned}$$

is a diffeomorphism. Therefore, $(S^n \setminus \{N\}, \sigma)$ and $(S^n \setminus \{S\}, \tilde{\sigma})$ are smoothly compatible charts and thus there exists a unique maximal atlas containing these charts which defines a smooth structure on S^2 .

(d) Show that this smooth structure is the same as the one defined in Example 1.31 from LEE SECOND or Example 1.20 in LEE FIRST.

Solution:

It suffices to show that σ and $\tilde{\sigma}$ are smoothly compatible with ϕ_i^\pm , because then the union of the smooth atlases is a smooth atlas which implies that the maximal atlases defined by the two sets of charts are in fact equal.

Consider $\phi_i^\pm \circ \sigma^{-1} : \sigma(U_i^\pm \cap (S^2 \setminus \{N\})) \rightarrow \phi_i^\pm(U_i^\pm \cap (S^2 \setminus \{N\}))$. Take $(x, y) \in \mathbb{R}^2$ then,

$$\phi_1^\pm \circ \sigma^{-1}(x, y) = \phi_1^\pm \left(\frac{(2x, 2y, x^2 + y^2 - 1)}{x^2 + y^2 + 1} \right) = \frac{(2x, -z^2)}{x^2 + y^2 + 1}$$

$$\phi_2^\pm \circ \sigma^{-1}(x, y) = \phi_2^\pm \left(\frac{(2x, 2y, x^2 + y^2 - 1)}{x^2 + y^2 + 1} \right) = \frac{(2y, -z^2)}{x^2 + y^2 + 1}$$

$$\phi_2^\pm \circ \sigma^{-1}(x, y) = \phi_2^\pm \left(\frac{(2x, 2y, x^2 + y^2 - 1)}{x^2 + y^2 + 1} \right) = \frac{(2x, 2y)}{x^2 + y^2 + 1}$$

which are all diffeomorphic by basic analysis.

Similarly, for $\phi_i^\pm \circ \tilde{\sigma}^{-1} : \tilde{\sigma}(U_i^\pm \cap (S^n \setminus S)) \rightarrow \phi_i^\pm(U_i^\pm \cap (S^n \setminus S))$. Take $(x, y) \in \mathbb{R}^2$ then,

$$\phi_1^\pm \circ \tilde{\sigma}^{-1}(x, y) = \phi_1^\pm \left(\frac{(2x, 2y, 1 - x^2 - y^2)}{x^2 + y^2 + 1} \right) = \frac{(2x, z^2)}{x^2 + y^2 + 1}$$

$$\phi_2^\pm \circ \tilde{\sigma}^{-1}(x, y) = \phi_2^\pm \left(\frac{(2x, 2y, 1 - x^2 - y^2)}{x^2 + y^2 + 1} \right) = \frac{(2y, z^2)}{x^2 + y^2 + 1}$$

$$\phi_2^\pm \circ \tilde{\sigma}^{-1}(x, y) = \phi_2^\pm \left(\frac{(2x, 2y, 1 - x^2 - y^2)}{x^2 + y^2 + 1} \right) = \frac{(2x, 2y)}{x^2 + y^2 + 1}$$

which are all diffeomorphic by basic analysis.

2. Lee 1.6 [SECOND EDITION] (probably more interesting than the first option)

Let M be a nonempty topological manifold of dimension $n \geq 1$. If M has a smooth structure, show that it has uncountably many distinct ones. [Hint: first show that for any $s > 0$, $F_s(x) = |x|^{s-1}x$ defines a homeomorphism from B^n to itself, which is a diffeomorphism if and only if $s = 1$.]

Solution: Let M be a nonempty smooth n -manifold for $n \geq 1$ with some smooth atlas \mathcal{A} and pick a point $p \in M$. First, we will need a lemma:

Lemma 1. *For any $p \in M$ there exists a smooth atlas \mathcal{A}' such that p is contained in the domain of exactly one chart in \mathcal{A}' and both \mathcal{A} and \mathcal{A}' define the same smooth structure on M .*

