

1 Geometry Identities

1.1 Interior Derivatives

Definition: Let ω be a k -form and X a vector field X . Then, we define the interior derivative,

$$(\iota_X \omega)(X_1, \dots, X_{k-1}) = \omega(X, X_1, \dots, X_{k-1})$$

Remark 1. By antisymmetry of forms $(\iota_X \circ \iota_Y + \iota_Y \circ \iota_X)\omega = 0$ and thus $\iota_X \circ \iota_X = 0$.

Lemma 1.1.

$$\mathcal{L}_X f = df(X) = X(f)$$

Proof. Consider the flow $\phi_t : M \rightarrow M$ along the vector field X . Then we define,

$$\begin{aligned} (\mathcal{L}_X f)(x) &= \frac{d}{dt} \Big|_{t=0} (\phi_t^* f) = \frac{d}{dt} \Big|_{t=0} (f \circ \phi_t) \\ &= df \circ d\phi(x) \left(\frac{\partial}{\partial t} \right) = df(X) \end{aligned}$$

because, by definition,

$$\frac{d}{dt} \phi_t(x) = d\phi(x) \left(\frac{\partial}{\partial t} \right) = X_x$$

□

Theorem 1.2. For any k -form ω and vector field X we have,

$$\mathcal{L}_X \omega = d\iota_X \omega + \iota_X d\omega$$

Proof. We will prove this by induction on k . For $k = 0$ we have,

$$\mathcal{L}_X f = df(X)$$

and furthermore,

$$d\iota_X f + \iota_X df = \iota_X df = df(X)$$

Now we can also consider,

$$\mathcal{L}_X(df) = d(\mathcal{L}_X f) = dX(f)$$

Furthermore,

$$[d\iota_X + \iota_X d](df) = d(\iota_X df) = dX(f)$$

Now, since Ω_M^1 is generated as a \mathcal{O}_M -module by the forms df it will suffice to show that both sides are derivations. Then, for α a p -form and β a q -form,

$$\begin{aligned} [d\iota_X + \iota_X d](\alpha \wedge \beta) &= d(\iota_X \alpha \wedge \beta + (-1)^p \alpha \wedge \iota_X \beta) + \iota_X (d\alpha \wedge \beta + (-1)^p \alpha \wedge d\beta) \\ &= d\iota_X \alpha \wedge \beta + (-1)^{p-1} \iota_X \alpha \wedge d\beta + (-1)^p d\alpha \wedge \iota_X \beta + \alpha \wedge d\iota_X \beta \\ &\quad + \iota_X d\alpha \wedge \beta + (-1)^{p+1} d\alpha \wedge \iota_X \beta + (-1)^p \iota_X \alpha \wedge d\beta + \alpha \wedge \iota_X d\beta \\ &= [d\iota_X + \iota_X d]\alpha \wedge \beta + \alpha \wedge [d\iota_X + \iota_X d]\beta \end{aligned}$$

so both sides are derivations and thus they must be equal since they agree for a basis of 1-forms. □

2 The Hodge Complex

Definition: Let (M, g) be an oriented Riemannian n -manifold and vol_g the canonical volume form. Then $g : TM \otimes TM \rightarrow \mathcal{O}_M$ defines a fiberwise nondegenerate inner product which we may view as an isomorphism $g : TM \rightarrow T^*M$ which, along with its inverse $g^{-1} : T^*M \rightarrow TM$, extends to isomorphisms on dual tensor bundles $T_m^n M \xrightarrow{\sim} T_m^n M$ and thus a nondegenerate pairing $\langle -, - \rangle : T_m^n M \otimes T_m^n M \rightarrow \mathcal{O}_M$.

Then we can define a Hilbert space $L^2(\mathcal{C}^\infty(M, T_m^n M))$ on the tensor bundles T_m^n via the inner product,

$$\langle\langle \alpha, \beta \rangle\rangle = \int_M \langle \alpha, \beta \rangle \text{vol}_g$$

Since vol_g is nonvanishing and the functions are smooth (and thus continuous) then,

$$\|\alpha\|^2 = \langle\langle \alpha, \alpha \rangle\rangle = 0 \iff \alpha = 0$$

Definition: On an oriented Riemannian n -manifold with canonical volume form vol_g we define the Hodge dual $\star : \Omega_M^k \rightarrow \Omega_M^{n-k}$ as the unique map such that,

$$\forall \alpha, \beta \in \Omega_M^k(U) : \alpha \wedge (\star \beta) = \langle \alpha, \beta \rangle \text{vol}_g$$

Furthermore, we have $\star \star \eta = (-1)^{n(n-k)} \eta$.