Proof. Let $\mathcal{C}_p \subset \mathcal{A}$ be the set $\mathcal{C}_p = \{(U, \phi) \in \mathcal{A} \mid p \in U\}$. Because M is Hausdorff, the singleton $\{p\}$ is closed so the sets $U \setminus \{p\}$ are open. Define \mathcal{A}' by replacing each $(U, \phi) \in \mathcal{C}_p$ with $(U \setminus \{p\}, \phi|_{U \setminus \{p\}})$ which is still a chart because $U \setminus \{p\}$ is open and the restriction of any homeomorphism is still a homeomorphism onto its image. Clearly, \mathcal{A}' is a smooth atlas because the transition maps are simply restrictions of the transition maps of \mathcal{A} which are smooth. To prove that \mathcal{A} and \mathcal{A}' define the same smooth structure, it suffices to show that their union is a smooth atlas. However, the transition maps between \mathcal{A} and \mathcal{A}' are also restrictions of smooth maps and are therefore smooth. \square

By the previous lemma, we can assume that \mathcal{A} has exactly one chart containing p , namely, (U_p, ϕ_p) . We will construct a new atlas \mathcal{B}_s by replacing (U_p, ϕ_p) with (U_p, ϕ_s) defined as,

$$\phi_s(x) = F_s(\phi_p(x) - \phi_p(p))$$

For any $s > 0$, I claim that \mathcal{B}_s is a smooth atlas. This is because for any other chart $(V, \psi) \in \mathcal{B}_s$ we know $p \notin U_p \cap V$ so the map,

$$\psi \circ \phi_s^{-1} : \phi_s(U \cap V_p) \rightarrow \psi(U \cap V_p)$$

cannot contain 0 in its domain. This is because $\phi_s(p) = 0$ but ϕ_s is an injection and $p \notin U \cap V_p$ so 0 is not in the image under ϕ'_s . I claim that F_s is a diffeomorphism on any set not containing 0. I will show this by exhibiting an inverse,

$$F_s^{-1}(x) = \frac{x}{|x|^{1-\frac{1}{s}}}$$

which is well defined ($s > 0$) and smooth as long as $x \neq 0$. Furthermore,

$$F_s \circ F_s^{-1}(x) = \frac{|x|^{s-1}}{|x|^{(1-\frac{1}{s})(s-1)}} \frac{x}{|x|^{1-\frac{1}{s}}} = x \quad F_s^{-1} \circ F_s(x) = \frac{|x|^{s-1}x}{|x|^{s(1-\frac{1}{s})}} = x$$

Thus, F_s is a diffeomorphism away from $x = 0$. Therefore,

$$\psi \circ \phi_s^{-1}(x) = \psi \circ \phi_p^{-1} \circ (F_s^{-1}(x) + \phi_p(p))$$

is a diffeomorphism because $x \neq 0$. Furthermore, the transition map of any two charts in \mathcal{B}_s neither of which are (U_p, ϕ_s) are smooth because they are also charts of \mathcal{A} which is a smooth atlas.

Finally, we need to show that \mathcal{B}_s and $\mathcal{B}_{s'}$ define different smooth structures on M if $s \neq s'$.

If \mathcal{B}_s and $\mathcal{B}_{s'}$ defined the same smooth structure then their union would be a smooth atlas. However,

$$\phi'_s \circ \phi_s^{-1}(x) = F_{s'}(\phi_p(\phi_p^{-1}(F_s^{-1}(x) + \phi_p(p)) - \phi_p(p)) = F_{s'}(F_s^{-1}(x))$$

which is not smooth unless $s = s'$. This holds because,

$$F_{s'} \circ F_s^{-1}(x) = \frac{|x|^{s'-1}}{|x|^{(1-\frac{1}{s})(s'-1)}} \frac{|x|^{s'-1}}{|x|^{s'-\frac{s'}{s}}} x = |x|^{\frac{s'}{s}-1} x$$

which is not differentiable at $x = 0$ unless $s = s'$. Thus, the charts of \mathcal{B}_s and $\mathcal{B}_{s'}$ are not smoothly compatible. Therefore, there is a distinct smooth structure on M for each $s \in (0, \infty)$ which is an uncountable set.

3. DO ONE OF the following:

Lee 1.7 [First Edition] = Lee 1.9 [Second Edition]

(Just do the case $n = 1$.) Also check that the projection $\mathbb{C}^2 \setminus \{0\} \rightarrow \mathbb{C}P^1$ is smooth.

Complex projective n -space, denoted by CP^n , is the set of all 1-dimensional complex-linear subspaces of \mathbb{C}^{n+1} , with the quotient topology inherited from the natural projection $\pi : \mathbb{C}^{n+1} \setminus \{0\} \rightarrow CP^n$. Show that CP^n is a compact $2n$ -dimensional topological manifold, and show how to give it a smooth structure analogous to the one we constructed for RP^n (done in an earlier example in Chapter 1 in both versions). We use the correspondence

$$(x^i + iy^1, \dots, x^{n+1} + iy^{n+1}) \leftrightarrow (x^1, y^1, \dots, x^{n+1}, y^{n+1})$$

to identify \mathbb{C}^{n+1} with \mathbb{R}^{2n+2}

Solution:

We first show that $\mathbb{C}P^1$ is locally euclidean. Notation: $\mathcal{C} : \mathbb{R}^2 \rightarrow \mathbb{C}$ defined by $x + iy \mapsto (x, y)$.

I will use the charts on $\mathbb{C}P^1$ defined by the charts,

$$\begin{aligned} (\mathbb{C}P^1 \setminus \{[1, 0]\}, \phi_1) \quad \text{with} \quad \phi_1 : [x + iy, u + iv] &\mapsto \mathcal{C} \left(\frac{x + iy}{u + iv} \right) \\ \phi_1^{-1} : (x, y) &\mapsto [x + iy, 1] \\ (\mathbb{C}P^1 \setminus \{[0, 1]\}, \phi_2) \quad \text{with} \quad \phi_2 : [x + iy, u + iv] &\mapsto \mathcal{C} \left(\frac{u + iv}{x + iy} \right) \\ \phi_2^{-1} : (x, y) &\mapsto [1, x + iy] \end{aligned}$$

We note that these are, in fact, inverses because. We have,

$$\phi_1^{-1} \circ \phi_1([x + iy, u + iv]) = \phi_1^{-1} \left(\frac{x + iy}{u + iv} \right) = \left[\frac{x + iy}{u + iv}, 1 \right] \cong [x + iy, u + iv]$$

which is well defined because $u + iv \neq 0$ on the domain of ϕ_1 . Similarly,

$$\phi_1 \circ \phi_1^{-1}(x, y) = \phi_1[x + iy, 1] = \mathcal{C} \left(\frac{x + iy}{1} \right) = (x, y)$$

Likewise,

$$\phi_2^{-1} \circ \phi_2([u + iv, x + iy]) = \phi_2^{-1} \left(\frac{u + iv}{x + iy} \right) = \left[1, \frac{u + iv}{x + iy} \right] \cong [u + iv, x + iy]$$

which is well defined because $x + iy \neq 0$ on the domain of ϕ_2 . Similarly,

$$\phi_2 \circ \phi_2^{-1}(x, y) = \phi_2[1, x + iy] = \mathcal{C} \left(\frac{x + iy}{1} \right) = (x, y)$$

Consider the maps from $\mathbb{C}^2 \rightarrow \mathbb{R}^2$,

$$\phi_1 \circ \pi(x + iy, u + iv) = \phi_1([x + iy, u + iv]) = \mathcal{C} \left(\frac{x + iy}{u + iv} \right)$$

and

$$\phi_2 \circ \pi(x + iy, u + iv) = \phi_2([x + iy, u + iv]) = \mathcal{C} \left(\frac{u + iv}{x + iy} \right)$$

which are continuous because the domains are restricted to the sets where these denominators are nonzero. By the properties of quotient maps, ϕ_1 and ϕ_2 must be continuous. Similarly, the inverses are easily seen to be continuous. Therefore ϕ_1 and ϕ_2 are homeomorphisms onto their image. The Hausdorff and second countable properties are easily checked via the identification with \mathbb{R}^4 . Therefore \mathbb{CP}^1 is a 2-manifold.