Definition: We define the codifferential $\delta : \Omega_M^{k+1} \rightarrow \Omega_M^k$ via $\delta = (-1)^{k+1} \star^{-1} d \star$.

Remark 2. This makes a chain complex since,

$$\delta \circ \delta = (-1)^{2k-1} (\star^{-1} d \star) \circ (\star^{-1} d \star) = - \star^{-1} d \circ d \star = 0$$

Lemma 2.1. For all $\alpha \in \Omega_M^k(U)$ and $\beta \in \Omega_M^{k+1}(U)$ we have,

$$\langle\langle d\alpha, \beta \rangle\rangle = \langle\langle \alpha, \delta\beta \rangle\rangle$$

Proof. We have $\langle d\alpha, \beta \rangle \text{vol}_g = d\alpha \wedge (\star \beta)$. Now consider,

$$\begin{aligned} d(\alpha \wedge (\star \beta)) &= d\alpha \wedge (\star \beta) + (-1)^k \alpha \wedge d(\star \beta) \\ &= d\alpha \wedge (\star \beta) + (-1)^k \alpha \wedge (\star (\star^{-1} d(\star \beta))) \\ &= d\alpha \wedge (\star \beta) - \alpha \wedge (\star \delta \beta) \end{aligned}$$

Then, by Stokes' theorem,

$$\int_M d(\alpha \wedge (\star \beta)) = \int_{\partial M} \alpha \wedge (\star \beta) = 0$$

because M is closed. Therefore,

$$\langle\langle d\alpha, \beta \rangle\rangle = \int_M \langle d\alpha, \beta \rangle \text{vol}_g = \int_M d\alpha \wedge (\star \beta) = \int_M \alpha \wedge (\star \delta \beta) = \int_M \langle \alpha, \delta \beta \rangle \text{vol}_g = \langle\langle \alpha, \delta \beta \rangle\rangle$$

□

Definition: We define the Laplace-deRham operator,

$$\Delta = \delta \circ d + d \circ \delta : \Omega_M^k \rightarrow \Omega_M^k$$

We say a k -form ω is *harmonic* if $\Delta\omega = 0$ and we denote the space of harmonic k -forms as $\mathcal{H}^k(M)$.

Remark 3. To motivate this definition, choose local coordinates such that,

$$\omega = g dx_1 \wedge \cdots \wedge dx_n$$

and consider a k -form in local coordinates,

$$\eta = \sum_{i_1 < \cdots < i_k} f_{i_1, \dots, i_k} dx_1 \wedge \cdots \wedge dx_{i_k}$$

Then,

$$d\eta = \sum_j \sum_{i_1 < \cdots < i_k} \frac{\partial f_{i_1, \dots, i_k}}{\partial x_j} dx_j \wedge dx_1 \wedge \cdots \wedge dx_{i_k}$$

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Lemma 2.2. $\star\Delta = \Delta\star$

Proof. It is clear that $\star\delta = (-1)^k d\star$ and $\star d = (-1)^k \delta\star$. Therefore,

$$\begin{aligned} \star\Delta &= \star(\delta d + d\delta) = (-1)^k d\star d + (-1)^k \delta\star\delta \\ &= d\delta\star + \delta d\star = \Delta\star \end{aligned}$$

□

Lemma 2.3. We have $\Delta\omega = 0$ iff $d\omega = \delta\omega = 0$.

Proof. Clearly if $d\omega = \delta\omega = 0$ then $\Delta\omega = 0$. Conversely, suppose that,

$$\Delta\omega = [\delta d + d\delta]\omega = 0$$

Consider,

$$\langle\langle\Delta\omega, \omega\rangle\rangle = \langle\langle\delta d\omega, \omega\rangle\rangle + \langle\langle d\delta\omega, \omega\rangle\rangle = \langle\langle d\omega, d\omega\rangle\rangle + \langle\langle \delta\omega, \delta\omega\rangle\rangle = \|d\omega\|^2 + \|\delta\omega\|^2$$

Since $\|\alpha\| \geq 0$ we see that if $\langle\langle\Delta\omega, \omega\rangle\rangle = 0$ then $\|\delta\omega\|^2 = 0$ and $\|d\omega\|^2 = 0$ and thus $\delta\omega = 0$ and $d\omega = 0$. □

Remark 4. Using this alternative characterization, we can make an alternative motivation for the definition of Δ . Suppose we wanted to choose the representative $[\alpha] \in H_{\text{dR}}^k(X)$ with minimum norm $\|\alpha\|$. According to calculus of variation we should perturb alpha slightly by an exact form to give $\alpha t d\eta$ and compute,

$$\|\alpha + t d\eta\|^2 = \|\alpha\|^2 + 2t \langle\langle\alpha, d\eta\rangle\rangle + t^2 \|d\eta\|^2 = \|\alpha\|^2 + 2t \langle\langle\delta\alpha, \eta\rangle\rangle + O(t^2)$$

Therefore, since we want the norm to be extremal we require it be constant to first order for every test form η . Setting $\eta = \delta\alpha$ forces $\delta\alpha = 0$. Since $[\alpha]$ is a cohomology class, we also have $d\alpha = 0$ and thus the minimal norm classes are represented by harmonic forms $\Delta\alpha = 0$.

Theorem 2.4 (Hodge). The space $\mathcal{H}^k(M)$ is finite dimensional and there is a canonical decomposition,

$$\Omega^k(M) = \Delta(\Omega^k(M)) \oplus \mathcal{H}^k(M) = d(\Omega^{k-1}(M)) \oplus \delta(\Omega^{k+1}(M)) \oplus \mathcal{H}^k(M)$$

Proof. The decomposition,

$$\Omega^k(M) = \Delta(\Omega^k(M)) \oplus \mathcal{H}^k(M) = \text{Im } \Delta \oplus \ker \Delta$$

follows immediately from splitting the sequence,

$$0 \longrightarrow \ker \Delta \longrightarrow \Omega^k(M) \longrightarrow \text{Im } \Delta \longrightarrow 0$$

First, suppose that $\eta = d\alpha = \delta\beta$ then,

$$\|\eta\|^2 = \langle \eta, \eta \rangle = \langle d\alpha, \delta\beta \rangle = \langle d^2\alpha, \beta \rangle = 0$$

and thus $\eta = 0$. Thus, $d(\Omega^{k-1}(M)) \cap \delta(\Omega^{k+1}(M)) = (0)$ so,

$$d(\Omega^{k-1}(M)) \oplus \delta(\Omega^{k+1}(M)) \subset \Omega^k(M)$$

Clearly,

$$\Delta(\Omega^k(M)) \subset d(\Omega^{k-1}(M)) \oplus \delta(\Omega^{k+1}(M))$$

because $\Delta\alpha = d(\delta\alpha) + \delta(d\alpha)$. Furthermore, if $d\alpha \in \mathcal{H}^k(M)$ then $\delta d\alpha = 0$ but

$$\|d\alpha\|^2 = \langle d\alpha, d\alpha \rangle = \langle \alpha, \delta d\alpha \rangle = 0$$

so $d\alpha = 0$ and similarly if $\delta\beta \in \mathcal{H}^k(M)$ then $d\delta\beta = 0$ but,

$$\|\delta\beta\|^2 = \langle \delta\beta, \delta\beta \rangle = \langle d\delta\beta, \beta \rangle = 0$$

so $\delta\beta = 0$. Therefore,

$$[d(\Omega^{k-1}(M)) \oplus \delta(\Omega^{k+1}(M))] \cap \mathcal{H}^k(M) = (0)$$

showing that,

$$\Delta(\Omega^k(M)) = d(\Omega^{k-1}(M)) \oplus \delta(\Omega^{k+1}(M))$$

The finite dimensionality of $\mathcal{H}^k(M)$ follows from the theory of elliptic operators on compact manifolds. However, we will prove it using the following result plus the following results: de Rham's theorem $H_{\text{dR}}^k(M) \cong H_{\text{sing}}^k(M)$, the fact that singular cohomology is finitely generated for a finite CW complex, and that any compact manifold has the homotopy type of a finite CW complex. \square

Theorem 2.5 (Hodge). Let M be compact oriented Riemann manifold. Then every deRham cohomology class on M has a unique harmonic representative and thus the canonical map,

$$\mathcal{H}^k(M) \xrightarrow{\sim} H_{\text{dR}}^k(M)$$

is an isomorphism.

Proof. I claim that,

$$\ker(d : \Omega^k(M) \rightarrow \Omega^{k+1}(M)) = d(\Omega^{k-1}(M)) \oplus \mathcal{H}^k(M)$$

We can write $\eta = d\alpha + \delta\beta + \varphi$ where φ is harmonic. Suppose that $d\eta = 0$ then $d\delta\beta = 0$ which we have shown implies that $\delta\beta = 0$ so $\eta = d\alpha + \varphi$ and thus,

$$\ker d \subset d(\Omega^{k-1}(M)) \oplus \mathcal{H}^k(M)$$

but it is clear that $d : \Omega^k(M) \rightarrow \Omega^{k+1}(M)$ vanishes on $d(\Omega^{k-1}(M)) \oplus \mathcal{H}^k(M)$ so,

$$\ker d = d(\Omega^{k-1}(M)) \oplus \mathcal{H}^k(M)$$

Using this we immediately see that the map,

$$\mathcal{H}^k(M) \rightarrow H_{\text{dR}}^k(M) \quad \varphi \mapsto [\varphi]$$

is an isomorphism because,

$$\ker d / \text{Im } d = [d(\Omega^{k-1}(M)) \oplus \mathcal{H}^k(M)] / d(\Omega^{k-1}(M)) = \mathcal{H}^k(M)$$