It remains to show that the atlas given by the charts ϕ_1 and ϕ_2 defines a smooth structure on \mathbb{CP}^1 . Consider the transition map,

$$\phi_1 \circ \phi_2^{-1} : \phi_2(U_1 \cap U_2) \rightarrow \phi_1(U_1 \cap U_2)$$

where $U_1 \cap U_2 = \mathbb{CP}^1 \setminus \{[1, 0], [0, 1]\}$. Now, consider, $(x, y) \in \phi_2(U_1 \cap U_2)$ then $(x, y) \neq 0$ since $\phi_2([1, 0]) = (0, 0) \notin \phi_2(U_1)$ and,

$$\phi_1 \circ \phi_2^{-1}(x, y) = \phi_1([1, x + iy]) = \mathcal{C} \left(\frac{1}{x + iy} \right) = \left(\frac{x}{x^2 + y^2}, \frac{-y}{x^2 + y^2} \right)$$

which is smooth in any region of the plane minus the origin. Similarly, the opposite transition map,

$$\phi_2 \circ \phi_1^{-1} : \phi_1(U_1 \cap U_2) \rightarrow \phi_2(U_1 \cap U_2)$$

and take $(x, y) \in \phi_1(U_1 \cap U_2)$ so $(x, y) \neq 0$ since $\phi_1([0, 1]) = (0, 0) \notin \phi_1(U_2)$. Then,

$$\phi_2 \circ \phi_1^{-1}(x, y) = \phi_2([x + iy, 1]) = \mathcal{C} \left(\frac{1}{x + iy} \right) = \left(\frac{x}{x^2 + y^2}, \frac{-y}{x^2 + y^2} \right)$$

which is likewise smooth in any region of the plane minus the origin. Therefore, the maps ϕ_1 and ϕ_2 are smoothly compatible so they define a smooth structure on \mathbb{CP}^1 . Under this smooth structure, we will show that \mathbb{CP}^1 is diffeomorphic to S^2 and thus homeomorphic because any smooth map is continuous. Therefore, \mathbb{CP}^1 is compact because S^2 is compact.

Finally, consider the projection map $\pi : \mathbb{C}^2 \setminus \{0\} \rightarrow \mathbb{CP}^1$. The chart, $\psi : \mathbb{C}^2 \setminus \{0\} \rightarrow \mathbb{R}^4$ given by,

$$\psi : (x + iy, u + iv) \rightarrow (x, y, u, v)$$

is obviously smoothly compatible with itself and therefore defines a smooth structure on $\mathbb{C}^2 \setminus \{0\}$. Therefore, the coordinate representation of the projection,

$$\phi_1 \circ \pi \circ \psi^{-1}(x, y, u, v) = \phi_1([x + iy, u + iv]) = \mathcal{C} \left(\frac{x + iy}{u + iv} \right)$$

which is smooth on a domain in which $(u, v) \neq 0$. For a point such that $u = v = 0$, the image of the projection is not within the domain of ϕ_1 so we must use the other chart,

$$\phi_2 \circ \pi \circ \psi^{-1}(x, y, u, v) = \phi_2([x + iy, u + iv]) = \mathcal{C} \left(\frac{u + iv}{x + iy} \right)$$

which is smooth on a domain in which $(x, y) \neq 0$. Therefore, one of these coordinate representations is well defined and smooth whenever $(x, y, u, v) \neq 0$ which always holds on $\mathbb{C}^2 \setminus \{0\}$. Thus, π is a smooth map.

4. Show that \mathbb{CP}^1 is diffeomorphic to S^2 .

Solution:

Notation: $\mathcal{C} : \mathbb{R}^2 \rightarrow \mathbb{C}$ defined by $x + iy \mapsto (x, y)$.

I will use the atlas on \mathbb{CP}^1 defined by the charts,

$$\begin{aligned} (\mathbb{CP}^1 \setminus \{[1, 0]\}, \phi_1) \quad \text{with} \quad \phi_1 : [x + iy, u + iv] &\mapsto \mathcal{C} \left(\frac{x + iy}{u + iv} \right) \\ \phi_1^{-1} : (x, y) &\mapsto [x + iy, 1] \\ (\mathbb{CP}^1 \setminus \{[0, 1]\}, \phi_2) \quad \text{with} \quad \phi_2 : [x + iy, u + iv] &\mapsto \mathcal{C} \left(\frac{u + iv}{x + iy} \right) \\ \phi_2^{-1} : (x, y) &\mapsto [1, x + iy] \end{aligned}$$