Explicitly, if $[\varphi] = 0$ then $\varphi = d\alpha$ but then $\Delta d\alpha = \delta d\alpha = 0$ which implies that $\varphi = d\alpha = 0$ so $\mathcal{H}^k(M) \rightarrow H_{\text{dR}}^k(M)$ is injective. Furthermore, consider a class $[\alpha] \in H_{\text{dR}}^k(M)$ with $d\alpha = 0$ then, by above, $\alpha \in d(\Omega^{k-1}(M)) \oplus \mathcal{H}^k(M)$ so $\alpha = \varphi + d\beta$ for some harmonic form $\varphi \in \mathcal{H}^k(M)$ and thus,

$$[\alpha] = [\varphi]$$

so the map $\mathcal{H}^k(M) \rightarrow H_{\text{dR}}^k(M)$ is surjective. \square

Theorem 2.6 (Poincare). Let M be compact oriented Riemann manifold. There is a canonical isomorphism $H_{\text{dR}}^k(M) \xrightarrow{\sim} H_{\text{dR}}^{n-k}(M)^\vee$.

Proof. Consider the bilinear pairing $H_{\text{dR}}^k(M) \times H_{\text{dR}}^{n-k}(M) \rightarrow \mathbb{R}$ via,

$$B([\omega], [\eta]) = \int_M \omega \wedge \eta$$

This is well-defined since if $\tilde{\omega} = \omega + d\alpha$ and $\tilde{\eta} = \eta + d\beta$ then,

$$\begin{aligned} \int_M \tilde{\omega} \wedge \tilde{\eta} &= \int_M (\omega + d\alpha) \wedge (\eta + d\beta) \\ &= \int_M \omega \wedge \eta + \int_M \omega \wedge d\beta + \int_M d\alpha \wedge (\eta + d\beta) \end{aligned}$$

However,

$$d(\omega \wedge \beta) = d\omega \wedge \beta + (-1)^k \omega \wedge d\beta$$

But ω is closed so we have,

$$\int_M \omega \wedge d\beta = (-1)^k \int_M d(\omega \wedge \beta) = (-1)^k \int_{\partial M} \omega \wedge \beta = 0$$

since M has no boundary. Likewise, since $\eta + d\beta$ is closed we have,

$$\int_M d\alpha \wedge (\eta + d\beta) = \int_{\partial M} \alpha \wedge (\eta + d\beta) = 0$$

Thus,

$$\int_M \tilde{\omega} \wedge \tilde{\eta} = \int_M \omega \wedge \eta$$

so this bilinear pairing is well-defined.

Now, it suffices to prove that the pairing is non-degenerate. For any class $[\omega]$ we can choose a harmonic representative φ . Furthermore $\star\varphi$ is harmonic since,

$$\Delta \star \varphi = \star \Delta \varphi = 0$$

so it represents a class $[\star\varphi] \in H_{\text{dR}}^{n-k}$. Then,

$$B([\omega], [\star\varphi]) = B([\varphi], [\star\varphi]) = \int_M \varphi \wedge (\star\varphi) = \int_M \langle \varphi, \varphi \rangle \omega = \|\varphi\|^2 = 0 \iff \varphi = 0$$

which shows that B is nondegenerate. \square

3 Local Systems

Definition: A \mathcal{A} -local system is a locally constant sheaf in the category \mathcal{A} i.e. a sheaf \mathcal{L} on X such that for each $x \in X$ there exists some open neighborhood U and an object A such that $\mathcal{L}|_U \cong \underline{A}$.

Lemma 3.1. If X is connected then any local system has constant fibers and thus we may take its constant objects on the trivializing neighborhoods to be equal.

Proof. For some fixed $p \in X$ let $D_p = \{x \in X \mid \mathcal{L}_x \cong \mathcal{L}_p\}$. Since \mathcal{L} is a local system, for any $x \in X$ we have an open U s.t. $\mathcal{L}|_U = \underline{A_x}$. If $x \in D_p$ then $\mathcal{L}_x \cong A_x \cong \mathcal{L}_p$. But then for any $y \in U$ we have,

$$\mathcal{L}_y \cong A_x \cong \mathcal{L}_x \cong \mathcal{L}_p$$

so $x \in U \subset D_p$ and thus D_p is open. Therefore,

$$X = \bigcup_{p \in X} D_p$$

is an open partition which implies that,

$$D_p^C = \bigcup_{x \neq p} D_p$$

is open so D_p is clopen. Since X is connected and $p \in D_p$ we have $D_p = X$. \square

Proposition 3.2. Let X be locally connected and \mathcal{L} be a \mathcal{A} -local system. Then there is a canonical functor $A : \Pi_1(X) \rightarrow \mathcal{A}$.