and the atlas on S^1 given by the stereographic projections defined above,

$$\begin{aligned} (S^2 \setminus \{(0, 0, 1)\}, \sigma) \quad \text{with} \quad \sigma : (x, y, z) &\mapsto \left(\frac{x}{1 - z}, \frac{y}{1 - z} \right) \\ \sigma^{-1} : (x, y) &\mapsto \left(\frac{2x}{x^2 + y^2 + 1}, \frac{2y}{x^2 + y^2 + 1}, \frac{x^2 + y^2 - 1}{x^2 + y^2 + 1} \right) \\ (S^2 \setminus \{(0, 0, -1)\}, \tilde{\sigma}) \quad \text{with} \quad \tilde{\sigma} : (x, y, z) &\mapsto \left(\frac{x}{1 + z}, \frac{y}{1 + z} \right) \\ \tilde{\sigma}^{-1} : (x, y) &\mapsto \left(\frac{2x}{x^2 + y^2 + 1}, \frac{2y}{x^2 + y^2 + 1}, \frac{1 - x^2 - y^2}{x^2 + y^2 + 1} \right) \end{aligned}$$

Now, I define the map $F : S^2 \rightarrow \mathbb{CP}^1$ by,

$$F : (x, y, z) \mapsto \begin{cases} \left[\frac{x + iy}{1 - z}, 1 \right] & z \neq 1 \\ [1, 0] & z = 1 \end{cases}$$

It remains to check that F is bijective, smooth, and has smooth inverse. First, we show that F is a bijection by exhibiting an inverse function,

$$F^{-1} : [x + iy, u + iv] \mapsto \begin{cases} \left(\frac{2\alpha}{\alpha^2 + \beta^2 + 1}, \frac{2\beta}{\alpha^2 + \beta^2 + 1}, \frac{\alpha^2 + \beta^2 - 1}{\alpha^2 + \beta^2 + 1} \right) & u + iv \neq 0 \\ (0, 0, 1) & u + iv = 0 \end{cases}$$

where $\alpha + i\beta = \frac{x + iy}{u + iv}$ which is well defined in \mathbb{CP}^1 because if $x + iy$ and $u + iv$ are scaled by the same nonzero complex number then their ratio $\alpha + i\beta$ remains constant. The following calculation shows that F is a bijection,

$$\begin{aligned} F \circ F^{-1}([x + iy, u + iv]) &= \begin{cases} F \left(\frac{2\alpha}{\alpha^2 + \beta^2 + 1}, \frac{2\beta}{\alpha^2 + \beta^2 + 1}, \frac{\alpha^2 + \beta^2 - 1}{\alpha^2 + \beta^2 + 1} \right) & u + iv \neq 0 \\ F(0, 0, 1) & u + iv = 0 \end{cases} \\ &= \begin{cases} \left[\frac{2\alpha + 2i\beta}{\alpha^2 + \beta^2 + 1 - (\alpha^2 + \beta^2 + 1)}, 1 \right] & u + iv \neq 0 \\ [1, 0] & u + iv = 0 \end{cases} \\ &= \begin{cases} [\alpha + i\beta, 1] & u + iv \neq 0 \\ [1, 0] & u + iv = 0 \end{cases} \end{aligned}$$

However, if $u + iv \neq 0$ then $[x + iy, u + iv] \sim [\alpha + i\beta, 1]$ and otherwise $[x + iy, 1] \sim [1, 0]$. Therefore, $F \circ F^{-1} = \text{id}_{\mathbb{CP}^1}$. Likewise,

$$\begin{aligned} F^{-1} \circ F(x, y, z) &= \begin{cases} F^{-1}\left(\left[\frac{x+iy}{1-z}, 1\right]\right) & z \neq 1 \\ F^{-1}([1, 0]) & z = 1 \end{cases} \\ &= \begin{cases} \left(\frac{2x(1-z)}{x^2+y^2+(1-z)^2}, \frac{2y(1-z)}{x^2+y^2+(1-z)^2}, \frac{x^2+y^2-(1-z)^2}{x^2+y^2+(1-z)^2}\right) & z \neq 1 \\ (0, 0, 1) & z = 1 \end{cases} \\ &= \begin{cases} (x, y, z) & z \neq 1 \\ (0, 0, 1) & z = 1 \end{cases} \end{aligned}$$

where the last line follows because $x^2 + y^2 + z^2 = 1$. Therefore $F^{-1} \circ F = \text{id}_{S^2}$. Now, we must check that F and F^{-1} are smooth. The charts $\sigma, \tilde{\sigma}$ cover S^2 so we need to show that some choice of chart on \mathbb{CP}^1 makes the coordinate representation smooth. Consider,

$$\phi_1 \circ F \circ \sigma^{-1}(x, y) = \phi_1 \circ F\left(\frac{2x}{x^2 + y^2 + 1}, \frac{2y}{x^2 + y^2 + 1}, \frac{x^2 + y^2 - 1}{x^2 + y^2 + 1}\right) = \phi_1([x + iy, 1]) = (x, y)$$

This map is a diffeomorphism $\mathbb{R}^2 \rightarrow \mathbb{R}^2$. Because $z = \frac{x^2+y^2-1}{x^2+y^2+1} \neq 1$ we have that the domain of σ is mapped to within the domain of ϕ_1 . Similarly,

$$\begin{aligned} \phi_2 \circ F \circ \tilde{\sigma}^{-1}(x, y) &= \phi_2 \circ F\left(\frac{2x}{x^2 + y^2 + 1}, \frac{2y}{x^2 + y^2 + 1}, \frac{1 - x^2 - y^2}{x^2 + y^2 + 1}\right) \\ &= \begin{cases} \phi_2\left(\left[\frac{2x+2iy}{x^2+y^2+1-(1-x^2-y^2)}, 1\right]\right) & (x, y) \neq 0 \\ \phi_2([1, 0]) & x = y = 0 \end{cases} \\ &= \begin{cases} \phi_2\left(\left[\frac{x+iy}{x^2+y^2}, 1\right]\right) & (x, y) \neq 0 \\ \phi_2([1, 0]) & x = y = 0 \end{cases} \\ &= \begin{cases} (x, -y) & (x, y) \neq 0 \\ (0, 0) & x = y = 0 \end{cases} \\ &= (x, -y) \end{aligned}$$

This map is a diffeomorphism $\mathbb{R}^2 \rightarrow \mathbb{R}^2$. Because $F(x, y, z) = [0, 1]$ only when $(x, y, z) = (0, 0, -1)$ which is not in the domain of $\tilde{\sigma}$. Therefore, F maps the domain of $\tilde{\sigma}$ to inside the domain of ϕ_2 . Because every point in one of S^2 is contained in one of these domains, F is a smooth map. In fact, the coordinate representations of F are diffeomorphisms and F is a bijection so immediately, the coordinate maps, $(\phi_1 \circ F \circ \sigma^{-1})^{-1} = \sigma \circ F^{-1} \circ \phi_1^{-1}$ and $(\phi_2 \circ F \circ \tilde{\sigma}^{-1})^{-1} = \tilde{\sigma} \circ F^{-1} \circ \phi_2^{-1}$ are also smooth (since they are the inverses of diffeomorphisms). Thus, F is a diffeomorphism so $\mathbb{CP}^1 \cong S^2$.

5. Consider spherical coordinates on \mathbb{R}^3 (not including the line $x = y = 0$) ρ, ϕ, θ defined in terms of the Euclidean coordinates x, y, z by

$$x = \rho \sin \phi \cos \theta, \quad y = \rho \sin \phi \sin \theta, \quad z = \rho \cos \phi.$$

- (a) Express $\partial/\partial\rho$, $\partial/\partial\phi$, and $\partial/\partial\theta$ as linear combinations of $\partial/\partial x$, $\partial/\partial y$, and $\partial/\partial z$.
(The coefficients in these linear combinations will be functions on $\mathbb{R}^3 \setminus (x = y = 0)$.)