Proof. Consider a path $\gamma : I \rightarrow X$ from x to y . Then, since $\text{Im } \gamma$ is compact, we can choose a finite cover of $\text{Im } \gamma$ by connected trivializing neighborhoods U_i s.t. $U_i \cap U_{i+1} \neq \emptyset$ and $x \in U_0$ and $y \in U_n$. Then on each we have $\mathcal{L}|_{U_i} \cong F$. Now we construct a map $[\gamma] : \mathcal{F}_x \rightarrow \mathcal{F}_y$ as follows. For a germ $f \in \mathcal{L}_x$ we lift to a section $f \in \mathcal{L}(U_0)$ since f is constant on U_0 . Now, suppose we have a section $f_i \in \mathcal{L}(U_i)$, choose a connected open $V \subset U_i \cap U_{i+1}$ then $f_i|_V \in \mathcal{L}(V)$. Since $\mathcal{L}|_{U_{i+1}}$ is constant then the restriction map,

$$\text{res}_{V, U_{i+1}} : \mathcal{L}(U_{i+1}) \rightarrow \mathcal{L}(V)$$

is an isomorphism and thus we get a section $f_{i+1} = \text{res}_{V, U_{i+1}}^{-1}(f_i|_V)$. Then we choose $\alpha_\gamma f = f_n$ which is the germ of $f_n \in \mathcal{L}(U_n)$. It is clear that this is a morphism and invariant under homotopy giving a well-defined map $\Pi_1(X, x, y) \rightarrow \text{Hom}_{\mathcal{A}}(\mathcal{L}_x, \mathcal{L}_y)$. \square

Proposition 3.3. Let X be path-connected and locally connected and \mathcal{L} be a local system with fiber $\mathcal{L}_p \cong F$. Then there is a canonical action $\pi_1(X, x_0) \rightarrow \text{Aut}(\mathcal{L}_{x_0})$ and $\Gamma(X, \mathcal{F}) = \mathcal{L}_{x_0}^{\pi_1(X, x_0)}$.

Proof. Consider the case $x_0 = x = y$ then we have a map $\pi_1(X, x_0) \rightarrow \text{Aut}(\mathcal{L}_{x_0})$. Now, consider the restriction map $\Gamma(X, \mathcal{L}) \rightarrow \mathcal{L}_{x_0}$. Since restrictions compose we have $\alpha_\gamma f|_{x_0} = f|_{x_0}$ since $f_i = f|_{U_i}$ and $(f|_{U_n})_{x_0} = f_{x_0}$ so the image lies in $\mathcal{L}_{x_0}^{\pi_1(X, x_0)}$. Conversely, consider $f \in \mathcal{L}_{x_0}^{\pi_1(X, x_0)}$ such that $[\gamma] \cdot f = f$ for any loop $\gamma : I \rightarrow X$. Now, taking $x \in X$ we can define $f_x = [\gamma] \cdot f$ where γ is a path from x_0 to x . This is well-defined because if $\gamma, \delta : I \rightarrow X$ are two paths from x_0 to x then $\delta^{-1} * \gamma$ is a loop at x_0 and $\alpha_{\delta^{-1} * \gamma} = \alpha_\delta^{-1} \circ \alpha_\gamma$ but by assumption $\alpha_{\delta^{-1} * \gamma} = \text{id}$ so $\alpha_\gamma = \alpha_\delta$. Furthermore, each f_x lifts to $f_x \in \mathcal{L}(U_x)$ for some trivializing neighborhood and these sections glue to a global section by the construction of the morphisms. This construction gives an inverse map $\mathcal{L}_{x_0}^{\pi_1(X, x_0)} \rightarrow \Gamma(X, \mathcal{L})$ showing the given isomorphism. \square

3.1 Connections

Definition: Let \mathcal{E} be a coherent sheaf on X . Then a *connection* on \mathcal{E} is a morphism $\nabla : \mathcal{E} \rightarrow \Omega_X^1 \otimes_{\mathcal{O}_X} \mathcal{E}$ of *abelian* sheaves (not \mathcal{O}_X -modules) which satisfies the Leibniz rule,

$$\nabla(fs) = df \otimes s + f\nabla s$$

Proposition 3.4. Given a connection $\nabla : \mathcal{E} \rightarrow \Omega_X^1 \otimes_{\mathcal{O}_X} \mathcal{E}$ it naturally extends to a connection $\nabla_k : \Omega_X^k \otimes_{\mathcal{O}_X} \mathcal{E} \rightarrow \Omega_X^{k+1} \otimes_{\mathcal{O}_X} \mathcal{E}$ via,

$$\nabla_k(\omega \otimes e) = d\omega \otimes e + (-1)^k \omega \wedge \nabla e$$

Definition: The connection ∇ defines a corresponding curvature form,

$$\omega_\nabla = \nabla_1 \circ \nabla : \mathcal{E} \rightarrow \Omega_X^2 \otimes_{\mathcal{O}_X} \mathcal{E}$$

We say that ∇ is flat or integrable if the curvature vanishes $\omega_\nabla = \nabla_1 \circ \nabla = 0$.

Proposition 3.5. When ∇ is flat we have $\nabla_{k+1} \circ \nabla_k = 0$ for all k . In this case we have the \mathcal{E} -valued deRham complex,

$$0 \longrightarrow \mathcal{E} \xrightarrow{\nabla} \Omega_X^1 \otimes_{\mathcal{O}_X} \mathcal{E} \xrightarrow{\nabla_1} \Omega_X^2 \otimes_{\mathcal{O}_X} \mathcal{E} \longrightarrow \dots$$

whose hypercohomology gives the deRham cohomology with coefficients in \mathcal{E} ,

$$H_{\text{dR}}^k(X, \mathcal{E}) = \mathbb{H}^k(X, \Omega_X^\bullet \otimes_{\mathcal{O}_X} \mathcal{E})$$

Definition: A connection ∇ on \mathcal{E} defines a subsheaf $\mathcal{E}^\nabla = \ker \nabla \subset \mathcal{E}$ of *horizontal* or *flat* sections.

Lemma 3.6. The curvature $\omega_\nabla : \mathcal{E} \rightarrow \Omega_X^2 \otimes_{\mathcal{O}_X} \mathcal{E}$ is a \mathcal{O}_X -module map.

Proof. Consider,

$$\begin{aligned} \omega_\nabla(fs) &= \nabla_1(df \otimes s + f\nabla s) = ddf \otimes s - df \wedge \nabla s + df \wedge \nabla s + f\nabla_1 \circ \nabla \\ &= f\nabla_1 \circ \nabla s = f \omega_\nabla(s) \end{aligned}$$

□

Remark 5. If we write locally,

$$\nabla e = \sum_i f_i dg_i \otimes s_i$$

then the curvature takes the form,

$$\omega_\nabla(e) = \sum_i (df_i \wedge dg_i \otimes e - f_i dg_i \otimes \nabla s_i)$$

Proposition 3.7. ∇ is flat iff the \mathcal{O}_X -map $Q : \mathcal{D}er(\mathcal{O}_X, \mathcal{O}_X) \rightarrow \mathcal{E}nd_{\mathcal{O}_X}(\mathcal{E})$ given by sending D to,

$$\mathcal{E} \xrightarrow{\nabla} \Omega_X^1 \otimes_{\mathcal{O}_X} \mathcal{E} \xrightarrow{D \otimes \text{id}} \mathcal{O}_X \otimes_{\mathcal{O}_X} \mathcal{E} \xrightarrow{a \otimes b \mapsto ab} \mathcal{E}$$

is a morphism of sheaves of Lie algebras.

Remark 6. In the definition of $Q(D)$ we have used D as an \mathcal{O}_X -module morphism $\Omega_X^1 \rightarrow \mathcal{O}_X$ via the universal property of Ω_X^1 ,

$$\mathcal{D}er(\mathcal{O}_X, \mathcal{O}_X) \cong \mathcal{H}om_{\mathcal{O}_X}(\Omega_X^1, \mathcal{O}_X) = \mathcal{T}_X$$

which identifies $\mathcal{D}er(\mathcal{O}_X, \mathcal{O}_X)$ with the tangent sheaf \mathcal{T}_X .