Solution:

For any function $f(x, y, z)$ on the set $\mathbb{R}^3 \setminus \{0\}$ we find that,

$$\begin{aligned} \frac{\partial f(x, y, z)}{\partial \rho} &= \frac{\partial x}{\partial \rho} \frac{\partial f}{\partial x} + \frac{\partial y}{\partial \rho} \frac{\partial f}{\partial y} + \frac{\partial z}{\partial \rho} \frac{\partial f}{\partial z} \\ &= \sin \phi \cos \theta \frac{\partial f}{\partial x} + \sin \phi \sin \theta \frac{\partial f}{\partial y} + \cos \phi \frac{\partial f}{\partial z} \\ \frac{\partial f(x, y, z)}{\partial \phi} &= \frac{\partial x}{\partial \phi} \frac{\partial f}{\partial x} + \frac{\partial y}{\partial \phi} \frac{\partial f}{\partial y} + \frac{\partial z}{\partial \phi} \frac{\partial f}{\partial z} \\ &= \rho \cos \phi \cos \theta \frac{\partial f}{\partial x} + \rho \cos \phi \sin \theta \frac{\partial f}{\partial y} + 0 \cdot \frac{\partial f}{\partial z} \\ \frac{\partial f(x, y, z)}{\partial \theta} &= \frac{\partial x}{\partial \theta} \frac{\partial f}{\partial x} + \frac{\partial y}{\partial \theta} \frac{\partial f}{\partial y} + \frac{\partial z}{\partial \theta} \frac{\partial f}{\partial z} \\ &= (-\rho \sin \phi \sin \theta) \frac{\partial f}{\partial x} + \rho \sin \phi \cos \theta \frac{\partial f}{\partial y} + \rho \sin \phi \cos \theta (-\sin \theta) \frac{\partial f}{\partial z} \end{aligned}$$

Therefore,

$$\begin{aligned} \frac{\partial}{\partial \rho} &= \sin \phi \cos \theta \frac{\partial f}{\partial x} + \sin \phi \sin \theta \frac{\partial f}{\partial y} + \cos \phi \frac{\partial f}{\partial z} \\ \frac{\partial}{\partial \phi} &= \rho \cos \phi \cos \theta \frac{\partial}{\partial x} + \rho \cos \phi \sin \theta \frac{\partial}{\partial y} \\ \frac{\partial}{\partial \theta} &= (-\rho \sin \phi \sin \theta) \frac{\partial}{\partial x} + \rho \sin \phi \cos \theta \frac{\partial}{\partial y} + \rho \sin \phi \cos \theta (-\sin \theta) \frac{\partial}{\partial z} \end{aligned}$$

- (b) Express $d\rho$, $d\phi$, and $d\theta$ as linear combinations of dx , dy , and dz .

Solution:

Note that $\rho^2 = x^2 + y^2 + z^2$ so,

$$2\rho d\rho = 2xdx + 2ydy + 2zdz \implies d\rho = \frac{xdx + ydy + zdz}{\rho} = \frac{xdx + ydy + zdz}{\sqrt{x^2 + y^2 + z^2}}$$

Similarly, $z = \rho \cos \phi$ and $\sin \phi = \sqrt{\frac{x^2 + y^2}{x^2 + y^2 + z^2}}$. Therefore,

$$\begin{aligned} dz &= -d\phi \rho \sin \phi + d\rho \cos \phi \\ d\phi &= \frac{\frac{z}{\rho} - d\rho}{\sqrt{x^2 + y^2}} = \frac{z \frac{xdx + ydy + zdz}{x^2 + y^2 + z^2} - dz}{\sqrt{x^2 + y^2}} \\ &= \frac{zxdx + zydy - (x^2 + y^2)dz}{(x^2 + y^2 + z^2)\sqrt{x^2 + y^2}} \end{aligned}$$

Finally, using $\tan \theta = \frac{y}{x}$ and differentiating both sides,

$$\begin{aligned} dy &= x \sec^2 \theta d\theta + dx \tan \theta \\ d\theta &= \frac{dy - dx \tan \theta}{x \sec^2 \theta} = \frac{\sin^2 \theta}{x} (dy - dx \tan \theta) = \frac{x}{x^2 + y^2} \left(dy - dx \frac{y}{x} \right) \\ &= \frac{x dy - y dx}{x^2 + y^2} \end{aligned}$$

6. Let V and W be finite dimensional vector spaces and let $A : V \rightarrow W$ be a linear map. Show that the dual map $A^* : W^* \rightarrow V^*$ is given in coordinates as follows. Let $\{e_i\}$ and $\{f_j\}$ be bases for V and W , and let $\{e^i\}$ and $\{f^j\}$ be the corresponding dual bases for V^* and W^* . If $Ae_i = A_i^j f_j$ then $A^* f^j = A_i^j e^i$.