Proof. We need to check that $Q[D_1, D_2] = [Q(D_1), Q(D_2)]$ is equivalent to $\nabla_1 \circ \nabla = 0$. Now,

$$[D_1, D_2] \in \text{Hom}_{\mathcal{O}_U}(\Omega_U^1, \mathcal{O}_U)$$

is the unique \mathcal{O}_X -map such that,

$$[D_1, D_2] \circ d = D_1 \circ d \circ D_2 \circ d - D_2 \circ d \circ D_1 \circ d$$

Now consider this action locally,

$$[D_1, D_2] \otimes \text{id} \circ \nabla = \sum_i f_i (D_1 \circ d \circ D_2 \circ d - D_2 \circ d \circ D_1 \circ d)(g_i) \cdot s_i$$

Furthermore,

$$[Q(D_1), Q(D_2)] = (D_1 \otimes \text{id}) \circ \nabla \circ (D_2 \otimes \text{id}) \circ \nabla - (D_2 \otimes \text{id}) \circ \nabla \circ (D_1 \otimes \text{id}) \circ \nabla$$

Again consider its local action,

$$\begin{aligned} Q(D_1) \circ Q(D_2)(e) &= (D_1 \otimes \text{id}) \circ \nabla \left(\sum_i f_i D_2(\text{d}g_i) \cdot s_i \right) \\ &= \sum_i \left([D_2(\text{d}g_i) D_1(\text{d}f_i) + f_i D_1(\text{d}(D_2(\text{d}g_i)))] \cdot s_i + f_i D_2(\text{d}g_i) D_1(\nabla s_i) \right) \end{aligned}$$

Now consider,

$$\begin{aligned} &\left[Q(D_1) \circ Q(D_2) - Q(D_2) \circ Q(D_1) \right] - Q([D_1, D_2])(e) \\ &= \sum_i \left(D_1(\text{d}f_i) D_2(\text{d}g_i) - D_2(\text{d}f_i) D_1(\text{d}g_i) \right) \cdot s_i \\ &\quad + \sum_i f_i \left(D_1(\text{d}(D_2(\text{d}g_i))) - D_2(\text{d}(D_1(\text{d}g_i))) \right) \cdot s_i \\ &\quad + \sum_i \left(f_i D_2(\text{d}g_i) D_1(\nabla s_i) - g_i D_1(\text{d}g_i) D_2(\nabla s_i) \right) \\ &\quad - \sum_i f_i (D_1 \circ d \circ D_2 \circ d - D_2 \circ d \circ D_1 \circ d)(g_i) \cdot s_i \\ &= \sum_i \left(D_1(\text{d}f_i) D_2(\text{d}g_i) - D_2(\text{d}f_i) D_1(\text{d}g_i) \right) \cdot s_i \\ &\quad + \sum_i \left(f_i D_2(\text{d}g_i) D_1(\nabla s_i) - g_i D_1(\text{d}g_i) D_2(\nabla s_i) \right) \\ &= (D_1 \otimes D_2 - D_2 \otimes D_1) \otimes \text{id}_{\mathcal{E}} \circ \omega_{\nabla} \end{aligned}$$

which is defined on $(\Omega_X^1)^{\otimes 2} \otimes_{\mathcal{O}_X} \mathcal{E}$ but descends to $\Omega_X^2 \otimes_{\mathcal{O}_X} \mathcal{E}$ since it sends the ideal $\omega \otimes \omega \mapsto 0$. Therefore, we see that Q is a Lie algebra map iff

$$\forall D_1, D_2 \in \text{Hom}_{\mathcal{O}_X}(\Omega_X^1, \mathcal{O}_X) : (D_1 \otimes D_2 - D_2 \otimes D_1) \otimes \text{id}_{\mathcal{E}} \circ \omega_{\nabla} = 0$$

in particular when $\omega_{\nabla} = 0$. Furthermore when Q is a Lie algebra map then we must have $\omega_{\nabla} = 0$ since, for any fixed form, there exists sections of Ω_X^1 which do not kill it. \square

Example 3.8. For $\mathcal{E} = \mathcal{O}_X$ we have the universal connection $d : \mathcal{O}_X \rightarrow \Omega_X^1$. Then the statment that d is flat is equivalent to $d^2 = 0$ leading to the deRham complex. Furthermore this means that d induces a Lie algebra map,

$$\mathcal{T}_X \rightarrow \text{End}_{\mathcal{O}_X}(\mathcal{O}_X) = \mathcal{O}_X$$

sending a vector field v to the map $f \mapsto \langle v, df \rangle$ proving the identity, $\langle [v, u], df \rangle = 0$ since \mathcal{O}_X has trivial Lie algebra structure.

Example 3.9. A connection on a scheme or manifold X is a connection on the cotangent (or equivalently tangent) bundle $\nabla : \Omega_X^1 \rightarrow (\Omega_X^1)^{\otimes 2}$. Such a connection is equivalent to a choice of global section $g \in \Gamma(X, \text{Sym}^2(\Omega_X^1))$ i.e. a metric. We say that (X, g) is flat if this connection ∇ is flat. In this case we have an augmented deRham complex $(\Omega_X^\bullet \otimes_{\mathcal{O}_X} \Omega_X^1, \nabla)$.

Remark 7. Note that a connection $\nabla : \mathcal{O}_X \rightarrow \Omega_X^1$ does NOT induce a connection on Ω_X^1 . Such a connection induces a connection,

$$\nabla_1 : \Omega_X^1 \otimes_{\mathcal{O}_X} \mathcal{O}_X = \Omega_X^1 \rightarrow \Omega_X^2 \otimes_{\mathcal{O}_X} \mathcal{O}_X = \Omega_X^2 = \bigwedge^2 \Omega_X^1$$

but it is only well-defined in the exterior algebra not on the tensor algebra $\Omega_X^1 \otimes_{\mathcal{O}_X} \Omega_X^1$. There is always a canonical derivation i.e. connection $d : \Omega_X \rightarrow \Omega_X^1$ but there is not generically a map $\Omega_X^1 \rightarrow (\Omega_X^1)^{\otimes 2}$.

3.2 Vector Bundles

Proposition 3.10. Let \mathcal{E} be a vector bundle on X with a flat connection

$$\nabla : \mathcal{E} \rightarrow \Omega_X^1 \otimes_{\mathcal{O}_X} \mathcal{E}$$

Then $\mathcal{E}^\nabla = \ker \nabla$ is a local system.

Proof. Since \mathcal{E} is locally free, we can find a cover of trivializing neighborhoods U such that $\mathcal{E}|_U \cong \mathcal{O}_U^{\oplus n}$. Then $\nabla : \mathcal{O}_U^{\oplus n} \rightarrow (\Omega_U^1)^{\oplus n}$ is a connection. Define,

$$\nabla e_j = \sum_{i=1}^n \omega_{ij} \otimes e_i$$

where $\omega_{ij} \in \Omega_X^1(U)$ is a form. This uniquely defines the connection since,

$$\begin{aligned} \nabla(f_1, \dots, f_n) &= \nabla \left(\sum_{i=1}^n f_i e_i \right) = \sum_{i=1}^n (f_i \nabla e_i + df_i \otimes e_i) \\ &= \sum_{i,j=1}^n \omega_{ij} \otimes f_j e_i + (df_1, \dots, df_n) \end{aligned}$$

Therefore, \mathcal{E}^∇ is given locally by (f_1, \dots, f_n) solving the linear system of differential equations,

$$df_i + \sum_{j=1}^n \omega_{ij} f_j = 0$$

The condition of flatness is that,

$$\nabla_1 \circ \nabla = 0$$

which locally is,

$$\begin{aligned}
\nabla_1 \circ \nabla(f_1, \dots, f_n) &= \nabla_1 \left(\sum_{i,j=1}^n \omega_{ij} \otimes f_j e_i + \sum_{j=1}^n df_j \otimes e_j \right) \\
&= \sum_{i,j=1}^n [d\omega_{ij} \otimes f_j e_i - \omega_{ij} \wedge \nabla(f_j e_i)] + \sum_{i=1}^n [ddf_i \otimes e_i - df_i \wedge \nabla e_i] \\
&= \sum_{i,j=1}^n \left[d\omega_{ij} \otimes f_j e_i - \omega_{ij} \wedge \left(df_j \otimes e_i + f_j \sum_{k=1}^n \omega_{ki} \otimes e_k \right) \right] - \sum_{i,j=1}^n [df_j \wedge \omega_{ij} \otimes e_i] \\
&= \sum_{i,j=1}^n \left[d\omega_{ij} \otimes e_i - \sum_{k=1}^n \omega_{ij} \wedge \omega_{ki} \otimes e_k \right] f_j \\
&= \sum_{i,j=1}^n \left[d\omega_{ij} + \sum_{k=1}^n \omega_{ik} \wedge \omega_{kj} \right] \otimes f_j e_i
\end{aligned}$$

So the curvature ω_∇ is given by coefficients,

$$\Theta_{ij} = d\omega_{ij} + \sum_{k=1}^n \omega_{ik} \wedge \omega_{kj}$$

Now I claim that if ε^∇ as a full set of solutions then $\omega_\Delta = 0$. To show this, consider,

$$d \left(df_i + \sum_{j=1}^n \omega_{ij} f_j \right) = 0$$

This implies,

$$\sum_{j=1}^n (d\omega_{ij} f_j - \omega_{ij} \wedge df_j) = 0$$

However, using the relation,

$$\sum_{j=1}^n (d\omega_{ik} + \omega_{ij} \wedge \omega_{jk}) f_k = 0$$

and thus,

$$\sum_{j=1}^n \Theta_{ij} f_j = 0$$

If we assume that f_i can be chosen to span then we must have $\Theta_{ij} = 0$ which implies $\omega_\nabla = 0$. This is also sufficient for integrability. \square

4 Hilbert Spaces