Solution:

Suppose that $Ae_i = A_i^j f_j$ then, $A^* f^j$ is a linear functional on V such that,

$$(A^* f^j)(e_k) = f^j(Ae_k) = f^j(A_i^r f_r) = A_i^r f^j(f_r) = A_i^r \delta_r^j = A_i^j$$

However, $A^* f^j$ can be expressed in the dual basis, $A^* f^j = C_i^j e^i$ and $C_i^j e^i(e_k) = C_i^j \delta_k^i = C_k^j$. Thus, $A^* f^j = A_i^j e^i$.

7. Let V be a finite dimensional vector space and let $\langle \cdot, \cdot \rangle$ be an inner product on V . The inner product determines an isomorphism $\phi : V \rightarrow V^*$.

- (a) Show that the isomorphism ϕ is given in coordinates as follows. Let $\{e_i\}$ be a basis for V , let $\{e^i\}$ be the dual basis, and write $g_{ij} = \langle e_i, e_j \rangle$. Then $\phi(e_i) = g_{ij}e^j$.

Solution:

Let the isomorphism $\phi : V \rightarrow V^*$ be given by $\phi(v) \mapsto \langle v, \cdot \rangle$. Then,

$$\phi(e_i)(e_k) = \langle e_i, e_k \rangle = g_{ik}$$

however, $\phi(e_i) \in V^*$ so $\phi(e_i)$ can be expressed in terms of the dual basis $\phi(e_i) = C_{ij}e^j$ and $C_{ij}e^j(e_k) = C_{ij}\delta_k^j = C_{ik}$ so $C_{ik} = g_{ik}$. Therefore, $\phi(e_i) = g_{ij}e^j$.

- (b) The inner product, together with the isomorphism ϕ , define an inner product on V^* . Write this in coordinates as $g^{ij} = \langle e^i, e^j \rangle$. Show that the matrix (g^{ij}) is the inverse of the matrix (g_{ij}) .

Solution:

Given the inner product $\langle \cdot, \cdot \rangle : V \times V \rightarrow \mathbb{R}$ and the isomorphism $\phi : V \rightarrow V^*$, we can define an inner product on the dual space by, $\langle u, w \rangle = \langle \phi^{-1}(u), \phi^{-1}(w) \rangle$ for $u, w \in V^*$. Now, define the upper components by $g^{ij} = \langle e^i, e^j \rangle$. Consider,

$$\phi^{-1}(e^i) = C^{ij}e_j \implies \phi(C^{ij}e_j) = C^{ij}\phi(e_j) = C^{ij}g_{jk}e^k \implies C^{ij}g_{jk} = \delta_k^i$$

Thus $C = g^{-1}$ but g is symmetric because,

$$g_{ij} = \langle e_i, e_j \rangle = \langle e_j, e_i \rangle = g_{ji}$$

so C is also symmetric and $g_{ij}C^{jk} = \delta_i^k$. Now, define $g^{ij} = \langle e^i, e^j \rangle$ then,

$$\begin{aligned} g_{ij}g^{jk} &= g_{ij} \langle e^j, e^k \rangle = \langle g_{ij}e^j, e^k \rangle = \langle \phi(e_i), e^k \rangle = \langle e_i, \phi^{-1}(e^k) \rangle = \langle e_i, C^{kl}e_l \rangle \\ &= \langle e_i, e_l \rangle C^{kl} = g_{il}C^{kl} = \delta_k^i \\ g^{ij}g_{jk} &= \langle e^i, e^j \rangle g_{jk} = \langle e^i, g_{jk}e^j \rangle = \langle e^i, \phi(e_k) \rangle = \langle \phi^{-1}(e^i), e_k \rangle = \langle C^{il}e_l, e_k \rangle = \\ &= C^{il} \langle e_l, e_k \rangle = C^{il}g_{lk} = \delta_k^i \end{aligned}$$

Therefore, g^{ij} is the inverse matrix of g_{ij} . In particular, $C^{ij} = g^{ij}$.

8. How difficult was this assignment? How many hours did you spend on it?

I would not say this assignment was exactly difficult. It was time consuming and at times tedious but the ideas were not too difficult. Rather, I got bogged down in computations and notation. I spent about 7 - 8 hours on it.